1.	Which of the following statements is NOT
	a reason for adding a dropout layer?

3/3 points

$\bigcirc$	Adding a dropout layer forces the network to have a redundant representation.
	Adding a dropout layer functions as regularization

Adding a dropout layer functions as regularization.

Adding a dropout layer makes the network more expressive during training time.

Adding a dropout layer trains an ensemble of models.

## (√) Correct

Your answer is correct. In the article Surprising properties of dropout in deep networks, Helmbold and Long (2018, p. 15) write, "dropout training can hijack part of the expressiveness of the wide layer to control the artificial variance due to dropout rather than fitting the underlying patterns in the data."

Helmbold, D. P., & Long, P. M. (2018). Surprising properties of dropout in deep networks. Journal of Machine Learning Research, 18, 1-28. https://doi.org/https://www.jmlr.org/papers/volume18/16-549/16-549.pdf

Your friend built a neural network model shown below but encountered an issue while training and is asking you for advice. Model:

3/3 points

```
model = tf.keras.Sequential()
model.add(tf.keras.layers.Dense(512, activation=tf.nn.relu, input_shape=(784,)))
model.add(tf.keras.layers.Dense(256, activation=tf.nn.relu))
model.add(tf.keras.layers.Dense(182, activation=tf.nn.relu))
model.add(tf.keras.layers.Dense(NUM_CAT, activation=tf.nn.softmax))
model.summary()
Model: "sequential_10"
Layer (type)
                                          Output Shape
                                                                                               Param #
                               (None, 512)
 dense_26 (Dense)
dense_28 (Dense)
                                                (None, 128)
                                                                                               32896
 dense_29 (Dense)
                                                  (None, 10)
                                                                                               1290
Total params: 567,434
Trainable params: 567,434
Non-trainable params: 0
```

## Training log:

opt = tf.keras.optimizers.80D(learning_rate=0.5)
model.compile(Loser*categorical_crosentropy*, optimizer-ups, optim
Epoch 21/100
55 3ms/step - loss: 0.2619 - accuracy: 0.9065 - val_loss: 0.4275 - val_accuracy: 0.8648
1500/1500 [===================================
Epoch 23/100 1500/1500 [===================================
Epoch 24/100 1500/1500 [===================================
Epoch 25/100 1500/1500 [===================================
Epoch 26/100 1500/1500 [
Epoch 27/100 1500/1500 [
Epoch 28/100 1500/1500 [
Epoch 29/100
1500/1500 [
1500/1500 [
1500/1500 [
1500/1500 [
Epoch 34/100  Epoch 34/100

What are possible recommendations that can improve the result? (Select all that apply).

Increase learning rate

	Add regu dropout, lasso etc	baten norma	ms such as lization, ridge, a	and
	regulari batch n	zation terms	ect. You could a s such as dropou , ridge and lass result.	ut,
	More epo Larger ar Early stop	chitecture		
			ect. Early stoppi esults.	ing
3.	shown below	but encoun	network model tered an issue ng you for advic	e.
	model = tf.keras.Sequent model.add(tf.keras.layer model.add(tf.keras.layer model.add(tf.keras.layer model.add(tf.keras.layer	s.Dense(512, activation s.Dense(256, activation s.Dense(128, activation	n=tf.nn.relu))	,)))
	model.summary()			
	Model: "sequential_10"			
	Layer (type)	Output Shape	Param #	
	dense_26 (Dense)	(None, 512)	401920	
	dense_27 (Dense)	(None, 256)	131328	
	dense_28 (Dense)	(None, 128)	32896	

3 / 3 points

dense_29 (Dense)	(None, 10)	1290
Total params: 567,434 Trainable params: 567,436 Non-trainable params: 0	1	
Training log:		
opt = tf.keras.optimizers.SSD(learning_ra	te=0.5)	
model.compile(loss='categorical_crossentr optimizer=opt, metrics=['accuracy']) model.fit(train_images, train_labels, val		
Booch 22/100  Sb0/1500 [	] 5s 3ms/step - loss: 0.2543 - accurs ] 5s 3ms/step - loss: 0.2528 - accurs ] 5s 3ms/step - loss: 0.2453 - accurs ] 5s 3ms/step - loss: 0.2414 - accurs ] 5s 3ms/step - loss: 0.2414 - accurs ] 5s 3ms/step - loss: 0.2493 - accurs ] 5s 3ms/step - loss: 0.2585 - accurs	acy: 0.5065 - wal_iess: 0.4275 - wal_accuracy: 0.5064 acy: 0.5068 - wal_iess: 0.4236 - wal_accuracy: 0.4737 acy: 0.5068 - wal_iess: 0.4236 - wal_accuracy: 0.4737 acy: 0.5033 - wal_iess: 0.4233 - wal_accuracy: 0.4746 acy: 0.5266 - wal_iess: 0.4467 - wal_accuracy: 0.4746 acy: 0.5268 - wal_iess: 0.4467 - wal_accuracy: 0.4746 acy: 0.5268 - wal_iess: 0.4267 - wal_accuracy: 0.4746 acy: 0.5264 - wal_iess: 0.4267 - wal_accuracy: 0.4746 acy: 0.5267 - wal_iess: 0.4267 - wal_accuracy: 0.4747 acy: 0.5267 - wal_iess: 0.4267 - wal_accuracy: 0.4747
1500/1500 [	] - 5s 3ms/step - loss: nan - accuracy: ] - 5s 3ms/step - loss: nan - accuracy: ] - 4s 3ms/step - loss: nan - accuracy:	: 0.8550 - wal_loss: nan - wal_scouracy: 0.1000 : 0.0993 - wal_loss: nan - wal_scouracy: 0.1000

What is the most important fix you recommend to your friend?

0	You can add regularization terms such as dropout, batch normalization, ridge
$\bigcirc$	and lasso etc. Try a smaller architecture
$\tilde{\bigcirc}$	Early stopping
$\widetilde{\odot}$	Reduce learning rate



Your answer is correct. The training log shows that it strongly overfits after certain epochs, and the loss even diverges due to the very high learning rate. The obvious observation is that the learning rate is very high, so I recommend reducing the learning rate first and seeing how it goes. The good values for the learning rate can be obtained by trying multiple learning rate values and monitoring the train/validation loss or accuracy, and choosing the one that leads the best validation accuracy.