Problem 1. Class Scheduling

Our greedy algorithm will consider classes in increasing order of finish time. The algorithm will schedule classes in a hall only if the class is compatible with the classes already taken. If no more classes can be scheduled in the hall and there are still remaining classes left to be scheduled, the algorithm will schedule classes in a new hall by choosing the next class with the earliest finish time.

```
Let C be the set of classes \{(s_i, f_i), 1 \le i \le n\} of start and finish times of n classes
 Let H be a set of schedules \{(s1, f1), (s2, f2) \dots\}, \{(s3, f3), (s4, s5), \dots\} \dots \}
 //Each schedule in H will be composed of classes that are compatible
 //The number of schedule will be equal to the number of halls required.
 Type equation here.
Class_Scheduler{
  Let c_i = (s_i, f_i), where s_i is the start and f_i is the finish of class i, 1 \le i \le n
  Let C = [c_1 .... c_n]
  Sort(C) in order of increasing finish times
  Let H = [], an empty array
  while C is not empty
     Let T = [] be an empty array
     T[1] = C[1]
     for i \leftarrow 2 to C. length
        if s_i \ge f_k:
          T.append(c_i)
          Delete C[i]
     H.append(T)
}
```

Sort will take $O(n \log n)$, if merge sort is used. In the worst case n halls will be needed, the outer while loop will execute n times and the inner for loop will execute n times. Deletion and shifting of the $C[\]$ is O(n).

$$T(n) = O(n \log n + n^2 + n) :: T(n) = O(n^2)$$

2. Scheduling Jobs with penalties.

Our greedy algorithm will first sort jobs in order of decreasing penalties. We will define an array S[] = [1.....n], where each index represents a one minute time slot. The algorithm will then seek to schedule the job in latest possible spot without exceeding the deadline. It search the possible intervals $1 \le k \le d_i$. If no spot is available it will search from the end of the possible spots in the Schedule, S, starting at index n.

Pseudo Code:

```
Scheduler{
Let j_i = (p_i, j_i), where p_i is the penalty and d_i is the deadline of job i, 1 \le i \le n
Let J = \{j_1, j_2, ... j_n\}, for n jobs
Let S \leftarrow \emptyset
Let S(t) return an element in the set at position t, j_t
k \leftarrow n
mergesort(J) #Sort in order of decreasing penalties p_1 \ge p_2 .... \ge p_n
for i \leftarrow 1 to n{
for t \leftarrow d_i to 1{
   if S(t) is empty{
    S(t) = j
}else{
   S(k) = j
k-=1
```

3. Activity Selection Last to Start

In the greedy algorithm where criteria was to select an activity based on the first to finish, it was beneficial to examine the activity, a_i , from start to finish, $[s_i, f_i)$.

Instead of examining from start to finish, we can look from finish to start. Let $a'_i = (f_i, s_i]$, the interval is equal to a_i , but in reverse.

If we let A be a set of activities $A=\{[s_1,f_1),[s_2,f_2),...[s_n,f_n)\}$. We can observe the following, all choices are compatible, they do not overlap. Because each choice is compatible, the following must be true $f_1 \leq s_1 \leq f_2 \leq s_2 \leq \cdots f_{n-1} \leq s_{n-1} \leq f_n \leq s_n$. The last activity in A, $[s_n,f_n)$ is the last to start in this set and is a valid first selection to A'. It follows that all the activities in A are a valid solution to A', but in reverse.

We can Prove by induction:

Let $P(n) \equiv$ the activities in the solution A are also a valid in A', but in reverse. That is $A = \{[s_1, f_1), [s_2, f_2), ..., [s_n, f_n)\}$ is compatible with A', where $A' = \{(f_n, s_n], (f_{n-1}, s_{n-1}], ..., (f_2, s_2], (f_1, s_1]\}$

Inductive Hypothesis: P(n-1) is true, then P(n) is also true. That is, if it is true that activites, $a_i, 1 \le i \le n-1$, in A are also in A', but in reverse, then it is true for a_n as well.

Base Case: P(1). An activity of one in $A = \{[s_1, f_1)\}$, the activity is both the first to finish and the last to start, therefore, $A' = \{(f_1, s_1]\}$. Thus P(1) is true.

Inductive Step: Suppose activity, a_k , k=n, is an activity that was chosen by the original greedy algorithm, then it must be true that a_k is compatible with a_{n-1} , that is

 $f_k \ge s_k \ge f_{n-1} \ge s_{n-1} \dots \ge f_2 \ge s_2 \ge f_1 \ge s_1.$

(I.H.) Because it is true that P(n-1) is true, that is $a'_{n-1} = (f_{n-1}, s_{n-1}]$ is currently the first selection in the set A', then activity a_k , can be added before a'_{n-1} in the set A', because it is compatible.

 a_k satisfies, the criteria of the new greedy algorithm, i. e it is the last to start and is is compatible with other acitive is in the set A'. Therefore P(n) is true. QED.

4. Activity Selection PseudoCode

```
Activity{
    Let A = \{a_1, a_2, \dots a_n\} be the set of activites to be scheduled
    Let a_i = (f_i, s_i), where f_i is the finish time and s_i of activity i, 1 \le i \le n
    Sort(A) in order of decreasing start times,
    S = \{a_1\}
    i = 1

for j \leftarrow 2 to n:
    if s_i \ge f_j:
    S = S \cup \{a_j\}
    i \leftarrow j
    A = A - \{a_j\}
```

Assume mergesort will be used to sort A, then the running time of the sorting algorithm is $\theta(n \log n)$

The for loop will iterate j=2 to n, the comparison, which is runs in constant time, T(1)=1 will always execute during each iteration. The three statement may or may not execute. In the worst case the if statement and all the assignments execute, (n-2)*4. In the best case only the if statement execute and none of the assignment execute, (n-2)*1. Therefore we can say that the running time of the for loop is:

$$\theta(n)$$

Overall the running time is:

$$T(n) = \theta(n \log n) + \theta(n) :: T(n) = \theta(n \log n)$$