

### Exercise 1:

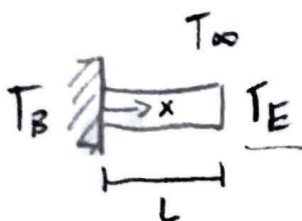
Exercise 1:  $\frac{dT}{dx^2} = \frac{h p}{k A} (T - T_\infty)$

$$Z = \frac{dT}{dx}$$

$$\bullet \quad \frac{dT}{dx} = Z \quad \begin{array}{l} T(x=0) = 600 \\ Z(x=0) = \beta \end{array}$$

$$\bullet \quad \frac{dz}{dx} = \frac{hP}{kA} (T - T_{\infty})$$

Aside  
for  
Exercise 3



$$A = \pi r^2$$
$$A = \pi \left( \frac{0.19}{2} \right)^2$$
$$A = .00785 \text{ m}^2$$

where  $h = 20 \text{ W/m}^2 \cdot \text{K}$

$L = 2.0\text{m}$     $K = 200\text{ W/m}\cdot\text{K}$

$$D = 0.1 \text{ m} \quad T_{\infty} = 300 \text{ K}$$

$$T_F = 350\text{K} \quad T_B = 600\text{K}$$

$$P = \pi D = \pi(0.1) = .314 \text{ m}$$

$$\frac{d}{dx} \begin{bmatrix} T \\ Z \end{bmatrix} = f(x, \begin{bmatrix} T \\ Z \end{bmatrix})$$

Cooling-fin: returns  $[z, \frac{dz}{dx}]$  given  $[x, [T, z], \text{constants}]$

aka: Can get  $\frac{dT}{dx}$  and  $\frac{dz}{dx}$  at a given  $T, z$

which can then be used to get  $T$  at a given  $x$  (by using Runge-Kutta solver for a system of equations).

(independent  
on x, y, z)  
then for an  
y be used in  
Runge-Kutta)

Ex. 1



$$\left| \frac{dT}{dx} = Z \right|$$

$$\frac{dz}{dx} = 4T - 1200$$

$$\begin{aligned} T(x=0) &= 600\text{K} \\ z(x=0) &= \beta \end{aligned}$$

$$\frac{dz}{dy} = \frac{hP}{KA} (T - T_{\infty}) = \frac{(20)(.314)}{(200)(.00785)} (T - 300) = 4T - 1200$$

$$z(\vec{0}) = \beta_1$$

Say  $\beta_1 = 0$

find  $T(B_i)$  using RunKutta 4

[illegible]

$x = 4$

 $x = 2$

## Exercise 2 Continued

$$\text{Set } \beta_2 = 4 \quad z(0) = \beta_2$$

	n	T <sup>n</sup>	z <sup>n</sup>	k <sub>11</sub>	k <sub>12</sub>	k <sub>21</sub>	k <sub>22</sub>	k <sub>31</sub>	k <sub>32</sub>	k <sub>41</sub>	k <sub>42</sub>	T <sup>n+1</sup>	z <sup>n+1</sup>
x=0	0	600	4	4	12000	404	1205.3	405.8	1738.7	1163.1	2282.1	904.63	1045.1
x=2/3	1	904.63	1045.1	1045.1	2438.5	782.96	3832.0	932.41	4915.8	4322.3	8631.7	2434.9	4214.1
x=4/3	2	2434.9	4219.1	4219.1	8539.9	7065.26	1165.44	8444.92	17460.9	11619.1	32382.4	8260.1	15405.24
x=2	3	8260.05	15405.24										

T at boundary should be 350K

Interleaved  
values  
shared in calculator

Now:  $z^0 = \beta_1 + \frac{\beta_2 - \beta_1}{T_1 - T_0} (T_1 - T_0) = 0 + \frac{4 - 0}{8260.05 - 8207.4} (350 - 8207.4)$

Since linear ODE  $z^0 = -596.771$

Now can solve IVP knowing  $T^0 = 600$   $z^0 = -596.771$  at  $x=0$

Runge Kutta Again

	n	T <sup>n</sup>	z <sup>n</sup>	k <sub>11</sub>	k <sub>12</sub>	k <sub>21</sub>	k <sub>22</sub>	k <sub>31</sub>	k <sub>32</sub>	k <sub>41</sub>	k <sub>42</sub>	T <sup>n+1</sup>	z <sup>n+1</sup>
x=0	0	600	-596.771	-596.771	1200	-196.771	1104.31	-462.0	937.6	28.32	-32.0	390.4	-168.78
x=2/3	1	390.4	-168.78	-168.78	361.78	-48.14	136.73	-123.20	297.525	29.56	33.23	336.84	-28.34
x=4/3	2	336.84	-28.34	-28.34	147.55	20.79	104.67	8.17	175.27	88.46	164.3	350	70.15
x=2	3	350	70.15										

$$T(0) = 600 \text{ K}$$

$$T(2/3) = 390.44 \text{ K}$$

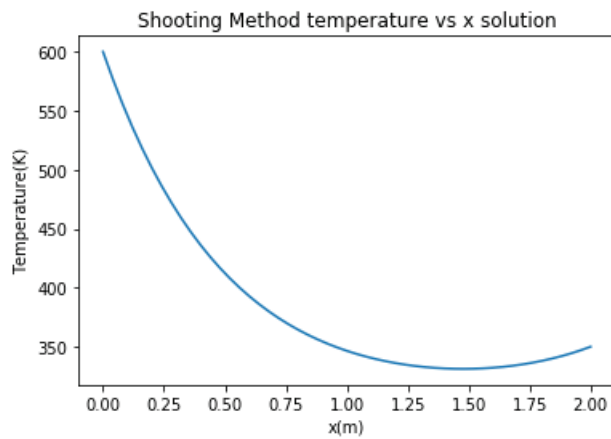
$$T(4/3) = 336.89 \text{ K}$$

$$T(2) = 350 \text{ K}$$

Python 3.6.5 |Anaconda, Inc.| (default, Mar 29 2018, 13:32:41) [MSC v.1900 64 bit (AMD64)]  
Type "copyright", "credits" or "license" for more information.

IPython 6.4.0 -- An enhanced Interactive Python.

```
In [1]: runfile('C:/Users/hoops/OneDrive/Documents/School/ME EN 2450 Numerical Methods/  
HW5/HW5b.py', wdir='C:/Users/hoops/OneDrive/Documents/School/ME EN 2450 Numerical Methods/  
HW5')
```



```
In [2]:
```



```

# -*- coding: utf-8 -*-
"""
Created on Tue Mar 19 15:56:27 2019
HW5b
@author: Ryan Dalby
"""

import math
import numpy as np
import matplotlib.pyplot as plt
from cooling_fin import cooling_fin
import scipy.integrate as integrate

import pandas as pd

#table = pd.DataFrame(columns = ["n", "y1n", "y2n", "k11", "k12", "k21", "k22", "k31", "k32", "k41", "k42"])

def runge_kutta_four(func, yInitial, xInitial, xFinal, numSteps):
    """
    Given a function(dy[]/dx = func(x,y[])) and yInitial[] values at an xInitial will find
    y[] at xFinal with a given number of steps between xInitial and xFinal
    """
    h = abs(xFinal - xInitial) / numSteps
    x = xInitial
    y = yInitial
    # row = np.empty(13)
    for i in range(numSteps):
        # print(x,y)
        # row[0] = i
        # row[1] = y[0]
        # row[2] = y[1]
        k1 = func(x, y)
        # row[3] = k1[0]
        # row[4] = k1[1]
        k2 = func(x + h/2, y + k1*h/2)
        # row[5] = k2[0]
        # row[6] = k2[1]
        k3 = func(x + h/2, y + k2*h/2)
        # row[7] = k3[0]
        # row[8] = k3[1]
        k4 = func(x + h, y + k3*h)
        # row[9] = k4[0]
        # row[10] = k4[1]
        y = y + (k1 + 2*k2 + 2*k3 + k4)/6 * h
        x = x + h
        # row[11] = y[0]
        # row[12] = y[1]
        # table.loc[i] = row
    # print(x,y)
    return y

##Define test ODE
#f = lambda t,y: 2 * (325/850) * (math.sin(t)**2) - (200*(1+y)**(3/2))/850
#print(rungeKutta4(f, 2, 0, 10, 50))

```

```
#w = integrate.solve_ivp(f, (0.0,10.0), np.array([2]))
#print(w)
```

```
def shootingMethodForCooling_fin(func, firstx, firstT, secondx, secondT, numberOfNodes, beta1, beta2):
    """
    From cooling_fin(passed in as func) which represents two linear ODEs say  $dT/dx = f(z)$  and  $dz/dx = f(T)$ 
    and two boundary conditions  $(x_1, T_1)$  and  $(x_2, T_2)$ , and number of nodes(essentially how many steps)
    and beta1 and beta2 guesses for a IVP that will satisfy a BVP
    Will return the  $z(\text{firstx})$  that allows problem to be IVP and yet satisfies BVP
    """
    xInitial = firstx #initial x value
    xFinal = secondx #x value we will integrate to

    z1Initial = beta1 #z = dT/dx; first guess for our IVP; z(firstx) = beta1
    z2Initial = beta2 #z = dT/dx; second guess for our IVP; z(firstx) = beta2

    Tb = firstT #K temperature at beginning
    Te = secondT #K temperature at end

    T1Final,_ = runge_kutta_four(func, np.array([Tb, z1Initial]), xInitial, xFinal, numberOfNodes-1)
    # print(table.to_string())
    # print()
    T2Final,_ = runge_kutta_four(func, np.array([Tb, z2Initial]), xInitial, xFinal, numberOfNodes-1)
    # print(table.to_string())

    # print(T1Final, T2Final)
    zInitial = z1Initial + ((z2Initial - z1Initial) / (T2Final - T1Final)) * (Te - T1Final) #Now we have zInitial
    # print(runge_kutta_four(func, np.array([Tb, zInitial]), xInitial, xFinal, numberOfNodes)) #Test it
    #Now that we have zInitial just solve like IVP and can change xFinal to get temperature at different x
    #Now use this zInitial value in another script to get an array of Ts at a given array of xs (calculated)
    return zInitial
```

```
def find_temperature_profile_shooting(firstx, firstT, secondx, secondT, numberOfNodes, shouldPlot):
    """
    From cooling_fin which represents two linear ODEs say  $dT/dx = f(z)$  and  $dz/dx = f(T)$ 
    and two boundary conditions  $(x_1, T_1)$  and  $(x_2, T_2)$ , and number of nodes(essentially how many steps)
    and an xDesired where the temperature will be calculated at
    Will display a plot of T vs x(if indicated to do so) and return np arrays of the x values and temperature values
    This is essentially a driver for shootingMethodForCooling_fin
    """
    d = 0.1 #m
    h = 20 #W/m^2*K
    k = 200 #W/m * K
    Too = 300 #K surrounding temperature, time at t = infinity
    func = lambda x,y: cooling_fin(x, y, d, h, k, Too) #Cooling fin returns [dT/dx, dz/dx] given [x, y]
```

```
zInitialAtfirstx = shootingMethodForCooling_fin(func, 0, 600, 2.0, 350, numberOfNodes, 0, 4) #Initial guess
xVals = np.linspace(firstx, secondx, numberOfNodes)
TVals = []
solverIterations = 30 #how many iterations our solver will take per value it is solving for
for xVal in xVals:
```

```

        TVal, _ = runge_kutta_four(func, [firstT, zInitialAtfirstx], firstx, xVal, solverIterations)
        TVals.append(TVal)
#     print(table.to_string())
    if(shouldPlot):
        fig, ax = plt.subplots()
        ax.plot(xVals, TVals)
        ax.set_title("Shooting Method temperature vs x solution")
        ax.set_xlabel("x(m)")
        ax.set_ylabel("Temperature(K)")
    return xVals, TVals

```

```

shootingx, shootingT = find_temperature_profile_shooting(0, 600, 2.0, 350, 51, shouldPlot=True)

```