Exercise

VHI = Tanh (Jaca t)

x(10s)-x(0s) = 5 / 9m tomh (Jack t) At

9=0.81 m/,2 Jan . In [cosh (1954 b)] 10 51.694. 5.269 · In[cosh (1898 6)] 110 Ca = 0.25

272.4 [In[cosh (18898)] - In[cosh[0])] 272.4 - PN[3.41027714] - ANTO) 334.178 m

Python 3.6.5 | Anaconda, Inc. | (default, Mar 29 2018, 13:32:41) [MSC v.1900 64 bit (AMD64)] Type "copyright", "credits" or "license" for more information.

IPython 6.4.0 -- An enhanced Interactive Python.

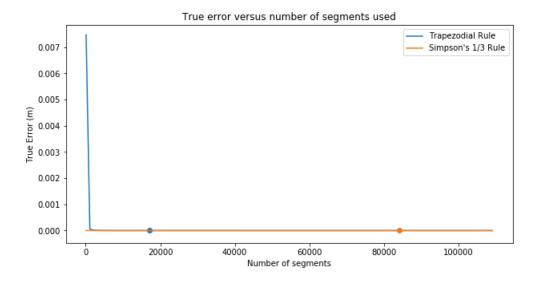
In [1]: runfile('C:/Users/hoops/OneDrive/Documents/School/ME EN 2450 Numerical Methods/
HW6/HW6b.py', wdir='C:/Users/hoops/OneDrive/Documents/School/ME EN 2450 Numerical Methods/
HW6')

Part 1:

Using the Trapezoidal Rule Integration with 10 segments the distance fallen after 10s = 333.42982m

Using the Simpson's 1/3 Rule with 10 segments distance the fallen after 10s = 334.18282m

Part 2: The optimum number of segments using the Trapezodial Rule for this problem is 17100 The optimum number of segments using Simpson's 1/3 Rule for this problem is 84100



In [2]:

```
Created on Sun Apr 7 22:43:06 2019
HW6b
@author: Ryan Dalby
   ort numpy <mark>as</mark> np
 mport matplotlib.pyplot as plt
    trapezoidalRuleIntegration(func, xi, xf, numSegments):
    Given a function f(x) and starting integration value (xi) and ending integration value (xf)
    along with the number of segments to apply the trapezoidal rule will take the definite integral between the
    h = (xf-xi)/numSegments
    x = xi #current >
    runningSum = func(x) #first segment
    x += h
    #now loop over middle segments
    for i in range(numSegments-1):
        runningSum += 2 * func(x)
        x += h
    runningSum += func(x) #final segment
    I = (h/2.0) * runningSum #integral value
   return I
    simpsonsOneThirdRuleIntegration(func, xi, xf, numSegments):
    Given a function f(x) and starting integration value (xi) and ending integration value (xf)
    along with the number of segments (must be even number) to apply simpson's 1/3 rule to take
    the definite integral between the designated values.
    if(np.mod(numSegments, 2) == 1): #if total number of segments is odd then can't use method
        raise Exception("Number of segments must be even")
    h = (xf-xi)/numSegments
    runningSum = func(x) #first segment
    x += h
    #now loop over middle segments
    for i in range(numSegments-1):
        if (np.mod((i+1), 2)) == 1 : #Segment is odd
            runningSum += 4 * func(x)
        else: #segment is even
            runningSum += 2 * \overline{func(x)}
        x += h
    runningSum += func(x) #final segment
    I = (h/3.0) * runningSum #integral value
   return I
g = 9.81 \, \frac{\#m/s^2}{2}
m = 68.1 \# kg
cd = 0.25 \# kg/
vFunc = lambda t: np.sqrt((g*m)/cd) * np.tanh(np.sqrt((g * cd)/m) * t)
print("Part 1:")
print("Using the Trapezoidal Rule Integration with 10 segments the distance fallen after 10s = \{:.5f\}m".format
```

```
print("Using the Simpson's 1/3 Rule with 10 segments distance the fallen after 10s = {:.5f}m".format(simpsonsOm
print()
print("Part 2:")
iterVals = np.arange(100, 110000, 1000)
trapError = []
simpError = []
trueVal = 334.178167 #analytical solution
 or i in iterVals: #get true error for each segment size
    trapError.append(np.abs(trueVal - trapezoidalRuleIntegration(vFunc,0,10, i)))
    simpError.append(np.abs(trueVal - simpsonsOneThirdRuleIntegration(vFunc,0,10, i)))
trapMinIndex = iterVals[np.argmin(trapError)]
trapMin = np.min(trapError)
simpMinIndex = iterVals[np.argmin(simpError)]
simpMin = np.min(simpError)
print("The optimum number of segments using the Trapezodial Rule for this problem is {}".format(trapMinIndex))
print("The optimum number of segments using Simpson's 1/3 Rule for this problem is {}".format(simpMinIndex))
fig, ax1 = plt.subplots(figsize = (10,5))
ax1.plot(iterVals, trapError, label = "Trapezodial Rule")
ax1.plot(iterVals, simpError, label = "Simpson's 1/3 Rule")
ax1.scatter(trapMinIndex, trapMin)
ax1.scatter(simpMinIndex, simpMin)
ax1.set_title("True error versus number of segments used")
ax1.set_xlabel("Number of segments")
ax1.set ylabel("True Error (m)")
ax1.legend()
```