

MCS8

DLL Software Interface

User Manual

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The information in this manual describes the hardware and the software as accurately as possible, but is subject to change without notice.

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1 Introduction

The MPANT software for the MCS8 consists of a hardware-dependent server program MCS8.EXE and a general graphics program MPANT.EXE that controls the hardware via a DLL DMCS8.DLL. Any other Windows application can also control the hardware via the DLL. To support the programming of such customer-specific user interfaces, as an option we deliver this documentation including source code and example programs for LabVIEW, Visual Basic, C and Delphi. The complete source code of the DLL that controls the hardware via the server program is included. A special FMPA3.DLL including source code allows to display calculated spectra including calculated error bars in the MPANT program.

The server program MCS8.EXE is a rather compact Windows application. It controls the hardware and data and allows to perform measurements with the system. MPANT is just a user interface to control the server program. It has access to the data in a shared memory region and can display spectra. It is not necessary that MPANT is running during an acquisition. It can be exited and restarted without stopping a running acquisition. If you don't want MPANT automatically started when starting the server, just rename the file MPANT.EXE in the working directory (default C:\MCS8 or C:\MCS8-x64) for example into MYMPANT.EXE.

The DLL DMCS8.DLL is an interface providing functions to communicate with the server program. Most of these functions send messages to the server as you do it when operating the server program by sending Windows messages via mouse clicks. Please do not expect any functions in this DLL for controlling the hardware directly. All software described in this manual requires that the server program is running. The DLL was mainly developed as an interface between the server program and MPANT, not as a nice developing tool for customers. But by looking at the programming examples and the following hints it should be easy to develop own programs that are able to control the server like MPANT does.

1.1 Some hints

The server program has a built-in command interpreter. The syntax of these commands is described in the MCS8 manual, chapter 5.2, and in the MPANT on-line help (look for: "How to use the command language.."). It is recommended to send commands like "range=16384" to the server via the RunCmd DLL function, i.e. RunCmd(0, "range=16384"); if you want to set parameters like a spectra length. The alternative method is to store all settings parameters into the DLL by calling the DLL function StoreSettingData(setting, 0); and then calling NewSetting(0); to send a message to the server to read new settings from the DLL. This method will not work for changing a spectra length to avoid the problem of any undefined memory pointers. The range parameter should be changed by the server program only (or by sending a "range=.." command). The recommended usage of the DLL is reading parameters like Status, Settings, Strings, Cnt numbers, ROI boundaries using the corresponding DLL functions, but for any actions or setting any parameters the command interpreter should be used.

If your application that controls the MCS8 server via the DLL is a true Windows application with a main window and corresponding message loop handling messages sent to this window, you can fetch a special Windows message to react immediately on actions like an acquisition status change without permanently polling the status:

Declare a global int MM_STATUS and somewhere when initializing your program register a Windows message using a code line like:

```
MM_STATUS=RegisterWindowMessage("MCS8Status");
```

furthermore, declare somewhere in your headers constants

```
#define ID_NEWSTATUS 162
#define ID_NEWSETTING 139
#define ID_NEWDATA 160
```

I assume your main Window Procedure is declared like

DWORD WINAPI MyMainWndProc(HWND hwnd, UINT msg, WPARAM wParam, LPARAM lParam)

you can then insert here code like

```
if (msg == MM_STATUS) {
    if (wParam == ID_NEWSTATUS) {
        // status change, read acquisition status and react accordingly...
    }
    else if (wParam == ID_NEWDATA) {
        // release all pointers, the server will reallocate some spectra..
    }
    else if (wParam == ID_NEWSETTING) {
        // the server has reallocated some spectra, get new pointers..
    }
}
```

On any status change the server sends a NEW_STATUS message. The lParam value is usually zero, but after a stop of an acquisition the lParam is equal to 1, so your program is able to react accordingly.

It is important that the DLL is loaded first by the Server program and that it is loaded from the same path by all programs using it. Otherwise it does not work to access the shared memory. The dmcs8.dll is installed into the Windows\System32 directory or when using the 32-bit Software on a 64-bit Windows into Windows\SYSWOW64\ . Please make sure that there is nowhere else any file dmcs8.dll. Start MCS8.exe by hand before starting your program, or by a call from your program for example like

```
{
    STARTUPINFO startupinfo = {0};
    PROCESS_INFORMATION procinfo = {0};
    startupinfo.cb = sizeof(STARTUPINFO);
    return CreateProcess ( "MCS8.EXE", NULL, NULL, NULL, FALSE, NORMAL_PRIORITY_CLASS, NULL,
        NULL, &startupinfo,&procinfo);
}
```

, but before your program loads the DLL. It is recommended not to link the DLL to your program using a dmcs8.LIB file, but explicitly load it at runtime as demonstrated in our example tstmcs8.c.

2 Using the DMCS8 DLL from LabVIEW

To access the MCS8 data directly from LabVIEW via the DLL, some LabVIEW VI's ("Virtual Instruments") contained in MCS8LV.LLB and the MCS8TEST.VI are provided.

2.1 The MCS8test demo VI

Files: mcs8lv.llb, mcs8test.vi

The distribution medium contains in a directory lv2011 the following files: mcs8lv.llb and mcs8test.vi. The mcs8test.vi demonstrates access to spectra data. Please start now MCS8.EXE and then LabVIEW and open the mcs8test.vi (or just double click on mcs8test.vi). You may load some data like spec1.mpa with MPANT or the server and then run the VI.

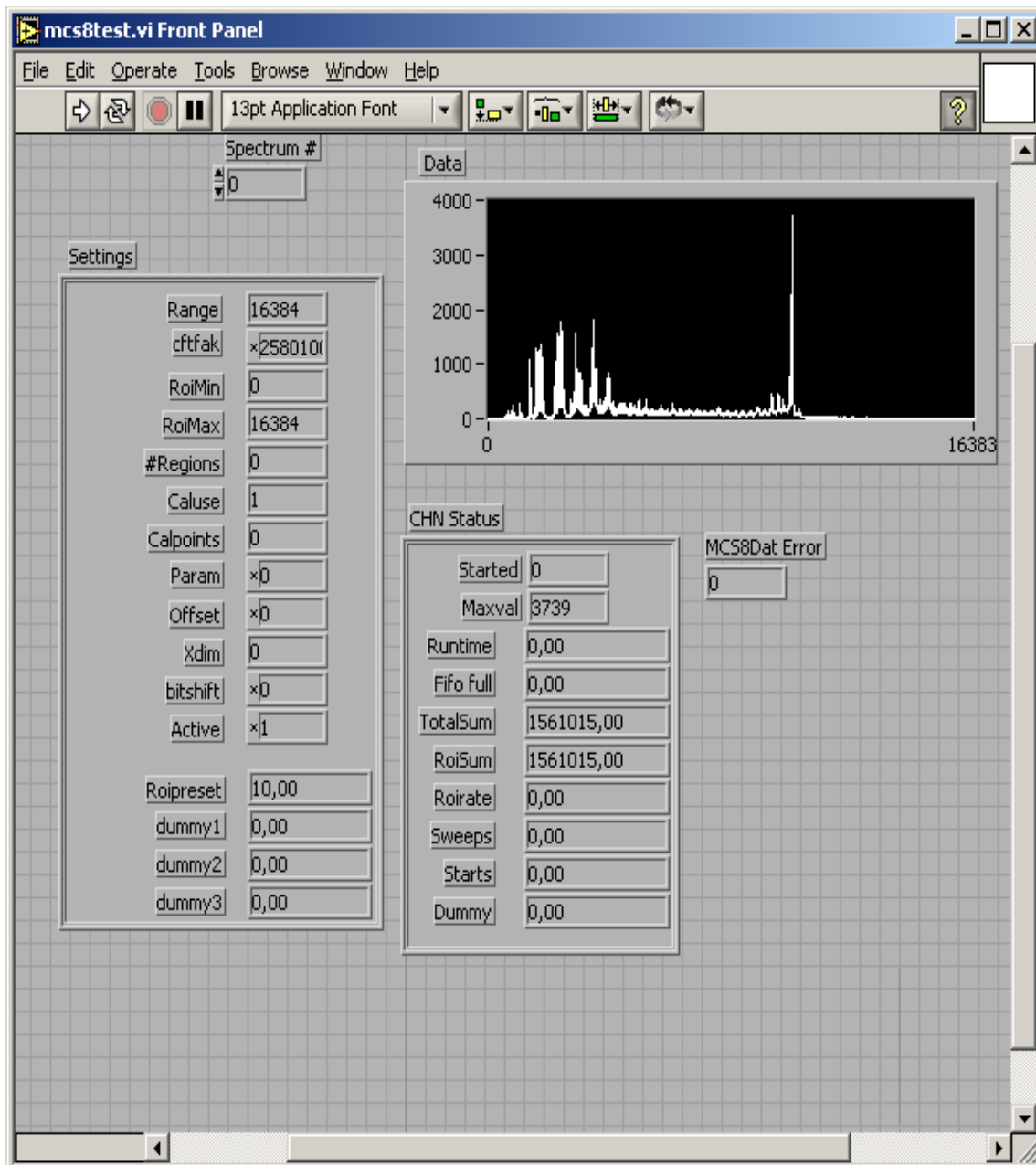


Fig. 2.1: The mcs8test VI

In the Windows menu, click on Show Diagram to display the diagram, and on Show Help Window to display the Help window.

The Demo VI contains the VI's to get the settings, status and spectrum data.

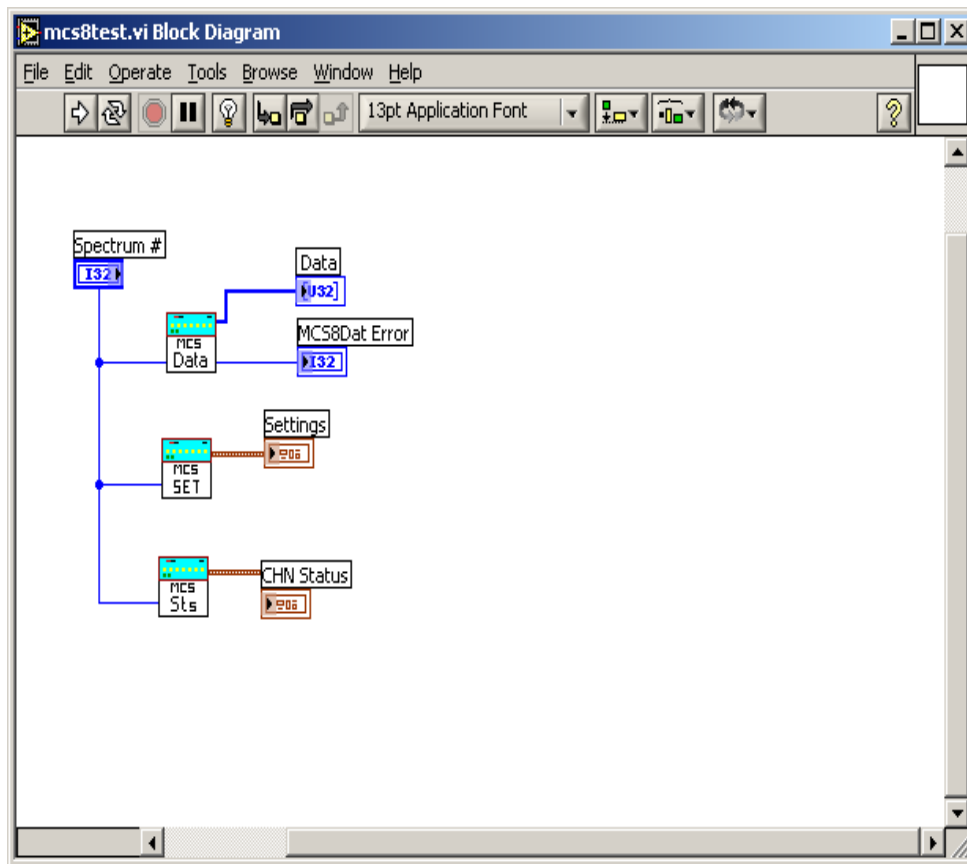
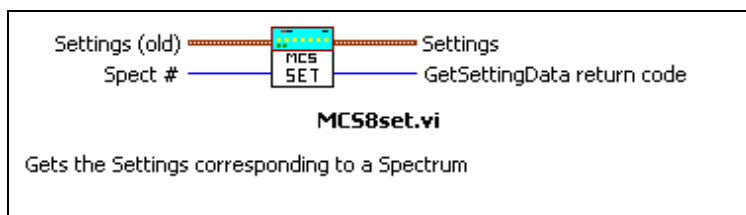


Fig. 2.2: Block diagram of mcs8test VI

2.2 Getting Parameters



The Settings are obtained with the MCS8set.vi. It results a 32 bit integer as an error code and the settings contained in a cluster.

You can use the help window to get information: on the front panel as the active window, just move the mouse over the item you are interested and observe the help window. The cluster has the components known from the DLL structure definitions:

- | | |
|-----------------------|-----------------------|
| 1. Range (I32) | 2. Prena (I32) |
| 3. RoiMin (I32) | 4. RoiMax (I32) |
| 5. #Regions (I32) | 6. Caluse (I32) |
| 7. Calpoints (I32) | 8. Param (hex) (I32) |
| 9. Offset (hex) (I32) | 10. Xdim (I32) |
| 11. Timesh (I32) | 12. Active(hex) (I32) |

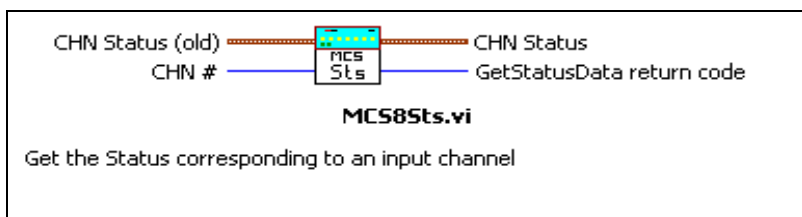
- | | |
|---------------------|---------------------|
| 13. Roipreset (DBL) | 14. Ltpreset (DBL) |
| 15. TimeOffs (DBL) | 16. Dwelltime (DBL) |

For the detailed meaning of each parameter please refer to the LabView on-line help window or the DLL description in this manual.

The error code has the following meanings:

- 1: ok
- 2: No Parameters available

2.3 Getting the Status



The Status corresponding to an input channel is obtained with the MCS8Sts.VI. The Input is the Channel number with 0 for STOP1 and so on. It results a 32 bit integer as an error code and the status parameters contained in a cluster.

The cluster has the following components:

- | | |
|--------------------|---|
| 1: Started (I32): | 0 == OFF, 1 == ON, 3 == READ OUT |
| 2: Maxval (U32): | Maximum value in spectra,
only available when stopped |
| 3: Runtime (DBL) | in seconds |
| 4: Fifo full (DBL) | counted number of datalost bits,
only available for special dataword formats |
| 5: TotalSum (DBL) | |
| 7: RoiSum (DBL) | |
| 8: RoiRate (DBL) | |
| 9: Sweeps (DBL) | |
| 10: Starts (DBL) | |

The error code has the following meanings:

- 1: ok
- 0: No data available

2.4 Avoiding memory leaks

All VI's returning parameters in a cluster structure have an "old" input for the same structure that is reallocated in the vi. When using repeated calling a status it is recommended to use it with a shift register added at the borders of a "while – loop" structure to recycle the memory as shown in Fig. 2.3

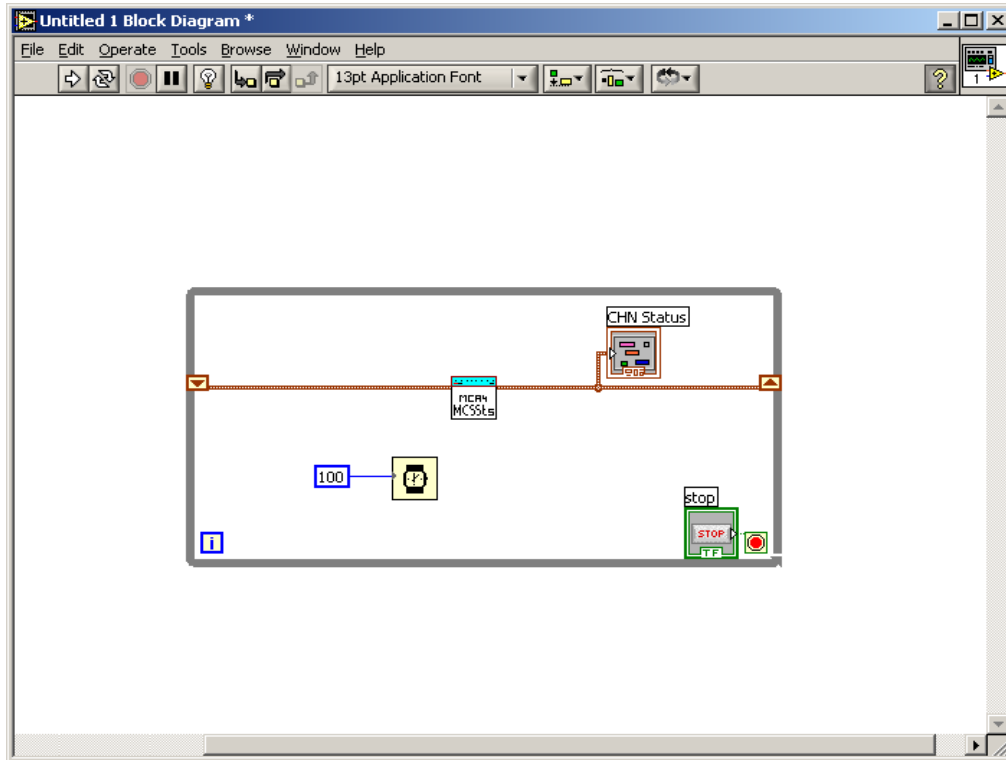
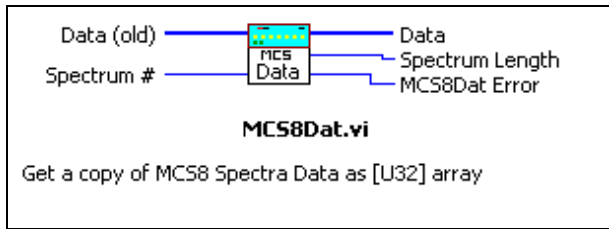


Fig. 2.3: Recycling of memory using shift registers

2.5 Getting the Spectrum Data



The Spectrum data is obtained with the MCS8Dat.vi. It results spectrum as a [U32] array, the spectrum length and an error codes as a 32 bit integer.

The error code has the following meanings:

- 0: ok
- 4: No Data available

How to use MCS8Dat.vi to get a display of a dualparameter spectra in LabVIEW is demonstrated in MCS28Dat.vi.

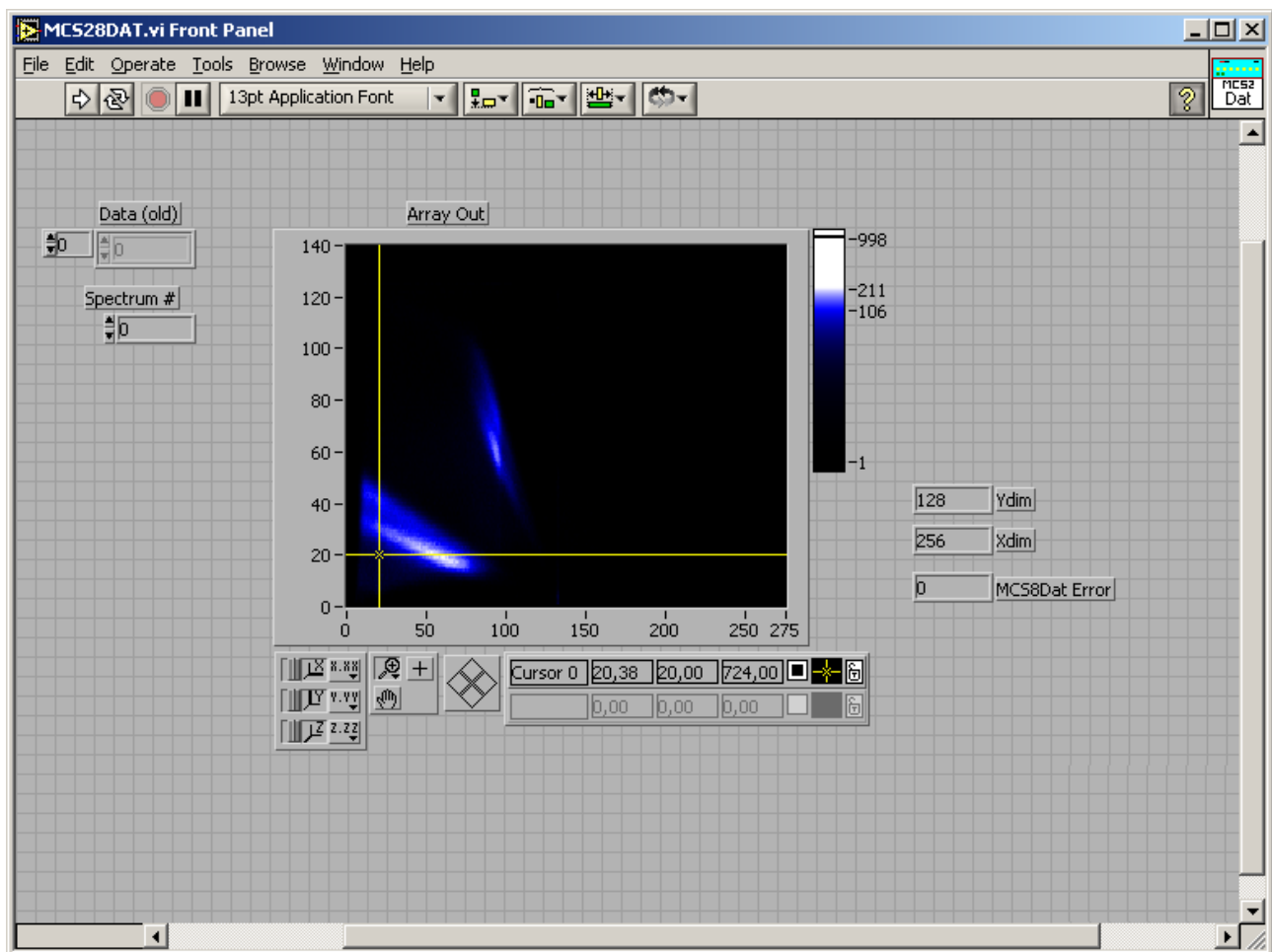
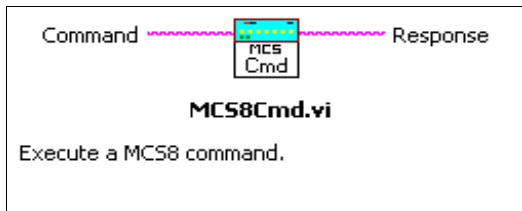


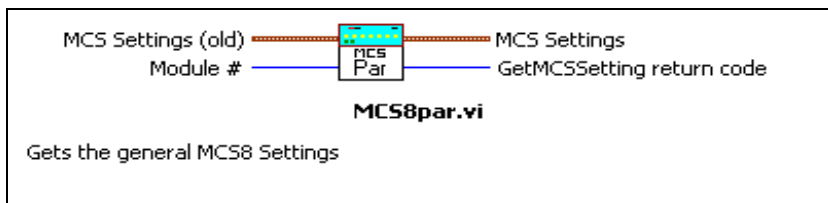
Fig. 2.4 MCS28DAT.VI

2.6 Executing a command



The MCS8LV.LLB contains some more VIs that are not used by MCS8test.VI. Any command for the MCS8 server can be executed by MCS8Cmd.VI. It results an response string.

2.7 Getting General MCS8 Settings



The MCS Settings are obtained with the MCS8par.vi. It results a 32 bit integer as an error code and the settings contained in a cluster.

You can use the help window to get information: on the front panel as the active window, just move the mouse over the item you are interested and observe the help window. The cluster has the components defined in the DLL structure definition of BOARDSETTING:

1. sweepmode (I32) // sweepmode & 0xF: 0 = normal,
 - // 1=differential (relative to first stop in sweep)
 - // 4=sequential
 - // 5=seq.+diff (Ch1), bit0 = differential mode
 - // 6 = CORRELATIONS
 - // 7 = diff.+Corr.
 - // 9=differential to stop in Ch2, bit3 = Ch2 ref (diff.mode)
 - // 0xF = Corr.+diff (Ch2)
 - // bit 4: Softw. Start
 - // bit 5: "Don't show" tagbits
 - // bit 6: Endless
 - // bit 7: Start event generation
 - // bit 8: Enable Tag bits
 - // bit 9: start with rising edge
 - // bit 10: time under threshold for pulse width
 - // bit 11: pulse width mode for any spectra with both edges enabled
 - // bit 12: abandon Sweepcounter in Data
 - // bit 13: "one-hot" mode with tagbits
 - // bit 14: start ref (diff.mode)
 - // bit 15: enable start input
 - // bit 16..bit 22 ~(input channel enable)
 - // bit 24: require data lost bit in data
 - // bit 25:
 - // bit 27: Folded
 - // bit 28: Interleaved
2. prena (I32)
 - // bit 0: realtime preset enabled
 - // bit 1:

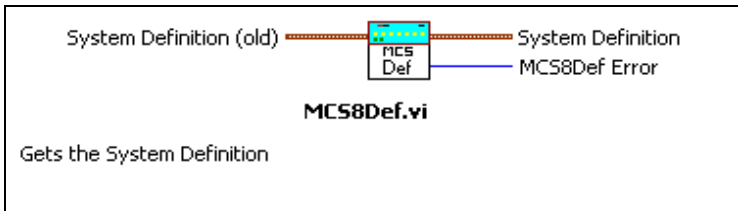
```

// bit 2: sweep preset enabled
// bit 3: ROI preset enabled
// bit 4: Starts preset enabled
// bit 5: ROI2 preset enabled
// bit 6: ROI3 preset enabled
// bit 7: ROI4 preset enabled
// bit 8: ROI5 preset enabled
// bit 9: ROI6 preset enabled
// bit 10: ROI7 preset enabled
// bit 11: ROI8 preset enabled
3. cycles (U32) // for sequential mode, = y-dimension
4. sequences (U32) // for sequential mode, how often to repeat filling the array
5. syncout (U32) // LOWORD: sync out; bit 0..5 NIM syncout, bit 8..13 TTL syncout
// bit7: NIM syncout_invert, bit15: TTL syncout_invert
// 0="0", 1=5 MHz, 2=50 MHz, 3=100 MHz, 4=97.656 MHz,
// 5=195.625 MHz, 6= 195 MHz (int ref), 7=Start, 8=Ch1, 9=Ch2, 10=Ch3,
// 11=Ch4, 12=Ch5, 13=Ch6, 14=Ch7, 15=GO, 16=Start_of_sweep,
// 17=Armed, 18=SWEEP_ON, 19=WINDOW, 20=HOLD_OFF,
// 21=EOS_DEADTIME, 22=TIME[0],...,51=TIME[29],
// 52...63=SWEEP[0]..SWEEP[11]
6. digio (U32) // LOWORD: Use of Dig I/O, GO Line:
// bit 0: status dig 0..3
// bit 1: Output digval and increment digval after stop
// bit 2: Invert polarity
// bit 3: Push-Pull output, not possible
// bit 4: Start with Input Dig 4
// bit 5: Start with Input GO
// bit 8: GOWATCH
// bit 9: GO High at Start
// bit 10: GO Low at Stop
// bit 11: Clear at triggered start
// bit 12: Only triggered start
7. digval (U32) // digval=0..255 value for samplechanger
8. dac0 (U32) // DAC0 value (START) bit 16: Start with rising edge
9. dac1 (U32) // DAC1 value (STOP 1)
10. dac2 (U32) // DAC2 value (STOP 2)
11. dac3 (U32) // DAC3 value (STOP 3)
12. dac4 (U32) // DAC4 value (STOP 4)
13. dac5 (U32) // DAC5 value (STOP 5)
14. dac6 (U32) // DAC6 value (STOP 6)
// bit (14,15) of each word: 0=falling, 1=rising, 2=both, 3=both+CFT
// bit 17 of each: pulse width mode under threshold
15. tagbits (U32) // number of tagbits
16. extclk (U32) // use external clock
17. periods (U32) // number of periods in folded mode, sweeplength = range * periods
18. serno (U32) // serial number
19. ddruse (U32) // bit0: DDR_USE, bit1: DDR_2GB
// bits[2:3]: usb_usage
// bits[4:5]: wrlen
20. active (U32) // module in system
21. holdafter (DBL) // hold off
22. swpreset (DBL) // sweep preset value
23. fstchan (DBL) // acquisition delay
24. timepreset (DBL) // time preset

```

Information about the parameters can be found in the on-line help window or the description of the BOARDSETTING structure in the DLL description in this manual.

2.8 Getting MCS8 System definition



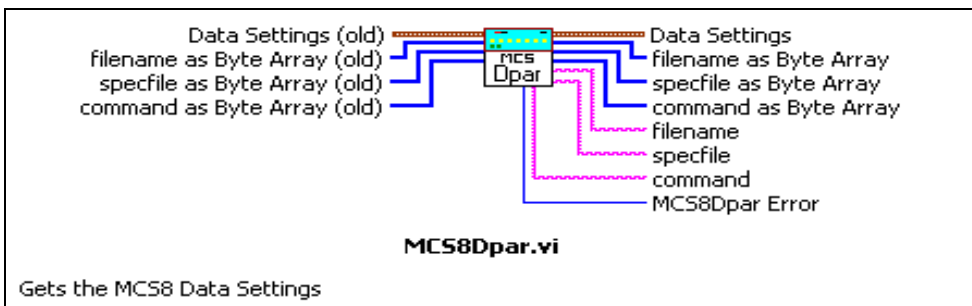
The MCS8 System Definition are obtained by MCS8Def.vi. It results the System Definition parameters in a cluster and a 32 bit integer as an error code. The System Definition has following components:

- | | |
|--------------------|--|
| 1. nDevices (I32) | nDevices is the number of physical channels (6) |
| 2. nDisplays (I32) | nDisplays is the number of spectra = 6 + calc. spectra |
| 3. nSystems (I32) | nSystems the number of independent systems which is 1 in the present version |
| 4. bRemote (I32) | bRemote indicates whether the MCS8 server is controlled by MPANT |
| 5. sys (I32) | System definition word, 0 for applications with only one module. |

The error code has the following meanings:

- 0: ok
- 1: No data available

2.9 Getting the MCS8 Data Settings



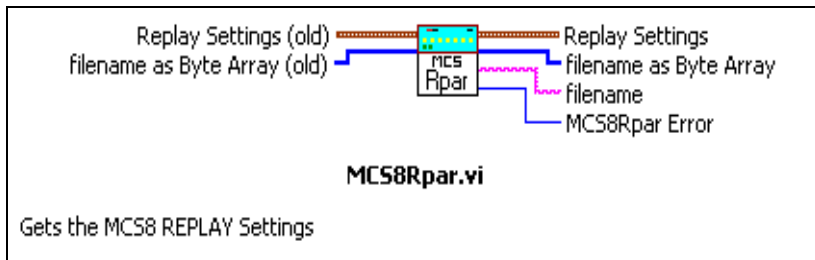
The MCS8 Data Settings can be obtained by MCS8Dpar.vi. It results the Data Settings in a cluster and a 32 bit integer as an error code. The Data Settings are:

- | | |
|--------------------|---|
| 1. savedata (I32): | 1 means auto save after stop |
| 2. autoinc (I32): | autoincrement MPA data filename |
| 3. fmt (I32): | MPA format type (0=ASCII, 1=binary, 2=CSV) |
| 4. sepfmt (I32): | format type for separate spectra |
| 5. sephead (I32) | 1 means separate header |
| 6. smpts (I32) | number of points for smoothing operation |
| 7. caluse (I32) | 1 means using calibration for shifted spectra summing |
| 8. filename (STR) | MPA data file name |
| 9. specfile (STR) | spectrum file name |
| 10. command (STR) | |

The error code has the following meanings:

- 0: ok
- 1: No data available

2.10 Getting the Replay Settings



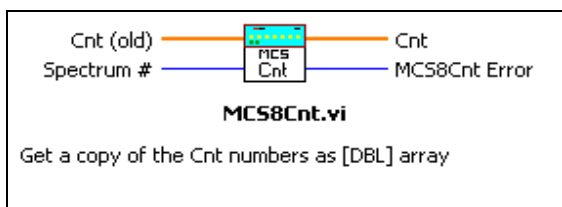
The Replay Settings can be obtained by MCS8Rpar.VI. It results a 32 bit integer as an error code and the Replay Settings:

- | | |
|----------------------|--|
| 1. use (I32): | 1 if Replay Mode ON |
| 2. modified (I32): | 1 if different settings are used from measurement time |
| 3. limit (I32): | 0=all, 1 = limited time range |
| 4. speed (I32): | replay speed in units of 100 kByte per sec |
| 5. timefrom (DBL): | first time (sec) |
| 6. timeto (DBL): | last time (sec) |
| 7. timepreset (DBL): | last time - first time |
| 8. filename (STR): | listfile for replay |

The return code has the following meanings:

- 0: ok
- 1: No data available

2.11 Getting the Cnt numbers



The Cnt numbers enable a very fast access to the acquisition status. They are very often actualized and are directly accessible via shared memory, whereas the status structure block is saved into the DLL in fix time intervals and is therefore available only after some delay.

The Cnt numbers can be obtained by MCS8Cnt.VI. It needs as input the spectrum number and results a 32 bit integer as an error code and the Cnt numbers as an array of 448 DBL containing the Cnt numbers.

Array of 448 DBL containing the Cnt numbers.

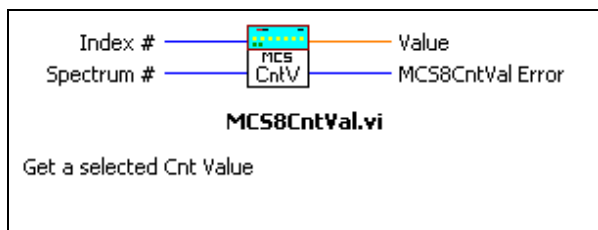
- Cnt[0] = Realtime,
- Cnt[1] = Totalsum,
- Cnt[2] = ROISum,
- Cnt[3] = ROIrate,
- Cnt[4]
- Cnt[5] = Sweeps,
- Cnt[6]
- Cnt[7] = cycle cnt
- Cnt[8] = sequence cnt
- Cnt[9]
- Cnt[10] = start time

Cnt[11] = c0 cal. coeff.,
 Cnt[12] = c1,
 Cnt[13] = c2,
 Cnt[14] = c3, for scope displays: vpp (mV) / 65535
 Cnt[15] for spectrum# =0: bit 0: system 1 started
 bit 1: system 2 started,
 bit 2: system 3 started,
 bit 3: system 4 started

 Cnt[16]
 Cnt[17] = FIFOcnt, indicates filling of large FIFO in units of bytes
 Cnt[18]
 Cnt[19] = calch0,
 Cnt[35] = calval0, calib. Points
 Cnt[20] = calch1,
 Cnt[36] = calval1,
 ...
 Cnt[64]..Cnt[191] : Peak values in corresponding Roi 0..127 for Calibration
 Cnt[192], Cnt[193] ,... Cnt[447]: Roi Sum and Roi Net Sum in corresponding Roi 0 (, 1, ..127)
 (actualized by MPANT when selected)

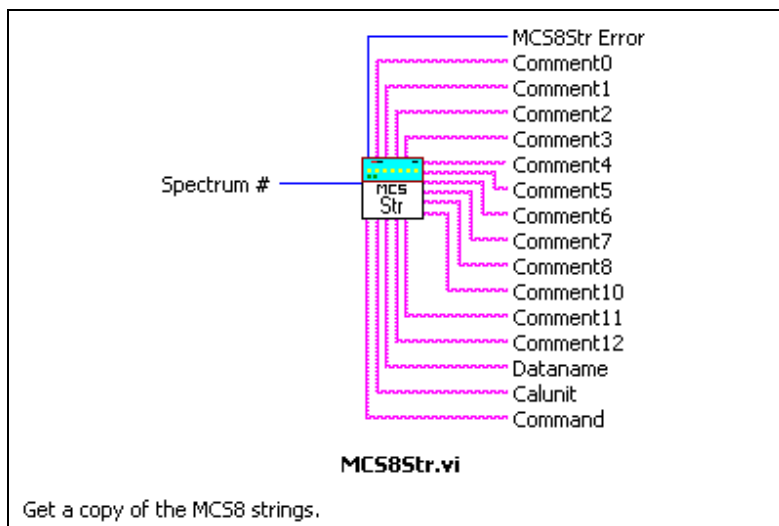
The error code has the following meanings:

0: ok
 4: No Data available



A selected Cnt Value can be obtained by MCS8CntVal.VI. Inputs are the spectrum number and the index into the Cnt array. It results a 32 bit integer as an error code and the selected Cnt value as DBL.

2.12 Getting the Strings

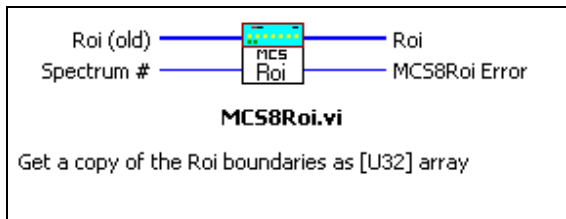


The Strings can be obtained by MCS8Str.VI. It results a 32 bit integer as an error code and the Strings.

The error code has the following meanings:

0: ok
 4: No Data available

2.13 Getting the ROI boundaries



The ROI boundaries can be obtained by MCS8Roi.VI. It results a 32 bit integer as an error code and the ROI boundaries for single spectra or rectangle ROIs for dual parameter spectra, respectively, contained in a [U32] array.

The error code has the following meanings:

- 0: ok
- 4: No Data available

2.14 Getting data from special views in MPANT like projections or slices

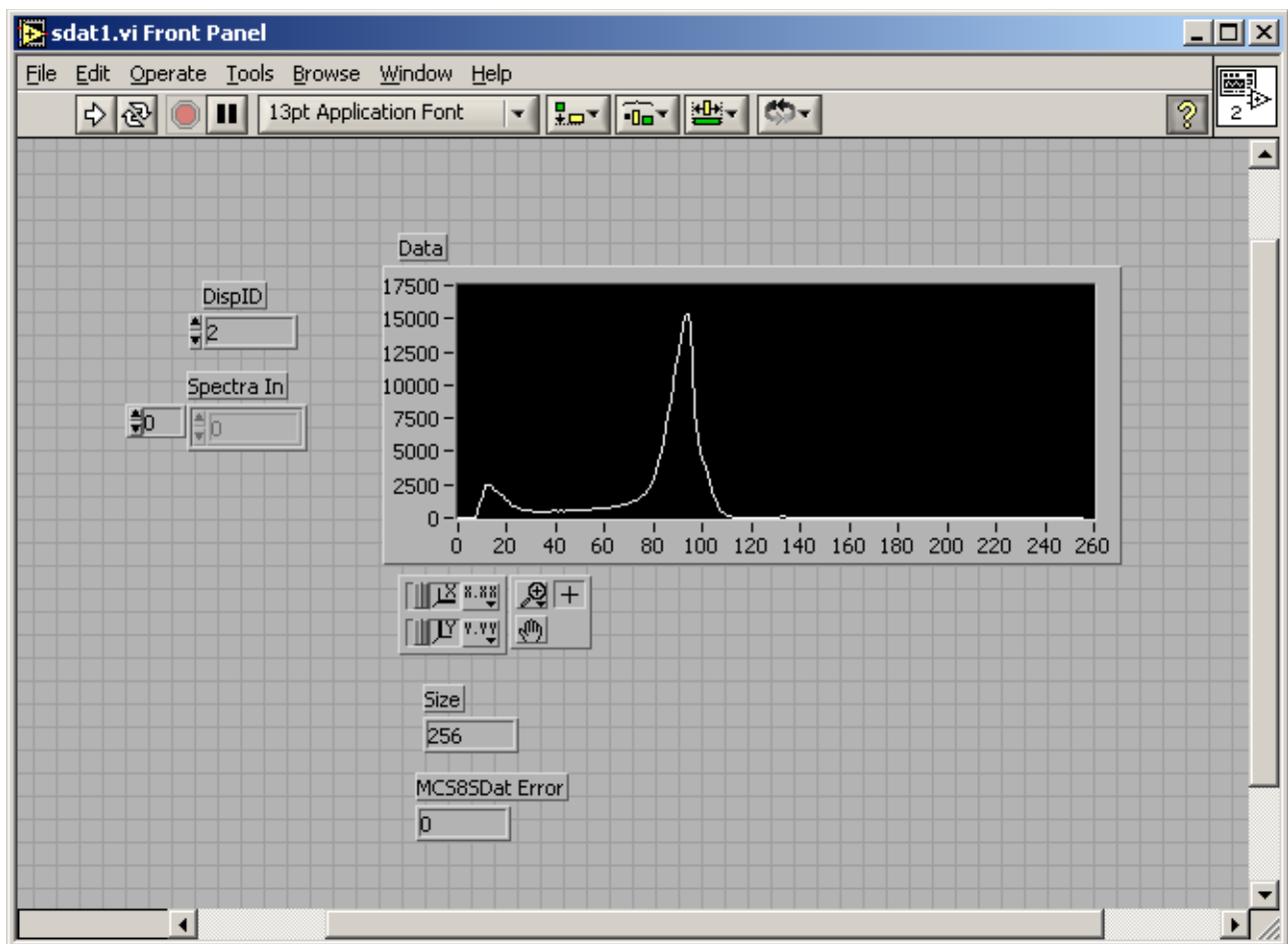
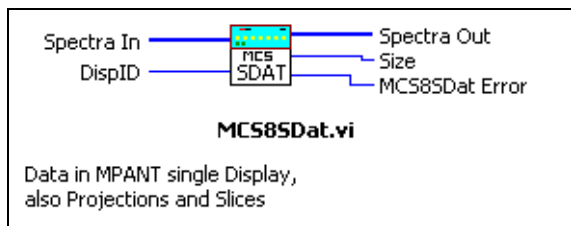


Fig. 2.5: Data from special MPANT views like slices or projections

SDAT1.VI contained in MCS8LV.LLB demonstrates how to access special single spectra like slices or projections of ROIs calculated within the MPANT program. Using the MPANT software create a projection of a ROI or a slice from a dual parameter spectra. Then start this VI, enter the Display Id shown within curved

brackets in the title bar of the display window in MPANT and run the VI: The SDAT1.VI demonstrates the use of MCS8SDat.VI contained in MCS8LV.LLB.



SDAT.VI has the following inputs:

DispID: (I32) ID number of the display view as shown in round brackets in the title bar of the Window in MPANT

Spectra In: One dimensional array [I32] to be resized. May be left open.

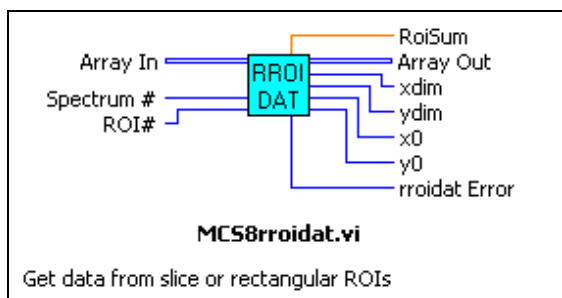
The outputs of SDAT.VI are:

Spectra Out: One dimensional array [I32] containing the data.

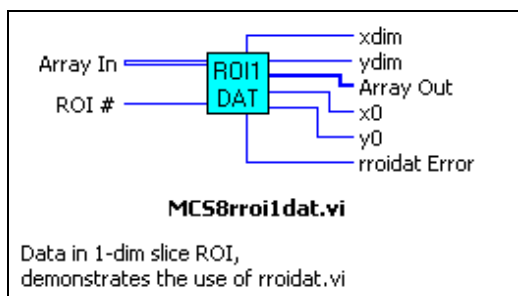
Size: dimension (I32) of the Array.

Sdat Error (I32): 0: ok
-4: MPANT not running
-5: no data.

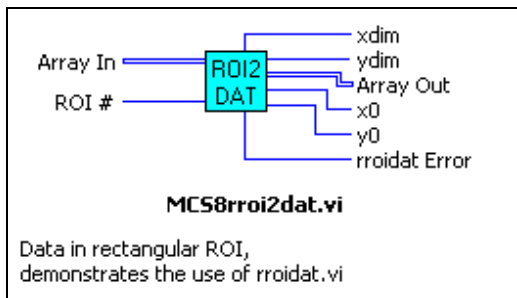
2.15 Get data from rectangular ROI



MCS8rroidat can be used to get data inside a rectangular or slice ROI. Enter the Spectrum # and the ROI number, for example 1 for the first TOF spectrum and 1 for the first ROI inside that spectrum.



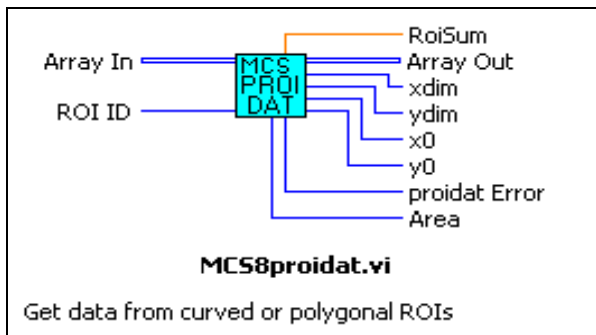
MC8rroi1dat.vi demonstrates the use of MCS8rroidat.vi for single spectra.



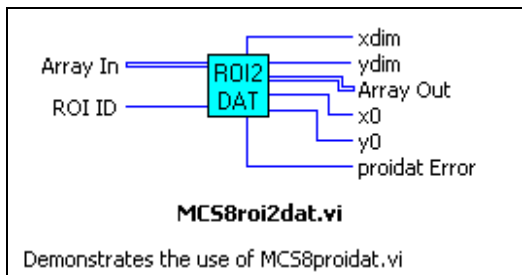
MCS8roi2dat.vi demonstrates the use of MCS8rroidat.vi for rectangular ROIs in dual parameter spectra.

2.16 Get Data from polygonal ROI

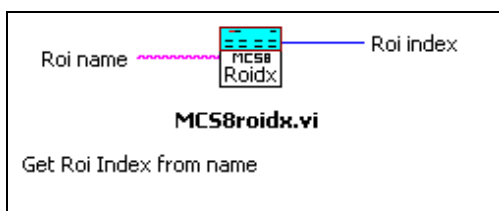
MCS8proidat.vi can be used to get data inside a two-dimensional polygonal ROI. The ROI ID to enter is the number like 900 shown in the MPANT display.



MCS8roi2dat.vi demonstrates the use of MCS8proidat.vi



2.17 Get ROI Index from ROI name



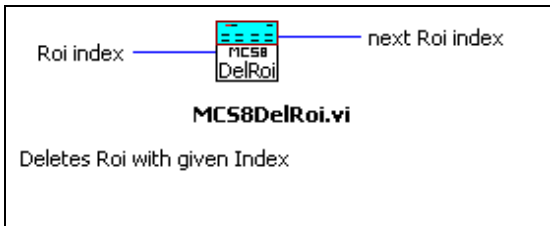
MCS8roidx.vi gets a unique index to address ROIs from named ROI's.

Rectangular or 1D ROIs: LOWORD is the spectra number, HIWORD is the ROI number (1,2,...).

Polygonal ROIs: LOWORD is an entry number, HIWORD is the roiid = 100 * spectra_number + ROI_number.

returns 0 if not found.

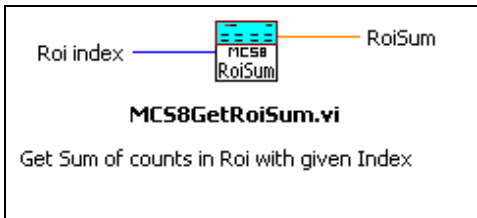
2.18 Delete ROI with given Index



MCS8DelRoi.vi deletes a ROI with given index.

A combined DelNamedROI.vi in MCS8.LLB can be used to delete a named ROI.

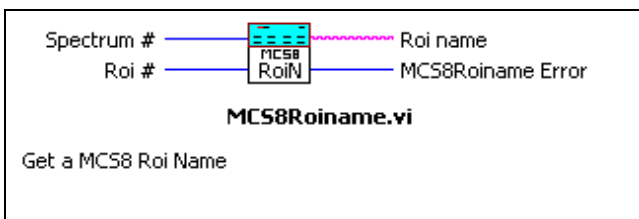
2.19 Get ROI sum



MCS8GetRoiSum.vi gets the sum of counts in a ROI with given index.

A combined NamedRoiSum.vi in MCS8.LLB can be used to get the ROIsum of a named ROI.

2.20 Get ROI Name



MCS8RoiName.vi gets the name of a ROI in a spectra. ROI # 0...127 are 2-point (rectangular or slice) ROIs, ROI #128...191 are polygonal ROIs. The error code has the following meanings:

0: ok

4. no data available

3 Using the DMCS8.DLL from Visual Basic

3.1 The Include File

The include file DECLMCS8.BAS contains the structure and function definitions of the DLL.

```
Attribute VB_Name = "DECLMCS8"
```

```
Type Acqstatus
```

```
    Val As Long
```

```
    Val1 As Long
```

```
    Cnt(0 To 7) As Double
```

```
End Type
```

```
Type Acqsetting
```

```
    Range As Long
```

```
    Cftfak As Long
```

```
    Roimin As Long
```

```
    Roimax As Long
```

```
    Nregions As Long
```

```
    Caluse As Long
```

```
    Calpoints As Long
```

```
    Param As Long
```

```
    Offset As Long
```

```
    Xdim As Long
```

```
    Bitshift As Long
```

```
    Active As Long
```

```
    Roipreset As Double
```

```
    Dummy1 As Double
```

```
    Dummy2 As Double
```

```
    Dummy3 As Double
```

```
End Type
```

```
Type Replaysetting
```

```
    Use As Long
```

```
    Modified As Long
```

```
    Limit As Long
```

```
    Speed As Long
```

```
    Timefrom As Double
```

```
    Timeto As Double
```

```
    Timepreset As Double
```

```
    Filename As String * 256
```

```
End Type
```

```
Type Datsetting
```

```
    SaveData As Long
```

```
    Autoinc As Long
```

```
    Fmt As Long
```

```
    Mpafmt As Long
```

```
    Sephead As Long
```

```
    Smpts As Long
```

```
    Caluse As Long
```

```
    Filename As String * 256
```

```
    Specfile As String * 256
```

```
    Command As String * 256
```

```
End Type
```

```
Type Boardsetting
```

```
    Sweepmode As Long
```

```
    Prena As Long
```

```
    Cycles As Long
```

```
    Sequences As Long
```

```
    Syncout As Long
```

```
    Digio As Long
```

```

Digval As Long
Dac0 As Long
Dac1 As Long
Dac2 As Long
Dac3 As Long
Dac4 As Long
Dac5 As Long
Fdac As Long
Tagbits As Long
Extclk As Long
Maxchan As Long
Serno As Long
Ddruse As Long
Active As Long
Holdafter As Double
Swpreset As Double
Fstchan As Double
Timepreset As Double
End Type

Type Acqdef
Ndevices As Long
Ndisplays As Long
Nsystems As Long
Bremote As Long
Sys As Long
Sys0(56) As Long
Sys1(56) As Long
End Type

Declare Sub StoreSettingData Lib "DMCS8.DLL" Alias "#2" (Setting As Acqsetting, ByVal Ndisplay As Long)
Declare Function GetSettingData Lib "DMCS8.DLL" Alias "#3" (Setting As Acqsetting, ByVal Ndisplay As Long) As Long
Declare Function GetStatusData Lib "DMCS8.DLL" Alias "#5" (Status As Acqstatus, ByVal Ndevice As Long) As Long
Declare Sub Start Lib "DMCS8.DLL" Alias "#6" (ByVal Nsystem As Long)
Declare Sub Halt Lib "DMCS8.DLL" Alias "#7" (ByVal Nsystem As Long)
Declare Sub Continue Lib "DMCS8.DLL" Alias "#8" (ByVal Nsystem As Long)
Declare Sub NewSetting Lib "DMCS8.DLL" Alias "#9" (ByVal Ndisplay As Long)
Declare Function ServExec Lib "DMCS8.DLL" Alias "#10" (ByVal Clwnd As Long) As Long
Declare Function GetSpec Lib "DMCS8.DLL" Alias "#13" (ByVal I As Long, ByVal Ndisplay As Long) As Long
Declare Sub SaveSetting Lib "DMCS8.DLL" Alias "#14" ()
Declare Function GetStatus Lib "DMCS8.DLL" Alias "#15" (ByVal Ndevice As Long) As Long
Declare Sub EraseData Lib "DMCS8.DLL" Alias "#16" (ByVal Nsystem As Long)
Declare Sub SaveData Lib "DMCS8.DLL" Alias "#17" (ByVal Ndevice As Long, ByVal All As Long)
Declare Sub GetBlock Lib "DMCS8.DLL" Alias "#18" (Hist As Long, ByVal Start As Long, ByVal Size As Long, ByVal Stp As Long, ByVal Ndisplay As Long)
Declare Function GetDefData Lib "DMCS8.DLL" Alias "#20" (Def As Acqdef) As Long
Declare Sub LoadData Lib "DMCS8.DLL" Alias "#21" (ByVal Ndevice As Long, ByVal All As Long)
Declare Sub NewData Lib "DMCS8.DLL" Alias "#22" ()
Declare Sub HardwareDlg Lib "DMCS8.DLL" Alias "#23" (ByVal Item As Long)
Declare Sub UnregisterClient Lib "DMCS8.DLL" Alias "#24" ()
Declare Sub DestroyClient Lib "DMCS8.DLL" Alias "#25" ()
Declare Sub RunCmd Lib "DMCS8.DLL" Alias "#28" (ByVal Ndevice As Long, ByVal Cmd As String)
Declare Sub AddData Lib "DMCS8.DLL" Alias "#29" (ByVal Ndisplay As Long, ByVal All As Long)
Declare Function LVGetRoi Lib "DMCS8.DLL" Alias "#30" (Roi As Long, ByVal Ndisplay As Long) As Long
Declare Function LVGetCnt Lib "DMCS8.DLL" Alias "#31" (Cnt As Double, ByVal Ndisplay As Long) As Long
Declare Function LVGetOneCnt Lib "DMCS8.DLL" Alias "#32" (Cnt As Double, ByVal Ndisplay As Long, ByVal Cntnum As Long) As Long
Declare Function LVGetStr Lib "DMCS8.DLL" Alias "#33" (ByVal Comment As String, ByVal Ndisplay As Long) As Long
Declare Sub SubData Lib "DMCS8.DLL" Alias "#34" (ByVal Ndisplay As Long, ByVal All As Long)
Declare Sub Smooth Lib "DMCS8.DLL" Alias "#35" (ByVal Ndisplay As Long)

```

```
Declare Function GetMCSSetting Lib "DMCS8.DLL" Alias "#39" (Msetting As Boardsetting) As Long
Declare Function GetDatSetting Lib "DMCS8.DLL" Alias "#41" (Dsetting As Datsetting) As Long
Declare Function GetReplaySetting Lib "DMCS8.DLL" Alias "#43" (Rsetting As Replaysetting) As Long
```



```
Dim Chan As Long
Dim Hist(24) As Long
Dim Toggle As Integer
```

```
Private Sub CommandContinue_Click()
    Call Continue(0)
End Sub
```

```
Private Sub CommandDatasettings_Click()
    Call GetDatSetting(Dsetting)
    LabelSavedata.Caption = Dsetting.SaveData
    LabelAutoinc.Caption = Dsetting.Autoinc
    LabelFmt.Caption = Dsetting.Fmt
    LabelMpafmt.Caption = Dsetting.Mpafmt
    LabelSephead.Caption = Dsetting.Sephead
    LabelSmpts.Caption = Dsetting.Smpts
    LabelAddcal.Caption = Dsetting.Caluse
    LabelMpafilename.Caption = Dsetting.Filename
    Labelspecfile.Caption = Dsetting.Specfile
    LabelCommand.Caption = Dsetting.Command
End Sub
```

```
Private Sub CommandErase_Click()
    Call EraseData(0)
End Sub
```

```
Private Sub CommandExecute_Click()
    Dim a As String * 1024
    Mid$(a, 1) = TextCommand.Text
    Call RunCmd(0, a)
    LabelRespons.Caption = a
    Mcano = Val(TextMC.Text)
    Ret = GetStatus(Mcano)
    Ret = GetStatusData(Status, 0)
    Call UpdateMpStatus
    Ret = GetStatusData(Status, Mcano)
    Call UpdateStatus
End Sub
```

```
Private Sub CommandGetspec_Click()
    Mcano = Val(TextMC.Text)
    Chan = Val(TextChan.Text)
    Call GetBlock(Hist(0), Chan, Chan + 24, 1, Mcano)
    For I = 0 To 23 Step 1
        LabelData(I).Caption = Hist(I)
    Next I
End Sub
```

```
Private Sub CommandGetString_Click()
    Dim b As String * 1024
    Mcano = Val(TextMC.Text)
    Ret = LVGetStr(b, Mcano)
    LabelLine(0).Caption = Mid$(b, 1, 60)
    LabelLine(1).Caption = Mid$(b, 61, 60)
    LabelLine(2).Caption = Mid$(b, 121, 60)
    LabelLine(3).Caption = Mid$(b, 181, 60)
    LabelLine(4).Caption = Mid$(b, 241, 60)
    LabelLine(5).Caption = Mid$(b, 301, 60)
    LabelLine(6).Caption = Mid$(b, 361, 60)
    LabelLine(7).Caption = Mid$(b, 421, 60)
    LabelLine(8).Caption = Mid$(b, 481, 60)
```

```
LabelLine(9).Caption = Mid$(b, 541, 60)
LabelLine(10).Caption = Mid$(b, 601, 60)
LabelLine(11).Caption = Mid$(b, 881, 60)
LabelLine(12).Caption = Mid$(b, 961, 60)
LabelLine(13).Caption = Mid$(b, 661, 100)
End Sub
```

```
Private Sub CommandHalt_Click()
    Call Halt(0)
End Sub
```

```
Private Sub CommandSave_Click()
    Call SaveData(0, 1)
End Sub
```

```
Private Sub CommandSetting_Click()
    Mcano = Val(TextMC.Text)
    If GetSettingData(Setting, Mcano) = 1 Then
        Call UpdateSetting
    End If
End Sub
```

```
Private Sub CommandStart_Click()
    Call Start(0)
End Sub
```

```
Private Sub CommandUpdate_Click()
    Mcano = Val(TextMC.Text)
    Ret = GetStatus(Mcano)
    If GetStatusData(Status, Mcano) = 1 Then
        Call UpdateStatus
    End If
End Sub
```

```
Private Sub Form_Load()
    OldStarted = 0
    Mcano = 0
    Sysno = 0
    Chan = 0
    Ret = ServExec(0)
    Ret = GetStatus(0)
    Ret = GetStatusData(Status, 0)
    Call UpdateMpStatus
    Ret = GetStatusData(Status, Mcano)
    Call UpdateStatus
    Ret = GetSettingData(Setting, 0)
    Call UpdateSetting
End Sub
```

```
Private Sub Timer1_Timer()
    Mcano = Val(TextMC.Text)
    If Mcano > 16 Then
        Mcano = 16
    End If
    If Mcano < 0 Then
        Mcano = 0
    End If
    Ret = GetStatus(0)
```

```
If GetStatusData(Status, 0) = 1 Then
  If Status.Val > 0 Or OldStarted > 0 Then
    Toggle = Not Toggle
    OldStarted = Status.Val
    Call UpdateMpStatus
    If GetStatusData(Status, Mcano) = 1 Then
      Call UpdateStatus
    End If
  End If
End If
End Sub

Private Sub UpdateMpStatus()
  LabelStarted.Caption = Status.Val
  LabelRuntime.Caption = Status.Cnt(0)
  LabelSweeps.Caption = Status.Cnt(5)
  LabelStarts.Caption = Status.Cnt(6)
End Sub

Private Sub UpdateStatus()
  LabelMaxval.Caption = Status.Val1
  LabelOfs.Caption = Status.Cnt(1)
  LabelTotalsum.Caption = Status.Cnt(2)
  LabelRoisum.Caption = Status.Cnt(3)
  LabelTotalrate.Caption = Format$(Status.Cnt(4), "#####0.0#")
End Sub

Private Sub UpdateSetting()
  LabelRange.Caption = Setting.Range
  LabelCtffak.Caption = Setting.Ctffak
  LabelRoimin.Caption = Setting.Roimin
  LabelRoimax.Caption = Setting.Roimax
  LabelNregions.Caption = Setting.Nregions
  LabelCaluse.Caption = Setting.Caluse
  LabelCalpoints.Caption = Setting.Calpoints
  LabelParam.Caption = Setting.Param
  LabelOffset.Caption = Setting.Offset
  LabelXdim.Caption = Setting.Xdim
  LabelBitshift.Caption = Setting.Bitshift
  LabelActive.Caption = Setting.Active
  LabelRoipreset.Caption = Setting.Roipreset
End Sub
```

4 Using the DMCS8.DLL from C

In the following an example is shown how to control the MCS8 from a simple console application written in Microsoft C.

```

C:\MCS8>tstmcs8
OFF
runtime= 0.000
sweeps= 0.000000
starts= 0.000000

Commands:
Q          Quit
?          Help
S          Show Status
H          Halt
T          Show Setting
B          Show BoardSetting
CHN=x      Switch to CHN #x
rdig       Read Dig. I/O port
w5 aabb    Write aabb into Reg.5
r5         Read Reg 5
rx0        Read Reg 0..f
rx7        Read Reg 70..7f
reep0      Read 64 byte from eeprom at address 0
sleep=10   Sleep 10 msec
run filename
<... more see command language in MPANT help>

t
CHN 0:
range=     4096
cftfak=    0x2580100
roimin=    0
roimax=    4096
nregions=  0
caluse=    1
calpoints= 0
param=     0x0
offset=    0x0
xdim=      0
bitshift=  0
active=    0x1
roipreset= 10

sweepmode= 0x200a080
prena=     0x0
cycles=    18
sequences= 1
syncout=   0x0
digio=     0x0
digval=    0
dac0=      0x92c
dac1=      0x92c
dac2=      0x92c
dac3=      0x92c
dac4=      0x92c
dac5=      0x92c
tagbits=   16
extclk=    0
periods=   2
serno=     1004
ddruse=    0x17
active=    1
holdafter= 0
swpreset=  1e+006
fstchan=   0
timepreset= 20

savedata=  0
autoinc=   0
fmt=       0
mpafmt=    0
sephead=   0
filename=  TEST.mpa
  
```

Fig. 4.1: The tstmcs8 Demo program written in C

4.1 The Include File

The include file DMCS8.h contains the function definitions of the DLL. It includes also the structure definitions from struct.h listed in the appendix 6.1.

```
#ifdef __cplusplus
extern "C"
{
#endif
#include "struct.h"
#include "scaler.h"
// pure constant definitions are omitted here

/** FUNCTION PROTOTYPES (do not change) */
#ifdef DLL

BOOL APIENTRY DIIMain(HANDLE hInst, DWORD ul_reason_being_called, LPVOID lpReserved);
VOID APIENTRY StoreSettingData(ACQSETTING *Setting, int nDisplay);
// Stores Settings into the DLL

int APIENTRY GetSettingData(ACQSETTING *Setting, int nDisplay);
// Get Settings stored in the DLL

VOID APIENTRY StoreExtSettingData(EXTACQSETTING *Setting, int nDisplay);
// Stores extended Settings into the DLL

int APIENTRY GetExtSettingData(EXTACQSETTING *Setting, int nDisplay);
// Get extended Settings stored in the DLL

VOID APIENTRY StoreStatusData(ACQSTATUS *Status, int nDisplay);
// Store the Status into the DLL

int APIENTRY GetStatusData(ACQSTATUS *Status, int nDisplay);
// Get the Status

VOID APIENTRY Start(int nSystem); // Start
VOID APIENTRY Halt(int nSystem); // Halt
VOID APIENTRY Continue(int nSystem); // Continue
VOID APIENTRY NewSetting(int nDevice); // Indicate new Settings to Server
UINT APIENTRY ServExec(HWND ClientWnd); // Execute the Server
VOID APIENTRY StoreData(ACQDATA *Data, int nDisplay);
// Stores Data pointers into the DLL

int APIENTRY GetData(ACQDATA *Data, int nDisplay);
// Get Data pointers

int APIENTRY GetSpec(int i, int nDisplay);
// Get a spectrum value

VOID APIENTRY SaveSetting(void); // Save Settings

int APIENTRY GetStatus(int nDevice); // Request actual Status from Server
VOID APIENTRY Erase(int nSystem); // Erase spectrum
VOID APIENTRY SaveData(int nDisplay, int all); // Saves data
VOID APIENTRY GetBlock(int *hist, int start, int end, int step, int nDisplay);
// Get a block of spectrum data

VOID APIENTRY StoreDefData(ACQDEF *Def);
// Store System Definition into DLL

int APIENTRY GetDefData(ACQDEF *Def);
// Get System Definition
```

```
VOID APIENTRY StoreCDefData(COINCDEF *Def);
int APIENTRY GetCDefData(COINCDEF *Def);
VOID APIENTRY LoadData(int nDisplay, int all);    // Loads data
VOID APIENTRY AddData(int nDisplay, int all);    // Adds data
VOID APIENTRY SubData(int nDisplay, int all);    // Subtracts data
VOID APIENTRY Smooth(int nDisplay);    // Smooth data
VOID APIENTRY NewData(void);    // Indicate new ROI or string Data
VOID APIENTRY HardwareDlg(int item);    // Calls the Settings dialog box
VOID APIENTRY UnregisterClient(void);    // Clears remote mode from MCDWIN
VOID APIENTRY DestroyClient(void);    // Close MCDWIN
UINT APIENTRY ClientExec(HWND ServerWnd);
    // Execute the Client MCDWIN.EXE
int APIENTRY LVGetDat(unsigned int *datap, int nDisplay);
    // Copies the spectrum to an array
VOID APIENTRY RunCmd(int nDisplay, LPSTR Cmd);
    // Executes command
int APIENTRY LVGetRoi(unsigned int *roip, int nDisplay);
    // Copies the ROI boundaries to an array
int APIENTRY LVGetOneRoi(int nDisplay, int roinum, int *x1, int *x2);
    // Get one ROI boundary
int APIENTRY LVGetCnt(double far *cntp, int nDisplay);
    // Copies Cnt numbers to an array
int APIENTRY LVGetStr(char far *strp, int nDisplay);
    // Copies strings to an array
VOID APIENTRY StoreMCSSetting(BOARDSETTING *Defmc, int ndev);
    // Store BOARDSETTING Definition into DLL
int APIENTRY GetMCSSetting(BOARDSETTING *Defmc, int ndev);
    // Get BOARDSETTING Definition from DLL
VOID APIENTRY StoreDatSetting(DATSETTING *Defdat);
    // Store Data Format Definition into DLL
int APIENTRY GetDatSetting(DATSETTING *Defdat);
    // Get Data Format Definition from DLL
VOID APIENTRY StoreReplaySetting(REPLAYSETTING *Repldat);
    // Store Replay Settings into DLL
int APIENTRY GetReplaySetting(REPLAYSETTING *Repldat);
    // Get Replay Settings from DLL
int APIENTRY GetDatInfo(int nDisplay, int *xmax, int *ymax);
    // returns spectra length;
int APIENTRY GetDatPtr(int nDisplay, int *xmax, int *ymax, LPSTR *pt);
    // Get a temporary pointer to spectra data
int APIENTRY ReleaseDatPtr(void);
    // Release temporary data pointer
int APIENTRY GetSVal(int DspID, int xval);
    // Get special display data like projections or slices from MPANT
int APIENTRY GetRoiIndex(LPSTR roiname);
    // get a unique index to address ROIs from named ROI's.
    // rectangular or 1D ROIs:
    //  LOWORD is the spectra number,
```

```

// HIWORD is the ROI number (1,2,...)
// polygonal ROIs:
// LOWORD is an entry number
// HIWORD is the roiid = 100 * spectra_number + ROI_number
// returns 0 if not found.

int APIENTRY DeleteRoi(DWORD roiindex);
// deletes ROI with given index

int APIENTRY SelectRoi(DWORD roiindex);
// selects ROI with given index

int APIENTRY GetRoiSum(DWORD roiindex, double *sum);
// get sum of counts in ROI,
// returns roiindex, or 0 if not found

int APIENTRY BytearrayToShortarray(short *Shortarray, char *Bytearray, int length);
// auxiliary function for VB.NET to convert strings

int APIENTRY LedBlink(int nDev);
// Lets the front leds blink for a while

int APIENTRY DigInOut(int value, int enable);
// controls Dig I/O, returns digin

int APIENTRY LVGetSpecLength(int nDisplay);

int APIENTRY LVGetRoiName(char *strp, int nDisplay);
// get Roi names

int APIENTRY LVGetDatSetting(LVDATSETTING *Defdat, LPSTR filename, LPSTR specfile, LPSTR
command);

int APIENTRY LVGetReplaySetting(LVREPLAYSETTING *Repldat, LPSTR filename);

int APIENTRY LVGetDefData(LVACQDEF *Def);

int APIENTRY LVGetRoiDat(int nDisplay, int roinum, int x0, int y0, int xdim, int ydim, int xmax,
double *RoiSum, int *datp, double *area);

int APIENTRY LVGetRoiRect(int nDisplay, int roinum, int *x0, int *y0, int *xdim, int *ydim, int *xmax);

int APIENTRY LVGetProiDat(int roiid, int x0, int y0, int xdim, int ydim, double *roisum, int *datp);

int APIENTRY LVGetCDefData(LVCOINCDEF *Def);

#else

typedef int (WINAPI *IMPAGETSETTING) (ACQSETTING *Setting, int nDisplay);
// Get Spectra Settings stored in the DLL

typedef int (WINAPI *IMPAGETSTATUS) (ACQSTATUS *Status, int nDisplay);
// Get the Status

typedef VOID (WINAPI *IMPARUNCMD) (int nDisplay, LPSTR Cmd);
// Executes command

typedef int (WINAPI *IMPAGETCNT) (double *cntp, int nDisplay);
// Copies Cnt numbers to an array

typedef int (WINAPI *IMPAGETROI) (unsigned int *roip, int nDisplay);
// Copies the ROI boundaries to an array

typedef int (WINAPI *IMPAGETDEF) (ACQDEF *Def);
// Get System Definition

typedef int (WINAPI *IMPAGETDAT) (unsigned int *datp, int nDisplay);
// Copies the spectrum to an array

typedef int (WINAPI *IMPAGETSTR) (char *strp, int nDisplay);
// Copies strings to an array

```

```
typedef UINT (WINAPI *IMPASERVEEXEC) (HWND ClientWnd); // Register client at server MCS8.EXE
typedef int (WINAPI *IMPANEWSTATUS) (int nDev); // Request actual Status from Server
typedef int (WINAPI *IMPAGETMCSSET) (BOARDSETTING *Board, int nDevice);
// Get MCSSettings from DLL
typedef int (WINAPI *IMPAGETDATSET) (DATSETTING *Defdat);
// Get Data Format Definition from DLL
typedef int (WINAPI *IMPADIGINOUT) (int value, int enable);
// controls Dig I/O, returns digin
typedef int (WINAPI *IMPADACOUT) (int value); // output Dac value as analogue voltage
typedef VOID (WINAPI *IMPASTART) (int nSystem); // Start
typedef VOID (WINAPI *IMPAHALT) (int nSystem); // Halt
typedef VOID (WINAPI *IMPACONTINUE) (int nSystem); // Continue
typedef VOID (WINAPI *IMPAERASE) (int nSystem); // Erase spectrum
#endif
#ifdef __cplusplus
}
#endif
```


4.2 The C demo program

The source of the simple C program is shown here: It shows how to access the DLL and to get Status, Settings and spectrum data. To perform actions like start, halt, continue, erase, just send the corresponding commands using the command language.

```
// -----  
// TSTMCS8.C : DMCS8.DLL Software driver C example  
// -----  
  
#include <stdio.h>  
#include <string.h>  
#include <windows.h>  
#include <time.h>  
  
#undef DLL  
#include "dmca4.h"  
  
HANDLE      hDLL = 0;  
  
IMPAGETSETTING    lpSet=NULL;  
IMPANEWSTATUS     lpNewStat=NULL;  
IMPAGETSTATUS     lpStat=NULL;  
IMPARUNCMD        lpRun=NULL;  
IMPAGETCNT        lpCnt=NULL;  
IMPAGETROI        lpRoi=NULL;  
IMPAGETDAT        lpDat=NULL;  
IMPAGETSTR        lpStr=NULL;  
IMPASERVEEXEC     lpServ=NULL;  
IMPAGETDATSET     lpGetDatSet=NULL;  
IMPAGETMCSSET     lpGetMCSSet=NULL;  
IMPADIGINOUT      lpDigInOut=NULL;  
IMPASTART         lpStart=NULL;  
IMPAHALT          lpHalt=NULL;  
IMPACONTINUE      lpContinue=NULL;  
IMPAERASE         lpErase=NULL;  
IMPALVGETCDEF     lpGetLCDef=NULL;  
IMPAGETBRDSET     lpGetBrdSet=NULL;  
  
ACQSETTING        Setting={0};  
ACQDATA           Data={0};  
ACQDEF            Def={0};  
ACQSTATUS         Status={0};  
DATSETTING        DatSetting={0};  
BOARDSETTING      MCSSetting={0};  
  
int nDev=0;  
  
void help()  
{  
    printf("Commands:\n");  
    printf("Q      Quit\n");  
    printf("?      Help\n");  
    printf("S      Show Status\n");  
    printf("H      Halt\n");  
    printf("T      Show Setting\n");  
    printf("B      Show BoardSetting\n");  
    printf("CHN=x  Switch to CHN #x\n");  
    printf("(... more see command language in MPANT help)\n");  
    printf("\n");  
}
```

```
void PrintMpaStatus(ACQSTATUS *Stat)
{
    if(Stat->started == 1) printf("ON\n");
    else if(Stat->started & 0x02) printf("READ OUT\n");
    else printf("OFF\n");
    printf("runtime=  %.3f\n", Stat->cnt[ST_RUNTIME]);
    printf("sweeps=  %.3f\n", Stat->cnt[ST_SWEEPS]);
    printf("starts=  %f\n", Stat->cnt[ST_STARTS]);
}

void PrintStatus(ACQSTATUS *Stat)
{
    printf("totalsum=  %.0f\n", Stat->cnt[ST_TOTALSUM]);
    printf("roisum=  %.0f\n", Stat->cnt[ST_ROISUM]);
    printf("rate=  %.2f\n", Stat->cnt[ST_ROIRATE]);
    printf("ofls=  %.2f\n", Stat->cnt[ST_OFLS]);
}

void PrintDatSetting(DATSETTING *Set)
{
    printf("savedata= %d\n", Set->savedata);
    printf("autoinc= %d\n", Set->autoinc);
    printf("fmt= %d\n", Set->fmt);
    printf("mpafmt= %d\n", Set->mpafmt);
    printf("sephead= %d\n", Set->sephead);
    printf("filename= %s\n", Set->filename);
}

void PrintMCSSetting(BOARDSETTING *Set)
{
    printf("sweepmode=  0x%x\n", Set->sweepmode);
    printf("prena=  0x%x\n", Set->prena);
    printf("cycles=  %d\n", Set->cycles);
    printf("sequences=  %d\n", Set->sequences);
    printf("syncout=  0x%x\n", Set->syncout);
    printf("digio=  0x%x\n", Set->digio);
    printf("digval=  %d\n", Set->digval);
    printf("dac0=  0x%x\n", Set->dac0);
    printf("dac1=  0x%x\n", Set->dac1);
    printf("dac2=  0x%x\n", Set->dac2);
    printf("dac3=  0x%x\n", Set->dac3);
    printf("dac4=  0x%x\n", Set->dac4);
    printf("dac5=  0x%x\n", Set->dac5);
    // printf("fdac=  0x%x\n", Set->fdac);
    printf("tagbits=  %d\n", Set->tagbits);
    printf("extclk=  %d\n", Set->extclk);
    printf("periods=  %d\n", Set->periods);
    printf("serno=  %d\n", Set->serno);
    printf("ddruse=  0x%x\n", Set->ddruse);
    printf("active=  %d\n", Set->active);
    printf("holdafter=  %lg\n", Set->holdafter);
    printf("swpreset=  %lg\n", Set->swpreset);
    printf("fstchan=  %lg\n", Set->fstchan);
    printf("timepreset=  %lg\n", Set->timepreset);
}

void PrintSetting(ACQSETTING *Set)
{
    printf("range=  %ld\n", Set->range);
    printf("cftfak=  0x%x\n", Set->cftfak);
    printf("roimin=  %ld\n", Set->roimin);
}
```

```

printf("roimax=  %ld\n", Set->roimax);
printf("nregions= %d\n", Set->nregions);
printf("caluse=   %d\n", Set->caluse);
printf("calpoints= %d\n", Set->calpoints);
printf("param=    0x%lx\n", Set->param);
printf("offset=   0x%lx\n", Set->offset);
printf("xdim=     %d\n", Set->xdim);
printf("bitshift= %d\n", Set->bitshift);
printf("active=   0x%lx\n", Set->active);
printf("ROIpreset= %lg\n", Set->eventpreset);
}

int run(char *command)
{
    int err;
    if (!strcmp(command, "?")) help();
    else if (!strcmp(command, "rdig")) { // read Dig I/O port
        if (lpDigInOut) {
            err = (*lpDigInOut)(0xff, 0);
            printf("%x\n", err);
        }
    }
    else if (!strcmp(command, "wdig=", 5)) { // write Dig I/O port (open drain)
        if (lpDigInOut) {
            unsigned int val;
            sscanf(command+5, "%x", &val);
            err = (*lpDigInOut)(val, 0);
            printf("%x\n", err);
        }
    }
    else if (!strcmp(command, "pdig=", 5)) { // write Dig I/O port (push-pull)
        if (lpDigInOut) {
            unsigned int val;
            sscanf(command+5, "%x", &val);
            err = (*lpDigInOut)(val, 0xff);
            printf("%x\n", err);
        }
    }
    else if (!strcmp(command, "Q"))
        return 1;
    else if (!strcmp(command, "S")) {
        err = (*lpStat)(&Status, nDev);
        if (nDev) PrintStatus(&Status);
        else PrintMpaStatus(&Status);
        return 0;
    }
    else if (!strcmp(command, "T")) {
        // spectra settings
        err = (*lpSet)(&Setting, nDev);
        printf("CHN %d:\n", nDev);
        PrintSetting(&Setting);
        if (nDev==0) { // MPA settings
            err = (*lpGetMCSSet)(&MCSSetting, 0);
            PrintMCSSetting(&MCSSetting);
            // DATSettings
            err = (*lpGetDatSet)(&DatSetting);
            PrintDatSetting(&DatSetting);
        }
        return 0;
    }
    else if (!strcmp(command, "H")) {
        (*lpHalt)(0);
    }
}

```

```

        return 0;
    }
    else if(!strnicmp(command, "CHN=", 4)) {
        sscanf(command+4, "%d", &nDev);
        (*IpRun)(0, command);
    }
    else if (!stricmp(command,"MPA")) {
        nDev=0;
        (*IpRun)(0, command);
    }
    else {
        (*IpRun)(0, command);
        printf("%s\n", command);
    }
    return 0;
}

int readstr(char *buff, int buflen)
{
    int i=0,ic;

    while ((ic=getchar()) != 10) {
        if (ic == EOF) {
            buff[i]='\0';
            return 1;
        }
        if (ic == 13) ic=0;
        buff[i]=(char)ic;
        i++;
        if (i==buflen-1) break;
    }
    buff[i]='\0';
    return 0;
}

//int PASCAL WinMain(HINSTANCE hInst, HINSTANCE hPrevInst, LPSTR lpCmd, int nShow)
void main(int argc, char *argv[])
{
    long Errset=0;
    char command[80];

    hDLL = LoadLibrary("DMCS8.DLL");
    if(hDLL){
        IpSet=(IMPAGETSETTING)GetProcAddress(hDLL,"GetSettingData");
        IpNewStat=(IMPANEWSTATUS)GetProcAddress(hDLL,"GetStatus");
        IpStat=(IMPAGETSTATUS)GetProcAddress(hDLL,"GetStatusData");
        IpRun=(IMPARUNCMD)GetProcAddress(hDLL,"RunCmd");
        IpCnt=(IMPAGETCNT)GetProcAddress(hDLL,"LVGetCnt");
        IpRoi=(IMPAGETROI)GetProcAddress(hDLL,"LVGetRoi");
        IpDat=(IMPAGETDAT)GetProcAddress(hDLL,"LVGetDat");
        IpStr=(IMPAGETSTR)GetProcAddress(hDLL,"LVGetStr");
        IpServ=(IMPASERVEXEC)GetProcAddress(hDLL,"ServExec");
        IpGetDatSet=(IMPAGETDATSET)GetProcAddress(hDLL,"GetDatSetting");
        IpGetMCSSet=(IMPAGETMCSSSET)GetProcAddress(hDLL,"GetMCSSSetting");
        IpStart=(IMPASTART)GetProcAddress(hDLL,"Start");
        IpHalt=(IMPAHALT)GetProcAddress(hDLL,"Halt");
        IpContinue=(IMPACONTINUE)GetProcAddress(hDLL,"Continue");
        IpErase=(IMPAERASE)GetProcAddress(hDLL,"Erase");
        IpDigInOut=(IMPADIGINOUT)GetProcAddress(hDLL,"DigInOut"); }
    else return;

    // Initialize parameters

```

```
Errset = (*lpNewStat)(0);
Errset = (*lpStat)(&Status, 0);
PrintMpaStatus(&Status);

help();
while(TRUE)
{
    readstr(command, 80);
    if (run(command)) break;
}
FreeLibrary(hDLL);
return;
}
```

5 Using the DMCS8.DLL from C#

To get the transfer working of a data block from the DLL to a program written in C#, it is important to change the project properties of the C# program. Under “build” you will find in Visual Studio a check box “allow unsafe code”. This must be checked. For the processor type change the default value “Any CPU” to “x64”. Then the following code example will work with the 64-bit Software.

5.1 The C# demo program

The source of a simple C# console program is shown here: It shows how to access the DLL and to get Status, Settings and spectrum data. To perform actions like start, halt, continue, erase, just send the corresponding commands using the command language.

```
using System;
using System.Collections.Generic;
using System.Linq;
using System.Text;
using System.Threading.Tasks;
using System.Runtime.InteropServices;

namespace MCS8Demo1
{
    static class Constants
    {
        public const int ST_RUNTIME = 0;
        public const int ST_OFLS = 1;
        public const int ST_TOTALSUM = 2;
        public const int ST_ROISUM = 3;
        public const int ST_ROIRATE = 4;
        public const int ST_SWEEPS = 5;
        public const int ST_STARTS = 6;
        public const int ST_ZEROEVTS = 7;
    }

    // MCS Channel Status
    public struct ACQSETTING
    {
        public int range;           // spectrum length
        public int cftfak;         // LOWORD: 256 * cft factor (t_after_peak / t_to_peak)
        // HIWORD: max pulse width for CFT
        public int roimin;         // lower ROI limit
        public int roimax;         // upper limit: roimin <= channel < roimax
        public int nregions;       // number of regions
        public int caluse;         // bit0: 1 if calibration used, higher bits: formula
        public int calpoints;      // number of calibration points
        public int param;          // (reserved:) for MAP and POS: LOWORD=x, HIWORD=y
        public int offset;         // (reserved:) zoomed MAPS: LOWORD: xoffset, HIWORD, yoffset
        public int xdim;           // (reserved:) x resolution of maps
        public int bitshift;       // LOWORD: Binwidth = 2 ^ (bitshift)
        // HIWORD: Threshold for Coinc
        public int active;         // Spectrum definition words for CHN1..6:
        // active & 0xF ==0 not used
        //      ==1 single
        // bit 8: Enable Tag bits
        // bit 9: start with rising edge
        // bit 10: time under threshold for pulse width
        // bit 11: pulse width mode for any spectra with both edges enabled
        // Spectrum definition words for calc. spectra:
        // active & 0xF ==3 MAP, ((x-xoffs)>>xsh) x ((y-yoffs)>>ysh)
        //      ((x-xoffs)>>xsh) x ((y-timeoffs)>>timesh)
        //      or ((x-timeoffs)>>timesh) x ((y-yoffs)>>ysh)
        // bit4=1: x zoomed MAP
    }
}
```

```

//      bit5=1: y zoomed MAP
//      ==5 SUM, (x + y)>>xsh
//      ==6 DIFF,(x - y + range)>>xsh
//      ==7 ANY, (for compare)
//      ==8 COPY, x
//      ==9 DLL fDLL(x,y,z),
//      ==0xA Sweep HISTORY, Sweepnum(x)
// bit 8..11 xsh, bit 12..15 ysh or bit 8..15 xsh
// HIWORD(active) = condition no. (0=no condition)
public double eventpreset;    // ROI preset value
public double dummy1;        // (Livetime preset)
public double dummy2;        // (Realtime preset)
public double dummy3;        //
}

unsafe public struct DATSETTING
{
    public int savedata;        // bit 0: auto save after stop
    // bit 1: write listfile
    // bit 2: listfile only, no evaluation
    // bit 5: drop zero events
    public int autoinc;        // 1 if auto increment filename
    public int fmt;            // format type (seperate spectra):
    // 0 == ASCII, 1 == binary,
    // 2 == GANAAS, 3 == EMSA, 4 == CSV
    public int mpafmt;        // format used in mpa datafiles
    public int sephead;        // seperate Header
    public int smpts;
    public int caluse;
    unsafe public fixed byte filename[256];
    unsafe public fixed byte specfile[256];
    unsafe public fixed byte command[256];
}

public struct BOARDSETTING
{
    public int sweepmode;        // sweepmode & 0xF: 0 = normal,
    // 1=differential (relative to first stop in sweep)
    // 4=sequential
    // 5=seq.+diff (Ch1), bit0 = differential mode
    // 6 = CORRELATIONS
    // 7 = diff.+Corr.
    // 9=differential to stop in Ch2, bit3 = Ch2 ref (diff.mode)
    // 0xF = Corr.+diff (Ch2)
    // bit 4: Softw. Start
    // bit 5: "Don't show" tagbits
    // bit 6: Endless
    // bit 7: Start event generation
    // bit 8: Enable Tag bits
    // bit 9: start with rising edge
    // bit 10: time under threshold for pulse width
    // bit 11: pulse width mode for any spectra with both edges enabled
    // bit 12: abandon Sweepcounter in Data
    // bit 13: "one-hot" mode with tagbits
    // bit 14: ch6 ref (diff.mode)
    // bit 16..bit 22 ~(input channel enable)
    // bit 24: require data lost bit in data
    // bit 25: don't allow 6 byte datalength
    // bit 27: Folded
    // bit 28: Interleaved
    public int prena;        // bit 0: realtime preset enabled
    // bit 1:

```

```

// bit 2: sweep preset enabled
// bit 3: ROI preset enabled
// bit 4: Starts preset enabled
// bit 5: ROI2 preset enabled
// bit 6: ROI3 preset enabled
// bit 7: ROI4 preset enabled
// bit 8: ROI5 preset enabled
// bit 9: ROI6 preset enabled
// bit 10: ROI7 preset enabled
// bit 11: ROI8 preset enabled
public int cycles;      // for sequential mode
public int sequences;   // for sequential mode
public int syncout;     // LOWORD: sync out; bit 0..5 NIM syncout, bit 8..13 TTL syncout
// bit7: NIM syncout_invert, bit15: TTL syncout_invert
// 0="0", 1=5 MHz, 2=50 MHz, 3=100 MHz, 4=97.656 MHz,
// 5=195.625 MHz, 6= 195 MHz (int ref), 7=Start, 8=Ch1, 9=Ch2, 10=Ch3,
// 11=Ch4, 12=Ch5, 13=Ch6, 14=Ch7, 15=GO, 16=Start_of_sweep, 17=Armed,
// 18=SWEEP_ON, 19=WINDOW, 20=HOLD_OFF, 21=EOS_DEADTIME
// 22=TIME[0],...,51=TIME[29], 52...63=SWEEP[0]..SWEEP[11]
//
public int digio;       // LOWORD: Use of Dig I/O, GO Line:
// bit 0: status dig 0..3
// bit 1: Output digval and increment digval after stop
// bit 2: Invert polarity
// bit 3: Push-Pull output, not possible
// bit 4: Start with Input Dig 4
// bit 5: Start with Input GO
// bit 8: GOWATCH
// bit 9: GO High at Start
// bit 10: GO Low at Stop
// bit 11: Clear at triggered start
// bit 12: Only triggered start
public int digval;      // digval=0..255 value for samplechanger
public int dac0;        // DAC0 value (START)
// bit 16: Start with rising edge
public int dac1;        // DAC1 value (STOP 1)
public int dac2;        // DAC2 value (STOP 2)
public int dac3;        // DAC3 value (STOP 3)
public int dac4;        // DAC4 value (STOP 4)
public int dac5;        // DAC5 value (STOP 5)
// bit (14,15) of each word: 0=falling, 1=rising, 2=both, 3=both+CFT
// bit 17 of each: pulse width mode under threshold
public int fdac;        // dummy
public int tagbits;     // number of tagbits
public int extclk;      // use external clock
public int periods;     // number of periods in folded mode, sweeplength = range * periods
public int serno;       // serial number
public int ddruse;      // bit0: DDR_USE, bit1: DDR_2GB
// bits[2:3]: usb_usage
// bits[4:5]: wrlen
public int active;      // module in system
public double holdafter; // Hold off
public double swpreset; // sweep preset value
public double fstchan;  // acquisition delay
public double timepreset; // time preset
}

public struct LVCOINCDEF
{
    public int adcnum;    // Number of active ADC's
    public int tofnum;    // Number of active MCS/Scope channels
    public int ntofs0;    // Number of TOF inputs

```



```

public int modules; // Number of MCS8 modules
public int nadc;    // Number of ADCs
}

unsafe public struct ACQSTATUS
{
    public int started; // aquisition status: 1 if running, 0 else
    public int maxval;
    unsafe public fixed double cnt[8]; // see ST_... defines above
}

class Program
{
    // imports from DMCS8.DLL
    [DllImport("dmcs8.dll", EntryPoint = "RunCmd")]
    extern static void RunCmd(int nDisplay, string Command);
    // private static extern void RunCmd(int nDisplay, StringBuilder Command);
    [DllImport("dmcs8.dll", EntryPoint = "GetStatus")]
    extern static int GetStatus(int nDevice);
    [DllImport("dmcs8.dll", EntryPoint = "GetStatusData")]
    extern static int GetStatusData(ref ACQSTATUS Status, int nDevice);
    [DllImport("dmcs8.dll", EntryPoint = "GetSettingData")]
    extern static int GetSettingData(ref ACQSETTING MSetting, int nDisplay);
    [DllImport("dmcs8.dll", EntryPoint = "LVGetCnt")]
    extern static int LVGetCnt(ref double cntp, int nDisplay);
    [DllImport("dmcs8.dll", EntryPoint = "LVGetRoi")]
    extern static int LVGetRoi(ref int roip, int nDisplay);
    [DllImport("dmcs8.dll", EntryPoint = "LVGetDat")]
    extern static int LVGetDat(ref int datp, int nDisplay);
    [DllImport("dmcs8.dll", EntryPoint = "LVGetCDefData")]
    extern static int LVGetCDefData(ref LVCOINCDEF LCDef);
    [DllImport("dmcs8.dll", EntryPoint = "GetMCSSetting")]
    extern static int GetMCSSetting(ref BOARDSETTING BoardSetting, int nDevice);
    [DllImport("dmcs8.dll", EntryPoint = "GetDatSetting")]
    extern static int GetDatSetting(ref DATSETTING DatSetting);
    [DllImport("dmcs8.dll", EntryPoint = "GetBlock")]
    extern static void GetBlock(ref int datp, int from, int to, int step, int nDisplay);

    static void Main(string[] args)
    {
        int nDev = 0;
        ACQSETTING acq;
        ACQSTATUS Status;
        String command;
        LVCOINCDEF LCDef;
        BOARDSETTING BoardSetting;
        LCDef = new LVCOINCDEF();
        BoardSetting = new BOARDSETTING();

        acq = new ACQSETTING();
        Status = new ACQSTATUS();
        GetStatus(0);
        GetStatusData(ref Status, 0);
        LVGetCDefData(ref LCDef);
        GetMCSSetting(ref BoardSetting, 0);
        PrintMPASStatus(ref Status);
        Console.WriteLine();
        GetSettingData(ref acq, nDev);
        PrintSetting(ref acq);
        help();
        while (true)
        {
            command = Console.ReadLine();

```

```

        if (run(command, ref nDev) == 1) break;
    }
}

unsafe static void PrintMPASStatus(ref ACQSTATUS Status)
{
    fixed (ACQSTATUS* s = &Status)
    {
        if ((s->started & 0x01) != 0) Console.WriteLine("ON");
        else if ((s->started & 0x02) != 0) Console.WriteLine("READ OUT");
        else Console.WriteLine("OFF");
        Console.Write("runtime= ");
        Console.WriteLine(s->cnt[Constants.ST_RUNTIME]);
        Console.Write("sweeps= ");
        Console.WriteLine(s->cnt[Constants.ST_SWEEPS]);
        Console.Write("starts= ");
        Console.WriteLine(s->cnt[Constants.ST_STARTS]);
    }
}

unsafe static void PrintStatus(ref ACQSTATUS Status)
{
    fixed (ACQSTATUS* s = &Status)
    {
        Console.Write("total= ");
        Console.WriteLine(s->cnt[Constants.ST_TOTALSUM]);
        Console.Write("roi= ");
        Console.WriteLine(s->cnt[Constants.ST_ROISUM]);
        Console.Write("rate= ");
        Console.WriteLine(s->cnt[Constants.ST_ROIRATE]);
        Console.Write("ofls= ");
        Console.WriteLine(s->cnt[Constants.ST_OFLS]);
    }
}

unsafe static void PrintDatSetting(ref DATSETTING Set)
{
    fixed (DATSETTING* d = &Set)
    {
        byte[] f = new byte[255];
        string s;
        int i;
        for (i = 0; i < 255; i++)
            f[i] = d->filename[i];
        s = Encoding.UTF8.GetString(f, 0, 255);
        Console.Write("savedata= ");
        Console.WriteLine(d->savedata);
        Console.Write("autoinc= ");
        Console.WriteLine(d->autoinc);
        Console.Write("fmt= ");
        Console.WriteLine(d->fmt);
        Console.Write("mpafmt= ");
        Console.WriteLine(d->mpafmt);
        Console.Write("sephead= ");
        Console.WriteLine(d->sephead);
        Console.Write("filename= ");
        Console.WriteLine(s);
    }
}

static void PrintMCSSSetting(ref BOARDSETTING Set)
{

```

```

Console.Write("sweepmode= ");
Console.WriteLine(Set.sweepmode);
Console.Write("prena= ");
Console.WriteLine(Set.prena);
Console.Write("cycles= ");
Console.WriteLine(Set.cycles);
Console.Write("sequences= ");
Console.WriteLine(Set.sequences);
Console.Write("digio= ");
Console.WriteLine(Set.digio);
Console.Write("digval= ");
Console.WriteLine(Set.digval);
Console.Write("dac0= ");
Console.WriteLine(Set.dac0);
Console.Write("dac1= ");
Console.WriteLine(Set.dac1);
Console.Write("dac2= ");
Console.WriteLine(Set.dac2);
Console.Write("dac3= ");
Console.WriteLine(Set.dac3);
Console.Write("dac4= ");
Console.WriteLine(Set.dac4);
Console.Write("dac5= ");
Console.WriteLine(Set.dac5);
Console.Write("serno= ");
Console.WriteLine(Set.serno);
Console.Write("ddruse= ");
Console.WriteLine(Set.ddruse);
Console.Write("active= ");
Console.WriteLine(Set.active);
Console.Write("holdafter= ");
Console.WriteLine(Set.holdafter);
Console.Write("swpreset= ");
Console.WriteLine(Set.swpreset);
Console.Write("fstchan= ");
Console.WriteLine(Set.fstchan);
Console.Write("timepreset= ");
Console.WriteLine(Set.timepreset);
}

static void PrintSetting(ref ACQSETTING acq)
{
    Console.Write("range= ");
    Console.WriteLine(acq.range);
    Console.Write("cftfak= ");
    Console.WriteLine(acq.cftfak);
    Console.Write("roimin= ");
    Console.WriteLine(acq.roimin);
    Console.Write("roimax= ");
    Console.WriteLine(acq.roimax);
    Console.Write("nregions= ");
    Console.WriteLine(acq.nregions);
    Console.Write("caluse= ");
    Console.WriteLine(acq.caluse);
    Console.Write("calpoints= ");
    Console.WriteLine(acq.calpoints);
    Console.Write("active= ");
    Console.WriteLine(acq.active);
    Console.Write("roipreset= ");
    Console.WriteLine(acq.eventpreset);
}

```

```

static int run(string command, ref int nDev)
{
    int[] Spec = new int[30];
    if (command == "H") help();
    else if (command == "Q")
    {
        return 1;
    }
    else if (command == "T")
    {
        ACQSETTING MSetting;
        Console.WriteLine("CHN ");
        Console.WriteLine(nDev);
        MSetting = new ACQSETTING();
        GetSettingData(ref MSetting, nDev);
        PrintSetting(ref MSetting);
    }
    else if (command == "S")
    {
        ACQSTATUS Status;
        Status = new ACQSTATUS();
        GetStatusData(ref Status, nDev);
        PrintStatus(ref Status);
    }
    else if (command == "D")
    {
        ACQSETTING MSetting;
        MSetting = new ACQSETTING();
        GetSettingData(ref MSetting, nDev);
        //         for (i=0; i<30; i++)
        //             GetBlock(ref Spec[i], i, i+1, 1, nDev);
        GetBlock(ref Spec[0], 0, 30, 1, nDev);
        PrintDat(MSetting.range, ref Spec);
    }
    else if (command == "F")
    {
        DATSETTING DSetting;
        DSetting = new DATSETTING();
        GetDatSetting(ref DSetting);
        PrintDatSetting(ref DSetting);
    }
    else
    {
        RunCmd(0, command);
    }
    return 0;
}

static void help()
{
    Console.WriteLine("Commands:");
    Console.WriteLine("Q  Quit");
    Console.WriteLine("H  Help");
    Console.WriteLine("S  Status");
    Console.WriteLine("T  Setting");
    Console.WriteLine("D  Data");
    Console.WriteLine("F  Datsetting");
    Console.WriteLine("(... more see command language in MPANT help)");
    Console.WriteLine();
}

```

```
static void PrintDat(int range, ref int[] datp)
{
    int i;
    Console.Write("first 30 of ");
    Console.Write(range);
    Console.WriteLine(" datapoints:");
    for (i = 0; i < 30; i++)
        Console.WriteLine(datp[i]);
    }
}
```

6 Appendix: The DMCS8 DLL

The Dynamic Link Library DMCS8.DLL provides an interface to the server program MCS8.EXE that is used by the MPANT software, but can also be used by any Windows program. Custom DLL functions allow user-defined calculated parameter spectra. In the following this DLL is described in detail including the complete source code.

6.1 The Structures

In struct.h some important structures are defined. A structure of type ACQSTATUS contains parameters describing the status of an acquisition. There is an array of these structures stored in the DLL, DLLMStatus[] contains general mpa status data for each MCA module, and DLLStatus[] Spectrum status data.

```
#define GET_WM_COMMAND_ID(w) LOWORD(w)
#define GET_WM_COMMAND_CMD(w,l) HIWORD(w)
#define GET_WM_COMMAND_HWND(l) l
#define GET_WM_SCRHWND(l) l
#define GET_WM_SCROLLPOS(w,l) (short)HIWORD(w)
#define FIND_WINDOW(a,b) FindWindow(a,b)
#define HUGE
#define _fmemcpy memcpy
#define _fstrcpy strcpy

typedef struct {
    int use;
    int port;
    unsigned int baud;
    int dbits;
    int sbits;
    int parity;
    int echo;
    HWND hwndserver;
    LPSTR cmd;
} COMCTL, far *LPCOMCTL;

#define ST_RUNTIME          0
#define ST_OFLS             1
#define ST_TOTALSUM        2
#define ST_ROISUM          3
#define ST_ROIRATE         4
#define ST_SWEEPS          5
#define ST_STARTS          6
#define ST_ZEROEVTS        7

typedef struct{
    unsigned int started;    // aquisition status
    unsigned int maxval;    // maxval
    double cnt[8];          // status: runtime in msec, ofls,
                           // total sum, roi sum, roi rate, sweeps, starts, zeros
} ACQSTATUS;

DATSETTING is a structure type containing data format settings.

typedef struct {
    int savedata;           // bit 0: auto save after stop
                           // bit 1: write listfile
                           // bit 2: listfile only, no evaluation
```

```

int autoinc;           // 1 if auto increment filename
int fmt;               // format type (seperate spectra):
                      // 0 == ASCII, 1 == binary,
                      // 2 == CSV
int mpafmt;           // format used in mpa datafiles
int sephead;           // seperate Header
int smpts;
int caluse;
char filename[256];
char specfile[256];
char command[256];
} DATSETTING;

```

REPLAYSETTING is a structure type containing Replay settings.

```

typedef struct {
    int use;           // 1 if Replay Mode ON
    int modified;      // Bit 0: 1 if different settings are used
                      // (Bit 1: Write ASCII, reserved)
    int limit;         // 0: all,
                      // 1: limited sweep range
    int speed;         // replay speed in units of 100 kB / sec
    double startsfrom; // first start#
    double startsto;   // last start#
    double startspreset; // last start - first start
    char filename[256];
} REPLAYSETTING;

```

ACQSETTING is a structure type containing all the spectra settings

```

typedef struct{
    int range;         // spectrum length
    int cftfak;        // LOWORD: 256 * cft factor (t_after_peak / t_to_peak)
                      // HIWORD: max pulse width for CFT
    int roimin;        // lower ROI limit
    int roimax;        // upper limit: roimin <= channel < roimax
    int nregions;      // number of regions
    int caluse;        // bit0: 1 if calibration used, higher bits: formula
    int calpoints;     // number of calibration points
    int param;         // (reserved:) for MAP and POS: LOWORD=x, HIWORD=y
    int offset;        // (reserved:) zoomed MAPS: LOWORD: xoffset, HIWORD: yoffset
    int xdim;          // (reserved:) x resolution of maps
    unsigned int bitshift; // LOWORD: Binwidth = 2 ^ (bitshift)
                      // HIWORD: Threshold for Coinc
    int active;        // Spectrum definition words for CHN1..8:
                      // active & 0xF ==0 not used
                      //      ==1 single
                      // bit 8: Enable Tag bits
                      // bit 9: start with rising edge
                      // bit 10: time under threshold for pulse width
                      // bit 11: pulse width mode for any spectra with both edges enabled
                      // Spectrum definition words for calc. spectra:
                      // active & 0xF ==3 MAP, ((x-xoffs)>>xsh) x ((y-yoffs)>>ysh)
                      //      ((x-xoffs)>>xsh) x ((y-timeoffs)>>timesh)
                      //      or ((x-timeoffs)>>timesh) x ((y-yoffs)>>ysh)
                      // bit4=1: x zoomed MAP
                      // bit5=1: y zoomed MAP
                      //      ==5 SUM, (x + y)>>xsh
                      //      ==6 DIFF,(x - y + range)>>xsh
                      //      ==7 ANY, (for compare)

```

```

//      ==8 COPY, x
//      ==9 DLL fDLL(x,y,z),
//      ==0xA Sweep HISTORY, Sweepnum(x)
// bit 8..11 xsh, bit 12..15 ysh or bit 8..15 xsh
// HIWORD(active) = condition no. (0=no condition)
double eventpreset; // ROI preset value
double dummy1;      // (for future use..)
double dummy2;      //
double dummy3;      //
} ACQSETTING;

typedef struct{
int range;           // spectrum length
int cftfak;          // LOWORD: 256 * cft factor (t_after_peak / t_to_peak)
// HIWORD: max pulse width for CFT
int roimin;          // lower ROI limit
int roimax;          // upper limit: roimin <= channel < roimax
int nregions;        // number of regions
int caluse;          // bit0: 1 if calibration used, higher bits: formula
int calpoints;       // number of calibration points
int param;           // (reserved:) for MAP and POS: LOWORD=x, HIWORD=y
int offset;          // (reserved:) zoomed MAPS: LOWORD: xoffset, HIWORD, yoffset
int xdim;            // (reserved:) x resolution of maps
unsigned int bitshift; // LOWORD: Binwidth = 2 ^ (bitshift)
// HIWORD: Threshold for Coinc
int active;          // Spectrum definition words for CHN1..8:
// active & 0xF ==0 not used
//      ==1 enabled
// bit 8: Enable Tag bits
// bit 9: start with rising edge
// bit 10: time under threshold for pulse width
// bit 11: pulse width mode for any spectra with both edges enabled
// Spectrum definition words for calc. spectra:
// active & 0xF ==3 MAP, ((x-xoffs)>>xsh) x ((y-yoffs)>>ysh)
//      bit4=1: x zoomed MAP
//      bit5=1: y zoomed MAP
//      ==5 SUM, (x + y)>>xsh
//      ==6 DIFF,(x - y + range)>>xsh
//      ==7 ANY, (for compare)
//      ==8 COPY, x
//      ==10 SW-HIS, Sweep History
// bit 8..11 xsh, bit 12..15 ysh or bit 8..15 xsh
// HIWORD(active) = condition no. (0=no condition)
double eventpreset; // ROI preset value
double dummy1;      // (for future use..)
double dummy2;      //
double dummy3;      //
// MPANT or Server private saved settings:
int type;            // 0=single, 1=MAP, 2=ISO...
int ydim;            // y resolution of maps
int reserved[16];
} EXTACQSETTING;

typedef struct {
int sweepmode;       // sweepmode & 0xF: 0 = normal,
// 1=differential (relative to first stop in sweep)
// 4=sequential
// 5=seq.+diff (Ch1), bit0 = differential mode
// 6 = CORRELATIONS
// 7 = diff.+Corr.

```



```

// 9=differential to stop in Ch2, bit3 = Ch2 ref (diff.mode)
// 0xF = Corr.+diff (Ch2)
// bit 4: Softw. Start
// bit 5: "Don't show" tagbits
// bit 6: Endless
// bit 7: Start event generation
// bit 8: Enable Tag bits
// bit 9: start with rising edge
// bit 10: time under threshold for pulse width
// bit 11: pulse width mode for any spectra with both edges enabled
// bit 12: abandon Sweepcounter in Data
// bit 13: "one-hot" mode with tagbits
// bit 14: start ref (diff.mode)
// bit 15: enable start input
// bit 16..bit 22 ~(input channel enable)
// bit 24: reserved
// bit 25: reserved
// bit 27: Folded
// bit 28: Interleaved
int prena; // bit 0: realtime preset enabled
           // bit 1:
           // bit 2: sweep preset enabled
           // bit 3: ROI preset enabled
           // bit 4: Starts preset enabled
           // bit 5: ROI2 preset enabled
           // bit 6: ROI3 preset enabled
           // bit 7: ROI4 preset enabled
           // bit 8: ROI5 preset enabled
           // bit 9: ROI6 preset enabled
           // bit 10: ROI7 preset enabled
           // bit 11: ROI8 preset enabled
int cycles; // for sequential mode
int sequences; //
int syncout; // LOWORD: sync out; bit 0..5 NIM syncout, bit 8..13 TTL syncout
              // bit7: NIM syncout_invert, bit15: TTL syncout_invert
              // 0="0", 1=5 MHz, 2=50 MHz, 3=100 MHz, 4=97.656 MHz,
              // 5=195.625 MHz, 6= 195 MHz (int ref), 7=Start, 8=Ch1, 9=Ch2, 10=Ch3,
              // 11=Ch4, 12=Ch5, 13=Ch6, 14=Ch7, 15=GO, 16=Start_of_sweep, 17=Armed,
              // 18=SWEEP_ON, 19=WINDOW, 20=HOLD_OFF, 21=EOS_DEADTIME
              // 22=TIME[0],...,51=TIME[29], 52...63=SWEEP[0]..SWEEP[11]
              //
int digio; // LOWORD: Use of Dig I/O, GO Line:
           // bit 0: status dig 0..3
           // bit 1: Output digval and increment digval after stop
           // bit 2: Invert polarity
           // bit 3: Push-Pull output, not possible
           // bit 4: Start with Input Dig 4
           // bit 5: Start with Input GO
           // bit 8: GOWATCH
           // bit 9: GO High at Start
           // bit 10: GO Low at Stop
           // bit 11: Clear at triggered start
           // bit 12: Only triggered start
int digval; // digval=0..255 value for samplechanger
int dac0; // DAC0 value (START)
           // bit 16: Start with rising edge
int dac1; // DAC1 value (STOP 1)
int dac2; // DAC2 value (STOP 2)
int dac3; // DAC3 value (STOP 3)
int dac4; // DAC4 value (STOP 4)
int dac5; // DAC5 value (STOP 5)
           // bit (14,15) of each word: 0=falling, 1=rising, 2=both, 3=both+CFT

```

```

// bit 17 of each: pulse width mode under threshold
int fdac; // reserved
int tagbits; // number of tagbits
int extclk; // use external clock
int periods; // number of periods in folded mode, sweeplength = range * periods
int serno; // serial number
int ddruse; // bits[0:1] 1=DDR_USE, 2=DDR_2GB, 3=DDR_4GB
// bits[2]: usb_usage (0 means demo mode)
// bits[4:5]: wrlen
int active; // module in system
double holdafter; // Hold off
double swpreset; // sweep preset value
double fstchan; // acquisition delay
double timepreset; // time preset
} BOARDSETTING;

typedef struct {
int nDevices; // Number of channels = number of modules * (6 + 8)
int nDisplays; // Number of histograms = nDevices + Positions + Maps
int nSystems; // Number of independent systems = 1
int bRemote; // 1 if server controlled by MPANT
unsigned int sys; // System definition word:
// bit0=0, bit1=0: dev#0 in system 1
// bit0=1, bit1=0: dev#0 in system 2
// bit0=0, bit1=1: dev#0 in system 3
// bit0=1, bit1=1: dev#0 in system 4
// bit2..bit6: ...
// bit6=1, bit7=1: dev#3 in system 4
// bit 31: any preset stops all
int sys0[56]; // (reserved:) System definition words for CHN1...
// bit 0 CHN active
// bit 1 =1 CHN coinc, =0 single
// bit 2..4 CHN in system1..7
int sys1[56]; // (reserved:) CHN in System
} ACQDEF;

typedef struct {
unsigned int adcnm; // Number of active ADC's (=0)
unsigned int tofnm; // Number of active TOF channels
unsigned int ntofs0; // Number of TOF inputs
unsigned int modules; // Number of modules
unsigned int nadcs; // Number of ADCs (=0)
int sys0[56]; // (reserved:) System definition words for CHN1...
// see active definition in ACQSETTING
int sys1[56]; // CHN in System (=1)
int adcs[8]; // Number of ADCs per module (0)
int tofs[8]; // Number of TOF inputs per module
int speed[8]; // TOF speed in module: 3=80ps ..100ps, 2=200ps, 1=400ps, 0=800ps
} COINCDEF;

```

ACQDATA is a structure type containing pointers to the data belonging to a measurement. The data is stored in a named memory-mapped file (see DLL source).

```

typedef struct{
unsigned int HUGE *s0; // pointer to spectrum
unsigned int *region; // pointer to regions
unsigned char *comment0; // pointer to strings
double *cnt; // pointer to counters
HANDLE hs0;
HANDLE hrg;
HANDLE hcm;

```

```
HANDLE hct;
} ACQDATA;
```

Data[nDisplay].s0 points to a block memory of unsigned long 32-bit numbers containing the spectra data.

Data[nDisplay].region points to a block of 256 unsigned long numbers containing the Roi (Region of interest) boundaries as defined in the MPANT program. The first Roi is:

Data[nDisplay].region[0] <= x < Data[nDisplay].region[1], the second

Data[nDisplay].region[2] <= x < Data[nDisplay].region[3] and so on, 128 Rois are possible.

These Rois have nothing to do with the special Roi defined in the ACQSETTING structure for the Roi Preset.

Data[nDisplay].comment0 points to a block of 1024 bytes containing the strings.

Data[nDisplay].comment0[0] is the first byte of the 0. comment line,
 Data[nDisplay].comment0[60] is the first byte of the 1. comment line,
 Data[nDisplay].comment0[120] is the first byte of the 2. comment line,
 Data[nDisplay].comment0[180] is the first byte of the 3. comment line,
 Data[nDisplay].comment0[240] is the first byte of the 4. comment line,
 Data[nDisplay].comment0[300] is the first byte of the 5. comment line,
 Data[nDisplay].comment0[360] is the first byte of the 6. comment line,
 Data[nDisplay].comment0[420] is the first byte of the 7. comment line,
 Data[nDisplay].comment0[480] is the first byte of the 8. comment line,
 Data[nDisplay].comment0[540] is the first byte of the 9. comment line,
 Data[nDisplay].comment0[600] is the first byte of the 10. comment line,
 Data[nDisplay].comment0[660] is the first byte of the data file name,
 Data[nDisplay].comment0[760] is the first byte of the calibration unit name,
 Data[nDisplay].comment0[800] is the first byte of the command string.
 Data[nDisplay].comment0[880] is the first byte of the 11. comment line,
 Data[nDisplay].comment0[960] is the first byte of the 12. comment line

Data[nDisplay].cnt points to a block of 448 double numbers containing:

Data[nDisplay].cnt[0] = Realtime
 Data[nDisplay].cnt[1] = Totalsum
 Data[nDisplay].cnt[2] = ROIsum
 Data[nDisplay].cnt[3] = Totalrate
 Data[nDisplay].cnt[4] = Net ROIsum
 Data[nDisplay].cnt[5] = Livetime / Sweeps
 Data[nDisplay].cnt[6] = Deadtime (%)
 Data[nDisplay].cnt[7] = Cycle counter in sequential mode
 Data[nDisplay].cnt[8] = Sequence counter
 Data[nDisplay].cnt[11] = c0 Calibration parameter
 Data[nDisplay].cnt[12] = c1 Calibration parameter
 Data[nDisplay].cnt[13] = c2 Calibration parameter
 Data[nDisplay].cnt[14] = c3 Calibration parameter, for scope displays: vpp (mV) / 65535
 Data[nDisplay].cnt[15] for nDisplay =0:
 bit 0: system 1 started,
 bit 1: system 2 started,
 bit 2: system 3 started,
 bit 3: system 4 started

Data[nDisplay].cnt[19] = Channel number of first calibration Point

Data[nDisplay].cnt[35] = Energy value at first calibration Point

Data[nDisplay].cnt[20] = Channel number of 2. calibration Point

Data[nDisplay].cnt[36] = Energy value at 2. calibration Point...

Data[nDisplay].cnt[64..191] = Energy value for calibration peak in ROI
 0..127

Data[nDisplay].cnt[192] = ROI Sum in ROI 0 (actualized by MPANT when
 selected in any spectra display)

Data[nDisplay].cnt[193] = ROI Net Sum in ROI 0 ...

Data[nDisplay].cnt[447] = ROI Net Sum in ROI 127

```
typedef struct {
```

```

int nDevices;      // Number of channels = number of modules * 6
int nDisplays;     // Number of histograms = nDevices + Positions + Maps
int nSystems;      // Number of independent systems = 1
int bRemote;       // 1 if server controlled by MPANT
unsigned int sys;   // System definition word:
                    // bit0=0, bit1=0: dev#0 in system 1
                    // bit0=1, bit1=0: dev#0 in system 2
                    // bit0=0, bit1=1: dev#0 in system 3
                    // bit0=1, bit1=1: dev#0 in system 4
                    // bit2..bit6:
                    // bit6=1, bit7=1: dev#3 in system 4
} LVACQDEF;

typedef struct {
    int savedata;    // bit 0: auto save after stop
                    // bit 1: write listfile
                    // bit 2: listfile only, no evaluation
    int autoinc;     // 1 if auto increment filename
    int fmt;         // format type (seperate spectra):
                    // 0 == ASCII, 1 == binary,
                    // 2 == CSV
    int mpafmt;      // format used in mpa datafiles
    int sephead;     // seperate Header
    int smpts;
    int caluse;
} LVDATSETTING;

typedef struct {
    int use;         // 1 if Replay Mode ON
    int modified;    // Bit 0: 1 if different settings are used
                    // (Bit 1: Write ASCII, reserved)
    int limit;       // 0: all,
                    // 1: limited sweep range
    int speed;       // replay speed in units of 100 kB / sec
    double startsfrom; // first start#
    double startsto;  // last start#
    double startspreset; // last start - first start
} LVREPLAYSETTING;

typedef struct {
    unsigned int adcnum; // Number of active ADC's (=0)
    unsigned int tofnum; // Number of active TOF channels
    unsigned int ntofs0; // Number of TOF inputs
    unsigned int modules; // Number of modules
    unsigned int nadcs;   // Number of ADCs (=0)
} LVCOINCDEF;

```

6.2 The Library Functions

In the header file DMCS8.h all functions are declared. It is already listed in chapter 4.1.

6.3 The Ordinal numbers of the functions

In the Definition file DMCS8.def the ordinal numbers of the library fuctions are defined:

```
.*DMCS8.def
;
.*Hardware:      MCS8
.*Op System:     Windows
.*Compiler:      MSVC++ 6.0
.*
;
```

LIBRARY DMCS8

SECTIONS

dmcs8sh READ WRITE SHARED

EXPORTS

```
; Functions in dmcs8.c
StoreSettingData      @2
GetSettingData        @3
StoreStatusData       @4
GetStatusData         @5
Start                 @6
Halt                  @7
Continue              @8
NewSetting            @9
ServExec              @10
GetSpec               @13
SaveSetting           @14
GetStatus             @15
Erase                 @16
SaveData              @17
GetBlock              @18
StoreDefData          @19
GetDefData            @20
LoadData              @21
NewData               @22
HardwareDlg           @23
UnregisterClient       @24
DestroyClient         @25
ClientExec            @26
LVGetDat              @27
RunCmd                @28
AddData               @29
LVGetRoi              @30
LVGetCnt              @31
LVGetOneCnt           @32
LVGetStr              @33
SubData               @34
Smooth                @35
StoreExtSettingData   @36
GetExtSettingData     @37
StoreMCSSetting       @38
GetMCSSetting         @39
StoreDatSetting       @40
GetDatSetting         @41
StoreReplaySetting    @42
GetReplaySetting      @43
```

GetDatPtr	@44
ReleaseDatPtr	@45
LVGetOneRoi	@46
GetSVal	@47
GetDatInfo	@48
BytearrayToShortarray	@49
LedBlink	@50
DigInOut	@51
StoreMStatusData	@52
GetMStatusData	@53
StoreCDefData	@54
GetCDefData	@55
StoreMP4Setting	@60
GetMP4Setting	@61
GetRoiIndex	@62
DeleteRoi	@63
GetRoiSum	@64
SelectRoi	@65
LVGetRoiName	@66
LVGetSpecLength	@67
LVGetDefData	@68
LVGetDatSetting	@69
LVGetReplaySetting	@70
LVGetProiDat	@71
LVGetRoiRect	@72
LVGetRroiDat	@73
LVGetCDefData	@74

6.4 The source code of the functions

In the source file DMCS8.c the body of the library functions is coded. It can be found in the DLL subfolder of the supplied software.

6.5 How to compile the DLL

The 32 bit DLL can be compiled with the Microsoft Visual C/C++ compiler version 6.0 or higher. To recompile the DLL under VC 6.0, use the makefile DMCS8.dsw. For later version create a new DLL project and include the files DMCS8.c and DMCS8.def.

The 64 bit DLL can be compiled with Microsoft Visual Studio 2013 using the file DMCS8.sln.