# Calc III Midterm Essay Review

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## Chapter 1

#### **Definition review**

**Definition 1.1** (standard basis in  $\mathbb{R}^3$ ). The vectors

$$i = (1, 0, 0), j = (0, 1, 0), k = (0, 0, 1)$$

are called the **standard basis** vectors of  $\mathbb{R}^3$ , and for any vector  $a = (a_1, a_2, a_3) \in \mathbb{R}^3$ , we can write

$$a = a_1i + a_2j + a_3k$$

**Definition 1.2** (Equation of a line). A **line** l in  $\mathbb{R}^3$  through the tip of  $a=(a_1,a_2,a_3)$  pointing in the direction of a vector  $v=(v_1,v_2,v_3)$  is given by

$$l(t) = a + tv = (a_1 + tv_1, a_2 + tv_2, a_3 + tv_3)$$

where  $t \in \mathbb{R}$ . Alternatively, a line passing through two points  $P = (x_1, y_1, z_1), Q = (x_2, y_2, z_2)$  is given by

$$l(t) = (x(t), y(t), z(t))$$

where

$$\begin{cases} x(t) = x_1 + (x_2 - x_1)t \\ y(t) = y_1 + (y_2 - y_1)t \\ z(t) = z_1 + (z_2 - z_1)t \end{cases}$$

**Definition 1.3** (inner product, dot product). Let  $a, b \in \mathbb{R}^3$ , the **dot product**, also called the inner product, of a, b is

$$a \cdot b = a_1 b_1 + a_2 b_2 + a_3 b_3$$

where  $a = (a_1, a_2, a_3), b = (b_1, b_2, b_3)$ . The **norm**, also called the length, of a is

$$||a|| = (a \cdot a)^{\frac{1}{2}}$$

A vector of norm 1 is called a **unit vector**. Given any  $u \in \mathbb{R}^3$ , we can find the unit vector  $\frac{u}{\|u\|}$  pointing in the same direction as u, this is called "normalizing" u.

Definition 1.4 (orthogonal projection). The **orthogonal projection** of vector v onto another vector a is

$$\mathrm{Proj}_a v = \frac{a \cdot v}{a \cdot a} a$$

For example, the orthogonal projection of (1, 1, 0) onto (1, 1, 1) is

$$\left(\frac{2}{3}, \frac{2}{3}, \frac{2}{3}\right)$$

**Definition 1.5** (orthogonal). Let  $a, b \in \mathbb{R}^n$ , then a, b are called **orthogonal** or perpendicular iff

$$a \cdot b = 0$$

**Definition 1.6** (determinant). The **determinant** of a  $2 \times 2$  matrix is given by

$$\det \begin{bmatrix} a & b \\ c & d \end{bmatrix} = ad - bc$$

and the determinant of a  $3 \times 3$  matrix is given by

$$\det\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} = a_{11}(a_{22}a_{33} - a_{23}a_{32}) - a_{12}(a_{21}a_{33} - a_{23}a_{31}) + a_{13}(a_{21}a_{32} - a_{22}a_{31})$$

**Definition 1.7** (cross product). Let  $a, b \in \mathbb{R}^3$ , write  $a = (a_1, a_2, a_3), b = (b_1, b_2, b_3)$ , then the **cross product** 

$$a \times b = \det \begin{bmatrix} i & j & k \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{bmatrix}$$

where i, j, k are the standard vectors in  $\mathbb{R}^3$ .

**Definition 1.8** (Plane in  $\mathbb{R}^3$ ). If a plane P passes through some point  $(x_0, y_0, z_0)$ , and n = (A, B, C) is a vector orthogonal to the plane, then the plane P is given by the equation:

$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0$$

(Notice that a point in P and a normal vector to P uniquely define a plane in  $\mathbb{R}^3$ .)

**Definition 1.9** (image, graph). The **image** of a function  $f:U\subset\mathbb{R}^n\to\mathbb{R}^m$  is a subset of  $\mathbb{R}^m$ ,

$$Image(f) = \{ f(x) \in \mathbb{R}^m : x \in U \}$$

and the **graph** of f is a subset of  $\mathbb{R}^{n+m}$ ,

$$Graph(f) = \{(x, f(x)) : x \in U\}$$

**Definition 1.10** (level set). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}^m$ , and  $c\in\mathbb{R}$  be some constant. Then the **level set** of f at c is the set

$$\{x \in U : f(x) = c\} \subset \mathbb{R}^n$$

**Definition 1.11** (open set, neighborhood, boundary). Let  $U \subset \mathbb{R}^n$ , we say U is an **open set** if for every  $x_0 \in U$ , there exists some r > 0 such that  $D_r(x_0) \subset U$ , where  $D_r(x_0)$  is the open disk of radius r centered at  $x_0$ :

$$D_r(x_0) = \{ x \in \mathbb{R}^n : ||x - x_0|| < r \}$$

Some examples of open sets:  $\mathbb{R}$ ,  $D_1((0,0))$ ,  $(1,2) \subset \mathbb{R}$ . A **neighborhood** of  $x_0 \in \mathbb{R}^n$  is an open set containing the point  $x_0$ . A point  $x \in \mathbb{R}^n$  is called a **boundary point** of A if *every* neighborhood of x contains at least one point in A and at least one point not in A.

**Definition 1.12** (limit). Let  $f: A \subset \mathbb{R}^n \to \mathbb{R}^m$ , where A is open, let  $x_0$  be in A or be a boundary point of A and A be a neighborhood of a point  $b \in \mathbb{R}^m$ . Now let x approach  $x_0$ , f is said to be **eventually in** X if there exists a neighborhood X of X of

if 
$$x \in U$$
, then  $f(x) \in N$ 

If f is eventually in N for any neighborhood N around b, then the **limit** of f as  $x \to x_0$  exists, denoted as

$$\lim_{x \to x_0} f(x) = b$$

**Definition 1.13** (continuous). Let  $f: A \subset \mathbb{R}^n \to \mathbb{R}^m$  and  $x_0 \in A$ , then f is **continuous** at  $x_0$  if

$$\lim_{x \to x_0} f(x) = f(x_0)$$

**Definition 1.14** (partial derivative). Let  $f: U \subset \mathbb{R}^n \to \mathbb{R}$ , where U is open. Then the **partial derivative** with respect to  $x_i$  is defined by

$$\frac{\partial f}{\partial x_i}(x_1, \dots, x_n) = \lim_{h \to 0} \frac{f(x + he_j) - f(x)}{h}$$

where  $e_i = (0, \dots, 1, \dots, 0)$  with 1 in the *i*th coordinate.

**Definition 1.15** (differentiability in two variables). Let  $f: \mathbb{R}^2 \to \mathbb{R}$ , then f is **differentiable** at  $(x_0, y_0)$  if

- (1)  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$  exist at  $(x_0, y_0)$
- (2)

$$\lim_{(x,y)\to(x_0,y_0)} \frac{f(x,y) - f(x_0,y_0) - \left[\frac{\partial f}{\partial x}(x_0,y_0)\right](x-x_0) - \left[\frac{\partial f}{\partial y}(x_0,y_0)\right](y-y_0)}{\|(x,y) - (x_0,y_0)\|} = 0$$

The derivative of f at  $(x_0, y_0)$  is the  $1 \times 2$  matrix

$$\begin{bmatrix} \frac{\partial f}{\partial x}(x_0, y_0) & \frac{\partial f}{\partial y}(x_0, y_0) \end{bmatrix}$$

Moreover, the **tangent plane** of the graph of f at  $(x_0, y_0, f(x_0, y_0))$  is given by

$$z = f(x_0, y_0) + \left[\frac{\partial f}{\partial x}(x_0, y_0)\right](x - x_0) + \left[\frac{\partial f}{\partial y}(x_0, y_0)\right](y - y_0)$$

**Definition 1.16** (differentiability in the general setting). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}^m$ , then f is differentiable at  $x_0\in U$  if

(1) the partial derivatives  $\frac{\partial f_i}{x_j}$  exist for all  $1 \le i \le m, 1 \le j \le n$ .

(2)

$$\lim_{x \to x_0} \frac{\|f(x) - f(x_0) - T(x - x_0)\|}{\|x - x_0\|} = 0$$

where  $T = Df(x_0)$  is the  $m \times n$  matrix

$$Df(x_0) = \begin{bmatrix} \frac{\partial f_1}{\partial x_1}(x_0) & \cdots & \frac{\partial f_1}{\partial x_n}(x_0) \\ \vdots & \ddots & \vdots \\ \frac{\partial f_m}{\partial x_1}(x_0) & \cdots & \frac{\partial f_m}{\partial x_n}(x_0) \end{bmatrix}$$

The derivative of f at  $x_0$  is the  $m \times n$  matrix  $Df(x_0)$ .

**Definition 1.17** (graident). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}$ , the **gradient**  $\nabla f(x)$  is a special case of the general case above when m=1, i.e., it is a  $1\times n$  matrix

$$Df(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} & \dots & \frac{\partial f}{\partial x_n} \end{bmatrix}$$

**Definition 1.18** (path and curve). A **path** in  $\mathbb{R}^n$  is a map  $c:[a,b]\to\mathbb{R}^n$ , and the image of c is called a **curve**. We say the path c parametrizes the curve.

For example,  $c(t) = (\cos t, \sin t)$  is a path, and the unit circle is a curve.

**Definition 1.19** (velocity of a path). Let  $c : [a,b] \to \mathbb{R}^n$  be a path, and we can write  $c(t) = (c_1(t), \ldots, c_n(t))$ . If c is differentiable, then we define the **velocity** of c at any  $t_0 \in [a,b]$  as

$$c'(t_0) = (c'_1(t_0), \dots, c'_n(t_0))$$

The velocity vector of c at  $t_0$  is also a **tangent** vector to c at  $t_0$ . The **speed** of the path c at  $t_0$  is the length of the velocity vector  $||c'(t_0)||$ .

**Definition 1.20** (tangent line to a path). Let  $c : [a,b] \to \mathbb{R}^n$  be a path, if  $c'(t_0) \neq 0$ , then the **tangent line** at  $x_0$  is given by

$$l(t) = c(t_0) + c'(t_0)(t - t_0)$$

**Definition 1.21** (directional derivative). Let  $f : \mathbb{R}^3 \to \mathbb{R}$ , be differentiable, then the **directional directive** at  $x_0 \in \mathbb{R}^3$  in the direction of a *unit vector* v is given by

$$\nabla f(x_0) \cdot v = \left[ \frac{\partial f}{\partial x_1}(x_0) \right] v_1 + \left[ \frac{\partial f}{\partial x_2}(x_0) \right] v_2 + \left[ \frac{\partial f}{\partial x_3}(x_0) \right] v_3$$

where  $v = (v_1, v_2, v_3)$ .



Warning 1.1. Make sure you normalize any given direction v! This formula works for unit vectors.

**Definition 1.22** (First order Taylor expansion). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}$  be differentiable at  $a\in U$ , then

$$f(x) = f(a) + \sum_{i=1}^{n} \frac{\partial f}{\partial x_i}(a)(x_i - a_i) + R_1(a, x)$$

where

$$\frac{R_1(a,x)}{\|x-a\|} \to 0 \text{ as } x \to a$$

**Definition 1.23** (Second order Taylor expansion). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}$  be twice continuously differentiable at  $a\in U$ , then

$$f(x) = f(a) + \sum_{i=1}^{n} \frac{\partial f}{\partial x_i}(a)(x_i - a_i) + \frac{1}{2} \sum_{i,j=1}^{n} \frac{\partial^2 f}{\partial x_i \partial x_j}(a)(x_i - a_i)(x_j - a_j) + R_2(a, x)$$

where

$$\frac{R_2(a,x)}{\|x-a\|} \to 0 \text{ as } x \to a$$

# **Chapter 2**

### Theorem Review

**Proposition 2.1** (dot product). Let  $a, b \in \mathbb{R}^3$ , and let  $\theta$  be the angle between a, b, where  $0 \le \theta \le \pi$ , then

$$a \cdot b = ||a|| ||b|| \cos \theta$$

**Proposition 2.2** (properties of the dot product). Let  $a, b, c \in \mathbb{R}^n$ , then

- (a) Nonnegativity:  $a \cdot a \ge 0$ , and  $a \cdot a = 0$  if and only if a = 0.
- (b) Scalar multiplication: let  $\lambda \in \mathbb{R}$ , then

$$\lambda(a \cdot b) = \lambda a \cdot b = a \cdot \lambda b$$

(c) Distributivity:

$$a \cdot (b+c) = a \cdot b + a \cdot c, \quad (a+b) \cdot c = a \cdot c + b \cdot c$$

(d) Symmetry:  $a \cdot b = b \cdot a$ .

**Proposition 2.3** (Cauchy-Schwarz). Let  $a, b \in \mathbb{R}^n$ , then  $a \cdot b \in \mathbb{R}$ ,

$$|a \cdot b| \le ||a|| ||b||$$

where the left hand side is the absolute value of  $a \cdot b$ , and the right hand side is multiplication of two nonnegative real numbers.

**Proposition 2.4** (triangle inequality). Let  $a, b \in \mathbb{R}^n$ , then

$$||a+b|| \le ||a|| + ||b||$$

**Proposition 2.5** (cross product). We have the following properties regarding the cross product: let  $a, b \in \mathbb{R}^3$ ,

- 1.  $a \times b$  is perpendicular to vectors a, b.
- 2. The length of the cross product is the area of the parallelogram:

$$||a \times b|| = ||a|| ||b|| \sin \theta$$

where  $0 \le \theta \le \pi$  is the angle between them.

- 3.  $a \times b = -b \times a$ ,  $(a + b) \times c = a \times c + b \times c$ , and  $a \times (b + c) = a \times b + a \times c$ . Moreover,  $a \times b = 0$  iff a, b are parallel or either a or b are 0.
- 4. The cross product is **not** associative! For example, compute

$$(i \times i) \times j, \quad i \times (i \times j)$$

**Proposition 2.6** (limits). Here are some properties of limits: let  $f: U_1 \subset \mathbb{R}^n \to \mathbb{R}^m, g: U_2 \subset \mathbb{R}^n \to \mathbb{R}^m$ ,

(a) (Uniquess):

If 
$$\lim_{x \to x_0} f(x) = b_1$$
,  $\lim_{x \to x_0} f(x) = b_2$ 

then we must have

$$b_1 = b_2$$

(b) (Scalar mutliplication): Let  $c \in \mathbb{R}$ , if  $\lim_{x \to x_0} f(x) = b_1$ , then

$$\lim_{x \to x_0} cf(x) = cb_1$$

(c) (Addition): Let f be as in (b), and  $\lim_{x\to x_0} g(x) = b_2$ , then

$$\lim_{x \to x_0} (f+g)(x) = b_1 + b_2$$

(d) (Component): Write  $f(x) = (f_1(x), \dots, f_n(x))$ , if  $\lim_{x\to x_0} f(x) = b = (b_1, \dots, b_n)$ , then

$$\lim_{x \to x_0} f_i(x) = b_i$$

for all  $i = 1, \ldots, m$ .

The same set of properties hold for continuity.

**Proposition 2.7** (continuity of compositions). Let  $g:A\subset\mathbb{R}^n\to\mathbb{R}^m$ , and  $f:B\subset\mathbb{R}^m\to\mathbb{R}^p$ , and  $g(A)\subset B$ . If g is continuous at  $x_0$ , f is continuous at  $g(x_0)$ , then  $f\circ g$  is continuous at  $x_0$ .

**Proposition 2.8** (differentiability implies continuity). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}^m$ . If f is differentiable at  $x_0\in U$ , then f is continuous at  $x_0$ .

**Proposition 2.9** (differentiability). Let  $f: U \subset \mathbb{R}^n \to \mathbb{R}^m$ . Suppose  $\partial f_i/\partial x_j$  exists for all i, j and are continuous in a neighborhood of  $x_0 \in U$ , then f is differentiable at  $x_0$ .

**Proposition 2.10** (properties of derivatives). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}^m$  be differentiable at  $x_0$ , then the derivative of f at  $x_0$  is an  $m\times n$  matrix  $Df(x_0)=\left(\frac{\partial f_i}{\partial x_j}\right)_{ij}$ . The derivative follows the same properties as derivative for single variable functions:

1. Let  $c \in \mathbb{R}$ , then

$$D(cf)(x_0) = cDf(x_0)$$
 (multiplication of a matrix by constant c)

2. Let  $g: U \subset \mathbb{R}^n \to \mathbb{R}^m$  also be differentiable at  $x_0$ , then

$$D(f+g)(x_0) = Df(x_0) + Dg(x_0)$$
 (sum of two matrices)

3. Let  $h_1:U\subset\mathbb{R}^n\to\mathbb{R}, h_2:U\subset\mathbb{R}^n\to\mathbb{R}$ ,then

$$D(h_1h_2)(x_0) = Dh_1(x_0)h_2(x_0) + h_1(x_0)Dh_2(x_0)$$
 (product rule)

and if  $h_2 \neq 0$  on U.

$$D(h_1/h_2)(x_0) = \frac{Dh_1(x_0)h_2(x_0) - h_1(x_0)Dh_2(x_0)}{h_2^2(x_0)}$$
(quotient rule)

4. Let  $g:U\subset\mathbb{R}^n\to\mathbb{R}^m, f:V\subset\mathbb{R}^m\to\mathbb{R}^p$  such that  $g(U)\subset V$ , then

$$D(f \circ g)(x_0) = Df(g(x_0))Dg(x_0)$$
 (chain rule)

**Proposition 2.11** (fastest rate of change). Suppose that  $\nabla f(x_0) \neq 0$ , then the direction for which f increases the fastest at  $x_0$  is along  $\nabla f(x_0)$ .

**Proposition 2.12** (gradient is normal, tangent plane). Let  $f: \mathbb{R}^3 \to \mathbb{R}$  be differentiable, let S be a level surface of f, i.e., S is a surface described by

$$f(x, y, z) = k$$

were k is some constant. Let  $(x_0, y_0, z_0) \in S$ , then

$$\nabla f(x_0, y_0, z_0)$$
 is **normal** to the level surface at  $(x_0, y_0, z_0)$ 

This means if c(t) is a path in S, and  $v(0) = (x_0, y_0, z_0)$ , and if v is a tangent vector to c(t) at t = 0, then

$$\nabla f(x_0, y_0, z_0) \cdot v = 0$$

Moreover, if  $\nabla f(x_0, y_0, z_0) \neq 0$ , the **tangent plane** of S at  $(x_0, y_0, z_0)$  is given by

$$\nabla f(x_0, y_0, z_0) \cdot (x - x_0, y - y_0, z - z_0) = 0$$

**Proposition 2.13** (Equality of mixed partials). If f(x,y) be twice continuously differentiable, then

$$\frac{\partial^2 f}{\partial x \partial y} = \frac{\partial^2 f}{\partial y \partial x}$$

**Proposition 2.14** (extremums are critical points). Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}$  be differentiable, where U is open. If  $x_0$  is a local extremum, then  $Df(x_0)=0$ .

## **Chapter 3**

### **Practice Problems**

**Problem 3.1.** Find the equation of the line passing through (1,0,2) in the direction (2,-1,3).

Problem 3.2. In which direction does the line

$$l(t) = (3 - 2t, 2 + 5t, 1 + t)$$

point?

**Problem 3.3.** Do the following two lines intersect?

$$l_1(t) = (1 + 2t, 2 + t, 3 - t), \quad l_2(s) = (3 - s, 4 - s, 2 + s)$$

**Problem 3.4.** Do the following points lie on the same line?

$$A = (1, 0, 1), \quad B = (2, 1, 1), \quad C = (0, -1, 1)$$

**Problem 3.5.** Find the angle between two vectors (1,2,0), (3,1,1).

**Problem 3.6.** Let b = (2, 1, 3) and P be the plane through the origin given by x + y + 2z = 0.

- (a) Find two distinct vectors  $v_1, v_2$  that are orthogonal in P.
- (b) Find the projection of *b* onto the plane *P*, namely,

$$\operatorname{Proj}_{v_1} b + \operatorname{Proj}_{v_2} b$$

**Problem 3.7.** Find a unit vector orthogonal to both vectors a = (1, 2, -1), b = (2, 3, -1).

Problem 3.8. Find the equation of the plane containing all three points below:

$$P = (2, 1, -1), \quad Q = (1, 0, -2), \quad T = (3, 2, 1)$$

**Problem 3.9.** (a) Find an equation for the line that passes through the point (1,1,0) and is perpendicular to the plane 3x + y - 2z + 1 = 0.

(b) Find an equation for the plane that contains the line

$$l(t) = (-1+t, 2+2t, 1+3t)$$

and is perpendicular to the plane

$$2x + y - z + 1 = 0$$

**Problem 3.10.** Compute the area of the parallelogram spanned by the vectors (1, 1, 0), (0, 2, 1).

**Problem 3.11.** Use the traingle inequality 2.4 to show the reverse triangle inequality:

$$\left| \|a\| - \|b\| \right| \le \|a - b\|$$

Problem 3.12. Compute the following limits if they exist; if the limits don't exist, please explain why.

1.

$$\lim_{(x,y)\to(2,1)} \frac{x^2 + y^2 - 2xy}{x - y}$$

2.

$$\lim_{(x,y)\to(0,0)} \frac{\cos x - 1}{x^2 + y^2}$$

3.

$$\lim_{(x,y)\to(0,0)} \frac{(x-y)^2}{(x+y)^2}$$

4.

$$\lim_{(x,y)\to(0,0)} \frac{\sin 2x - 2x + y}{x^3 + y}$$

5.

$$\lim_{(x,y,z)\to (0,0,0)} \frac{2x^2y\cos z}{x^2+y^2}$$

6.

$$\lim_{(x,y)\to(2,1)}\frac{x^2-2xy}{x^2-4y^2}$$

7.

$$\lim_{(x,y)\to(0,0)} \frac{x^2 - y^6}{xy^3}$$

**Problem 3.13.** (a) Show that  $f: \mathbb{R} \to \mathbb{R}$ ,

$$f(x) = (1-x)^8 + \cos(1+x^3)$$

is continuous.

(b) Show  $f: \mathbb{R} \to \mathbb{R}$ ,

$$f(x) = \frac{x^2 e^x}{2 - \sin x}$$

is continuous.

**Problem 3.14.** Compute all the partial derivatives.

- 1.  $w = e^{xy} \log(x^2 + y^2)$ .
- 2.  $w = \cos(ye^{xy})\sin x$ .

**Problem 3.15.** Compute the gradient of  $h(x, y, z) = (x + z)e^{x-y}$  at (1, 1, 0).

**Problem 3.16.** Determine the velocity vector of the given path:

$$c(t) = (\cos 2t, 3t^2 - t, -t)$$

**Problem 3.17.** Find the tangent line to the given path at t = 0

$$c(t) = (e^t \sin t, 2t, -t^3)$$

**Problem 3.18.** Compute the derivatives.

1. Let

$$f(u, v) = u^2v + 2v, \quad u = -x^2 + y, v = x + y$$

Compute  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$ .

2. Let

$$g(u, v) = (e^u, u + \sin v), \quad f(x, y, z) = (x^2, yz)$$

Compute  $D(g \circ f)$  at (0, 1, 0).

3. Let  $f: \mathbb{R}^3 \to \mathbb{R}$  and  $c(t) = \mathbb{R} \to \mathbb{R}^3$ . Suppose c(0) = (1, 2, 0), and

$$\nabla f(1,2,0) = (0,0,1), \quad c'(0) = (2,1,1)$$

Compute  $\frac{d(f \circ c)}{dt}$  at t = 0.

Problem 3.19. Determine the directional derivative of

$$f(x, y, z) = x^3y - xyz$$

at (1,1,0) along v = (0,-1,1).

Problem 3.20. Find a unit vector normal to the surface

$$xe^y + ye^z + ze^x = e + 1$$

at the point (0, 1, 1).

**Problem 3.21.** Find the tangent plane of  $f(x, y, z) = \ln(x + y) - 2xz$  at (1, 2, -1).

**Problem 3.22.** A function  $f: \mathbb{R}^n \to \mathbb{R}$  is called an *even* function if f(x) = f(-x) for every x in  $\mathbb{R}^n$ . If f is differentiable and even, find  $\nabla f$  at the origin.

Problem 3.23. Consider the function

$$f(x,y) = \frac{1}{\log(x^2 + y)}.$$

Verify by hand that  $f_{xy} = f_{yx}$ .

**Problem 3.24.** Consider the function  $f(x, y, z) = (x^2 + y^2 + z^2)^{-1/2}$ . Show that

$$f_{xx} + f_{yy} + f_{zz} = 0.$$

Problem 3.25. Find the second-order Taylor expansion for the function

$$f(x,y) = x^2 + 2xy$$

at (1, 1).

### Chapter 4

# **Answer Key**

**Problem 4.1.** Find the equation of the line passing through (1,0,2) in the direction (2,-1,3).

*Proof.* By definition 1.2, the line is given by

$$l(t) = (1 + 2t, -t, 2 + 3t)$$

Problem 4.2. In which direction does the line

$$l(t) = (3 - 2t, 2 + 5t, 1 + t)$$

point?

*Proof.* In the direction of the vector (-2, 5, 1).

**Problem 4.3.** Do the following two lines intersect?

$$l_1(t) = (1+2t, 2+t, 3-t), \quad l_2(s) = (3-s, 4-s, 2+s)$$

*Proof.* For them to intersect, we must have t,s such that

$$\begin{cases} 1 + 2t = 3 - s & (1) \\ 2 + t = 4 - s & (2) \\ 3 - t = 2 + s & (3) \end{cases}$$

(2)-(1) gives -t+1=1, which implies t=0, s=2, but this does not satisfy (3), hence these two lines do not intersect!

Problem 4.4. Do the following points lie on the same line?

$$A = (1,0,1), \quad B = (2,1,1), \quad C = (0,-1,1)$$

*Proof.* We can find the unique line passing through A, B by the equation given in 1.2

$$l(t) = (1,0,1) + (1,1,0)t$$

then for *C* to lie on this line, there must exists some *t* such that

$$\begin{cases} 1+t=0 \\ t=-1 \\ 1=1 \end{cases}$$

and t = -1 satisfies. This means all three points lie on the same line!

**Problem 4.5.** Find the angle between two vectors (1, 2, 0), (3, 1, 1).

Proof. By Proposition 2.1

$$\cos \theta = \frac{a \cdot b}{\|a\| \|b\|} = \frac{5}{\sqrt{5}\sqrt{11}} = \sqrt{\frac{5}{11}}$$

hence

$$\theta = \arccos\left(\sqrt{\frac{5}{11}}\right)$$

**Problem 4.6.** Let b = (2, 1, 3) and P be the plane through the origin given by x + y + 2z = 0.

- (a) Find two distinct vectors  $v_1, v_2$  that are orthogonal in P.
- (b) Find the projection of b onto the plane P, namely,

$$\operatorname{Proj}_{v_1}b+\operatorname{Proj}_{v_2}b$$

*Proof.* (a) We can let  $v_1 = (1, -1, 0), v_2 = (1, 1, -1)$ . One can verify that  $v_1, v_2 \in P$  and  $v_1 \cdot v_2 = 0$ .

(b) The projection is given by

$$\begin{split} \operatorname{Proj}_{v_1} b + \operatorname{Proj}_{v_2} b &= \frac{v_1 \cdot b}{v_1 \cdot v_1} v_1 + \frac{v_2 \cdot b}{v_2 \cdot v_2} v_2 \\ &= \frac{1}{2} (1, -1, 0) + 0 \\ &= \left( \frac{1}{2}, -\frac{1}{2}, 0 \right) \end{split}$$

**Problem 4.7.** Find a unit vector orthogonal to both vectors a = (1, 2, -1), b = (2, 3, -1).

*Proof.* The cross product is orthognal to both of the vectors:

$$a \times b = \det \begin{bmatrix} i & j & k \\ 1 & 2 & -1 \\ 2 & 3 & -1 \end{bmatrix} = (1, -1, -1)$$

Problem 4.8. Find the equation of the plane containing all three points below:

$$P = (2, 1, -1), \quad Q = (1, 0, -2), \quad T = (3, 2, 1)$$

*Proof.* We can find two vectors in this plane:

$$PO = Q - P = (-1, -1, -1), PT = T - Q = (1, 1, 2)$$

then we can find a normal vector  $\boldsymbol{n}$  to the plane by taking the cross product:

$$n = PQ \times PT = \det \begin{bmatrix} i & j & k \\ -1 & -1 & -1 \\ 1 & 1 & 2 \end{bmatrix} = (-1, 1, 0)$$

Then by Definition 1.8, using point Q, we see the plane can be written as

$$-1(x-1) + y = 0$$

simplifying we get x - y = 1.

**Problem 4.9.** (a) Find an equation for the line that passes through the point (1,1,0) and is perpendicular to the plane 3x + y - 2z + 1 = 0.

(b) Find an equation for the plane that contains the line

$$l(t) = (-1+t, 2+2t, 1+3t)$$

and is perpendicular to the plane

$$2x + y - z + 1 = 0$$

*Proof.* (a) A normal vector to the plane 3x + y - 2z + 1 is (3, 1, -2), since the line is perpendicular to the plane, the line is parallel along the direction (3, 1, -2). Now the line passes through (1, 1, 0), thus we have the equation for the line

$$l(t) = (1, 1, 0) + t(3, 1, -2)$$

(b) A normal vector to 2x+y-z is n=(2,1,-1), and since our plane is perpendicular to this, it is parallel to the vector n. Thus a normal vector to our plane must be orthogonal to both n and (1,2,3), where the latter is given by the line in the plane. Thus taking the cross product:

$$n_1 = n \times (1, 2, 3) = (5, -7, 3)$$

Hence the equation for the plane is given by:

$$5(x+1) - 7(y-2) + 3(z-1) = 0$$

simplifying we get 5x - 7y + 3z + 16 = 0.

**Problem 4.10.** Compute the area of the parallelogram spanned by the vectors (1, 1, 0), (0, 2, 1).

Proof. Since we know

$$||u \times v|| = ||u|| ||v|| \sin \theta$$

the length of the cross product is exactly the area of the parallelogram, thus computing

$$\|(1,1,0)\times(0,2,1)\| = \|(1,-1,2)\| = \sqrt{6}$$

**Problem 4.11.** Use the traingle inequality 2.4 to show the reverse triangle inequality:

$$\left| \|a\| - \|b\| \right| \le \|a - b\|$$

Proof. We know by traingle inequality

$$||a|| = ||(a - b) + b||$$
  
 $\leq ||a - b|| + ||b||$ 

rearranging, we get  $||a|| - ||b|| \le ||a - b||$ . Similarly

$$||b|| - ||a|| \le ||a - b||$$

Together this implies

$$\bigg| \|a\| - \|b\| \bigg| \leq \|a-b\|$$

Problem 4.12. Compute the following limits if they exist; if the limits don't exist, please explain why.

1.

$$\lim_{(x,y)\rightarrow (2,1)}\frac{x^2+y^2-2xy}{x-y}$$

2.

$$\lim_{(x,y)\to(0,0)} \frac{\cos x - 1}{x^2 + y^2}$$

3.

$$\lim_{(x,y)\to(0,0)} \frac{(x-y)^2}{(x+y)^2}$$

4.

$$\lim_{(x,y)\to (0,0)} \frac{\sin 2x - 2x + y}{x^3 + y}$$

5.

$$\lim_{(x,y,z)\to(0,0,0)} \frac{2x^2y\cos z}{x^2+y^2}$$

6.

$$\lim_{(x,y)\to(2,1)} \frac{x^2 - 2xy}{x^2 - 4y^2}$$

7.

$$\lim_{(x,y)\to(0,0)} \frac{x^2 - y^6}{xy^3}$$

Proof. 1.

$$\lim_{(x,y)\to(2,1)}\frac{x^2+y^2-2xy}{x-y}=\lim_{(x,y)\to(2,1)}\frac{(x-y)^2}{x-y}=\lim_{(x,y)\to(2,1)}x-y=1$$

2. The limit doesn't exist,

$$\lim_{(x,y)\to(0,0)} \frac{\cos x - 1}{x^2 + y^2}$$

Consider the path  $x = 0, y \rightarrow 0$ , we have

$$\lim_{x=0, y \to 0} \frac{0}{y^2} = 0$$

Consider the path  $y = 0, x \to 0$ ,

$$\lim_{y=0,x\to 0} \frac{\cos x - 1}{x^2} = \lim_{x\to 0} \frac{-\sin x}{2x} = \lim_{x\to 0} \frac{-\cos x}{2} = -\frac{1}{2}$$

3. The limit doesn't exist,

$$\lim_{(x,y)\to(0,0)} \frac{(x-y)^2}{(x+y)^2}$$

Consider the path  $x = 0, y \to 0$ ,

$$\lim_{x=0,y\to 0}\frac{y^2}{y^2}=1$$

Consider the path  $y = x \rightarrow 0$ ,

$$\lim_{x=y\to 0} \frac{0}{4x^2} = 0$$

4. The limit doesn't exist,

$$\lim_{(x,y)\to(0,0)} \frac{\sin 2x - 2x + y}{x^3 + y}$$

Consider the path  $x = 0, y \rightarrow 0$ ,

$$\lim_{x=0, y\to 0} \frac{y}{y} = 1$$

Consider the path  $y = 0, x \to 0$ ,

$$\lim_{y=0,x\to 0} \frac{\sin 2x - 2x}{x^3} = \lim_{x\to 0} \frac{2\cos 2x - 2}{3x^2}$$

$$= \lim_{x\to 0} \frac{-4\sin 2x}{6x}$$

$$= \lim_{x\to 0} \frac{-8\cos 2x}{6}$$

$$= -\frac{4}{3}$$

5.

$$\lim_{(x,y,z)\to(0,0,0)} \frac{2x^2y\cos z}{x^2+y^2}$$

Writing  $x = r \cos \theta$ ,  $y = r \sin \theta$  in polar coordinates, we can rewrite this as

$$\left| \frac{2r^3 \cos^2 \theta \sin \theta \cos z}{r^2} \right| = |2r \cos^2 \theta \sin \theta \cos z| \le 2r \to 0$$

as  $(x, y, z) \rightarrow (0, 0, 0)$ . Thus the limit is 0.

6.

$$\lim_{(x,y)\to(2,1)} \frac{x^2 - 2xy}{x^2 - 4y^2}$$

We factor:

$$\lim_{(x,y)\to(2,1)}\frac{x^2-2xy}{x^2-4y^2}=\lim_{(x,y)\to(2,1)}\frac{(x-2y)x}{(x+2y)(x-2y)}=\lim_{(x,y)\to(2,1)}\frac{x}{x+2y}=\frac{1}{2}$$

7. The limit doesn't exist,

$$\lim_{(x,y)\to(0,0)} \frac{x^2 - y^6}{xy^3}$$

Consider  $x = y \rightarrow 0$ , then

$$\lim_{x=y\to 0} \frac{x^2 - x^6}{x^4} = \lim_{x\to 0} \frac{1 - x^4}{x^2} = \infty$$

Consider  $x = y^3 \rightarrow 0$ , then

$$\lim_{x=y^3\to 0}\frac{0}{y^6}=0$$

**Problem 4.13.** (a) Show that  $f: \mathbb{R} \to \mathbb{R}$ ,

$$f(x) = (1 - x)^8 + \cos(1 + x^3)$$

is continuous.

(b) Show  $f: \mathbb{R} \to \mathbb{R}$ ,

$$f(x) = \frac{x^2 e^x}{2 - \sin x}$$

is continuous.

(a)  $(1-x)^8$  is a polynomial, thus continuous, and  $\cos x$ ,  $1+x^3$  are both continuous, thus the composition  $cos(1 + x^3)$  is also continuous. Thus adding continuous functions gives another continuous

(b)  $x^2e^x$ ,  $2-\sin x$  are both continuous, and  $\frac{x^2e^x}{2-\sin x}$  is continuous if  $2-\sin x\neq 0$  for all x. This is indeed true because  $-1\leq \sin x\leq 1$ , thus  $1\leq 2-\sin x\leq 3$ .

Problem 4.14. Compute all the partial derivatives.

1. 
$$w = e^{xy} \log(x^2 + y^2)$$
.  
2.  $w = \cos(ye^{xy}) \sin x$ .

2. 
$$w = \cos(ye^{xy})\sin x$$

Proof. 1.

$$\frac{\partial w}{\partial x} = ye^{xy}\ln(x^2 + y^2) + e^{xy}\frac{2x}{x^2 + y^2}$$

and

$$\frac{\partial w}{\partial y} = xe^{xy}\ln(x^2 + y^2) + e^{xy}\frac{2y}{x^2 + y^2}$$

2.

$$\frac{\partial w}{\partial x} = -y^2 e^{xy} \sin(ye^{xy}) \sin x + \cos(ye^{xy}) \cos x$$

and

$$\frac{\partial w}{\partial y} = -(1+xy)e^{xy}\sin(ye^{xy})\sin x$$

**Problem 4.15.** Compute the gradient of  $h(x, y, z) = (x + z)e^{x-y}$  at (1, 1, 0).

Proof. The gradient is

$$\begin{split} \nabla h(x,y,z) &= \begin{bmatrix} \frac{\partial h}{\partial x} & \frac{\partial h}{\partial y} & \frac{\partial h}{\partial z} \end{bmatrix} \\ &= \begin{bmatrix} e^{x-y}(1+x+z) & -(x+z)e^{x-y} & e^{x-y} \end{bmatrix} \end{split}$$

Thus

$$\nabla h(1,1,0) = \begin{bmatrix} 2 & -1 & 1 \end{bmatrix}$$

**Problem 4.16.** Determine the velocity vector of the given path:

$$c(t) = (\cos 2t, 3t^2 - t, -t)$$

*Proof.* It is given by

$$c'(t) = (-2\sin 2t, 6t - 1, -1)$$

**Problem 4.17.** Find the tangent line to the given path at t = 0

$$c(t) = (e^t \sin t, 2t, -t^3)$$

*Proof.* By the equation in Definition 1.20, we have

$$c'(t) = (e^t \sin t + e^t \cos t, 2, -3t^2)$$

and c(0) = (0,0,0), c'(0) = (1,2,0). Thus the tangent line is given by

$$l(t) = (t, 2t, 0)$$

**Problem 4.18.** Compute the derivatives.

1. Let

$$f(u,v) = u^2v + 2v, \quad u = -x^2 + y, v = x + y$$

Compute  $\frac{\partial f}{\partial x}$ ,  $\frac{\partial f}{\partial y}$ .

2. Let

$$g(u, v) = (e^u, u + \sin v), \quad f(x, y, z) = (x^2, yz)$$

Compute  $D(g \circ f)$  at (0, 1, 0).

3. Let  $f: \mathbb{R}^3 \to \mathbb{R}$  and  $c(t) = \mathbb{R} \to \mathbb{R}^3$ . Suppose c(0) = (1, 2, 0), and

$$\nabla f(1,2,0) = (0,0,1), \quad c'(0) = (2,1,1)$$

Compute  $\frac{d(f \circ c)}{dt}$  at t = 0.

*Proof.* 1. We have

$$\frac{\partial f}{\partial x} = \frac{\partial f}{\partial u}\frac{\partial u}{\partial x} + \frac{\partial f}{\partial v}\frac{\partial v}{\partial x} = -4xuv + u^2 + 2$$

and

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial u} \frac{\partial u}{\partial y} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial y} = 2uv + u^2 + 2$$

(You might want to replace u, v with x, y, but I am lazy).

2. We have

$$D(g \circ f)(0,1,0) = Dg(f(0,1,0))Df(0,1,0)$$

where f(0, 1, 0) = (0, 0)

$$Dg(u,v) = \begin{bmatrix} e^u & 0 \\ 1 & \cos v \end{bmatrix}, \quad , Df(x,y,z) = \begin{bmatrix} 2x & 0 & 0 \\ 0 & z & y \end{bmatrix}$$

Thus

$$D(g \circ f)(0, 1, 0) = Dg(0, 0)Df(0, 1, 0)$$

$$= \begin{bmatrix} 1 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

3. We have

$$\frac{d(f \circ c)}{dt}(0) = \nabla f(1, 2, 0)c'(0) = \begin{bmatrix} 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} 2\\1\\1 \end{bmatrix} = 1$$

Problem 4.19. Determine the directional derivative of

$$f(x, y, z) = x^3y - xyz$$

at (1,1,0) along v = (0,-1,1)

*Proof.* First we compute

$$\nabla f(x, y, z) = (3x^2y - yz, x^3 - xz, -xy)$$

Thus

$$\nabla f(1,1,0) = (3,1,-1)$$

Recall the directional derivative is given by

$$\nabla f(1,1,0) \cdot \frac{v}{\|v\|} = -\frac{2}{\sqrt{2}}$$

We need to make sure that the direction vector is a unit vector!

Problem 4.20. Find a unit vector normal to the surface

$$xe^y + ye^z + ze^x = e + 1$$

at the point (0, 1, 1).

*Proof.* This is a level set for the multivariate function  $f(x, y, z) = xe^y + ye^z + ze^x$ . We compute the gradient

$$\nabla f(x, y, z) = (e^y + ze^x, e^z + xe^y, e^x + ye^z).$$

hence  $\nabla f(0,1,1) = (e+1,e,e+1)$ , and this vector is normal to the surface. To make this a unit vector, we normalize to get

$$\frac{\nabla f(0,1,1)}{\|\nabla f(0,1,1)\|} = \frac{1}{\sqrt{3e^2+4e+2}}(e+1,e,e+1),$$

**Problem 4.21.** Find the tangent plane of  $f(x, y, z) = \ln(x + y) - 2xz$  at (1, 2, -1).

*Proof.* By the equation given in Proposition 2.12, the point (1,2) lies on the level set

$$f(x,y) = 2 - \ln 3$$

In order to find a normal vector to the tangent plane, we compute the gradient of f at (1, 2, -1):

$$\nabla f(x,y) = \left(\frac{1}{x+y} - 2z, \frac{1}{x+y}, -2x\right)$$

and  $\nabla f(1,2,-1) = (\frac{7}{3},\frac{1}{3},-2)$ , thus the tangent plane is given by

$$\frac{7}{3}(x-1) + \frac{1}{3}(y-2) - 2(z+1) = 0$$

simplifying we get 7x + y - 6z - 15 = 0.

**Problem 4.22.** A function  $f: \mathbb{R}^n \to \mathbb{R}$  is called an *even* function if f(x) = f(-x) for every x in  $\mathbb{R}^n$ . If f is differentiable and even, find  $\nabla f$  at the origin.

*Proof.* We claim that  $\nabla f(0,\ldots,0)=0$ . It suffices to show that  $\nabla f(0,\ldots,0)\cdot v=\nabla f(0,\ldots,0)\cdot (-v)$  for any vector  $v\in\mathbb{R}^n$ . Because this implies  $2\nabla f(0,\ldots,0)\cdot v=0$  for every  $v\in\mathbb{R}^n$ , so  $Df(0,\ldots,0)=0$ . We know that

$$\left. \nabla f(0,\dots,0) \cdot v = \frac{d}{dt} f(tv) \right|_{t=0}, \quad \left. \nabla f(0,\dots,0)(-v) = \frac{d}{dt} f(-tv) \right|_{t=0}$$

But f(tv) = f(-tv) since f is even, thus

$$\nabla f(0, \dots, 0) \cdot v = \nabla f(0, \dots, 0) \cdot (-v)$$

as desired.  $\Box$ 

Problem 4.23. Consider the function

$$f(x,y) = \frac{1}{\log(x^2 + y)}.$$

Verify by hand that  $f_{xy} = f_{yx}$ .

*Proof.* We compute these separately.

$$f_x = \frac{2x}{x^2 + y}, \quad f_{xy} = -\frac{2x}{(x^2 + y)^2}$$

and

$$f_y = \frac{1}{x^2 + y}, \quad f_{yx} = -\frac{2x}{(x^2 + y)^2}$$

**Problem 4.24.** Consider the function  $f(x, y, z) = (x^2 + y^2 + z^2)^{-1/2}$ . Show that

$$f_{xx} + f_{yy} + f_{zz} = 0.$$

Proof. Note

$$f_x = -\frac{1}{2} \cdot \frac{2x}{(x^2 + y^2 + z^2)^{3/2}} = -\frac{x}{(x^2 + y^2 + z^2)^{3/2}},$$

so

$$f_{xx} = -\frac{\left(x^2 + y^2 + z^2\right)^{3/2} - x \cdot \frac{3}{2} \left(x^2 + y^2 + z^2\right)^{1/2} \cdot 2x}{\left(x^2 + y^2 + z^2\right)^3},$$

which is

$$f_{xx} = -\frac{x^2 + y^2 + z^2 - 3x^2}{\left(x^2 + y^2 + z^2\right)^{5/2}},$$

or

$$f_{xx} = -\frac{-2x^2 + y^2 + z^2}{(x^2 + y^2 + z^2)^{5/2}}.$$

By symmetry,

$$f_{yy} = -\frac{x^2 - 2y^2 + z^2}{(x^2 + y^2 + z^2)^{5/2}},$$

and

$$f_{zz} = -\frac{x^2 + y^2 - 2z^2}{(x^2 + y^2 + z^2)^{5/2}},$$

so we see that  $f_{xx} + f_{yy} + f_{zz} = 0$ .

Problem 4.25. Find the second-order Taylor expansion for the function

$$f(x,y) = x^2 + 2xy$$

at (1, 1).

*Proof.* First f(1,1) = 3, then we find all first-order and second-order partial derivatives:

$$f_x = 2x + 2y, f_y = 2x, f_{xx} = 2, f_{xy} = 2, f_{yy} = 0$$

Thus by formula in Definition 1.23, we have

$$f(x,y) = 3 + 4(x-1) + 2(y-1) + \frac{1}{2}2(x-1)^2 + \frac{1}{2}2(x-1)(y-1) + \frac{1}{2}2(x-1)(y-1) + R_2((1,1),(x,y))$$
  
= 3 + 4(x-1) + 2(y-1) + (x-1)^2 + 2(x-1)(y-1) + R\_2((1,1),(x,y))

where

$$\frac{R_2((1,1),(x,y))}{\|(x-1,y-1)\|} \to 0$$

as 
$$(x,y) \to (1,1)$$
.

### **Chapter 5**

# Tips

1. When asked to find the limit:

Step 1: Factor out common factor, for example,

$$\frac{x^2 - 2xy}{x^2 - 4y^2} = \frac{(x - 2y)x}{(x - 2y)(x + 2y)} = \frac{x}{x + 2y}$$

Step 2: Try the following four paths: take  $(x, y) \rightarrow (0, 0)$  as an example,

i. 
$$x = 0, y \to 0$$
.

ii. 
$$y = 0, x \to 0$$
.

iii. 
$$x = y \rightarrow 0$$
.

iv. 
$$x = -y \to 0$$
.

Step 3: Try to put into expressions that you are familiar with, for example,

$$\lim_{(x,y)\rightarrow (0,0)}\frac{\sin xy}{x}=\lim_{(x,y)\rightarrow (0,0)}\frac{\sin xy}{xy}y$$

and use the fact that  $\lim_{t\to 0} \frac{\sin t}{t} = 1$ .

If any two paths give different limits, then the limit doesn't exist. Step 2:

- 2. When asked to find a directional derivative of f along v: make sure you normalize v as  $\frac{v}{\|v\|}$ .
- 3. When asked to find an equation for a plane: identify a normal vector by
  - (a) taking the cross product of two vectors in the plane 1.8.
  - (b) computing the gradient if the plane is the tangent plane to a level surface 2.12.
- 4. Let  $f:U\subset\mathbb{R}^n\to\mathbb{R}^m$  be differentiable, then Df is an  $m\times n$  matrix. Let A be an  $m\times n$  matrix and B be a  $k\times p$  matrix, then the matrix multiplication AB only makes sense when n=k.