Assignment2Q2

July 3, 2018

```
In [1]: %run main.py --env-id Pendulum-v0 --nb-epochs 50
Logging to C:\Users\LINDAI~1\AppData\Local\Temp\openai-2018-07-02-23-26-41-735687
WARN: gym.spaces.Box autodetected dtype as <class 'numpy.float32'>. Please provide explicit dtype
WARN: gym.spaces.Box autodetected dtype as <class 'numpy.float32'>. Please provide explicit dtype
rank 0: seed=0, logdir=C:\Users\LINDAI~1\AppData\Local\Temp\openai-2018-07-02-23-26-41-735687
scaling actions by [2.] before executing in env
setting up param noise
  param_noise_actor/dense/kernel:0 <- share/dense/kernel:0 + noise</pre>
 param_noise_actor/dense/bias:0 <- share/dense/bias:0 + noise</pre>
 param_noise_actor/LayerNorm/beta:0 <- share/LayerNorm/beta:0</pre>
 param_noise_actor/LayerNorm/gamma:0 <- share/LayerNorm/gamma:0</pre>
 param_noise_actor/dense_1/kernel:0 <- actor/dense/kernel:0 + noise</pre>
  param_noise_actor/dense_1/bias:0 <- actor/dense/bias:0 + noise</pre>
 param_noise_actor/LayerNorm_1/beta:0 <- actor/LayerNorm/beta:0</pre>
  param_noise_actor/LayerNorm_1/gamma:0 <- actor/LayerNorm/gamma:0</pre>
 param_noise_actor/dense_2/kernel:0 <- actor/dense_1/kernel:0 + noise</pre>
  param_noise_actor/dense_2/bias:0 <- actor/dense_1/bias:0 + noise</pre>
  adaptive_param_noise_actor/dense/kernel:0 <- share/dense/kernel:0 + noise
  adaptive_param_noise_actor/dense/bias:0 <- share/dense/bias:0 + noise
  adaptive_param_noise_actor/LayerNorm/beta:0 <- share/LayerNorm/beta:0
  adaptive_param_noise_actor/LayerNorm/gamma:0 <- share/LayerNorm/gamma:0
  adaptive_param_noise_actor/dense_1/kernel:0 <- actor/dense/kernel:0 + noise
  adaptive_param_noise_actor/dense_1/bias:0 <- actor/dense/bias:0 + noise
  adaptive_param_noise_actor/LayerNorm_1/beta:0 <- actor/LayerNorm/beta:0
  adaptive_param_noise_actor/LayerNorm_1/gamma:0 <- actor/LayerNorm/gamma:0
  adaptive_param_noise_actor/dense_2/kernel:0 <- actor/dense_1/kernel:0 + noise
  adaptive_param_noise_actor/dense_2/bias:0 <- actor/dense_1/bias:0 + noise
setting up actor optimizer
  actor shapes: [[3, 64], [64], [64], [64], [64], [64], [64], [64], [64], [64, 1], [1]]
  actor params: 4737
setting up critic optimizer
  regularizing: share/dense/kernel:0
  regularizing: critic/dense/kernel:0
  regularizing: critic/dense_1/kernel:0
  applying 12 regularization with 0.01
  critic shapes: [[3, 64], [64], [64], [64], [65, 64], [64], [64], [64], [64, 1], [1]]
```

```
critic params: 4801
WARNING:tensorflow:From c:\users\lin daiwei\baselines\baselines\ddpg\ddpg.py:29: calling reduce_
Instructions for updating:
keep_dims is deprecated, use keepdims instead
setting up target updates ...
  target_actor/dense/kernel:0 <- share/dense/kernel:0</pre>
  target_actor/dense/bias:0 <- share/dense/bias:0</pre>
  target_actor/LayerNorm/beta:0 <- share/LayerNorm/beta:0</pre>
  target_actor/LayerNorm/gamma:0 <- share/LayerNorm/gamma:0</pre>
  target_actor/dense_1/kernel:0 <- actor/dense/kernel:0</pre>
  target_actor/dense_1/bias:0 <- actor/dense/bias:0</pre>
  target_actor/LayerNorm_1/beta:0 <- actor/LayerNorm/beta:0</pre>
  target_actor/LayerNorm_1/gamma:0 <- actor/LayerNorm/gamma:0</pre>
  target_actor/dense_2/kernel:0 <- actor/dense_1/kernel:0</pre>
  target_actor/dense_2/bias:0 <- actor/dense_1/bias:0</pre>
setting up target updates ...
  target_critic/dense/kernel:0 <- share/dense/kernel:0</pre>
  target_critic/dense/bias:0 <- share/dense/bias:0</pre>
  target_critic/LayerNorm/beta:0 <- share/LayerNorm/beta:0</pre>
  target_critic/LayerNorm/gamma:0 <- share/LayerNorm/gamma:0</pre>
  target_critic/dense_1/kernel:0 <- critic/dense/kernel:0</pre>
  target_critic/dense_1/bias:0 <- critic/dense/bias:0</pre>
  target_critic/LayerNorm_1/beta:0 <- critic/LayerNorm/beta:0</pre>
  target_critic/LayerNorm_1/gamma:0 <- critic/LayerNorm/gamma:0</pre>
  target_critic/dense_2/kernel:0 <- critic/dense_1/kernel:0</pre>
  target_critic/dense_2/bias:0 <- critic/dense_1/bias:0</pre>
Using agent with the following configuration:
dict_items([('obs0', <tf.Tensor 'obs0:0' shape=(?, 3) dtype=float32>), ('obs1', <tf.Tensor 'obs1
_____
obs_rms_mean
                          | -0.583
| obs_rms_std
                          1 1.48
                        | 0.167
| param_noise_stddev
| reference_Q_mean
                          | -58.2
| reference_Q_std
                         | 12.3
| reference_action_mean | 0.0971
| reference_action_std | 0.937
| reference_actor_Q_mean | -57.6
| reference_actor_Q_std | 13
| reference_perturbed_... | 0.535
| rollout/Q_mean
                          | -25.1
| rollout/actions_mean
                         -0.183
| rollout/actions_std
                          0.708
| rollout/episode_steps
                          1 200
| rollout/episodes
                          l 10
                          | -1.49e+03 |
| rollout/return
| rollout/return_history | -1.49e+03 |
| total/duration
                           13.5
| total/episodes
                          | 10
```

| total/epochs | 1 |
|---------------------------------------|-----------|
| total/steps | 2000 |
| total/steps_per_second | 148 |
| train/loss_actor | 52.1 |
| train/loss_critic | 15.4 |
| train/param_noise_di | 0.842 |
| | |
| | |
| | |
| obs_rms_mean | -0.0671 |
| obs_rms_std | 1.97 |
| param_noise_stddev | 0.137 |
| reference_Q_mean | -115 |
| reference_Q_std | 21.5 |
| reference_action_mean | -0.229 |
| reference_action_std | 0.928 |
| reference_actor_Q_mean | -114 |
| reference_actor_Q_std | 22.2 |
| reference_perturbed | 0.493 |
| rollout/Q_mean | -45.1 |
| rollout/actions_mean | -0.0265 |
| rollout/actions_std | 0.729 |
| rollout/episode_steps | 200 |
| rollout/episodes | 20 |
| rollout/return | -1.41e+03 |
| rollout/return_history | -1.41e+03 |
| total/duration | 26.5 |
| total/episodes | 20 |
| total/epochs | 2 |
| total/steps | 4000 |
| total/steps_per_second | 151 |
| train/loss_actor | 98.1 |
| train/loss_critic | 60.3 |
| train/param_noise_di | 0.514 |
| | |
| | |
| | |
| · · · · · · · · · · · · · · · · · · · | -0.165 |
| obs_rms_std | 1.95 |
| param_noise_stddev | 0.112 |
| reference_Q_mean | -152 |
| reference_Q_std | 28.9 |
| | 0.17 |
| | 0.935 |
| | -149 |
| | 28.9 |
| - <u>-</u> | 0.885 |
| rollout/Q_mean | -67 |

| rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | -0.143 |
|---|---|
| obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std | -0.265 |
| reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed | 0.244 |
| <pre> rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes</pre> | -79.5 |
| <pre> rollout/return rollout/return_history total/duration total/episodes total/epochs total/store</pre> | -1.35e+03 -1.35e+03 52.3 40 4 |
| <pre> total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di </pre> | 8000 |
| obs_rms_mean obs_rms_std param_noise_stddev | -0.374 1.92 0.0754 |

| reference_Q_mean | -191 |
|-----------------------------------|-----------|
| reference_Q_std | 51 |
| reference_action_mean | 0.189 |
| reference_action_std | 0.948 |
| reference_actor_Q_mean | -187 |
| reference_actor_Q_std | 53.1 |
| reference_perturbed | 0.812 |
| rollout/Q_mean | -89 |
| rollout/actions_mean | -0.151 |
| rollout/actions_std | 0.745 |
| rollout/episode_steps | 200 |
| rollout/episodes | 50 |
| rollout/return | -1.31e+03 |
| <pre>rollout/return_history</pre> | -1.31e+03 |
| total/duration | 65 |
| total/episodes | 50 |
| total/epochs | 5 |
| total/steps | 10000 |
| total/steps_per_second | 154 |
| train/loss_actor | 142 |
| train/loss_critic | 90.4 |
| train/param_noise_di | 0.626 |

| _ | | | _ |
|---|------------------------|-----------|---|
| - | obs_rms_mean | -0.419 | I |
| | obs_rms_std | 1.9 | |
| | param_noise_stddev | 0.0618 | |
| | reference_Q_mean | -197 | |
| | reference_Q_std | 61.1 | l |
| | reference_action_mean | 0.172 | l |
| | reference_action_std | 0.944 | l |
| | reference_actor_Q_mean | -193 | l |
| | reference_actor_Q_std | 62.3 | l |
| | reference_perturbed | 0.843 | ١ |
| | rollout/Q_mean | -90.9 | l |
| | rollout/actions_mean | -0.165 | l |
| | rollout/actions_std | 0.748 | l |
| | rollout/episode_steps | 200 | l |
| | rollout/episodes | 60 | l |
| | rollout/return | -1.24e+03 | l |
| | rollout/return_history | -1.24e+03 | |
| | total/duration | 77.9 | l |
| | total/episodes | 60 | l |
| | total/epochs | 6 | l |
| | total/steps | 12000 | l |
| | total/steps_per_second | 154 | l |
| - | train/loss_actor | 137 | |

| train/loss_critic | 158 |
|---|-------------------|
| train/param_noise_di | |
| obs_rms_mean | -0.337 |
| | -0.337 1.88 |
| obs_rms_std | l 0.0507 |
| param_noise_stddev reference_Q_mean | 1 -202 |
| reference_Q_mean reference_Q_std | l -202 l 69.8 |
| · | |
| reference_action_mean | 0.309 |
| reference_action_std | 0.878 |
| reference_actor_Q_mean | -198 |
| reference_actor_Q_std | 71.3 |
| reference_perturbed | 0.904 |
| rollout/Q_mean | -90.8 |
| rollout/actions_mean | -0.149 |
| rollout/actions_std | 0.746 |
| rollout/episode_steps | 200 |
| rollout/episodes | 70 |
| rollout/return | -1.17e+03 |
| rollout/return_history | -1.17e+03 |
| total/duration | 90.8 |
| total/episodes | 70 |
| total/epochs | 7 |
| total/steps | 14000 |
| total/steps_per_second | 154 |
| train/loss_actor | 126 |
| train/loss_critic | 122 |
| train/param_noise_di | 0.539 |
| | |
| obs_rms_mean | -0.235 |
| obs_rms_std | 1.89 |
| param_noise_stddev | 0.0415 |
| reference_Q_mean | -205 |
| reference_Q_std | 77.6 |
| reference_action_mean | 0.399 |
| | 0.878 |
| ,- | -200 |
| | 78.1 |
| | l 0.869 |
| -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 -1 - | 1 00 |
| rollout/Q_mean | -89 |
| rollout/Q_mean rollout/actions_mean | -0.119 |
| rollout/Q_mean rollout/actions_mean rollout/actions_std | -0.119 0.753 |
| rollout/Q_mean rollout/actions_mean | -0.119 |

| rollout/return | -1.11e+03 |
|--|----------------------------|
| rollout/return_history | -1.11e+03 |
| total/duration | 104 |
| total/episodes | 80 |
| total/epochs | 8 |
| total/steps | 16000 |
| total/steps_per_second | 154 |
| train/loss_actor | 1 110 |
| train/loss_critic | l 103 |
| train/param_noise_di | 0.629 |
| | |
| | |
| | |
| obs_rms_mean | -0.179 |
| obs_rms_std | 1.86 |
| param_noise_stddev | 0.034 |
| reference_Q_mean | l -190 |
| reference_Q_std | 77.2 |
| | 0.37 |
| | l 0.886 l |
| | -184 |
| | 76.3 |
| reference_perturbed | 0.902 |
| rollout/Q_mean | -85.4 |
| rollout/actions_mean | -0.0935 |
| rollout/actions_mean | 0.752 |
| rollout/episode_steps | 0.732 200 |
| rollout/episode_steps | 200 90 |
| rollout/return | -1.06e+03 |
| | -1.06e+03 -1.06e+03 |
| rollout/return_history total/duration | -1.00e+03 117 |
| | |
| total/episodes | 90 |
| total/epochs | 9 |
| total/steps | 18000 |
| | 154 |
| | 94.5 |
| | 85.8 |
| train/param_noise_di | 0.491 |
| | |
| | |
| l obg rmg moor | I 0 006E I |
| | -0.0865 |
| obs_rms_std | |
| param_noise_stddev | 0.0279 |
| reference_Q_mean | -183 |
| reference_Q_std | 79.1 |
| | 0.352 |
| reference_action_std | 0.897 |

| reference_actor_Q_mean | 1 | -177 | I |
|------------------------|---|-----------|---|
| reference_actor_Q_std | - | 79.5 | |
| reference_perturbed | - | 0.789 | |
| rollout/Q_mean | - | -79.3 | |
| rollout/actions_mean | - | -0.0574 | |
| rollout/actions_std | - | 0.75 | |
| rollout/episode_steps | - | 200 | |
| rollout/episodes | - | 100 | |
| rollout/return | - | -1.02e+03 | |
| rollout/return_history | - | -1.02e+03 | |
| total/duration | - | 129 | |
| total/episodes | - | 100 | |
| total/epochs | - | 10 | |
| total/steps | - | 20000 | |
| total/steps_per_second | - | 155 | |
| train/loss_actor | - | 71.6 | |
| train/loss_critic | - | 110 | |
| train/param_noise_di | - | 0.437 | |

| obs_rms_mean | -0.0212 | obs_rms_std l 1.84 | param_noise_stddev 0.0229 | reference_Q_mean | -172 | reference_Q_std 81.4 | reference_action_mean 0.373 | reference_action_std 0.888 | reference_actor_Q_mean | -165 | reference_actor_Q_std 81.4 | reference_perturbed_... | 0.884 | rollout/Q_mean | -71.2 | rollout/actions_mean | -0.0571 | rollout/actions_std 0.741 | rollout/episode_steps 200 | rollout/episodes | 110 | rollout/return | -967 | rollout/return_history | -915 | total/duration | 142 | total/episodes l 110 | total/epochs | 11 | total/steps | 22000 | total/steps_per_second | 155 | train/loss_actor | 47.8 | train/loss_critic | train/param_noise_di... | 0.285

| obs_rms_mean | 0.0501 |
|------------------------|---------|
| obs_rms_std | 1.83 |
| param_noise_stddev | 0.0191 |
| reference_Q_mean | -156 |
| reference_Q_std | 87.4 |
| reference_action_mean | 0.378 |
| reference_action_std | 0.884 |
| reference_actor_Q_mean | -149 |
| reference_actor_Q_std | 86.9 |
| reference_perturbed | 0.786 |
| rollout/Q_mean | -63.7 |
| rollout/actions_mean | -0.0403 |
| rollout/actions_std | 0.736 |
| rollout/episode_steps | 200 |
| rollout/episodes | 120 |
| rollout/return | -937 |
| rollout/return_history | -842 |
| total/duration | 155 |
| total/episodes | 120 |
| total/epochs | 12 |
| total/steps | 24000 |
| total/steps_per_second | 155 |
| train/loss_actor | 24.3 |
| train/loss_critic | 117 |
| train/param_noise_di | 0.445 |
| | |
| | |
| | |

| ı | oha rma moon | ī | 0.152 | ı |
|---|------------------------|---|----------|---|
| | obs_rms_mean | ! | * | |
| | obs_rms_std | | 1.86 | ı |
| | param_noise_stddev | | 0.0163 | |
| | reference_Q_mean | | -148 | |
| | reference_Q_std | | 93.9 | |
| | reference_action_mean | | 0.396 | - |
| | reference_action_std | | 0.869 | - |
| | reference_actor_Q_mean | | -142 | - |
| | reference_actor_Q_std | | 95.3 | - |
| | reference_perturbed | | 0.93 | - |
| | rollout/Q_mean | | -58.2 | |
| | rollout/actions_mean | | -0.00247 | - |
| - | rollout/actions_std | | 0.741 | |
| - | rollout/episode_steps | | 200 | |
| - | rollout/episodes | | 130 | |
| - | rollout/return | | -944 | |
| - | rollout/return_history | | -806 | |
| | total/duration | | 168 | |
| | total/episodes | | 130 | |
| | | | | |

| total/epochs | 13 |
|---|---------|
| total/steps | 26000 |
| total/steps_per_second | 155 |
| train/loss_actor | 5.6 |
| train/loss_critic | 62.7 |
| train/param_noise_di | 0.268 |
| | |
| | |
| | |
| obs_rms_mean | 0.204 |
| obs_rms_std | 1.85 |
| param_noise_stddev | 0.0142 |
| reference_Q_mean | -139 |
| reference_Q_std | 95.7 |
| reference_action_mean | 0.414 |
| reference_action_std | 0.869 |
| reference_actor_Q_mean | -132 |
| reference_actor_Q_std | 96.2 |
| reference_perturbed | 0.879 |
| rollout/Q_mean | -49.9 |
| rollout/actions_mean | 0.00247 |
| rollout/actions_std | 0.738 |
| rollout/episode_steps | 200 |
| rollout/episodes | 140 |
| rollout/return | -922 |
| rollout/return_history | -751 |
| total/duration | 181 |
| total/episodes | 140 |
| total/epochs | 14 |
| total/steps | 28000 |
| total/steps_per_second | 155 |
| train/loss_actor | -19.1 |
| train/loss_critic | 134 |
| train/param_noise_di | 0.205 |
| | |
| | |
| | |
| · · · · · · - · · · - · · · · · · · · · | 0.23 |
| obs_rms_std | 1.82 |
| param_noise_stddev | 0.0121 |
| reference_Q_mean | -126 |
| reference_Q_std | 105 |
| reference_action_mean | 0.71 |
| reference_action_std | 0.608 |
| | -120 |
| | 106 |
| , | 0.803 |
| rollout/Q_mean | -39.3 |

| <pre> rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | 0.00628 0.727 200 150 150 194 150 155 30000 155 44.6 94.1 0.16 |
|--|--|
| | |
| | 0.266 |
| obs_rms_std | 1.81 0.0112 |
| <pre> param_noise_stddev reference_Q_mean</pre> | 0.0112 -118 |
| reference_Q_mean | 116 |
| reference_action_mean | 0.679 |
| reference_action_std | 0.639 I |
| reference_actor_Q_mean | -113 |
| | 110 107 |
| reference_perturbed | l 0.653 |
| rollout/Q_mean | -30.6 |
| rollout/actions_mean | 0.00624 |
| rollout/actions_std | 0.725 |
| rollout/episode_steps | 200 |
| rollout/episodes | l 160 |
| rollout/return | -866 |
| rollout/return_history | -640 |
| total/duration | 207 |
| total/episodes | 160 |
| total/epochs | 16 |
| total/steps | 32000 |
| total/steps_per_second | 155 |
| train/loss_actor | -64.8 |
| train/loss_critic | 107 |
| train/param_noise_di | 0.253 |
| | |
| obs_rms_mean | 0.275 |
| obs_rms_std | 1.78 |
| param_noise_stddev | 0.00991 |

| | reference_Q_mean | -114 | |
|---|----------------------------|---------|--|
| - | reference_Q_std | 112 | |
| - | reference_action_mean | 0.647 | |
| - | reference_action_std | 0.644 | |
| - | reference_actor_Q_mean | -108 | |
| | $reference_actor_Q_std$ | 112 | |
| | reference_perturbed | 0.811 | |
| | rollout/Q_mean | -20.1 | |
| | rollout/actions_mean | 0.00816 | |
| | rollout/actions_std | 0.714 | |
| | rollout/episode_steps | 200 | |
| | rollout/episodes | 170 | |
| | rollout/return | -833 | |
| | rollout/return_history | -599 | |
| | total/duration | 220 | |
| | total/episodes | 170 | |
| | total/epochs | 17 | |
| | total/steps | 34000 | |
| | total/steps_per_second | 155 | |
| | train/loss_actor | -82.4 | |
| - | train/loss_critic | 185 | |
| | train/param_noise_di | 0.14 | |
| | | | |

| obs_rms_mean 0.262 | obs_rms_std 1.76 | param_noise_stddev 0.00915 | reference_Q_mean | -110 | reference_Q_std | 115 | reference_action_mean 0.734 | reference_action_std 0.557 | reference_actor_Q_mean | -105 | reference_actor_Q_std | 117 | reference_perturbed_... | 0.565 | rollout/Q_mean | -10.7 | rollout/actions_mean 0.0105 | rollout/actions_std 1 0.708 | rollout/episode_steps | 200 | rollout/episodes l 180 | rollout/return | -804 | rollout/return_history | -559 | total/duration | 233 | total/episodes | 180 | total/epochs | 18 | total/steps 36000 | total/steps_per_second | 155 | train/loss_actor | -99.3

| train/loss_critic | 164 |
|------------------------|---------|
| train/param_noise_di | 0.29 |
| | |
| obs_rms_mean | 0.262 |
| obs_rms_std | 1.72 |
| param_noise_stddev | 0.00828 |
| reference_Q_mean | -107 |
| reference_Q_std | 122 |
| reference_action_mean | 0.583 |
| reference_action_std | 0.703 |
| reference_actor_Q_mean | -101 |
| reference_actor_Q_std | 123 |
| reference_perturbed | 0.627 |
| rollout/Q_mean | 0.606 |
| rollout/actions_mean | 0.00981 |
| rollout/actions_std | 0.694 |
| rollout/episode_steps | 200 |
| rollout/episodes | 190 |
| rollout/return | -770 |
| rollout/return_history | -509 |
| total/duration | 246 |
| total/episodes | 190 |
| total/epochs | 19 |
| total/steps | 38000 |
| total/steps_per_second | 155 |
| train/loss_actor | -120 |
| train/loss_critic | 184 |
| train/param_noise_di | 0.508 |
| | |
| obs_rms_mean | 0.272 |
| obs_rms_std | 1.7 |
| param_noise_stddev | 0.00812 |
| reference_Q_mean | -92 |
| reference_Q_std | 121 |
| reference_action_mean | 0.647 |
| reference_action_std | 0.634 |
| reference_actor_Q_mean | -84.6 |
| reference_actor_Q_std | 120 |
| reference_perturbed | 0.288 |
| rollout/Q_mean | 10.4 |
| rollout/actions_mean | 0.0103 |
| rollout/actions_std | 0.686 |
| rollout/episode_steps | 200 |
| rollout/episodes | 200 |

| rollout/return | l -748 l |
|------------------------|-----------|
| rollout/return_history | l -480 l |
| total/duration | l 259 |
| total/episodes | l 200 l |
| total/epochs | 1 20 |
| total/steps | l 40000 l |
| total/steps_per_second | l 155 |
| train/loss_actor | -137 |
| train/loss_critic | 158 |
| train/param_noise_di | 0.252 |
| | |
| | |
| obs_rms_mean | 0.272 |
| obs_rms_std | 1.68 |
| param_noise_stddev | 0.00796 |
| reference_Q_mean | -80.2 |
| reference_Q_std | 123 |
| reference_action_mean | 0.663 |
| reference_action_std | 0.637 |
| reference_actor_Q_mean | -71.1 |
| reference_actor_Q_std | 123 |
| reference_perturbed | 0.629 |
| rollout/Q_mean | 19.1 |
| rollout/actions_mean | 0.0109 |
| rollout/actions_std | 0.682 |
| rollout/episode_steps | 200 |
| rollout/episodes | 210 |
| rollout/return | -727 |
| rollout/return_history | -463 |
| total/duration | 272 |
| total/episodes | 210 |
| total/epochs | 21 |
| total/steps | 42000 |
| total/steps_per_second | 155 |
| train/loss_actor | -147 |
| train/loss_critic | 350 |
| train/param_noise_di | 0.415 |
| | |
| obs_rms_mean | 0.286 |
| obs_rms_std | 1.67 |
| param_noise_stddev | 0.00735 |
| | 1 7/4 1 |

| reference_Q_mean

| reference_Q_std

| reference_action_mean

| reference_action_std

| -74.1

0.657

0.663

| 123

| - | reference_actor_Q_mean | -66 | |
|---|------------------------|--------|---|
| - | reference_actor_Q_std | 124 | |
| - | reference_perturbed | 0.736 | |
| | rollout/Q_mean | 26.9 | |
| - | rollout/actions_mean | 0.0124 | |
| - | rollout/actions_std | 0.68 | |
| - | rollout/episode_steps | 200 | - |
| - | rollout/episodes | 220 | |
| - | rollout/return | -716 | |
| - | rollout/return_history | -451 | |
| - | total/duration | 285 | |
| - | total/episodes | 220 | |
| - | total/epochs | 22 | |
| | total/steps | 44000 | |
| | total/steps_per_second | 155 | |
| | train/loss_actor | -164 | |
| | train/loss_critic | 257 | |
| | train/param_noise_di | 0.381 | - |
| | | | |

| - | | |
|---|------------------------|---------|
| | obs_rms_mean | 0.288 |
| | obs_rms_std | 1.66 |
| | param_noise_stddev | 0.00721 |
| | reference_Q_mean | -53.9 |
| | reference_Q_std | 126 |
| | reference_action_mean | 0.599 |
| | reference_action_std | 0.723 |
| | reference_actor_Q_mean | -45.2 |
| | reference_actor_Q_std | 128 |
| | reference_perturbed | 0.787 |
| | rollout/Q_mean | 34.4 |
| | rollout/actions_mean | 0.00895 |
| | rollout/actions_std | 0.68 |
| | rollout/episode_steps | 200 |
| | rollout/episodes | 230 |
| | rollout/return | -705 |
| | rollout/return_history | -395 |
| | total/duration | 298 |
| | total/episodes | 230 |
| | total/epochs | 23 |
| | total/steps | 46000 |
| | total/steps_per_second | 154 |
| | train/loss_actor | -185 |
| | train/loss_critic | 386 |
| | train/param_noise_di | 0.373 |
| | | |

| obs_rms_mean | 0.286 |
|------------------------|---------|
| obs_rms_std | 1.65 |
| param_noise_stddev | 0.00652 |
| reference_Q_mean | -52.4 |
| reference_Q_std | 130 |
| reference_action_mean | 0.55 |
| reference_action_std | 0.726 |
| reference_actor_Q_mean | -44.8 |
| reference_actor_Q_std | 131 |
| reference_perturbed | 0.714 |
| rollout/Q_mean | 43.7 |
| rollout/actions_mean | 0.00866 |
| rollout/actions_std | 0.677 |
| rollout/episode_steps | 200 |
| rollout/episodes | 240 |
| rollout/return | -690 |
| rollout/return_history | -366 |
| total/duration | 311 |
| total/episodes | 240 |
| total/epochs | 24 |
| total/steps | 48000 |
| total/steps_per_second | 154 |
| train/loss_actor | -212 |
| train/loss_critic | 586 |
| train/param_noise_di | 0.26 |
| | |

| obs_rms_mean | Ι | 0.285 | I |
|------------------------|---|---------|---|
| obs_rms_std | Ι | 1.64 | I |
| param_noise_stddev | - | 0.00602 | 1 |
| reference_Q_mean | - | -31.8 | 1 |
| reference_Q_std | - | 140 | 1 |
| reference_action_mean | | 0.404 | 1 |
| reference_action_std | | 0.86 | 1 |
| reference_actor_Q_mean | | -19.9 | 1 |
| reference_actor_Q_std | | 140 | 1 |
| reference_perturbed | | 0.838 | 1 |
| rollout/Q_mean | | 52.2 | 1 |
| rollout/actions_mean | | 0.00446 | 1 |
| rollout/actions_std | | 0.676 | 1 |
| rollout/episode_steps | | 200 | 1 |
| rollout/episodes | | 250 | 1 |
| rollout/return | | -680 | I |
| rollout/return_history | | -370 | 1 |
| total/duration | - | 324 | 1 |
| total/episodes | | 250 | l |

| <pre> total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | 25 |
|--|-------|
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return rollout/return total/duration total/episodes total/steps total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | 0.284 |
| | 0.285 |

| rollout/actions mean | -0.00731 |
|---|------------------|
| rollout/actions_mean rollout/actions_std | 0.67 |
| | |
| rollout/episode_steps | 200 |
| rollout/episodes | 270 |
| rollout/return | -653 |
| rollout/return_history | -348 |
| total/duration | 350 |
| total/episodes | 270 |
| total/epochs | 27 |
| total/steps | 54000 |
| total/steps_per_second | 154 |
| train/loss_actor | - 297 |
| train/loss_critic | 1.19e+03 |
| train/param_noise_di | 0.386 |
| | |
| | |
| obs rms moon | 0.284 |
| | 0.284 1.6 |
| obs_rms_std | |
| param_noise_stddev | 0.00535 |
| reference_Q_mean | 51.9 |
| reference_Q_std | 129 |
| reference_action_mean | 0.262 |
| reference_action_std | 0.891 |
| reference_actor_Q_mean | 62.9 |
| reference_actor_Q_std | |
| reference_perturbed | 0.875 |
| rollout/Q_mean | 82.4 |
| rollout/actions_mean | -0.0068 |
| rollout/actions_std | 0.667 |
| rollout/episode_steps | 200 |
| rollout/episodes | 280 I |
| rollout/return | -645 l |
| rollout/return_history | -359 l |
| total/duration | 363 I |
| total/episodes | 280 |
| total/epochs | 28 |
| total/steps | 56000 I |
| total/steps_per_second | 154 |
| train/loss_actor | -302 |
| train/loss_critic | 747 |
| train/param_noise_di | 0.322 |
| | |
| | |
| | |
| obs_rms_mean | 0.281 |
| obs_rms_std | 1.59 |
| param_noise_stddev | 0.00494 |

| reference_Q_mean | 56.1 | |
|-----------------------------|----------|---|
| reference_Q_std | 134 | |
| reference_action_mean | 0.294 | |
| reference_action_std | 0.914 | |
| $reference_actor_Q_mean$ | 66.5 | |
| $reference_actor_Q_std$ | 134 | |
| reference_perturbed | 0.898 | |
| rollout/Q_mean | 92.7 | |
| rollout/actions_mean | -0.00738 | |
| rollout/actions_std | 0.662 | |
| rollout/episode_steps | 200 | |
| rollout/episodes | 290 | |
| rollout/return | -633 | |
| rollout/return_history | -373 | |
| total/duration | 376 | |
| total/episodes | 290 | |
| total/epochs | 29 | |
| total/steps | 58000 | |
| total/steps_per_second | 154 | |
| train/loss_actor | -309 | |
| train/loss_critic | 893 | |
| train/param_noise_di | 0.599 | I |

| obs_rms_mean | 0.285 | 1 |
|------------------------|---------|---|
| obs_rms_std | 1.57 | |
| param_noise_stddev | 0.00465 | |
| reference_Q_mean | 88.8 | |
| reference_Q_std | 120 | |
| reference_action_mean | 0.301 | |
| reference_action_std | 0.914 | |
| reference_actor_Q_mean | 100 | |
| reference_actor_Q_std | 118 | |
| reference_perturbed | 0.896 | |
| rollout/Q_mean | 102 | |
| rollout/actions_mean | -0.0106 | |
| rollout/actions_std | 0.656 | |
| rollout/episode_steps | 200 | |
| rollout/episodes | 300 | |
| rollout/return | -620 | |
| rollout/return_history | -364 | |
| total/duration | 389 | |
| total/episodes | 300 | |
| total/epochs | 30 | |
| total/steps | 60000 | |
| total/steps_per_second | 154 | |
| train/loss_actor | -317 | |

| train/loss_critic | 622 |
|------------------------|--------------------|
| train/param_noise_di | 0.193 |
| | |
| | |
| | |
| obs_rms_mean | 0.284 |
| obs_rms_std | 1.56 |
| param_noise_stddev | 0.00456 |
| reference_Q_mean | 119 |
| reference_Q_std | 110 |
| reference_action_mean | 0.382 |
| reference_action_std | 0.871 |
| reference_actor_Q_mean | 129 |
| reference_actor_Q_std | 110 |
| reference_perturbed | 0.892 |
| rollout/Q_mean | 111 |
| rollout/actions_mean | -0.0125 |
| rollout/actions_std | 0.651 |
| rollout/episode_steps | l 200 l |
| rollout/episodes | 310 |
| rollout/return | l -608 |
| rollout/return_history | l -356 l |
| total/duration | l 402 |
| total/episodes | l 310 |
| total/epochs | 31 |
| total/steps | l 62000 l |
| total/steps_per_second | 154 |
| train/loss_actor | -319 |
| train/loss_actor | -319 |
| | 0.171 |
| train/param_noise_di | 0.171 |
| | |
| | |
| obs_rms_mean | 0.282 |
| obs_rms_std | 1.54 |
| param_noise_stddev | 0.00465 |
| reference_Q_mean | 125 |
| reference_Q_std | l 104 |
| reference_action_mean | l 0.365 l |
| reference_action_std | l 0.844 l |
| | 134 |
| reference_actor_Q_std | 104 |
| reference_perturbed | 102 |
| rollout/Q_mean | 0.821 120 |
| rollout/q_mean | 120 -0.0146 |
| rollout/actions_mean | 0.647 |
| | |
| rollout/episode_steps | 200 |
| rollout/episodes | 320 |

| rollout/return | l -595 l |
|----------------------------------|--------------|
| rollout/return_history | l -328 |
| total/duration | 415 |
| total/episodes | 1 320 |
| total/episodes total/epochs | 1 32 |
| - | 64000 |
| total/steps | 1 154 |
| total/steps_per_second | -317 |
| train/loss_actor | -51 <i>t</i> |
| train/loss_critic | |
| train/param_noise_di | 0.347 |
| | |
| obs_rms_mean | 0.279 |
| obs_rms_std | 1 1.53 |
| | |
| param_noise_stddev | 0.00465 |
| reference_Q_mean | 129 |
| reference_Q_std | 105 |
| reference_action_mean | 0.63 |
| reference_action_std | 0.596 |
| reference_actor_Q_mean | 134 |
| reference_actor_Q_std | 103 |
| reference_perturbed | 0.662 |
| rollout/Q_mean | 128 |
| rollout/actions_mean | -0.0166 |
| rollout/actions_std | 0.641 |
| rollout/episode_steps | 200 |
| rollout/episodes | 330 |
| rollout/return | -582 |
| rollout/return_history | -299 |
| total/duration | 428 |
| total/episodes | 330 |
| total/epochs | 33 |
| total/steps | 66000 |
| total/steps_per_second | l 154 |
| train/loss_actor | I -304 |
| train/loss_critic | 1.23e+03 |
| train/param_noise_di | |
| | |
| | |
| obs_rms_mean | 0.276 |
| obs_rms_std | 1.51 |
| param_noise_stddev | 0.00474 |
| reference_Q_mean | 1 114 |
| l rererence d'mean | 1 114 |

| reference_Q_std

| reference_action_mean

| reference_action_std

93.6

0.469

0.753

| | reference_actor_Q_mean | 1 | 120 | | |
|--|-----------------------------------|---|---------|---|--|
| | reference_actor_Q_std | | 95.1 | | |
| | $\tt reference_perturbed_\dots$ | | 0.699 | | |
| | $rollout/Q_mean$ | | 135 | | |
| | rollout/actions_mean | | -0.0158 | | |
| | rollout/actions_std | - | 0.636 | | |
| | rollout/episode_steps | | 200 | | |
| | rollout/episodes | - | 340 | | |
| | rollout/return | - | -571 | | |
| | rollout/return_history | | -283 | | |
| | total/duration | - | 441 | | |
| | total/episodes | - | 340 | | |
| | total/epochs | - | 34 | | |
| | total/steps | - | 68000 | | |
| | total/steps_per_second | - | 154 | | |
| | train/loss_actor | 1 | -285 | | |
| | train/loss_critic | 1 | 493 | | |
| | train/param_noise_di | 1 | 0.102 | 1 | |
| | | | | | |

| obs_rms_mean | 0.268 | |
|------------------------|---------|---|
| obs_rms_std | 1.51 | |
| param_noise_stddev | 0.00494 | - |
| reference_Q_mean | 82.4 | |
| reference_Q_std | 105 | |
| reference_action_mean | 0.651 | |
| reference_action_std | 0.658 | |
| reference_actor_Q_mean | 89.4 | |
| reference_actor_Q_std | 106 | |
| reference_perturbed | 0.659 | |
| rollout/Q_mean | 140 | |
| rollout/actions_mean | -0.0136 | - |
| rollout/actions_std | 0.634 | |
| rollout/episode_steps | 200 | |
| rollout/episodes | 350 | |
| rollout/return | -563 | |
| rollout/return_history | -273 | |
| total/duration | 454 | |
| total/episodes | 350 | |
| total/epochs | 35 | |
| total/steps | 70000 | |
| total/steps_per_second | 154 | |
| train/loss_actor | -266 | |
| train/loss_critic | 512 | |
| train/param_noise_di | 0.281 | |
| | | |

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| obs_rms_mean | 0.263 |
|------------------------|---------|
| obs_rms_std | 1.5 |
| param_noise_stddev | 0.00535 |
| reference_Q_mean | 72.4 |
| reference_Q_std | 103 |
| reference_action_mean | 0.589 |
| reference_action_std | 0.725 |
| reference_actor_Q_mean | 78.3 |
| reference_actor_Q_std | 104 |
| reference_perturbed | 0.636 |
| rollout/Q_mean | 145 |
| rollout/actions_mean | -0.0111 |
| rollout/actions_std | 0.631 |
| rollout/episode_steps | 200 |
| rollout/episodes | 360 |
| rollout/return | -556 |
| rollout/return_history | -277 |
| total/duration | 467 |
| total/episodes | 360 |
| total/epochs | 36 |
| total/steps | 72000 |
| total/steps_per_second | 154 |
| train/loss_actor | -256 |
| train/loss_critic | 696 |
| train/param_noise_di | 0.192 |
| | |

| ١ | obs_rms_mean | 1 | 0.262 | - |
|---|------------------------|---|---------|---|
| - | obs_rms_std | | 1.48 | - |
| - | param_noise_stddev | | 0.00545 | - |
| - | reference_Q_mean | | 54.8 | - |
| - | reference_Q_std | | 100 | - |
| - | reference_action_mean | | 0.525 | - |
| - | reference_action_std | | 0.743 | - |
| - | reference_actor_Q_mean | | 61.3 | - |
| - | reference_actor_Q_std | | 99 | - |
| - | reference_perturbed | | 0.716 | - |
| - | rollout/Q_mean | | 149 | - |
| - | rollout/actions_mean | | -0.0125 | |
| - | rollout/actions_std | | 0.625 | - |
| - | rollout/episode_steps | | 200 | - |
| - | rollout/episodes | | 370 | - |
| - | rollout/return | | -545 | - |
| - | rollout/return_history | | -252 | |
| - | total/duration | | 480 | - |
| - | total/episodes | | 370 | |

| total/steps | 37 |
|---|-------------------|
| obs_rms_mean | 0.26 |
| obs_rms_std | 1.47 |
| param_noise_stddev | 0.00504 |
| reference_Q_mean | 30.8 |
| reference_Q_std | 97.7 |
| reference_action_mean | 0.281 |
| reference_action_std | 0.898 |
| reference_actor_Q_mean | 36.6 |
| , | 99 |
| <pre> reference_perturbed rollout/Q_mean</pre> | 0.895 152 |
| rollout/q_mean rollout/actions_mean | 152 |
| rollout/actions_mean | 0.621 |
| rollout/episode_steps | 1 200 |
| rollout/episodes | 380 |
| rollout/return | -537 |
| rollout/return_history | -234 |
| total/duration | 493 |
| total/episodes | 380 |
| total/epochs | 38 |
| total/steps | 76000 |
| total/steps_per_second | 154 |
| train/loss_actor | -241 |
| train/loss_critic | 377 |
| train/param_noise_di | 0.183 |
| | |
| • | 0.254 |
| obs_rms_std | 1.46 |
| param_noise_stddev | 0.00474 |
| reference_Q_mean | 22.8 |
| reference_Q_std | 108 |
| reference_action_mean | 0.242 |
| | 0.907 29.4 |
| 1 101010100_00001_4 | 29.4 109 |
| | 0.934 |
| | 0.934 |
| I TOTTOUC/ M-mean | 1 100 |

| rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | -0.0158 0.617 200 390 -530 -233 506 390 39 78000 154 -235 522 0.177 |
|--|---|
| | |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return rollout/return total/duration total/episodes total/steps total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | 0.252 |
| obs_rms_mean obs_rms_std param_noise_stddev | 0.252 1.44 0.00494 |

| - | reference_Q_mean | - | 19.2 | 1 |
|-----|------------------------|---|---------|---|
| - 1 | reference_Q_std | | 121 | 1 |
| | reference_action_mean | - | 0.343 | 1 |
| - 1 | reference_action_std | - | 0.855 | 1 |
| - 1 | reference_actor_Q_mean | 1 | 25.1 | 1 |
| - 1 | reference_actor_Q_std | 1 | 121 | 1 |
| | reference_perturbed | 1 | 0.903 | 1 |
| | rollout/Q_mean | 1 | 162 | 1 |
| - 1 | rollout/actions_mean | 1 | -0.0224 | 1 |
| - 1 | rollout/actions_std | 1 | 0.609 | 1 |
| | rollout/episode_steps | 1 | 200 | 1 |
| | rollout/episodes | 1 | 410 | 1 |
| | rollout/return | 1 | -515 | 1 |
| - 1 | rollout/return_history | 1 | -226 | 1 |
| - 1 | total/duration | 1 | 533 | 1 |
| | total/episodes | 1 | 410 | 1 |
| | total/epochs | 1 | 41 | 1 |
| | total/steps | 1 | 82000 | 1 |
| - | total/steps_per_second | Ι | 154 | 1 |
| - | train/loss_actor | 1 | -255 | 1 |
| - | train/loss_critic | 1 | 736 | 1 |
| - | train/param_noise_di | 1 | 0.161 | 1 |
| | - | | | |

| obs_rms_mean | 0.25 |
|------------------------|---------|
| obs_rms_std | 1.43 |
| param_noise_stddev | 0.00484 |
| reference_Q_mean | 17 |
| reference_Q_std | 126 |
| reference_action_mean | 0.352 |
| reference_action_std | 0.823 |
| reference_actor_Q_mean | 22.1 |
| reference_actor_Q_std | 128 |
| reference_perturbed | 0.809 |
| rollout/Q_mean | 165 |
| rollout/actions_mean | -0.0313 |
| rollout/actions_std | 0.607 |
| rollout/episode_steps | 200 |
| rollout/episodes | 420 |
| rollout/return | -508 |
| rollout/return_history | -228 |
| total/duration | 546 |
| total/episodes | 420 |
| total/epochs | 42 |
| total/steps | 84000 |
| total/steps_per_second | 154 |
| train/loss_actor | -294 |
| | |

| <pre> train/loss_critic train/param_noise_di</pre> | 1.02e+03 0.259 |
|---|-----------------------|
| | |
| obs_rms_mean | 0.246 |
| obs_rms_std | 1.43 |
| param_noise_stddev | 0.00484 |
| reference_Q_mean | 5.24 |
| reference_Q_std | 146 |
| reference_action_mean | 0.625 |
| reference_action_std | 0.639 |
| reference_actor_Q_mean | 11.7 |
| reference_actor_Q_std | 148 |
| reference_perturbed | 0.644 |
| rollout/Q_mean | 167 |
| rollout/actions_mean | -0.036 |
| rollout/actions_std | 0.607 |
| rollout/episode_steps | 200 |
| rollout/episodes | 430 |
| rollout/return | -502 |
| rollout/return_history | -238 |
| total/duration | 559 |
| total/episodes | 430 |
| total/epochs | 43 |
| total/steps | 86000 |
| total/steps_per_second | 154 |
| train/loss_actor | -316 |
| train/loss_critic | 1.06e+03 |
| train/param_noise_di | 0.243 |
| | |
| obs_rms_mean | 0.243 |
| obs_rms_std | 1.42 |
| param_noise_stddev | 0.00535 |
| reference_Q_mean | 14.8 |
| reference_Q_std | 164 |
| reference_action_mean | 0.57 |
| reference_action_std | 0.706 |
| reference_actor_Q_mean | 21 |
| reference_actor_Q_std | 167 |
| reference_perturbed | 0.755 |
| rollout/Q_mean | 172 |
| rollout/actions_mean | -0.0324 |
| rollout/actions_std | 0.607 |
| rollout/episode_steps | 200 |
| rollout/episodes | 440 |
| | |

| <pre> rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second</pre> | -497 |
|--|---------|
| <pre> train/loss_actor train/loss_critic</pre> | -346 |
| train/param_noise_di | 0.14 |
| | |
| | |
| obs_rms_mean | 0.238 |
| obs_rms_std | 1.41 |
| param_noise_stddev | 0.00545 |
| reference_Q_mean | 34.2 |
| reference_Q_std | 171 |
| reference_action_mean | 0.457 |
| reference_action_std | 0.793 |
| reference_actor_Q_mean | 42 |
| reference_actor_Q_std | 174 |
| reference_perturbed | 0.744 |
| rollout/Q_mean | 176 |
| rollout/actions_mean | -0.0294 |
| rollout/actions_std | 0.607 |
| rollout/episode_steps | 200 |
| rollout/episodes | 450 |
| rollout/return | -491 |
| rollout/return_history | -240 |
| total/duration | 585 |
| total/episodes | 450 |
| | 45 |
| total/steps | 90000 |
| | 154 |
| train/loss_actor | -366 |
| train/loss_critic | 981 |
| train/param_noise_di | 0.166 |
| | |
| | |
| l oha rma moon | 0.236 |
| • | |
| obs_rms_std | 1.4 |
| param_noise_stddev | 0.00545 |
| reference_Q_mean | 56.1 |
| reference_Q_std | 177 |
| reference_action_mean | 0.229 |
| reference_action_std | 0.921 |

| - | reference_actor_Q_mean | | 66.8 | - |
|---|------------------------|--|---------|---|
| | reference_actor_Q_std | | 177 | |
| | reference_perturbed | | 0.878 | |
| | $rollout/Q_mean$ | | 181 | - |
| | rollout/actions_mean | | -0.0278 | |
| | rollout/actions_std | | 0.606 | |
| | rollout/episode_steps | | 200 | |
| | rollout/episodes | | 460 | - |
| | rollout/return | | -485 | |
| | rollout/return_history | | -232 | |
| | total/duration | | 598 | - |
| | total/episodes | | 460 | - |
| | total/epochs | | 46 | - |
| | total/steps | | 92000 | |
| | total/steps_per_second | | 154 | |
| | train/loss_actor | | -387 | |
| | train/loss_critic | | 974 | - |
| | train/param_noise_di | | 0.238 | |
| | | | | |

| obs_rms_mean | 0.23 |
|------------------------|---------|
| obs_rms_std | 1.41 |
| param_noise_stddev | 0.00524 |
| reference_Q_mean | 111 |
| reference_Q_std | 151 |
| reference_action_mean | 0.271 |
| reference_action_std | 0.874 |
| reference_actor_Q_mean | 123 |
| reference_actor_Q_std | 151 |
| reference_perturbed | 0.889 |
| rollout/Q_mean | 185 |
| rollout/actions_mean | -0.0297 |
| rollout/actions_std | 0.606 |
| rollout/episode_steps | 200 |
| rollout/episodes | 470 |
| rollout/return | -484 |
| rollout/return_history | -260 |
| total/duration | 611 |
| total/episodes | 470 |
| total/epochs | 47 |
| total/steps | 94000 |
| total/steps_per_second | 154 |
| train/loss_actor | -386 |
| train/loss_critic | 538 |
| train/param_noise_di | 0.247 |
| | |

| | | - |
|------------------------|---------|---|
| obs_rms_mean | 0.223 | |
| obs_rms_std | 1.42 | |
| param_noise_stddev | 0.00545 | |
| reference_Q_mean | 119 | |
| reference_Q_std | 134 | |
| reference_action_mean | 0.197 | l |
| reference_action_std | 0.87 | l |
| reference_actor_Q_mean | 127 | l |
| reference_actor_Q_std | 134 | l |
| reference_perturbed | 0.854 | |
| rollout/Q_mean | 189 | |
| rollout/actions_mean | -0.0272 | l |
| rollout/actions_std | 0.608 | l |
| rollout/episode_steps | 200 | l |
| rollout/episodes | 480 | ı |
| rollout/return | -493 | ı |
| rollout/return_history | -325 | ı |
| total/duration | 624 | |
| total/episodes | 480 | |
| total/epochs | 48 | |
| total/steps | 96000 | |
| total/steps_per_second | 154 | l |
| train/loss_actor | -372 | ı |
| train/loss_critic | 503 | |
| train/param_noise_di | 0.2 | l |
| | | - |

| l ob | s_rms_mean | ı | 0.213 | 1 |
|------|-----------------------|---|---------|---|
| | s_rms_std | İ | 1.43 | i |
| l pa | ram_noise_stddev | Ī | 0.00494 | ĺ |
| | ference_Q_mean | ١ | 110 | |
| re | ference_Q_std | ١ | 119 | |
| re | eference_action_mean | ١ | 0.287 | 1 |
| re | ference_action_std | | 0.857 | 1 |
| re | ference_actor_Q_mean | | 118 | 1 |
| re | ference_actor_Q_std | | 117 | 1 |
| re | ference_perturbed | | 0.87 | |
| ro | ollout/Q_mean | | 192 | |
| ro | ollout/actions_mean | | -0.0256 | |
| ro | llout/actions_std | | 0.608 | |
| ro | llout/episode_steps | | 200 | |
| ro | llout/episodes | | 490 | |
| ro | ollout/return | | -501 | |
| ro | ollout/return_history | | -385 | |
| to | tal/duration | | 637 | |
| to | otal/episodes | | 490 | |
| | | | | |

```
| total/steps_per_second | 154
| train/loss_actor
                        | -334
| train/loss_critic
                        I 761
| train/param_noise_di... | 0.208
obs_rms_mean
                        0.195
                        1.44
| obs_rms_std
| param_noise_stddev
                       0.00465
| reference_Q_mean
                        | 105
| reference_Q_std
                        94.4
| reference_action_mean
                        0.254
| reference_action_std
                        0.86
| reference_actor_Q_mean | 114
| reference_actor_Q_std
                      | 93
| reference_perturbed_... | 0.856
| rollout/Q_mean
                        194
| rollout/actions_mean
                       | -0.0244
| rollout/actions_std
                        0.608
| rollout/episode_steps
                        1 200
| rollout/episodes
                        I 500
| rollout/return
                        I -506
| rollout/return_history | -440
| total/duration
                        650
| total/episodes
                        | 500
| total/epochs
                        | 50
| total/steps
                        100000
| total/steps_per_second | 154
| train/loss_actor
                        | -287
| train/loss_critic
                        | 478
| train/param_noise_di... | 0.231
total runtime: 653.5052380561829s
WARN: gym.spaces.Box autodetected dtype as <class 'numpy.float32'>. Please provide explicit dtype
WARN: gym.spaces.Box autodetected dtype as <class 'numpy.float32'>. Please provide explicit dtype
rank 0: seed=0, logdir=C:\Users\LINDAI~1\AppData\Local\Temp\openai-2018-07-02-23-26-41-735687
scaling actions by [ 2.] before executing in env
setting up param noise
 param_noise_actor/dense/kernel:0 <- actor/dense/kernel:0 + noise</pre>
 param_noise_actor/dense/bias:0 <- actor/dense/bias:0 + noise</pre>
 param_noise_actor/LayerNorm/beta:0 <- actor/LayerNorm/beta:0</pre>
 param_noise_actor/LayerNorm/gamma:0 <- actor/LayerNorm/gamma:0</pre>
```

| total/epochs

| total/steps

1 49

1 98000

param_noise_actor/dense_1/kernel:0 <- actor/dense_1/kernel:0 + noise</pre>

```
param_noise_actor/dense_1/bias:0 <- actor/dense_1/bias:0 + noise</pre>
   param_noise_actor/LayerNorm_1/beta:0 <- actor/LayerNorm_1/beta:0</pre>
   param_noise_actor/LayerNorm_1/gamma:0 <- actor/LayerNorm_1/gamma:0</pre>
   param_noise_actor/dense_2/kernel:0 <- actor/dense_2/kernel:0 + noise</pre>
   param_noise_actor/dense_2/bias:0 <- actor/dense_2/bias:0 + noise</pre>
   adaptive_param_noise_actor/dense/kernel:0 <- actor/dense/kernel:0 + noise
   adaptive_param_noise_actor/dense/bias:0 <- actor/dense/bias:0 + noise
   adaptive_param_noise_actor/LayerNorm/beta:0 <- actor/LayerNorm/beta:0
   adaptive_param_noise_actor/LayerNorm/gamma:0 <- actor/LayerNorm/gamma:0
   adaptive_param_noise_actor/dense_1/kernel:0 <- actor/dense_1/kernel:0 + noise
   adaptive_param_noise_actor/dense_1/bias:0 <- actor/dense_1/bias:0 + noise
   adaptive_param_noise_actor/LayerNorm_1/beta:0 <- actor/LayerNorm_1/beta:0
   adaptive_param_noise_actor/LayerNorm_1/gamma:0 <- actor/LayerNorm_1/gamma:0
   adaptive_param_noise_actor/dense_2/kernel:0 <- actor/dense_2/kernel:0 + noise
   adaptive_param_noise_actor/dense_2/bias:0 <- actor/dense_2/bias:0 + noise
setting up actor optimizer
   actor shapes: [[3, 64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [61], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], [64], 
   actor params: 4737
setting up critic optimizer
   regularizing: critic/dense/kernel:0
   regularizing: critic/dense_1/kernel:0
   regularizing: critic/dense_2/kernel:0
   applying 12 regularization with 0.01
   critic shapes: [[3, 64], [64], [64], [64], [65, 64], [64], [64], [64], [64, 1], [1]]
   critic params: 4801
setting up target updates ...
   target_actor/dense/kernel:0 <- actor/dense/kernel:0</pre>
   target_actor/dense/bias:0 <- actor/dense/bias:0</pre>
   target_actor/LayerNorm/beta:0 <- actor/LayerNorm/beta:0</pre>
   target_actor/LayerNorm/gamma:0 <- actor/LayerNorm/gamma:0</pre>
   target_actor/dense_1/kernel:0 <- actor/dense_1/kernel:0</pre>
   target_actor/dense_1/bias:0 <- actor/dense_1/bias:0</pre>
   target_actor/LayerNorm_1/beta:0 <- actor/LayerNorm_1/beta:0</pre>
   target_actor/LayerNorm_1/gamma:0 <- actor/LayerNorm_1/gamma:0</pre>
   target_actor/dense_2/kernel:0 <- actor/dense_2/kernel:0</pre>
   target_actor/dense_2/bias:0 <- actor/dense_2/bias:0</pre>
setting up target updates ...
   target_critic/dense/kernel:0 <- critic/dense/kernel:0</pre>
   target_critic/dense/bias:0 <- critic/dense/bias:0</pre>
   target_critic/LayerNorm/beta:0 <- critic/LayerNorm/beta:0</pre>
   target_critic/LayerNorm/gamma:0 <- critic/LayerNorm/gamma:0</pre>
   target_critic/dense_1/kernel:0 <- critic/dense_1/kernel:0</pre>
   target_critic/dense_1/bias:0 <- critic/dense_1/bias:0</pre>
   target_critic/LayerNorm_1/beta:0 <- critic/LayerNorm_1/beta:0</pre>
   target_critic/LayerNorm_1/gamma:0 <- critic/LayerNorm_1/gamma:0</pre>
   target_critic/dense_2/kernel:0 <- critic/dense_2/kernel:0</pre>
   target_critic/dense_2/bias:0 <- critic/dense_2/bias:0</pre>
Using agent with the following configuration:
```

dict_items([('obs0', <tf.Tensor 'obs0:0' shape=(?, 3) dtype=float32>), ('obs1', <tf.Tensor 'obs1

| - | | |
|---|----------------------------|-----------|
| | obs_rms_mean | -0.0591 |
| | obs_rms_std | 1.72 |
| | param_noise_stddev | 0.188 |
| | reference_Q_mean | -58.3 |
| | reference_Q_std | 11.9 |
| | reference_action_mean | 0.935 |
| | reference_action_std | 0.0133 |
| | reference_actor_Q_mean | -58.2 |
| | $reference_actor_Q_std$ | 11.9 |
| | reference_perturbed | 0.276 |
| | rollout/Q_mean | -25.1 |
| | rollout/actions_mean | 0.03 |
| | rollout/actions_std | 0.617 |
| | rollout/episode_steps | 200 |
| | rollout/episodes | 10 |
| | rollout/return | -1.55e+03 |
| | rollout/return_history | -1.55e+03 |
| | total/duration | 13 |
| | total/episodes | 10 |
| | total/epochs | 1 |
| | total/steps | 2000 |
| | total/steps_per_second | 154 |
| | train/loss_actor | 55 |
| | train/loss_critic | 17 |
| | train/param_noise_di | 0.132 |
| | | |

| obs_rms_mean | 1 | -0.202 | 1 |
|------------------------|---|----------|---|
| obs_rms_std | | 1.96 | |
| param_noise_stddev | 1 | 0.158 | |
| reference_Q_mean | 1 | -114 | |
| reference_Q_std | 1 | 20.7 | |
| reference_action_mean | 1 | -0.475 | |
| reference_action_std | 1 | 0.869 | |
| reference_actor_Q_mean | 1 | -113 | |
| reference_actor_Q_std | 1 | 21.8 | |
| reference_perturbed | | 0.0659 | |
| rollout/Q_mean | | -53 | |
| rollout/actions_mean | 1 | -0.0864 | |
| rollout/actions_std | 1 | 0.721 | |
| rollout/episode_steps | 1 | 200 | |
| rollout/episodes | | 20 | |
| rollout/return | | -1.5e+03 | |
| rollout/return_history | 1 | -1.5e+03 | |
| total/duration | | 25.6 | |

| total/episodes | 20 |
|------------------------|-----------|
| total/epochs | 1 2 |
| total/steps | 4000 |
| total/steps_per_second | l 156 |
| train/loss_actor | I 108 I |
| train/loss_critic | 1 56.4 |
| train/param_noise_di | |
| | |
| | |
| | |
| obs_rms_mean | -0.0779 |
| obs_rms_std | 1.94 |
| param_noise_stddev | 0.129 |
| reference_Q_mean | -161 |
| reference_Q_std | 23.2 |
| reference_action_mean | 0.494 |
| reference_action_std | 0.836 |
| reference_actor_Q_mean | -159 |
| reference_actor_Q_std | 24.3 |
| reference_perturbed | 0.524 |
| rollout/Q_mean | -77.9 |
| rollout/actions_mean | -0.0793 |
| rollout/actions_std | 0.743 |
| rollout/episode_steps | 200 |
| rollout/episodes | 30 |
| rollout/return | -1.48e+03 |
| rollout/return_history | -1.48e+03 |
| total/duration | 38.2 |
| total/episodes | 30 |
| total/epochs | 3 |
| total/steps | 6000 |
| total/steps_per_second | 157 |
| train/loss_actor | 149 |
| train/loss_critic | 100 |
| train/param_noise_di | 0.621 |
| | |
| | |
| | |
| obs_rms_mean | -0.0434 |
| obs_rms_std | 1.85 |
| param_noise_stddev | 0.106 |
| reference_Q_mean | -189 |
| reference_Q_std | 36 |
| reference_action_mean | 0.449 |
| reference_action_std | 0.836 |
| reference_actor_Q_mean | -186 |
| reference_actor_Q_std | 37.2 |
| reference_perturbed | 0.552 |
| | |

| <pre> rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | -98.4 |
|--|--------------------|
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/return rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | -0.0486 |
| obs_rms_mean obs_rms_std | 0.0786 1.85 |

| | param_noise_stddev | | 0.0711 | |
|--|-----------------------------|---|-----------|--|
| | reference_Q_mean | | -216 | |
| | reference_Q_std | | 46.9 | |
| | reference_action_mean | | 0.062 | |
| | reference_action_std | | 0.935 | |
| | $reference_actor_Q_mean$ | | -212 | |
| | $reference_actor_Q_std$ | | 49.1 | |
| | reference_perturbed | | 0.58 | |
| | rollout/Q_mean | | -115 | |
| | rollout/actions_mean | | 0.00566 | |
| | rollout/actions_std | | 0.723 | |
| | rollout/episode_steps | | 200 | |
| | rollout/episodes | | 60 | |
| | rollout/return | | -1.27e+03 | |
| | rollout/return_history | | -1.27e+03 | |
| | total/duration | | 76.1 | |
| | total/episodes | | 60 | |
| | total/epochs | | 6 | |
| | total/steps | | 12000 | |
| | total/steps_per_second | | 158 | |
| | train/loss_actor | | 182 | |
| | train/loss_critic | | 247 | |
| | train/param_noise_di | I | 0.55 | |
| | | | | |

| obs_rms_mean | 0.193 |
|------------------------|----------|
| obs_rms_std | 1.85 |
| param_noise_stddev | 0.0582 |
| reference_Q_mean | -219 |
| reference_Q_std | 56 |
| reference_action_mean | 0.0381 |
| reference_action_std | 0.942 |
| reference_actor_Q_mean | -214 |
| reference_actor_Q_std | 59.2 |
| reference_perturbed | 0.449 |
| rollout/Q_mean | -117 |
| rollout/actions_mean | 0.019 |
| rollout/actions_std | 0.714 |
| rollout/episode_steps | 200 |
| rollout/episodes | 70 |
| rollout/return | -1.2e+03 |
| rollout/return_history | -1.2e+03 |
| total/duration | 88.7 |
| total/episodes | 70 |
| total/epochs | 7 |
| total/steps | 14000 |
| total/steps_per_second | 158 |
| | |

| <pre> train/loss_actor train/loss_critic train/param_noise_di</pre> | 171 |
|--|-------|
| | |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return total/duration total/duration total/steps total/steps total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | 0.258 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps | 0.264 |

| - | rollout/episodes | - | 90 | 1 |
|---|------------------------|---|-----------|---|
| | rollout/return | 1 | -1.06e+03 | |
| | rollout/return_history | 1 | -1.06e+03 | |
| - | total/duration | | 114 | |
| | total/episodes | 1 | 90 | |
| | total/epochs | 1 | 9 | |
| - | total/steps | | 18000 | |
| - | total/steps_per_second | - | 158 | |
| - | train/loss_actor | - | 132 | |
| - | train/loss_critic | - | 126 | |
| - | train/param_noise_di | | 0.455 | |
| | | | | |

| obs_rms_mean 0.266 1.74 | obs_rms_std | param_noise_stddev 0.0334 | reference_Q_mean | -207 | reference_Q_std 84.1 | reference_action_mean | -0.0385 | reference_action_std 0.924 | reference_actor_Q_mean | -200 | reference_actor_Q_std 86.9 | reference_perturbed_... | 0.817 | rollout/Q_mean | -101 | rollout/actions_mean 0.0291 | rollout/actions_std 0.676 | rollout/episode_steps | 200 | rollout/episodes 100 | rollout/return | -983 | rollout/return_history | -983 | total/duration | 126 | total/episodes 100 | total/epochs | 10 | total/steps 20000 | total/steps_per_second | 158 | train/loss_actor | 106 | train/loss_critic | 136 | train/param_noise_di... | 0.723

| obs_rms_mean | 0.265 | - |
|-----------------------|--------|---|
| obs_rms_std | 1.7 | - |
| param_noise_stddev | 0.0279 | |
| reference_Q_mean | -196 | |
| reference_Q_std | 86.7 | |
| reference_action_mean | -0.423 | - |

| - | reference_action_std | 0.824 | |
|---|------------------------|--------|---|
| | reference_actor_Q_mean | -189 | |
| | reference_actor_Q_std | 88.7 | |
| | reference_perturbed | 0.82 | |
| | $rollout/Q_mean$ | -94.2 | |
| | rollout/actions_mean | 0.0364 | |
| | rollout/actions_std | 0.662 | |
| | rollout/episode_steps | 200 | |
| | rollout/episodes | 110 | |
| | rollout/return | -927 | - |
| | rollout/return_history | -864 | |
| | total/duration | 139 | |
| | total/episodes | 110 | - |
| | total/epochs | 11 | |
| | total/steps | 22000 | - |
| | total/steps_per_second | 158 | |
| | train/loss_actor | 88.1 | |
| | train/loss_critic | 111 | |
| | train/param_noise_di | 0.388 | - |
| | | | |

| obs_rms_mean | 0.248 |
|------------------------|--------|
| obs_rms_std | 1.68 |
| param_noise_stddev | 0.0233 |
| reference_Q_mean | -182 |
| reference_Q_std | 89.8 |
| reference_action_mean | -0.484 |
| reference_action_std | 0.826 |
| reference_actor_Q_mean | -174 |
| reference_actor_Q_std | 92.8 |
| reference_perturbed | 0.746 |
| rollout/Q_mean | -88.1 |
| rollout/actions_mean | 0.0375 |
| rollout/actions_std | 0.651 |
| rollout/episode_steps | 200 |
| rollout/episodes | 120 |
| rollout/return | -881 |
| rollout/return_history | -757 |
| total/duration | 152 |
| total/episodes | 120 |
| total/epochs | 12 |
| total/steps | 24000 |
| total/steps_per_second | 158 |
| train/loss_actor | 73.7 |
| train/loss_critic | 109 |
| train/param_noise_di | 0.302 |
| | |

| reference_Q_mean reference_Q_std reference_action_mean reference_action_std | 0.249 1.64 0.0199 -179 91.3 0.0835 0.939 |
|---|--|
| <pre> reference_actor_Q_mean reference_actor_Q_std </pre> | -171 92.8 |
| reference_perturbed | 0.877 |
| rollout/Q_mean | -81.1 |
| rollout/actions_mean | 0.0387 |
| rollout/actions_std | 0.64 |
| rollout/episode_steps | 200 |
| rollout/episodes rollout/return | 130 -830 |
| rollout/return_history | -630 -634 |
| total/duration | 164 |
| total/episodes | 130 |
| total/epochs | 13 |
| total/steps | 26000 |
| total/steps_per_second | 158 |
| train/loss_actor | 62.8 |
| train/loss_critic | 25.6 |
| | |
| train/param_noise_di | 0.265 |
| | 0.265 |
| train/param_noise_di | 0.25 |
| train/param_noise_di | 0.25 |
| train/param_noise_di | 0.25 1.6 0.018 |
| <pre> train/param_noise_di </pre> | 0.25 1.6 0.018 -163 |
| <pre> train/param_noise_di </pre> | 0.25 1.6 0.018 -163 82.7 |
| <pre> train/param_noise_di </pre> | 0.25 1.6 0.018 -163 82.7 0.0906 |
| train/param_noise_di obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 |
| train/param_noise_di obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std | 0.25 1.6 0.018 -163 82.7 0.0906 |
| train/param_noise_di obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 |
| train/param_noise_di obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 |
| train/param_noise_di obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 0.87 |
| train/param_noise_di obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std reference_actor_Q_std reference_sector_Q_std reference_sector_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 0.87 -75.1 |
| train/param_noise_di obs_rms_mean | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 0.87 -75.1 0.0282 0.628 200 |
| train/param_noise_di obs_rms_mean | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 0.87 -75.1 0.0282 0.628 200 140 |
| train/param_noise_di obs_rms_mean | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 0.87 -75.1 0.0282 0.628 200 140 -783 |
| train/param_noise_di obs_rms_mean | 0.25 1.6 0.018 -163 82.7 0.0906 0.937 -156 84.2 0.87 -75.1 0.0282 0.628 200 140 |

| total/episodes | 140 |
|------------------------|--------|
| total/epochs | 14 |
| total/steps | 28000 |
| total/steps_per_second | 158 |
| train/loss_actor | 52.9 |
| train/loss_critic | 41.9 |
| train/param_noise_di | 0.319 |
| | |
| | |
| | |
| obs_rms_mean | 0.253 |
| obs_rms_std | 1.57 |
| param_noise_stddev | 0.0163 |
| reference_Q_mean | -158 |
| reference_Q_std | 82.4 |
| reference_action_mean | 0.0745 |
| reference_action_std | 0.956 |
| reference_actor_Q_mean | -152 |
| reference_actor_Q_std | 84 |
| reference_perturbed | 0.907 |
| rollout/Q_mean | -69.9 |
| rollout/actions_mean | 0.025 |
| rollout/actions_std | 0.616 |
| rollout/episode_steps | 200 |
| rollout/episodes | 150 |
| rollout/return | -743 |
| rollout/return_history | -443 |
| total/duration | 190 |
| total/episodes | 150 |
| total/epochs | 15 |
| total/steps | 30000 |
| total/steps_per_second | 158 |
| train/loss_actor | 47.3 |
| train/loss_critic | 17.1 |
| train/param_noise_di | 0.206 |
| | |
| | |
| -h | |
| obs_rms_mean | 0.255 |
| obs_rms_std | 1.54 |
| param_noise_stddev | 0.016 |
| reference_Q_mean | -156 |
| reference_Q_std | 80.4 |
| reference_action_mean | -0.152 |
| reference_action_std | 0.957 |
| reference_actor_Q_mean | -149 |
| reference_actor_Q_std | 81 |
| reference_perturbed | 0.938 |

| <pre> rollout/Q_mean rollout/actions_mean rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | -65.2 |
|--|-------------------|
| obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/return rollout/return rollout/return total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic | 0.25 |
| obs_rms_mean obs_rms_std | 0.248 1.48 |

| | param_noise_stddev | 0.016 | |
|--|-----------------------------|-------|-----|
| | reference_Q_mean | -152 | - 1 |
| | reference_Q_std | 76.9 | - 1 |
| | reference_action_mean | 0.146 | - 1 |
| | reference_action_std | 0.958 | - 1 |
| | $reference_actor_Q_mean$ | -146 | - 1 |
| | $reference_actor_Q_std$ | 78.3 | - 1 |
| | reference_perturbed | 0.935 | - |
| | $rollout/Q_mean$ | -57.9 | - 1 |
| | rollout/actions_mean | 0.034 | - 1 |
| | rollout/actions_std | 0.591 | - |
| | rollout/episode_steps | 200 | - 1 |
| | rollout/episodes | 180 | - 1 |
| | rollout/return | -650 | - 1 |
| | rollout/return_history | -259 | - 1 |
| | total/duration | 228 | - 1 |
| | total/episodes | 180 | - 1 |
| | total/epochs | 18 | - 1 |
| | total/steps | 36000 | - 1 |
| | total/steps_per_second | 158 | - 1 |
| | train/loss_actor | 38.6 | - 1 |
| | train/loss_critic | 25.7 | - 1 |
| | train/param_noise_di | 0.172 | - 1 |
| | | | |

| obs_rms_mean | 0.245 | |
|------------------------|--------|--|
| obs_rms_std | 1.46 | |
| param_noise_stddev | 0.0148 | |
| reference_Q_mean | -150 | |
| reference_Q_std | 74.6 | |
| reference_action_mean | 0.215 | |
| reference_action_std | 0.94 | |
| reference_actor_Q_mean | -143 | |
| reference_actor_Q_std | 75.2 | |
| reference_perturbed | 0.912 | |
| rollout/Q_mean | -54.8 | |
| rollout/actions_mean | 0.0342 | |
| rollout/actions_std | 0.583 | |
| rollout/episode_steps | 200 | |
| rollout/episodes | 190 | |
| rollout/return | -625 | |
| rollout/return_history | -231 | |
| total/duration | 240 | |
| total/episodes | 190 | |
| total/epochs | 19 | |
| total/steps | 38000 | |
| total/steps_per_second | 158 | |
| | | |

| train/loss_actor | 36.7 |
|---|--------|
| train/loss_critic | 12.4 |
| train/param_noise_di | 0.158 |
| | |
| obs_rms_mean | 0.245 |
| obs_rms_std | 1.44 |
| param_noise_stddev | 0.0145 |
| reference_Q_mean | -152 |
| reference_Q_std | 74.7 |
| reference_action_mean | -0.162 |
| reference_action_std | 0.953 |
| reference_actor_Q_mean | -146 |
| reference_actor_Q_std | 75.4 |
| , = <u>-</u> , | 0.935 |
| rollout/Q_mean | -52.3 |
| rollout/actions_mean | 0.0386 |
| rollout/actions_std | 0.577 |
| rollout/episode_steps | 200 |
| rollout/episodes | 200 |
| rollout/return | -605 |
| rollout/return_history | -227 |
| total/duration | 253 |
| total/episodes | 200 |
| total/epochs | 20 |
| total/steps | 40000 |
| total/steps_per_second | 158 |
| train/loss_actor | 34.9 |
| train/loss_critic | 21.2 |
| train/param_noise_di | 0.333 |
| | |
| | 0.252 |
| obs_rms_std | 1.41 |
| param_noise_stddev | 0.0139 |
| reference_Q_mean | -150 |
| reference_Q_std | 74.4 |
| reference_action_mean | -0.133 |
| | 0.945 |
| | -143 |
| | 74.4 |
| | 0.897 |
| • | -49.1 |
| rollout/actions_mean | 0.0242 |
| rollout/actions_std | 0.571 |
| rollout/episode_steps | 200 |

| rollout/episodes | 210 |
|------------------------|---------|
| rollout/return | -582 |
| rollout/return_history | l -203 |
| total/duration | 266 |
| total/episodes | 210 |
| total/epochs | 21 |
| total/steps | 42000 |
| total/steps_per_second | 158 |
| train/loss_actor | 34.1 |
| train/loss_critic | 18.5 |
| train/param_noise_di | 0.245 |
| | |
| obs_rms_mean | 0.256 |
| obs_rms_std | 1.39 |
| param_noise_stddev | 0.0139 |
| reference_Q_mean | -149 |
| reference_Q_std | 74.3 |
| reference_action_mean | 0.184 |
| reference_action_std | 0.912 |
| reference_actor_Q_mean | -143 |
| reference_actor_Q_std | 75.3 |
| reference_perturbed | 0.909 |
| rollout/Q_mean | -46.1 |
| rollout/actions_mean | 0.00381 |
| rollout/actions_std | 0.571 |
| rollout/episode_steps | 200 |
| rollout/episodes | 220 |
| rollout/return | -562 |
| rollout/return_history | -180 |
| total/duration | 279 |
| total/episodes | 220 |
| total/epochs | 22 |
| total/steps | 44000 |
| total/steps_per_second | 158 |
| train/loss_actor | 28.4 |
| train/loss_critic | 50.8 |
| train/param_noise_di | 0.216 |

| obs_rms_mean | 0.263 | ı |
|-----------------------|--------|---|
| obs_rms_std | 1.38 | |
| param_noise_stddev | 0.0142 | |
| reference_Q_mean | -147 | |
| reference_Q_std | 72.5 | |
| reference_action_mean | 0.219 | |
| | | |

| | reference_action_std | | 0.911 | |
|--|------------------------|--|--------|-----|
| | reference_actor_Q_mean | | -141 | |
| | reference_actor_Q_std | | 73.3 | |
| | reference_perturbed | | 0.905 | |
| | rollout/Q_mean | | -43.6 | |
| | rollout/actions_mean | | -0.017 | |
| | rollout/actions_std | | 0.575 | |
| | rollout/episode_steps | | 200 | |
| | rollout/episodes | | 230 | |
| | rollout/return | | -547 | - |
| | rollout/return_history | | -179 | |
| | total/duration | | 291 | |
| | total/episodes | | 230 | |
| | total/epochs | | 23 | |
| | total/steps | | 46000 | |
| | total/steps_per_second | | 158 | |
| | train/loss_actor | | 21.3 | |
| | train/loss_critic | | 23.7 | |
| | train/param_noise_di | | 0.284 | - 1 |
| | train/loss_critic | | 23.7 | |

| obs_rms_mean | 0.27 |
|------------------------|---------|
| obs_rms_std | 1.36 |
| param_noise_stddev | 0.0154 |
| reference_Q_mean | -145 |
| reference_Q_std | 73.4 |
| reference_action_mean | 0.0563 |
| reference_action_std | 0.936 |
| reference_actor_Q_mean | -139 |
| reference_actor_Q_std | 74.6 |
| reference_perturbed | 0.874 |
| rollout/Q_mean | -40.9 |
| rollout/actions_mean | -0.0368 |
| rollout/actions_std | 0.58 |
| rollout/episode_steps | 200 |
| rollout/episodes | 240 |
| rollout/return | -532 |
| rollout/return_history | -179 |
| total/duration | 304 |
| total/episodes | 240 |
| total/epochs | 24 |
| total/steps | 48000 |
| total/steps_per_second | 158 |
| train/loss_actor | 16.8 |
| train/loss_critic | 48.2 |
| train/param_noise_di | 0.186 |
| | |

| obs_rms_mean | 0.276 |
|--|-----------------------------------|
| obs_rms_std | 1.35 |
| param_noise_stddev | 0.0163 |
| reference_Q_mean | -145 |
| reference_Q_std | 79.2 |
| reference_action_mean | -0.198 |
| reference_action_std | 0.924 |
| reference_actor_Q_mean | -139 |
| reference_actor_Q_std | 80.5 |
| reference_perturbed | 0.894 |
| rollout/Q_mean | -38.5 |
| rollout/actions_mean | -0.0553 |
| rollout/actions_std | 0.583 |
| rollout/episode_steps | 200 |
| rollout/episodes | 250 |
| rollout/return | -521 |
| rollout/return_history | -189 |
| total/duration | 317 |
| total/episodes | 250 |
| total/epochs | 25 |
| total/steps | 50000 |
| total/steps_per_second | 158 |
| train/loss_actor | 13 |
| train/loss_critic | 27.5 |
| train/param_noise_di | 0.0989 |
| ,, F | |
| | |
| | |
| obs_rms_mean | 0.278 |
| obs_rms_std | 1.34 |
| param_noise_stddev | 1.0 1 |
| reference_Q_mean | -142 |
| reference_Q_mean | 81.5 |
| | 0.172 |
| reference_action_mean | |
| reference_action_std | 0.928 136 |
| reference_actor_Q_mean | -136 |
| reference_actor_Q_std | 82 0.907 |
| reference_perturbed | |
| | |
| rollout/Q_mean | -36.6 |
| rollout/actions_mean | -36.6 -0.0685 |
| rollout/actions_mean rollout/actions_std | -36.6 -0.0685 0.585 |
| <pre> rollout/actions_mean rollout/actions_std rollout/episode_steps</pre> | -36.6 -0.0685 0.585 |
| <pre> rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes</pre> | -36.6 |
| <pre> rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return</pre> | -36.6 |
| <pre> rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history</pre> | -36.6 |
| <pre> rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history</pre> | -36.6 |

| total/episodes | 260 |
|------------------------|---------|
| total/epochs | 1 26 |
| total/steps | 52000 |
| total/steps_per_second | l 158 |
| train/loss_actor | 1 10.2 |
| train/loss_critic | 1 28.6 |
| train/param_noise_di | |
| , F | |
| | |
| | |
| obs_rms_mean | 0.285 |
| obs_rms_std | 1.33 |
| param_noise_stddev | 0.016 |
| reference_Q_mean | -138 |
| reference_Q_std | 80.9 |
| reference_action_mean | 0.119 |
| reference_action_std | 0.941 |
| reference_actor_Q_mean | -132 |
| reference_actor_Q_std | 81.2 |
| reference_perturbed | 0.906 |
| rollout/Q_mean | -34.4 |
| rollout/actions_mean | -0.0855 |
| rollout/actions_std | 0.588 |
| rollout/episode_steps | 200 |
| rollout/episodes | 270 |
| rollout/return | -505 |
| rollout/return_history | -215 |
| total/duration | 342 |
| total/episodes | 270 |
| total/epochs | 27 |
| total/steps | 54000 |
| total/steps_per_second | 158 |
| train/loss_actor | 4.83 |
| train/loss_critic | 31.8 |
| train/param_noise_di | 0.288 |
| | |
| | |
| | |
| obs_rms_mean | 0.29 |
| obs_rms_std | 1.32 |
| param_noise_stddev | 0.015 |
| reference_Q_mean | -134 |
| reference_Q_std | 79.9 |
| reference_action_mean | 0.126 |
| reference_action_std | 0.96 |
| reference_actor_Q_mean | -128 |
| reference_actor_Q_std | 80 |
| reference_perturbed | 0.928 |
| | |

| <pre> rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | -32.1 |
|---|------------------|
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/return rollout/return rollout/return total/duration total/episodes total/epochs total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | 0.293 |
| obs_rms_mean obs_rms_std | 0.298 1.3 |

| F | param_noise_stddev | 0.0139 | |
|---|------------------------|--------|---|
| r | reference_Q_mean | -126 | |
| r | reference_Q_std | 74.8 | |
| r | reference_action_mean | -0.147 | |
| r | reference_action_std | 0.95 | |
| r | reference_actor_Q_mean | -120 | |
| r | reference_actor_Q_std | 74.9 | |
| r | reference_perturbed | 0.933 | |
| r | collout/Q_mean | -27.7 | |
| r | collout/actions_mean | -0.135 | |
| r | collout/actions_std | 0.593 | |
| r | collout/episode_steps | 200 | |
| r | collout/episodes | 300 | |
| r | collout/return | -476 | |
| r | collout/return_history | -217 | |
| t | otal/duration | 380 | |
| t | otal/episodes | 300 | |
| t | otal/epochs | 30 | |
| t | otal/steps | 60000 | |
| t | otal/steps_per_second | 158 | |
| t | rain/loss_actor | -5.55 | |
| t | rain/loss_critic | 24.3 | |
| t | rain/param_noise_di | 0.274 | |
| | | | _ |

| _ | | | _ |
|---|------------------------|--------|---|
| | obs_rms_mean | 0.302 | |
| - | obs_rms_std | 1.29 | |
| - | param_noise_stddev | 0.0142 | |
| - | reference_Q_mean | -126 | |
| - | reference_Q_std | 77.2 | |
| - | reference_action_mean | 0.11 | |
| | reference_action_std | 0.953 | |
| - | reference_actor_Q_mean | -119 | |
| - | reference_actor_Q_std | 77.3 | |
| | reference_perturbed | 0.943 | |
| - | rollout/Q_mean | -25.7 | |
| - | rollout/actions_mean | -0.151 | |
| | rollout/actions_std | 0.594 | |
| | rollout/episode_steps | 200 | |
| | rollout/episodes | 310 | |
| | rollout/return | -466 | |
| | rollout/return_history | -222 | |
| | total/duration | 393 | |
| | total/episodes | 310 | |
| - | total/epochs | 31 | |
| | total/steps | 62000 | |
| - | total/steps_per_second | 158 | |

| train/loss_actor | |
|--------------------------------|-------|
| train/param_noise_di 0.181 | i |
| train/param_noise_dr train/ | _ ' |
| | |
| | |
| obs_rms_mean | I |
| obs_rms_std | i |
| param_noise_stddev 0.0131 | i |
| reference_Q_mean -125 | i |
| reference_Q_std 77.5 | i |
| reference_action_mean 0.207 | i |
| reference_action_std 0.922 | i |
| reference_actor_Q_mean -119 | i |
| reference_actor_Q_std 78.1 | i |
| reference_perturbed 0.877 | i |
| rollout/Q_mean -23.7 | i |
| rollout/actions_mean -0.164 | i |
| rollout/actions_std 0.594 | i |
| rollout/episode_steps 200 | i |
| rollout/episodes 320 | İ |
| rollout/return -456 | Ì |
| rollout/return_history -224 | - 1 |
| total/duration 406 | |
| total/episodes 320 | - |
| total/epochs 32 | 1 |
| total/steps | 1 |
| total/steps_per_second 158 | - 1 |
| train/loss_actor -13.3 | |
| train/loss_critic 22.3 | |
| train/param_noise_di 0.22 | - 1 |
| | |
| | |
| | |
| obs_rms_mean | - 1 |
| obs_rms_std | |
| param_noise_stddev 0.0142 | - |
| reference_Q_mean | - 1 |
| reference_Q_std 77.4 | |
| reference_action_mean -0.121 | |
| reference_action_std 0.95 | |
| reference_actor_Q_mean -116 | |
| reference_actor_Q_std 77.5 | |
| reference_perturbed 0.911 | |
| rollout/Q_mean -21.7 | |
| rollout/actions_mean -0.176 | |
| rollout/actions_std 0.592 | |
| rollout/episode_steps 200 | |

| rollout/episodes | 330 |
|------------------------|--------|
| rollout/return | -447 |
| rollout/return_history | -216 |
| total/duration | 419 |
| total/episodes | 330 |
| total/epochs | 33 |
| total/steps | 66000 |
| total/steps_per_second | 158 |
| train/loss_actor | -11.8 |
| train/loss_critic | 46.4 |
| train/param_noise_di | 0.468 |
| | |
| obs_rms_mean | 0.306 |
| obs_rms_std | 1.25 |
| param_noise_stddev | 0.0145 |
| reference_Q_mean | -124 |
| reference_Q_std | 78.3 |
| reference_action_mean | -0.141 |
| reference_action_std | 0.956 |
| reference_actor_Q_mean | -119 |
| reference_actor_Q_std | 78 |
| reference_perturbed | 0.877 |
| rollout/Q_mean | -19.8 |
| rollout/actions_mean | -0.189 |
| rollout/actions_std | 0.59 |
| rollout/episode_steps | 200 |
| rollout/episodes | 340 |
| rollout/return | -438 |
| rollout/return_history | -213 |
| total/duration | 432 |
| total/episodes | 340 |
| total/epochs | 34 |
| total/steps | 68000 |
| total/steps_per_second | 158 |
| train/loss_actor | -10.3 |
| | 17.3 |
| train/loss_critic | • |

| obs_rms_mean | 0.306 | |
|-----------------------|----------|-----|
| obs_rms_std | 1.24 | |
| param_noise_stddev | 0.0142 | - |
| reference_Q_mean | -120 | |
| reference_Q_std | 73.1 | |
| reference action mean | l -0.121 | - 1 |

| - | reference_action_std | 0.946 | I | |
|---|------------------------|-------|-----|--|
| | reference_actor_Q_mean | -114 | | |
| | reference_actor_Q_std | 72.2 | | |
| | reference_perturbed | 0.911 | | |
| | rollout/Q_mean | -18.3 | - 1 | |
| | rollout/actions_mean | -0.2 | | |
| | rollout/actions_std | 0.591 | | |
| | rollout/episode_steps | 200 | | |
| | rollout/episodes | 350 | | |
| | rollout/return | -431 | | |
| | rollout/return_history | -205 | | |
| | total/duration | 444 | - 1 | |
| | total/episodes | 350 | | |
| | total/epochs | 35 | | |
| | total/steps | 70000 | | |
| | total/steps_per_second | 158 | | |
| | train/loss_actor | -10 | | |
| | train/loss_critic | 28 | - 1 | |
| | train/param_noise_di | 0.216 | | |
| | | | | |

| obs_rms_mean | 0.31 |
|------------------------|--------|
| obs_rms_std | 1.23 |
| param_noise_stddev | 0.0139 |
| reference_Q_mean | -124 |
| reference_Q_std | 74 |
| reference_action_mean | -0.113 |
| reference_action_std | 0.951 |
| reference_actor_Q_mean | -118 |
| reference_actor_Q_std | 73.5 |
| reference_perturbed | 0.852 |
| rollout/Q_mean | -16.8 |
| rollout/actions_mean | -0.209 |
| rollout/actions_std | 0.589 |
| rollout/episode_steps | 200 |
| rollout/episodes | 360 |
| rollout/return | -424 |
| rollout/return_history | -189 |
| total/duration | 457 |
| total/episodes | 360 |
| total/epochs | 36 |
| total/steps | 72000 |
| total/steps_per_second | 157 |
| train/loss_actor | -13 |
| train/loss_critic | 22.8 |
| train/param_noise_di | 0.175 |
| | |

| obs_rms_mean | 0.311 |
|--|---|
| obs_rms_std | 1.22 |
| param_noise_stddev | 0.0136 |
| reference_Q_mean | -126 |
| reference_Q_std | 74.2 |
| reference_action_mean | -0.118 |
| reference_action_std | 0.948 |
| reference_actor_Q_mean | -120 |
| | 73.6 |
| | 0.847 |
| rollout/Q_mean | -15.2 |
| rollout/actions_mean | -0.219 |
| rollout/actions_std | 0.587 |
| rollout/episode_steps | 200 |
| rollout/episodes | 370 |
| rollout/return | -416 |
| | -410 -174 |
| rollout/return_history | |
| total/duration | 470 |
| total/episodes | 370 |
| total/epochs | 37 |
| total/steps | 74000 |
| . 1 -1 - | 157 |
| train/loss_actor | -12.4 |
| train/loss_critic | 16.7 |
| | |
| train/param_noise_di | 0.238 |
| | 0.311 |
| | |
| obs_rms_mean | 0.311 |
| obs_rms_mean | 0.311 1.21 |
| obs_rms_mean obs_rms_std param_noise_stddev | 0.311 1.21 0.0123 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean | 0.311 1.21 0.0123 -125 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean | 0.311 1.21 0.0123 -125 75 -0.0533 0.956 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std reference_perturbed rollout/Q_mean | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_actor_Std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return | 0.311 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/return rollout/return_history | 0.311 |

| <pre> total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | 380 |
|---|--|
| obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean | 0.311 |
| : | 0.313 1.2 0.0134 -126 76.5 -0.0707 0.928 -120 75.7 |

| <pre> rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | -11.5 |
|--|-------|
| obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/return rollout/return rollout/return total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic | 0.316 |
| obs_rms_mean obs_rms_std | 0.316 |

| | param_noise_stddev | 0.015 | |
|--|------------------------|--------|---|
| | reference_Q_mean | -125 | |
| | reference_Q_std | 74.7 | |
| | reference_action_mean | -0.106 | |
| | reference_action_std | 0.936 | |
| | reference_actor_Q_mean | -119 | |
| | reference_actor_Q_std | 74.5 | |
| | reference_perturbed | 0.921 | |
| | rollout/Q_mean | -9.21 | |
| | rollout/actions_mean | -0.252 | |
| | rollout/actions_std | 0.581 | |
| | rollout/episode_steps | 200 | |
| | rollout/episodes | 420 | |
| | rollout/return | -389 | |
| | rollout/return_history | -173 | |
| | total/duration | 534 | |
| | total/episodes | 420 | |
| | total/epochs | 42 | |
| | total/steps | 84000 | |
| | total/steps_per_second | 157 | |
| | train/loss_actor | -16.8 | |
| | train/loss_critic | 20.7 | |
| | train/param_noise_di | 0.264 | |
| | | | _ |

| _ | | | |
|---|------------------------|--------|---|
| | obs_rms_mean | 0.319 | 1 |
| | obs_rms_std | 1.17 | |
| | param_noise_stddev | 0.0157 | - |
| | reference_Q_mean | -126 | |
| | reference_Q_std | 75.7 | |
| | reference_action_mean | -0.362 | - |
| | reference_action_std | 0.872 | |
| | reference_actor_Q_mean | -120 | - |
| | reference_actor_Q_std | 75.9 | - |
| | reference_perturbed | 0.858 | - |
| | rollout/Q_mean | -8.03 | |
| | rollout/actions_mean | -0.258 | |
| - | rollout/actions_std | 0.577 | - |
| | rollout/episode_steps | 200 | |
| | rollout/episodes | 430 | |
| | rollout/return | -382 | |
| | rollout/return_history | -169 | |
| | total/duration | 547 | |
| | total/episodes | 430 | |
| | total/epochs | 43 | |
| - | total/steps | 86000 | |
| - | total/steps_per_second | 157 | 1 |

| <pre> train/loss_actor train/loss_critic train/param_noise_di</pre> | -15.1 |
|---|-------|
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/return | 0.322 |
| <pre> rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | -377 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps | 0.321 |

| <pre> rollout/episodes rollout/return rollout/return_history total/duration total/episodes total/epochs total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di</pre> | 450 |
|---|-------|
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean reference_action_std reference_actor_Q_mean reference_actor_Q_mean reference_actor_Q_std reference_perturbed rollout/Q_mean rollout/actions_mean rollout/actions_std rollout/episode_steps rollout/episodes rollout/return rollout/return rollout/return total/duration total/episodes total/epochs total/steps total/steps total/steps total/steps_per_second train/loss_actor train/loss_critic train/param_noise_di | 0.32 |
| obs_rms_mean obs_rms_std param_noise_stddev reference_Q_mean reference_Q_std reference_action_mean | 0.321 |

| - | reference_action_std | 0.918 | - |
|---|------------------------|--------|---|
| - | reference_actor_Q_mean | -121 | |
| | reference_actor_Q_std | 74.4 | |
| | reference_perturbed | 0.888 | |
| | rollout/Q_mean | -4.41 | |
| | rollout/actions_mean | -0.275 | |
| | rollout/actions_std | 0.567 | |
| | rollout/episode_steps | 200 | |
| | rollout/episodes | 470 | |
| | rollout/return | -363 | |
| | rollout/return_history | -169 | |
| | total/duration | 598 | |
| | total/episodes | 470 | |
| | total/epochs | 47 | |
| | total/steps | 94000 | |
| | total/steps_per_second | 157 | |
| | train/loss_actor | -16.3 | |
| | train/loss_critic | 11.4 | |
| | train/param_noise_di | 0.44 | |
| | | | |

| obs_rms_mean | 0.322 |
|------------------------|--------|
| obs_rms_std | 1.14 |
| param_noise_stddev | 0.0157 |
| reference_Q_mean | -129 |
| reference_Q_std | 75.3 |
| reference_action_mean | 0.0138 |
| reference_action_std | 0.927 |
| reference_actor_Q_mean | -123 |
| reference_actor_Q_std | 74.9 |
| reference_perturbed | 0.873 |
| rollout/Q_mean | -3.64 |
| rollout/actions_mean | -0.278 |
| rollout/actions_std | 0.565 |
| rollout/episode_steps | 200 |
| rollout/episodes | 480 |
| rollout/return | -359 |
| rollout/return_history | -163 |
| total/duration | 610 |
| total/episodes | 480 |
| total/epochs | 48 |
| total/steps | 96000 |
| total/steps_per_second | 157 |
| train/loss_actor | -16.1 |
| train/loss_critic | 11.6 |
| train/param_noise_di | 0.173 |
| | |

| obs_rms_mean | 0.323 |
|------------------------|---------|
| obs_rms_std | 1.13 |
| param_noise_stddev | 0.016 |
| reference_Q_mean | -128 |
| reference_Q_std | 75 |
| reference_action_mean | 0.408 |
| reference_action_std | 0.863 |
| reference_actor_Q_mean | -123 |
| reference_actor_Q_std | 75.2 |
| reference_perturbed | 0.88 |
| rollout/Q_mean | -2.88 |
| rollout/actions_mean | -0.28 |
| rollout/actions_std | 0.563 |
| rollout/episode_steps | 200 |
| rollout/episodes | 490 |
| rollout/return | -355 |
| rollout/return_history | -160 |
| total/duration | 623 |
| total/episodes | 490 |
| total/epochs | 49 |
| total/steps | 98000 |
| total/steps_per_second | 157 |
| train/loss_actor | -15.4 |
| train/loss_critic | 15 |
| train/param_noise_di | 0.103 |
| | |
| | |
| | |
| obs_rms_mean | 0.322 |
| obs_rms_std | 1.13 |
| param_noise_stddev | 0.0157 |
| reference_Q_mean | -123 |
| reference_Q_std | 68.9 |
| reference_action_mean | -0.0272 |
| reference_action_std | 0.941 |
| reference_actor_Q_mean | -117 |
| reference_actor_Q_std | 69.5 |
| reference_perturbed | 0.95 |
| rollout/Q_mean | -2.17 |
| rollout/actions_mean | -0.283 |
| rollout/actions_std | 0.561 |
| rollout/episode_steps | 200 |
| 1 77 . / . 1 | I F00 I |

| rollout/episodes

| rollout/return_history | -159

| rollout/return

| total/duration

| 500

| -351

| 636

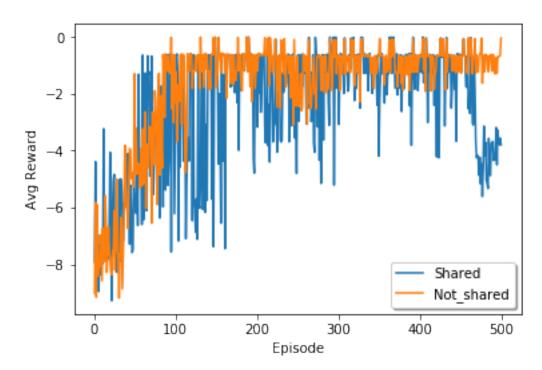
| | total/episodes | 1 | 500 | - |
|---|------------------------|---|--------|---|
| | total/epochs | 1 | 50 | - |
| | total/steps | - | 100000 | |
| | total/steps_per_second | 1 | 157 | - |
| | train/loss_actor | - | -13.7 | |
| | train/loss_critic | - | 40.9 | |
| | train/param_noise_di | - | 0.617 | |
| _ | | | | |

[-9.0083088729298666, -5.8098595500575776, -9.1528298098407159, -5.8953800171774011, -8.40900707 total runtime: 639.1219322681427s

In [3]: %matplotlib inline

```
In [4]: import matplotlib.pyplot as plt
    x = np.linspace(1,500,500)
    fig, ax = plt.subplots()
    ax.plot(x, r_history[0,:], label = "Shared")
    ax.plot(x, r_history[1,:], label = "Not_shared")

legend = ax.legend(loc='lower right', shadow=True)
    plt.xlabel("Episode")
    plt.ylabel("Avg Reward")
    plt.show()
```



From the graph above, we can see that the NN which has shared weights has a relatively faster convergence rate. However, variance of average rewards is larger when sharing weights between actor and critic network. This is because when sharing weights between critic and actor, the actor's network gets updates directly associated with rewards. This associate will accelerate training if the sample is a good move. However, as samples cannot always be good move, it will harm the learning process and increase the variance. Another posible cause is everytime the function calls agent.train() function, it updates the network parameters using actor_optimizer and critic_optimizer. These two will both update the first layer variables, meaning that the variables will be updated twice. This can cause faster learning, but will lead to higher variance and unstable performance.