

The lasso, persistence, and cross-validation

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THE QUESTION:

All the results about lasso are for oracle tuning parameter. What happens if you choose it using the data?

The answer: YES!

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THE MOTIVATION:

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THE SETUP

Suppose we have data

$$\mathcal{D}_n = \{(Y_1, X_1^\top), \dots, (Y_n, X_n^\top)\}$$

where

- $X_i = (X_{i1}, \dots, X_{ip})^\top \in \mathbb{R}^p$ are the features
- $Y_i \in \mathbb{R}$ are the responses

We use \mathcal{D}_n to find a function \hat{f} that can predict Y from X .

The **regression function** is the best possible function

$$m(X) = \mathbb{E}[Y|X] = \underset{f}{\operatorname{argmin}} \mathbb{E}[(Y - f(X))^2]$$

PARAMETERIZING THIS RELATIONSHIP

A good start is to find the best **linear** approximation of $m(X)$.

A linear predictor specifies a $\beta \in \mathbb{R}^p$ and forms

$$\hat{f}(X) = X_1^\top \beta_1 + \dots + X_p^\top \beta_p = X^\top \beta$$

Important: This does not assume that m is linear in X !

We need to find a good estimator of β .

The lasso

Of course, for large p , small n , we need to regularize

Known as

- ‘lasso’
- ‘basis pursuit’

The estimator satisfies

$$\hat{\beta}_t = \underset{\beta}{\operatorname{argmin}} ||\mathbb{Y} - \mathbb{X}\beta||_2^2 \text{ subject to } ||\beta||_1 \leq t$$

Alternatively:

$$\hat{\beta}_\lambda = \underset{\beta}{\operatorname{argmin}} ||\mathbb{Y} - \mathbb{X}\beta||_2^2 + \lambda ||\beta||_1$$

SOME PROPERTIES

Suppose $m(X)$ IS linear, p is small¹...

- If $\lambda = o(n)$, then $\hat{\beta}_\lambda \xrightarrow{\text{a.s.}} \beta$
- If $\frac{\lambda}{n} \rightarrow a \in (0, \infty)$, then $\hat{\beta}_\lambda \nrightarrow \beta$ in general
- If $\frac{\lambda}{n} \rightarrow \infty$, then $\hat{\beta}_\lambda \xrightarrow{\text{a.s.}} 0$
- If $\lambda = o(\sqrt{n})$, then $\sqrt{n} \|\hat{\beta}_\lambda - \beta\| \xrightarrow{d} A$, A is a random variable.

¹ Knight and Fu (2000), Chatterjee and Lahiri (2011)

DIFFERENT PROPERTIES

What if $m(X)$ is not linear, $p \gg n \dots$?

Define $\mathcal{Z}^\top = (\mathcal{Y}, \mathcal{X}^\top)$ to be a new observation [same distribution].

We define the (predictive) risk to be

$$R(\beta) = \mathbb{E}_{\mathcal{Z}} \left[\left(\mathcal{Y} - \mathcal{X}^\top \beta \right)^2 \right].$$

Define the oracle estimator

$$\beta_t^* = \underset{\{\beta: \|\beta\|_1 \leq t\}}{\operatorname{argmin}} R(\beta)$$

The excess risk is

$$\mathcal{E}(\hat{\beta}_t, \beta_t^*) = R(\hat{\beta}_t) - R(\beta_t^*)$$

DIFFERENT PROPERTIES (CONT.)

A procedure is **persistent** (relative to the oracle) if

$$\mathcal{E}(\hat{\beta}_t, \beta_t^*) \xrightarrow{P} 0$$

Then²

- If $t^4 = o\left(\frac{n}{\log n}\right)$, $\hat{\beta}_t$ is persistent relative to β_t^*
- $\hat{\beta}_t$ is **not necessarily** persistent if $t^4 \notin o\left(\frac{n}{\log n}\right)$

² Greenshtein and Ritov (2004)

You've got data. . .

What t to use?

METHODS FOR CHOOSING t

The tuning parameter can be selected by

- unbiased risk estimation using degrees of freedom
- using an adapted Bayesian information criterion

However...

Many papers recommend **cross-validation** [3, 4, 7, 8, 9, 10, 11]

[It is also the default method in the R package **glmnet**. See [Zou, Hastie, and Tibshirani \(2010\)](#)]

CROSS-VALIDATION

Define

- $V_n = \{v_1, \dots, v_{K_n}\}$ to be a set of validation sets
- $\hat{\beta}_t^{(v)}$ lasso estimator computed on observations not in $v \subset \{1, \dots, n\}$

The cross-validation estimator of the risk is

$$\begin{aligned}\hat{R}_{V_n}(t) &= \hat{R}_{V_n}(\hat{\beta}_t^{(v_1)}, \dots, \hat{\beta}_t^{(v_{K_n})}) \\ &:= \frac{1}{K_n} \sum_{v \in V_n} \frac{1}{|v|} \sum_{r \in v} \left(Y_r - X_r^\top \hat{\beta}_t^{(v)} \right)^2\end{aligned}$$

Define

$$\hat{t} := \operatorname{argmin}_{t \in T_n} \hat{R}_{V_n}(t)$$

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In practice, the optimization set $T_n = [0, t_{\max}]$ needs to be specified

However, if t_{\max} is too small, good solutions might be excluded

What is too small?

By definition, $\hat{\beta}_t \in \{\beta : \|\beta\|_1 \leq t\}$

This constraint is only binding if

$$t < \min_{\eta \in \mathcal{K}} \|\hat{\beta}^0 + \eta\|_1 =: t_0,$$

where

- $\hat{\beta}^0 := (\mathbb{X}^\top \mathbb{X})^\dagger \mathbb{X}^\top \mathbb{Y}$ is a least squares solution
- $\mathcal{K} := \{a : \mathbb{X}a = 0\}$ is the null space of \mathbb{X}

If $t \geq t_0$, then $\hat{\beta}_t$ is ‘equal to’ $\hat{\beta}^0$

We define $t_{\max} := \|\hat{\beta}^0\|_1$

DOES CROSS-VALIDATION WORK?

Prevailing heuristic:

“Regarding the choice of the regularization parameter, we typically use [the tuning parameter chosen by] cross-validation. ‘Luckily’, empirical and some theoretical indications support [good performance]...”

— *Peter Bühlmann’s comments to Tibshirani (2011).*

What does theory have to say?

STABILITY (OR LACK THEREOF)

Sparsity inducing algorithms, such as lasso, are not (uniformly) algorithmically stable

Algorithmic stability is **sufficient**, but not **necessary**, for persistence⁴

⁴ Xu and Mannor (2008) and Bousquet and Elisseeff (2002)

MODEL SELECTION AND CROSS-VALIDATION

There is a close connection between lasso and model selection
[e.g. the LARS algorithm]

For model selection⁵...

- Leave-one-out cross-validation is inconsistent
- If $c_n/n \rightarrow 1$ and $n - c_n \rightarrow \infty$, then cross-validation is consistent
[[c_n is the size of the smallest held-out set]]

Very restrictive: asymptotically, **all** the data is used for validation

⁵ Shao (1993)

Results: Cross-validation does work

CONDITIONS

C1. $\mathbb{E} [\|t_{\max}\|_1^4] = \mathbb{E} [\|\widehat{\beta}^0\|_1^4] = o(t_n^4)$

C2. Held-out sets contain at least c_n observations, don't overlap.

C3. Let $\mathcal{Z} = (\mathcal{Y}, \mathcal{X}) \sim F_n$. Then, $(F_n)_{n \geq 1}$ is such that $\exists C < \infty$ for all n where

$$\mathbb{E}_{F_n} \max_{0 \leq j, k \leq p} (\mathcal{Z}_j \mathcal{Z}_k - \mathbb{E}_{F_n} \mathcal{Z}_j \mathcal{Z}_k)^2 \leq C$$

RESULTS (CONT.)

THEOREM

Assume **C1–C3** and that $p_n = n^\alpha$ for some $\alpha > 0$.

Then, for any $\delta > 0$,

$$P(\mathcal{E}(\hat{\beta}_t, \beta_{t_n}) > \delta) = o\left(t_n^2 \sqrt{\frac{\log n}{c_n}}\right).$$

Some remarks

- $c_n \asymp n$ for K -fold cross-validation
- leave-one-out cross-validation has $c_n = 1$
- $\mathcal{E}(\hat{\beta}_t, \beta_{t_n})$ **CAN** be negative (don't care)

PROPERTIES OF t_n

The faster $t_n \rightarrow \infty \dots$

- the less restrictive condition C1 becomes
- $R_n(\beta_{t_n})$ shrinks faster
- But, if t_n grows as fast or faster than $\left(\frac{n}{\log n}\right)^{1/4}$, then $\widehat{\beta}_{t_n}$ is not necessarily persistent

Can $\mathbb{E} \left[\|\widehat{\beta}^0\|_1^4 \right] = o(t_n^4)$ if $t_n = o\left(\left(\frac{n}{\log n}\right)^{1/4}\right)$?

Yes...

WHEN IT WORKS...

Suppose $Y = m(X) + \epsilon$, $m(X)$ bounded, $\mathbb{E}[\epsilon^4] < \infty$

EXAMPLE 1:

- $X_i \in \mathbb{R}^p$ i.i.d sub-Gaussian with independent components

EXAMPLE 2:

- Fixed design $e_i = i/n$
- $\mathbb{X}_{ij} = h^{-1}\phi(|e_j - e_i|/h)$
- ϕ satisfies $h^{-1}\phi(1/h) \rightarrow 0$ as $h \rightarrow \infty$

EXAMPLE 3:

- Orthogonal basis regression

FUTURE WORK

Show similar results for lasso-type estimators, such as **group lasso**

- G is a partition of $\{1, \dots, p\}$
- $\mathcal{G}_u := \{\beta : \sum_{g \in G} \sqrt{|g|} \|\beta_g\|_2 \leq u\}$

THEOREM

Suppose

- 1 $\mathbb{E} \left[\left(\sum_{g \in G} \|\hat{\beta}_g^0\|_2 \right)^4 \right] = o(u_n^4)$
- 2 $p_n = n^\alpha$ for some $\alpha > 0$
- 3 $\max_{g \in G} |g| = a_n$
- 4 conditions **C2** and **C3**

Then, for any $\delta > 0$,

$$P_{F_n} \left(\mathcal{E} \left(\hat{\beta}_{\hat{u}}, \beta_{u_n} \right) > \delta \right) = o \left(a_n u_n^2 \sqrt{\frac{\log n}{c_n}} \right).$$

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