# SE 3K04

# Assignment 2

Assignment counts 20% of your final grade

Due Date: November 26th, 2023 @23:59

# Introduction

There are 3 major components to this assignment. The first part is continuing to build out pacemaker functionality. The second part will require you to complete an assurance case on the safety of your design. And finally all of these changes should be reflected in your updated documentation.

# Prerequisites

1. Familiarity with the (natural language) PACEMAKER Requirements Document. Specific sections that you need to understand at this stage are:

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1 Introduction (italics for sections additional to Assignment 1)
2.1 - 2.2 Overview/Components
3.1 - 3.2 DCM (English only, 3.2.2, 3.2.3, 3.2.4 only 1 and 2, for 3.2.5 display egrams without markers)
3.4 Pacing Pulses
3.5 - 3.6 Modes and States
4.7 Real-Time Electrograms (egrams)
5 Modes and Their Programmable Parameters
Appendix A Programmable Parameters
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The document srsVVI rev 2 provides formal requirements for VVI mode. You should consult this document if you are unsure of the exact pacing requirements you will need in the future. Also, use this document for a serial protocol for communications, and details regarding egrams (electrograms).

- 2. Familiarity with pacemaker\_shield\_explained.pdf to understand how to operate the pacemaker shield.
- 3. Familiarity with software development on the hardware platform.

# Part 1 - Pacemaker Design

This assignment uses the model developed in the previous assignment and adds on to its functionality. You are required to implement three different functionalities:

- 1. Have a working implementation of the following modes using all meaningful programmable parameters: AOO, VOO, AAI, VVI, AOOR, VOOR, AAIR, VVIR.
- 2. Rate adaptive modes must track activity using the on-board accelerometer. The pulse rate (LRL) should increase once sufficient activity is detected. It is the responsibility of each group to design and justify the rate at which the LRL changes.
- 3. If you haven't already done so for assignment 1, all the modes must be integrated into one model.

<u>Demo scenario for Rate Adaptivity:</u> The pacemaker will be shaken by hand to simulate various speeds of activity; walking, jogging, and running. The device's rate should change accordingly.

## Part 2 - Assurance Case

As you have now designed a safety critical embedded system, the pacemaker, it is of critical importance that you be able to generate assurance in why your system is safe. This is referred to as an assurance case. For part 2 of the assignment you are supposed to generate an assurance case for the safety requirements and specifications that you have implemented in your design.

# 1 Part 3 - DCM

- 1. Expand the DCM to include all required modes and parameters.
- 2. Implement serial communication to transmit and receive information between the DCM and the Pacemaker.
- 3. The system will be able to set, store, transmit programmable parameter data, and verify it is stored correctly on the Pacemaker device. A minimal set of the parameter data is specified in the *srsVVI rev 2* document in section 3.1); the complete set is in PACEMAKER, Table 7.

The following requirement changes are introduced to reflect the specifications of our system and to facilitate demonstrative purposes. Accommodate these changes in your implementation.

Parameter	Programmable Values	Increment	Nominal	Tolerance
A or V Pulse Amplitude Regulated	Off, 0.1-5.0V	0.1V	5V	$\pm 12\%$
A or V Pulse Width	1-30 ms	$1 \mathrm{ms}$	1 ms	$1 \mathrm{\ ms}$
A or V Sensitivity	0-5V	0.1V	-	$\pm 2\%$

- 4. The system will be able to display egram data when the user chooses to do so (for either ventricle, atrium, or both). The DCM must receive the egram data from the Pacemaker over the serial communication link in order to display it.
- 5. Document how programmable parameters originate at the DCM and are implemented in the device. Show how you can ensure the parameters stored in the Pacemaker are what the doctor input on the DCM. Also justify your choice of the data types used to represent parameters data.

#### What is an egram?

An egram or Electrogram is a visual output of the electrical activity inside each chamber of the heart. For our hardware, pins VENT\_SIGNAL and ATR\_SIGNAL are electrically connected to the analog egram signals for each chamber.

## Part 4 - Documentation

The Heartview testing environment allows you to build test cases by configuring natural atrial activity, ventricle activity, heart rate and AV delay to perform functional testing on the pacemaker. You are required to prove correctness in functionality and safety by designing sufficient test-sets for your implementation. When documenting the testing portion provide the following:

- 1. Purpose/Test Justification, very brief explanation
- 2. System Input
- 3. Expected Output
- 4. Actual Output
- 5. Result (Pass/Fail)

For part 4 you need to update your documentation to reflect the steps that you have taken to implement the new requirement changes that you have received or generated. This should be a continuation of your previously submitted documentation. This **SHOULD NOT** be a new document. The same principles you applied to the documentation for assignment 1 still apply to assignment 2.

# **Bonus**

When the pacemaker is performing the DDD operating mode both chambers should be receiving a pace. But remember, both chambers cannot pace at the same time! There must be an **AV delay** between their paces to allow the blood to flow from the atrium to the ventricle.

To complete the bonus you will have to implement two functionalities:

- 1. DDDR mode with the proper AV delay (don't forget to make it rate adaptive).
- 2. Inhibit only ventricular pacing when holding down the pushbutton (i.e. atrial functionality is unaffected). Once the pushbutton is released then ventricular pacing will appear.

## **Deliverables**

<u>Submission:</u> You are required to push all necessary code files to your repository. You may push as much or as little as you want as long at the repository has clear explanations on how to navigate.

Documentation Folder docs\_group#
Simulink Folder code\_group#
DCM Folder DCM\_group#

# **Design Principles**

This is a course on software development, and design principles are a huge part of being able to achieve dependable, safe and secure applications. As such, you should pay particular attention to the following design principles as you develop this project in these 2 assignments:

- 1. Separation of concerns in particular, effective modularity
- 2. Your designs must be robust with respect to anticipated changes apply information hiding.
- 3. High cohesion and low coupling of modules

#### **Deliverables**

- 1. All design and code pushed to your repository if you have one and submitted on Avenue in a zip file.
- 2. Demo in lab

# Grading

1. Demo: **60 Marks** 

Pacemaker/Simulink 25 DCM/GUI 25 Discussion 10

2. Documentation: 40 Marks

3. Bonus: 10 Marks