

Supplementary of “WPML³CP: Wasserstein Partial Multi-Label Learning with Dual Label Correlation Perspectives”

A Optimization of Regularized Wasserstein Distance

In this section, we present the optimization details of regularized Wasserstein distance:

$$W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K) = \inf_{\mathbf{T} \in U(\boldsymbol{\mu}, \boldsymbol{\nu})} \langle \mathbf{T}, \mathbf{M}_K \rangle - \frac{1}{\lambda} H(\mathbf{T}). \quad (1)$$

We convert the above regularized Wasserstein distance into its dual problem, and solve them as well as optimize the parameters $\{\boldsymbol{\mu}, \boldsymbol{\nu}, \mathbf{M}_K\}$ by employing the Sinkhorn’s algorithm [Cuturi, 2013; Cuturi and Doucet, 2014].

Following [Cuturi and Doucet, 2014], its dual problem can be formulated by:

$${}^dW_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K) = \sup_{(\boldsymbol{\alpha}, \boldsymbol{\beta})} \boldsymbol{\alpha}^\top \boldsymbol{\mu} + \boldsymbol{\beta}^\top \boldsymbol{\nu} - \sum_{i,j} \frac{e^{-\lambda(\mathbf{M}_K(i,j) - \alpha_i - \beta_j)}}{\lambda}.$$

Then, the regularized Wasserstein distance and its dual problem can be both efficiently solved by the Sinkhorn’s algorithm with $O(K^2)$ complexity [Cuturi, 2013; Cuturi and Doucet, 2014]. Thanks to their efficient computations, one can utilize this regularized Wasserstein distance as the loss function under various learning paradigms. Specifically, given models with parameters of interest, *i.e.*, denoted by $\{\boldsymbol{\mu}, \boldsymbol{\nu}, \mathbf{M}_K\}$, we can optimize them by leveraging their subgradients of $W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)$, being equivalent to the optimum $\{\boldsymbol{\alpha}^*, \boldsymbol{\beta}^*, \mathbf{T}^*\}$ of the dual problem ${}^dW_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)$ [Bertsimas and Tsitsiklis, 1997; Cuturi and Doucet, 2014; Frogner *et al.*, 2015]:

$$\frac{\partial W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)}{\partial \boldsymbol{\mu}} \triangleq \boldsymbol{\alpha}^* = -\frac{\log(\mathbf{a})}{\lambda} + \frac{\log(\mathbf{a})^\top \mathbf{1}}{\lambda K} \mathbf{1}, \quad (2)$$

$$\frac{\partial W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)}{\partial \boldsymbol{\nu}} \triangleq \boldsymbol{\beta}^* = -\frac{\log(\mathbf{b})}{\lambda} + \frac{\log(\mathbf{b})^\top \mathbf{1}}{\lambda K} \mathbf{1}, \quad (3)$$

$$\frac{\partial W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)}{\partial \mathbf{M}_K} \triangleq \mathbf{T}^* = \text{diag}(\mathbf{a}) \mathbf{K} \text{diag}(\mathbf{b}), \quad (4)$$

where $\mathbf{a}, \mathbf{b} \in \mathbb{R}_+^K$ can be computed by solving a matrix balancing problem with the Sinkhorn’s algorithm [Cuturi, 2013; Cuturi and Doucet, 2014]:

$$(\mathbf{a}, \mathbf{b}) \leftarrow (\boldsymbol{\mu} \oslash \mathbf{K} \mathbf{b}, \boldsymbol{\nu} \oslash \mathbf{K}^\top \mathbf{a}), \quad (5)$$

$\mathbf{K} = e^{-\lambda \mathbf{M}_K}$ denotes the element-wise exponential of $-\lambda \mathbf{M}_K$, and \oslash represents the element-wise division. For clarity, the full computation process of subgradients is summarized in *Algorithm 1*.

Algorithm 1 Regularized Wasserstein distance’s subgradient

Input: parameters $\{\boldsymbol{\mu}, \boldsymbol{\nu}\}$, matrix $\mathbf{K} = e^{-\lambda \mathbf{M}_K}$ and regularization parameter $\lambda > 0$;

1: **Initialize** $\mathbf{a} = \mathbf{1}, \mathbf{b} = \mathbf{1}$;

2: **while** $\{\mathbf{a}, \mathbf{b}\}$ have not converged **do**

3: $(\mathbf{a}, \mathbf{b}) \leftarrow (\boldsymbol{\mu} \oslash \mathbf{K} \mathbf{b}, \boldsymbol{\nu} \oslash \mathbf{K}^\top \mathbf{a})$, *i.e.*, Eq.(5)

4: **end while**

Output: $\frac{\partial W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)}{\partial \boldsymbol{\mu}}, \frac{\partial W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)}{\partial \boldsymbol{\nu}}, \frac{\partial W_\lambda(\boldsymbol{\mu}, \boldsymbol{\nu}; \mathbf{M}_K)}{\partial \mathbf{M}_K}$, *i.e.*, Eqs.(2), (3) and (4)

B Optimization of WPML³CP

In this section, we describe the optimization details of WPML³CP. We first revisit the objective of WPML³CP:

$$\begin{aligned} \min_{\mathbf{W}, \mathbf{Q}, \mathbf{C}, \mathbf{E}} \quad & \sum_{i=1}^n W_\lambda(\mathbf{s}(\mathbf{q}_i), \mathbf{s}(\mathbf{W} \mathbf{x}_i); \mathbf{m}(\mathbf{C})) \\ & + \frac{\beta_1}{2} \sum_{i=1}^l \sum_{j=1}^l \mathbf{C}_{ij} \|\mathbf{w}_i - \mathbf{w}_j\|_2^2 + \frac{\beta_2}{2} \|\mathbf{W}\|_F^2 \\ & + \beta_3 \|\mathbf{Q}\|_* + \beta_4 \|\mathbf{E}\|_1 \\ \text{s.t.} \quad & \mathbf{Y} = \mathbf{Q} + \mathbf{E}. \end{aligned} \quad (6)$$

By employing the LADMAP method [Lin *et al.*, 2011] over its augmented Lagrangian, we reformulate the optimization problem in Eq.(6) as follows:

$$\begin{aligned} \min_{\mathbf{W}, \mathbf{Q}, \mathbf{C}, \mathbf{E}, \mathbf{H}} \quad & \sum_{i=1}^n W_\lambda(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W} \mathbf{x}_i); \mathbf{m}(\mathbf{C})) + \frac{\beta_1}{2} \text{tr}(\mathbf{W}^\top \mathbf{L} \mathbf{W}) \\ & + \frac{\beta_2}{2} \|\mathbf{W}\|_F^2 + \beta_3 \|\mathbf{Q}\|_* + \beta_4 \|\mathbf{E}\|_1 \\ & + \frac{\mu_1}{2} \|\mathbf{Y} - \mathbf{Q} - \mathbf{E}\|_F^2 + \frac{\mathbf{Y}_1}{\mu_1} \\ & + \frac{\mu_2}{2} \|\mathbf{Q} - \mathbf{H}\|_F^2 + \frac{\mathbf{Y}_2}{\mu_2}, \end{aligned} \quad (7)$$

where $\mathbf{L} = \text{diag}(\mathbf{C} \mathbf{1}) - \mathbf{C}$ is the Laplacian matrix of \mathbf{C} . Accordingly, we employ the gradient decent approach to optimize $\{\mathbf{W}, \mathbf{C}, \mathbf{H}\}$, whose gradients can be easily calculated with some simple derivations and the Sinkhorn algorithm in *Algorithm 1*, and update $\{\mathbf{Q}, \mathbf{E}\}$ as well as $\{\mathbf{Y}_1, \mathbf{Y}_2, \mu_1, \mu_2\}$

with the linear ADM method following [Liu *et al.*, 2010a]. Details are described in the following part.

Updating \mathbf{W} : Fixing $\{\mathbf{Q}, \mathbf{C}, \mathbf{E}, \mathbf{H}\}$ as constants, the subproblem of Eq.(7) with respect to \mathbf{W} can be compactly formulated as follows:

$$\min_{\mathbf{W}} \sum_{i=1}^n W_{\lambda}(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i); \mathbf{m}(\mathbf{C})) + \frac{\beta_1}{2} \text{tr}(\mathbf{W}^{\top} \mathbf{L} \mathbf{W}) + \frac{\beta_2}{2} \|\mathbf{W}\|_F^2. \quad (8)$$

After some simple derivations, the gradient of \mathbf{W} can be computed based on the chain rule:

$$g(\mathbf{W}) = \sum_{i=1}^n \left(g(\mathbf{s}(\mathbf{W}\mathbf{x}_i)) \times \frac{\partial \mathbf{s}(\mathbf{W}\mathbf{x}_i)}{\partial (\mathbf{W}\mathbf{x}_i)} \right) \mathbf{x}_i^{\top} + \frac{\beta_1}{2} (\mathbf{L}\mathbf{W} + \mathbf{L}^{\top} \mathbf{W}) + \beta_2 \mathbf{W}, \quad (9)$$

where

$$g(\mathbf{s}(\mathbf{W}\mathbf{x}_i)) = \frac{\partial W_{\lambda}(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i); \mathbf{m}(\mathbf{C}))}{\partial \mathbf{s}(\mathbf{W}\mathbf{x}_i)}.$$

Then, \mathbf{W} can be updated with the gradient decent method as:

$$\mathbf{W} \leftarrow \mathbf{W} - \rho_t g(\mathbf{W}). \quad (10)$$

Updating \mathbf{H} : When keeping $\{\mathbf{W}, \mathbf{Q}, \mathbf{C}, \mathbf{E}\}$ fixed, the subproblem of Eq.(7) with respect to \mathbf{H} is given by:

$$\min_{\mathbf{H}} \sum_{i=1}^n W_{\lambda}(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i); \mathbf{m}(\mathbf{C})) + \frac{\mu_2}{2} \|\mathbf{Q} - \mathbf{H} + \frac{\mathbf{Y}_2}{\mu_2}\|_F^2. \quad (11)$$

With some simple derivations, we can compute the gradient of \mathbf{H} by leveraging the chain rule:

$$g(\mathbf{H}) = \sum_{i=1}^n g(\mathbf{s}(\mathbf{h}_i)) \times \frac{\partial \mathbf{s}(\mathbf{h}_i)}{\partial \mathbf{h}_i} - \mu_2 (\mathbf{Q} - \mathbf{H} + \frac{\mathbf{Y}_2}{\mu_2}), \quad (12)$$

where

$$g(\mathbf{s}(\mathbf{h}_i)) = \frac{\partial W_{\lambda}(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i); \mathbf{m}(\mathbf{C}))}{\partial \mathbf{s}(\mathbf{h}_i)}.$$

Consequently, we can update \mathbf{H} with:

$$\mathbf{H} \leftarrow \mathbf{H} - \rho_t g(\mathbf{H}). \quad (13)$$

Updating \mathbf{C} : Fixing $\{\mathbf{W}, \mathbf{Q}, \mathbf{E}, \mathbf{H}\}$ as constants, the subproblem of Eq.(7) with respect to \mathbf{C} can be compactly formulated as follows:

$$\min_{\mathbf{C}} \sum_{i=1}^n W_{\lambda}(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i); \mathbf{m}(\mathbf{C})) + \frac{\beta_1}{2} \sum_{i=1}^l \sum_{j=1}^l \mathbf{C}_{ij} \|\mathbf{w}_i - \mathbf{w}_j\|_2^2 \quad (14)$$

After some simple derivations, the gradient of \mathbf{C} can be computed based on the chain rule:

$$g(\mathbf{C}) = g(\mathbf{m}(\mathbf{C})) \times \frac{\partial \mathbf{m}(\mathbf{C})}{\partial \mathbf{C}} + \frac{\beta_1}{2} \mathbf{A}, \quad (15)$$

where

$$g(\mathbf{m}(\mathbf{C})) = \sum_{i=1}^n \mathbf{T}_i^*,$$

\mathbf{T}_i^* is the optimal transport plan of $W_{\lambda}(\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i); \mathbf{m}(\mathbf{C}))$, and $\mathbf{A} \in \mathbb{R}^{l \times l}$ is defined by $\mathbf{A}_{ij} = \|\mathbf{w}_i - \mathbf{w}_j\|_2^2$. Then, \mathbf{C} can be updated with the gradient decent method as follows:

$$\mathbf{C} \leftarrow \mathbf{C} - \rho_t g(\mathbf{C}). \quad (16)$$

Updating $\{\mathbf{Q}, \mathbf{E}\}$: Holding $\{\mathbf{W}, \mathbf{C}, \mathbf{H}\}$ fixed, the subproblem of Eq.(7) with respect to $\{\mathbf{Q}, \mathbf{E}\}$ can be rewritten as follows:

$$\min_{\mathbf{Q}, \mathbf{E}} \beta_3 \|\mathbf{Q}\|_* + \beta_4 \|\mathbf{E}\|_1 + \frac{\mu_1}{2} \|\mathbf{Y} - \mathbf{Q} - \mathbf{E} + \frac{\mathbf{Y}_1}{\mu_1}\|_F^2 + \frac{\mu_2}{2} \|\mathbf{Q} - \mathbf{H} + \frac{\mathbf{Y}_2}{\mu_2}\|_F^2. \quad (17)$$

The above optimization problem can be solved by employing a robust PCA (RPCA) technique, and its Lineared Alternating Direction Method (LADM) solution is given by:

$$\mathbf{Q}^{k+1} = \mathcal{D}_{1/\beta_Q} \left[\mathbf{Q}^k - \frac{\mathbf{F}_Q^k}{\beta_Q} \right], \quad (18)$$

$$\mathbf{E}^{k+1} = \mathcal{S}_{\beta_4/\mu_1} \left[\mathbf{Y} - \mathbf{Q}^{k+1} + \frac{\mathbf{Y}_1^k}{\mu_1^k} \right], \quad (19)$$

where $\mathcal{D}_{1/\beta_Q}(\cdot)$ is the singular value thresholding [Liu *et al.*, 2010b], $\mathcal{S}_{\beta_4/\mu_1}(\cdot)$ is the shrinkage operator [Zhuang *et al.*, 2012], $\beta_Q = (\mu_1 + \mu_2)\tau_Q/2$, $\tau_Q > \rho(\mathbf{I}^{\top} \mathbf{I})$ is the proximal parameter, $\rho(\mathbf{I}^{\top} \mathbf{I})$ denotes the spectral radius of $\mathbf{I}^{\top} \mathbf{I}$, and \mathbf{F}_Q^k is derived by \mathbf{Q}^k for the third and fourth terms in Eq.(17):

$$\mathbf{F}_Q^k = \mu_1 (\mathbf{Q} - \mathbf{Y} + \mathbf{E}) + \mu_2 (\mathbf{Q} - \mathbf{H}) + \mathbf{Y}_2 - \mathbf{Y}_1.$$

Updating $\{\mathbf{Y}_1, \mathbf{Y}_2, \mu_1, \mu_2\}$: The Lagrange multiplier matrixes $\{\mathbf{Y}_1, \mathbf{Y}_2\}$ and the corresponding regularization parameters $\{\mu_1, \mu_2\}$ can be updated by utilizing the LADM as follows:

$$\begin{aligned} \mathbf{Y}_1^{k+1} &\leftarrow \mathbf{Y}_1^k + \mu_1^k (\mathbf{Y} - \mathbf{Q} - \mathbf{E}), \\ \mathbf{Y}_2^{k+1} &\leftarrow \mathbf{Y}_2^k + \mu_2^k (\mathbf{Q} - \mathbf{H}), \\ \mu_1^{k+1} &\leftarrow \min(\mu_{max}, \psi \mu_1^k), \\ \mu_2^{k+1} &\leftarrow \min(\mu_{max}, \psi \mu_2^k), \end{aligned} \quad (20)$$

where ψ is a positive scalar.

Note that both gradients of Eqs.(9), (12) and (15) can be efficiently calculated. **First**, we can compute the subgradients of regularized Wasserstein distance, *i.e.*, $g(\mathbf{s}(\mathbf{W}\mathbf{x}_i))$, $g(\mathbf{s}(\mathbf{h}_i))$ and $g(\mathbf{m}(\mathbf{C}))$, by directly using *Algorithm 1* mentioned in Section A, specifically substituting $\{\mathbf{s}(\mathbf{h}_i), \mathbf{s}(\mathbf{W}\mathbf{x}_i), \mathbf{m}(\mathbf{C})\}$ into $\{\mu, \nu, \mathbf{M}_K\}$. **Second**, we can directly calculate the two gradients of the softmax function, *i.e.*, $\partial \mathbf{s}(\mathbf{W}\mathbf{x}_i) / \partial (\mathbf{W}\mathbf{x}_i)$ and $\partial \mathbf{s}(\mathbf{h}_i) / \partial \mathbf{h}_i$, as well as the gradient of the sigmoid function, *i.e.*, $\partial \mathbf{m}(\mathbf{C}) / \partial \mathbf{C}$.

Full Algorithm: In summary, we iteratively update parameters $\{\mathbf{W}, \mathbf{Q}, \mathbf{C}, \mathbf{E}, \mathbf{H}\}$ and Lagrange multiplier variables $\{\mathbf{Y}_1, \mathbf{Y}_2, \mu_1, \mu_2\}$. Finally, we can obtain the optimal model parameter \mathbf{W}^* for predicting future instances. For clarity, the full optimization procedure of WPML³CP is summarized in *Algorithm 2*.

Algorithm 2 Optimization for WPML³CP

Input: Training dataset $\mathcal{D} = \{(\mathbf{x}_i, \mathbf{y}_i)\}_{i=1}^{i=n}$, regularization parameters $\{\beta_1, \beta_2, \beta_3, \beta_4, \lambda\}$; LADM parameters $\{\psi, \mu_{max}\}$;

Output: Model parameter \mathbf{W}^* .

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1: Initialize  $\{\mathbf{W}, \mathbf{Q}, \mathbf{E}, \mathbf{H}\}$  and  $\{\mathbf{Y}_1, \mathbf{Y}_2, \mu_1, \mu_2\}$ ;  
2: Calculate the initial pairwise similarity matrix  $\mathbf{C}$ ;  
3: for  $t = 1$  to  $N_{iter}$  do  
4:   for  $i = 1$  to  $n$  do  
5:     Calculate  $g(\mathbf{s}(\mathbf{h}_i)), g(\mathbf{s}(\mathbf{W}\mathbf{x}_i)), \mathbf{T}_i^*$  by Algorithm 1;  
6:   end for  
7:   Calculate  $g(\mathbf{H}), g(\mathbf{W})$  and  $g(\mathbf{C})$  by Eqs.(12), (9) and (15);  
8:   Update  $\{\mathbf{W}, \mathbf{Q}, \mathbf{C}, \mathbf{E}, \mathbf{H}\}$  and  $\{\mathbf{Y}_1, \mathbf{Y}_2, \mu_1, \mu_2\}$  by Eqs.(10), (18), (16), (19), (13) and (20);  
9: end for
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