Logic - Notes

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1 Introduction

1.1 Alphabets & Strings

Definition 1.1 - Alphabet

An Alphabet is a set of symbols from which Strings can be created.

Definition 1.2 - String

A String over a set \mathcal{A} is any sequence $\alpha := \langle a_1, \ldots, a_n \rangle$ where $a_1, \ldots, a_n \in \mathcal{A}$. N.B. Here we say α has length n and $\alpha \in \mathcal{A}^n$.

Definition 1.3 - Power Set

Let \mathcal{A} be an alphabet. We define

$$\mathcal{A}^* := \bigcup_{n \in \mathbb{N}} \mathcal{A}^n = \{ \langle a_1, \dots, a_n \rangle : n \in \mathbb{N}; a_1, \dots, a_n \in \mathcal{A} \}$$

This means \mathcal{A}^* is the set of all possible strings over alphabet \mathcal{A} .

Remark 1.1 - Concatenating Strings

Define Strings $\alpha := \langle a_1, \dots, a_n \rangle \in \mathcal{A}^n$ and $\beta := \langle b_1, \dots, b_m \rangle \in \mathcal{A}^m$.

We define Concatenation of α & β as $\alpha\beta := \langle a_1, \ldots, a_n, b_1, \ldots, b_m \rangle$ Note that

$$\alpha\beta \neq \langle \alpha, \beta \rangle = \langle \langle a_1, \dots, a_n \rangle, \langle b_1, \dots, b_m \rangle \rangle$$

N.B. Sometimes the following notation is used $\alpha * \beta$.

Example 1.1 - English Alphabet

If we define an alphabet $\mathcal{A} := \{`a`, \ldots, `z`\}$ then $\langle `t`, `h`, `i`, `s` \rangle$ is a *String* of \mathcal{A} .

Remark 1.2 - Ambiguity when using multiple Alphabets

Consider the Alphabets $A_1 := \{0, 1, \dots, 9\} \& A_2 := \mathbb{N}$.

Then we are unsure which of the following definitions of 123 is valid

$$\langle 123 \rangle$$
, $\langle 12, 3 \rangle$, $\langle 1, 23 \rangle$, $\langle 1, 2, 3 \rangle$

Remark 1.3 - $A := \{0,1\}$ is sufficient to describe any language - binary

Remark 1.4 - Describing Formal Languages

When describing a Formal Language we need to provide two things

- i) An Alphabet which defines what symbols are allowed.
- ii) A Grammar which defines what combinations of symbols are allowed.

1.2 Countable Sets

Definition 1.1 - Countable Set

A set X is said to be Countable if

$$\exists$$
 a surjection $f: \mathbb{N} \to X$
 \exists an injection $f: X \to \mathbb{N}$

Definition 1.2 - Countably Infinite Set

A set X is said to be Countably Infinite if \exists a bijection $f: X \to \mathbb{N}$.

Theorem 1.1 - Power set is Countable

If set \mathcal{A} is countable then \mathcal{A}^* is countable.

Proof 1.1 - *Theorem 1.1*

Let $f: \mathcal{A} \longrightarrow \mathbb{N}$ (This function exists trivally since we define \mathcal{A} to be countable).

Define the following function $g(\cdot): \mathcal{A}^* \longrightarrow \mathbb{N}$

$$g(\langle a_1, \dots, a_n \rangle) := p_1^{f(a_1)+1} \cdot \dots \cdot p_n^{f(a_n)+1}$$

where p_i is the i^{th} prime.

Since each natural number can be described by a unique composition of primes and since $f(\dot{)}$ is injective, then $g(\cdot)$ is injective.

Thus there exists an injection from \mathcal{A}^* to \mathbb{N} , making \mathcal{A}^* countable.

Theorem 1.2 - If A is countable, then so are $A^*, (A^*)^*, \dots$

2 First-Order Languages

Definition 2.1 - First-Order Language, \mathcal{L}

The Alphabet of a First-Order Language, comprises of the following, pairwise disjoint, categories (and nothing else)

- i) Negation, \neg , and implication, \longrightarrow .
- ii) For all, \forall .
- iii) Infinitely many variables, $\{v_0, v_1, \dots\}$.
- iv) Parentheses, '(' ')', and comman ','.
- v) Equality, \equiv , which is the only logical predicate symbol with 2-arity.
- vi) A set of constant symbols, $\{c_1, c_2, \dots\}$. (Possibly empty)
- vii) For each $n \ge 1$, a set of n-arity function symbols $\{f_1^n, f_2^n, \dots\}$. (Possibly empty)
- viii) For each $n \ge 1$, a set of *n*-arity non-logical predicate symbols $\{P_1^n, P_2^n, \dots\}$. (Possibly empty)

N.B. We denote the set of variables by $Var := \{v_0, v_1, \dots\}$; denote a language as \mathcal{L} and the alphabet of \mathcal{L} as $\mathcal{A}_{\mathcal{L}}$.

N.B. In this course Alphabets are restricted to being Countable.

Definition 2.2 - Negation, \neg

Negation returns in the inverse of a predicate (DO I MEAN PREDICATE)

$$\begin{array}{c|c} P & \neg P \\ \hline T & F \\ F & T \end{array}$$

Definition 2.3 - *Implication*, \longrightarrow

Implication returns whether one predicate being true necessarily implies a second predicate being true

$$\begin{array}{c|cc} P & Q & P \rightarrow Q \\ \hline T & T & T \\ T & F & F \\ F & T & T \\ F & F & T \\ \end{array}$$

Remark 2.1 - First-Order Languages don't have \land , \lor , \exists

Alphabets for First-Order Languages do not contain propositional connectives for AND, \land , OR, \lor , or EXISTS, \exists since they can be expressed as a combination of negation & implication.

$$\begin{array}{ccc} P \vee Q & \Longleftrightarrow & \neg P \to Q \\ P \wedge Q & \Longleftrightarrow & \neg (P \to \neg Q) \\ \exists \; x \; \mathrm{st} \; P(x) \; \mathrm{is} \; \mathrm{true} & \Longleftrightarrow & \neg (\forall \; x, \; \neg P(x)) \end{array}$$

P	Q	$\neg P$	$\neg P \rightarrow Q$	P	Q	$\neg Q$	$P \to \neg Q$	$\neg (P \to \neg Q)$
Т	Т	F	T	Т	Т	F	F	T
\mathbf{T}	\mathbf{F}	F	${ m T}$	\mathbf{T}	F	Τ	${ m T}$	${ m F}$
F	\mathbf{T}	F	${ m T}$	\mathbf{F}	\mathbf{T}	F	${ m T}$	${ m F}$
\mathbf{F}	F	F	F	\mathbf{F}	\mathbf{F}	Τ	${ m T}$	${ m F}$

Example 2.1 - Recursive Defintion

Consider the following, normal, deifition

x is a multiple of
$$5 \iff \exists y \in \mathbb{Z} \text{ st } y.5 = x$$

We can instead use the recursive definition

- i) 0 is a multiple of 5.
- ii) If n is a multiple of 5 then n + 5 is a multiple of 5.

Definition 2.4 - *L-Term & Complexity*

Let \mathcal{L} be a First-Order Language.

We define \mathcal{L} -Terms & Complexity, $cp(\cdot)$, together using the following recursive definition

- i) If s is a variable or a constant symbol, then s is an \mathcal{L} -Term with cp(s) = 0. N.B. Terms with $cp(\cdot) = 0$ are called Atomic Terms.
- ii) If f is a function symbol with k-arity & if a_1, \ldots, a_k are \mathcal{L} -Terms then $f(a_1, \ldots, f_k)$ is an \mathcal{L} -Term with complexity

$$cp(f(a_1,...,a_k)) := \max\{cp(a_1),...,cp(a_k)\} + 1$$

N.B. Terms with $cp(\cdot) \geq 1$ are called Compound Terms.

- iii) Nothing else is an \mathcal{L} -Term
- *N.B.* We denote the set of \mathcal{L} Terms by $T_{\mathcal{M}_{\mathcal{L}}}$.

Example 2.2 - L-Term & Complexity

Let $\{c,d,f,g,h,p\}\subseteq \mathbbm{L}$ with c,d being constants, g,p being uniary functions & f,h being binary functions.

Show that the following is an \mathcal{L} -Term & find its Complexity

i) x is an \mathcal{L} -Term with cp(x) = 0 by (i).

- ii) c & d are \mathcal{L} -Terms with cp(c) = 0 = cp(d) by (i).
- iii) f(x,c) is an \mathcal{L} -Term with $cp(f) = \max 0, 0 + 1 = 1$ by (ii).
- iv) p(d) is an \mathcal{L} -Term with $cp(f) = \max 0 + 1 = 1$ by (ii).
- v) g(f(x,c),p(d)) is an \mathcal{L} -Term with $cp(g) = \max 1, 1+1=2$ by (ii).
- vi) h(g(f(x,c),p(d))) is an \mathcal{L} -Term with $cp(h) = \max 2 + 1 = 3$ by (ii).

Thus h(q(f(x,c),p(d))) is an \mathcal{L} -Term with Complexity 3.

Notation 2.1 - More readble Functions

WE often write $x \circ y$ instead of $\circ(x, y)$ as it is more readable (even though the later is technically the only correct notation). Similarly, x + y instead of +(x, y).

Definition 2.5 - Atomic Formulae

Let \mathcal{L} be a First-Order Language.

The atomic \mathcal{L} -Formulae are those strings over $\mathcal{A}_{\mathcal{L}}$ of the form

$$R(t_1,\ldots,t_n)$$
 for $n\in\mathbb{N}$

where R is a predicate symbol of \mathcal{L} with n-arity and t_1, \ldots, t_n are \mathcal{L} -terms. $N.B. \equiv (t_1, t_2)$ is an $Atomic \mathcal{L}$ -Formula for each \mathcal{L} terms t_1, t_2 .

Definition 2.6 - L-Formulae & Complexity

We define \mathcal{L} -Formulae & Complexity, $cp(\cdot)$, together using the following recursive definition

- i) If $\phi \in \mathcal{A}_{\mathcal{L}}^*$ is an Atomic \mathcal{L} -Formula then ϕ is an \mathcal{L} -Formula with $cp(\phi) = 0$.
- ii) If ϕ is an \mathcal{L} -Formula with $cp(\phi) = n$ then $\neg \phi$ is an \mathcal{L} -Formula with $cp(\neg \phi) = n + 1$.
- iii) If $\phi \& \psi$ are \mathcal{L} -Formulae then $\phi \to \psi$ is an \mathcal{L} -Formula with $cp(\phi \to \psi) = \max\{cp(\phi), cp(\psi)\} + 1$.
- iv) if ϕ is an \mathcal{L} -Formula then $\forall x \phi$ is an \mathcal{L} -Formula with $cp(\forall x \phi) = cp(\phi) + 1$, where x is a variable.

N.B. Complexity is just a measure of the syntactic complexity, not semantic. Notice how $cp(\neg\neg\phi) = cp(\phi) + 2$.

Remark 2.2 - Formulae are uniquely readable & parsable

Example 2.3 - L-Formulae Complexity

Let $\{R, f\} \subset \mathcal{L}$ be binary operations.

Show that the following is an \mathcal{L} -Formula

$$\forall v_0 (\neg R(f(v_0, v_2), v_2) \longrightarrow \underbrace{\equiv (v_0, v_2)}_{v_0 \equiv v_2}$$

- i) v_0, v_2 are \mathcal{L} -Terms.
- ii) $f(v_0, v_2)$ is an \mathcal{L} -Term.
- iii) $R(f(v_0, v_2), v_2)$ is an \mathcal{L} -Formula with $cp(\cdot) = 0$.
- iv) $\neg R(f(v_0, v_2), v_2)$ is an \mathcal{L} -Formula with $cp(\cdot) = 0 + 1 = 1$.

- v) $\equiv (v_0, v_2)$ is an \mathcal{L} -Formula with $cp(\cdot) = 0$.
- vi) $\neq R(f(v_0, v_2), v_2) \longrightarrow \equiv (v_0, v_2)$ is an \mathcal{L} -Formula with $cp(\cdot) = \max\{0, 1\} + 1 = 2$.
- vii) $\forall v_0 \ (\neg R(f(v_0, v_2), v_2) \longrightarrow \equiv (v_0, v_2))$ is an \mathcal{L} -Formula with $cp(\dot) = 2 + 1 = 3$.

Notation 2.2 - Convention for common operators

To make formulae more readble we general make the following allowances in notation

$$t_1 \equiv t_2 \text{ for } \equiv (t_1, t_2)$$

 $t_1 \not\equiv t_2 \text{ for } \neg \equiv (t_1, t_2)$
 $t_1 < t_2 \text{ for } < (t_1, t_2)$
 $t_1 \not\equiv t_2 \text{ for } \neg \equiv (t_1, t_2)$

Further, when a formula is encapsulated by parantheses then we will often surpress the outermost parentheses (only), as they do not affect anything.

$$\phi \longrightarrow (\psi \longrightarrow \theta) \text{ for } (\phi \longrightarrow (\psi \longrightarrow \theta))$$

Definition 2.7 - More complex operators

- AND, $(\phi \wedge \psi) := \neg(\phi \longrightarrow \neg \psi)$.
- OR, $(\phi \lor \psi) := (\neg \phi \longrightarrow \psi)$.
- IFF, $(\phi \longleftrightarrow \psi) := (\phi \longrightarrow \psi) \land (\psi \longrightarrow \phi)$.
- EXISTS, $(\exists x\phi) := \neg \forall x \neg \phi$.

Notation 2.3 - Sets of \mathcal{L} Features

- $T_{\mathcal{M}_{\mathcal{L}}} := \text{Set of } \mathcal{L}\text{-Terms.}$
- $F_{\mathcal{M}_{\mathcal{L}}} := \text{Set of } \mathcal{L}\text{-Formulae}.$
- Var := Set of Variables.

Proposition 2.1 - $T_{\mathcal{M}_{\mathcal{L}}}$ & $F_{\mathcal{M}_{\mathcal{L}}}$ are always countable in this course since we assume \mathcal{L} to be finite.

2.1 Induction of Terms & Formulae

Theorem 2.1 - Inheritance of a Proeprty - L-Terms

Let P be a property of \mathcal{L} -Terms.

Suppose the following to be true

- i) All Atomic \mathcal{L} -Terms have property P.
- ii) $\forall k \in \mathbb{N}, \forall$ function symbols f with k-arity: If \mathcal{L} -Terms t_1, \ldots, t_k have property P then $f(t_1, \ldots, t_k)$ has P.

Then every \mathcal{L} -Term has property P.

Proof 2.1 - *Theorem 2.1*

This is a proof by contradiction. Suppose that i) & ii) are true but there exists some \mathcal{L} -Term which does not have P.

Let t be an \mathcal{L} -Term with minimum complexity st t does not have P.

Then $cp(t) \neq 0$ otherwise i) would be untrue.

Thus $t \equiv f(t_1, \ldots, t_k)$ by the minimlaity of cp(t).

We know that t_1, \ldots, t_k have P.

Thus $f(t_1, \ldots, t_k)$ has P. This is a contradiction.

Theorem 2.2 - Inheritance of a Proeprty - L-Formulae

Let P be a property of \mathcal{L} -Formula.

Suppose the following to be true

- i) All Atomic \mathcal{L} -Formulae have property P.
- ii) If $\phi, \psi \in F_{\mathcal{M}_{\mathcal{L}}}$ have P then $\neg \phi, (\phi \to \psi)$ & $\forall x \phi$ have P to.

Then every \mathcal{L} -Formulae has property P.

Theorem 2.3 - Number of Parenthese

Ever \mathcal{L} -Formula has as many left parentheses as right parentheses.

Ever \mathcal{L} -Term has as many left parentheses as right parentheses.

Proof 2.2 - *Theorem 2.3*

This is a proof by induction.

Let P be the property "Has as many left parenthese as right".

Base Case - When ϕ is an Atomic \mathcal{L} Formula it trivially has equal number of parenthese.

<u>Inductive Case</u>

Let $\phi \& \psi$ be arbitrary \mathcal{L} -Formulae.

Assume that $P(\phi) \& P(\psi)$ hold.

We need to show that $P(\neg \phi)$, $P(\phi \rightarrow \psi)$ & $P(\forall x\phi)$ all hold.

We do not need to show $P(\neg \psi)$, $P(\psi \rightarrow \phi)$ & $P(\forall x\psi)$ hold as ϕ & ψ are arbitrary.

We have that $\neg \phi$ and $\forall x \phi$ don't add any brackets, so P holds.

We have that $(\phi \to \psi)$ add one left & one right parentheses (although they are often surpressed), thus P holds.

Thus by the process of mathematical induction P holds for all \mathcal{L} -Formulae.

N.B. The proof for \mathcal{L} -Terms is very similar.

2.2 Free Variables

Definition 2.1 - Variable Function, $var(\cdot)$

Define $var: \mathcal{A}_{\mathcal{L}}^* \to 2^{\text{Var}}$ st var(s) is the set of all variables in string s.

Example 2.4 - $Var(\cdot)$

$$var(f(x, f(y, c)) = \{x, y\}$$

 $var(f(c, f(c, c)) = \emptyset$
 $var(\equiv, \equiv, \equiv) = \emptyset$ nonsense strins are acceptable

Definition 2.2 - Free Variables

Free Variables are variables whose value are ambiguous in an \mathcal{L} -Formula.

Definition 2.3 - Free Variable Function, $FV(\cdot)$

We recursively define $FV(\phi)$ for \mathcal{L} -Formulae as ϕ as follows

- i) $FV(\phi) = var(\phi)$ if ϕ is an Atomic \mathcal{L} -Formula.
- ii) $FV(\neg \phi) = FV(\phi)$.
- iii) $FV((\phi \to \psi)) = FV(\phi) \cup FV(\psi)$.

iv)
$$FV(\forall x\phi) = FV(\phi) \setminus \{x\}.$$

Example 2.5 - Free Variable Function

$$\begin{array}{lcl} FV(\forall x(P(y) \rightarrow Q(x))) & = & FV(P(y) \rightarrow Q(x)) \backslash \{x\} \\ & = & [FV(P(y)) \cup FV(Q(x))] \backslash \{x\} \\ & = & [\{y\} \cup \{x\}] \backslash \{x\} \\ & = & \{y\} \end{array}$$

Proposition 2.2 - Free Variable Function for more complex operators

$$FV(\phi \wedge \psi) = FV(\neg(\phi \to \neg \psi)) \text{ by definition of } \wedge$$

$$= FV(\phi) \cup FV(\psi)$$

$$FV(\phi \vee \psi) = FV(\neg\phi \to \psi) \text{ by definition of } \vee$$

$$= FV(\phi) \cup FV(\psi)$$

$$FV(\exists x\phi) = FV(\neg \forall x \neg \phi) \text{ by definition of } \exists$$

$$= FV(\phi) \backslash \{x\}$$

Definition 2.4 - Closed L-Term

Let t be an \mathcal{L} -Term.

If $var(t) = \emptyset$ then t is called a Closed \mathcal{L} -Term.

Definition 2.5 - \mathcal{L} -Sentence

Let ϕ be an \mathcal{L} -Formula.

If $FV(\phi) = \emptyset$ then ϕ is called an \mathcal{L} -Sentence.

Example 2.6 - \mathcal{L} -Sentence

$$FV(\forall x (P(x) \rightarrow \exists y \ R(y,x)) = FV((P(x) \rightarrow \exists y \ R(y,x)) \backslash \{x\}$$

$$= FV(P(x)) \cup FC(\exists y \ R(y,x)) \backslash \{x\}$$

$$= \{x\} \cup (FV(R(y,x) \backslash \{y\}) \backslash \{x\}$$

$$= \{x\} \cup (\{y,x\} \backslash \{y\}) \backslash \{x\}$$

$$= \{x\} \cup \{x\} \backslash \{x\}$$

$$= \emptyset$$

Remark 2.3 - L-Sentences have no Free Variables and thus no ambiguity in meaning.

3 Semantics of First-Order Languages

Definition 3.1 - *L-Structure*

Let \mathcal{L} be a first-order language.

An \mathcal{L} -Structure is an ordered pair $\mathfrak{M} = \langle D, \mathfrak{I} \rangle$

- i) D is a non-empty set.
- ii) \Im is a function on the non-logical symbols of \mathcal{L} st
 - For each predicate symbol $P \in \mathcal{L}$ with n-arity.

$$\mathfrak{I}(P) \subset D^n$$

- For each function symbol f of \mathcal{L} with n-arity

$$\mathfrak{I}(f):D^n\to D$$

- For each constant symbol c of \mathcal{L}

$$\Im(c) \in D$$

N.B. D is the domain, \Im is the interpretation.

Notation 3.1 - *L-Structure*

For ease we use the following notation wrt \mathcal{L} -Structure

$$|\mathfrak{M}| := D \quad f^{\mathfrak{M}} := \mathfrak{I}(f) \quad c^{\mathfrak{M}} := \mathfrak{I}(c) \quad p^{\mathfrak{M}} = \mathfrak{I}(p)$$

Example 3.1 - \mathcal{L} -Structure

Let $\mathcal{L}_{Rng} := \{\bar{0}, \bar{1}\bar{+}, \bar{\cdot}\}\$ where $\bar{+}$ & $\bar{\cdot}$ are binary functions and $\bar{0}$ & $\bar{1}$ are constants.

(This is the language for ring theory)

We use the overline to distringuish language symbols from standard symbols.

Define

$$\begin{array}{rcl} D & := & \mathbb{R} \\ \Im(\bar{0}) & = & 0 \in \mathbb{R} \\ \Im(\bar{1}) & = & 1 \in \mathbb{R} \\ \Im(\bar{+}) & : & \mathbb{R} \times \mathbb{R} \to \mathbb{R} \text{ with}(a,b) \mapsto (a+b) \\ \Im(\bar{\cdot}) & : & \mathbb{R} \times \mathbb{R} \to \mathbb{R} \text{ with}(a,b) \mapsto (a \cdot b) \end{array}$$

We recall $\langle D, \mathbf{1} \rangle$ is the standard model of the real field.

N.B. We can alternatively write $\langle D, \mathfrak{I} \rangle = \langle \mathbb{R}, 0, 1, +, \cdot \rangle$ for neatness.

Definition 3.2 - Variable Assignment

A $Variable\ Assignment\ over\ an\ \mathcal{L}\text{-Structure}$ is a function which maps from the set of variables to the domain of the $\mathcal{L}\text{-Structure}$.

$$s: \mathrm{Var} \to |\mathfrak{M}|$$

Definition 3.3 - Extension of Variable Assignment

Let \mathfrak{M} be an \mathcal{L} -Structure & s be a variable assignment over \mathfrak{M} .

The function $\bar{s}: T_{\mathfrak{M}_{\mathcal{L}}} \to |\mathfrak{M}|$ is defined using the following recursion

- i) $\bar{s}(t) = s(t)$ if $t \in \text{Var}$.
- ii) $\bar{s}(t) = t^{\mathfrak{M}}$ if t is a constant symbol.
- iii) $\bar{s}(f(t_1,\ldots,t_k)) = f^{\mathfrak{M}}(\bar{s}(t_1),\ldots,\bar{s}(t_k)).$

Example 3.2 - Variable Assignment

Let ${\mathfrak M}$ be the standard model of the real field.

Let s be avariable assignment over \mathfrak{M} st $s(x) = s(y) = \pi$. Then

$$\bar{s}(x + y) = \bar{+}^{\mathfrak{M}}(\bar{s}(x), \bar{s}(y))$$

$$= \bar{+}^{\mathfrak{M}}(s(x), s(y))$$

$$= \bar{+}^{\mathfrak{M}}(\pi, \pi)$$

$$= \pi + \pi$$

$$= 2\pi$$

Theorem 3.1 -

Let s be a variable assignment over \mathfrak{M} , $x \in \text{Var } \& d \in |\mathfrak{M}|$. A new variable assignment $\frac{sd}{x}$ over \mathfrak{M} is defined as

$$\frac{sd}{x}(y) = \begin{cases} d & \text{if } y = x\\ s(y) & \text{otherwise} \end{cases}$$

Definition 3.4 - Satisfaction Relation

Let \mathfrak{M} be an \mathcal{L} -Structure & s be a variable assignment over \mathfrak{M} .

The Satiscation Relation, $\mathfrak{M}, s \models \phi$ between \mathfrak{M}, s and \mathcal{L} -Formula ϕ is recursively defined as

- i) $\mathfrak{M}, s \vDash t_1 \equiv t_2 \text{ iff } \bar{s}(t_1) = \bar{s}(t_2).$
- ii) $\mathfrak{M}, s \models P(t_1, \ldots, t_k)$ iff $\langle \bar{s}(t_1), \ldots, \bar{s}(t_k) \rangle \in P^{\mathfrak{M}} \subset D^k$.
- iii) $\mathfrak{M}, s \vDash \neg \phi \text{ iff } \mathfrak{M}, s \not\equiv \phi.$
- iv) $\mathfrak{M}, s \models \phi \rightarrow \psi$ iff if $\mathfrak{M}, s \models \phi$ then $\mathfrak{M}, s \models \psi$.
- v) $\mathfrak{M}, s \models \forall x \phi \text{ iff for all } d \in |\mathfrak{M}|, \mathfrak{M}^{\underline{sd}}_{\underline{\sigma}} \models \phi.$

Proposition 3.1 - Extension of Satisfaction Relation

$$\begin{array}{lll} \mathfrak{M},s\vDash\phi\wedge\psi & \text{ iff } & \mathfrak{M},s\vDash\phi \text{ and } \mathfrak{M},s\vDash\psi \\ \mathfrak{M},s\vDash\phi\vee\psi & \text{ iff } & \mathfrak{M},s\vDash\phi \text{ or } \mathfrak{M},s\vDash\psi \\ \mathfrak{M},s\vDash\phi\leftrightarrow\psi & \text{ iff } & \mathfrak{M},s\vDash\phi \text{ iff } \mathfrak{M},s\vDash\psi \\ \mathfrak{M},s\vDash\exists x\phi & \text{ iff } & \mathfrak{M},s\frac{d}{x}\vDash\phi \text{ for some } d\in|\mathfrak{M}| \end{array}$$

Definition 3.5 - Model

Let $\Phi \subset \operatorname{Fml}_{\mathcal{L}}$, a subset of formulae of a first order language \mathcal{L} .

 \mathfrak{M}, s is a model of Φ iff $\mathfrak{M}, s \propto \phi$ for all $\phi \in \Phi$.

N.B. This is denoted $\mathfrak{M}, s \models \Phi$.

Example 3.3 - Model

Let \mathfrak{M} be the standard model of ring theory & s be a variable assignment over \mathfrak{M} st $s(v_1) = 3$ & $s(v_2) = -\pi$.

 $\mathfrak{M}, s \models \bar{0} \bar{<} v_1 \bar{+} v_2$

$$\Leftrightarrow \quad \overline{<}^{\mathfrak{M}}(\bar{s}(\bar{0}), \bar{s}(v_1 + v_2))$$

$$\Leftrightarrow \quad \overline{<}^{\mathfrak{M}}(\bar{0}^{\mathfrak{M}}, \bar{+}^{\mathfrak{M}}(\bar{s}(v_1), \bar{s}(v_2)))$$

$$\Leftrightarrow \quad \overline{<}^{\mathfrak{M}}(0, \bar{+}^{\mathfrak{M}}(s(v_1), s(v_2)))$$

$$\Leftrightarrow \quad 0 < 3 + (-\pi)$$

$$\Rightarrow \quad \mathfrak{M}, s \not\vDash \bar{0} \overline{<} v_1 \bar{+} v_2$$

$$\mathfrak{M}, s \vDash \forall v_2 \exists v_0, \ v_2 \overline{<} v_0$$

$$\Leftrightarrow \quad \text{for all } d \in \mathbb{R}, \ \mathfrak{M} s \frac{d}{v_2} \propto \exists v_0, \ v_2 \overline{<} v_0$$

$$\Leftrightarrow \quad \text{for all } e \in \mathbb{R}, \ \mathfrak{M} (s \frac{d}{v_2}) \frac{e}{v_0} \propto v_2 \overline{<} v_0$$

$$\Leftrightarrow \quad \text{for all } d \in \mathbb{R} \text{ there is } e \in \mathbb{R}, \ s (\frac{d}{v_2}) \frac{e}{v_0} v_2 < (s \frac{d}{v_0}) \frac{e}{v_0} v_0$$

$$\Leftrightarrow \quad \text{for all } d \in \mathbb{R} \text{ there is } e \in \mathbb{R} \text{ st } d < e$$

Theorem 3.2 -

Let $\mathcal{L}_1, \mathcal{L}_2$ be first order languages.

Define models

$$\mathfrak{M}_1 = \langle D, \mathcal{I}_1 \rangle : \mathcal{L}_1 \text{ structure}$$

 $\mathfrak{M}_1 = \langle D, \mathcal{I}_2 \rangle : \mathcal{L}_2 \text{ structure}$

Note that D is the same for both (i.e. Different languages, same world). Let $\mathcal{L} := \mathcal{L}_1 \cup \mathcal{L}_2$

i) For all \mathcal{L} -Terms, t, for all variable assignments s_1 over \mathfrak{M}_1 & s_2 over \mathfrak{M}_2 .

If
$$\begin{cases} c^{\mathfrak{M}_1} = c^{\mathfrak{M}_2} & \text{for all constants symbols that occur in } t \\ f^{\mathfrak{M}_1} = f^{\mathfrak{M}_2} & \text{for all functions symbols that occur in } t & \text{then } \bar{s}_1(t) = \bar{s}_2(t). \\ s_1(x) = s_2(x) & \text{for all variable symbols that occur in } t \end{cases}$$

ii) For all $\phi \in \text{Fml}_{\mathcal{L}}$ & for all variable assignemnts s_1 over \mathfrak{M}_1 & s_2 over \mathfrak{M}_2 .

If
$$\begin{cases} c^{\mathfrak{M}_{1}} = c^{\mathfrak{M}_{2}} & \text{for all constants symbols that occur in } \phi \\ f^{\mathfrak{M}_{1}} = f^{\mathfrak{M}_{2}} & \text{for all functions symbols that occur in } \phi \\ R^{\mathfrak{M}_{1}} = R^{\mathfrak{M}_{2}} & \text{for all predicate symbols that occur in } \phi \end{cases}$$
 then $\mathfrak{M}_{1}s_{1} \models \phi$ iff $\mathfrak{M}_{2} \models \phi$.
$$s_{1}(x) = s_{2}(x) \quad \text{for all variable symbols in } FV(\phi)$$

N.B. If $\mathcal{L} = \emptyset$ it is not very interesting.

Proof 3.1 - Theorem 3.2 i)

This is a proof by induction on \mathcal{L} -Term.

Base Case

Let t be atomic then $\bar{s}_1(t) = \bar{s}_2(t)$ is trivial, $\bar{s}_1(x) = s_1(x) = s_2(x) = \bar{s}_2(x)$ and $\bar{s}_1(c) = c^{\mathfrak{M}_1} = c^{\mathfrak{M}_2} = \bar{s}_2(c)$.

Inductive Case

Let $t = f(t_1, \ldots, t_k)$. Then

$$\begin{array}{lll} \bar{s}_{1}(t) & = & f^{\mathfrak{M}_{1}}(\bar{s}_{1}(t_{1}), \ldots, \bar{s}_{1}(t_{k})) \\ & = & f^{\mathfrak{M}_{1}}(\bar{s}_{2}(t_{1}), \ldots, \bar{s}_{2}(t_{k})) \text{ by inductive hypothesis} \\ & = & f^{\mathfrak{M}_{2}}(\bar{s}_{2}(t_{1}), \ldots, \bar{s}_{2}(t_{k})) \\ & = & \bar{s}_{2}(t) \end{array}$$

Proof 3.2 - *Theorem 3.2 ii)*

This is a proof by induction on \mathcal{L} -Formulae. Base Case

Let $\phi = R(t_1, \dots, t_k)$ be an atomic \mathcal{L} -formula (i.e. $cp(\phi) = 0$).

Note that $FV(\phi) = \text{var}(\phi)$, thu conditions in **ii**) for ϕ imply the conditions of **i**) for t_1, \ldots, t_k . Therefore $\bar{s}_i(t_i) = \bar{s}_1(t_i) \ \forall i \in [1, k]$. Then

$$\mathfrak{M}_{1}, s_{1} \vDash \phi
\iff \langle \bar{s}_{1}(t_{1}), \dots, \bar{s}_{1}(t_{k}) \rangle \in R^{\mathfrak{M}_{1}}
\iff \langle \bar{s}_{2}(t_{1}), \dots, \bar{s}_{2}(t_{k}) \rangle \in R^{\mathfrak{M}_{1}}
\iff \langle \bar{s}_{2}(t_{1}), \dots, \bar{s}_{2}(t_{k}) \rangle \in R^{\mathfrak{M}_{2}}
\iff \mathfrak{M}_{2}, s_{2} \vDash \phi$$

Inductive Case

Let $\phi := \psi \to \theta$.

Since the conditions hold for ϕ they hold for $\psi \& \theta$. Then

$$\begin{array}{ccc} & \mathfrak{M}_{1}, s_{1} \vDash \phi \\ \Longleftrightarrow & \text{if } \mathfrak{M}_{1}, s_{1} \vDash \phi \text{ then } \mathfrak{M}_{1}, s_{1} \vDash \theta \\ \stackrel{\text{by IH}}{\Longleftrightarrow} & \text{if } \mathfrak{M}_{2}, s_{2} \vDash \phi \text{ then } \mathfrak{M}_{2}, s_{2} \vDash \theta \\ \Longleftrightarrow & \mathfrak{M}_{2}, s_{2} \vDash \phi \end{array}$$

Let $\phi := \neg \psi$.

By the inductive hypothesis the claim holds for ψ .

Since the conditions of ii) hold for ϕ they hold for ψ .

Note that $FV(\neg \psi) = FV(\psi)$. Hence

$$\begin{array}{ccc} & \mathfrak{M}_{1}, s_{1} \vDash \phi \\ \Longleftrightarrow & \mathfrak{M}_{1}, s_{1} \not\vDash \psi \\ \overset{\text{by IH}}{\Longleftrightarrow} & \mathfrak{M}_{2}, s_{2} \not\vDash \psi \\ \Longleftrightarrow & \mathfrak{M}_{2}, s_{2} \vDash \phi \end{array}$$

Let $\phi := \forall z \psi$.

By the last condition of **ii**) we have that $s_1(x) = s_2(x) \ \forall \ x \in FV(\phi)$. Since $FV(\phi) \subset FV(\psi) \subset FV(\phi) \cup \{z\}$ it holds that $\forall \ d \in D$ that $s_1 \frac{d}{z}(x) = s_2 \frac{d}{z}(x) \ \forall \ x \in FV(\psi)$. Meaning that $\forall \ d \in D$ the conditions of **ii**) hold for ψ wrt $s_1 \frac{d}{z} \ \& \ s_2 \frac{d}{z}$. Hence

$$\mathfrak{M}_{1}, s_{1} \vDash \phi
\iff \forall d \in D, \, \mathfrak{M}_{1}, s_{1} \frac{d}{z} \vDash \psi
\stackrel{\text{by IH}}{\iff} \forall d \in D, \, \mathfrak{M}_{2}, s_{2} \frac{d}{z} \vDash \psi
\iff \mathfrak{M}_{2}, s_{2} \vDash \phi$$

Theorem 3.3 -

Let \mathfrak{M} be an \mathcal{L} -Strucutre, t be a closed \mathcal{L} -Term, ϕ to be an \mathcal{L} -Sentence and s_1, s)2 to be variable assignments over \mathfrak{M} .

Then $\bar{s}_1(t) = \bar{s}_2(t)$ and $\mathfrak{M}, s_1 \models \phi$ iff $\mathfrak{M}, s_2 \models \phi$.

N.B. This is since t is closed and thus its sematnic value is indepedent of variable assignment.

Notation 3.2 -

Let t be a closed \mathcal{L} -Term & ϕ an \mathcal{L} -Sentence.

We use the following notation

 $t^{\mathfrak{M}}:=$ the unique $d\in D$ st bars(t)=d for **some** variable assignment s over \mathfrak{M} := the unique $d\in D$ st bars(t)=d for **all** variable assignment s over \mathfrak{M} $\mathfrak{M} \models \phi := \mathfrak{M}, s \models \phi$ for **some** variable assignment s over \mathfrak{M} := $\mathfrak{M}, s \models \phi$ for **all** variable assignment s over \mathfrak{M}

N.B. The s is dropped in $\mathfrak{M} \models \phi$.