# Statistics 2 - Reviewed Notes

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# 1 General

# 1.1 Definitions

# **Definition 1.1** - Probability Space, $(\Omega, \mathcal{F}, \mathbb{P})$

A *Probability Space* is a mathematical construct for modelling the real world. A *Probability Space* has three elements

- i)  $\Omega$ , Sample space;
- ii)  $\mathcal{F}$ , Set of events; and,
- iii) P, Probability Measure

and must filfil the following criteria

- i)  $\Omega \in \mathcal{F}$ ;
- ii)  $\forall A \in \mathcal{D} \implies A^c \in \mathcal{F}$ ;

iii) 
$$\forall A_0, \dots, A_n \in \mathcal{F} \implies \left(\bigcup_{i=0}^n A_i\right) \in \mathcal{F};$$

- iv)  $\mathbb{P}(\Omega) = 1$ ; and,
- v)  $\mathbb{P}\left(\bigcup_{i=0}^{n}\right) = \sum_{i=0}^{n} \mathbb{P}(A_i)$  for any n disjoint  $A_0, \dots, A_n$ .

### **Definition 1.2 -** Random Variable

A  $Random\ Variable$  is a function which maps maps an event in the sample space to a value. X is a random variable if it satisfies the signature

$$X:\Omega\to\mathbb{R}$$

### **Definition 1.3 -** Parametric Models

Parametric Models are the class of statistical distributions whose probability mass/density function take parameters. These parameters represent values of interest in the population, such as mean or variance. We generally do not know these values so we estimate them from samples.

# **Definition 1.4** - Quantity of Interest

When analysing distributions it often helps to define Quantities of Interest about the distributions (e.g. Mean). These are defined as functions in terms of the parameters  $\tau(\theta)$ . We estimate Quantities of Interest by passing estimated values of the parameters  $\hat{\tau} = \tau(\hat{\theta})$ .

### 1.2 Theorems

**Theorem 1.1 -** Samples from a Normal Distribution are  $\chi^2$  Distributed Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$ . Then

$$\sum_{i=1}^{n} \frac{(X_i - \mu)^2}{\sigma^2} \sim \chi_n^2$$

$$\sum_{i=1}^{n} \frac{(X_i - \bar{X})^2}{\sigma^2} \sim \chi_{n-1}^2$$

**Theorem 1.2** - Distance between Sample Mean & Population Mean is  $t_r$  Distributed Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$ . Then

$$\frac{\sqrt{n}}{s}(\bar{X}-\mu) \sim t_{n-1}$$

N.B. We don't need to know  $\sigma^2$  to estimate the distance between  $\bar{X}$  and  $\mu$ .

# **Theorem 1.3 -** Multidimension Transform of a Random Variable

Consider an *n*-dimensional *continuous* random variable  $\mathbf{X} \sim f_{\mathbf{X}}(\cdot)$  which we wish to transform. Define a continuously differentiable bijective function  $\mathbf{g} : \mathbb{R}^n \to \mathbb{R}^n$  and  $\mathbf{h} := \mathbf{g}^{-1}$ .

Then if  $\mathbf{Y} := \mathbf{g}(\mathbf{X}) \sim f_{\mathbf{Y}}(\cdot)$  we have

$$f_{\mathbf{Y}}(\mathbf{y}) = f_{\mathbf{X}}(\mathbf{h}(\mathbf{y}))J_{\mathbf{h}}(\mathbf{y})$$

where 
$$J_h(\mathbf{y}) := \left| \det \left( \frac{\partial \mathbf{h}}{\partial \mathbf{y}} \right) \right| = \left| \det \left( \frac{\frac{\partial h_1}{\partial y_1} \cdots \frac{\partial h_1}{\partial y_n}}{\vdots \cdots \vdots \vdots} \right) \right|$$
.

**Theorem 1.4** - Weak Law of Large Numbers

Let  $\{X_n\}_{n\in\mathbb{N}}$  be a sequence of idependent & identically distributed random varibles. If  $\mathbb{E}(X_i) = \mu < \infty$  then

$$\frac{1}{n}\sum_{i=1}^{n}X_{i}\to_{\mathbb{P}}\mu$$

### Theorem 1.5 - Central Limit Theorem

Let  $\{X_n\}_{n\in\mathbb{N}}$  be a sequence of independent & indetically distributed with  $\mathbb{E}(X_i) = \mu < \infty$  and  $\mathrm{Var}(X_i) = \sigma^2 < \infty$ . Then

$$\sqrt{\frac{n}{\sigma^2}}(Z_n - \mu) \to_{\mathcal{D}} Z \sim \text{Normal}(0, 1)$$

# 2 Estimation

# 2.1 Likelihood

# **Definition 2.1** - Likelihood Function

The *Likelihood Function* is a family of functions which measure the likely of a certain realisation of a random variable is given the parameters of a model have a certain value.

$$L(\boldsymbol{\theta}; \mathbf{x}) := C f_X(\mathbf{x}; \boldsymbol{\theta}) \text{ for } C > 0$$

where  $\mathbf{X} \sim f_n(\cdot; \boldsymbol{\theta}^*)$  with  $\boldsymbol{\theta}^*$  unknown and  $\mathbf{x}$  is a realisation of  $\mathbf{X}$ .

N.B. Likelihood Functions have signature  $L(\mathbf{x}): \theta \to [0, \infty)$ .

N.B. This is also known as the Observed Likelihood Function.

### **Definition 2.2 -** Log-Likelihood Function

The Log-Likelihood Function is the family of functions which are equivalent to the natural log of the Likelihood Function.

$$\ell(\theta; \mathbf{x}) := \ln f_n(\mathbf{x}; \theta) + C \text{ for } \underbrace{C}_{\equiv \ln C} \in \mathbb{R}$$

N.B. This is increasing with  $L(cdot; \mathbf{x})$ .

**Remark 2.1** - Likelihood for Independent & Identically Distributed Random Variables Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta)$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ . Then

$$L_n(\theta; \mathbf{x}) := \prod_{i=1}^n L(\theta; x_i)$$
  
 $\ell_n(\theta; \mathbf{x}) := \sum_{i=1}^n \ell(\theta; x_i)$ 

**Theorem 2.1 -** The Likelihood Function is Invariant under Bijective Transformations which are independent of Model Parameters

Consider  $\mathbf{X} \sim f_{\mathbf{X}}(\cdot; \theta)$  and  $\mathbf{g} : \mathbb{R}^n \to \mathbb{R}^n$  be a bijective function which is independent of  $\theta$ . Define  $\mathbf{Y} := \mathbf{g}(\mathbf{X}) \sim f_{\mathbf{Y}}(\cdot; \theta)$ . Then

$$f_{\mathbf{Y}}(\mathbf{y};\theta) \propto f_{\mathbf{X}}(\mathbf{g}^{-1}(\mathbf{y});\theta)$$

Hence

$$L_{\mathbf{Y}}(\theta; \mathbf{g}(\mathbf{x})) \propto L_{\mathbf{X}}(\theta; \mathbf{x})$$

**Proof 2.1** - *Theorem 2.1* 

Consider  $\mathbf{X} \sim f_{\mathbf{X}}(\cdot; \theta)$  and  $\mathbf{g} : \mathbb{R}^n \to \mathbb{R}^n$  be a bijective function which is independent of  $\theta$ . Define  $\mathbf{h} := \mathbf{g}^{-1}$  and  $\mathbf{Y} := \mathbf{g}(\mathbf{X})$ .

We consider the cases where X is discrete & continuous independently

Discrete Case Let X be a discrete random variable. Then

$$f_{\mathbf{Y}}(\mathbf{y}; \theta) = \mathbb{P}(\mathbf{Y} = \mathbf{y}; \theta)$$

$$= \mathbb{P}(\mathbf{g}^{-1}(\mathbf{Y}) = \mathbf{g}^{-1}(\mathbf{y}); \theta)$$

$$= \mathbb{P}(h(\mathbf{Y}) = h(\mathbf{Y}); \theta)$$

$$= \mathbb{P} * \mathbf{X} = h(\mathbf{y}); \theta)$$

$$= f_{\mathbf{X}}(\mathbf{g}^{-1}(\mathbf{y}); \theta)$$

Continuous Case Let X be a continuous random variable.

By Theorem 1.3

$$f_{\mathbf{Y}}(\mathbf{y}; \theta) = f_{\mathbf{X}}(\mathbf{g}^{-1}(\mathbf{y}); \theta) J_{g^{-1}}(\mathbf{y})$$

Since  $J_{g^{-1}}$  is independent of  $\theta$  this case is solved.

In both cases  $L_{\mathbf{Y}}(\theta; \mathbf{y}) = f_{\mathbf{Y}}(\mathbf{y}; \theta) \propto f_{\mathbf{X}}(\mathbf{g}^{-1}(\mathbf{y}); \theta) = L_{\mathbf{X}}(\theta; \mathbf{x}).$ 

**Definition 2.3 -** Maximum Likelihood Estimate

Let  $\mathbf{X} \sim f_n(\cdot; \theta)$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

The Maximum Likelihood Estimate of **X** is the value  $\hat{\theta} \in \Theta$  which produces the greatest value of the Likelihood Function of **X**.

$$\hat{\theta}_{\mathrm{MLE}}(\mathbf{x}) := \mathrm{argmax}_{\theta} L(\theta; \mathbf{x}) = \mathrm{argmax}_{\theta} \ell(\theta; \mathbf{x})$$

N.B. The Maximum Likelihood Estimate is not necessarily unique.

**Theorem 2.2 -** Maximum Likelihood Estimate of Reparameterisation Define random variable  $\tau = g(X)$  where  $g : \mathbb{R} \to \mathbb{R}$ . Then

$$\hat{\tau}_{\mathrm{MLE}} = \tau(\hat{\theta}_{\mathrm{MLE}})$$

**Proof 2.2** - *Theorem 2.2* 

This is a proof by contradiction.

Suppose  $\exists \tau^* \in G \text{ st } \tilde{f}(x;\tau^*) > \tilde{f}(x;\tau^*).$ 

We know that  $\forall \theta \in \Theta$ ,  $f(x;\theta) = \tilde{f}(x;g(\theta))$  and  $\forall \tau \in G$ ,  $f(x;g^{-1}(\tau)) = \tilde{f}(x;\tau)$ .

We deduce that

$$\begin{array}{lcl} f(x;g^{-1}(\tau^*)) & = & \tilde{f}(x;\tau^*) \\ & > & \tilde{f}(x;\hat{\tau}) \text{ by assumption} \\ & = & f(x;g^{-1}(\hat{\tau})) \\ & = & f(x;\hat{\theta}) \end{array}$$

This contradicts the assumption that  $\hat{\theta}$  is an maximum likelihood estimate of  $\theta$ .

# Remark 2.2 - Finding Maximum Likelihood Estimates - Multivariate

Let  $X \sim f_X(\cdot; \boldsymbol{\theta})$  be continuous random variable where  $f_X(\cdot)$  is differentiable and  $\boldsymbol{\theta}$  is an *n*-dimensional parameter.

Let  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

To find a Maximum Likelihood Estimate for  $\boldsymbol{\theta}$ 

i) Find the gradient of  $\ell(\boldsymbol{\theta}; \mathbf{x})$  wrt  $\boldsymbol{\theta}$ .

$$abla \ell(\boldsymbol{ heta}; \mathbf{x}) := \left( \frac{\partial}{\partial \theta_1} \ell(\boldsymbol{ heta}; \mathbf{x}) \quad \dots \quad \frac{\partial}{\partial \theta_n} \ell(\boldsymbol{ heta}; \mathbf{x}) \right)$$

ii) Equate  $\nabla \ell(\boldsymbol{\theta}; \mathbf{x})$  to the zero-vector and solve for each  $\boldsymbol{\theta}$  to find extrama of  $\ell$ .

$$\nabla \ell(\boldsymbol{\theta}; \mathbf{x}) = \mathbf{0}$$

iii) Calculate the *Hessian* of  $\ell(\boldsymbol{\theta}; \mathbf{x})$ 

$$\nabla^2 \ell(\boldsymbol{\theta}; \mathbf{x}) = \begin{pmatrix} \frac{\partial}{\partial \theta_1^2} \ell(\boldsymbol{\theta}; \mathbf{x}) & \dots & \frac{\partial}{\partial \theta_1 \theta_n} \ell(\boldsymbol{\theta}; \mathbf{x}) \\ \vdots & \ddots & \vdots \\ \frac{\partial}{\partial \theta_n \theta_1} \ell(\boldsymbol{\theta}; \mathbf{x}) & \dots & \frac{\partial}{\partial \theta_n^2} \ell(\boldsymbol{\theta}; \mathbf{x}) \end{pmatrix}$$

iv) Test each extremum  $\hat{\boldsymbol{\theta}}$  to see if it is a maximum

If 
$$\det(H(\hat{\boldsymbol{\theta}})) > 0$$
 and  $\frac{\partial}{\partial \theta_1^2} \ell(\hat{\boldsymbol{\theta}}; \mathbf{x}) < 0$  then  $\hat{\boldsymbol{\theta}}$  is a local maximum.

i.e. Check  $H(\hat{\boldsymbol{\theta}})$  is negative definite.

# **Definition 2.4** - Likelihood Ratio

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta^*)$  for  $\theta^* \in \Theta$  and  $\{\hat{\theta}_i\}_{n \in \mathbb{N}}$  be a sequence of consistent Maximum Likelihood Estimaors of  $\theta^* \in \Theta$ .

We define the Likelihood Ratio as

$$\Lambda_n(\mathbf{x}) := \frac{L(\theta^*; \mathbf{x})}{L(\hat{\theta}_n; \mathbf{x})} \in [0, 1] \text{ for } \mathbf{x} \in \mathcal{X}^n$$

Theorem 2.3 - Asymptotic Distribution of Likelihood Ratio

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta^*)$  for  $\theta^* \in \Theta$  and  $\{\hat{\theta}_i\}_{n \in \mathbb{N}}$  be a sequence of consistent Maximum Likelihood Estimaors of  $\theta^* \in \Theta$ .

Suppose the conditions of **Theorem 2.13** hold (i.e.  $X_n$  is asymptotically normal). Then

$$-2\ln\Lambda_n(\mathbf{X}_n) \to_{\mathcal{D}(\cdot;\theta^*)} \chi_1^2$$

# 2.2 Estimators

### **Definition 2.5 -** Estimation

Let  $\mathbf{X} \sim f_n(\cdot; \theta^*)$  with  $\theta^* \in \Theta$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

As Estimation of model parameter  $\theta^*$  is a statistic,  $\hat{\theta}(\mathbf{x}) = T(\mathbf{x})$ , which is indtended to approximated the true value of  $\theta^*$ .

N.B. Interchangeable with Estimate.

### **Definition 2.6** - Estimator

Let  $\mathbf{X} \sim f_n(\cdot; \theta^*)$  with  $\theta^* \in \Theta$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

An Estimator of model paramter  $\theta^*$  is the random variable  $\hat{\theta} := \hat{\theta}(\mathbf{X})$  where  $\hat{\theta}(\mathbf{x})$  is an estimation of  $\theta^*$ .

# **Definition 2.7** - Bias

The Bias of an Estimator,  $\hat{\theta}$ , is its expected error.

i.e. By how much an estimator consistently deviates from the true value of the parameter). Let  $\theta^*$  be the true value of parameter  $\theta$ . Then

$$\begin{array}{ll} \operatorname{Bias}(\hat{\theta}; \theta^*) & := & \mathbb{E}(\hat{\theta} - \theta^*; \theta^*) \\ & = & \mathbb{E}(\hat{\theta}; \theta^*) - \theta^* \end{array}$$

N.B. An Estimator is Unbiased if  $\forall \theta \in \Theta \operatorname{Bias}(\theta^*; \theta) = 0 \iff \mathbb{E}(\hat{\theta}; \theta) = \theta$ .

# **Definition 2.8** - Mean Square Error

The Mean Square Error of an Estimator,  $\hat{\theta}$ , measures the average of its square error. Let  $\theta^*$  be the true value of parameter  $\theta$ . Then

$$\begin{split} \mathrm{MSE}(\hat{\theta}; \theta^*) &:= & \mathbb{E}\left[(\hat{\theta}(\mathbf{X}) - \theta^*)^2; \theta^*\right] \\ &= & \mathrm{Var}(\hat{\theta}; \theta^*) + \mathrm{Bias}(\hat{\theta}; \theta^*)^2 \end{split}$$

# **Definition 2.9 -** Distribution of an Estimator

Let  $\mathbf{X} \sim f_n(\cdot; \theta^*)$  with  $\theta^* \in \Theta \subseteq \mathbb{R}$ .

Let  $\hat{\theta}(\mathbf{X})$  be a real-valued *Estimator* of  $\theta^*$ . Then

$$F_{\hat{\theta}(\mathbf{X})}(t; \theta^*) := \mathbb{P}(\hat{\theta}(\mathbf{X}) \le t; \theta^*)$$
$$= \int_{\mathcal{X}^n} \mathbb{I}\{\hat{\theta}(\mathbf{x}) \le t\} f_n(\mathbf{x}; \theta^*) d\mathbf{x}$$

N.B. The distribution of an Estimator depends on the true value of the parameter it is estimating. N.B. As sample size increases the distribution of an estimator should converge to a more standard distribution.

# 2.3 Confidence Sets

**Definition 2.10 -** Random Interval TODO

**Definition 2.11 -** Observed Confidence Interval

Let **X** be a random variable,  $\mathcal{I}(\mathbf{X}) := [L(\mathbf{X}), U(\mathbf{X})]$  and **x** be a realisation of **X**.  $\mathcal{I}(\mathbf{x}) = [L(\mathbf{x}), U(\mathbf{x})]$  is an *Observed Confidence Interval*.

**Definition 2.12 -** Coverage of an Interval

Let  $\mathbf{X} \sim f_n(\cdot; \theta)$  for  $\theta \in \Theta = \mathbb{R}$ .

Define  $L: \mathcal{X}^n \to \Theta \& U: \mathcal{X}^n \to \Theta \text{ st } \forall \mathbf{x} \in \mathcal{X}^n, \ L(\mathbf{x}) < U(\mathbf{x}).$ 

The Coverage of the Random Interval  $\mathcal{I}(\mathbf{X}) := [L(\mathbf{X}), U(\mathbf{X})]$  at  $\theta$  is defined to be

$$C_{\mathcal{I}}(\theta) := \mathbb{P}(\theta \in [L(\mathbf{X}), U(\mathbf{X})]; \theta)$$

 $N.B.\ Coverage$  is the probability that a realisation of a random variable lies in a given random interval for a given parameter value.

# **Definition 2.13 -** Confidence Interval

Let  $\alpha \in [0,1]$  and  $\mathcal{I}(\mathbf{X}) := [L(\mathbf{X}), U(\mathbf{X})]$  be a random interval.

We say that  $\mathcal{I}(\mathbf{X})$  is a  $1-\alpha$  Confidence Interval if

$$\forall \theta \in \Theta, C_{\mathcal{T}}(\theta) > 1 - \alpha$$

N.B.  $\mathcal{I}(\mathbf{X})$  is an <u>Exact</u> Confidence Interval if  $\forall \theta \in \Theta$ ,  $C_{\mathcal{I}}(\theta) = 1 - \alpha$ .

# Proposition 2.1 - Transformed Confidence Interval

Let  $\mathbf{X} \sim f(\cdot; \theta^*)$  for  $\theta^* \in \Theta$  and  $\mathcal{I}(\mathbf{X}) := [L(\mathbf{X}), U(\mathbf{X})]$  be a confidence interval for  $\theta^*$ .

Let  $\tau := g(\theta)$  be a bijective, continuously differential function. If

- $g(\cdot)$  is increasing then  $[L(\mathbf{x}), U(\mathbf{x})] = [g(L(\mathbf{x})), g(U(\mathbf{x}))].$
- $g(\cdot)$  is decreasing then  $[L(\mathbf{x}), U(\mathbf{x})] = [g(U(\mathbf{x})), g(L(\mathbf{x}))].$

# Proposition 2.2 - Confidence Interval for Reparameterisations

Let  $\mathbf{X}_n \sim f(\cdot; \theta^*)$  for  $\theta^* \in \Theta \subseteq \mathbb{R}$  and  $\tau_n := g(\theta)$  be a bijective & continuously differentiable function.

When  $\mathbf{X}_n$  is a regular statistical model we have

$$\sqrt{n\tilde{I}(\tau^*)}(\hat{\tau}_n - \tau^*) \to_{\mathcal{D}(\cdot;\tau^*)} Z \sim \text{Normal}(0,1)$$

which leads to the Confidence Interval

$$\tilde{\mathcal{I}}(\mathbf{X}) := [\tilde{L}(\mathbf{X}), \tilde{U}(\mathbf{X})] \text{ where } \tilde{L}(\mathbf{X}) = \hat{\tau}_n - z_{\alpha/2} \sqrt{\frac{g'(\theta^*)^2}{nI(\theta^*)}} \text{ and } \tilde{U}(\mathbf{X}) = \hat{\tau}_n + z_{\alpha/2} \sqrt{\frac{g'(\theta^*)^2}{nI(\theta^*)}}$$

N.B. This confidence interval is **not** necessarily the same as transforming  $[L(\mathbf{x}), U(\mathbf{x})]$  directly.

**Proposition 2.3 -** Confidence Intervals with unknown variance,  $\sigma^2$ 

When variance,  $\sigma^2$ , is unknown we can define a consistent sequence of estimators  $\{\hat{\sigma}_n^2\}_{n\in\mathbb{N}}$ 

$$\hat{\sigma}_n^2 := \frac{1}{n-1} \sum_{i=1}^n (\mathbf{X}_i - \hat{\mu}_n)^2$$

# **Definition 2.14** - Wald's Approach

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta^*)$  for  $\theta^* \in \Theta \subset \mathbb{R}$ .

Using Wald's Approach we can define a confidence interval for  $\theta^*$  using the asymptotic distribution of the Maximum Likelihood Estimator for  $\theta^*$ .

$$\mathcal{I}(\tau^*) := [L(\mathbf{X}), U(\mathbf{X})] \text{ where } L(\mathbf{x}) := \hat{\theta}_n - z_{\alpha/2} \sqrt{nI(\theta^*)} \text{ and } U(\mathbf{x}) = \hat{\theta}_n + z_{\alpha/2} \sqrt{nI(\theta^*)}$$

N.B. This definition ensures that as  $\mathbb{P}(\theta \in \mathcal{I}(\mathbf{X})) \xrightarrow[n \to \infty]{} 1 - \alpha$ .

# Remark 2.3 - Limitations of Wald's Approach

Let  $\mathcal{I}(\theta^*)$  be a Confidence Interval defined using Wald's Approach.

There are certain limitations of Wald's Approach

- i) It is possible  $\exists \theta \notin \mathcal{I}(\theta^*)$  st  $\exists \theta' \in \mathcal{I}(\theta^*)$  where  $L(\theta; \mathbf{x}) > L(\theta'; \mathbf{x})$ .
- ii) It is possible  $\exists \theta \in \mathcal{I}(\theta^*)$  where  $L(\theta; \mathbf{x}) = 0$ .
- iii) Wald Confidence Intervals are not invariant under reparameterisation.

# **Definition 2.15 -** Confidence Set

Let  $\mathbf{X}_n \stackrel{\text{iid}}{\sim} f_n(\cdot; \theta^*)$  for  $\theta^* \in \Theta$  and  $\hat{\theta}_n$  be an estimator of  $\theta$ .

Confidence Sets for  $\theta^*$  are the possible values of  $\theta$  whoses likelihood is close to that of the Maximum Likelihood Estimate of  $\theta$ .

Confidence Sets are not necessarily contiguous.

$$C(\mathbf{X}_n) := \left\{ \theta \in \Theta : \ell(\hat{\theta}_n; \mathbf{X}_n) - \ell(\theta; \mathbf{X}_n) \le \frac{1}{2} \chi_{1,\alpha}^2 \right\} \subseteq \Theta$$

Confidence Interval sets are asymptotically  $1 - \alpha$  for  $\theta^*$  since

$$\mathbb{P}(\theta^* \in C(\mathbf{X}_n); \theta^*) \xrightarrow[n \to \infty]{} 1 - \alpha$$

N.B. This definition and result are applications of **Definition 2.4** & **Theorem 2.3**.

N.B. Confidence Sets are hard to define explicitly without a computer.

# **Theorem 2.4 -** Confidence Set of Reparameterisation

Let  $\mathbf{X} \sim f(\cdot; \theta^*)$  for  $\theta^* \in \Theta$  and  $\tau := g(\theta)$  where  $g : \Theta \to G$  is a bijection.

Let  $C(\mathbf{x})$  be a confidence set for  $\theta^*$  and  $\tilde{C}(\mathbf{x})$  be a confidence set for  $\tau^*$ . Then

$$\forall \mathbf{x} \in \mathcal{X}^n, \ \theta^* \in \Theta \text{ we have } \theta \in C(\mathbf{x}) \iff g(\theta \in \tilde{C}(\mathbf{x}))$$

$$N.B. \ \tilde{C}(\mathbf{x}) := \Big\{ \theta \in \Theta : \tilde{\ell}_n(\hat{\theta}_n; \mathbf{x}) - \tilde{\ell}(\theta; \mathbf{x}) \leq \frac{1}{2} \chi_{1,\alpha}^2 \Big\}.$$

# **Proof 2.3** - *Theorem 2.4*

Let  $\mathbf{x} \in \chi^n$  be arbitrary.

Everything rests on the observation that

$$\forall \theta \in \Theta, \ \ell(\theta; \mathbf{x}) = \ln f(\mathbf{x}; \theta) = \ln f(\mathbf{x}; g(\theta)) = \tilde{\ell}(g(\theta; \mathbf{x}))$$

and similary

$$\forall \ \tau \in G, \ \tilde{\ell}(\tau; \mathbf{x}) = \ln \tilde{f}(\mathbf{x}; \tau) = \ln f(\mathbf{x}; g^{-1}(\tau)) = \ell(g^{-1}(\tau); \mathbf{x})$$

Note that  $g(\hat{\theta}_n)$  is the Maximum Likelihood Estimate of  $\tau$ .

Assume  $\theta \in C(\mathbf{x})$ . Then

$$-2\left[\ell(\theta; \mathbf{x}) - \ell(\hat{\theta}_n; \mathbf{x})\right] \le \chi_{1,\alpha}^2$$

Thus

$$-2\left[\tilde{\ell}(g(\theta);\mathbf{x}) - \tilde{\ell}(g(\hat{\theta}_n);\mathbf{x})\right] \le \chi_{1,\alpha}^2$$

Thus  $q(\theta \in \tilde{C}(\mathbf{x}))$ .

So 
$$\theta \in C(\mathbf{x}) \implies g(\theta) \in \tilde{C}(\mathbf{x})$$
.

Similarly, assume that  $g(\theta) \in C(\mathbf{x})$ . Thus

$$-2\left[\ell(\theta; \mathbf{x}) - \ell(\hat{\theta}_n; \mathbf{x})\right] \le \chi_{1,\alpha}^2$$

Thus  $\theta \in C(\mathbf{x})$ .

So 
$$\theta \in C(\mathbf{x}) \iff g(\theta) \in \tilde{X}(\mathbf{x})$$
.

For the last part, this correspondence implies that

$$\{\mathbf{x} \in \chi^n; \theta^* \in C(\mathbf{x})\} = \{\mathbf{x} \in \chi^2 : g(\theta^*) \in \tilde{C}(\mathbf{x})\}$$

Thus, we can conclude from the equivalnce of the events

$$\{\theta^* \in C(\mathbf{X}) = \{g(\theta^*) \in \tilde{C}(\mathbf{X})\}\$$

Remark 2.4 - Confidence Set Rule of Thumb

Under the conditions of **Theorem 2.3** there is a rule of thumb that

$$\mathbb{P}(\theta^* \in C(\mathbf{x})) \approx 0.95 \text{ where } C \approx \left\{ \theta \in \Theta : \ell(\hat{\theta}_n; \mathbf{x}) - \ell(\theta; \mathbf{x}) \le 2 \right\}$$

**Definition 2.16** - Wilk's Approach

TODO - Is this just confidence sets?

# 2.4 Convergence

**Definition 2.17 -** Convergence

Let  $\{z_n\}_{n\in\mathbb{N}}$  be a deterministic sequence of real values and  $z\in\mathbb{R}$ .

We say  $\{z_n\}$  converges to limit z if

$$\forall \varepsilon > 0 \exists n_0 \in \mathbb{N} \text{ st } \forall n > n_0 \quad |z_n - z| < \varepsilon$$

*N.B.* This is the same for vectors.

**Definition 2.18 -** Convergence in Probability

Let  $\{Z_n\}_{n\in\mathbb{N}}$  be a sequence of random variables and Z be a random variable in the same probability space.

We say that  $\{Z_n\}_{n\in\mathbb{N}}$  Converges in Probability to Z if

$$\forall \ \varepsilon > 0 \quad \lim_{n \to \infty} \mathbb{P}(|Z_n - Z| > \varepsilon) = 0$$

*N.B.* This is denoted as  $Z_n \to_{\mathbb{P}} Z$ .

**Definition 2.19 -** Convergence in Distribution

Let  $\{Z_n\}_{n\in\mathbb{N}}$  be a sequence of random variables and Z be a random variable, not necessarily in the same probability space.

We say  $\{Z_n\}_{n\in\mathbb{N}}$  Converges in Distribution to Z if

$$\forall z \in Z \text{ where } F_Z(z) \text{ is continuous } \lim_{n \to \infty} F_{Z_n}(z) = F_Z(z)$$

i.e.  $F_{X_n}$  converges in value to  $F_X$  as  $n \to \infty$ .

N.B. This is dentoed as  $Z_n \to_{\mathcal{D}} Z$ .

**Definition 2.20 -** Convergence in Quadratic Mean

Let  $\{Z_n\}_{n\in\mathbb{N}}$  be a sequence of random variables and Z be a random variable, not necessarily in the same probability space.

We say  $\{Z_n\}_{n\in\mathbb{N}}$  Converges in Quadratic Mean to Z if

$$\lim_{n \to \infty} \mathbb{E}\left[ (Z_n - Z)^2 \right] = 0$$

N.B. This is denoted as  $Z_n \to_{\mathrm{qm}} Z$ .

Theorem 2.5 -  $Z_n \rightarrow_{\mathbb{P}} Z \implies Z_n \rightarrow_{\mathcal{D}} Z$ 

Theorem 2.6 -  $Z_n \rightarrow_{qm} Z \implies Z_n \rightarrow_{\mathbb{P}} Z$ 

**Theorem 2.7 -**  $Z_n \to_{\mathbb{P}} a \iff Z_n \to_{\mathcal{D}} a \text{ for } a \in \mathbb{R}$ 

Theorem 2.8 - Continuous Mapping Theorem

Let  $\{Z_n\}_{n\in\mathbb{N}}$  be a sequence of random variabesl and Z be a random variable.

Let  $g:Z\to G$  be a function which maps from the space of random variable Z to a space G. Then

- i) If  $Z_n \to_{\mathbb{P}} Z$  then  $g(Z_n) \to_{\mathbb{P}} g(Z)$ .
- ii) If  $Z_n \to_{\mathcal{D}} Z$  then  $q(Z_n) \to_{\mathcal{D}} q(Z)$ .

Theorem 2.9 - Slutsky's Theorem

Let  $\{Y_n\}_{n\in\mathbb{N}}$  &  $\{Z_n\}_{n\in\mathbb{N}}$  be sequences of random variables, Y be a random variables &  $c\in\mathbb{R}\setminus\{0\}$ . If  $Y_n\to_{\mathcal{D}} Y$  and  $Z_n\to_{\mathcal{D}} c$ . Then

- i)  $Y_n + Z_n \to_{\mathcal{D}} Y + c$ .
- ii)  $Y_n Z_n \to_{\mathcal{D}} Y c$ .
- iii)  $\frac{Y_n}{Z_n} \to_{\mathcal{D}} \frac{Y}{c}$ .

**Definition 2.21 -** Consistent Sequence of Estimators

Let  $\mathbf{X}_n \sim f_n(\cdot; \theta)$  be a random vector and  $\{\hat{\theta}_n(\cdot) : \mathcal{X}^n \to \Theta\}_{n \in \mathbb{N}}$  be a sequence of estimators for  $\theta$ 

We say  $\{\hat{\theta}_n\}$  is Consistent if

$$\forall \ \theta \in \Theta \quad \hat{\theta}_n(\mathbf{X}_n) \to_{\mathbb{P}(\cdot;\theta)} \theta$$

**Theorem 2.10** -  $\hat{\theta}_n \rightarrow_{qm} \theta \implies {\{\hat{\theta}_n\}}$  is consistent

# 2.5 Performance of Estimators

Remark 2.5 - Measuring Performance of an Estimator

We measure the performance of an estimator  $\hat{\theta}$  in terms of variance since its mean should be  $\theta^*$  and is thus a bad measure.

Lower variance indicates better performance.

**Definition 2.22 -** Fisher Information Regularity Conditions

Define  $\Theta \subset \mathbb{R}$  and  $f(x;\theta)$  be a probability mass/density function.

If a model fulfils the following criteria then it is sufficiently regular for  $Fisher\ Information$  to be drawn from it

- i)  $\forall x \in \mathcal{X}$  both  $L'(\theta; x) = \frac{d}{d\theta} f(x; \theta)$  and  $L''(\theta; x) = \frac{d^2}{d\theta^2} f(x; \theta)$  exist.
- ii)  $\forall \theta \in \Theta$  the set  $S := \{x \in \mathcal{X} : f(x; \theta) > 0\}$  is independent of  $\theta \in \Theta$ .
- iii) The idenity below exists

$$\int_{S} \frac{d}{d\theta} f(x;\theta) dx = \frac{d}{d\theta} \int_{S} f(x;\theta) dx = 0$$

N.B. Statistical Models which fulfil all these criteria are described as Regular.

**Definition 2.23 -** Score Function - Single Random Variable

Let  $X \sim f(\cdot; \theta)$  for some  $\theta \in \Theta$  and x be a realisation of X.

The Score Function measures the sensitivity of the likelihood function wrt the parameter it is estimating.

$$\ell'(\theta; x) := \frac{d}{d\theta} \ell(\theta; x) = \frac{\frac{d}{d\theta} f(x; \theta)}{f(x; \theta)}$$

**Definition 2.24** - Score Function - Independent & Identically Distributed Random Variables Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta)$  with  $\theta \in \Theta$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

$$\ell'_n(\theta; \mathbf{x}) := \sum_{i=1}^n \frac{d}{d\theta} \ell(\theta; x_i)$$

**Proof 2.4** - By Regularity Conditions  $\mathbb{E}(\ell'(\theta;X);\theta) = 0 \ \forall \ \theta \in \Theta$ 

$$\mathbb{E}(\ell'(\theta;X);\theta) = \int_{S} \frac{\frac{d}{d\theta}f(x;\theta)}{f(x;\theta)} f(x;\theta) dx$$

$$= \int_{S} \frac{d}{d\theta} f(x;\theta) dx$$

$$= \frac{d}{d\theta} \int_{S} f(x;\theta) dx$$

$$= \frac{d}{d\theta} (1)$$

$$= 0 \ \forall \ \theta \in \Theta$$

**Definition 2.25 -** Fisher Information - Single Random Variable

Let  $X \sim f(\cdot; \theta)$  be an sufficiently regular (see **Definition 2.14**) observable random variable with  $\theta$  unknown.

Fisher Information measures the amount of information X carries about  $\theta$ .

$$I(\theta) := \mathbb{E}(\ell'(\theta; X)^2; \theta)$$
  
=  $Var(\ell'(\theta; X); \theta)$  by **Proof 2.3**

N.B. This is the expectation of the score, squared  $\equiv$  The second moment of the score.

 $\textbf{Definition 2.26 -} \textit{Fisher Information - Independent } \mathcal{E} \textit{ Identically Distributed Random Variables}$ 

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta)$  with  $\theta \in \Theta$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

$$I_n(\theta) := \mathbb{E}(\ell'_n(\theta; \mathbf{X})^2; \theta)$$

$$= \operatorname{Var}(\ell'_n(\theta; \mathbf{X}); \theta)$$

$$= nI(\theta)$$

**Definition 2.27 -** Observed Fisher Information

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} f(\cdot; \theta^*)$  be a random n-dimensional vector.

The Observed Fisher Information at  $\theta$  is

$$nJ_n(\theta) = -\ell''(\theta; \mathbf{X}) = -\sum_{i=1}^n \ell''(\theta; X_i)$$

N.B.  $\mathbb{E}(J_n(\theta^*; \theta^*) = I(\theta^*)$ . This is a deterministic value, not an expectation like Fisher Information.

# **Theorem 2.11 -** Fisher Information of Reparameterisation

Let  $X \sim f(\cdot; \theta)$  for  $\theta \in \Theta \subseteq \mathbb{R}$  and  $\tau := g(\theta)$  be a bijective & continuously differentiable function. Consider the reparameterisation  $\tilde{f}(x;\tau) := f(x;g(\theta)) = f(x;g^{-1}(\tau))$ .

The Fisher Information for this reparameterisation,  $\tilde{f}$  is given by

$$\tilde{I}(\tau) = \frac{I(\theta)}{g'(\theta)^2}$$

# **Proof 2.5** - *Theorem 2.9*

Since  $\tilde{f}(x;\tau) = f(x;g^{-1}(\tau))$  the log-likelihood for tau is

$$\tilde{\ell}(\tau; x) = \ln \tilde{f}(x; \tau) = \ln f(x; g^{-1}(\tau))$$

The score is therefore

$$\tilde{\ell}'(\tau;x) = \frac{d}{d\tau} \ln f(x;g^{-1}(\tau))$$

$$= \frac{d}{d\theta} \ln f(x;g^{-1}(\tau)) \times \frac{d}{d\tau} g^{-1}(\tau)$$

$$= \ell'(g^{-1}(\tau);x) \times \frac{1}{g'(g^{-1}(\tau))}$$

$$= \frac{\ell'(\theta;x)}{g'(\theta)}$$

No we use the definition of Fisher Information

$$\begin{split} \tilde{I}(\tau) &= & \mathbb{E}(\tilde{\ell}'(\tau;X)^2;\tau) \\ &= & \mathbb{E}\left(\frac{\ell'(\theta;X)^2}{g'(\theta)^2};\theta\right) \\ &= & \frac{1}{g'(\theta)^2}\mathbb{E}\left(\ell'(\theta;X)^2;\theta\right) \\ &= & \frac{I(\theta)}{g'(\theta)^2} \end{split}$$

**Theorem 2.12** - Alternative Expression of Fisher Information Let  $X \sim f(\cdot; \theta)$  be a sufficiently regular random variable. Then

if 
$$\forall \theta \in \Theta$$
  $\int_{\mathcal{X}} \frac{d^2}{d\theta^2} f(x;\theta) dx = \frac{d}{d\theta} \int_{\mathcal{X}} \frac{d}{d\theta} f(x;\theta) dx$  then  $I(\theta) = -\mathbb{E}\left(\frac{d^2}{d\theta^2} \ell(\theta;X);\theta\right)$ 

# **Proof 2.6** - *Theorem 2.9*

By the Quotient Rule

$$\frac{d^2}{d\theta^2}\ell(\theta;x) = \frac{d}{d\theta} \frac{\frac{d}{d\theta}f(x;\theta)}{f(x;\theta)}$$
$$= \frac{\frac{d^2}{d\theta^2}f(x;\theta)}{f(x;\theta)} - \left(\frac{\frac{d}{d\theta}f(x;\theta)}{f(x;\theta)}\right)^2$$

Consequently

$$\mathbb{E}\left(\frac{d^2}{d\theta^2}\ell(\theta;X);\theta\right) = \int_S \frac{\frac{d^2}{d\theta^2}f(x;\theta)}{f(x;\theta)}f(x;\theta)dx - \int_S \left(\frac{\frac{d}{d\theta}f(x;\theta)}{f(x;\theta)}\right)^2 f(x;\theta)dx$$

$$= \int_S \frac{d^2}{d\theta^2}f(x;\theta)dx - \int_S \ell'(\theta;x)^2 f(x;\theta)dx$$

$$= 0 - \mathbb{E}(\ell'(\theta;X)^2;\theta)$$

$$= -I(\theta)$$

$$= -I(\theta)$$

$$= -\mathbb{E}\left(\frac{d^2}{d\theta^2}\ell(\theta;X);\theta\right)$$

**Theorem 2.13** - Distribution of Maximum Likelihood Estimators for Regular Models Let  $\mathbf{X}_n \overset{\text{iid}}{\sim} f_n(\cdot; \theta^*)$  be a sufficiently regular statistically model and  $\{\hat{\theta}_n\}_{n\in\mathbb{N}}$  be a consistent sequence of Maximum Likelihood Estimators for  $\theta^*$ . Then

$$\sqrt{nI(\theta^*)}(\hat{\theta}_n - \theta^*) \to_{\mathcal{D}(\cdot;\theta^*)} Z \sim \text{Normal}(0,1)$$

Here  $I(\theta^*)$  is unknown so we replace it with

- i)  $I(\hat{\theta}_n)$  when
  - (a)  $I(\theta)$  is continuous in a neighbourhood of  $\theta^*$ ;
  - (b) And, the interval  $[L(\mathbf{X}), U(\mathbf{X})]$  with  $L(\mathbf{x}) := \hat{\theta}_n z_{\alpha/2} \sqrt{nI(\hat{\theta}_n)}$  and  $U(\mathbf{x}) := \hat{\theta}_n + z_{\alpha/2} \sqrt{nI(\hat{\theta}_n)}$  is an asymptotically exact  $1 \alpha$  confidence interval for  $\theta *$ .
- ii)  $J_n(\hat{\theta}_n) := -\frac{1}{n} \sum_{i=1}^n \ell''(\hat{\theta}_n; X_i)$  when
  - (a)  $\hat{\theta}_n \to_{\mathbb{P}(\cdot;\theta^*)} \theta^*;$
  - (b)  $I(\theta) = -\mathbb{E}(\ell''(\theta; X); \theta) \ \forall \ theta \in \Theta;$
  - (c)  $\exists C: \mathcal{X} \to [0, \infty)$  st  $\mathbb{E}(C(X_1); \theta^*) < \infty$ ,  $\Xi \subset \Theta$  is an open set containing  $\theta^*$  and  $\Delta(\cdot): \Xi \to [0, \infty)$  is continuous at 0 st  $\Delta(0) = 0$ , and st  $\forall \theta, \theta^*, x \in \Xi^2 \times \mathcal{X}$

$$|\ell''(\theta; x) - \ell''(\theta'; x)| \le C(x)\Delta(\theta - \theta')$$

(d) And, the interval  $[L(\mathbf{X}), U(\mathbf{X})]$  with  $L(\mathbf{x}) := \hat{\theta}_n - z_{\alpha/2} \sqrt{nJ_n(\hat{\theta}_n)}$  and  $U(\mathbf{x}) := \hat{\theta}_n + z_{\alpha/2} \sqrt{nJ_n(\hat{\theta}_n)}$  is an asymptotically exact  $1 - \alpha$  confidence interval for  $\theta^*$ 

# Theorem 2.14 - Cramer-Rao Inequality

Let Cramer-Rao Inequality provides us with a lower bound for the performance of all estimators. Let  $\mathbf{X}_n \stackrel{\text{iid}}{\sim} f(\cdot; \theta)$  be a sufficiently regular random vector and  $\hat{\theta}_n(\cdot)$  be an estimator of  $\theta$  with expectation  $m_1(\theta) := \mathbb{E}(\hat{\theta}_n(\mathbf{X}_n); \theta)$ .

if 
$$\forall \theta \in \Theta$$
,  $\underbrace{\frac{d}{d\theta} \int \hat{\theta}_n(\mathbf{x}) f_n(\mathbf{x}; \theta) d\mathbf{x}}_{\mathbb{E}(\hat{\theta}_n)} = \int \hat{\theta}_n(\mathbf{x}) \frac{d}{d\theta} f_n(\mathbf{x}; \theta) d\mathbf{x}$ 

Then

$$\forall \ \theta \in \Theta, \ \operatorname{Var}(\hat{\theta}_n(\mathbf{X}); \theta) \ge \frac{m_1'(\theta)^2}{nI(\theta)}$$

### **Proof 2.7** - Cramer-Rao Inequality

We notice that

$$m'(\theta) = \frac{d}{d\theta} \mathbb{E}(\hat{\theta}_n(\mathbf{X}_n); \theta)$$
  
= 
$$\frac{d}{d\theta} \int_{S^n} \hat{\theta}_n(\mathbf{x}_n) f_n(\mathbf{x}_n; \theta) d\mathbf{x}_n$$

The clever part of this proof is to observe that

$$\begin{aligned} \operatorname{Var}(\hat{\theta}_n(\mathbf{X}_n);\theta) n I(\theta) &= \operatorname{Var}(\hat{\theta}_n(\mathbf{X}_n);\theta) \operatorname{Var}(\ell_n(\theta;\mathbf{X}_n);\theta) \\ &\geq \operatorname{Cov}(\hat{\theta}_n(X_n),\ell_n'(\theta;\mathbf{X}_n);\theta)^2 \text{ by Covariance Inequality} \end{aligned}$$

Thus

$$\operatorname{Cov}(\hat{\theta}_{n}(X_{n}), \ell'_{n}(\theta; \mathbf{X}_{n}); \theta)^{2} = \mathbb{E}(\hat{\theta}_{n}(X_{n})\ell'_{n}(\theta; \mathbf{X}_{n}); \theta) - \mathbb{E}(\hat{\theta}_{n}(\mathbf{X}_{n}); \theta)\mathbb{E}(\ell'_{n}(\theta; \mathbf{X}_{n}); \theta)$$

$$= \mathbb{E}(\hat{\theta}_{n}(X_{n})\ell'_{n}(\theta; \mathbf{X}_{n}); \theta) - \mathbb{E}(\hat{\theta}_{n}(\mathbf{X}_{n}); \theta) \times 0$$

$$= \mathbb{E}(\hat{\theta}_{n}(X_{n})\ell'_{n}(\theta; \mathbf{X}_{n}); \theta)$$

$$= \int_{S^{n}} \hat{\theta}_{n}(\mathbf{x}_{n})\ell'_{n}(\theta; \mathbf{x}_{n})f_{n}(\mathbf{x}_{n}; \theta)d\mathbf{x}_{n}$$

$$= \int_{S^{n}} \hat{\theta}_{n}(\mathbf{x}_{n})\frac{\frac{d}{d\theta}f_{n}(\mathbf{x}_{n}; \theta)}{f_{n}(\mathbf{x}_{n}; \theta)}f_{n}(\mathbf{x}_{n}; \theta)d\mathbf{x}_{n}$$

$$= \int_{S^{n}} \hat{\theta}_{n}(\mathbf{x}_{n})\frac{d}{d\theta}f_{n}(\mathbf{x}_{n}; \theta)$$

$$= \frac{d}{d\theta}\int_{S^{n}} \hat{\theta}_{n}(\mathbf{x}_{n})f_{n}(\mathbf{x}_{n}; \theta)d\mathbf{x}_{n} \text{ by regularity assumption}$$

$$= m'(\theta)$$

$$\Rightarrow \operatorname{Var}(\hat{\theta}_{n}(X_{n}); \theta)nI(\theta) \geq m'(\theta)^{2}$$

**Remark 2.6** - Cramer-Rao Inequality with an Unbiased Estimator Let  $\hat{\theta}_n$  be an unbiased estimator of  $\theta$  (i.e.  $m_1(\theta) = \theta$ ). Then

$$\operatorname{Var}(\hat{\theta}_n(\mathbf{X}_n); \theta) = \operatorname{MSE}(\hat{\theta}_n(\mathbf{X}_n); \theta) \ge \frac{1}{nI(\theta)}$$

# 2.6 Asymptotic Distribution of Estimators

**Theorem 2.15** - Asymptotic Distribution of Maximum Likelihood Estimators Suppose that  $\mathbf{X}_n \stackrel{\text{iid}}{\sim} f(\cdot; \theta^*)$  for some  $\theta^* \in \Theta$  and assume that

- i) The sequence of maximum likelihood estiamtors  $\{\hat{\theta}_n(\mathbf{X}_n)\}\$  is consistent;
- ii) The Fisher Information Regularity Conditions (**Definition 6.2**) hold and  $I(\theta^*) = -\mathbb{E}[\ell''(\theta; X); \theta] > 0$ .
- iii)  $\exists C : \mathcal{X} \to [0, \infty)$  such that  $\mathbb{E}[C(X_1); \theta^*] < \infty$  and  $\Delta : \Xi \to [0, \infty)$ , where  $\Xi \subset \Theta$  st  $\theta^* \in \Xi$ , that is continuous at 0 st  $\Delta(0) = 0$ , such that

$$\forall (\theta, \theta', x') \in \chi^2 \times \mathcal{X}, \quad |\ell''(\theta; x) - \ell(\theta'; x)| \le C(x)\Delta(\theta - \theta')$$

Then  $\forall \ \theta^* \in \Theta$ 

$$\sqrt{nI(\theta^*)}(\hat{\theta}_n(\mathbf{X}_n) - \theta^*) \to_{\mathcal{D}(;\theta^*)} Z \sim \text{Normal}(0,1)$$

**Proof 2.8** - Theorem 2.11

By **Theorem 2.11**  $\ell'_n(\hat{\theta}_n; \mathbf{X}) = \ell'_n(\theta^*; \mathbf{X}) + (\hat{\theta}_n - \theta^*)[\ell''_n(\theta^*; \mathbf{X}) + R_n]$  where  $\frac{1}{n}R_n \to_{\mathbb{P}(\cdot; \theta^*)} 0$ .

Since  $\hat{\theta}_n$  is the maximum likelihood estimator & the Fisher Information Regularity Conditions hold, the score at  $\ell'(\hat{\theta}_n; X) = 0$ .

Hence,  $0 = \ell''(\hat{\theta}_n; X) = \ell'_n(\theta; X) + (\hat{\theta}_n - \theta^*) \{ \ell''(\theta; X) + R_n \}.$ 

Rearranging & rescalling by  $\sqrt{n}$  gives

$$\sqrt{n}(\hat{\theta}_n - \theta^*) = \frac{\frac{1}{\sqrt{n}}\ell'(\theta^*; X)}{-\frac{1}{\sqrt{n}}\{\ell''(\theta^*; X) + R_n} =: \frac{U_n}{V_n - \frac{R_n}{n}}$$

Recall that  $\ell'_n(\theta^*; X) = \sum_{i=1}^n \ell'(\theta; X_i)$  and  $\ell''_n(\theta^*; X) = \sum_{i=1}^n \ell''(\theta^*; X_i)$ .

Since  $\mathbb{E}(\ell'(\theta^*; X_i); \theta^*) = 0$  and  $Var(\ell'(\theta^*; X_i); \theta^*) = I(\theta^*)$ 

 $\implies U_n \to_{\mathcal{D}(\cdot;\theta^*)} U \sim \text{Normal}(0, I(\theta^*))$  by the Central Limit Theorem.

We observed that  $V_n \to_{\mathbb{P}(\cdot;\theta^*)} I(\theta^*)$  by the Weak Law of Large Numbers since  $\mathbb{E}(-\ell''(\theta^*;X_i);\theta^*) = I(\theta^*)$ .

It follows that  $V_n - \frac{1}{n}R_n \to_{\mathbb{P}(\cdot;\theta^*)} I(\theta^*)$  by *Slutsky's Theorem*. Using *Slutsky's Theorem* again

$$\sqrt{n}(\hat{\theta}_n - \theta^*) = \frac{U_n}{V_n - \frac{1}{n}R_n} \to_{\mathcal{D}(\cdot;\theta^*)} \frac{\sqrt{I(\theta^*)}}{I(\theta^*)} Z \text{ where } Z \sim \text{Normal}(0, 1)$$

We can rewrite this as

$$\sqrt{nI(\theta^*)}(\hat{\theta}_n - \theta^*) \to_{\mathcal{D}(\cdot;\theta^*)} Z \sim \text{Normal}(0,1)$$

**Theorem 2.16** - Convergence of Score of Maximum Likelihood Estimators Under the conditions in **Theorem 2.11**, with  $\hat{\theta}_n$  a Maximum Likelihood Estimator

$$\ell'_n(\hat{\theta}_n; \mathbf{X}) = \ell'_n(\theta^*; \mathbf{X}) + (\hat{\theta}_n - \theta^*) [\ell''_n(\theta^*; \mathbf{X}) + R_n]$$

where  $\frac{1}{n}R_n \to_{\mathbb{P}(\cdot;\theta^*)} 0$ .

### **Proof 2.9 -** *Theorem 2.12*

This is an non-examinable, sketch proof of **Theorem 8.2**. By the regularity conditions and the mean alue theorem

$$\frac{\ell'_n(\theta; \mathbf{x}) - \ell'_n(\theta^*; \mathbf{x})}{\theta - \theta^*} = \ell''_n(\tilde{\theta}; \mathbf{x})$$

for some  $\tilde{\theta} \in (\theta, \theta^*)$ . Hence, we deduce that

$$\ell'_{n}(\theta; \mathbf{x}) - \ell'_{n}(\theta^{*}; \mathbf{x}) = (\theta - \theta^{*}) \ell''_{n}(\tilde{\theta}; \mathbf{x})$$

$$= (\theta - \theta^{*}) \{ \ell''_{n}(\theta^{*}; \mathbf{x}) + [\ell''_{n}(\tilde{\theta}; \mathbf{x}) - \ell_{n}(\theta^{*}; \mathbf{x})] \}$$

$$= (\theta - \theta^{*}) \{ \ell''_{n}(\theta; \mathbf{x}) + R_{n}(\theta, \theta^{*}, \mathbf{x}) \}$$

Now we replace  $\theta$  with the maximum likelihood estimator  $\hat{\theta}_n := \hat{\theta}_n(\mathbf{X})$ . We find

$$\ell'(\hat{\theta}_n; \mathbf{X}) = \ell'_n(\theta^*; \mathbf{X}) + (\hat{\theta}_n - \theta^*) \{ \ell''_n(\theta^*; \mathbf{X}) + R_n(\hat{\theta}_n, \theta^*, \mathbf{x}) \}$$

and we need to analyse  $R_n$ .

Since  $\hat{\theta}_n \to_{\mathbb{P}(\cdot;\theta^*)} \theta^*$  we can take n large enough that  $\mathbb{P}(\hat{\theta}_n \in \Xi; \theta^*)$  with arbitrarily high probability.

On the event  $\{\hat{\theta} \in \Xi\}$  and we have  $\{\tilde{\theta}_n \in \Xi\}$  since  $\tilde{\theta}_n \in (\hat{\theta}_n, \theta^*)$  and

$$|\frac{1}{n}R_n| = \frac{1}{n}|\ell_n''(\tilde{\theta}_n; \mathbf{X}) - \ell_n''(\theta^*; \mathbf{X})|$$

$$= \frac{1}{n}\left|\sum_{i=1}^n \ell''(\tilde{\theta}_n; X_i) - \ell''(\theta^*; X_i)\right|$$

$$\leq \frac{1}{n}\sum_{i=1}^n \left|\ell''(\tilde{\theta}_n; X_i) - \ell''(\theta^*; X_i)\right|$$

$$\leq \Delta(\tilde{\theta}_n - \theta^*) \left\{\frac{1}{n}\sum_{i=1}^n C(X_i)\right\}$$

from the smoothness condition on  $\ell''$ .

From the Weak Law of Large Numbers

$$\frac{1}{n} \sum_{i=1}^{n} C(X_i) \to_{\mathbb{P}(\cdot;\theta^*)} \mathbb{E}(C(X_1);\theta^*) < \infty$$

and from the consistency of  $\{\hat{\theta}_n\}$  and  $\{\tilde{\theta}_n\}$  and continuity of  $\Delta(\cdot)$  we have by the *Continuous Mapping Theorem* 

$$\Delta(\tilde{\theta}_n - \theta^*) \to_{\mathbb{P}(\cdot;\theta^*)} 0$$

Hence, 
$$\frac{1}{n}R_n \to_{\mathbb{P}(\cdot;\theta^*)} 0$$

#### 2.6.1 Confidence Intervals

**Theorem 2.17 -** Convergence in Distirbution of Confidence Intervals

Let  $\mathbf{X} \sim f(\cdot; \theta^*)$  with  $\theta \in \Theta$  and define  $\{\hat{\theta}_n\}_{n \in \mathbb{N}}$  be a consistent sequence of estimators of  $\theta^*$ . Suppose that  $\{\hat{\theta}_n\}$  is asymptotically normal in the sense that

$$\exists \sigma^2 > 0 \text{ st } \frac{\hat{\theta}_n(\mathbf{X}) - \theta^*}{\sqrt{\sigma^2/n}} \to_{\mathcal{D}(\cdot;\theta^*)} Z \sim \text{Normal}(0,1)$$

Then

 $\forall \alpha \in (0,1), \mathcal{I}_n(\mathbf{X}) - [L_n(\mathbf{X}), U_n(\mathbf{X})]$  is an asymptotically exact  $1 - \alpha$  condifence interval

where 
$$L_n(\mathbf{x}) := \hat{\theta}_n(\mathbf{x}) - z_{\alpha/2} \sqrt{\frac{\sigma^2}{n}}$$
 and  $U_n(\mathbf{x}) := \hat{\theta}(\mathbf{x}) + z_{\alpha/2} \sqrt{\frac{\sigma^2}{n}}$ .

**Proof 2.10 -** Theorem 2.13 Let  $\{W_n\}_{n\in\mathbb{N}}$  be defined by  $W_n := \frac{\hat{\theta}_n(X) - \theta^*}{\sqrt{\sigma^2/n}}$ .

Since  $W_n \to_{\mathcal{D}(\cdot;\theta^*)} Z \sim \text{Normal}(0,1)$  we have

$$\mathbb{P}(-z_{\alpha/2} \le W_n \le z_{\alpha/2}) = F_{W_n}(z_{\alpha/2}) - F_{W_n}(-z_{\alpha/2})$$

$$\underset{n \to \infty}{\longrightarrow} \Phi(z_{\alpha/2}) - \Phi(-z_{\alpha/2})$$

$$= 1 - \alpha$$

Similary to before we have the equivalence of events

$$\{-z_{\alpha/2} \le W_n \le z_{\alpha/2}\} = \left\{\hat{\theta}_n - z_{\alpha/2} \frac{\sigma}{\sqrt{n}} \le \theta^* \le \hat{\theta}_n + z_{\alpha/2} \frac{\sigma}{\sqrt{n}}\right\}$$

So 
$$\lim_{n\to\infty} \mathbb{P}\left(\hat{\theta}_n(X) - z_{\alpha/2} \frac{\sigma}{\sqrt{n}} \le \theta^* \le \hat{\theta}_n(X) + z_{\alpha/2} \frac{\sigma}{\sqrt{n}}; \theta^*\right) = 1 - \alpha.$$

#### 2.7 **Efficiency of Estimators**

**Definition 2.28 -** Efficient Estimator

Let  $\hat{\theta}$  be an estimator of parameter  $\theta$ .

 $\hat{\theta}$  is said to be an Efficient Estimator if its variance is equal to the Craner-Rao Lower Bound  $\forall \theta^*$ .

$$\forall \ \theta^*, \ \operatorname{Var}(\hat{\theta}; \theta^*) = \frac{m'(\theta^*)^2}{nI(\theta)}$$

**Definition 2.29 -** Asymptotically Efficient Sequence of Estimators

Let  $\mathbf{X} \sim f(\cdot; \theta)$  for  $\theta \in \Theta$  and  $\{\theta_n(\mathbf{X})\}_{n \in \mathbb{N}}$  be a sequence of estimators.

The sequence  $\{\hat{\theta}_n\}$  is Asymptotically Efficient if either

i) its Mean-Squared Error converges in value to the Cramer-Rao Lower Bound

$$\forall \ \theta \in \Theta, \ n \text{MSE}(\hat{\theta}_n(\mathbf{X}_n); \theta) \xrightarrow[n \to \infty]{} \frac{1}{I(\theta)}$$

ii) Or,  $\hat{\theta}_n$  Converges in Distribution to a standard Normal

$$\forall \theta \in \Theta, \ \sqrt{nI(\theta)}(\hat{\theta} - \theta) \rightarrow_{\mathcal{D}(\cdot;\theta)} Z \sim \text{Normal}(0,1)$$

Remark 2.7 - Under the conditions of Theorem 2.11 Maximum Likelihood Estimators are Asymptotically Efficient

# 0 Appendix

### 0.1 Notation

# Notation 0.1 - Convergence

 $\{z_n\}_{n\in\mathbb{N}}\to z$  denotes that the sequence of deterministic values  $\{z_n\}_{n\in\mathbb{N}}$  converges in <u>value</u> to  $z\in\mathbb{R}$ .

 $\{Z_n\}_{n\in\mathbb{N}}\to_{\mathbb{P}} Z$  denotes that the sequence of random variables  $\{Z_n\}_{n\in\mathbb{N}}$  converges in <u>probability</u> to random variable Z.

 $\{Z_n\}_{n\in\mathbb{N}} \to_{\mathbb{P}(\cdot;\theta)} Z$  denotes that the sequence of random variables  $\{Z_n\}_{n\in\mathbb{N}}$  converges in <u>probability</u> to random variable Z, dependent upon parameter  $\theta$ .

 $\{Z_n\}_{n\in\mathbb{N}}\to_{\mathcal{D}} Z$  denotes that the sequence of random variables  $\{Z_n\}_{n\in\mathbb{N}}$  converges in <u>distribution</u> to random variable Z.

### Notation 0.2 - Gamma Function

$$\Gamma(x) := \int_0^\infty t^{x-1} e^{-t} dt$$

### 0.2 Definitions

# **Definition 0.1 -** Correlation

LEt X & Y be random variables.

Correlation is a measure of dependence between two random variables

$$\operatorname{Corr}(X,Y) := \frac{\operatorname{Cov}(X,Y)}{\sqrt{\operatorname{Var}(X)\operatorname{Var}(Y)}} \in [-1,1]$$

### **Definition 0.2 -** Covariance

Covariance is a measures the joint variability of two random variables.

Consider random variable X & Y

$$Cov(X, Y) = \mathbb{E}[(X - \mathbb{E}(X))(Y - \mathbb{E}(Y))] = \mathbb{E}(XY) - \mathbb{E}(X)\mathbb{E}(Y)$$

If X & Y are independent then Cov(X, Y) = 0.

By definition of Covaraince Cov(X, X) = Var(X).

# **Definition 0.3 -** Estimation

Let  $\mathbf{X} \sim f_n(\cdot; \theta^*)$  with  $\theta^* \in \Theta$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

As Estimation of model parameter  $\theta^*$  is a statistic,  $\hat{\theta}(\mathbf{x}) = T(\mathbf{x})$ , which is indtended to approximated the true value of  $\theta^*$ .

N.B. Interchangeable with Estimate.

# **Definition 0.4 -** Estimator

Let  $\mathbf{X} \sim f_n(\cdot; \theta^*)$  with  $\theta^* \in \Theta$  and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ .

An Estimator of model paramter  $\theta^*$  is the random variable  $\hat{\theta} := \hat{\theta}(\mathbf{X})$  where  $\hat{\theta}(\mathbf{x})$  is an estimation of  $\theta^*$ .

### **Definition 0.5 -** Expectation

Expectation is the mean value for a random variable.

Consider continuous random variable X with pdf  $f_X$  and discrete random variable Y with pmf  $f_Y$ . Then

$$\mathbb{E}(X) := \int_{\mathbb{R}} x f_X(x) dx$$
 and  $\mathbb{E}(Y) := \sum_{y \in \mathcal{Y}} y p_Y(y)$ 

For a function  $g: \mathbb{R} \to \mathbb{R}$  we have

$$\mathbb{E}(g(X)) := \int_{\mathbb{R}} g(x) f_X(x) dx \quad \text{and} \quad \mathbb{E}(g(Y)) := \sum_{y \in \mathcal{Y}} g(y) p_Y(y)$$

For linear transformations of a random variable Z we find

$$\mathbb{E}(aZ + b) = a\mathbb{E}(Z) + b \quad \text{for } a, b \in \mathbb{R}$$

# **Definition 0.6 -** Five-Number Summary

The Five-Number Summary of a sample contains the sample's: median; lower hinge; upper hinge; minimum value; & maximum value.

# **Definition 0.7 -** *Hinges*

Hinges describe the spread of data in a sample, while trying to ignore extreme data. The Lower Hinge,  $H_1$ , is the median of the set containing the median & values with rank <u>less</u> than the sample median. The Upper Hinge,  $H_3$ , is the median of the set containing the median & values with rank greater than the sample median.

### **Definition 0.8** - Median

The *Median* is the central value of a data set.

Consider a data set  $x_0, \ldots, x_n$ 

- If  $\exists m \in \mathbb{N}$  st n = 2m + 1 (i.e. n is odd) then the median is  $x_{(m+1)}$ .
- Else  $\exists m \in \mathbb{N} \text{ st } n = 2m \text{ (i.e. } n \text{ is even) then the median is } x_{(m+1)}$ .

### **Definition 0.9 - Moments**

The *Moments* of a random variable X are the expected values of powers of X.

$$n^{\text{th}}$$
 moment of  $X := \mathbb{E}(X^n)$ 

N.B.  $\mathbb{E}(X^n) \neq \mathbb{E}(X)^n$ .

### **Definition 0.10 -** Order Statistic

An *Order Statistic* is a data set where the data has been placed in increasing order of value, not time. We use  $x_{(i)}$  to denote the  $i^{\text{th}}$  lowest value in  $(x_0, \ldots, x_n)$ .

### **Definition 0.11 -** Quartiles

Quartiles describe the spread of data in a sample. The Lower Quartile,  $Q_1$ , is the median of the set of values with rank <u>less</u> than the sample median. The Upper Quartile,  $Q_3$ , is the median of the set of values with rank greater than the sample median.

N.B. These sets do <u>not</u> contain the median.

### **Definition 0.12** - Sample Mean

The Sample Mean is the mean value of all data points within a sample. Consider a sample  $\{x_1, \ldots, x_n\}$ 

$$\bar{x} := \frac{1}{n} \sum_{i=1}^{n} x_i$$

### **Definition 0.13 -** Sample Variance

Sample Variance is a measure of spread of data in a sample around the sample mean. For a sample  $\{x_1, \ldots, x_n\}$ 

$$s^{2} := \frac{1}{n-1} \sum_{i=1}^{n} (x_{i} - \bar{x})^{2} = \frac{1}{n-1} \left( \left( \sum_{i=1}^{n} x_{i}^{2} \right) - n\bar{x}^{2} \right)$$

### **Definition 0.14 -** Statistic

Let  $\mathbf{x}$  be some data.

A Statistic is any function of the data,  $T(\mathbf{x})$ .

N.B. Statistics are independent of unknown model parameters.

# **Definition 0.15 -** Trimmed Sample Mean

The Trimmed Sample Mean is the average value of a subset of data points within a sample. The subset is defined to ignore the  $\frac{\Delta}{2}\%$  largest & smallest values of the sample. For a  $\Delta\%$  trimmed mean we define

$$\bar{x}_{\Delta} := \frac{1}{n-2k} \sum_{i=k+1}^{n-k-1} x_i \text{ with } k = \left\lfloor \frac{n\Delta}{100} \right\rfloor$$

### **Definition 0.16 -** Variance

Variance measures how far a set of random numbers are spread from their average value. Consider random variable X

$$Var(X) := \mathbb{E}[(X - \mathbb{E}(X))^2] = \mathbb{E}(X^2) - \mathbb{E}(X)^2$$

For linear transformation of a random variable X we find

$$Var(aX + b) = a^2 Var(X)$$

For a linear transformation of two random variables X & Y we abve

$$Var(aX + bY) = a^2 Var(X) + b^2 Var(Y) + 2abCov(X, Y)$$
 for  $a, b \in \mathbb{R}$ 

### **Definition 0.17 - Skew**

Skew describes the spread of values in a sample which are less than the median, relative to the spread of values greater than the median. A sample is Left-Skewed if  $|H_3 - H_2| < |H_1 - H_2|$ . A sample is Right-Skewed if  $|H_3 - H_2| > |H_1 - H_2|$ .

### 0.3 Theorems

Theorem 0.1 - Cauchy-Scwarz Inequality

Let X & Y be real-valued random variables in the same probability space. Then

$$\mathbb{E}(XY)^2 \le \mathbb{E}(X^2)\mathbb{E}(Y^2)$$

Theorem 0.2 - Chebyshev's Inequality

Let X be a random variable.

Define  $\mu := \mathbb{E}(X)$  and  $\sigma^2 := \operatorname{Var}(X)$ . Then

$$\forall a > 0 \quad \mathbb{P}(|X - \mu| \ge a) \le \frac{\sigma^2}{a^2}$$

**Theorem 0.3** - Covariance Inequality

Let X & Y be real-valued random variables in teh same probability space. Then

$$Cov(X, Y)^2 \le Var(X)Var(Y)$$

Theorem 0.4 - Joint Probability Density of Simple Random Sample

Let  $\mathbf{X}_1, \ldots, X_n$  be a set of <u>independent</u> random variables with pdfs  $f_{X_1}, \ldots, f_{X_n}$ , respectfully,

and  $x_1, \ldots, x_n$  be a realisation of  $X_1, \ldots, X_n$ . The probability of obtaining  $x_1, \ldots, x_n$  is

$$f_{X_1,...,X_n}(x_1,...,x_n) = \prod_{i=1}^n f_{X_i}(x_i;\theta)$$

Theorem 0.5 - Markov's Inequality

Let  $X \sim f_X(\cdot)$  be a non-negative continuous random variable. Then

$$\forall \ a > 0 \quad \mathbb{P}(X \ge a) \le \frac{\mathbb{E}(X)}{a}$$

# 0.4 Probability Distributions

**Definition 0.18 -** Bernoulli Distribution

Let  $X \sim \text{Bernoulli}(p)$ .

A discrete random variable which takes 1 with probability p & 0 with probability (1-p). Then

$$p_X(k) = \begin{cases} 1-p & \text{if } k = 0 \\ p & \text{if } k = 1 \\ 0 & \text{otherwise} \end{cases}$$

$$P_X(k) = \begin{cases} 0 & \text{if } k < 0 \\ 1-p & \text{if } k \in [0,1) \\ 1 & \text{otherwise} \end{cases}$$

$$\mathbb{E}(X) = p$$

$$\text{Var}(X) = p(1-p)$$

$$\mathcal{M}_X(t) = (1-p) + pe^t$$

N.B. Often we define q := 1 - p for simplicity.

**Definition 0.19 -** Binomial Distribution

Let  $X \sim \text{Binomial}(n, p)$ .

A discrete random variable modelled by a Binomial Distribution on n independent events and rate of success p.

$$p_X(k) = \binom{n}{k} p^k (1-p)^{n-k}$$

$$P_X(k) = \sum_{i=1}^k \binom{n}{i} p^i (1-p)^{n-i}$$

$$\mathbb{E}(X) = np$$

$$Var(X) = np(1-p)$$

$$\mathcal{M}_X(t) = [(1-p) + pe^t]^n$$

N.B. If  $Y := \sum_{i=1}^{n} X_i$  where  $\mathbf{X} \stackrel{\text{iid}}{\sim} \text{Bernoulli}(p)$  then  $Y \sim \text{Binomial}(n, p)$ .

**Definition 0.20 -**  $\chi^2$  *Distribution* 

Let  $X \sim \chi_r^2$ .

A continuous random variable modelled by the  $\chi^2$  Distribution with r degrees of freedom. Then

$$f_X(x) = \frac{1}{2^{r/2}\Gamma(r/2)} x^{\frac{r}{2}-1} e^{-\frac{x}{2}}$$

$$F_X(x) = \frac{1}{\Gamma(k/2)} \gamma\left(\frac{r}{2}, \frac{x}{2}\right)$$

$$\mathbb{E}(X) = r$$

$$Var(X) = 2r$$

$$\mathcal{M}_X(t) = \mathbb{1}\{t < \frac{1}{2}\}(1-2t)^{-\frac{r}{2}}$$

N.B. If  $Y := \sum_{i=1}^k Z_i^2$  with  $\mathbf{Z} \stackrel{\text{iid}}{\sim} \text{Normal}(0,1)$  then  $Y \sim \chi_k^2$ .

# **Definition 0.21 -** Exponential Distribution

Let  $X \sim \text{Exponential}(\lambda)$ .

A continuous random variable modelled by a Exponential Distribution with rate-parameter  $\lambda$ . Then

$$f_X(x) = \mathbb{1}\{t \ge 0\}.\lambda e^{-\lambda x}$$

$$F_X(x) = \mathbb{1}\{t \ge 0\}.\left(1 - e^{-\lambda x}\right)$$

$$\mathbb{E}(X) = \frac{1}{\lambda}$$

$$Var(X) = \frac{1}{\lambda^2}$$

$$\mathcal{M}_X(t) = \mathbb{1}\{t < \lambda\}\frac{\lambda}{\lambda - t}$$

N.B. Exponential Distribution is used to model the wait time between decays of a radioactive source.

# **Definition 0.22 -** Gamma Distribution

Let  $X \sim \Gamma(\alpha, \beta)$ .

A continuous random variable modelled by a Gamma Distribution with shape parameter  $\alpha > 0$  & rate parameter  $\beta$ . Then

$$f_X(x) = \frac{1}{\Gamma(\alpha)} \beta^{\alpha} x^{\alpha - 1} e^{-\beta x}$$

$$F_X(x) = \frac{\Gamma(\alpha)}{\gamma} (\alpha, \beta x)$$

$$\mathbb{E}(X) = \frac{\alpha}{\beta}$$

$$Var(X) = \frac{\alpha}{\beta^2}$$

$$\mathcal{M}_X(t) = \mathbb{1}\{t < \beta\} \left(1 - \frac{t}{\beta}\right)^{-\alpha}$$

N.B. There is an equivalent definition of a  $Gamma\ Distribution$  in terms of a shape & scale parameter. The scale parameter is 1 over the rate parameter in this definition.

### **Definition 0.23 -** Normal Distribution

Let X be a continuous random variable modelled by a Normal Distribution with mean  $\mu$  & variance  $\sigma^2$ .

Then

$$f_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

$$F_X(x) = \frac{1}{\sqrt{2\pi\sigma^2}} \int_{-\infty}^x e^{-\frac{(y-\mu)^2}{2\sigma^2}} dy$$

$$\mathbb{E}(X) = \mu$$

$$Var(X) = \sigma^2$$

$$\mathcal{M}_X(\theta) = e^{\mu\theta + \sigma^2\theta^2(1/2)}$$

# **Definition 0.24** - Pareto Distribution

Let  $X \sim \text{Pareto}(x_0, \theta)$ .

A continuous random variable modelled by a Pareto Distribution with minimum value  $x_0$  &

shape parameter  $\alpha > 0$ . Then

$$f_X(x) = \frac{\alpha x_0^{\alpha}}{x^{\alpha+1}}$$

$$F_X(x) = 1 - \left(\frac{x_0}{x}\right)^{\alpha}$$

$$\mathbb{E}(X) = \begin{cases} \infty & \alpha \le 1 \\ \frac{\alpha x_0}{\alpha - 1} & \alpha > 1 \end{cases}$$

$$\text{Var}(X) = \begin{cases} \infty & \alpha \le 2 \\ \frac{x_0^2 \alpha}{(\alpha - 1)^2 (\alpha - 2)} & \alpha > 2 \end{cases}$$

$$\mathcal{M}_X(t) = 1 \{ t < 0 \} \alpha (-x_0 t)^{\alpha} \Gamma(-\alpha, -x_0 t) \}$$

# **Definition 0.25 -** Poisson Distribution

Let  $X \sim \text{Poisson}(\lambda)$ .

A discrete random variable modelled by a Poisson Distribution with rate parameter  $\lambda$ . Then

$$p_X(k) = \frac{e^{-\lambda}\lambda^k}{k!} \quad \text{for } k \in \mathbb{N}_0$$

$$P_X(k) = e^{-\lambda} \sum_{i=1}^k \frac{\lambda^i}{i!}$$

$$\mathbb{E}(X) = \lambda$$

$$\text{Var}(X) = \lambda$$

$$\mathcal{M}_X(t) = e^{\lambda(e^t - 1)}$$

N.B. Poisson Distribution is used to model the number of radioactive decays in a time period.

### **Definition 0.26 -** t-Distribution

Let  $X \sim t_r$ .

A *continuous* random variable with r degrees of freedom. Then

$$f_X(k) = \frac{\Gamma\left(\frac{\nu+1}{2}\right)}{\sqrt{\nu\pi}\Gamma\left(\frac{\nu}{2}\right)} \left(1 + \frac{x^2}{\nu}\right)^{-\frac{\nu+1}{2}}$$

$$\mathbb{E}(X) = \begin{cases} 0 & \text{if } \nu > 1\\ \text{undefined otherwise} \end{cases}$$

$$\text{Var}(X) = \begin{cases} \frac{\nu}{\nu-2} & \text{if } \nu > 2\\ \infty & 1 < \nu \leq 2\\ \text{undefined otherwise} \end{cases}$$

$$\mathcal{M}_X(t) = \text{undefined}$$

N.B. Let  $Y \sim \text{Normal}(0,1)$  &  $Z \sim \chi_r^2$  be independent random variables then  $X := \frac{Y}{\sqrt{Z/r}} \sim t_r$ .

**Definition 0.27 -** Uniform Distribution - Uniform Let  $X \sim \text{Uniform}(a, b)$ .

A continuous random variable with lower bound a & upper bound b. Then

$$f_X(x) = \begin{cases} \frac{1}{b-a} & x \in [a,b] \\ 0 & \text{otherwise} \end{cases}$$

$$F_X(x) = \begin{cases} 0 & x < a \\ \frac{x-a}{b-a} & x \in [a,b] \\ 1 & \text{otherwise} \end{cases}$$

$$\mathbb{E}(X) = \frac{1}{2}(a+b)$$

$$\text{Var}(X) = \frac{1}{12}(b-a)^2$$

$$\mathcal{M}_X(t) = \begin{cases} \frac{e^{tb} - e^{ta}}{t(b-a)} & t \neq 0 \\ 1 & t = 0 \end{cases}$$

### 0.5 Identities

### 0.5.1 Likelihood

# Proposition 0.1 - Binomial

Let  $X \sim \text{Binomial}(n, p)$  with n & p unknown and x be a realisation of X. Then

$$\begin{array}{rcl} L(n,p;x) & \propto & \binom{n}{x} p^x (1-p)^{n-x} \\ \ell(n,p;\mathbf{x}) & = & \ln \binom{n}{x} + x \ln p + (n-x) \ln (1-p) + C \\ \hat{n}_{\text{MLE}} & = & \frac{x}{\hat{p}} \\ \hat{p}_{\text{MLE}} & = & \frac{x}{\hat{n}} \end{array}$$

# Proposition 0.2 - Normal

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} \text{Normal}(\mu, \sigma^2)$  with  $\mu \& \sigma^2$  unknown and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ . Then

$$L(\mu, \sigma^{2}; \mathbf{x}) \propto (\sigma^{2})^{-\frac{n}{2}} \exp\left(-\frac{1}{2\sigma^{2}} \sum_{i=1}^{n} (x_{i} - \mu)^{2}\right)$$

$$\ell(\mu, \sigma^{2}; \mathbf{x}) = -n \ln \sigma^{2} - \frac{1}{\sigma^{2}} \sum_{i=1}^{n} (x_{i} - \mu)^{2} + C$$

$$\hat{\mu}_{\text{MLE}} = \bar{\mathbf{x}}$$

$$\hat{\sigma}_{\text{MLE}}^{2} = \frac{1}{n} \sum_{i=1}^{n} (x_{i} - \hat{\mu})^{2}$$

# Proposition 0.3 - Poisson

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} \text{Poisson}(\lambda)$  with  $\lambda$  unknown and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ . Then

$$L(\lambda; \mathbf{x}) \propto e^{-\lambda n} \lambda^{n\bar{x}}$$

$$\ell(\lambda; \mathbf{x}) = -\lambda_n + n\bar{x} \ln \lambda + C$$

$$\hat{\lambda}_{\text{MLE}} = \bar{x}$$

# Proposition 0.4 - Uniform

Let  $\mathbf{X} \stackrel{\text{iid}}{\sim} \text{Uniform}(a, b)$  with a & b unknown and  $\mathbf{x}$  be a realisation of  $\mathbf{X}$ . Then

$$L(a, b; \mathbf{x}) \propto \begin{cases} \frac{1}{(b-a)^n} & a \leq x_i \leq b \ \forall \ x_i \in \mathbf{x} \\ 0 & \text{otherwise} \end{cases}$$

$$\ell(a, b; \mathbf{x}) = \begin{cases} -\ln(b-a) & a \leq x_i \leq b \ \forall \ x_i \in \mathbf{x} \\ 0 & \text{otherwise} \end{cases}$$

$$\hat{a}_{\text{MLE}} = \min\{x_i : x_i \in \mathbf{x}\}$$

$$\hat{b}_{\text{MLE}} = \max\{x_i : x_i \in \mathbf{x}\}$$