

Jing (Daisy) Dai

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Education

Shanghai Jiao Tong University

Master in Mechanical Engineering | Advisor: Weixin Yan

GPA: 3.6 / 4.0

Shanghai

Sep. 2023 - Jun. 2026 (Expected)

Hunan University

Bachelor in Mechanical Design, Manufacturing and Automation

GPA: 3.66 / 4.0 (ranking: 15/248, top 6%)

Changsha

Sep. 2019 - Jun. 2023

Research Statement

My research focuses on robot learning with concrete hardware implementations, bridging mechatronics and AI to enable dexterous manipulation. With experience spanning from embedded systems to RL algorithms, I bring a unique hardware-software co-design perspective essential for advancing embodied intelligence. I thrive in cross-disciplinary teams, having collaborated with engineers, researchers, and designers across academia and industry.

Publications

- [1] **Jing Dai**, Jianbo Yuan, Yiwen Lu, Haohua Zhu, Sheng Yi, and Weixin Yan. “IntuitCap: A 60-DOF Upper-body Motion Capture System for Dexterous Robot Manipulation”. Accepted by 8th The International Conference on Robotics, Control and Automation Engineering (RCAE), 2025.
- [2] **Jing (Daisy) Dai***, Qianshu Wang*, Shurui Zhang*, Bin Zhao, Jiahong Zhang, Jianbo Yuan, and Yiwen Lu. “HOVER: Generalized Retargeting for Dexterous Manipulation”. To be presented at IROS 2025 Workshop on Learning from Human Teleoperation; *In preparation for Robotics: Science and Systems (RSS)*, 2026.
- [3] Xinyue Xu*, Jieqiang Sun*, **Jing (Daisy) Dai***, Siyuan Chen, Lanjie Ma, Ke Sun, Bin Zhao, Jianbo Yuan, and Yiwen Lu. “DexCanvas: Bridging Human Demonstrations and Robot Learning for Dexterous Manipulation”. Submitted to International Conference on Learning Representations (ICLR), 2026.
- [4] Jianbo Yuan, Haohua Zhu, **Jing Dai**, and Sheng Yi. “Development of the Bioinspired Tendon-Driven DexHand 021 with Proprioceptive Compliance Control”. *IEEE Robotics and Automation Letters (RA-L)*, 2025.
- [5] Jianbo Yuan, **Jing Dai**, Yerui Fan, Yaxiong Wu, Yunpeng Liang, Weixin Yan. “Robustness study of the bio-inspired musculoskeletal arm robot based on the data-driven iterative learning algorithm”. *Science China Information Sciences*, 2025, 68: 222203. doi: 10.1007/s11432-024-4540-7
- [6] Yuchen Jia, Suzhen Wu, Gang Wang, **Jing Dai**, Jingyuan Gao, Rui Lei, and Aonan Li. “A Bionic Peacock”, *Invention Patent*, ZL116423533A, 2023-07-14. [\[Link\]](#)

Research Projects

Task-Centric Reinforcement Learning for High-DOF Dexterous Hands

Research Intern | DexRobot Inc.

Shanghai

Feb. 2025 – Present

Advancing dexterous manipulation through task-centric RL applied to high-DOF robotic hands. Leveraging real-to-sim human demonstrations and large-scale datasets for robust skill transfer.

- **HOVER retargeting framework:** Virtual operator method for human-to-robot retargeting achieving both task fidelity and anthropomorphism; deployed for efficient real-world teleoperation on DexHand021
- **DexCanvas dataset:** Large-scale hybrid dataset combining 70 hours real mocap with physics-validated synthetic expansion; developed RL-based force extraction methodology producing 7,000 hours of physically consistent manipulation data across 21 manipulation types from Cutkosky taxonomy

- **Simulation setup:** Constructed simulation scenes in MuJoCo and Isaac Gym; deployed benchmark datasets such as ARCTIC to evaluate manipulation accuracy and generalization
- **Policy deployment:** Implemented hardware and control integration for the 19-DOF DexHand 021, enabling adaptive in-hand manipulation under dynamic contact conditions

Upper Limb 60-DOF Data Acquisition and Digital Twin System

Shanghai

Engineering Intern | DexRobot Inc.

Sep. 2024 – Mar. 2025

Engineered a 60-DOF upper-limb capture system that enables real-time teleoperation for high-fidelity human demonstration capture

- **Mechanical Design:** Designed lightweight exoskeleton using 3D-printed nylon structures, integrating magnetic encoders for joint angle sensing and smart gloves with tactile feedback for hand motion capture
- **Embedded Systems:** Implemented Socket and CANFD bus communication for low-latency peripheral device control and data streaming, achieving 10ms end-to-end latency
- **Robot Kinematics & Control:** Implemented kinematic modeling and mapping algorithms to reconstruct operator motion. Created Unity3D-based digital twin environment for real-time teleoperation of dual-arm JAKA robots and DexHand 021 systems

Bionic Robotic Peacock

Changsha

National First Prize, Mechanical Innovation Design Competition | Advisor: Gang Wang

May 2022 – Aug. 2022

Engineered a bionic robotic peacock with embedded control, multi-axis actuation, and voice interaction for educational exhibition

- Architected embedded control system based on dual STM32 microcontrollers, programmed in embedded C using Keil IDE, with modular architecture supporting coordinated actuation of 11 motors
- Programmed complex motion behaviors (tail spreading, wing retracting, dancing, walking) through heterogeneous motor control: servo motors for tail and legs, brushless DC motors for neck and wings
- Integrated real-time voice control via LU-ASR01 speech recognition module; conducted three design iterations to optimize motion smoothness and structural reliability

Teaching Experience

Teaching Assistant | Introduction to Robotics

Shanghai

Shanghai Jiao Tong University

Spring 2025

- Taught kinematics, dynamics, and control systems through interactive lab sessions
- Mentored 30+ students on robotic system design projects bridging theory and implementation

Skills

Programming Matlab, Python, C, C++, Qt

Professional Software SOLIDWORKS, UG NX, Simulink

Robotics Technology ROS, Simulators (MuJoCo, Isaac Gym, Unity), Deep Learning (PyTorch)

Drawing & Typesetting MS Office, Photoshop, L^AT_EX, Markdown

Languages Chinese (Native), English (IELTS: 7)

Selected Honors & Activities

2020	National Scholarship (Top 0.2% nationwide)	<i>Changsha</i>
2022	National First Prize , 10th National College Mechanical Innovation Design Competition	<i>Shenzhen</i>
2025	Trane Technologies Future Star Women Engineers Scholarship	<i>Shanghai</i>
2023	Outstanding Graduate of Hunan University	<i>Changsha</i>
2022	Honorable Mention Prize , Mathematical Contest in Modeling (MCM)	<i>USA</i>

Leadership & Service: New Media Center Director, SJTU-ME Student Union (2023-2025) | Peer Mentor, Hunan University (2021-2023)