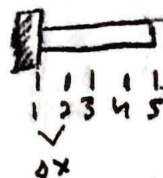


Exercise 4

$$\frac{d^2 T}{dx^2} = \frac{hP}{KA} (T - T_\infty) = 4(1 - 300) \quad \text{From Exercise 2}$$

$$\frac{d^2 T}{dx^2} - \frac{hP}{KA} (T - T_\infty) = 0$$



$$L = 2.0 \text{ m}$$

$$\Delta x = \frac{2.0}{4} = 0.5$$

$$\frac{d^2 T}{dx^2} - 4(T - 300) = 0$$

$$\frac{T_{i+1} - 2T_i + T_{i-1}}{\Delta x^2} - 4(T_i - 300) = 0 \quad \frac{hP}{KA} = \frac{(20)(\pi(1))}{(200)\pi(\frac{1}{2})^2} = 4$$

$$-T_{i-1} + (2 + 4\Delta x^2)T_i - T_{i+1} = 4(300)\Delta x^2$$

$$-T_1 + (3T_2) - T_3 = 300 \quad \text{when } T_1 = 600 \text{ K}$$

$$-T_2 + 3T_3 - T_4 = 300 \quad T_5 = 350 \text{ K}$$

$$-T_3 + 3T_4 - T_5 = 300$$

$$\begin{bmatrix} 3 & -1 & 0 \\ -1 & 3 & -1 \\ 0 & -1 & 3 \end{bmatrix} \begin{bmatrix} T_2 \\ T_3 \\ T_4 \end{bmatrix} = \begin{bmatrix} 900 \\ 300 \\ 650 \end{bmatrix}$$

Forward Elimination

$$\left[\begin{array}{ccc|c} 3 & -1 & 0 & 900 \\ -1 & 3 & -1 & 300 \\ 0 & -1 & 3 & 650 \end{array} \right] \rightarrow \left[\begin{array}{ccc|c} 3 & -1 & 0 & 900 \\ 0 & 2.67 & -1 & 600 \\ 0 & 0 & 2.67 & 815 \end{array} \right]$$

Back Substitution

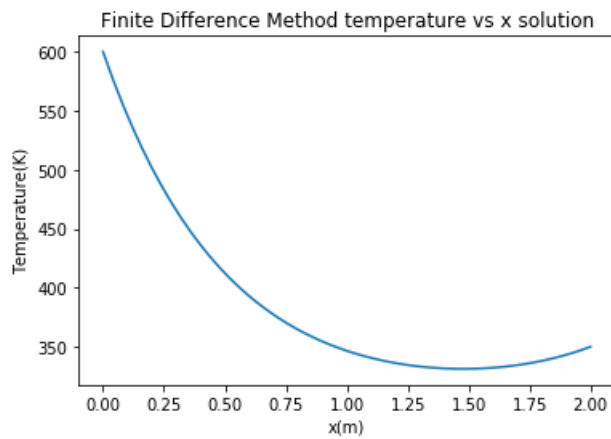
$$\begin{bmatrix} T_2 \\ T_3 \\ T_4 \end{bmatrix} = \begin{bmatrix} 416.67 \\ 350 \\ 333.33 \end{bmatrix}$$

$$\begin{aligned} T_1 &= 600 \text{ K} \\ T_2 &= 416.67 \text{ K} \\ T_3 &= 350 \text{ K} \\ T_4 &= 333.33 \text{ K} \\ T_5 &= 350 \text{ K} \end{aligned}$$

Python 3.6.5 |Anaconda, Inc.| (default, Mar 29 2018, 13:32:41) [MSC v.1900 64 bit (AMD64)]
Type "copyright", "credits" or "license" for more information.

IPython 6.4.0 -- An enhanced Interactive Python.

```
In [1]: runfile('C:/Users/hoops/OneDrive/Documents/School/ME EN 2450 Numerical Methods/  
HW5/HW5a.py', wdir='C:/Users/hoops/OneDrive/Documents/School/ME EN 2450 Numerical Methods/  
HW5')
```



```
In [2]:
```

```

# -*- coding: utf-8 -*-
"""
Created on Wed Mar 27 23:54:09 2019
HW5a
@author: Ryan Dalby
"""
import numpy as np
import matplotlib.pyplot as plt
from NaiveGaussElimination import gaussElimination

def find_temperature_profile_finite(firstx, firstT, secondx, secondT, numberOfNodes, shouldPlot = True):
    """
    Given two boundary conditions (x1, T1) and (x2, T2), and number of nodes (nodes are inclusive of boundaries)
    and an xDesired where the temperature will be calculated at
    Will display a plot of T vs x (if indicated to do so) and return np arrays of the x values and T values
    """
    d = 0.1 #m
    h = 20 #W/m^2*K
    k = 200 #W/m * K
    Too = 300 #K surrounding temperature, time at t = infinity
    P = np.pi * d
    A = np.pi * (d / 2) ** 2

    deltaX = (secondx - firstx) / (numberOfNodes - 1) #delta x
    alpha = (h * P) / (k * A)

    #create A matrix that represents our finite difference equations reduced from numberOfNodes to n
    n = numberOfNodes - 2 #The number of equations needed is numberOfNodes - 2 since we know the temperatures at the boundaries
    diagNum = (2 + alpha * deltaX**2)
    A = np.diag(np.full((n), diagNum)) + np.diag(np.full((n-1), -1), 1) + np.diag(np.full((n-1), -1), -1)
    #Create b vector of size n (subtract values from first and second since we know 2 of the nodes)
    diagb = Too * alpha * deltaX**2
    b = np.full((n), diagb)
    b[0] += firstT
    b[n-1] += secondT
    TVals = np.concatenate([[firstT], np.squeeze(gaussElimination(A, b)), [secondT]])
    xVals = np.linspace(firstx, secondx, numberOfNodes)
    if(shouldPlot):
        fig, ax = plt.subplots()
        ax.plot(xVals, TVals)
        ax.set_title("Finite Difference Method temperature vs x solution")
        ax.set_xlabel("x(m)")
        ax.set_ylabel("Temperature(K)")
    return xVals, TVals

finitex, finiteT = find_temperature_profile_finite(0, 600, 2.0, 350, 51, shouldPlot=True)

```

```

# -*- coding: utf-8 -*-
"""
Created on Tue Mar 26 21:13:09 2019
Naive Gauss Elimination from HW3 Exercise 3
@author: Ryan Dalby
"""

import numpy as np

def gaussElimination(A, b):
    """
    Uses naive gauss elimination method without pivoting to determine solutions to  $Ax = b$ 
    Will directly modify A passed into upper triangular form
    """
    n = np.shape(A)[0] #assuming nxn matrix

    # print("Naive Gauss Elimination Steps:\n")
    # print("Original Matrix:")
    # print(A, "\n")
    # print("Perform forward elimination:")
    #Perform forward elimination
    for k in range(n - 1):
        for i in range(k + 1, n):
            s = A[i,k] / A[k,k]
            for j in range(k, n):
                A[i,j] = A[i,j] - s * A[k,j]
            # print("A = \n{}\nb = \n{}\n".format(A,b))
            b[i] = b[i] - s * b[k]
            # print("A = \n{}\nb = \n{}\n".format(A,b))

    # print()
    # print("Perform back substitution:")
    #Perform back substitution
    xSol = np.zeros(shape = (n,1), dtype='float')
    xSol[n-1] = b[n-1] / A[n-1,n-1] #index last element of xSol and set it to the solution value for
    # print("A = \n{}\nb = \n{}\n".format(A,b))
    for i in range(n-1, -1, -1):
        s = 0.0
        for j in range(i+1, n):
            s = s + A[i,j] * xSol[j]
        xSol[i] = (b[i] - s) / A[i,i]
    # print("x = \n{}\n".format(xSol))
    return xSol

```