Recorded at time: 1622302811.850 world Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1622302811.850 sec old) Buffer length: 0.000 sec base_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1622302811.850 sec old) Most recent transform: 1622302811.773 (0.077 sec old) Buffer length: 0.000 sec Buffer length: 4.800 sec shoulder_link base Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1622302811.773 (0.077 sec old) Buffer length: 4.800 sec upper_arm_link Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1622302811.773 (0.077 sec old) Buffer length: 4.800 sec forearm_link Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1622302811.773 (0.077 sec old) Buffer length: 4.800 sec wrist_1_link Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1622302811.773 (0.077 sec old) Buffer length: 4.800 sec wrist_2_link Broadcaster: /robot_state_publisher Average rate: 10.208 Hz Most recent transform: 1622302811.773 (0.077 sec old) Buffer length: 4.800 sec wrist_3_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1622302811.850 sec old) Most recent transform: 0.000 (1622302811.850 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec tool0 ee_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1622302811.850 sec old) Buffer length: 0.000 sec rod Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1622302811.850 sec old) Buffer length: 0.000 sec

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view_frames Result