

MC558 - Análise de Algoritmos

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Lista 1

22.1-1

Given an adjacency-list representation of a directed graph, how long does it take to compute the out-degree of every vertex? How long does it take to compute the in-degrees?

```
1 OUT-DEGREE(G)
2   for each vertex v in G.V
3     v.out_degree = 0
4     for each vertex u in G.Adj[v]
5       v.out_degree++
```

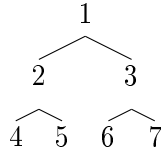
```
1 IN-DEGREE(G)
2   for each vertex v in G.V
3     v.in_degree = 0
4     for each vertex u in G.Adj[v]
5       u.in_degree++
```

According to the book, "if G is a directed graph, the sum of the lengths of all the adjacency lists is $|E|$ ". Therefore, as both OUT-DEGREE and IN-DEGREE algorithms visit every vertex and every entry of every adjacency list once, their complexity is $\Theta(V + E)$.

22.1-2

Give an adjacency-list representation for a complete binary tree on 7 vertices. Give an equivalent adjacency-matrix representation. Assume that vertices are numbered from 1 to 7 as in a binary heap.

Tree representation:



Adjacency-matrix representation:

	1	2	3	4	5	6	7
1	0	1	1	0	0	0	0
2	0	0	0	1	1	0	0
3	0	0	0	0	0	1	1
4	0	0	0	0	0	0	0
5	0	0	0	0	0	0	0
6	0	0	0	0	0	0	0
7	0	0	0	0	0	0	0

22.1-3

The transpose of a directed graph $G = (V, E)$ is the graph $G^T = (V, E^T)$, where $E^T = \{(v, u) \in V \times V : (u, v) \in E\}$. Thus, G^T is G with all its edges reversed. Describe efficient algorithms for computing G^T from G , for both the adjacency-list and adjacency-matrix representations of G . Analyze the running times of your algorithms.

```

1 TRANSPOSE-LIST(G)
2   G_t.V = G.V
3   for each vertex v in G.V
4     for each vertex u in G.Adj[v]
5       G_t.Adj[u].append(v)
6   return G_t

```

```

1 TRANSPOSE-MATRIX(G)
2   G_t = G
3   for i from 1 to |G.V|
4     for j from i+1 to |G.V|
5       swap(G_t[i][j], G_t[j][i])

```

In TRANSPOSE-LIST, the complexity analysis is the same as exercise 22.1-1, which is $O(V + E)$.

In TRANSPOSE-MATRIX, the nested loop between lines 3 and 5 has $\sum_{n=1}^V V - i$ (consider $V = |V|$) iterations, and its complexity is

$$\begin{aligned} \sum_{n=1}^V V - i &= \sum_{n=1}^V V - \sum_{n=1}^V i = V^2 - \frac{V(V+1)}{2} = \\ V^2 - \frac{V^2}{2} - \frac{V}{2} &= \frac{V^2}{2} - \frac{V}{2} = \frac{V(V-1)}{2} = \Theta(V^2) \end{aligned} \quad (1)$$

22.1-4

Given an adjacency-list representation of a multigraph $G = (V, E)$, describe an $O(V + E)$ -time algorithm to compute the adjacency-list representation of the “equivalent” undirected graph $G' = (V, E')$, where E' consists of the edges in E with all multiple edges between two vertices replaced by a single edge and with all self-loops removed.

```

1 EQUIVALENT(G)
2   G'.V = G.V
3   for each vertex v in G.V
4     for each vertex u in G.Adj[v]
5       if (u != v) and (u not in G'.Adj[v])
6         G'.Adj[v].append(u)
7         G'.Adj[u].append(v)
8   return G'
```

22.1-5

The square of a directed graph $G = (V, E)$ is the graph $G^2 = (V, E^2)$ such that $(u, v) \in E^2$ if and only if G contains a path with at most two edges between u and v . Describe efficient algorithms for computing G^2 from G for both the adjacency-list and adjacency-matrix representations of G . Analyze the running times of your algorithms.

```

1 SQUARE-MATRIX(G)
2   G' = G
3   for i from 1 to |G.V|
4     for j from 1 to |G.V|
5       G'[i][j] = 0
6       for k from 1 to |G.V|
7         G'[i][j] = G[i][k]*G[k][j]
8   return G'
```

```

1 SQUARE-LIST(G)
2   G'.V = G.V
3   for each vertex v in G.V
4     for each vertex u in G.Adj[v]
```

```

5     G'.Adj[v].append(G.Adj[u])
6   for each vertex v in G.V
7     COUNTING-SORT(G'.Adj[v])
8     REMOVE-DUPPLICATES(G'.Adj[v])
9   return G'

```

xx' SQUARE-MATRIX has complexity $O(V^3)$, while SQUARE-LIST has complexity $O(VE)$.

22.1-6