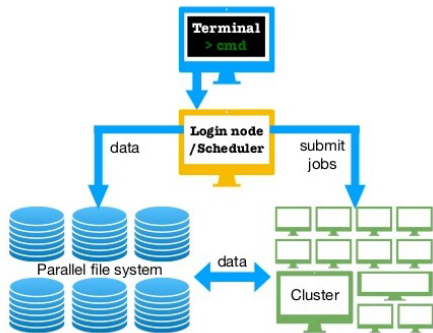


SC3260 / SC5260

Batch Scheduler

Lecture by: Ana Gainaru



► HPC system middleware

► Distributed operating system

- Memory management, processes and communication management

► Parallel file system

- Access performance, resiliency, security

► Scheduler

► Daemons on compute nodes

- Performance monitoring, fault tolerance



Batch Scheduling

- ▶ From the **user's perspective**
 - ▶ Submission principles
 - ▶ Performance
- ▶ From the **system's perspective**
 - ▶ Principles
 - ▶ Brief theoretical results
 - ▶ Currently used schedulers
 - ▶ How good is a schedule?



Why are schedulers needed?



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Why are schedulers needed?

- ▶ Performance
- ▶ Fairness (every user wants to be on a dedicated machine)



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From the system's perspective

Administrators want to keep the system utilized

- ▶ Utilization (max) : percentage of the CPU time that is spent computing
- ▶ Power consumption (min)
- ▶ User fairness : give space on the machine to all users



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From the system's perspective

Administrators want to keep the system utilized

- ▶ Utilization (max) : percentage of the CPU time that is spent computing
- ▶ Power consumption (min)
- ▶ User fairness : give space on the machine to all users

From the user's perspective

Users want their job to compute as fast as possible

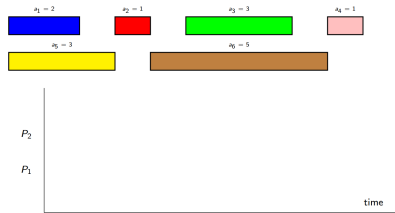
- ▶ Makespan (min) : time to complete the job from start to end
- ▶ Response time (min) : time to complete the job from submission to end
- ▶ Stretch (min) : ration between the response time and the ideal execution time



Scheduling policies

The scheduler can be used to balance all the metrics

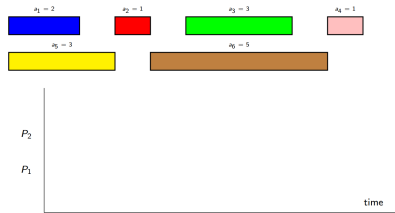
- ▶ User fairness
- ▶ System utilization
- ▶ Application response time



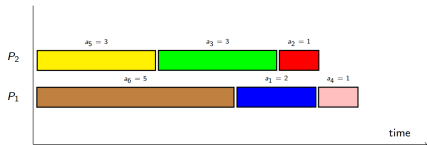
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Longest job first

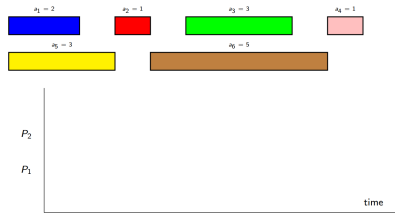


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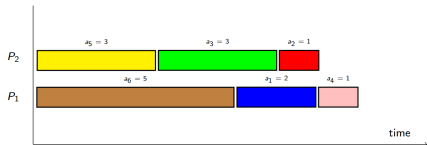
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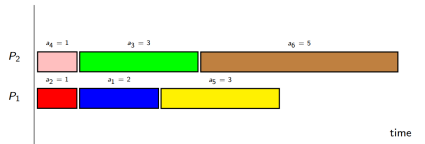
- ▶ User fairness
- ▶ System utilization
- ▶ Application response time



Longest job first



Shortest job first



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Batch Schedulers

- ▶ Applications in HPC systems are run as batch jobs, i.e. time-limited requests for resources to run the application binaries.
- ▶ Once an application is submitted on a cluster it becomes a job
- ▶ Each job is defined as a **Number of nodes** (p_i) and a **Time** (t_i)
I want 6 nodes for 1h

Typically users are charged against an allocation: e.g. "You only get 100 CPU hours per week"

A batch scheduler is a central middleware to manage resources (e.g. processors)

- ▶ accept jobs (computing tasks) submitted by users
- ▶ decide when and where jobs are executed
- ▶ start jobs execution



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Batch Schedulers

Schedulers take into account:

- ▶ unavailability of some nodes
- ▶ users jobs mutual exclusion
- ▶ specific needs for jobs (memory, network, ...)

While trying to :

- ▶ maximize resources usage
- ▶ be fair among users

To run multiple applications concurrently, **HPC schedulers order the execution of batch jobs** to achieve high utilization while controlling their turnaround times



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Batch Schedulers

Typical wanted features:

- ▶ Interactive mode
- ▶ Batch mode
- ▶ Parallel jobs support
- ▶ Multi-queues with priorities
- ▶ Reservations
- ▶ Admission policies (limit on usage, notions of user groups)
- ▶ Resources matching
- ▶ File staging
- ▶ Jobs dependences
- ▶ Backfilling
- ▶ Environment reconfiguration

There are many existing batch schedulers: Slurm, LSF, Moab, PBS/Torque, EASY, OAR, ...

These are complex systems with many config options !



Batch Scheduler Components

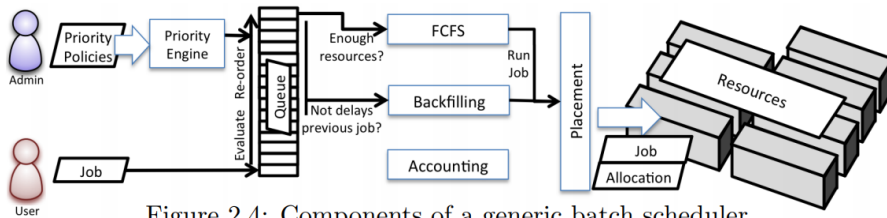


Figure 2.4: Components of a generic batch scheduler.



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Life-cycle of a batch job

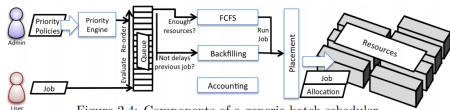


Figure 2.4: Components of a generic batch scheduler.

1) Job submission to the system

The job submission must provide

- ▶ Detailed specification of the requested resources (e.g. the number of cores, minimum RAM per core, or specific compute nodes to run on)
- ▶ An estimate of the job's runtime
- ▶ A priority request (expressing the job's importance)
- ▶ Optionally, a list of dependencies on other jobs (e.g. statements that the job should not start until some set of conditions is met)



Life-cycle of a batch job

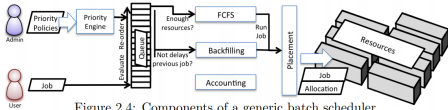


Figure 2.4: Components of a generic batch scheduler.

2) The scheduler contacts the resource manager

- ▶ If no other jobs are waiting and there are enough resources available, the scheduler runs the job immediately
- ▶ If there are holes in a schedule that would fit the current job, the job is ran immediately (backfilling)
- ▶ Otherwise, the job is appended to a job waiting queue



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Life-cycle of a batch job

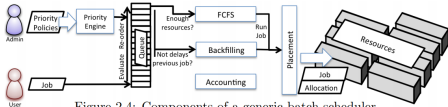


Figure 2.4: Components of a generic batch scheduler.

3) Jobs placed in the waiting queue

- ▶ Jobs in the waiting queue are initially ordered by arrival time
- ▶ Jobs are ranked and re-ordered by a priority engine
- ▶ Different ranking policies define priorities, based on
 - ▶ job size (e.g. smaller jobs should run sooner)
 - ▶ priority class (e.g. jobs in the real time class should run before any other job)
 - ▶ fairness (i.e. priorities dictated by system quotas)
 - ▶ wait time in the queue (jobs that have been waiting a long time to start)
 - ▶ other administrator-defined criteria

Life-cycle of a batch job

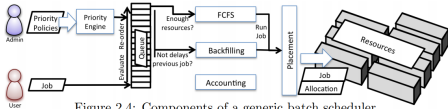


Figure 2.4: Components of a generic batch scheduler.

4) Jobs are allocated on the compute nodes

- ▶ Jobs progress towards the top area of the waiting queue until they are extracted by the scheduling algorithms and then executed
- ▶ Online or reservation-based placement decision
- ▶ Scheduler informs the resource manager about the new placement

Most HPC batch schedulers include the FCFS (First Come First Served) and backfilling scheduling algorithms with different priority re-ordering



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There are usually many jobs in the queue waiting for resources to become available

Online Scheduler

- ▶ When a job finishes, the scheduler chooses the first job in the queue to execute that fits the available resources
- ▶ To make sure that large jobs do not starve, the scheduler divided all jobs in the queue in batches
- ▶ **Advantage** Easy to implement, fast, the resource requests of jobs don't need to be accurate
- ▶ **Disadvantage** Local optimal execution, not the best utilization nor makespan



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There are usually many jobs in the queue waiting for resources to become available

Reservation-based Scheduler

- ▶ On job arrival and when a job finishes, the scheduler computes tentative start times for all (most of) the jobs in the queue in order to maximize utilization. **These start times are called reservations**
- ▶ Jobs start within their assigned reservations
- ▶ **Advantage** Gives the best job placements, fair and starvation free algorithm
- ▶ **Disadvantage** More complex and slower (cut of in the waiting queue), resource requests must reflect resource usage



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There are usually many jobs in the queue waiting for resources to become available

Reservation-based Scheduler

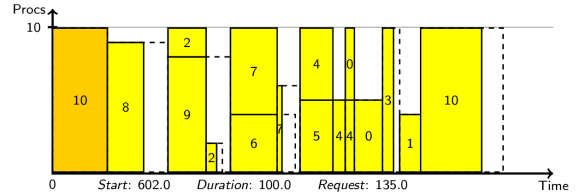
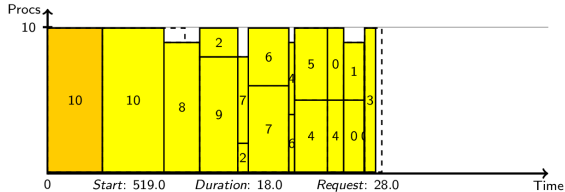
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Most schedulers are reservation-based using priority queues and backfilling



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Online / Reservation-based



Placement of 11 jobs using online or reservation-based strategies.

- The reservations are computed only during job arrival and not job ending

Stochastic jobs will get better results from online schedulers



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Online / Reservation-based

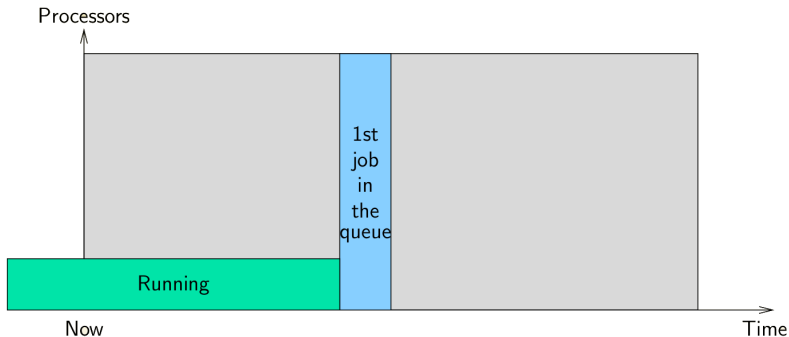
- ▶ FCFS = simplest scheduling option
- ▶ **Fragmentation** = need for backfilling



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Online / Reservation-based

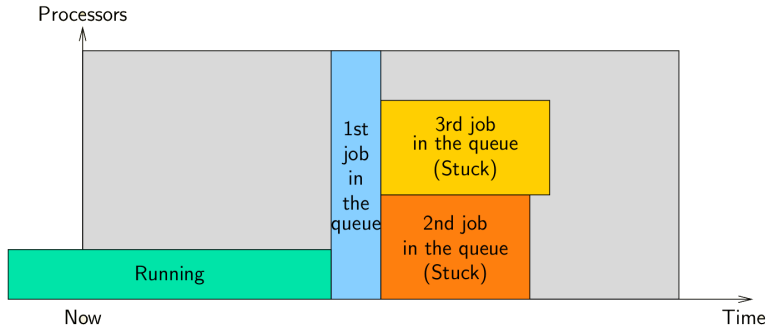
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Online / Reservation-based

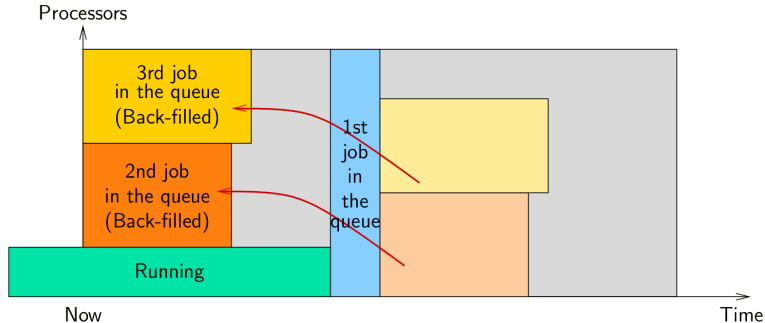
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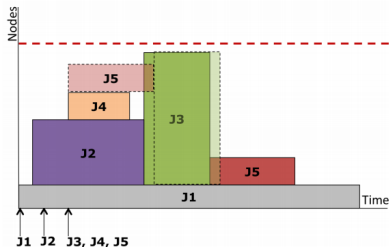
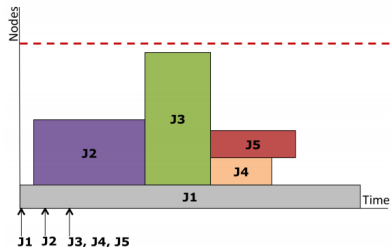
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Additional functions

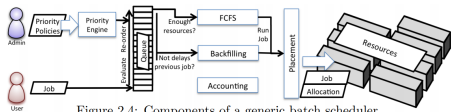


Figure 2.4: Components of a generic batch scheduler.

Mechanisms that are needed to manage an HPC system

- ▶ Placement systems that calculate which resources should be used for specific jobs.
 - ▶ These decisions take into account the network topology or special job requirements
 - ▶ Example: in a system with a fat-tree interconnect topology, a tightly coupled application will run faster if all its assigned nodes are leaves pending from same network switch
- ▶ Workload managers include functions to handle the basic operations to run an HPC system, such as managing the compute resources, staging-in jobs, controlling their execution, and staging-out resources



Additional functions

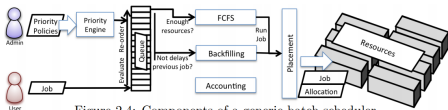


Figure 2.4: Components of a generic batch scheduler.

HPC Accounting for registering the use of compute hours and resources by user jobs

- ▶ Prevent users from utilizing the system beyond their assigned quota (e.g. by de-prioritizing their jobs)
- ▶ Encourage those who have not used it (e.g. by elevating the priority of users with little quota usage)



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Backfilling policies

Which job(s) should be picked for promotion through the queue?



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Which job(s) should be picked for promotion through the queue?

- ▶ Many heuristics are possible
- ▶ Two have been studied in detail
 - ▶ EASY
 - ▶ Conservative Back Filling (CBF)
- ▶ In practice EASY is used in almost all current schedulers
- ▶ The OAR scheduler (used by french clusters) uses CBF



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Extensible Argonne Scheduling System

Maintain only one reservation, for the first job in the queue.

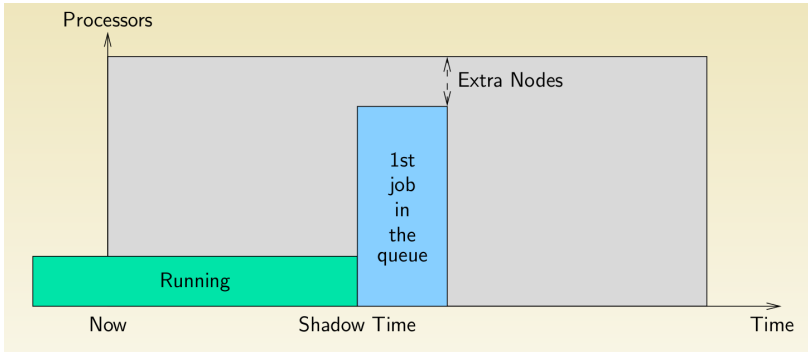
Definitions:

- ▶ **Shadow time** time at which the first job in the queue starts execution
- ▶ **Extra nodes** number of nodes idle when the first job in the queue starts execution

Policy

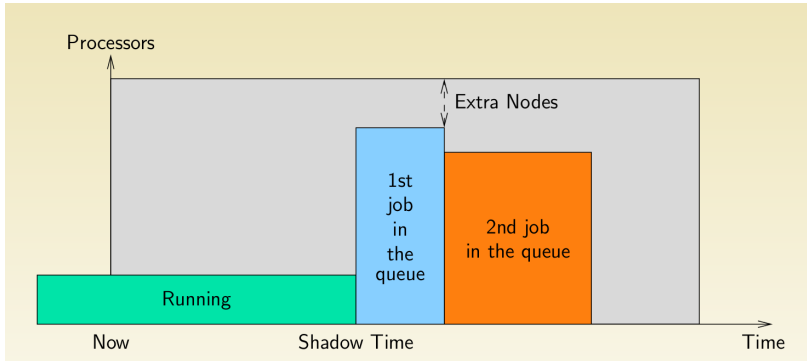
- 1 Go through the queue in order starting with the 2nd job.
- 2 Backfill a job if it will terminate by the shadow time, or it needs less than the extra nodes.





Property

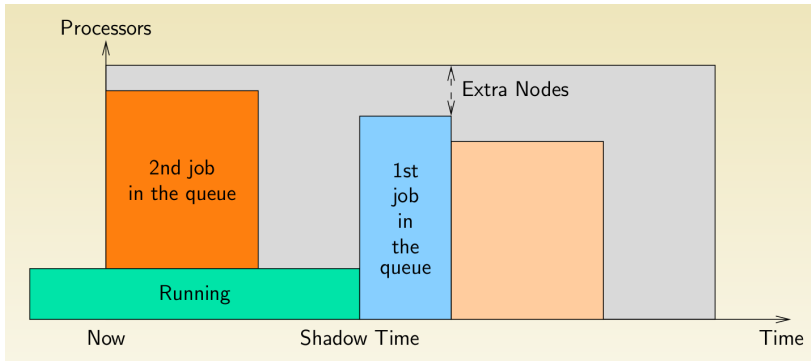
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Property

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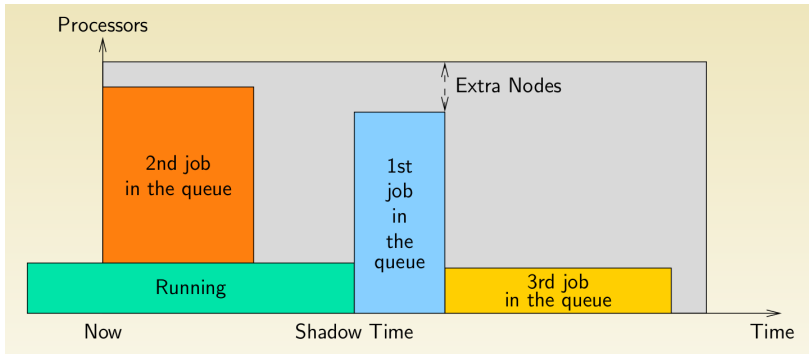




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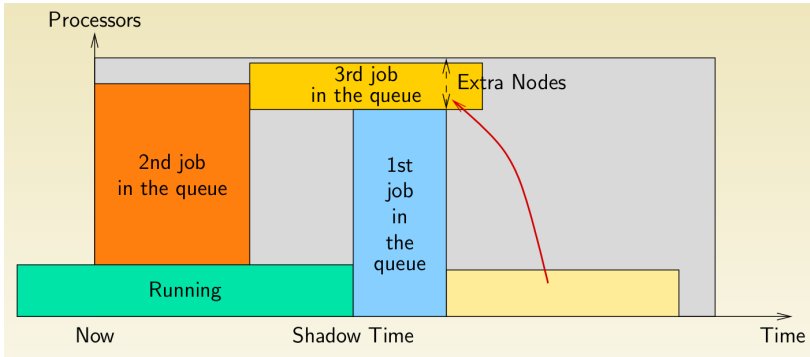
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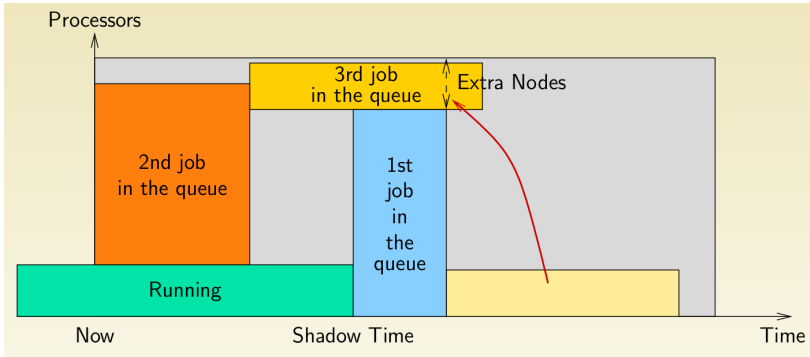
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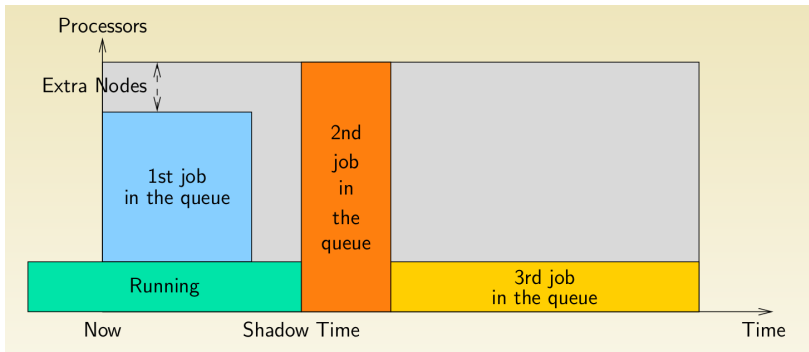
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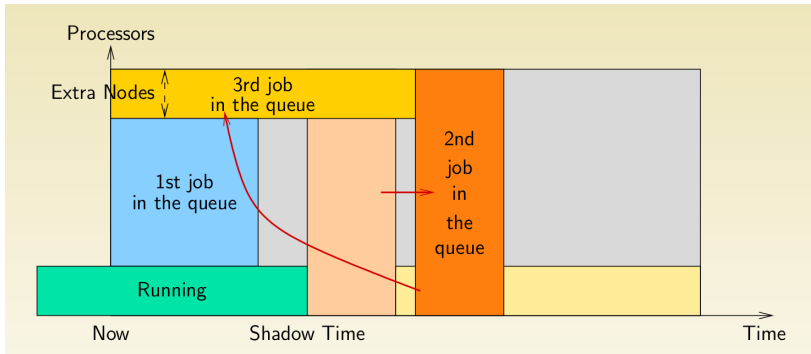
Property

- ▶ The first job in the queue will never be delayed by backfilled jobs
- ▶ **BUT, other jobs may be delayed infinitely!**



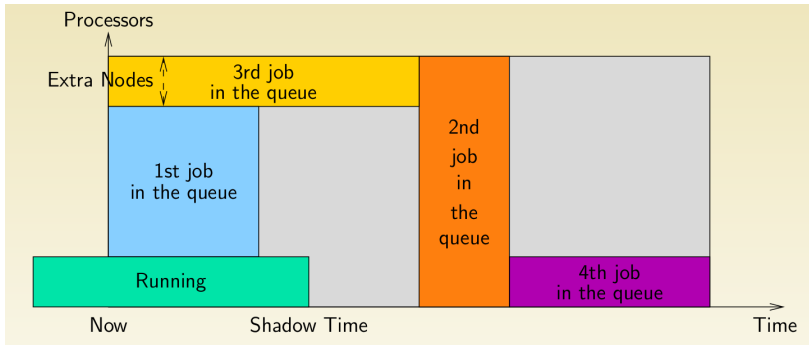
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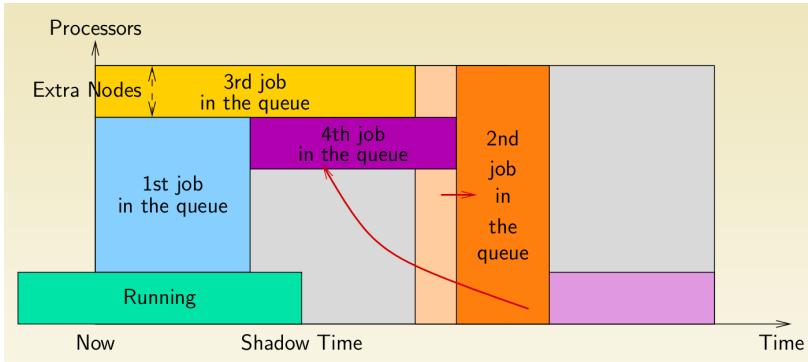
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Property

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Unbounded Delay

- ▶ The first job in the queue will never be delayed by backfilled jobs
- ▶ BUT, other jobs may be delayed infinitely!

No starvation

- ▶ Delay of first job is bounded by runtime of current jobs
- ▶ When the first job finishes, the second job becomes the first job in the queue
- ▶ Once it is the first job, it cannot be delayed further



Other backfilling approach

Conservative Backfilling

- ▶ EVERY job has a reservation. A job may be backfilled only if it does not delay any other job ahead of it in the queue
- ▶ Fixes the unbounded delay problem that EASY has. More complicated to implement (The algorithm must find holes in the schedule) though.
- ▶ EASY favors small long jobs and harms large short jobs.



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How Good is the Schedule?



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When does backfilling happen?

Possibly when

- ▶ A new job arrives
- ▶ The first job in the queue starts
- ▶ When a job finishes early



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When does backfilling happen?

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- ▶ The first job in the queue starts
- ▶ When a job finishes early

Users provide job **runtime estimates** (Jobs are killed if they go over). Trade-off:

- ▶ provide a **conservative estimate**: goes through the queue faster (may be backfilled)
- ▶ provide a **loose estimate**: your job will not be killed



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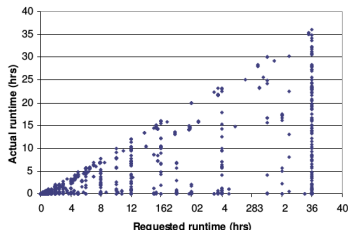
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Measure performance

... but how do we know what a "good" schedule is? FCFS, EASY, CFB, Random?

What we need are metrics to quantify how good a schedule is. It has to be an aggregate metric over all jobs



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1 Turn-around time or flow (Wait time + Run time)

Job 1 needs 1h of compute time and waits 1s

Job 2 needs 1s of compute time and waits 1h

Clearly Job 1 is really happy, and Job 2 is not happy at all



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Job 1 needs 1h of compute time and waits 1s

Job 2 needs 1s of compute time and waits 1h

Clearly Job 1 is really happy, and Job 2 is not happy at all

❷ **Wait time** (equivalent to "user happiness")

Job 1 asks for 1 nodes and waits 1 h

Job 2 asks for 512 nodes and waits 1h

Again, Job 1 is unhappy while Job 2 is probably sort of happy.

We need a metric that represents happiness for small, large, short, long jobs



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Measure performance

- ▶ **Slowdown or Stretch** (turn-around time divided by turn-around time if alone in the system)
Doesn't really take care of the small/large problem.
Could think of some scaling, but unclear !

For now this is all we have



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Measure performance

- ▶ **Slowdown or Stretch** (turn-around time divided by turn-around time if alone in the system)
Doesn't really take care of the small/large problem.
Could think of some scaling, but unclear !

For now this is all we have We can run simulations of the scheduling algorithms, and see how they fare. We need to test these algorithms in representative scenarios Supercomputer/cluster traces. Collect the following for long periods of time:

- ▶ Time of submission
- ▶ How many nodes asked
- ▶ How much time asked
- ▶ How much time was actually used
- ▶ How much time spent in the queue



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Measure performance

Example experiment: replace user estimate by f times the actual run time Possible to improve performance by multiplying user estimates by 2!

	EASY	CBF
Mean Slowdown		
KTH	-4.8%	-23.0%
CTC	-7.9%	-18.0%
SDSC	+4.6%	-14.2%
Mean Response time		
KTH	-3.3%	-7.0%
CTC	-0.9%	-1.6%
SDSC	-1.6%	-10.9%



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Performance of Schedulers

- ▶ All the schedulers presented are all heuristics
 - ▶ They are not specifically designed to optimize the metrics we have designed
- ▶ It is difficult to truly understand the reasons for the results.
- ▶ But one can derive some empirical wisdom.

- ▶ One of the reasons why one is stuck with possibly obscure heuristics is that we're dealing with an on-line problem
- ▶ We cannot wait for all jobs to be submitted to make a decision
- ▶ But we can wait for a while, accumulate jobs, and schedule them together.



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Batch Schedulers are what we're stuck with at the moment

They are often hated by users

- ▶ I submit to the queue asking for 10 nodes for 1 hour.
- ▶ I wait for two days.
- ▶ My code finally starts, but doesn't finish within 1 hour and gets killed!!



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A lot of research (and theoretical results), a few things happening "in the field".

When you go to a company that has clusters (like most of them), they typically have a job scheduler, so it's good to have some idea of what it is.



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- ① SLURM and how to use it
- ② A few promising directions for the future
 - ▶ Gang scheduling
 - ▶ Task based scheduler (work stealing)



Book on the theory of scheduling

D.B. Shmoys, J. Wein, and D.P. Williamson. *Scheduling parallel machines on-line* Symposium on Foundations of Computer Science, 0:131-140, 1991.

Figures from today's slides courtesy of Arnaud Legrand and Guillaume Pallez

http://people.bordeaux.inria.fr/gaupy/ressources/teachings/2019/algo_hpc/



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