

Xiongming Dai

Ph.D. Candidate

Division of Computer Science and Engineering

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Research and Hobbies

I am a Ph.D. candidate at Louisiana State University . Currently, my main work is in State Estimation for Sequential Data Analysis. I have been actively involved in various inter-disciplinary researches. My research interest includes Bayesian Learning, Monte Carlo Sampling, Tracking, Simultaneous Localization and Mapping (SLAM), Robotics, Anomaly Detection (Deep One-Class Learning), Evolutionary Algorithm, Graph Theory and Riesz Potentials. I am crazy about Mathematics, Cooking, Drawing and Playing Basketball & Badminton. I am a person, who is always unstoppable and persevering in learning to meet new challenges. Consistency matters in performance!

I am looking for a job now! If you have openings related to Machine Learning, Computer Vision, Robotics, and Autonomous Driving (Visual SLAM), please feel free to recommend, thank you very much!

Experience

Graduate Research & Teaching Assistant Louisiana State University May 2018 - Present

- Responsible for theoretical research of resampling for sequential Monte Carlo, and have proposed a repetitive ergodicity in deterministic domain with median, it is faster than the state of the art, which is verified by theoretical deduction and experiments of a hidden Markov model in both the linear and non-linear cases.
- Responsible for theoretical research of optimal camera configuration for large-scale motion capture systems, a NP hard problem, and have developed a 3D simulation framework, further introduce Riesz potentials to discretize rectifiable submanifolds of the maximum overlapping coverage, it proves that the proposal grows at most logarithmically, under mild assumptions.
- Responsible for theoretical research of Monte Carlo Sampling, and have proposed a weighted Riesz potentials interaction, where only few samplers required to achieve high performance for hidden Markov model.

Director Shenzhen Realis Multimedia Technology Co.,Ltd. Jul 2016 - Aug 2017

- Responsible for the location and tracking of infrared reflective markers corresponding to rigid bodies to realize multiplayer motion capture.
- Responsible for the optimization of optimal camera configuration solutions.
- Responsible for the optimization of the inverse kinematics and the integration of the system.

- Project Leader Shenzhen Realis Multimedia Technology Co.,Ltd. Feb 2016 - Jun 2016
- Served as a leader for developing inverse kinematics software from scratch.
 - Responsible for the configuration and optimization of the infrared reflective markers solution so that the corresponding rigid body is most easily captured by the camera system.
 - Responsible for the interactive communication mechanism between cameras to ensure minimum latency of the camera system.
- Senior Software Development Engineer Hunan VisualTouring Technology Co.,Ltd. Jun 2015 - Jan 2016
- Responsible for service robot multitasking development based on robotic systems ROS.
 - Responsible for theoretical research of Visual SLAM and related software development.
 - Responsible for 3D reconstruction of interior scenes.
 - Responsible for 3D face recognition based on 3-dimensional projection volume invariance feature.
- Graduate Research Assistant Huazhong University of Science & Technology Aug 2012 - May 2015
- Software Development Engineer Huazhong Numerical Control Co.,Ltd. Aug 2012 - May 2015
- Responsible for calibration research and software development of industrial robot systems.
 - Responsible for the algorithm research and software development of CNC toolpaths in order to obtain smooth machining results.

Education

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|---|--------------------------|-------------------------------|
| Louisiana State University | Computer Science | Ph.D., (Nov, 2022 (Expected)) |
| Louisiana State University | Computer Science | M.Sc., 2022 |
| Huazhong University of Science & Technology | Mechatronics Engineering | M.Sc., 2015 |
| Changsha University of Science & Technology | Mechanical Engineering | M.Sc., 2012 |

Publications

- **Xiongming Dai**, Gerald Baumgartner. **Weighted Riesz Particles**. Neural Information Processing Systems(NeurIPS), 2022 submitted
- **Xiongming Dai**, Gerald Baumgartner. **Optimal Camera Configuration for Large-Scale Motion Capture Systems**. Neural Information Processing Systems(NeurIPS), 2022 submitted
- **Xiongming Dai**, Gerald Baumgartner, **Variance Reduction of Resampling for Sequential Monte Carlo**. Association for the Advancement of Artificial Intelligence(AAAI), 2022 submitted

Awards

- Three software copyright
- Two inventive patents
- 2nd place in the 3rd Changsha University of Technology Cooking Competition
- 2009-2010 School of Mechanical Engineering at Changsha University of Sci&Tech 1 on 1 Basketball competition champion, called “The King of 1 on 1”.
- The team got the 3rd place in the 15th HUST Graduate Cup Soccer League, Forward
- The team got the 2nd place in the 25th HUST Graduate Cup Basketball League, Small Forward

Technical Strengths

- **Languages Proficient:** Python, R, Matlab, C/C++, Shell.
- **Robotic System:** ROS operating system
- **GPU Programming:** NVIDIA CUDA
- **Computer Vision/Graphics:** OpenGL, OpenCV.
- **SDLC/Documentation:** LaTeX, Overleaf
- **Platforms/ Frameworks:** Windows, UNIX/Linux •
- **Others:** Git
- **The Most Important:** non-stopable and perseverance in learning