

Iris Recognition

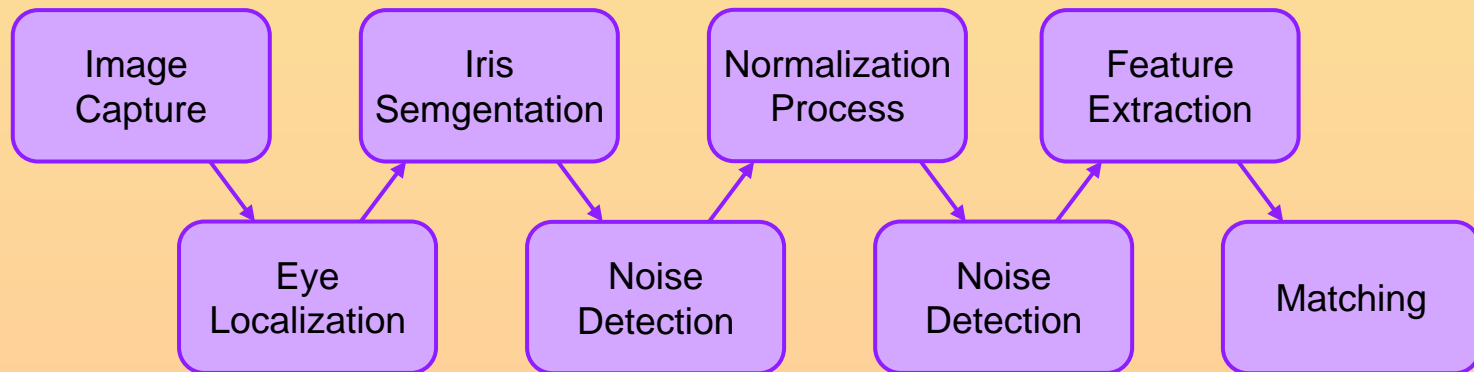
Cyrille Baptiste

Outline

- Block Diagram
- CASIA Iris image database
- Eye localization
- Iris Segmentation
- Noise detection
- Comparing iris codes
- Possible improvements

Block Diagram

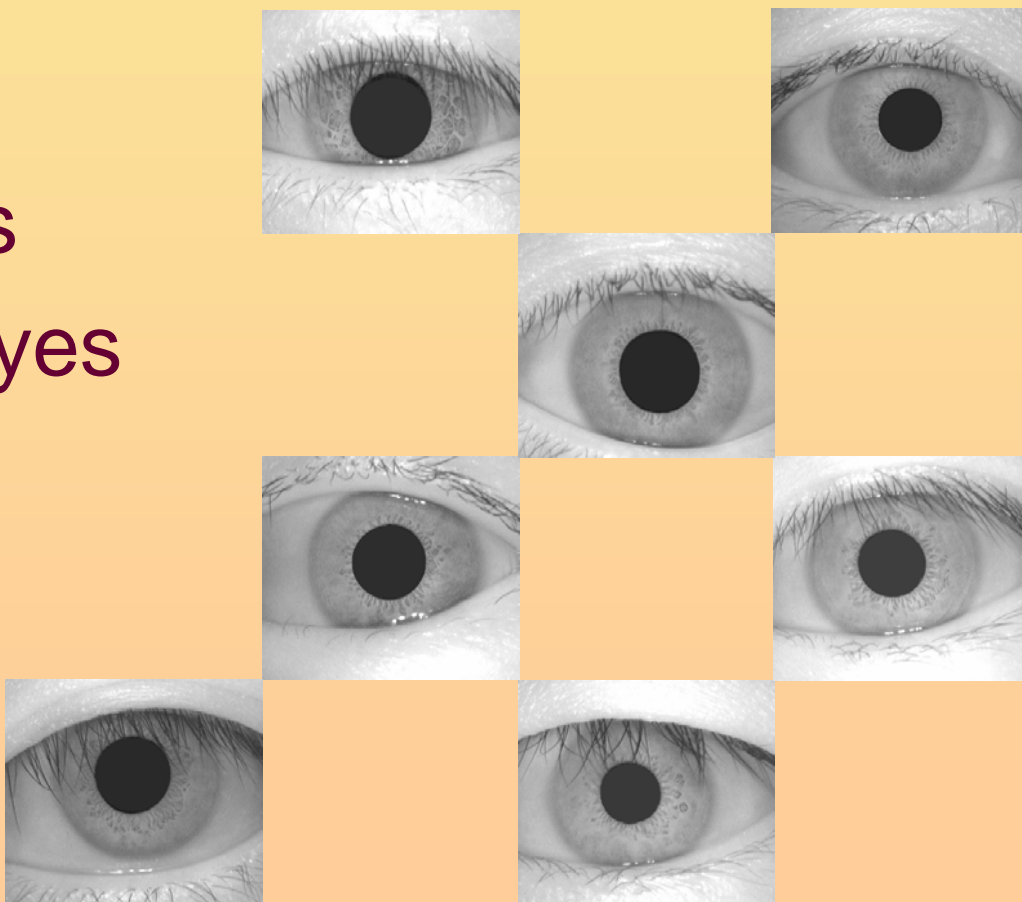
How Iris recognition works



CASIA Iris Image database

Version 1.0

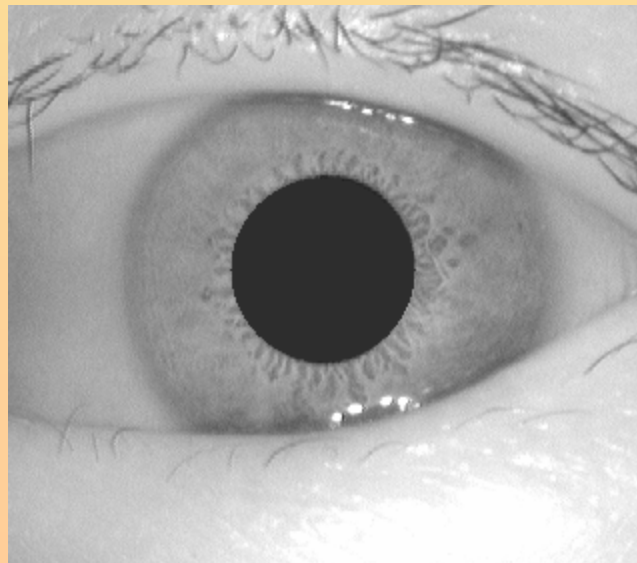
- 756 iris images
- 108 different eyes
- 7 images / eye



CASIA Iris Image database

Version 1.0

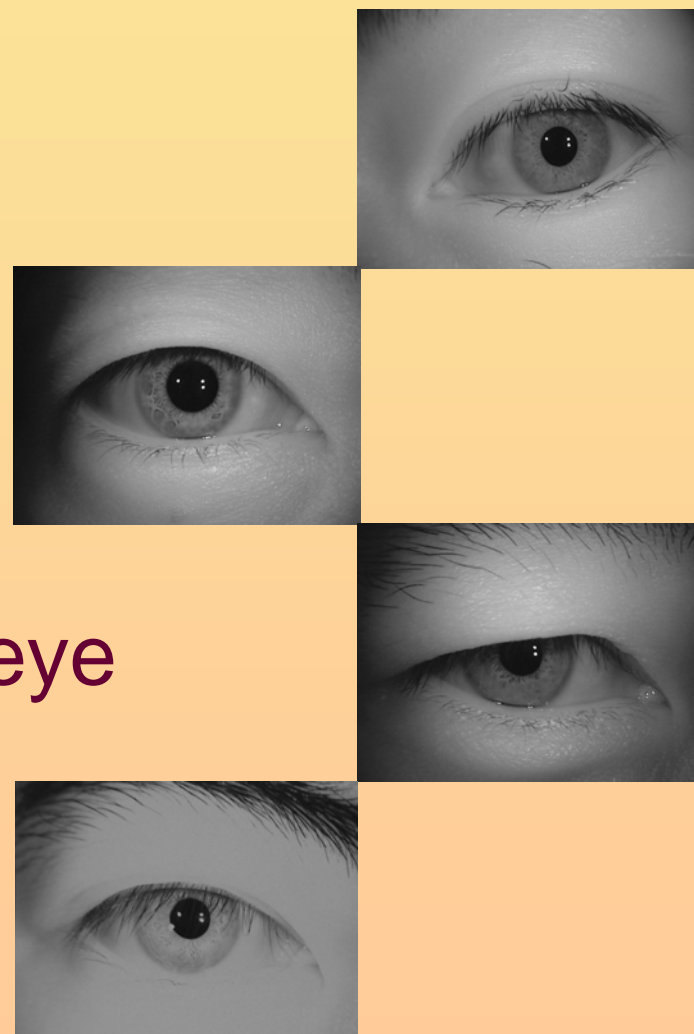
320 x 280 pixels



CASIA Iris Image database

Version 2.0

- 2400 iris images
- 60 different eyes
- 2 devices
- 20 images / device / eye



Eye localization

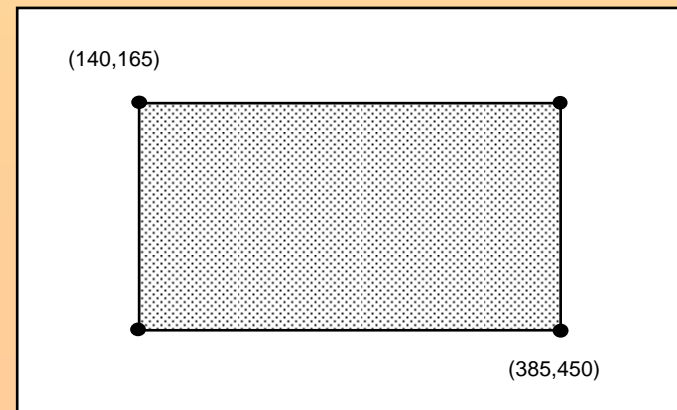
Version 2.0
640 x 480
pixels



Eye localization

Algorithm to localize the eye

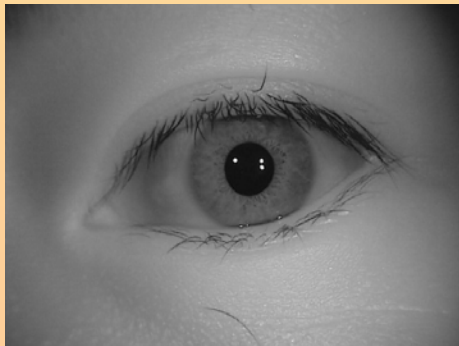
1. Mean intensity of the image
2. Cut off the interest part of the image
285 x 245 pixels
(640 x 480)



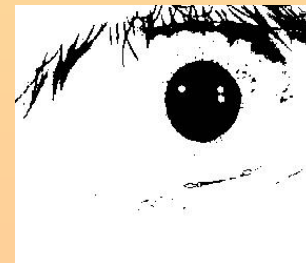
Eye localization

3. Binarization of the interest part

$$threshold = 0.52 \cdot \frac{1}{size_{image}} \sum Intensity_{pixels}$$



640 x 480



285 x 245

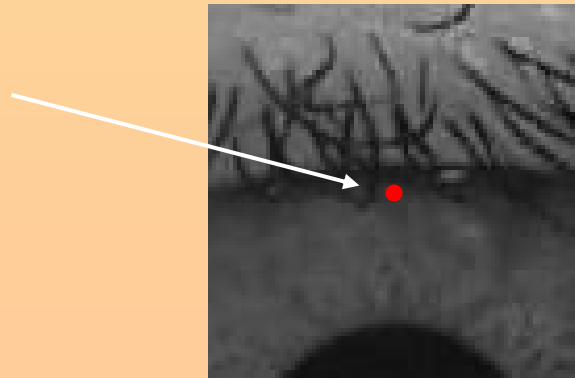
Eye localization

4. Projection in the vertical and horizontal direction

$$X_{p1} = \arg \min_x \left(\sum_y I(x, y) \right)$$

$$Y_{p1} = \arg \min_y \left(\sum_x I(x, y) \right)$$

5. 90 x 90 pixels cut off image, center is X_{p1}, Y_{p1}



Eye localization

6. Second projection in the vertical and horizontal direction

$$X_p 2 = \arg \min_x \left(\sum_y I(x, y) \right)$$

$$Y_p 2 = \arg \min_y \left(\sum_x I(x, y) \right)$$

7. Calcul of Xp3, Yp3

$$X_p 3 = 0.5 \cdot (X_p 1 + X_p 2)$$

$$Y_p 3 = 0.5 \cdot (Y_p 1 + Y_p 2)$$

Eye localization

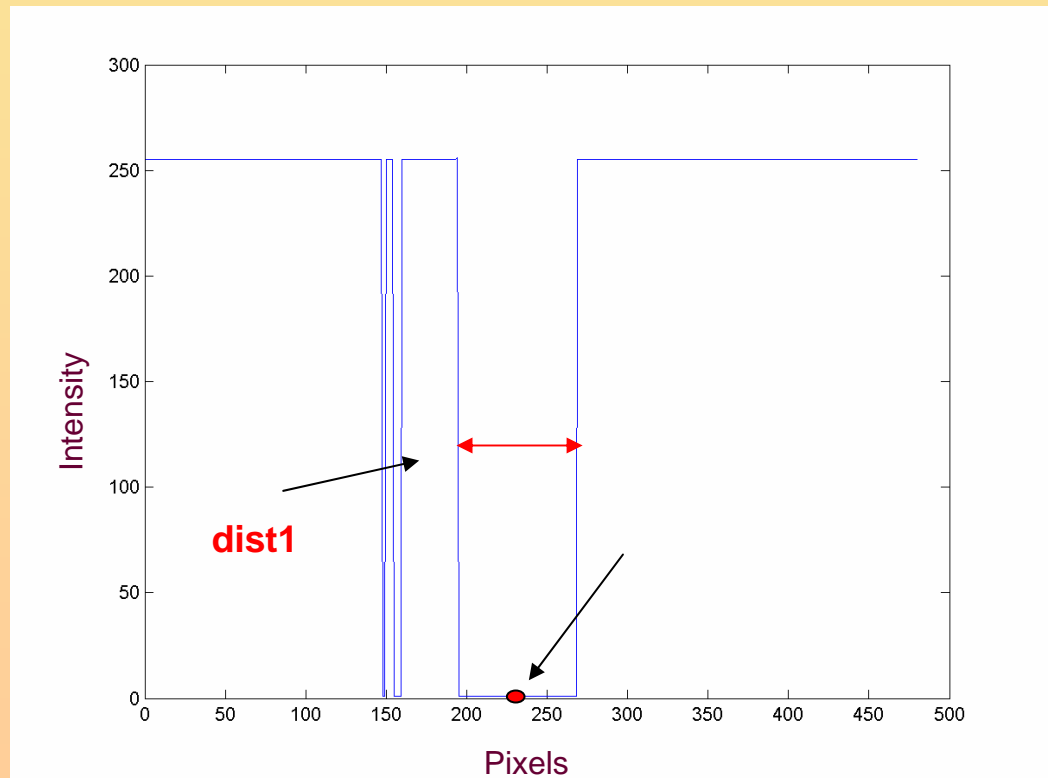
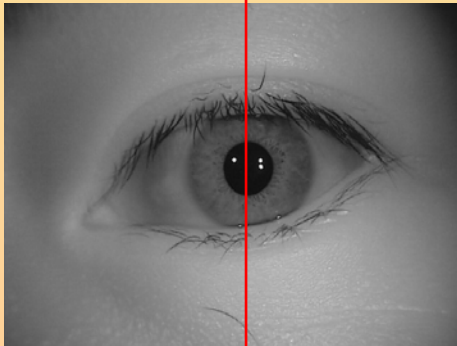
8. Binarization of the original image

$$threshold = 0.6 \cdot \left(0.52 \cdot \frac{1}{size_{image}} \sum Intensity_{pixels} \right)$$

9. Find the maximum distance between two minimum (black => intensity = 1), vertical direction at Xp3 for a new approximation of Yp3

Eye localization

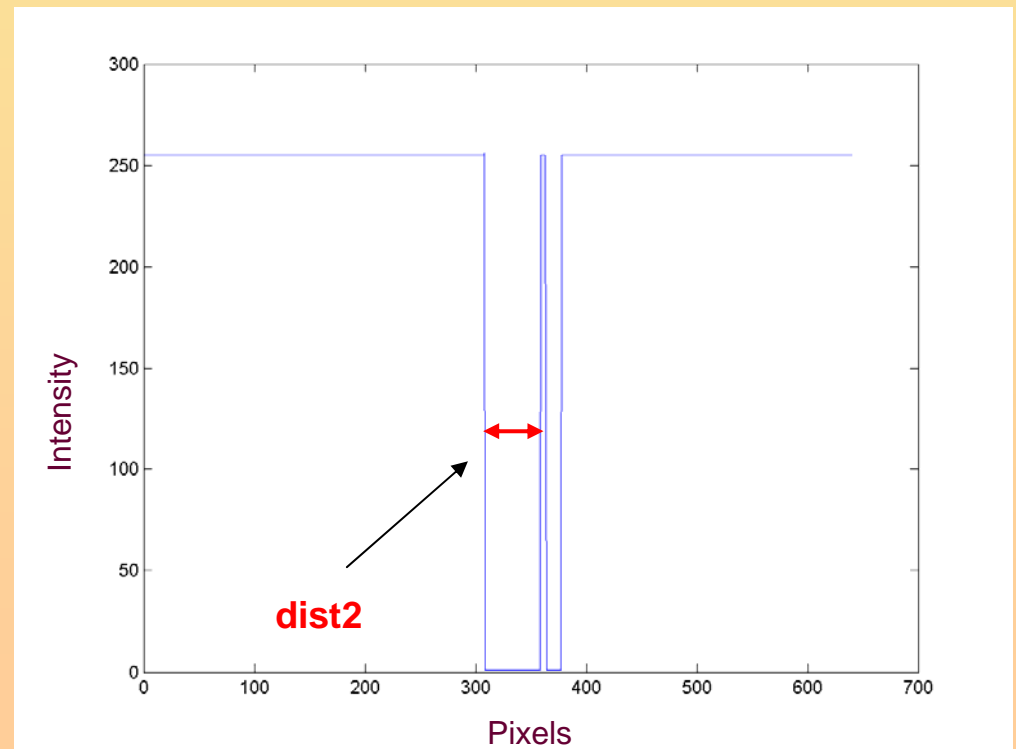
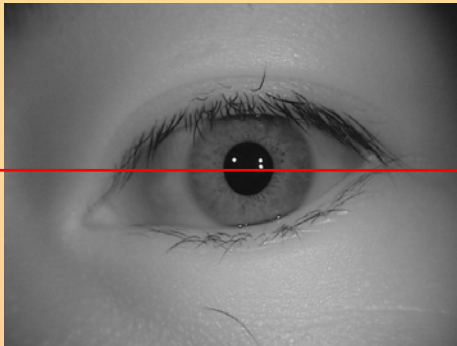
9. Suite



This distance will be use... pupil's radius

Eye localization

10. Second pupil's radius approximation



Eye localization

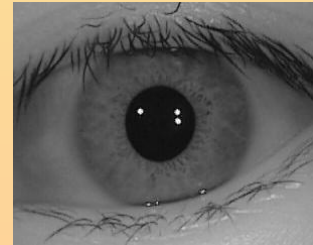
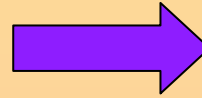
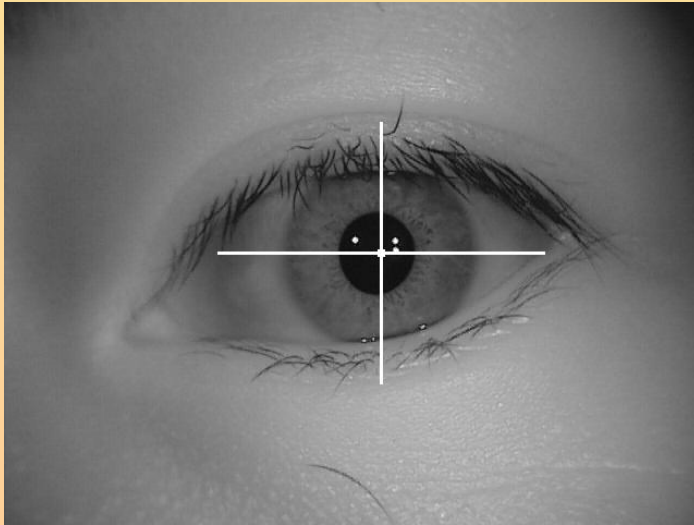
11. Second pupil's radius approximation

$$Pupil's_{Radius} = \max\left(\frac{dist1}{2}, \frac{dist2}{2}\right)$$

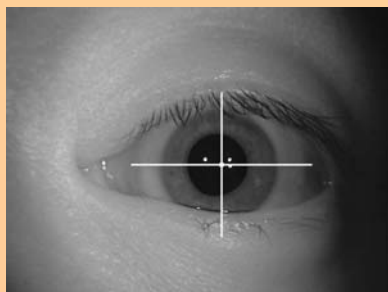
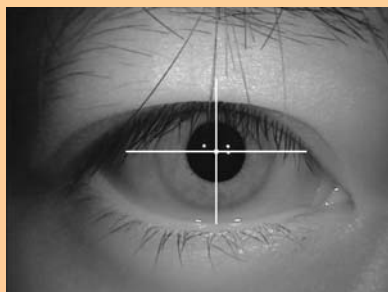
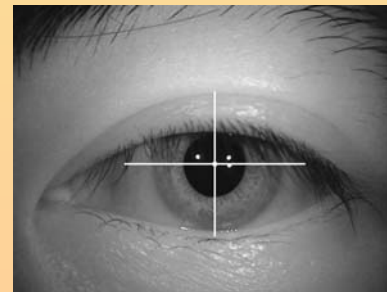
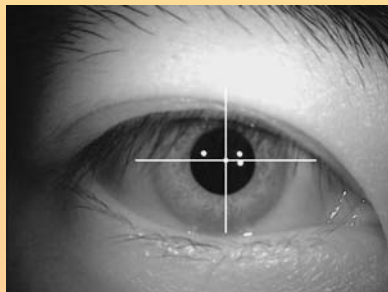
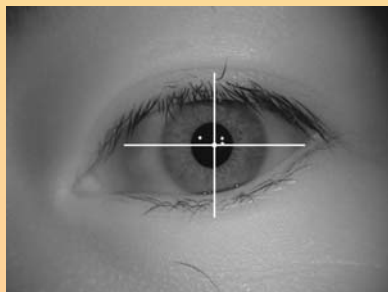
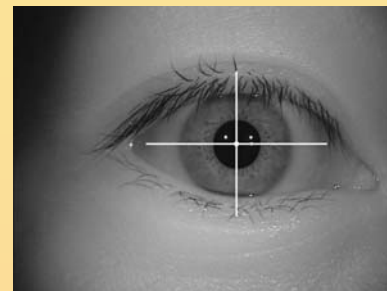
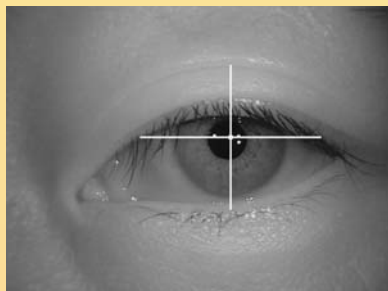
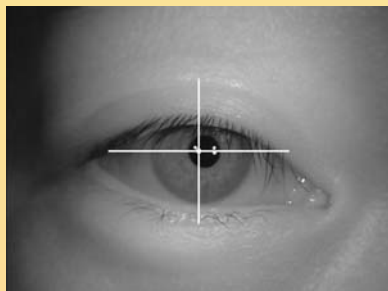
12. End... The algorithm return a 300 by 240 pixels image, center (Xp3,Yp3)

Eye localization

12. Suite



Eye localization

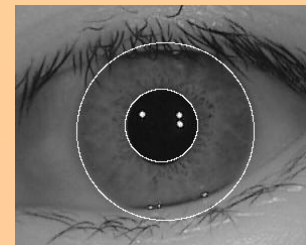


Iris Segmentation

Parameters of the pupil



“gradient amplitude”
“gamma modification”
“non-maxima suppression”
“hysteresis thresholding”.

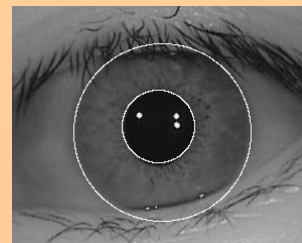
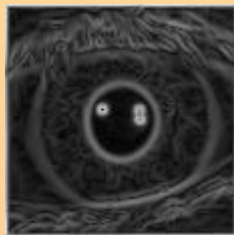


Iris Segmentation

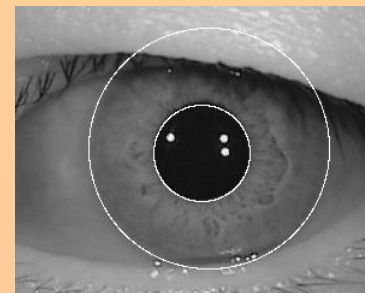
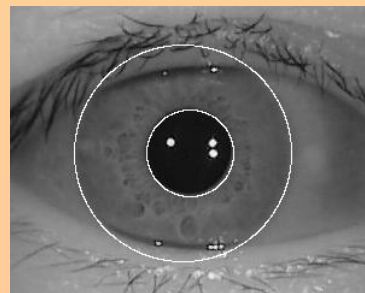
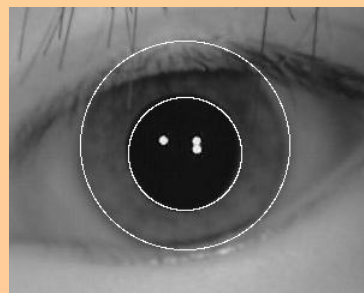
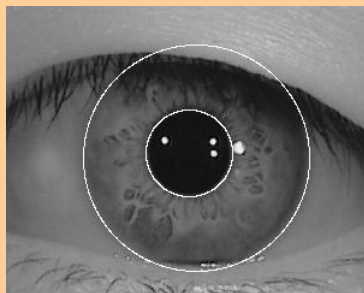
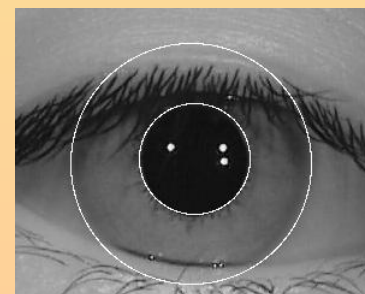
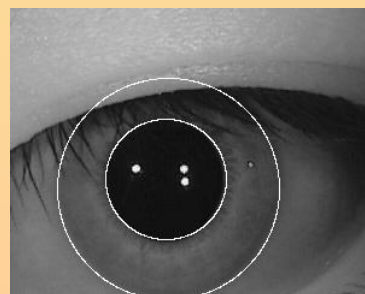
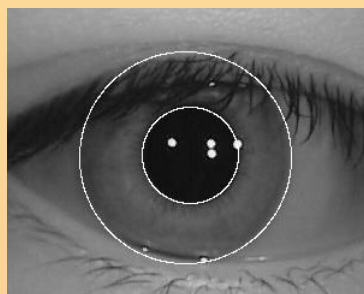
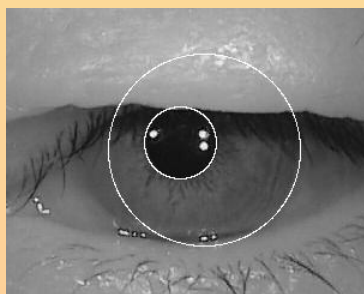
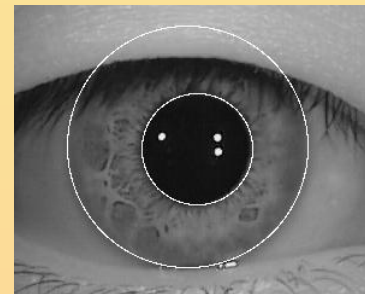
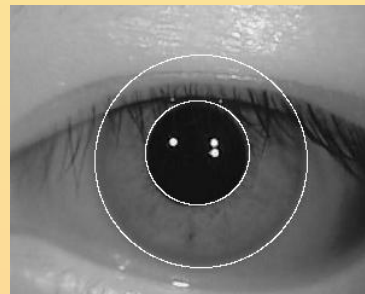
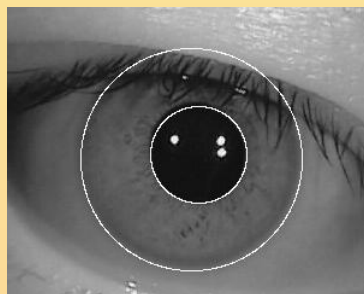
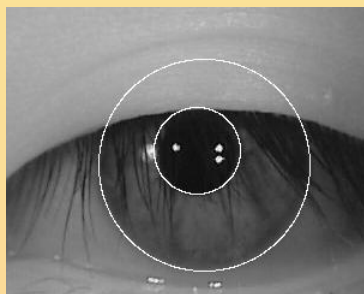
Parameters of the Iris



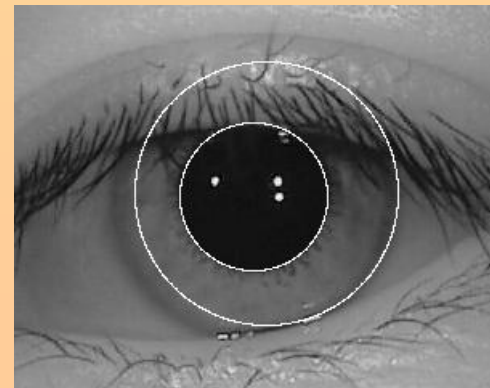
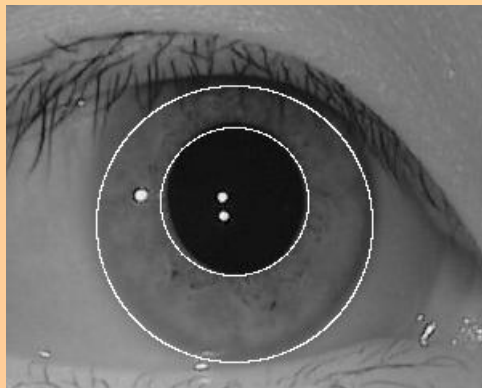
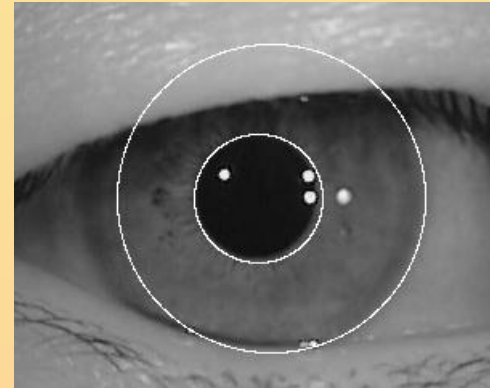
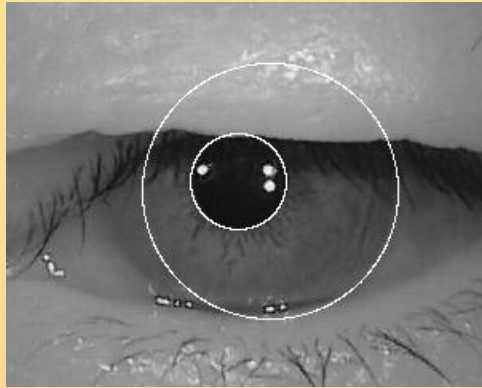
“gradient amplitude”
“gamma modification”
“non-maxima suppression”
“hysteresis thresholding”.



Iris Segmentation



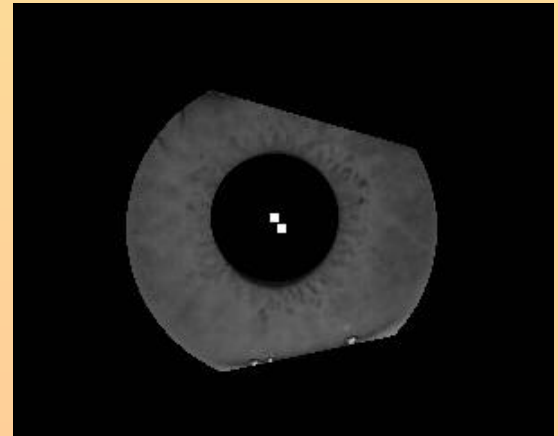
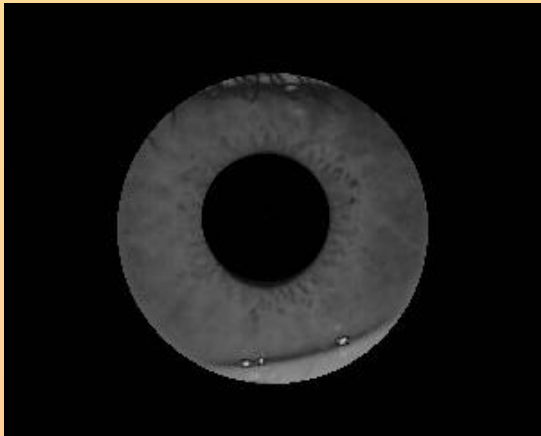
Iris Segmentation



Noise detection

Canny edge detection

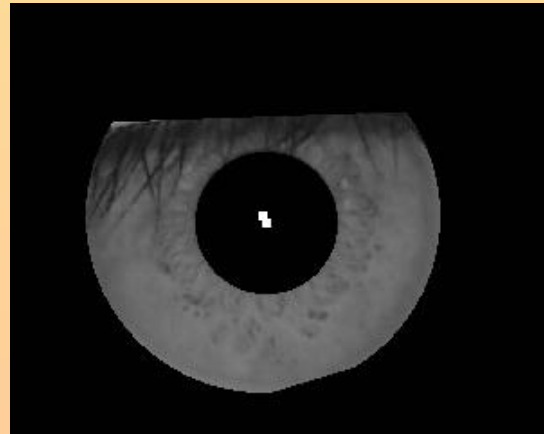
Radon transform



Noise detection

Canny edge detection

Radon transform



Noise detection

Eyelashes detection

Phase congruency details in [11]

$$N_1(x, y) = PC_2(x, y) + W_1 \left(1 - \frac{f(x, y)}{255} \right) - T_1$$

$$N_1(x, y) = \begin{cases} \geq 0 \dots \text{noise} \\ < 0 \dots \text{other} \end{cases}$$



White pixels ... mask (noise)

Comparing Iris codes

Hamming distance

$$Hd = \frac{(A \oplus B) \otimes \square mask}{Nbit_{template} - Nbit_{mask}}$$

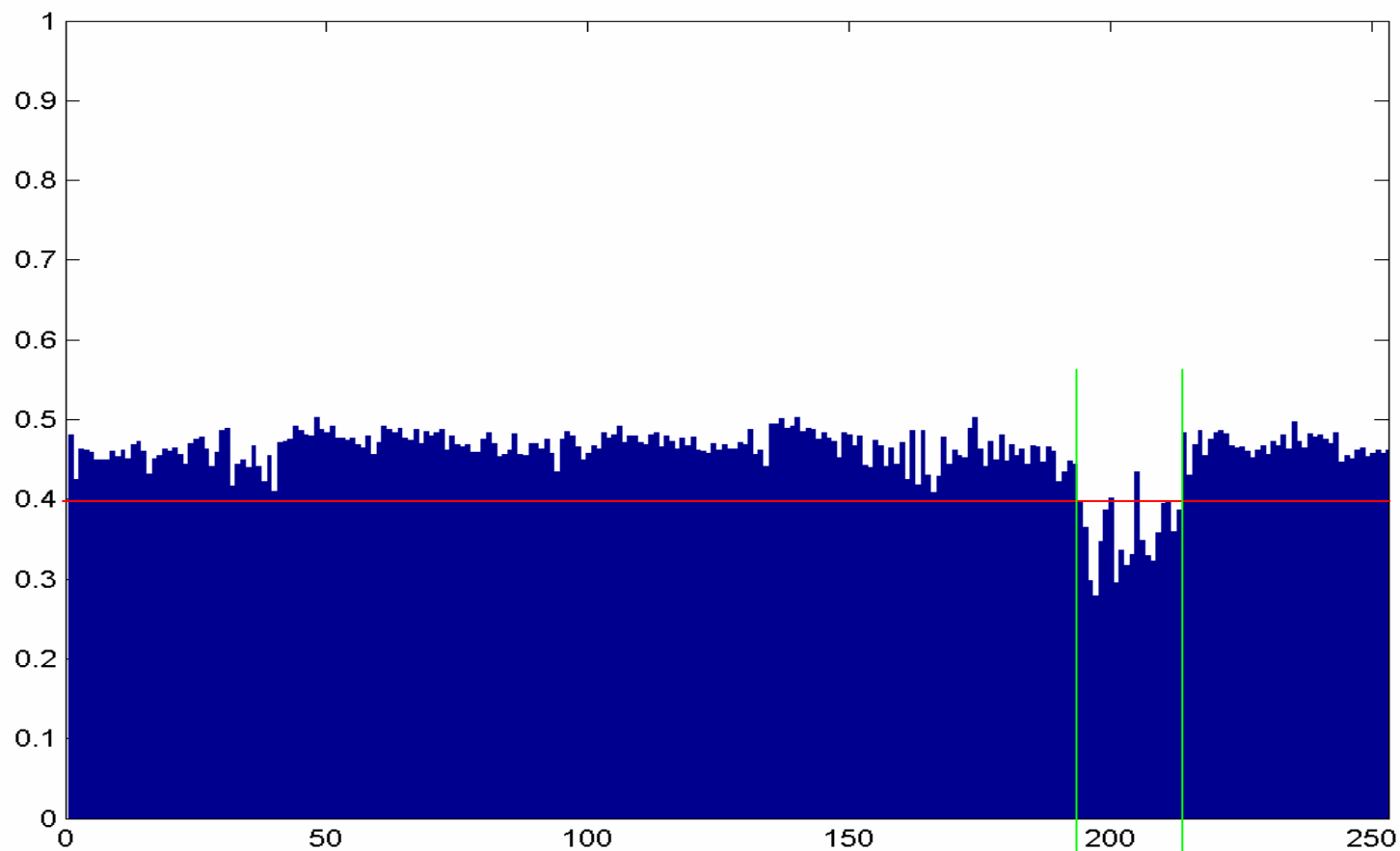
Hamming distance of two identical vectors is
Zero

Test with 253 templates from 39 different eyes

Comparing Iris codes



Comparing Iris codes



Comparing Iris codes

Eye image n°0033_0xy

[illegible]

Comparing Iris codes

[illegible]

Possible improvements

- o Eye detection, no need to cut off the original image
- o Approximation of the iris radius
- o Size of the template
- o Brightness of the normalized image, effects on results ?
- o Noise detection, eyelashes

References

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- [3] L. Ma, T.Tan, Y. Wang, D. Zhang. « Personal Identification Based on Iris Texture Analysis », *IEEE Transaction on Pattern Analysis and Machine Intelligence*, vol. 25, n°12, December 2003
- [4] Libor Masek, « Recognition of Human Iris Patterns for Biometric Identification », *School of Computer and Software Engineering, The University of Western Autralia*, 2003
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- [10] Y. Du, R. Ives, T. Welch, « *A One-Dimensional Approach for Iris Identification* », *Electrical Engineering Department, US Naval Academy, Dept. Computer Science, Univ. Maryland, Baltimore.*
- [11] J. Huang, Y. Wang, T. Tan, J. Cui, « *A New Iris Segmentation Method for Recognition* », *Proceedings of the 17th International Conference on Pattern Recognition*, 2004
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- [15] *Tsuyoshi Kawaguchi, Mohamed Rizon. « Iris detection using intensity and edge information », The Journal of pattern recognition society, 2002*
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- [17] *Peter Kovesi « Phase Congruency Detects Corners and Edges », School of Computer Science & Software Engineering, The University of Western Australia Crawley, W.A. 2003*
Delft University of Technology, 2004

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- [18] *Qi-Chuan Tian, Quan Pan, Yong-Mei Cheng, Quan-Xue Gao, « Fast Algorithm and application of Hough transform in iris segmentation », Proceedings of the Third International Conference on Machine Learning and Cybernetics, Shangai, 2004*
- [19] *M. van Ginkel, C.L. Luengo Hendriks, L.J. van Vilet, « A short introduction to the Radon and Hough transforms and how they relate to each other », Quantitative Imaging Group, Imaging Science & Technology Department, Faculty of Applied Science, Delft University of Technology, 2004*

References

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- o **Chinese Academy of Sciences (CASIA) ,
Center for Biometrics and Security Research**
www.sinobiometrics.com
- o **Webpage for John Daugman**
<http://www.cl.cam.ac.uk/users/jgd1000/>
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- **Iris Recognition Immigration System (IRIS), UK immigration,**
http://www.ind.homeoffice.gov.uk/ind/en/home/applying/iris/introduction_to_iris.html
- **UK Passport Service, Biometrics Enrolment trial**
http://www.passport.gov.uk/downloads/UKPS_Biometrics_Enrolment_Trial_Report.pdf

Matlab Code

To create an iris template

make_template('0001_014.bmp', 1, 1)

The output is **0001_014.bmp-info.mat**

This contains two matrixes mask_G and template_G

To show the iris code and the mask

load 0001_014.bmp-info.mat

Matlab Code (suite)

To compare two iris codes

```
compare_code_one_to_one('0033_005.bmp  
info.mat','0001_014.bmp-info.mat');
```

To compare one iris code to all

```
compare_code_one_to_all('0016_019.bmp  
info.mat')
```

Questions?

....

If you want more information, e-mail

`cyrille.baptiste@epfl.ch`

or

`cyrille.baptiste@unisys.ch`