# Mastering the Game of Go Without Human Knowledge

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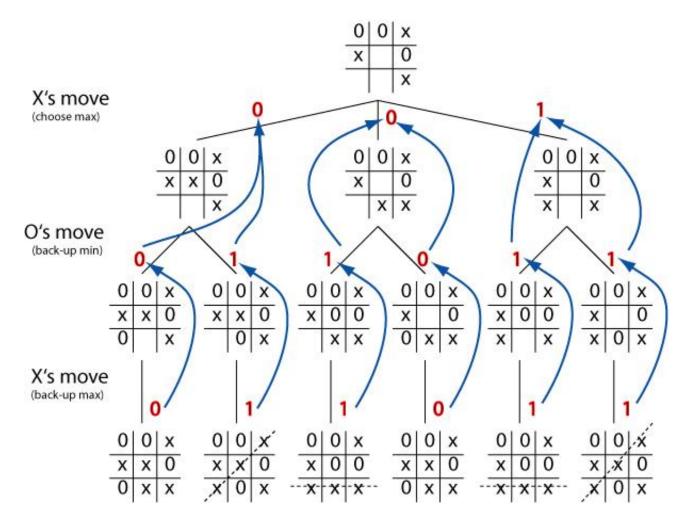


# \* AlphaGo Zero

#### Overview

- Brief History of Al in Games
- What is Go and Why Should You Care?
- How AlphaGo Zero Works
- Results
- Discussion

#### **Minimax**



## Heuristics

Reduces search depth











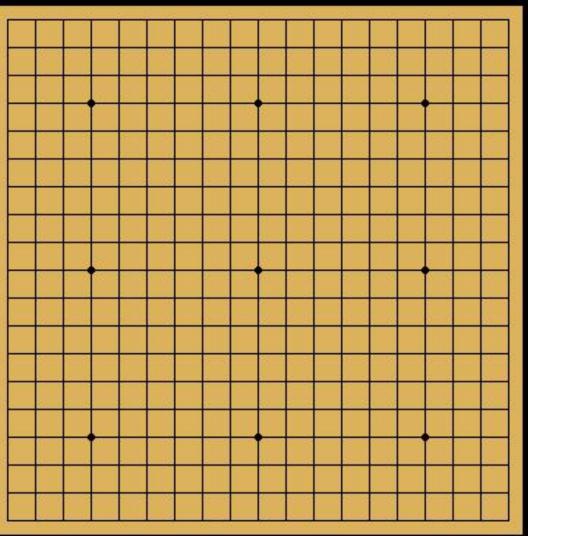
#### Deep Blue

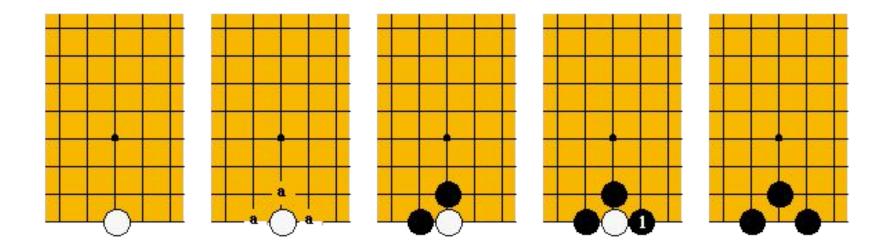
- 126 million positions per second
- Hand-designed Heuristics



## The Game of Go

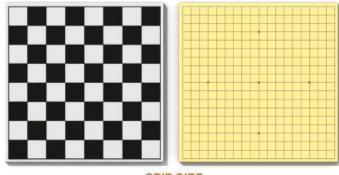






#### Go is Incredibly Complex

Go is Hard for Computers



#### **GRID SIZE**

8 x 8 19 x 19

#### AVERAGE NUMBER OF MOVE CHOICES PER TURN

35 200-300

#### LENGTH OF TYPICAL GAME

60 moves 200 moves

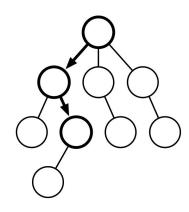
#### NUMBER OF POSSIBLE GAME POSITIONS

1044 10170

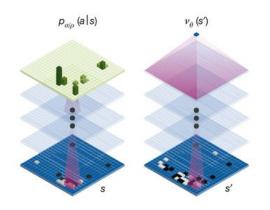
#### EXPLOSION OF CHOICES (starting from average game position)

35 Move I 200 1225 Move 2 40 000 42 875 Move 3 8 000 000 1 500 625 Move 4 I 600 000 000

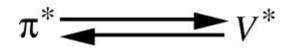
#### How AlphaGo Zero Works



Monte-Carlo Tree Search



Residual Network

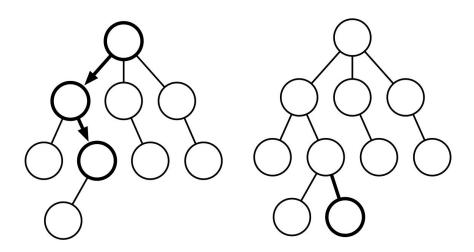


Policy Iteration

#### Monte-Carlo Tree Search (MCTS)

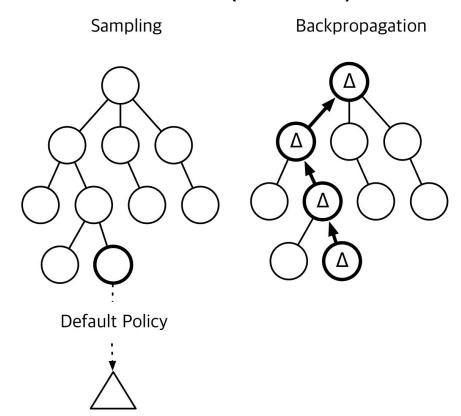
Selection

Expansion



Tree Policy

#### Monte-Carlo Tree Search (MCTS)



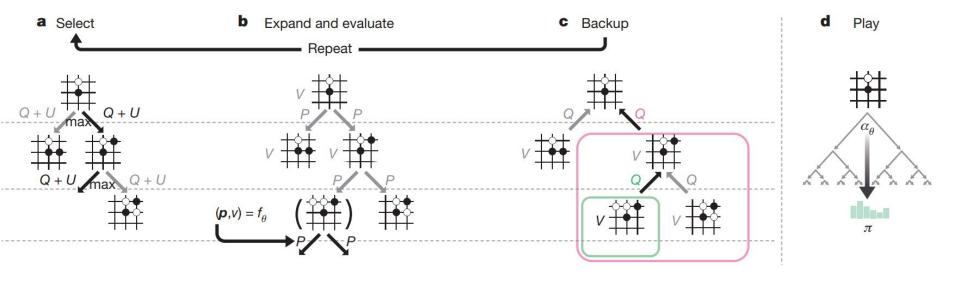
#### MCTS: Advantages

- Aheuristic
- Online-search
- Works well on large trees

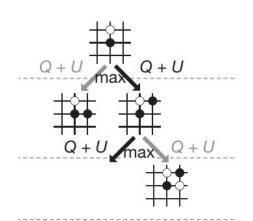
#### MCTS: Disadvantages

- Many simulation are required
- No generalization between similar states
- Performance is dependent on "rollout" policy

## MCTS in AlphaGo Zero

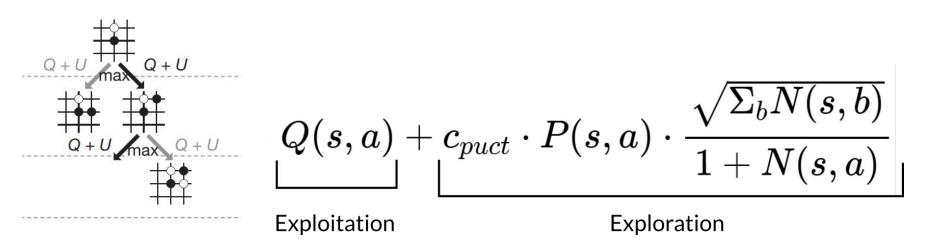


## Upper Confidence Bound for Trees (UCT)



$$Q(s,a) + c_{puct} \cdot P(s,a) \cdot rac{\sqrt{\Sigma_b N(s,b)}}{1 + N(s,a)}$$

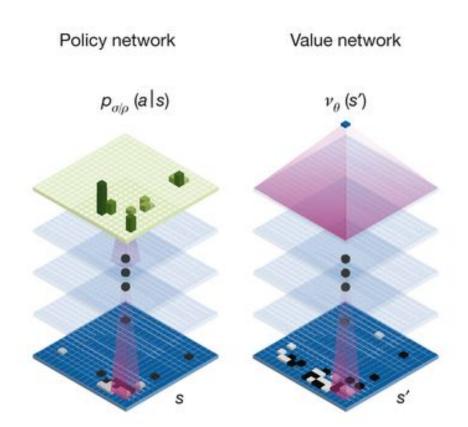
## Upper Confidence Bound for Trees (UCT)



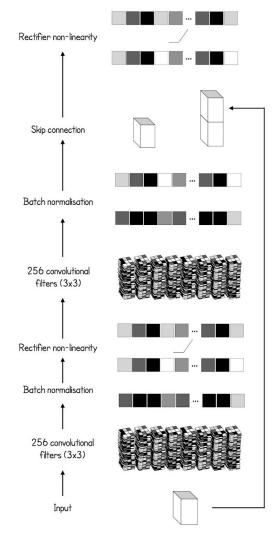
## Upper Confidence Bound for Trees (UCT)

s State a Action Q(s, a) Expected Reward P(s, a) Policy N(s, a) # of state visits $Q(s, a) + c_{puct} \cdot P(s, a) \cdot \frac{\sqrt{\Sigma}}{1 + c_{puct}}$ Exploitation Exploration	c <sub>puct</sub> Hyperparameter Exploitation Exploration
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#### AlphaGo Zero's Network Architecture

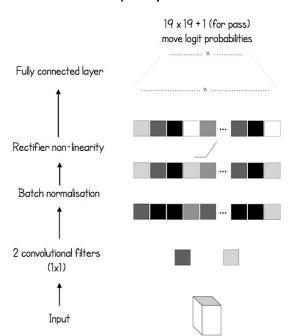


## Residual Layer

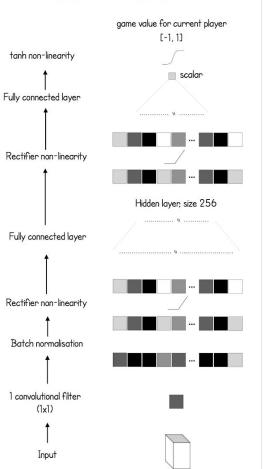


#### **Dual Heads**

#### The policy head



#### The value head



## **Training**

Self-play Worker



 $\pi$ 



**Training Worker** 

$$l = (z - v)^2 - \boldsymbol{\pi}^{\mathrm{T}} \log \boldsymbol{p} + c \|\boldsymbol{\theta}\|^2$$

Evaluator

$$\pi' > \pi$$

## How AlphaGo Zero Chooses a Move

1600 Simulations

$$\pi \sim N^{1/\tau}$$

#### Self-Play Workers



The game state



The search probabilities



The winner

#### **Training Worker**

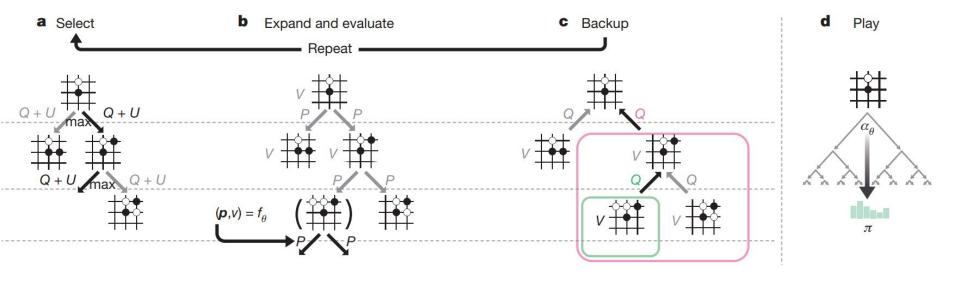
$$l = (z - v)^2 - \pi^{\mathrm{T}} \log p + c \|\theta\|^2$$

**Evaluator** 

400 Games

55% Win Rate

## MCTS in AlphaGo Zero



# 5 Minute Break

## AlphaGo Zero

VS

AlphaGo

Entirely self-play

Input is game board

Single network

No rollouts

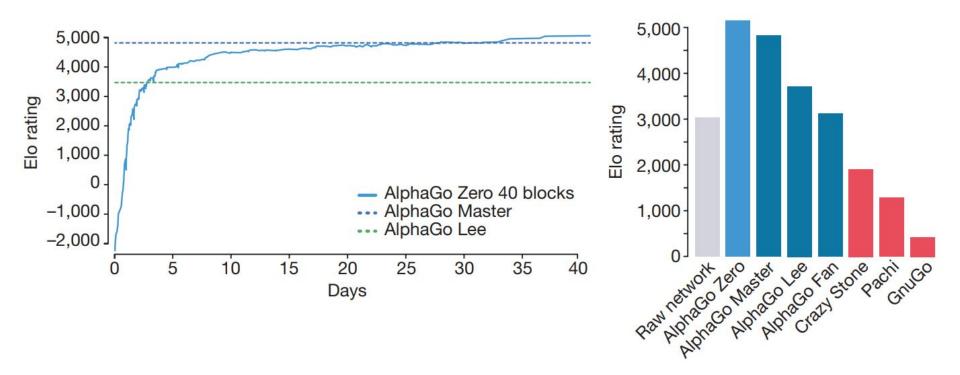
Supervised learning + self-play

Input is hand-crafted features

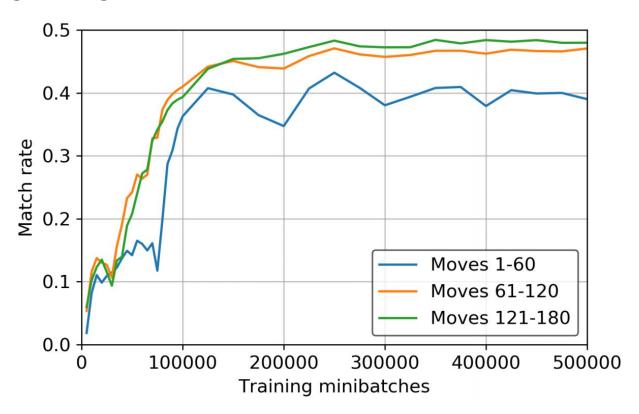
Two networks

Rollouts were used

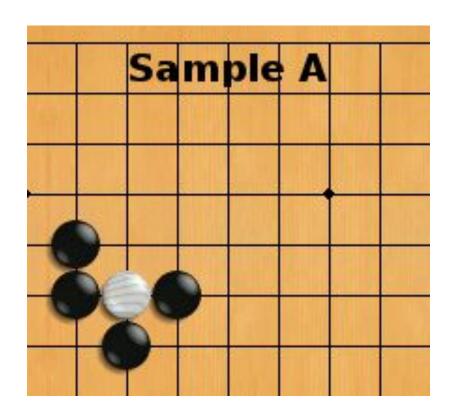
#### Results



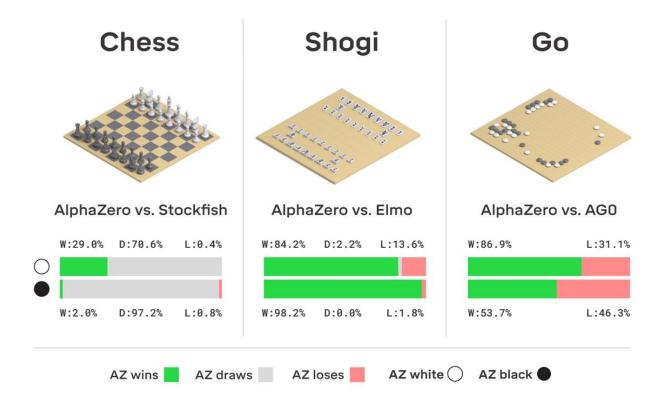
#### **Learning Stages**



#### Ladders



#### AlphaZero





## AlphaGo Zero's Gift





## Discussion



#### Discussion

How can the AlphaGo Zero algorithm be extended to different games?

How can the sample efficiency of AlphaGo Zero be improved?

A very stable training environment is need for the algorithm.

Can this be alleviated to let AlphaZero applied to real-world problems?

#### Resources

Mastering the Game of Go without Human Knowledge

David Silver 2017 NIPS Talk

ELF OpenGo: An Analysis and Open Reimplementation of AlphaZero

David Silver's PhD Thesis: Reinforcement Learning and Simulation-Based Search in Computer Go

A Brief History of Game Al Up To AlphaGo - Andrey Kurenkov

AlphaGo Zero Demystified - Dylan Djian