Combinatorics - Reviewed Notes

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1 Counting Techniques

Theorem 1.1 - Bijection Rule

A set X has $n \in \mathbb{N}$ elements iff \exists a bijection $f: X \to [n]$.

Theorem 1.2 - Addition Rule

Let A_1, \ldots, A_n be finite pairwise disjoint sets. Then

$$\left| \bigcup_{i=1}^{n} A_i \right| = \sum_{i=1}^{n} |A_i|$$

Theorem 1.3 - Multiplication Rule

If a counting problem can be split into n independent stages, each of which involves choosing an option out of a set A_i . Then the total number of possible outcomes is

Possible Outcomes =
$$\prod_{i=1}^{n} |A_i|$$

Theorem 1.4 - Inclusion-Exclusion Principle

Let A_1, \ldots, A_n be finite sets. Then

$$\left| \bigcup_{i=1}^{n} A_i \right| = \sum_{i=1}^{n} |A_i| - \sum_{i_1 < i_2} |A_{i_1} \cap A_{i_2}| + \sum_{i_1 < i_2 < i_3} |A_{i_1} \cap A_{i_2} \cap A_{i_3}| - \dots + (-1)^{n+1} |A_1 \cap \dots \cap A_n|$$

Theorem 1.5 - Binomial Coefficient Identities

$$\binom{n}{k} = \binom{n}{n-k}, \qquad \binom{n}{0} = 1 = \binom{n}{n}$$

$$\binom{n}{k} = 0 \ \forall \ k > n, \quad \binom{n}{k} = \frac{(n)_k}{k!} = \frac{n!}{k!(n-k)!}$$

Definition 1.1 - Ordered Selection

In an Ordered Selection problem we are selecting k elements from a set of n, and care about the order in which we pick them, so $\{x_1, x_2\} \not\equiv \{x_2, x_1\}$.

Definition 1.2 - Unordered Selection

In an *Unordered Selection* problem we are selecting k elements from a set of n, and do not care about the order we pick them so $\{x_1, x_2\} \equiv \{x_2, x_1\}$.

Proposition 1.1 - Number of Possible Selections

The table below summarises the number of possible ways to choose k elements from a set of n, for each scenario of selection problems.

	Ordered Selection	Unordered Selection
With Repetition	n^k	$\binom{n+k-1}{k}$
Without Repetition	$\frac{n!}{(n-k)!}$	$\binom{n}{k}$

Theorem 1.6 - Pascal's Identity

$$\binom{n}{i} = \binom{n-1}{i} + \binom{n-1}{i-1} \; \forall \; i \in \mathbb{N}^{\leq n}$$

Theorem 1.7 - Binomial Theorem

$$(a+b)^n = \sum_{i=0}^n \binom{n}{i} a^i b^{n-i} \ \forall \ a, b \in \mathbb{R} \ n \in \mathbb{N}$$

Theorem 1.8 - Sum of Binomial Coefficients

$$\sum_{i=0}^{n} \binom{n}{i} = 2^n$$

Theorem 1.9 - Identity

$$(j+1)\binom{n}{j+1} = n\binom{n-1}{j}$$

Theorem 1.10 - Pigeonhole Principle

If there are more pigeons than pigeonholes, then at least 2 pigeons must occupy the same hole.

Theorem 1.11 - Generalised Pigeonhole Principle

If m objects are distributed into n boxes and m > nk for $k \in \mathbb{N}$, then at least one box contains at least k+1 objects.

2 Generating Functions

Definition 2.1 - Generating Functions

Given a sequence $(a_n)_{n\geq 0}$ with $a_i \in \mathbb{R}$ we associate the power series $f(x) = \sum_{i=0}^{\infty} a_n x^n$. f(x) is the Generating Function of the sequence $(a_n)_{n\geq 0}$.

Theorem 2.1 - Scaling Rule

If
$$f(x) \leftrightarrows (a_0, a_1, a_2, \dots) \implies cf(x) \leftrightarrows (ca_0, ca_1, ca_2, \dots)$$

Theorem 2.2 - Addition Rule

If
$$f(x) \leftrightarrows (a_0, a_1, a_2, \dots) \& g(x) \leftrightarrows (b_0, b_1, b_2, \dots) \implies f(x) + g(x) \leftrightarrows (a_0 + b_0, a_1 + b_1, \dots)$$

Theorem 2.3 - Right Shift Rule

If
$$f(x) \leftrightarrows (a_0, a_1, a_2, \dots) \implies x^k f(x) \leftrightarrows \underbrace{(0, \dots, 0,}_{k \text{ times}}, a_0, a_1, a_2, \dots)$$

Theorem 2.4 - Differentiation Rule

If
$$f(x) = \sum_{i=0}^{\infty} a_i x^i \leftrightarrows (a_0, a_1, a_2, \dots) \implies f'(x) = \sum_{i=0}^{\infty} i a_{i+1} x^i \leftrightarrows (a_1, 2a_2, 3a_3, \dots)$$

Theorem 2.5 - Convolution Rule

If
$$f(x) \leftrightarrows (a_0, a_1, a_2, \dots) \& g(x) \leftrightarrows (b_0, b_1, b_2, \dots) \implies f(x) \cdot g(x) \leftrightarrows (c_0, c_1, c_2, \dots)$$
 where $c_i := \sum_{j=0}^{i} a_j b_{i-j}$

Definition 2.2 - Recurrence Relation

A sequence, $(a_n)_{n\geq 0}$ is a *Recurrence Relation* if, for large enough n, a_n is defined in terms of its previous terms. Generating functions can be used to express $(a_n)_{n\geq 0}$ in terms of n.

Theorem 2.6 - Generating Function Identities

$$\frac{1}{1-x} \iff (1,1,1,\dots)$$
$$(1+x)^n \iff \left(\binom{n}{k}\right)_{k\geq 0}$$
$$(1+x)^{-n} \iff \sum_{i=0}^{\infty} (-1)^k \binom{n+k-1}{k} x^k$$

Theorem 2.7 - Sum Identities

$$\left(\sum_{i=0}^{\infty} x^i\right)^n = \sum_{i=0}^{\infty} \binom{n+k-1}{k} x^k$$

$$\frac{1}{(1-x)^n} = \sum_{i=0}^{\infty} \binom{n+k-1}{k} x^k$$

3 Combinatorial Design

Definition 3.1 - Set System

 (V, \mathcal{B}) is a *Set System* where V is a finite set & \mathcal{B} is a set of subsets, which are not necessarily disjoint), of V. V is called the *Ground Set* & \mathcal{B} is called *Blocks*.

Definition 3.2 - k-Uniform

A Set System, (V, \mathcal{B}) , is k-uniform iff $\forall B \in \mathcal{B}, |B| = k$.

Definition 3.3 - Block Design

Let $v, k, t, \lambda \in \mathbb{N}$ with $v > k \ge k \ge t \ge 1$.

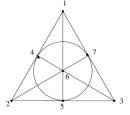
A Block Design of type $t - (v, k, \lambda)$ is a set system (V, \mathcal{B}) with

- |V| = v;
- $\forall B \in \mathcal{B}, |B| = k$; and,
- $\forall T \subseteq V \text{ with } |T| = t \exists \lambda \text{ blocks, } B \in \mathcal{B}, \text{ with } T \subseteq B.$

Definition 3.4 - Fano Plane

The Fano Plane is a set-system with $V = \{1, 2, 3, 4, 5, 6, 7\}$

& $\mathcal{B} = \{\{1,2,3\},\{1,4,7\},\{3,6,7\},\{1,5,6\},\{3,4,5\},\{2,5,7\},\{2,4,6\}\}\}$. This is a *Block Design* of type 2 - (7,3,1).



N.B. - This is the smallest example of a Finite Projective Plane.

Definition 3.5 - Replication Number

The Replication Number is the number of blocks each element appears in in a Block Design.

Theorem 3.1 - Number of Blocks in Block Design

The number of blocks in a block design of type $t - (v, k, \lambda)$ is found by the following formula

$$b := \frac{\lambda \binom{v}{t}}{\binom{k}{t}}$$

Theorem 3.2 - Replication Number

In a block design of type $2 - (v, k, \lambda)$ every element lies in r blocks where

$$r := \frac{(k-1)}{\lambda(v-1)} = \frac{bk}{v}$$

Theorem 3.3 - Fisher's Inequality

Let (V, \mathcal{B}) be a block design of type $2 - (v, k, \lambda)$ with v > k. Then

$$|\mathcal{B}| \ge |V|$$

Definition 3.6 - *Incidence Matrix*

The Incidence Matrix of a Set System (V, \mathcal{B}) is a $|V| \times |\mathcal{B}|$ matrix where

$$a_{i,j} = \begin{cases} 1 & \text{if } v_i \in B_j \\ 0 & \text{otherwise} \end{cases}$$

4 Graph Theory

4.1 Introduction

Definition 4.1 - *Graph*

A Graph, G, is an ordered pair (V, E) where V is a set of vertices & E is a set of edges between these vertices. Edges are represented by a 2-element subset of V.

Definition 4.2 - Sub-Graph

Consider a graph G = (V, E). G' = (V', E') is a Sub-Graph of G if

$$V' \subseteq V \& E' = \{\{u, v\} \in E : u, v \in V'\}$$

Definition 4.3 - *Induced Sub-Graph*

A Sub-Graph G' = (V', E') of G = (V, E) is an Induced Sub-Graph if E' contains all the edges in E that run between vertices in V'.

Definition 4.4 - Order of a Graph

The Order of a Graph G = (V, E) is the number of vertices, |V|.

Definition 4.5 - Simple Graph

A Simple Graph is an unweighted, undirected with no edges which start & end on the same vertex, nor duplicate edges.

Proposition 4.1 - Graphs are 2-Uniform Set Systems

Definition 4.6 - Adjacency

For a graph G = (V, E), $u, v \in V$ are Adjacent if $\{u, v\} \in E$.

Definition 4.7 - Neighbourhood

Consider a graph G = (V, E) & $v \in V$. The Neighbourhood of v in G is the vertices adjacent to v in G.

$$N_G(v) := \{ u : u \in V \& \{u, v\} \in E \}$$

Definition 4.8 - Neighbourhood of a Set of Vertices

Let G = (V, E) be a graph, then for $S \subseteq V$

$$N_G(S) := \bigcup_{s \in S} N_G(s)$$

Definition 4.9 - Degree

Consider a graph G = (V, E) & $v \in V$. The Degree of v is the size of its Neighbourhood of v.

$$deg_G(v) := |N_G(v)|$$

Theorem 4.1 - Handshaking Lemma

Consider a graph G = (V, E). Then

$$|E| = \frac{1}{2} \sum_{v \in V} deg_G(v)$$

Theorem 4.2 - Maximum Number of Edges

A graph has at most $\binom{n}{2} = \frac{1}{2}n(n-1)$ edges.

Definition 4.10 - Graph Isomorphism

Two graphs $G_1 = (V_1, E_1) \& G_2 = (V_2, E_2)$ are Isomorphic if \exists a bijection $\phi: V_1 \to V_2$ st

$$\forall \{u, v\} \in E_1 \implies \{\phi(u), \phi(v)\} \in E_2$$

Definition 4.11 - Degree Sequence

Consider a graph G = (V, E). Order the vertices $\{v_1, \ldots, v_n\}$ with $deg(v_i) \leq deg(v_j) \ \forall \ i < j$. The Degree Sequence of G is

$$(deg(v_1),\ldots,deg(v_n))$$

Theorem 4.3 - Isomorphic Graphs

If two graphs are isomorphic then the following properties hold

- i) They have the same number of edges;
- ii) They have the same Degree Sequence.

4.2 Types of Graph

Definition 4.12 - Walk

Consider a graph G = (V, E) and $u, v \in V$. A Walk from u to v is a sequence of not-necessarily-distinct vertices $V_c = (u = x_1, x_2, \dots, x_n = v)$ with $E_c = \{\{x_i, x_{i+1}\} : i \in [1, n-1]\} \subseteq E$. Neither the edges, nor vertices, are necessarily unique.

Definition 4.13 - Circuit

A Circuit is a closed Walk.

N.B. - A Circuit is generally not a graph since they often have repeated edges.

Definition 4.14 - Trail

A Trail is a Walk with no repeated edges. It can still have repeated vertices.

Definition 4.15 - Path

A Path of length n has vertex set $V_P = \{v_1, \dots, v_n : v_i \neq v_j \ \forall i \neq j\}$ & edge set $E_p = \{\{v_i, v_{i+1}\} : i \in [1, n-1]\} \subseteq E$. All vertices, and thus edges, in a path are distinct.

Definition 4.16 - Connected

Two vertices are *Connected* if there exists a path between them.

A Graph is Connected if there exists a path between all pairs of vertices in it.

Definition 4.17 - Disconnected

A Graph G = (V, E) is Disconnected if there $\exists u, v \in V \text{ st } \nexists$ a path in G between u & v. The Maximally Connected Sub-Graphs of G are called Components of G.

Definition 4.18 - Cycle

A Cycle of length n has vertex set $V_c = \{v_1, \dots, v_n : v_i \neq v_j \ \forall \ i \neq j\}$ & edge set $E_c = \{v_n, v_1\} \cup \{\{v_i, v_j\} : i \in [1, n-1]\}\}$. This is a path that starts and ends on the same vertex.

Theorem 4.4 - If a graph admits an odd circuit, then it admits an odd cycle

Definition 4.19 - Tree

A Tree is a Graph with no cycles.

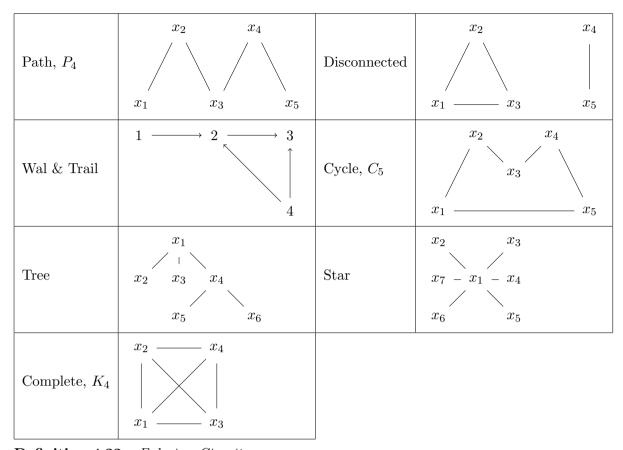
Definition 4.20 - Star

A Star is a Graph G = (V, E) with $V = \{v_1, \dots, v_n\} \& E = \{\{v_1, v_i\} : i \in [2, n]\}.$

Definition 4.21 - Complete Graph

A Complete Graph is a Graph G = (V, E) with $V = \{v_1, \dots, v_n\}$ & $E = \{\{v_i, v_j\} : i \neq j\}$. There exists an edge between each pair of vertices.

Example 4.1 - Common Graphs



Definition 4.22 - Eulerian Circuit

An Eulerian Circuit is a Circuit that traverses every edge exactly once. It traverses every edge exactly once, with no repeated vertices.

N.B. - A Eulerian Graph admits an Eulerian Circuit.

Theorem 4.5 - Every vertex of a connected graph has even degree \Leftrightarrow Eulerian Graph

Theorem 4.6 - Decomposing into Cycles

If every vertex of a graph has even degree then its edge set can be partitioned into disjoint subsets st each subset is a cycle.

Definition 4.23 - Hamiltonian Path

A Hamiltonian Path is a path that visits every vertex.

Definition 4.24 - Hamiltonian Cycle

A Hamiltonian Cycle is a cycle that visits every vertex in a graph.

N.B. - A Hamiltonian Graph admits a Hamiltonian Cycle.

Theorem 4.7 - Dirac's Theorem

Let G be a graph of order $n \geq 3$. If $\delta(G) \geq \frac{n}{2}$ then G is Hamiltonian.

Definition 4.25 - k-Partite Graph

Consider a graph G=(V,E), G is a k-Partite Graph if V can be partitioned into k disjoint vertex classes, $\{V_1,\ldots,V_k\},$ st $E\subseteq \{\{x,y\}:x\in V_i,\ y\in V_j,\ i\neq j\}.$

Definition 4.26 - Complete k-Partite Graph

A k-Partite Graph, G = (V, E) with vertex classes $\{V_1, \ldots, V_k\}$, is a Complete k-Partite Graph

if $E = \{\{x, y\} : x \in V_i, y \in V_j, i \neq j\}.$

Definition 4.27 - Bipartite Graph

A graph G = (V, E) is a *Bipartite Graph* iff V can be partitioned into two sets $V_1 \& V_2$ st $V_1 \cup V_2 = V$, $V_1 \cap V_2 = \emptyset \& \forall u \in V_1$, $v \in V_2 \{u, v\} \notin E$. N.B. - - This graph is denoted $G = (V_1 \cup V_2, E)$.

Theorem 4.8 - Characterisation of Bipartite Graph

A graph is bipartite iff it contains no odd cycles.

Theorem 4.9 - Handshaking Lemma for Bipartite Graph

Let $G = (V_1 \cup V_2, E)$ be a bipartite graph. Then

$$\sum_{v \in V_1} deg_G(v) = \sum_{u \in V_2} deg_G(u)$$

Definition 4.28 - *Matching*

Consider a bipartite graph $G = (X \cup Y, E)$ a *Matching* from X to Y is a set of edges $\{\{x,y\}: x \in X, y \in Y\}$ where no two edges have a vertex in common.

Theorem 4.10 - Hall's Theorem

Consider a bipartite graph $G = (X \cup Y, E)$. Then

$$\exists$$
 matching from X to $Y \Leftrightarrow \forall s \subseteq X, |N_G(S)| \geq |S|$

Theorem 4.11 - Degree Constrained Version of Hall's Theorem

Consider a bipartite graph $G = (X \cup Y, E)$. Then

$$\delta(X) \geq \Delta(Y) \Leftrightarrow \exists$$
 matching from X to Y

4.3 Trees & Forests

Definition 4.29 - Acyclic

A graph is *Acyclic* if it contains no cycles.

N.B. - An Acyclic Graph is called a Forest.

Proposition 4.2 - A tree is an acyclic connected graph

Definition 4.30 - Leaf

A vertex of degree one is called a *Leaf*.

Theorem 4.12 - Every tree on at least two vertices has a leaf

Theorem 4.13 - Characterisation of Trees

The following are different ways to characterise a tree G = (V, E)

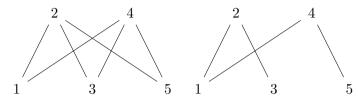
- i) G is maximally acyclic (i.e. G is acyclic & any additional edge creates a cycle).
- ii) G is minimally collected (i.e. G is connected & the removal of any edge disconnects G).
- iii) G is connected and |E| = |V| 1.
- iv) G is acyclic and |E| = |V| 1.
- v) Any two vertices in G has a unique path.

Definition 4.31 - Spanning Tree

Consider a graph G = (V, E), any tree on all vertices in V is a *Spanning Tree*. N.B. - T = (V, E') with $E' \subseteq E$.

Example 4.2 - Spanning Tree

Below is a graph and then a spanning tree of that graph



Theorem 4.14 - Every connected graph contains a spanning tree

Definition 4.32 - Weight Function

For G = (V, E) we define a Weight Function $W : V \to \mathbb{R}$.

Definition 4.33 - Minimum Spanning Tree

Consider a graph G = (V, E) with a weight function $W : V \to \mathbb{R}$. Let T be a Spanning Tree of G. T = (V, E') is a Minimum Spanning Tree if $W(E') := \sum_{e \in E'} W(e)$ is minimised relative to the other Spanning Trees of G.

Theorem 4.15 - Algorithm for Finding Spanning Tree

Let G = (V, E) be a graph with n vertices and m edges.

Order the edges of G arbitrarily into a sequence e_1, \ldots, e_m .

The algorithm constructs sets of edges $E_0, E_1, \ldots, \subseteq E$ in stances.

Set $E_0 = \emptyset$.

At state i the algorithm has already defined E_{i-1} . Then

$$E_i = \begin{cases} E_{i-1} \bigcup \{e_i\} & \text{If graph } (V, E_{i-1} \bigcup \{e_i\} \text{ contains no cycles} \\ E_{i-1} & \text{otherwise} \end{cases}$$

The algorithm stops if after stage i we have that $|E_i| = n - 1$.

This condition means that (V, E_i) is a tree.

Theorem 4.16 - Kruskal's Algorithm

Let G = (V, E) be a connected weighted graph equipped with weight function $W : E \to \mathbb{R}$. Label the edges of G with e_1, \ldots, e_m , with m = |E|, in such a way that

$$W(e_1) \le \cdots \le W(e_m)$$

Set $E_0 = \emptyset$.

At state i the algorithm has already defined E_{i-1} . Then

$$E_i = \begin{cases} E_{i-1} \bigcup \{e_i\} & \text{If graph } (V, E_{i-1} \bigcup \{e_i\} \text{ contains no cycles} \\ E_{i-1} & \text{otherwise} \end{cases}$$

The algorithm stops if after stage i we have that $|E_i| = n - 1$.

<u>N.B.</u> - This is the algorithm from **Definition 6.6**.

4.4 Cliques

Definition 4.34 - *k-Clique*

A k-Clique is a sub-graph which is a Complete Graph on k vertices.

Theorem 4.17 - Mantel's Theorem

Consider a graph G = (V, E), with n := |V|, containing no 3-cycle sub-graphs. Then

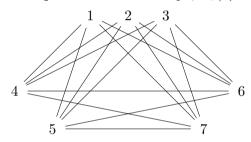
- i) $|E| \leq \lfloor \frac{n^2}{4} \rfloor$; &
- ii) \exists a graph where $|E| = \lfloor \frac{n^2}{4} \rfloor$.

<u>N.B.</u> - The graph described *ii*) is isomorphic to $K_{\lfloor n/2 \rfloor, n-\lfloor n/2 \rfloor}$.

Definition 4.35 - Turán Graph

A Turán Graph is a graph $T_k(n)$ that is a Complete k-Partite Graph on n vertices with vertex classes $\{V_1, \ldots, V_k\}$ where the difference in size of any pair of vertices is no more than 1 (i.e. $||V_i|| - |V_j|| \le 1 \ \forall i, j \in [1, k]$).

Example 4.3 - $Turan\ Graph,\ T_3(7)$



In the Turán Graph $T_k(n)$ each vertex class has size: $\lfloor \frac{n}{k} \rfloor$; or $\lceil \frac{n}{k} \rceil$.

Theorem 4.19 - Degree of Vertices in Turán Graph

Consider a Turán Graph $T_k(n)$ with vertex classes $\{V_1, \ldots, V_k\}$. Then

$$\forall V_i \ \forall \ x \in V_i, \ deg_G(x) = |V| - |V_i|$$

Theorem 4.20 - Number of Edges in a Turán Graph

Consider the Turán Graph $T_k(n) = (V, E)$ then

$$\max |E| = \left\lfloor \frac{(k-1)n^2}{2k} \right\rfloor$$

Theorem 4.21 - Turán's Theorem

Consider a graph G = (V, E) with n := |V| with no k-Cliques. Then

$$|E| < |E(T_{k-1}(n))|$$

Theorem 4.22 - Distance in Bounded Diameter Sets

Let $\{x_1, \ldots, x_n\}$ be a finite set of points in a circular plane of diameter ≤ 1 . Then the maximum number of pairs of points whose distance exceeds $\frac{1}{\sqrt{2}}$ is $\lfloor \frac{n^2}{3} \rfloor$.

4.5 Planar Graphs

Definition 4.36 - Arc

An Arc is a line in the 2D plane which does not intersect itself. An Arc can be described by an injective, continuous map $\gamma:[0,1]\to\mathbb{R}^2$. $\gamma(0)$ & $\gamma(1)$ are endpoints of the arc.

Definition 4.37 - Drawing of a Graph

A Drawing of a graph G = (V, E) is an assignment of the following form

- i) $\forall v \in V$ assign a unique point, p_v , in the plane, in such a way that the map $v \mapsto p_v$ is injective.
- ii) $\forall e =: \{u, v\} \in E \text{ assign an arc } \gamma_e \text{ in the plane whose endpoints as } p_u \& p_v \text{ and does not pass through any other points } p_u \text{ with } u \in V.$

Definition 4.38 - Planar Drawing

A $Planar\ Drawing$ of a graph G=(V,E) is a drawing of G where any two arcs, corresponding to edges, either have no intersections or only share an endpoint. A $Planar\ Graph$ is a graph which can be drawn in the 2D plane, with no edges intersecting.

Definition 4.39 - Planar Graph

A Planar Graph is a Graph which admits at least one Planar Drawing.

Example 4.4 - Non-Planar Drawing of K_3

Below is a *Drawing* of K_3 on the vertices $\{v_1, v_2, v_3\}$ which is not planar.



Definition 4.40 - Jordan Curve

A Jordan Curve is a closed arc. This is a non-intersecting, closed curve.

Theorem 4.23 - Jordan Curve Theorem

Any Jordan Curve, C, divides the plane into precisely two connected parts. These parts are called the interior & exterior. C is called the boundary of both regions.

Proposition 4.3 - If G contains a non-planar sub-graph, then G is non-planar

Definition 4.41 - Sub-Division

Consider a graph G, G' is a Sub-Division of G if the additional vertices it includes partition the edges of E. G' contains the partitions of the edges, but not the edges themselves.

Theorem 4.24 - Kuratowski's Theorem

A graph is $Planar \Leftrightarrow \text{Every sub-division of } G \text{ is planar.}$

Definition 4.42 - Face of a Planar Graph

Consider the set of all points which do not lie on any arc of a *Planar Drawing*. This set consists of a finite number of connected regions. Each of these regions is called a *Face* of the planar Graph.

Theorem 4.25 - Euler's Theorem

Consider a connected graph G = (V, E) with faces F being the set of faces of a *Planar Drawing* of G. Then

$$|V| - |E| + |F| = 2$$

N.B. - The number of faces does not depend upon how the *Planar Drawing* is drawn.

Theorem 4.26 - Planar Graph's have Few Edges

Consider a connected planar graph G = (V, E) with $|V| \ge 3$. Then

$$|E| \le 3|V| - 6$$

4.6 Graph Colouring

Definition 4.43 - k-Colouring

A k-Colouring of a graph G is an assignment of one of k colours to each vertex st no adjacent vertices share a colour.

Definition 4.44 - Chromatic Number

The Chromatic Number of a graph G is the lowest $k \in \mathbb{N}$ for which there is a valid k-Colouring of G.

Theorem 4.27 - Chromatic Number & Max Degree

For any graph G = (V, E) we have

$$\chi(G) \le \Delta(G) + 1$$

<u>N.B.</u> - $\forall k \in \mathbb{N}$ with $k \geq \Delta(G) \implies \chi(G) \leq k+1 \implies G$ is k+1-Colourable.

Theorem 4.28 - Five-Colour Theorem

At most five colours are required to colour a map st no two adjacent territories share a colour.

Proposition 4.4 - Assumptions for Five-Colour Theorem

We make the following assumptions about the maps referred to in the Five-Colour Theorem

- i) Each state is a single connected region;
- ii) Two states are neighbours iff they share a continuous interval of a border (*i.e.* If two states just meet at a point they are not neighbours & no pair of states share two borders).

Proposition 4.5 - Map as a Planar Drawing

We can consider a map to be a planar drawing of a graph where the faces correspond to states & edges correspond to borders between them.

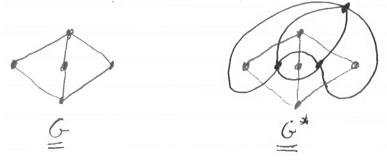
Definition 4.45 - Dual Graph

Consider a planar graph G = (V, E) along with its planar drawing. The dual graph $G^* = (V^*, E^*)$ of the planar drawing of G is obtained by drawing a vertex inside each face of the planar drawing & an edge between the vertices which correspond to adjacent faces.

N.B. - We can ignore duplicate edges in a *Dual Graph*.

Example 4.5 - Dual-Graph

Below is a planar drawing of $G = K_{2,3}$ & its dual-graph G^* .



Proposition 4.6 - Using Dual-Graphs

Consider a map G & its dual-graph G^* . A valid colouring of the faces of G corresponds to a valid colouring of the vertices of G^* . Thus there is a k-colouring of G iff there is a k-colouring of G^* .

 $\underline{\text{N.B.}}$ - Thus proving the *Five-Colour Theorem* is equivalent to showing that every planar graph s 5-colourable.

4.7 Ramsey Numbers

Definition 4.46 - Ramsey Number

The Ramsey Number for $s \in \mathbb{N}^{\geq 2}$, r(s), is the least $n \in \mathbb{N}$ st \forall 2-colourings of the edges of $K_n \exists$ a Monochromatic K_s subgraph.

N.B. - $\forall s \in \mathbb{N}^{\geq 2}$, r(s) exists.

Definition 4.47 - Off-Diagonal Ramsey Number

The Off-Diagonal Ramsey Number for $s, t \in \mathbb{N}$, r(s,t) is the least $n \in \mathbb{N}$ st \forall 2-Colourings of the edges of $K_n \exists$ a Monochromatic K_s or K_t subgraph.

Theorem 4.29 - Off-Diagonal Ramsey Number Identities

$$\begin{array}{lll} r(s,s) &=& r(s) & \forall \ s \in \mathbb{N} \\ r(s,t) &=& r(t,s) & \forall \ s,t \in \mathbb{N} \\ r(2,t) &=& t & \forall \ t \in \mathbb{N} \end{array}$$

Theorem 4.30 - Ramsey's Theorem

The Off-Diagonal Ramsey Number r(s,t) exists $\forall s,t \in \mathbb{N}^{\geq 2}$. Moreover,

$$r(s,t) \leq r(s-1,t) + r(s,t-1) \ \forall \ s,t \in \mathbb{N}^{\geq 3}$$

Theorem 4.31 - Upper Bound on Ramsey Number

 $\forall s, t \geq 2$ we have

$$r(s,t) \le 2^{s+t}$$

Equivalently, $r(s) < 4^s$.

Further

$$r(s) \leq r(s-1,s) + r(s,s-1) = 2r(s-1,s) \ \forall \ s \in \mathbb{N}^{\geq 3}$$

If r(s-1,t) & r(s,t-1) are both even then

$$r(s,t) < r(s-1,t) + r(s,t-1)$$

<u>N.B.</u> - This is a strict inequality.

0 Reference

0.1 Definition

Definition 0.1 - Linearly Independent Vertices

A vector v is linearly independent of vertices u_1, \ldots, u_n iff

$$\nexists a_1, \dots, a_n \in \mathbb{R} \ st \ v = \sum_{i=1}^n a_i u_i$$

Definition 0.2 - Rank of Matrix

The Rank of a Matrix is the number of linearly independent columns in the matrix.

0.2 Notation

Notation 0.1 - Binomial Coefficient

Let $n, k \in \mathbb{N}$. We denote the number of k-element subsets of an n-element set as

$$\binom{n}{k}$$

Notation 0.2 - Chromatic Number, $\chi(G)$

 $\chi(G)$ denotes the *Chromatic Number* of G.

Notation 0.3 - Complete Graph, K_n

We denote the Complete Graph on n vertices as K_n .

Notation 0.4 - Complete Bipartite Graph, $K_{m,n}$

We denote the Complete Bipartite Graph with vertex classes of sizes n & m as $K_{m,n}$.

Notation 0.5 - Consecutive Numbers, [n]

For $n \in \mathbb{N}$ we have $[n] := \{1, 2, \dots, n\}$.

Notation 0.6 - Generating Function

Let f(x) be the generating function of sequence (a_1, a_2, \dots) we denote this as

$$f(x) \leftrightarrows (a_1, a_2, \dots)$$

Notation 0.7 - Minimum & Maximum Degree

$$\delta(G) := \min\{deg_G(x) : x \in V\} \quad \& \quad \Delta(G) := \max\{deg_G(x) : x \in V\}$$

Notation 0.8 - $(n)_k$

 $(n)_k$ denote the product of k natural numbers less than n, including n.

$$(n)_k := n \times (n-1) \times \cdots \times (n-k+1) = \frac{n!}{(n-k)!}$$