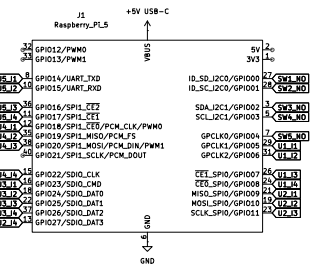
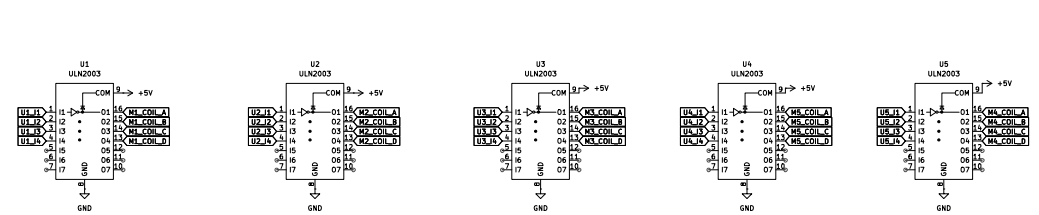


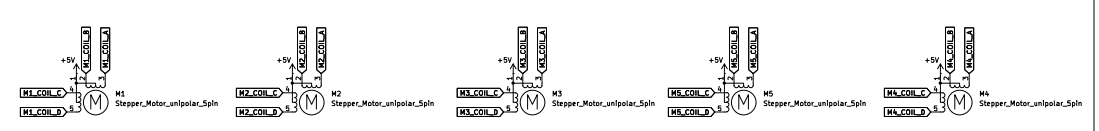
RPI 5



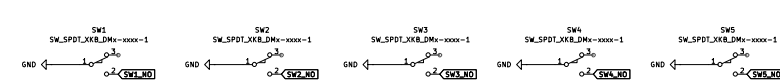
MOTOR DRIVERS



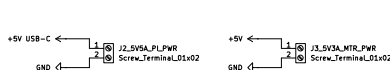
STEPPER MOTORS



LIMIT SWITCHES



POWER



COMPONENTS:

- Raspberry Pi Power: 5V @ 5A (USB-C)
- Motor Power Supply: 5V @ 3A
- Total Motors: 5
- Motor Driver: 1 per motor
- Limit Switches: 5

CALCULATIONS

Per-coil current $I_{\text{phase}} = 0.20 \text{ A}$
 Two coils energized simultaneously
 $I_{\text{motor}} = 2 \times I_{\text{phase}}$
 $I_{\text{motor}} = 2 \times 0.20 \text{ A} = 0.40 \text{ A}$ per motor

Total motor current:
 $I_{\text{totalMotors}} = 5 \times 0.40 \text{ A} = 2.00 \text{ A}$

MOTOR POWER:
 $P_{\text{motors}} = 5.0 \text{ V} \times 2.00 \text{ A} = 10.0 \text{ W}$

RASPBERRY PI CURRENT (estimate):
 $I_{\text{pi}} = 1.50 \text{ A}$ (Pi + camera + peripherals)
 $P_{\text{pi}} = 5.0 \text{ V} \times 1.50 \text{ A} = 7.50 \text{ W}$

TOTAL SYSTEM POWER (approx.):
 $P_{\text{total}} = P_{\text{motors}} + P_{\text{pi}}$
 $P_{\text{total}} = 10.0 \text{ W} + 7.5 \text{ W} = 17.5 \text{ W}$

NOTES:

- +5V_Pi and +5V_Motor are separate rails.
- Common GND is shared between Pi and Motor Supply.
- Values are worst-case continuous estimates.