

clear : restart

$$z \quad v \quad t$$

$$0, \quad 0, \quad \frac{t_z}{v \cdot t_z},$$

$$x_a := c \cdot (t - t_z) \cdot \sin(\theta) \cdot \cos(\varphi) \quad c \cdot (t - t_z) \cdot \sin(\theta) \cdot \cos(\varphi) \quad (1)$$

$$y_a := c \cdot (t - t_z) \cdot \sin(\theta) \cdot \sin(\varphi) \quad c \cdot (t - t_z) \cdot \sin(\theta) \cdot \sin(\varphi) \quad (2)$$

$$xy_a := c \cdot (t - t_z) \cdot \sin(\theta) \quad c \cdot (t - t_z) \cdot \sin(\theta) \quad (3)$$

$$\begin{pmatrix} z \\ v \cdot t_z \\ z \end{pmatrix}, \quad \begin{pmatrix} z \\ v \cdot t_z \\ z \end{pmatrix}.$$

$$z_a := c \cdot (t - t_z) \cdot \cos(\theta) + v \cdot t_z \quad c \cdot (t - t_z) \cdot \cos(\theta) + v \cdot t_z \quad (4)$$

$$(a, b, c) \quad R$$

$$(x - a)^2 + (y - b)^2 + (z - c)^2 - R^2 = 0 \quad (x - a)^2 + (y - b)^2 + (z - c)^2 - R^2 = 0 \quad (5)$$

$$M(x, y, z, v, c, t, t_z) := (x - 0)^2 + (y - 0)^2 + (z - v \cdot t_z)^2 - (c \cdot (t - t_z))^2 \quad (x, y, z, v, c, t, t_z) \rightarrow x^2 + y^2 + (z - v \cdot t_z)^2 - c^2 \cdot (t - t_z)^2 \quad (6)$$

$$(x - 0)^2 + (y - 0)^2 + (z - v \cdot t_z)^2 - (c \cdot (t - t_z))^2 = 0 \quad x^2 + y^2 + (-t_z \cdot v + z)^2 - c^2 \cdot (t - t_z)^2 = 0 \quad (7)$$

$$\text{simplify}((x - 0)^2 + (y - 0)^2 + (z - v \cdot t_z)^2 - (c \cdot (t - t_z))^2 = 0) \quad -c^2 \cdot t^2 + 2 \cdot c^2 \cdot t \cdot t_z - c^2 \cdot t_z^2 + t_z^2 \cdot v^2 - 2 \cdot t_z \cdot v \cdot z + x^2 + y^2 + z^2 = 0 \quad (8)$$

$$t_z \qquad \theta = \theta_{\theta'}, \varphi = \varphi_{\theta}$$

$$x_{\theta} := subs\Big(\theta = \theta_{\theta'} \varphi = \varphi_{\theta'} x_a\Big) \qquad c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \cos(\varphi_{\theta}) \qquad (9)$$

$$y_{\theta} := subs\Big(\theta = \theta_{\theta'} \varphi = \varphi_{\theta'} y_a\Big) \qquad c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \sin(\varphi_{\theta}) \qquad (10)$$

$$xy_{\theta} := subs\Big(\theta = \theta_{\theta'} \varphi = \varphi_{\theta'} xy_a\Big) \qquad c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \qquad (11)$$

$$z_{\theta} := subs\Big(\theta = \theta_{\theta'} \varphi = \varphi_{\theta'} z_a\Big) \qquad c \left(t - t_z \right) \cos\left(\theta_{\theta}\right) + v t_z \qquad (12)$$

$$\frac{\partial}{\partial x} M(x, y, z, v, c, t, t_z) \qquad 2 x \qquad (13)$$

$$\frac{\partial}{\partial y} M(x, y, z, v, c, t, t_z) \qquad 2 y \qquad (14)$$

$$\frac{\partial}{\partial z} M(x, y, z, v, c, t, t_z) \qquad -2 t_z v + 2 z \qquad (15)$$

$$\frac{x - x_{\theta}}{subs\left(x = x_{\theta'} \frac{\partial}{\partial x} M(x, y, z, v, c, t, t_z)\right)} \qquad \frac{1}{2} \frac{x - c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \cos(\varphi_{\theta})}{c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \cos(\varphi_{\theta})} \qquad (16)$$

$$\frac{y - y_{\theta}}{subs\left(y = y_{\theta'} \frac{\partial}{\partial y} M(x, y, z, v, c, t, t_z)\right)} \qquad \frac{1}{2} \frac{y - c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \sin(\varphi_{\theta})}{c \left(t - t_z \right) \sin\left(\theta_{\theta}\right) \sin(\varphi_{\theta})} \qquad (17)$$

$$\frac{z - z_{\theta}}{subs\left(z = z_{\theta'} \frac{\partial}{\partial z} M(x, y, z, v, c, t, t_z)\right)}$$

$$\frac{1}{2} \frac{z - c (t - t_z) \cos(\theta_0) - v t_z}{c (t - t_z) \cos(\theta_0)} \quad (18)$$

$$\begin{aligned} \frac{x - x_0}{\text{subs}\left(x = x_0, \frac{\partial}{\partial x} M(x, y, z, v, c, t, t_z)\right)} &= \frac{y - y_0}{\text{subs}\left(y = y_0, \frac{\partial}{\partial y} M(x, y, z, v, c, t, t_z)\right)} \\ &= \frac{z - z_0}{\text{subs}\left(z = z_0, \frac{\partial}{\partial z} M(x, y, z, v, c, t, t_z)\right)} \end{aligned}$$

$$\begin{aligned} x_izo_tzip_normal(p) &:= x_0 + p \cdot \text{subs}\left(x = x_0, \frac{\partial}{\partial x} M(x, y, z, v, c, t, t_z)\right) \\ &\quad p \rightarrow x_0 + p \text{subs}\left(x = x_0, \frac{\partial}{\partial x} M(x, y, z, v, c, t, t_z)\right) \end{aligned} \quad (19)$$

$$\begin{aligned} y_izo_tzip_normal(p) &:= y_0 + p \cdot \text{subs}\left(y = y_0, \frac{\partial}{\partial y} M(x, y, z, v, c, t, t_z)\right) \\ &\quad p \rightarrow y_0 + p \text{subs}\left(y = y_0, \frac{\partial}{\partial y} M(x, y, z, v, c, t, t_z)\right) \end{aligned} \quad (20)$$

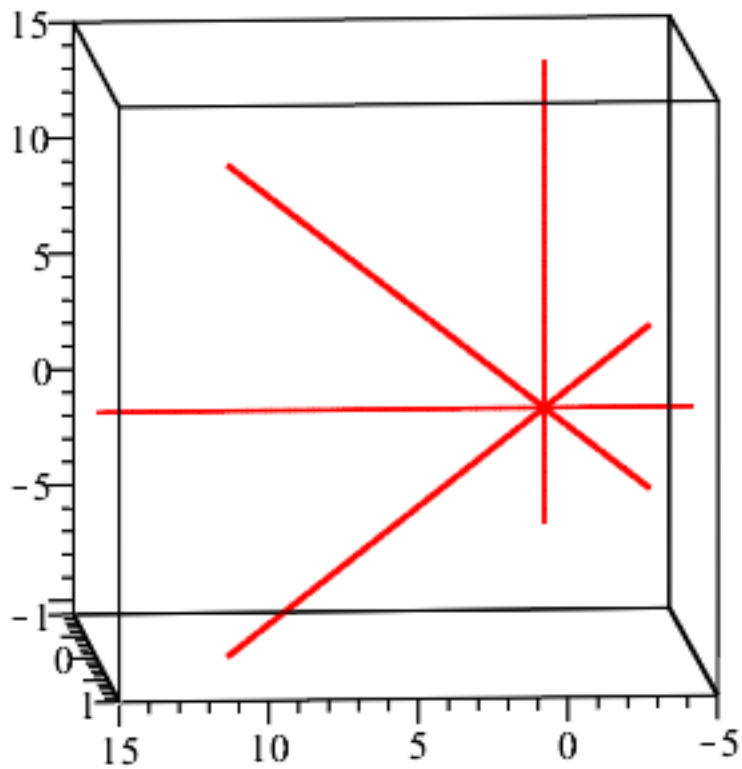
$$\begin{aligned} z_izo_tzip_normal(p) &:= z_0 + p \cdot \text{subs}\left(z = z_0, \frac{\partial}{\partial z} M(x, y, z, v, c, t, t_z)\right) \\ &\quad p \rightarrow z_0 + p \text{subs}\left(z = z_0, \frac{\partial}{\partial z} M(x, y, z, v, c, t, t_z)\right) \end{aligned} \quad (21)$$

$$\begin{aligned} izo_tzip_normal &:= \text{subs}\left(c = 1, t = 5, v = 0.5, \left[x_0 + p \cdot \text{subs}\left(x = x_0, \frac{\partial}{\partial x} M(x, y, z, v, c, t, t_z)\right), y_0 + p \right. \right. \\ &\quad \left. \cdot \text{subs}\left(y = y_0, \frac{\partial}{\partial y} M(x, y, z, v, c, t, t_z)\right), z_0 + p \cdot \text{subs}\left(z = z_0, \frac{\partial}{\partial z} M(x, y, z, v, c, t, t_z)\right)\right] \Big) \\ &\quad \left[(5 - t_z) \sin(\theta_0) \cos(\varphi_0) + 2 p (5 - t_z) \sin(\theta_0) \cos(\varphi_0), (5 - t_z) \sin(\theta_0) \sin(\varphi_0) + 2 p (5 \right. \\ &\quad \left. - t_z) \sin(\theta_0) \sin(\varphi_0), (5 - t_z) \cos(\theta_0) + 0.5 t_z + 2 p (5 - t_z) \cos(\theta_0) \right] \end{aligned} \quad (22)$$

with(plots) :

$$\begin{aligned} \text{spacecurve}\left(\left[\text{subs}\left(t_z = 0, \theta_0 = 0, \varphi_0 = 0, izo_tzip_normal\right), \text{subs}\left(t_z = 0, \theta_0 = \frac{\pi}{4}, \varphi_0 = 0, \right. \right. \right. \\ \left. \left. izo_tzip_normal\right), \text{subs}\left(t_z = 0, \theta_0 = \frac{\pi}{2}, \varphi_0 = 0, izo_tzip_normal\right), \text{subs}\left(t_z = 0, \theta_0 = 3 \cdot \frac{\pi}{4}, \varphi_0 = 0, \right. \right. \end{aligned}$$

$$izo_tzip_normal \Big) \Big], p = -1 \dots 1, thickness = 1, numpoints = 100, color = red \Big)$$



$$t_z + dt_z$$

$$M(x, y, z, v, c, t, t_z)$$

$$x^2 + y^2 + (-t_z v + z)^2 - c^2 (t - t_z)^2 \quad (23)$$

$$M(x, y, z, v, c, t, t_z + dt_z)$$

$$x^2 + y^2 + (z - v(t_z + dt_z))^2 - c^2(t - t_z - dt_z)^2 \quad (24)$$

$$[x_izo_tzap_normal(p), y_izo_tzap_normal(p), z_izo_tzap_normal(p)]$$

$$\begin{aligned} & \left[c(t-t_z) \sin(\theta_0) \cos(\varphi_0) + 2p c(t-t_z) \sin(\theta_0) \cos(\varphi_0), c(t-t_z) \sin(\theta_0) \sin(\varphi_0) \right. \\ & \left. + 2p c(t-t_z) \sin(\theta_0) \sin(\varphi_0), c(t-t_z) \cos(\theta_0) + v t_z + 2p c(t-t_z) \cos(\theta_0) \right] \end{aligned} \quad (25)$$

$$\begin{array}{c} t_z + dt_z \\ t_z \end{array}$$

$$\begin{aligned} & M(x_izo_tzap_normal(p), y_izo_tzap_normal(p), z_izo_tzap_normal(p), v, c, t, t_z + dt_z) \\ & \left(c (t - t_z) \sin(\theta_0) \cos(\varphi_0) + 2 p c (t - t_z) \sin(\theta_0) \cos(\varphi_0) \right)^2 + \left(c (t - t_z) \sin(\theta_0) \sin(\varphi_0) \right. \\ & \quad \left. + 2 p c (t - t_z) \sin(\theta_0) \sin(\varphi_0) \right)^2 + \left(c (t - t_z) \cos(\theta_0) + v t_z + 2 p c (t \right. \\ & \quad \left. - t_z) \cos(\theta_0) - v (t_z + dt_z) \right)^2 - c^2 (t - t_z - dt_z)^2 \end{aligned} \quad (26)$$

$$\begin{aligned} & p_{t_{z2}} := solve(M(x_izo_tzap_normal(p), y_izo_tzap_normal(p), z_izo_tzap_normal(p), v, c, t, t_{z2}), \\ & \quad p) \\ & \frac{1}{4} \frac{1}{c (t - t_z)} \left(-2 \cos(\theta_0) t_z v + 2 \cos(\theta_0) t_{z2} v - 2 c t + 2 c t_z \right. \\ & \quad \left. + 2 \left(\cos(\theta_0)^2 t_z^2 v^2 - 2 \cos(\theta_0)^2 t_z t_{z2} v^2 + \cos(\theta_0)^2 t_{z2}^2 v^2 + c^2 t^2 - 2 c^2 t t_{z2} + c^2 t_{z2}^2 \right. \right. \\ & \quad \left. \left. - t_z^2 v^2 + 2 t_z t_{z2} v^2 - t_{z2}^2 v^2 \right)^{1/2} \right), \frac{1}{4} \frac{1}{c (t - t_z)} \left(-2 \cos(\theta_0) t_z v + 2 \cos(\theta_0) t_{z2} v \right. \\ & \quad \left. - 2 c t + 2 c t_z \right. \\ & \quad \left. - 2 \left(\cos(\theta_0)^2 t_z^2 v^2 - 2 \cos(\theta_0)^2 t_z t_{z2} v^2 + \cos(\theta_0)^2 t_{z2}^2 v^2 + c^2 t^2 - 2 c^2 t t_{z2} + c^2 t_{z2}^2 \right. \right. \\ & \quad \left. \left. - t_z^2 v^2 + 2 t_z t_{z2} v^2 - t_{z2}^2 v^2 \right)^{1/2} \right) \end{aligned} \quad (27)$$

$$\begin{aligned} & p_{dt_z} := solve(M(x_izo_tzap_normal(p), y_izo_tzap_normal(p), z_izo_tzap_normal(p), v, c, t, t_z \\ & \quad + dt_z), p) \\ & \frac{1}{4} \frac{1}{c (t - t_z)} \left(2 \cos(\theta_0) dt_z v - 2 c t + 2 c t_z \right. \\ & \quad \left. + 2 \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} \right), \\ & \frac{1}{4} \frac{1}{c (t - t_z)} \left(2 \cos(\theta_0) dt_z v - 2 c t + 2 c t_z \right. \\ & \quad \left. - 2 \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} \right) \end{aligned} \quad (28)$$

$$\begin{array}{c} dt_z \\ x_izo_dtz(dt_z) := simplify(x_izo_tzap_normal(p_dt_z)) : \end{array}$$

$$\begin{aligned}
& \text{simplify}(x_izo_dtz(dt_z)) \\
& \sin(\theta_0) \cos(\varphi_0) \left(\cos(\theta_0) dt_z v \right. \\
& \quad \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c - dt_z v) ((t - t_z - dt_z) c + dt_z v)} \right)
\end{aligned} \tag{29}$$

$$\begin{aligned}
& y_izo_dtz(dt_z) := \text{simplify}(y_izo_tzap_normal(p_dt_z)) : \\
& \text{simplify}(y_izo_dtz(dt_z)) \\
& \sin(\theta_0) \sin(\varphi_0) \left(\cos(\theta_0) dt_z v \right. \\
& \quad \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c - dt_z v) ((t - t_z - dt_z) c + dt_z v)} \right)
\end{aligned} \tag{30}$$

$$\begin{aligned}
& z_izo_dtz(dt_z) := \text{simplify}(z_izo_tzap_normal(p_dt_z)) : \\
& \text{simplify}(z_izo_dtz(dt_z)) \\
& \cos(\theta_0) \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c - dt_z v) ((t - t_z - dt_z) c + dt_z v)} \\
& \quad + v (dt_z \cos(\theta_0)^2 + t_z)
\end{aligned} \tag{31}$$

$$\begin{aligned}
& \text{simplify}\left(\sqrt{x_izo_dtz(dt_z)^2 + y_izo_dtz(dt_z)^2}\right) \\
& \left(\sin(\theta_0)^2 \left(\cos(\theta_0) dt_z v \right. \right. \\
& \quad \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c - dt_z v) ((t - t_z - dt_z) c + dt_z v)} \right)^2 \right)^{1/2}
\end{aligned} \tag{32}$$

$$\begin{aligned}
& \lim_{dt_z \rightarrow 0} \frac{x_izo_dtz(dt_z) - x_0}{dt_z} \\
& \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\sin(\theta_0) \cos(\varphi_0) \left(\cos(\theta_0) dt_z v \right. \right. \\
& \quad \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} \right) \right. \\
& \quad \left. - c (t - t_z) \sin(\theta_0) \cos(\varphi_0) \right)
\end{aligned} \tag{33}$$

$$\lim_{dt_z \rightarrow 0} \frac{y_izo_dtz(dt_z) - y_0}{dt_z}$$

$$\lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\sin(\theta_0) \sin(\varphi_0) \left(\cos(\theta_0) dt_z v \right. \right. \quad (34)$$

$$\left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} \right)$$

$$\left. - c (t - t_z) \sin(\theta_0) \sin(\varphi_0) \right)$$

$$\lim_{dt_z \rightarrow 0} \frac{z_izo_dtz(dt_z) - z_0}{dt_z}$$

$$\lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\cos(\theta_0)^2 dt_z v \right. \quad (35)$$

$$\left. + \cos(\theta_0) \right.$$

$$\left. \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} - c (t \right.$$

$$\left. - t_z) \cos(\theta_0) \right)$$

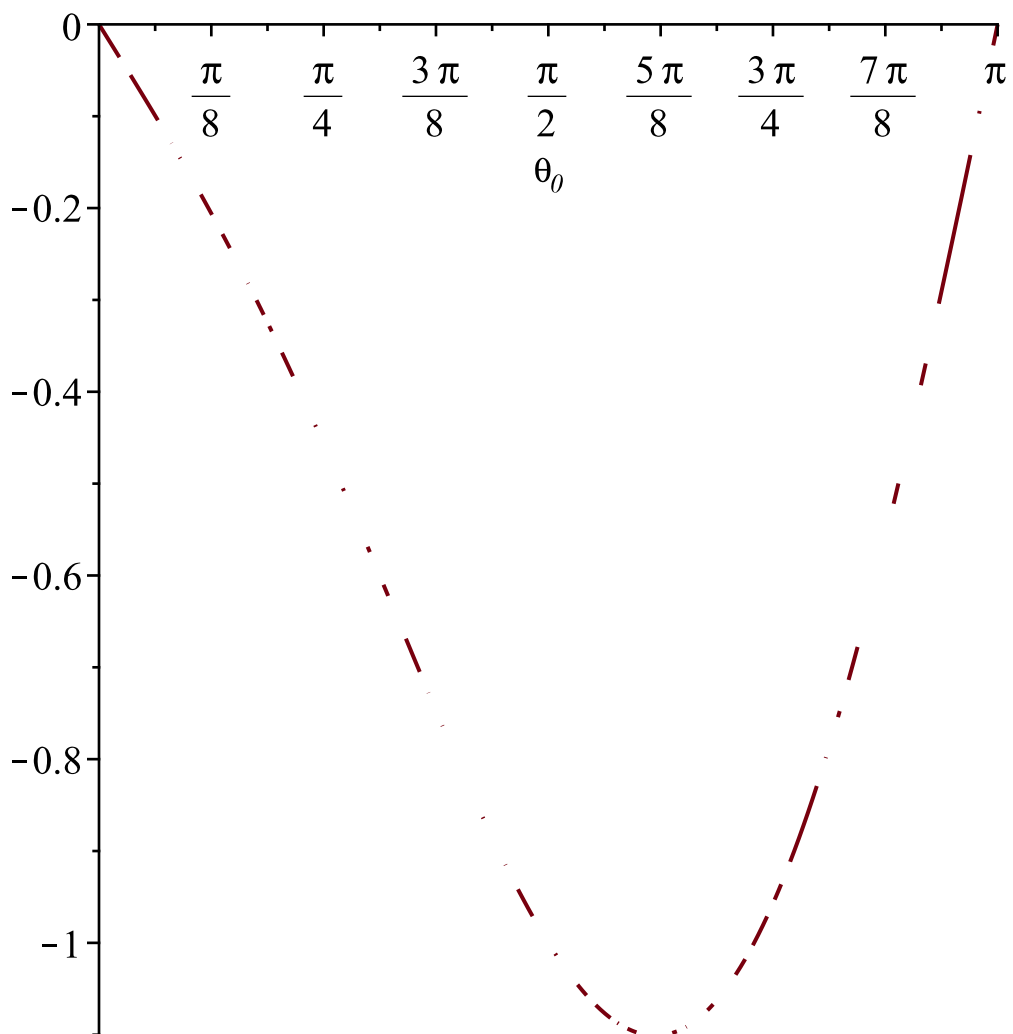
$$evalf \left(subs \left(c = 1, v = 0.5, t = 5, \varphi_0 = 0, \lim_{dt_z \rightarrow 0} \frac{x_izo_dtz(dt_z) - x_0}{dt_z} \right) \right)$$

$$\lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\sin(\theta_0) \cos(0) \left(0.5 \cos(\theta_0) dt_z \right. \right. \quad (36)$$

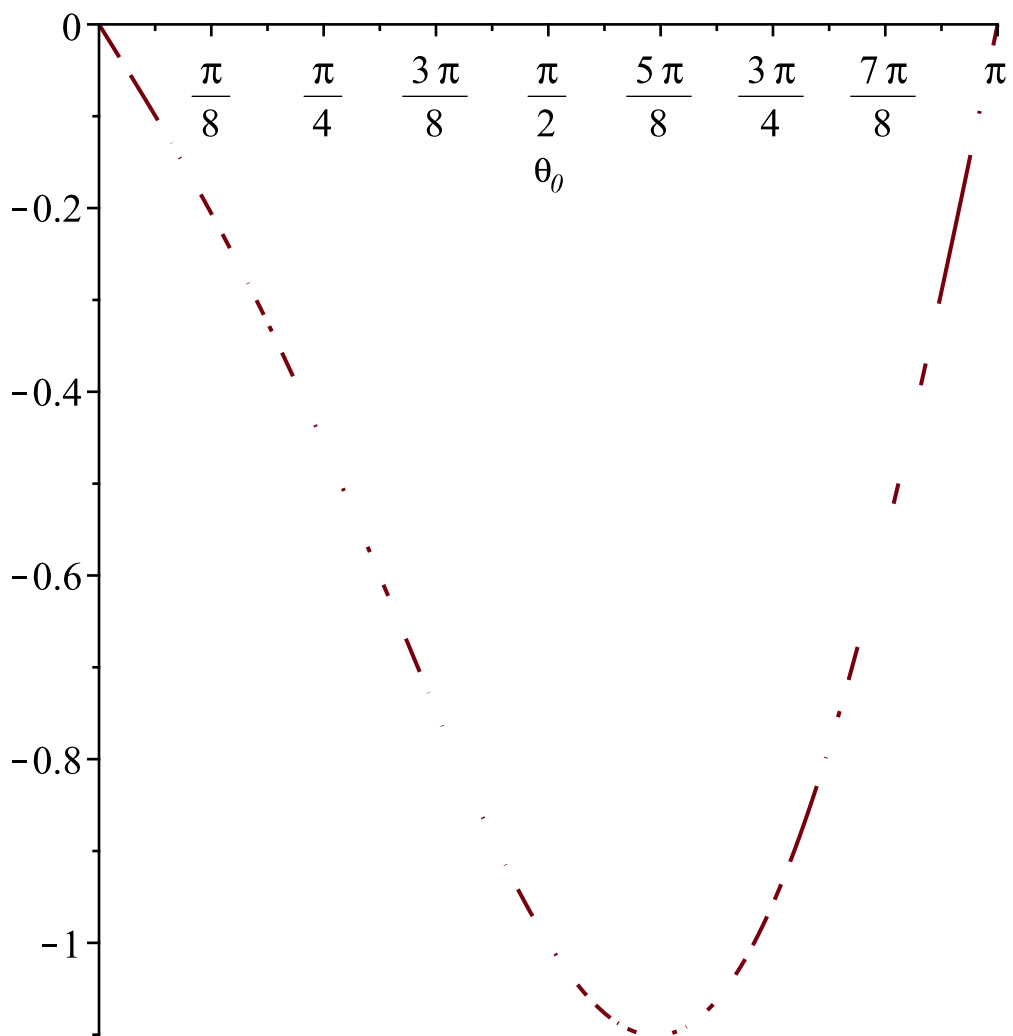
$$\left. + \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} \right) - (5$$

$$- t_z) \sin(\theta_0) \cos(0) \left. \right)$$

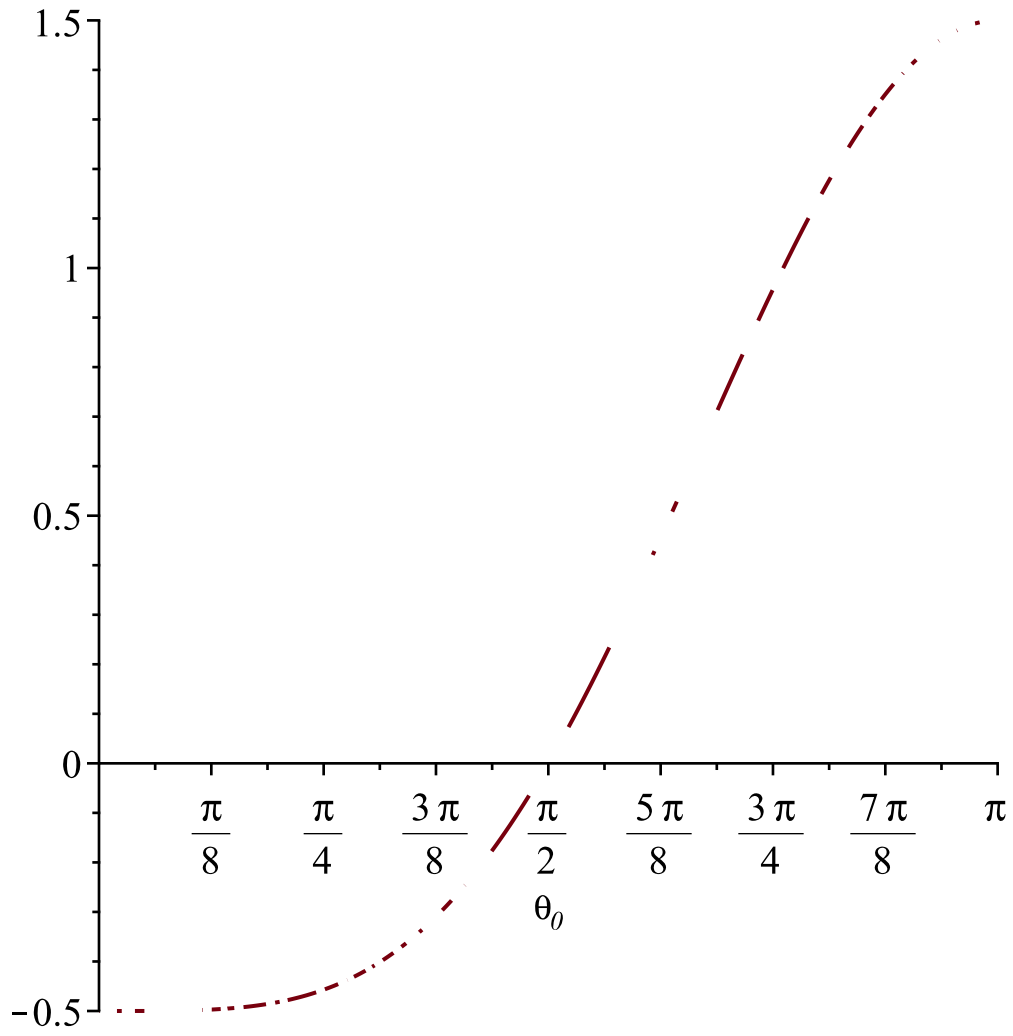
$$plot \left(subs \left(c = 1, v = 0.5, t = 5, t_z = 0, \varphi_0 = 0, \lim_{dt_z \rightarrow 0} \frac{x_izo_dtz(dt_z) - x_0}{dt_z} \right), \theta_0 = 0 .. \pi \right)$$



$$plot\left(subs\left(c=1, v=0.5, t=5, t_z=0, \phi_0=\frac{\pi}{2}, \lim_{dt_z \rightarrow 0} \frac{y_{izo_dtz}(dt_z) - y_0}{dt_z}\right), \theta_0=0..\pi\right)$$



$$plot\left(subs\left(c=1, v=0.5, t=5, t_z=0, \lim_{dt_z \rightarrow 0} \frac{z_{izo_dtz}(dt_z) - z_0}{dt_z}\right), \theta_0=0..\pi\right)$$



$$xy_izo_dtz(dt_z) := simplify\left(\sqrt{x_izo_dtz(dt_z)^2 + y_izo_dtz(dt_z)^2}\right) \\ dt_z \rightarrow simplify\left(\sqrt{x_izo_dtz(dt_z)^2 + y_izo_dtz(dt_z)^2}\right) \quad (37)$$

$$simplify\left(\lim_{dt_z \rightarrow 0} \frac{xy_izo_dtz(dt_z)}{(t - t_z) c}\right) \\ \frac{\sqrt{\sin(\theta_0)^2 c^2 (t - t_z)^2}}{(t - t_z) c} \quad (38)$$

$$\lim_{\substack{dt_z \rightarrow 0 \\ z}} \frac{z_izo_dtz(dt_z) - v \cdot (t_z + dt_z)}{(t - t_z - dt_z) c} \frac{\cos(\theta_0) \sqrt{c^2 (t - t_z)^2}}{c t - c t_z} \quad (39)$$

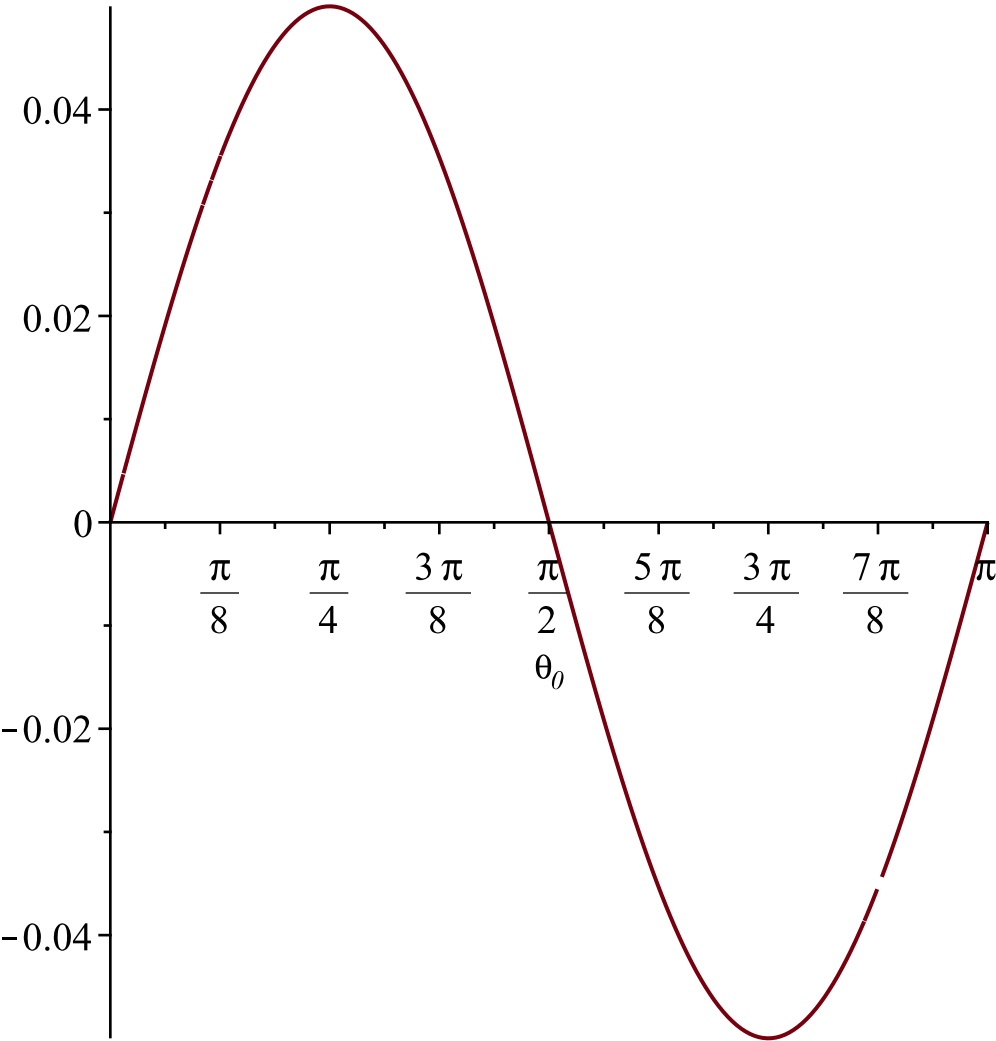
$$\lim_{\substack{dt_z \rightarrow 0 \\ z}} \frac{\frac{xy_izo_dtz(dt_z)}{(t - t_z - dt_z) c} - \sin(\theta_0)}{dt_z} \quad (40)$$

$$\lim_{\substack{dt_z \rightarrow 0 \\ z}} \frac{1}{dt_z} \left(\frac{1}{(t - t_z - dt_z) c} \left(\sin(\theta_0)^2 \left(\cos(\theta_0) dt_z v \right. \right. \right. \\ \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} \right)^2 \right) \\ \left. - \sin(\theta_0) \right) \quad (41)$$

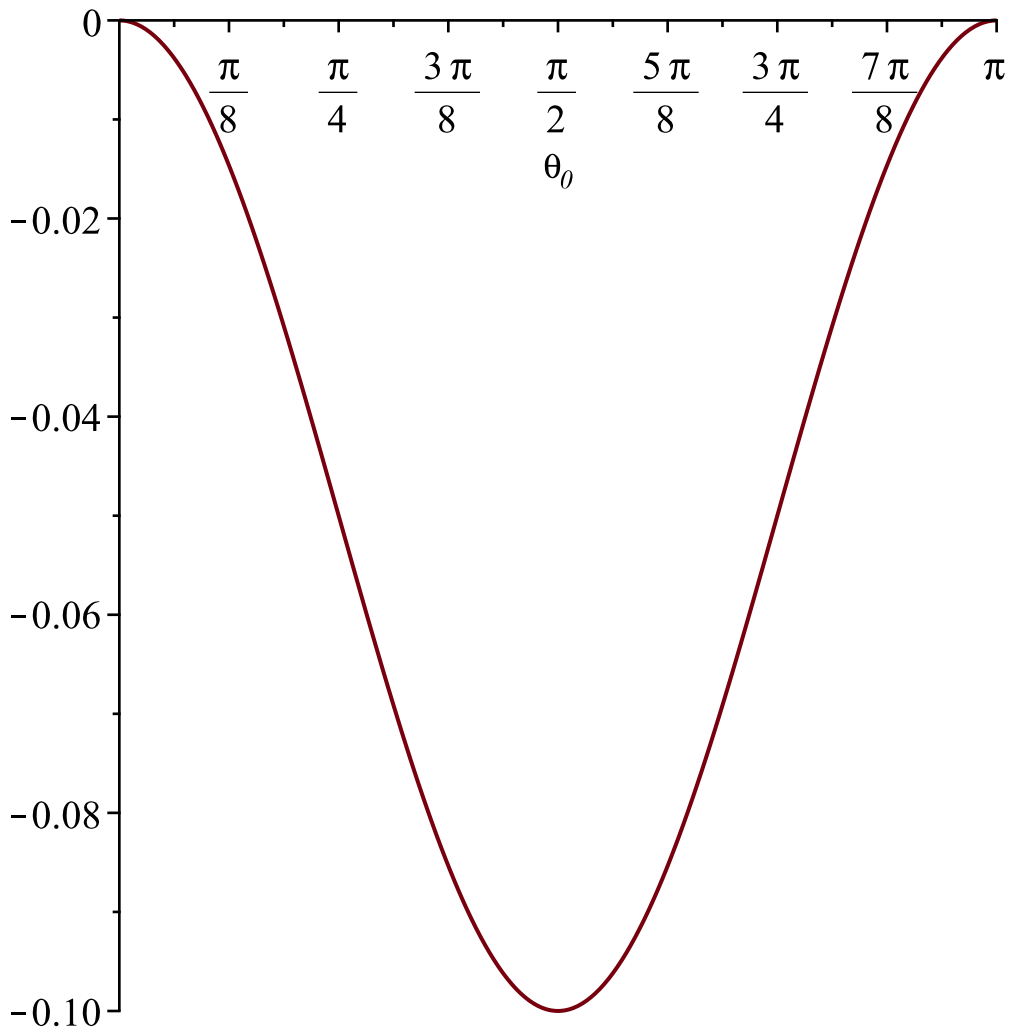
$$\lim_{\substack{dt_z \rightarrow 0 \\ z}} \frac{z_izo_dtz(dt_z) - v \cdot (t_z + dt_z)}{(t - t_z - dt_z) c} - \cos(\theta_0)$$

$$\lim_{\substack{dt_z \rightarrow 0 \\ z}} \frac{1}{dt_z} \left(\frac{1}{(t - t_z - dt_z) c} \left(\cos(\theta_0)^2 dt_z v \right. \right. \\ \left. \left. + \cos(\theta_0) \right. \right. \\ \left. \left. \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} + v t_z \right. \right. \\ \left. \left. - v (t_z + dt_z) \right) - \cos(\theta_0) \right)$$

$$plot\left(subs\left(c=1, v=0.5, t=5, t_z=0, \lim_{dt_z \rightarrow 0} \frac{\frac{xy_izo_dtz(dt_z)}{(t-t_z-dt_z) c} - \sin(\theta_0)}{dt_z}\right), \theta_0=0..\pi\right)$$



$$plot\left(subs\left(c=1, v=0.5, t=5, t_z=0, \lim_{dt_z \rightarrow 0} \frac{\frac{z_izo_dtz(dt_z) - v \cdot (t_z + dt_z)}{(t-t_z-dt_z) c} - \cos(\theta_0)}{dt_z}\right), \theta_0=0..\pi\right)$$

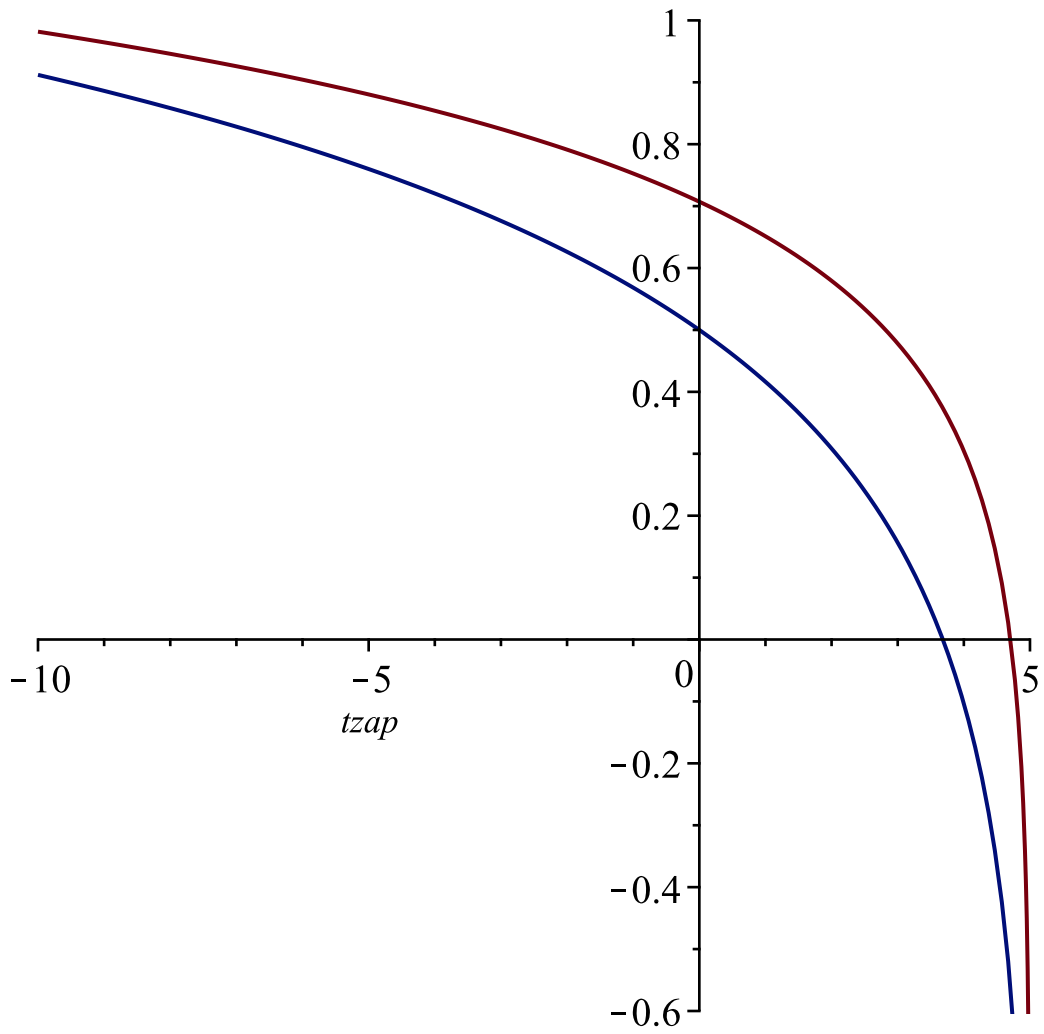


$$\begin{aligned}
 \sin_theta &:= \sin(\theta_0) + \int_0^{t_{zap}} \text{subs}\left(c = 1, v = 0.5, t = 5, \lim_{dt_z \rightarrow 0} \frac{\frac{xy_izo_dtz(dt_z)}{(t - t_z - dt_z) c} - \sin(\theta_0)}{dt_z}\right) dt_z \\
 \sin(\theta_0) &+ \int_0^{t_{zap}} \lim_{dt_z \rightarrow 0} \\
 &\frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(\sin(\theta_0)^2 \left(0.5 \cos(\theta_0) dt_z \right. \right. \right. \\
 &\left. \left. \left. + \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} \right)^2 \right)^{1/2} - \sin(\theta_0) \right)
 \end{aligned} \tag{42}$$

$$dt_z$$

$$\begin{aligned} cos_theta &:= \cos(\theta_0) + \int_0^{tzap} subs \left(c = 1, v = 0.5, t = 5, \right. \\ &\quad \left. \lim_{dt_z \rightarrow 0} \frac{\frac{z_izo_dtz(dt_z) - v \cdot (t_z + dt_z)}{(t - t_z - dt_z) \cdot c} - \cos(\theta_0)}{dt_z} \right) dt_z \\ cos(\theta_0) &+ \int_0^{tzap} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(0.5 \cos(\theta_0)^2 dt_z \right. \right. \\ &\quad \left. \left. + \cos(\theta_0) \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} - 0.5 dt_z \right) \right. \\ &\quad \left. - \cos(\theta_0) \right) dt_z \end{aligned} \tag{43}$$

$$plot \left(\left[subs \left(\theta_0 = \frac{\pi}{4}, cos_theta \right), subs \left(\theta_0 = \frac{\pi}{3}, cos_theta \right) \right], tzap \right)$$



$$xy_a := c \cdot (t - t_z) \cdot \sin(\theta) \quad z_a := c \cdot (t - t_z) \cdot \cos(\theta) + v \cdot t_z$$

$$xn := \sin_theta \cdot (t - tzap) \cdot c$$

$$\left(\sin(\theta_0) + \int_0^{tzap} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(\sin(\theta_0)^2 \left(0.5 \cos(\theta_0) dt_z \right. \right. \right. \right. \\ \left. \left. \left. + \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} \right)^2 \right)^{1/2} - \sin(\theta_0) \right) \\ dt_z \right) (t - tzap) c \quad (44)$$

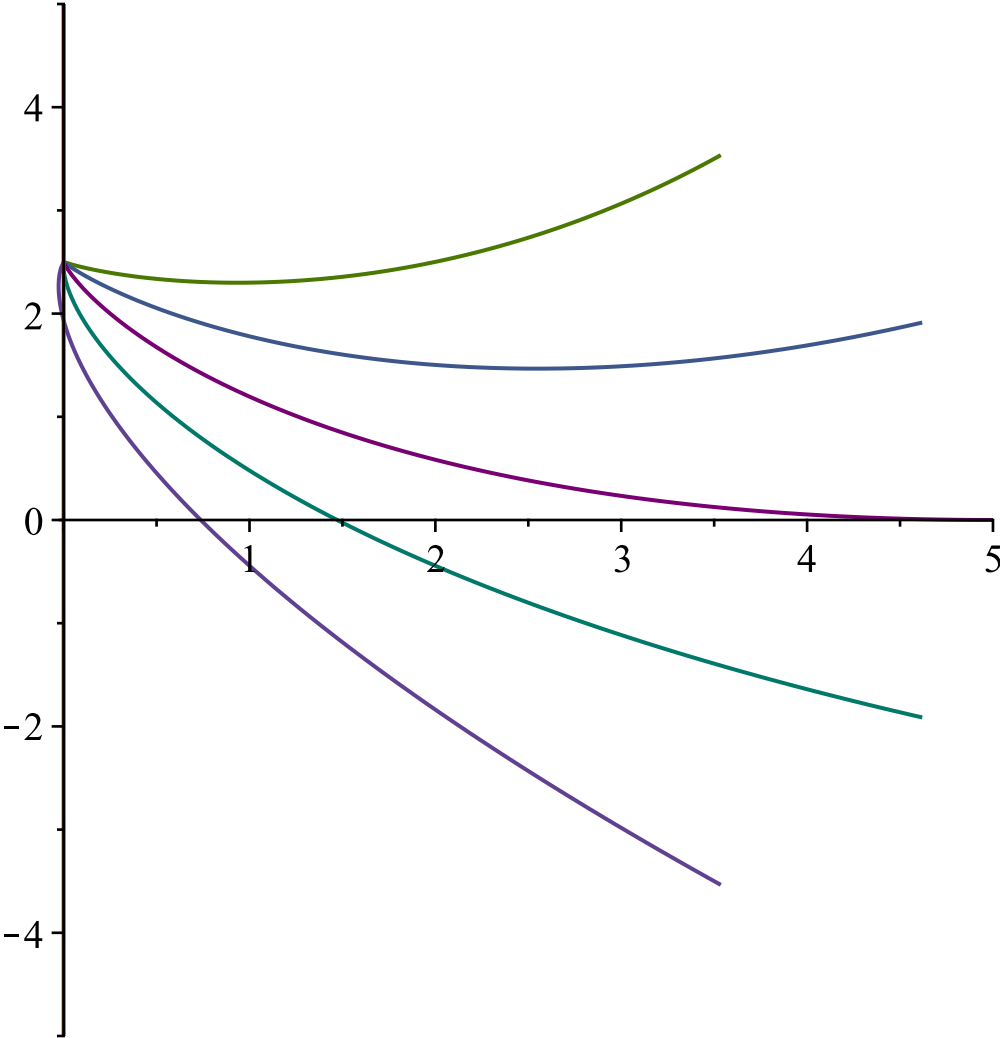
$$\begin{aligned}
zn &:= \cos_theta \cdot (t - tzap) \cdot c + v \cdot tzap \\
&\left(\cos(\theta_0) + \int_0^{tzap} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(0.5 \cos(\theta_0)^2 dt_z \right. \right. \right. \\
&\quad \left. \left. \left. + \cos(\theta_0) \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} - 0.5 dt_z \right) \right. \right. \\
&\quad \left. \left. - \cos(\theta_0) \right) dt_z \right) (t - tzap) c + v tzap
\end{aligned} \tag{45}$$

$$\begin{aligned}
izo_tzap &:= evalf(subs(c = 1, v = 0.5, t = 5, ([xn, zn, tzap = 0..5])) \\
&\left[\left(\sin(\theta_0) + \int_0^{tzap} \lim_{dt_z \rightarrow 0} \right. \right.
\end{aligned} \tag{46}$$

$$\begin{aligned}
&\frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(\sin(\theta_0)^2 \left(0.5 \cos(\theta_0) dt_z \right. \right. \right. \\
&\quad \left. \left. \left. + \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} \right)^2 \right)^{1/2} - \sin(\theta_0) \right) \\
&\left. dt_z \right) (5. - 1. tzap), \left(\cos(\theta_0) + \int_0^{tzap} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(0.5 \cos(\theta_0)^2 dt_z \right. \right. \right. \\
&\quad \left. \left. \left. + \cos(\theta_0) \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} - 0.5 dt_z \right) \right. \right. \\
&\quad \left. \left. - \cos(\theta_0) \right) dt_z \right) (5. - 1. tzap) + 0.5 tzap, tzap = 0..5. \left. \right]
\end{aligned}$$

$$\begin{aligned}
plot &\left(\left[subs(\theta_0 = 0, izo_tzap), subs\left(\theta_0 = \frac{\pi}{8}, izo_tzap\right), subs\left(\theta_0 = \frac{2 \cdot \pi}{8}, izo_tzap\right), subs\left(\theta_0 = \frac{3 \cdot \pi}{8}, \right. \right. \right. \\
&\quad \left. \left. izo_tzap \right), subs\left(\theta_0 = \frac{\pi}{2}, izo_tzap\right), subs\left(\theta_0 = \frac{5 \cdot \pi}{8}, izo_tzap\right), subs\left(\theta_0 = \frac{6 \cdot \pi}{8}, izo_tzap\right), \right.
\end{aligned}$$

$$subs\left(\theta_0=\frac{7\cdot \pi}{8}, izo_tzap\right), subs\left(\theta_0=\frac{8\cdot \pi}{8}, izo_tzap\right)\Big]\Big]$$



$$izo_tzap2 := evalf(subs(c = 1, v = 0.5, t = 5, ([xn, zn])))$$

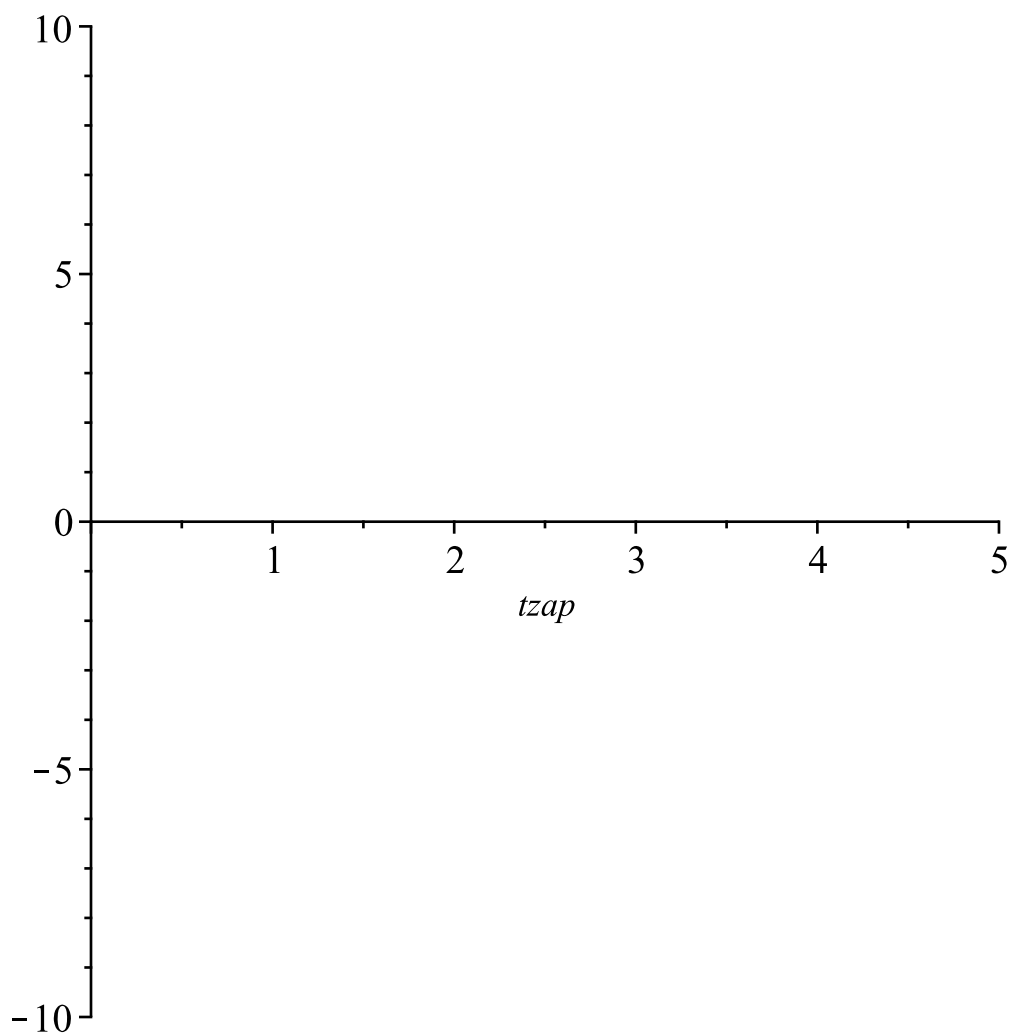
$$\left[\left(\sin(\theta_0) + \int\limits_0^{tzap} \lim_{\substack{dt \rightarrow 0 \\ z}} \right. \right. \tag{47}$$

$$\frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(\sin(\theta_0)^2 \left(0.5 \cos(\theta_0) \, dt_z \right. \right. \right.$$

$$+ \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2}^2)^{1/2} - \sin(\theta_0) \Bigg)$$

$$dt_z \Bigg) (5. - 1. t_{zap}), \left(\cos(\theta_0) + \int_{0.}^{t_{zap}} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\frac{1}{5 - t_z - dt_z} \left(0.5 \cos(\theta_0)^2 dt_z \right. \right. \right. \\ \left. \left. + \cos(\theta_0) \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} - 0.5 dt_z \right) \right. \\ \left. \left. - \cos(\theta_0) \right) dt_z \right) (5. - 1. t_{zap}) + 0.5 t_{zap} \Bigg]$$

$$plot \left(\left[subs(\theta_0 = 0, ize_t_{zap}2), subs\left(\theta_0 = \frac{\pi}{8}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{2 \cdot \pi}{8}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{3 \cdot \pi}{8}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{\pi}{2}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{5 \cdot \pi}{8}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{6 \cdot \pi}{8}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{7 \cdot \pi}{8}, ize_t_{zap}2\right), subs\left(\theta_0 = \frac{8 \cdot \pi}{8}, ize_t_{zap}2\right) \right], t_{zap} = 0 .. 5 \right)$$



$$plot\left(\left[evalf\left(subs\left(c=1,v=0.5,t=5,\theta_0=\frac{\pi}{3},\varphi_0=0,xn\right)\right),evalf\left(subs\left(c=1,v=0.5,t=5,\theta_0=\frac{\pi}{3},\right.\right.\right. \\ \left.\left.\left.\varphi_0=0,zn\right)\right)\right],tzap=0..5\right]$$

$$int_x:=\int\limits_0^{tzap}\lim\limits_{dt_z\rightarrow 0}\frac{x_izo_dtz(dt_z)-x_0}{dt_z}\,dt_z$$

$$\int\limits_0^{tzap}\lim\limits_{dt_z\rightarrow 0}\frac{1}{dt_z}\left(\sin(\theta_0)\cos(\varphi_0)\left(\cos(\theta_0)dt_zv\right.\right.$$

(48)

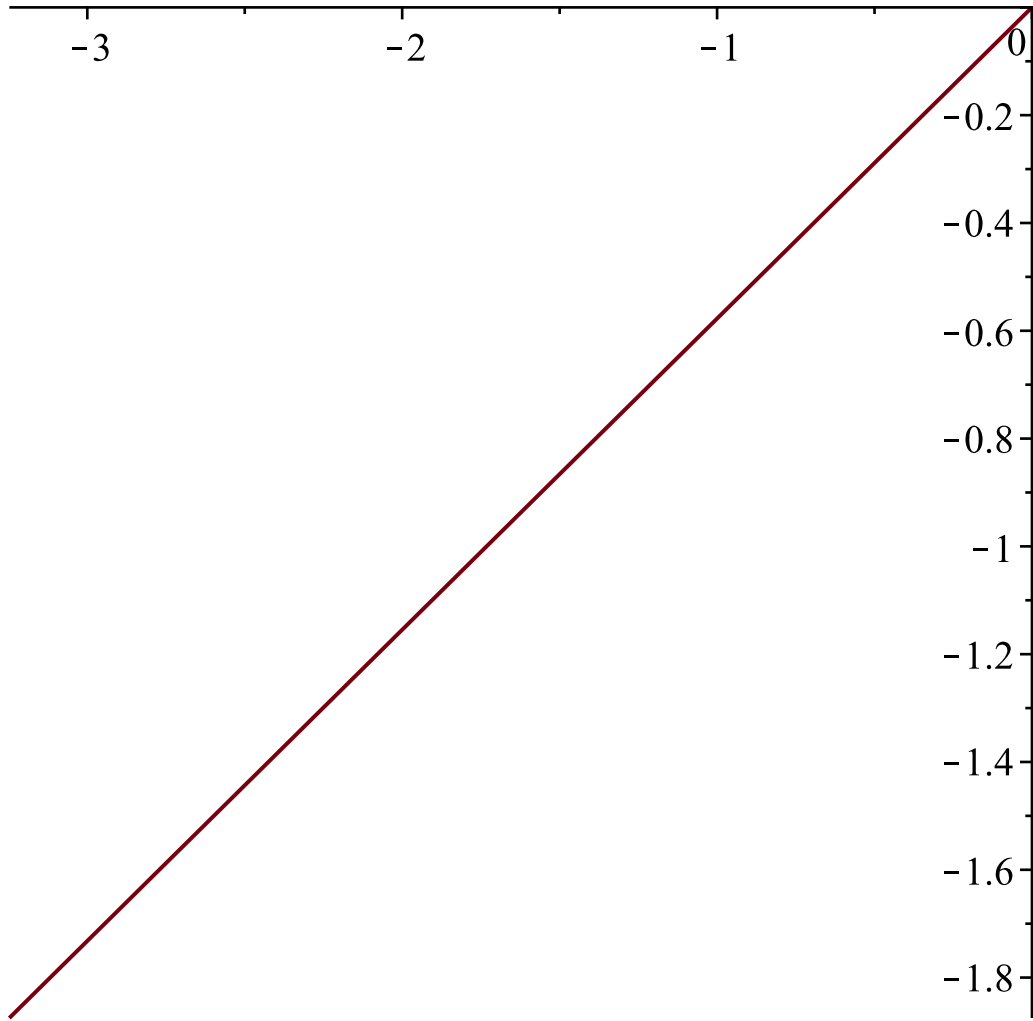
$$+ \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} \\ - c (t - t_z) \sin(\theta_0) \cos(\varphi_0) \Big) dt_z$$

$$int_z := \int_0^{tzap} \lim_{dt_z \rightarrow 0} \frac{z_izo_dtz(dt_z) - z_0}{dt_z} dt_z$$

$$\int_0^{tzap} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \Big(\cos(\theta_0)^2 dt_z v$$
(49)

$$+ \cos(\theta_0) \\ \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + c^2 dt_z^2 - 2 c^2 dt_z t + 2 c^2 dt_z t_z + c^2 t^2 - 2 c^2 t t_z + c^2 t_z^2 - dt_z^2 v^2} - c (t \\ - t_z) \cos(\theta_0) \Big) dt_z$$

$$plot \Big(\Big[evalf \Big(subs \Big(c = 1, v = 0.5, t = 5, \theta_0 = \frac{\pi}{3}, \varphi_0 = 0, int_x \Big) \Big), evalf \Big(subs \Big(c = 1, v = 0.5, t = 5, \theta_0 \\ = \frac{\pi}{3}, \varphi_0 = 0, int_z \Big) \Big), tzap = 0..5 \Big] \Big)$$



$$\begin{aligned}
 & \int_0^t evalf\left(subs\left(c=1, v=0.5, t=5, \varphi_0=0, int_x\right)\right) dt_z \\
 & \int_0^t \int_{0.}^{t_{zap}} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(\sin(\theta_0) \cos(0) \left(0.5 \cos(\theta_0) dt_z \right. \right. \\
 & \quad \left. \left. + \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2} \right) - (5 \right. \\
 & \quad \left. - t_z) \sin(\theta_0) \cos(0) \right) dt_z dt_z
 \end{aligned} \tag{50}$$

$$\begin{aligned}
 & \int_0^t evalf\left(subs\left(c=1, v=0.5, t=5, int_z\right)\right) dt_z \\
 & \int_0^t \int_{0.}^{t_{zap}} \lim_{dt_z \rightarrow 0} \frac{1}{dt_z} \left(0.5 \cos(\theta_0)^2 dt_z \right.
 \end{aligned} \tag{51}$$

$$+ \cos(\theta_0) \sqrt{0.25 \cos(\theta_0)^2 dt_z^2 + 0.75 dt_z^2 - 10 dt_z + 2 dt_z t_z + 25 - 10 t_z + t_z^2 - (5 - t_z) \cos(\theta_0)} dt_z dt_z$$

`plot([subs()], t2=0..2)`

Error, invalid input: subs expects 1 or more arguments, but received 0

$$\begin{aligned} & \text{simplify}\left(\frac{x_{izo_dtz}(dt_z) - x_0}{dt_z}\right) \\ & \frac{1}{dt_z} \left(\left(\cos(\theta_0) dt_z v + (-t + t_z) c \right. \right. \\ & \quad \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c + dt_z v) ((t - t_z - dt_z) c - dt_z v)} \right) \right. \\ & \quad \left. \cos(\varphi_0) \sin(\theta_0) \right) \end{aligned} \tag{52}$$

$$\begin{aligned} & \text{simplify}\left(\frac{y_{izo_dtz}(dt_z) - y_0}{dt_z}\right) \\ & \frac{1}{dt_z} \left(\left(\cos(\theta_0) dt_z v + (-t + t_z) c \right. \right. \\ & \quad \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c + dt_z v) ((t - t_z - dt_z) c - dt_z v)} \right) \right. \\ & \quad \left. \sin(\varphi_0) \sin(\theta_0) \right) \end{aligned} \tag{53}$$

$$\begin{aligned} & \text{simplify}\left(\frac{z_{izo_dtz}(dt_z) - z_0}{dt_z}\right) \\ & \frac{1}{dt_z} \left(\left(\cos(\theta_0) dt_z v + (-t + t_z) c \right. \right. \\ & \quad \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c + dt_z v) ((t - t_z - dt_z) c - dt_z v)} \right) \cos(\theta_0) \right) \\ & \text{simplify}\left(\frac{xy_{izo_dtz}(dt_z) - xy_0}{dt_z}\right) \end{aligned} \tag{54}$$

$$\frac{1}{dt_z} \left(\left(\sin(\theta_0)^2 \left(\cos(\theta_0) dt_z v \right. \right. \right. \quad (55)$$

$$\left. \left. \left. + \sqrt{\cos(\theta_0)^2 dt_z^2 v^2 + ((t - t_z - dt_z) c + dt_z v) ((t - t_z - dt_z) c - dt_z v)} \right)^2 \right)^{1/2} + (-t \right.$$

$$\left. + t_z) c \sin(\theta_0) \right)$$

$$\text{simplify}(x_izo_t\text{zap_normal}(p_t_{z2}))$$

$$\cos(\varphi_0) \left(\sqrt{v^2 (t_z - t_{z2})^2 \cos(\theta_0)^2 + (c^2 - v^2) t_{z2}^2 + (-2 c^2 t + 2 t_z v^2) t_{z2} + c^2 t^2 - t_z^2 v^2} \right. \quad (56)$$

$$\left. - v \cos(\theta_0) (t_z - t_{z2}) \right) \sin(\theta_0)$$

$$\text{simplify}(y_izo_t\text{zap_normal}(p_t_{z2}))$$

$$\sin(\varphi_0) \left(\sqrt{v^2 (t_z - t_{z2})^2 \cos(\theta_0)^2 + (c^2 - v^2) t_{z2}^2 + (-2 c^2 t + 2 t_z v^2) t_{z2} + c^2 t^2 - t_z^2 v^2} \right. \quad (57)$$

$$\left. - v \cos(\theta_0) (t_z - t_{z2}) \right) \sin(\theta_0)$$

$$\text{simplify}(z_izo_t\text{zap_normal}(p_t_{z2}))$$

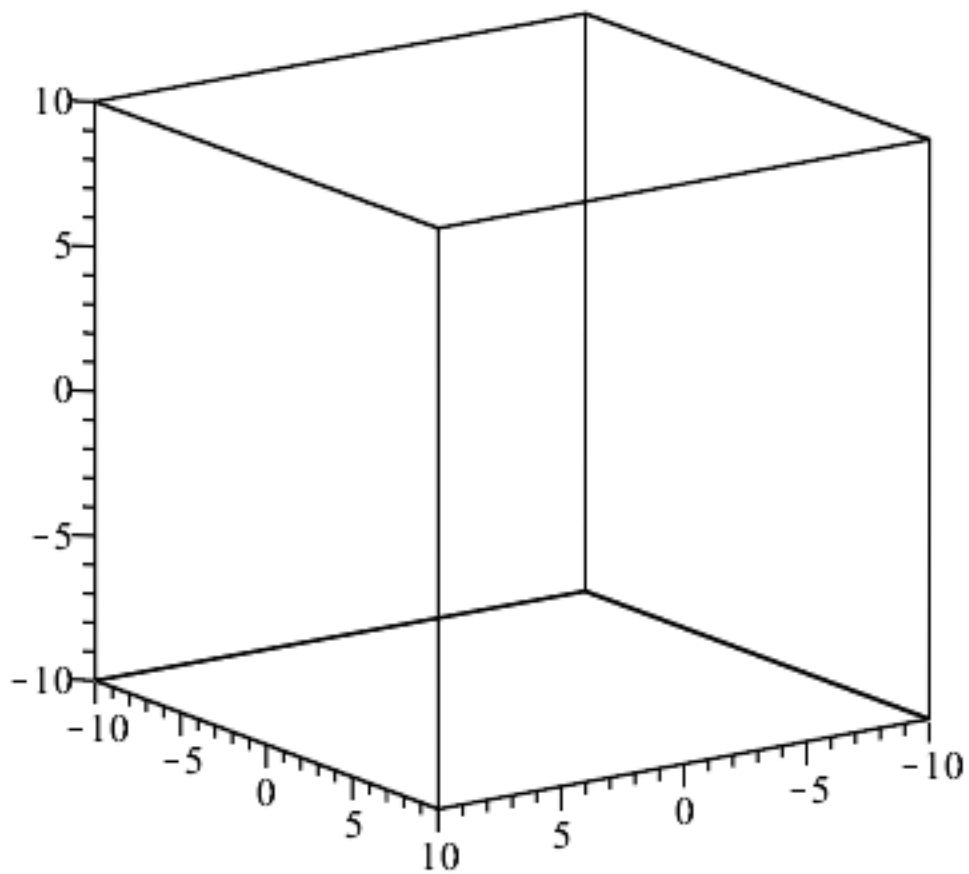
$$\sqrt{v^2 (t_z - t_{z2})^2 \cos(\theta_0)^2 + (c^2 - v^2) t_{z2}^2 + (-2 c^2 t + 2 t_z v^2) t_{z2} + c^2 t^2 - t_z^2 v^2} \cos(\theta_0) \quad (58)$$

$$- v \left((t_z - t_{z2}) \cos(\theta_0)^2 - t_z \right)$$

$$\text{spacecurve} \left(\left[\text{subs} \left(c = 1, t = 5, v = 0.5, \theta = \frac{\pi}{8}, \varphi = 0, [x_z, y_z, z_z] \right), \text{subs} \left(c = 1, t = 5, v = 0.5, \theta = \frac{\pi}{10}, \varphi \right. \right. \right.$$

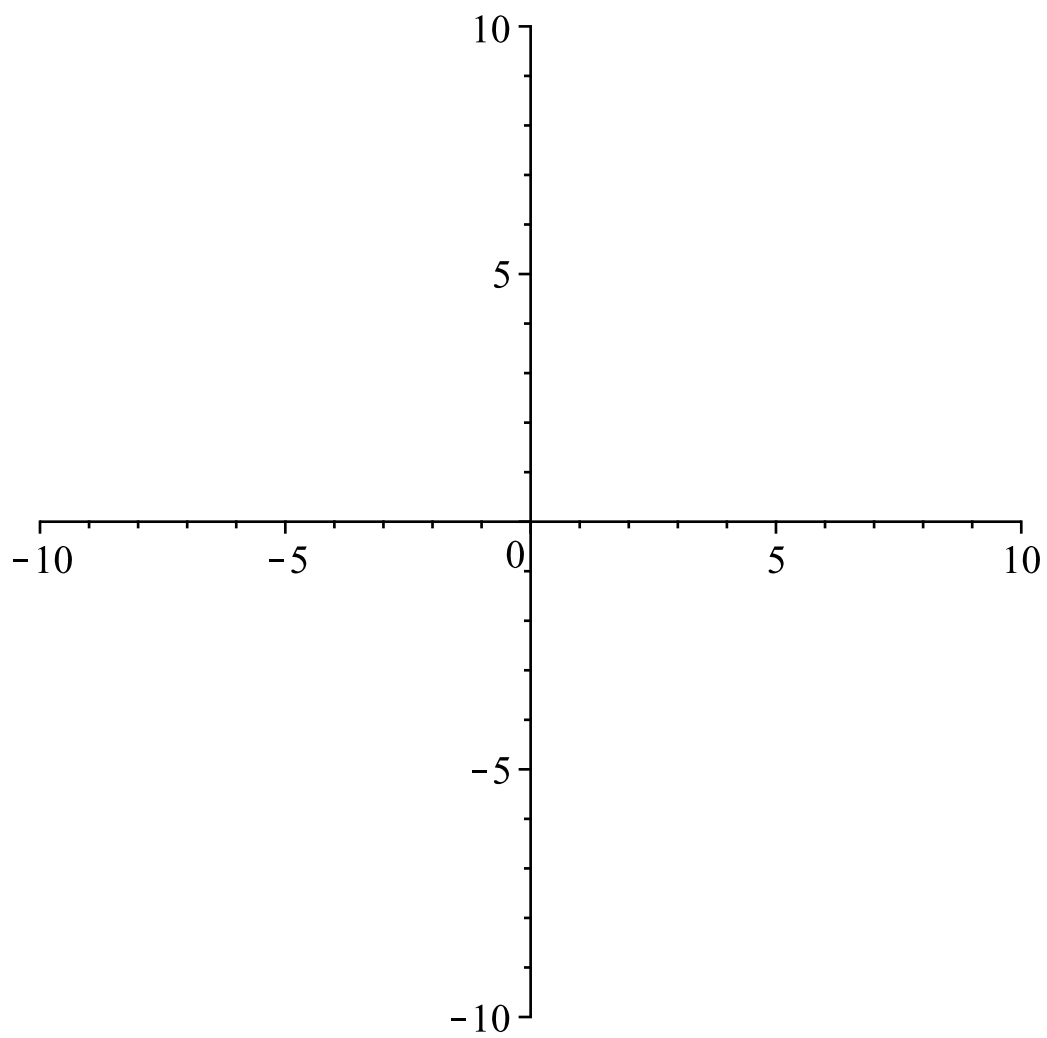
$$\left. \left. = 0, [x_z, y_z, z_z] \right) \right], t_z = 0..5, \text{thickness} = 1, \text{numpoints} = 100, \text{color} = \text{black} \right)$$

Warning, unable to evaluate the functions to numeric values in the region; see the plotting command's help page to ensure the calling sequence is correct



$plot\left(subs\left(c=1, t=5, v=0.5, \theta=\frac{\pi}{2}, [xy_z, z_z, t_z=0..t]\right)\right)$

Warning, expecting only range variable t_z in expressions [xy_z, z_z] to be plotted but found names [xy_z, z_z]

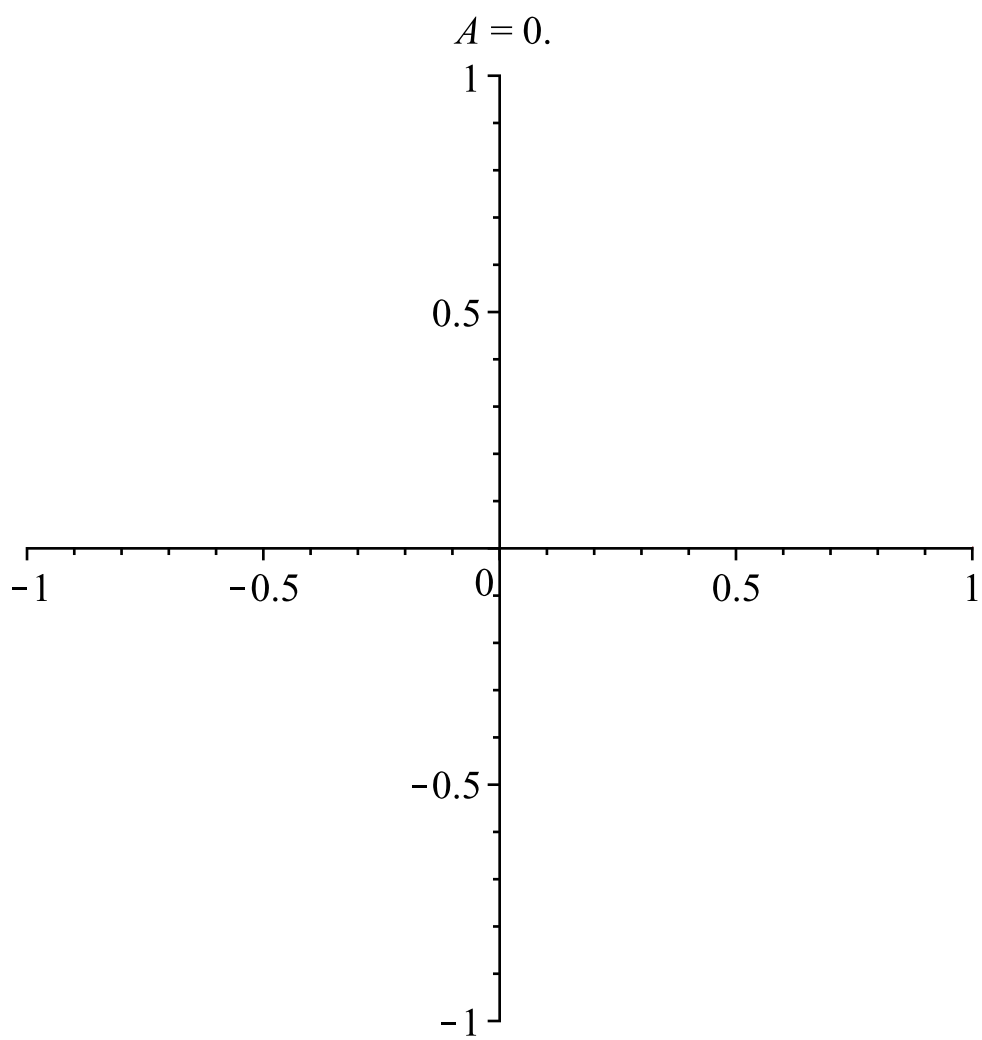


6 d

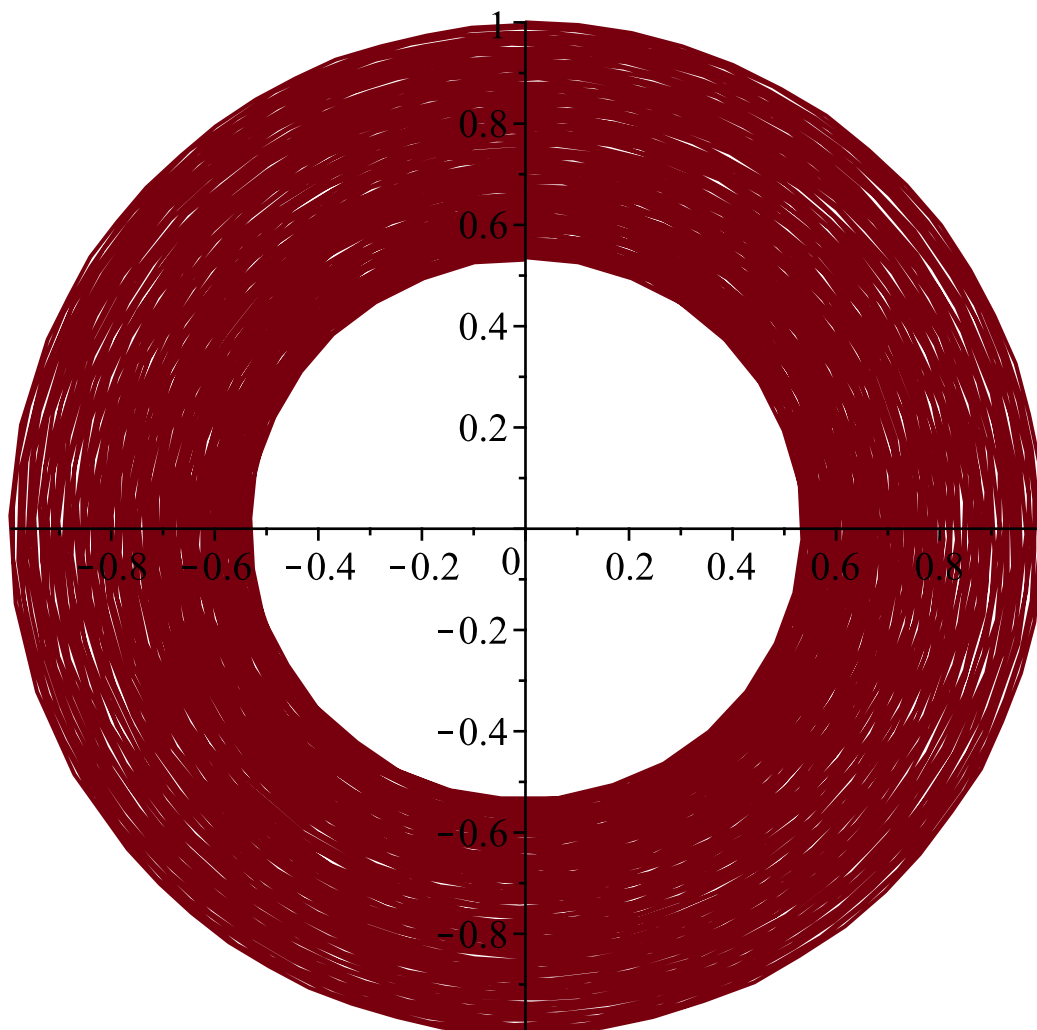
6 d

(59)

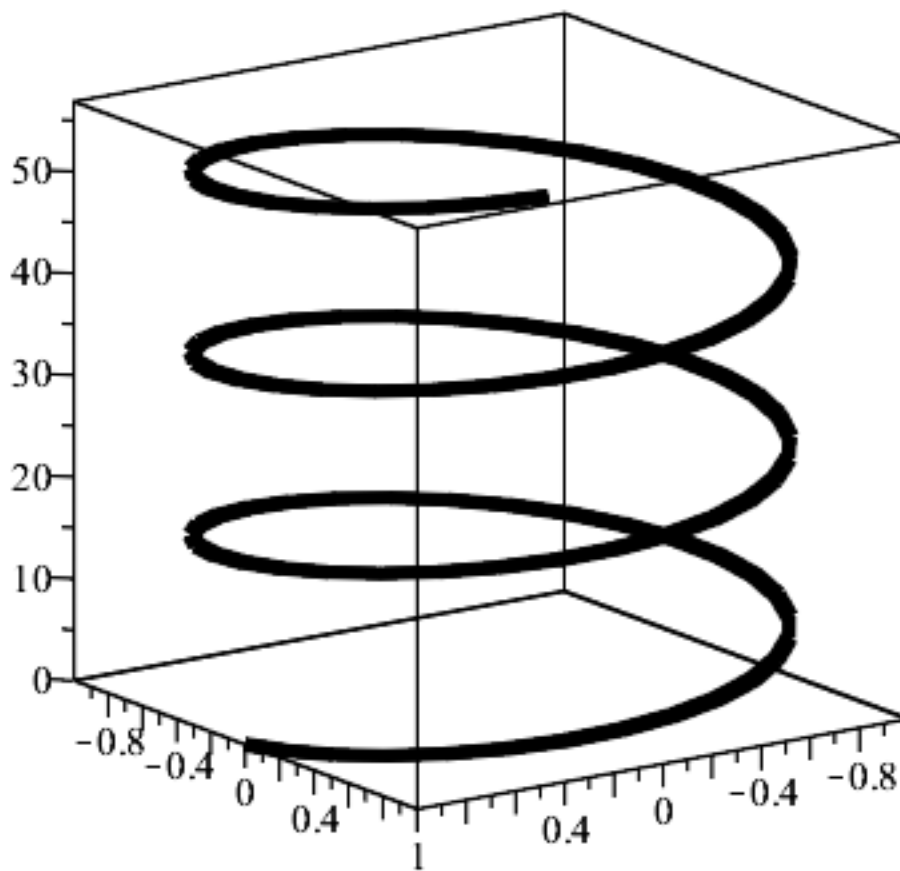
`animate(plot, [[cos(t), sin(t), t = 0 .. A]], A = 0 .. 2 π , scaling = constrained, frames = 50)`



$plot([\exp(-0.001 \cdot t) \cdot \sin(t), \exp(-0.001 \cdot t) \cdot \cos(t), t = 0 .. 200 \cdot \pi])$



```
opts := thickness=5, numpoints = 100, color = black :  
spacecurve( [cos(t), sin(t), (2 + sin(1)) t], t=0 ..20, opts)
```



animate(spacecurve, [[cos(t), sin(t), (2 + sin(A)) t], t=0..20, opts], A=0..20 π)

$$A = 0.$$

