

# A Switching Kalman Filter for Modeling Classical Music Performances

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## Why?

- Easy to describe musical characteristics you like: “up-tempo,” “strong beat,” “good lyrics,” “jazzy,” etc.
- Harder to describe characteristics of a **performance** that you like.
- In classical music, there are hundreds or thousands of recordings of the **same** piece.
- Why do we like some better than others?

## What’s different?

1. Mistakes
2. Extraneous noise
3. Recording quality
4. Articulation/Legato/Bowing/Breathing
5. Dynamics
6. Rubato/Tempo

The first three are mostly uninteresting, but the rest are about **interpretation**.

We like performances with “better” interpretations.

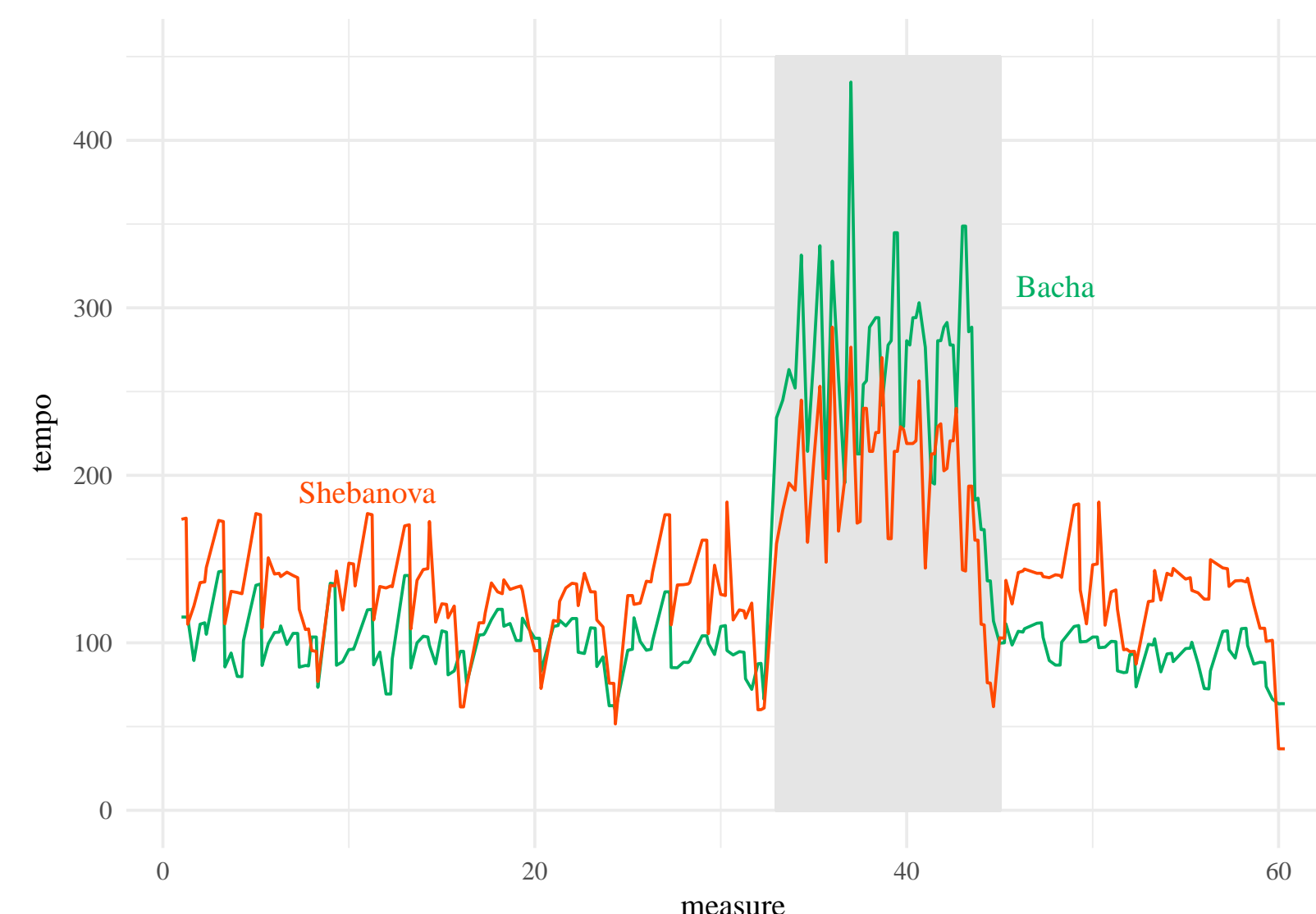


## Piano music

- Can focus on **dynamics** and **tempo**
- We have quantitative data on **everything** from a specially equipped piano.
- This piano records keystroke velocity, pedaling, timing, duration.
- It lives in a studio at the IU Jacobs School of Music.

## Data

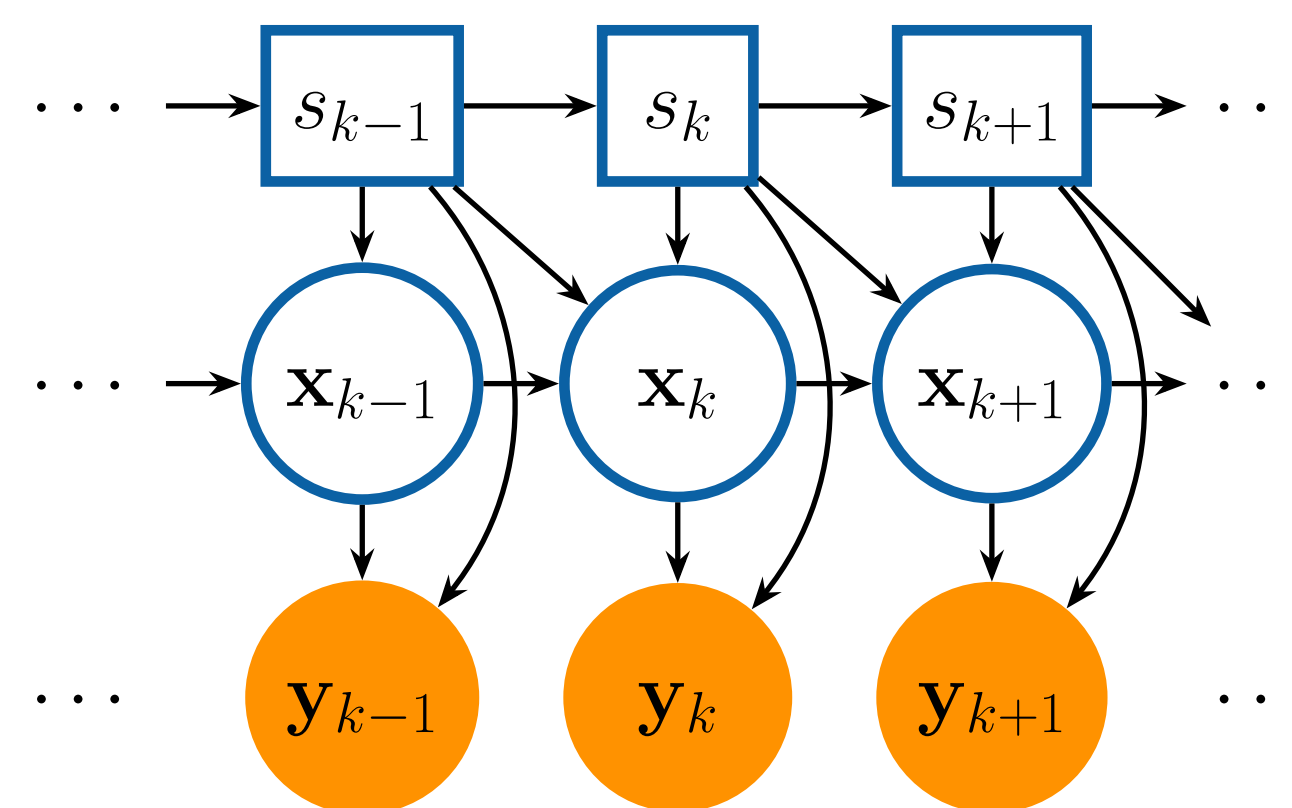
- CHARM Mazurka Project
- Focus on timing only (dynamics also available)
- 50 recordings: Chopin Mazurka Op. 68 No. 3
- Recorded between 1931 and 2006
- 45 different performers



measure 1 9 17 25 | 33 37 41 | 45 53 |  
section a a' b a' | pedal c c' | a a' |

**Allegro ma non troppo.** (♩ = 132.)

## Switching Kalman filter



Intentional tempo

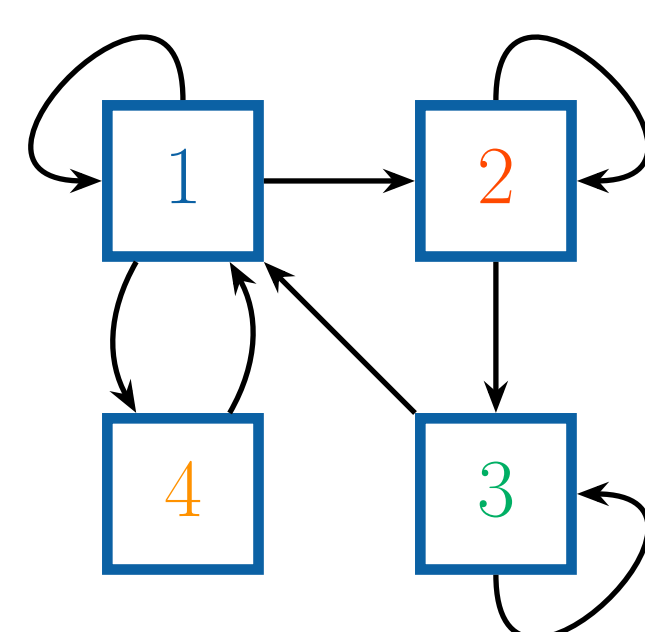
$$x_t = d(s_t, s_{t-1}) + T(s_t, s_{t-1})x_t + R(s_t, s_{t-1})\eta_t$$

Observed tempo

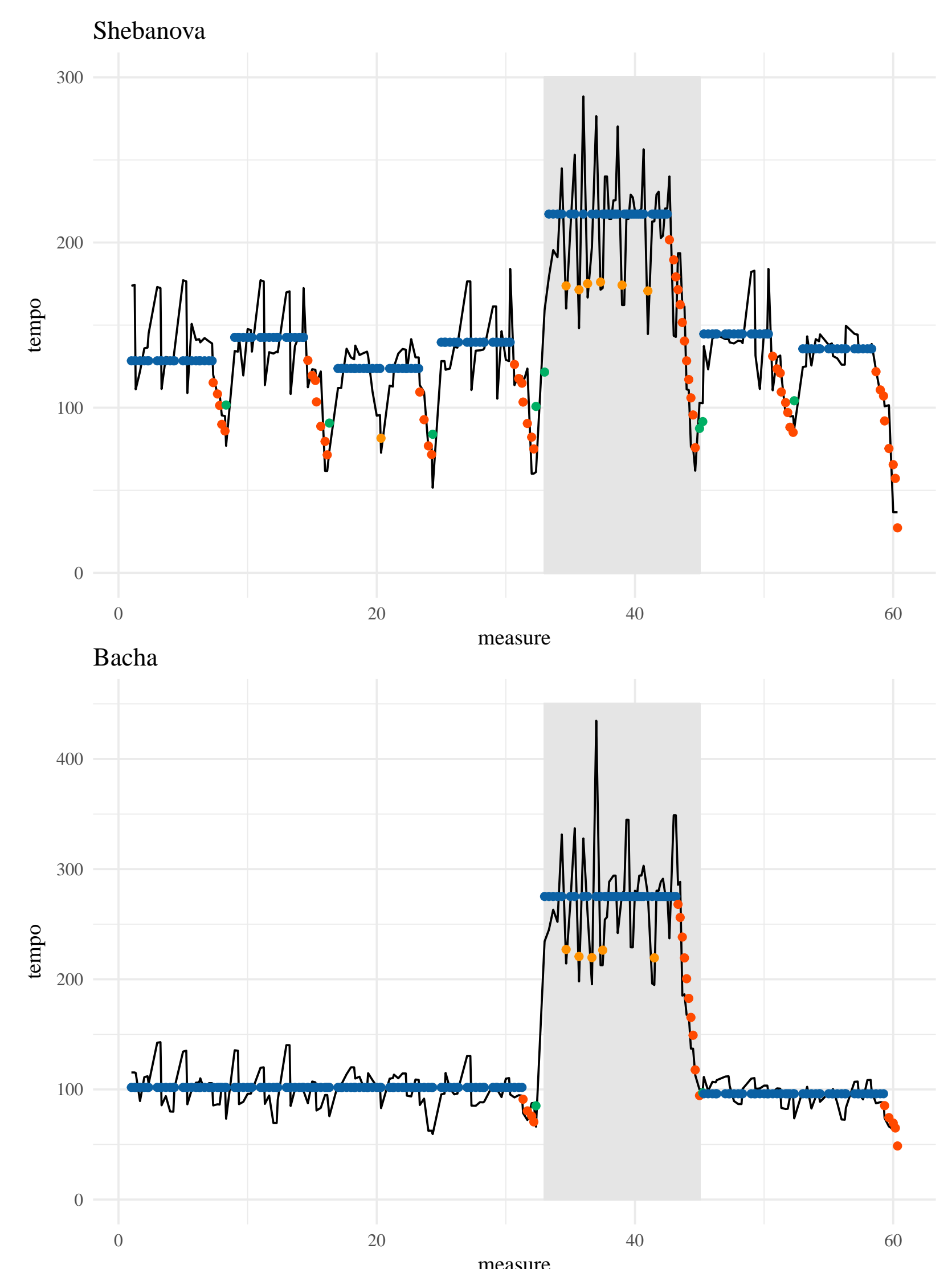
$$y_t = c(s_t) + Z(s_t)x_t + \epsilon_t$$

Error distribution

$$\eta_t \sim N(0, Q(s_t, s_{t-1})) \quad \epsilon_t \sim N(0, G(s_t))$$



1. Constant tempo
2. Slowing down
3. Speeding up
4. Tenuto (emphasis)



## Algorithm (Greedy discrete particle filter)

- 1: **Input:** A distribution  $w$  on  $S_0$ . Parameters of matrices. Number of particles  $B$ .
- 2: **for**  $t = 1$  **to**  $N$  **do**
- 3: For each current path, calculate the 1-step likelihood for moving to each potential  $S_t$
- 4: Multiply the likelihood by the transition probability  $p(S_{t-1}, S_t)$
- 5: Multiply by weights  $w$
- 6: If  $\|w\|_0 > B$ , resample to  $B$  non-zero weights and renormalize
- 7: Keep only those paths corresponding to the non-zero weights
- 8: **end for**
- 9: Return path with largest weight  $w$ .

## Future work

- Using dynamic information
- Bayesian hierarchical clustering
- Musical structure recovery
- Looking at tempo tracks for multiple recordings displays obvious structure
- Testing in real people

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