TYCamport3

3

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## **Chapter 1**

## Main Page

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## 1.1 Note

Depth camera, called "device", consists of several components. Each component is a hardware module or virtual module, such as RGB sensor, depth sensor. Each component has its own features, such as image width, exposure time, etc..

NOTE: The component TY\_COMPONENT\_DEVICE is a virtual component that contains all features related to the whole device, such as trigger mode, device IP.

Each frame consists of several images. Normally, all the images have identical timestamp, means they are captured at the same time.

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## **Chapter 2**

# **Class Index**

## 2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

Depthemenceralameters
Default parameter value definition
DepthSpeckleFilterParameters
Default parameter value definition
pattern_bin_param
pattern_gray_param
pattern_sine_param
TY_PHC_GROUP_ATTR::phc_group_attr
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# **Chapter 3**

# File Index

## 3.1 File List

Here is a list of all documented files with brief descriptions:

TYApi.h	
TYApi.h includes camera control and data receiving interface, which supports configuration for	
image resolution, frame rate, exposure time, gain, working mode,etc	33
TYCoordinateMapper.h	
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Tylsp.h	97

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## **Chapter 4**

## **Class Documentation**

## 4.1 DepthEnhenceParameters Struct Reference

default parameter value definition

```
#include <TYImageProc.h>
```

#### **Public Attributes**

- float sigma\_s
  - filter param on space
- · float sigma\_r
  - filter param on range
- int outlier\_win\_sz
  - outlier filter windows ize
- float outlier\_rate

## 4.1.1 Detailed Description

default parameter value definition

Definition at line 54 of file TYImageProc.h.

The documentation for this struct was generated from the following file:

• TYImageProc.h

## 4.2 DepthSpeckleFilterParameters Struct Reference

default parameter value definition

```
#include <TYImageProc.h>
```

## **Public Attributes**

- int max\_speckle\_size
- int max\_speckle\_diff

## 4.2.1 Detailed Description

default parameter value definition

Definition at line 34 of file TYImageProc.h.

The documentation for this struct was generated from the following file:

• TYImageProc.h

## 4.3 pattern\_bin\_param Struct Reference

## **Public Attributes**

- uint32\_t offset
- uint8\_t data [512]

## 4.3.1 Detailed Description

Definition at line 949 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.4 pattern\_gray\_param Struct Reference

## **Public Attributes**

- uint32\_t phase\_num
- uint32\_t param1
- · uint32 t param2
- uint32\_t param3

## 4.4.1 Detailed Description

Definition at line 941 of file TYApi.h.

The documentation for this struct was generated from the following file:

TYApi.h

## 4.5 pattern\_sine\_param Struct Reference

#### **Public Attributes**

- uint32\_t phase\_num
- float period

## 4.5.1 Detailed Description

Definition at line 935 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.6 TY\_PHC\_GROUP\_ATTR::phc\_group\_attr Struct Reference

## **Public Attributes**

- uint8\_t type
- uint8\_t amp\_thresh
- uint16\_t **ch**
- uint8\_t rsvd [28]

## 4.6.1 Detailed Description

Definition at line 927 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.7 TY\_ACC\_BIAS Struct Reference

```
#include <TYApi.h>
```

## **Public Attributes**

• float **data** [3]

## 4.7.1 Detailed Description

a 3x3 matrix

•		
BIASx	BIASy	BIASz

Definition at line 999 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.8 TY\_ACC\_MISALIGNMENT Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [3 \*3]

## 4.8.1 Detailed Description

a 3x3 matrix |.|.|.

1	-GAMAyz	GAMAzy
GAMAxz	1	-GAMAzx
-GAMAxy	GAMAyx	1

Definition at line 1011 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.9 TY\_ACC\_SCALE Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [3 \*3]

## 4.9.1 Detailed Description

a 3x3 matrix

	•	•
SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

Definition at line 1022 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.10 TY\_AEC\_ROI\_PARAM Struct Reference

#### **Public Attributes**

- uint32\_t x
- uint32\_t y
- uint32\_t w
- uint32\_t **h**

## 4.10.1 Detailed Description

Definition at line 907 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.11 TY\_BYTEARRAY\_ATTR Struct Reference

byte array data structure

#include <TYApi.h>

## **Public Attributes**

- int32\_t size
   Bytes array size in bytes.
- int32\_t unit\_size
- int32\_t valid\_size

## 4.11.1 Detailed Description

byte array data structure

See also

**TYGetByteArray** 

Definition at line 775 of file TYApi.h.

#### 4.11.2 Member Data Documentation

4.11.2.1 unit\_size

int32\_t TY\_BYTEARRAY\_ATTR::unit\_size

unit size in bytes for special parse

Definition at line 778 of file TYApi.h.

#### 4.11.2.2 valid\_size

int32\_t TY\_BYTEARRAY\_ATTR::valid\_size

valid size in bytes in case has reserved member, Must be multiple of unit\_size, mem\_length = valid\_size/unit\_size

Definition at line 781 of file TYApi.h.

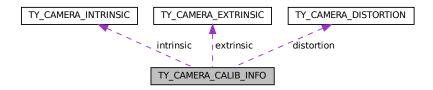
The documentation for this struct was generated from the following file:

• TYApi.h

## 4.12 TY\_CAMERA\_CALIB\_INFO Struct Reference

#include <TYApi.h>

Collaboration diagram for TY\_CAMERA\_CALIB\_INFO:



#### **Public Attributes**

- int32\_t intrinsicWidth
- int32\_t intrinsicHeight
- TY\_CAMERA\_INTRINSIC intrinsic
- TY\_CAMERA\_EXTRINSIC extrinsic
- TY\_CAMERA\_DISTORTION distortion

## 4.12.1 Detailed Description

camera 's cailbration data

See also

**TYGetStruct** 

Definition at line 850 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.13 TY\_CAMERA\_DISTORTION Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [12]

Definition is compatible with opencv3.0+ :k1,k2,p1,p2,k3,k4,k5,k6,s1,s2,s3,s4.

## 4.13.1 Detailed Description

camera distortion parameters

See also

#### TYGetStruct Usage:

Definition at line 842 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.14 TY\_CAMERA\_EXTRINSIC Struct Reference

#include <TYApi.h>

## **Public Attributes**

• float data [4 \*4]

## 4.14.1 Detailed Description

a 4x4 matrix

	•		
r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

#### See also

#### TYGetStruct Usage:

```
TY_CAMERA_EXTRINSIC extrinsic;
TYGetStruct(hDevice, some_compoent, TY_STRUCT_EXTRINSIC, &extrinsic, sizeof(extrinsic));
```

Definition at line 830 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.15 TY\_CAMERA\_INTRINSIC Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [3 \*3]

## 4.15.1 Detailed Description

a 3x3 matrix

	•	
fx	0	СХ
0	fy	су
0	0	1

#### See also

#### TYGetStruct Usage:

Definition at line 812 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.16 TY\_CAMERA\_STATISTICS Struct Reference

## **Public Attributes**

- uint64\_t packetReceived
- uint64\_t packetLost
- uint64\_t imageOutputed
- uint64\_t imageDropped
- uint8\_t rsvd [1024]

## 4.16.1 Detailed Description

Definition at line 973 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.17 TY\_CAMERA\_TO\_IMU Struct Reference

#include <TYApi.h>

#### **Public Attributes**

• float data [4 \*4]

## 4.17.1 Detailed Description

a 4x4 matrix

r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

Definition at line 1065 of file TYApi.h.

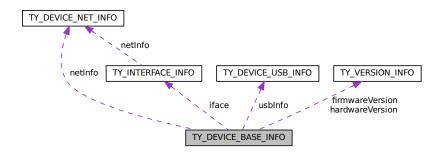
The documentation for this struct was generated from the following file:

• TYApi.h

## 4.18 TY\_DEVICE\_BASE\_INFO Struct Reference

#include <TYApi.h>

Collaboration diagram for TY\_DEVICE\_BASE\_INFO:



#### **Public Attributes**

```
• TY_INTERFACE_INFO iface
```

• char id [32]

device serial number

- char vendorName [32]
- char userDefinedName [32]
- char modelName [32]

device model name

TY\_VERSION\_INFO hardwareVersion

deprecated

TY\_VERSION\_INFO firmwareVersion

deprecated

```
union {
    TY_DEVICE_NET_INFO netInfo
    TY_DEVICE_USB_INFO usbInfo
};
```

- · char buildHash [256]
- char configVersion [256]
- · char reserved [256]

#### 4.18.1 Detailed Description

See also

**TYGetDeviceList** 

Definition at line 723 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.19 TY\_DEVICE\_NET\_INFO Struct Reference

#### device network information

#include <TYApi.h>

#### **Public Attributes**

- char mac [32]
- char ip [32]
- · char netmask [32]
- char gateway [32]
- · char broadcast [32]
- char reserved [96]

## 4.19.1 Detailed Description

device network information

Definition at line 695 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.20 TY\_DEVICE\_USB\_INFO Struct Reference

#### **Public Attributes**

- int bus
- int addr
- char reserved [248]

## 4.20.1 Detailed Description

Definition at line 705 of file TYApi.h.

The documentation for this struct was generated from the following file:

TYApi.h

## 4.21 TY\_DI\_WORKMODE Struct Reference

#### **Public Attributes**

- TY\_E\_DI\_MODE mode
- TY\_E\_DI\_INT\_ACTION int\_act
- uint32\_t mode\_supported
- uint32\_t int\_act\_supported
- uint32\_t status
- uint32\_t reserved [3]

#### 4.21.1 Detailed Description

Definition at line 1147 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.22 TY\_DO\_WORKMODE Struct Reference

## **Public Attributes**

- TY\_E\_DO\_MODE mode
- TY E VOLT T volt
- uint32\_t freq
- uint32\_t duty
- uint32\_t mode\_supported
- uint32\_t volt\_supported
- uint32\_t reserved [3]

#### 4.22.1 Detailed Description

Definition at line 1124 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.23 TY\_ENUM\_ENTRY Struct Reference

#include <TYApi.h>

#### **Public Attributes**

- char description [64]
- · uint32 t value
- uint32\_t reserved [3]

#### 4.23.1 Detailed Description

enum feature entry information

See also

#### **TYGetEnumEntryInfo**

Definition at line 786 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.24 TY\_EVENT\_INFO Struct Reference

#### **Public Attributes**

- · TY EVENT eventId
- · char message [124]

#### 4.24.1 Detailed Description

Definition at line 1118 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.25 TY\_FEATURE\_INFO Struct Reference

#### **Public Attributes**

bool isValid

true if feature exists, false otherwise

TY\_ACCESS\_MODE accessMode

feature access privilege

· bool writableAtRun

feature can be written while capturing

- char reserved0 [1]
- TY\_COMPONENT\_ID componentID

owner of this feature

TY\_FEATURE\_ID featureID

feature unique id

• char name [32]

describe string

TY\_COMPONENT\_ID bindComponentID

component ID current feature bind to

• TY\_FEATURE\_ID bindFeatureID

feature ID current feature bind to

char reserved [252]

## 4.25.1 Detailed Description

Definition at line 741 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.26 TY\_FLOAT\_RANGE Struct Reference

float range data structure

#include <TYApi.h>

#### **Public Attributes**

- float min
- · float max
- float inc increaing step
- · float reserved [1]

## 4.26.1 Detailed Description

float range data structure

See also

TYGetFloatRange

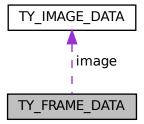
Definition at line 765 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.27 TY\_FRAME\_DATA Struct Reference

Collaboration diagram for TY\_FRAME\_DATA:



#### **Public Attributes**

void \* userBuffer

Pointer to user enqueued buffer, user should enqueue this buffer in the end of callback.

int32\_t bufferSize

Size of userBuffer.

int32\_t validCount

Number of valid data.

• int32\_t reserved [6]

Reserved: reserved[0],laser\_val;.

• TY\_IMAGE\_DATA image [10]

Buffer data, max to 10 images per frame, each buffer data could be an image or something else.

## 4.27.1 Detailed Description

Definition at line 1108 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.28 TY\_GYRO\_BIAS Struct Reference

#include <TYApi.h>

#### **Public Attributes**

• float data [3]

## 4.28.1 Detailed Description

a 3x3 matrix

•	•	•
BIASx	BIASy	BIASz

Definition at line 1031 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.29 TY\_GYRO\_MISALIGNMENT Struct Reference

#include <TYApi.h>

## **Public Attributes**

• float data [3 \*3]

## 4.29.1 Detailed Description

a 3x3 matrix

1	-ALPHAyz	ALPHAzy
0	1	-ALPHAzx
0	0	1

Definition at line 1042 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.30 TY\_GYRO\_SCALE Struct Reference

#include <TYApi.h>

## **Public Attributes**

• float data [3 \*3]

## 4.30.1 Detailed Description

a 3x3 matrix

•	•	
SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

Definition at line 1053 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.31 TY\_IMAGE\_DATA Struct Reference

## **Public Attributes**

· uint64 t timestamp

Timestamp in microseconds.

int32\_t imageIndex

image index used in trigger mode

· int32\_t status

Status of this buffer.

• TY\_COMPONENT\_ID componentID

Where current data come from.

• int32\_t size

Buffer size.

void \* buffer

Pointer to data buffer.

· int32 t width

Image width in pixels.

• int32\_t height

Image height in pixels.

TY\_PIXEL\_FORMAT pixelFormat

Pixel format, see TY\_PIXEL\_FORMAT\_LIST.

• int32\_t reserved [9]

Reserved.

## 4.31.1 Detailed Description

Definition at line 1093 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.32 TY\_IMU\_DATA Struct Reference

#### **Public Attributes**

- uint64\_t timestamp
- float acc\_x
- float acc\_y
- float acc\_z
- float gyro\_x
- float gyro\_y
- float gyro\_z
- float temperature
- float reserved [1]

## 4.32.1 Detailed Description

Definition at line 982 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.33 TY\_INT\_RANGE Struct Reference

## **Public Attributes**

- int32\_t min
- int32\_t max
- int32\_t inc

increaing step

• int32\_t reserved [1]

## 4.33.1 Detailed Description

Definition at line 755 of file TYApi.h.

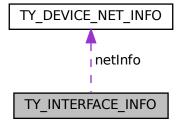
The documentation for this struct was generated from the following file:

• TYApi.h

## 4.34 TY\_INTERFACE\_INFO Struct Reference

```
#include <TYApi.h>
```

Collaboration diagram for TY\_INTERFACE\_INFO:



#### **Public Attributes**

- char **name** [32]
- char id [32]
- TY\_INTERFACE\_TYPE type
- char reserved [4]
- TY\_DEVICE\_NET\_INFO netInfo

#### 4.34.1 Detailed Description

See also

**TYGetInterfaceList** 

Definition at line 713 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.35 TY\_ISP\_FEATURE\_INFO Struct Reference

#### **Public Attributes**

- TY\_ISP\_FEATURE\_ID id
- int32\_t size
- const char \* name
- const char \* value\_type
- TY\_ACCESS\_MODE mode

## 4.35.1 Detailed Description

Definition at line 63 of file Tylsp.h.

The documentation for this struct was generated from the following file:

• Tylsp.h

## 4.36 TY\_LASER\_PARAM Struct Reference

## **Public Attributes**

- uint32\_t idx
- uint32\_t en
- uint32\_t power

### 4.36.1 Detailed Description

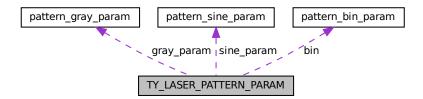
Definition at line 1083 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.37 TY\_LASER\_PATTERN\_PARAM Struct Reference

Collaboration diagram for TY\_LASER\_PATTERN\_PARAM:



### **Public Attributes**

```
    uint32_t img_index
    uint32_t type
    union {
        uint8_t payload [512+16]
        pattern_sine_param sine_param
        pattern_gray_param gray_param
        pattern_bin_param bin
    };
```

### 4.37.1 Detailed Description

Definition at line 955 of file TYApi.h.

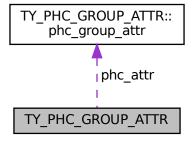
The documentation for this struct was generated from the following file:

• TYApi.h

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# 4.38 TY\_PHC\_GROUP\_ATTR Struct Reference

Collaboration diagram for TY\_PHC\_GROUP\_ATTR:



#### Classes

struct phc\_group\_attr

### **Public Attributes**

- uint32\_t offset
- uint32\_t size
- struct TY\_PHC\_GROUP\_ATTR::phc\_group\_attr phc\_attr [16]

### 4.38.1 Detailed Description

Definition at line 923 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.39 TY\_PIXEL\_COLOR\_DESC Struct Reference

### **Public Attributes**

- int16\_t x
- int16\_t **y**
- uint8\_t bgr\_ch1
- uint8\_t bgr\_ch2
- uint8\_t bgr\_ch3
- uint8\_t rsvd

### 4.39.1 Detailed Description

Definition at line 20 of file TYCoordinateMapper.h.

The documentation for this struct was generated from the following file:

· TYCoordinateMapper.h

# 4.40 TY\_PIXEL\_DESC Struct Reference

### **Public Attributes**

- int16\_t x
- int16\_t y
- uint16\_t depth
- uint16\_t rsvd

### 4.40.1 Detailed Description

Definition at line 12 of file TYCoordinateMapper.h.

The documentation for this struct was generated from the following file:

· TYCoordinateMapper.h

# 4.41 TY\_TOF\_FREQ Struct Reference

### **Public Attributes**

- uint32\_t freq1
- uint32\_t freq2

### 4.41.1 Detailed Description

Definition at line 1070 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.42 TY\_TRIGGER\_PARAM Struct Reference

### **Public Attributes**

- TY\_TRIGGER\_MODE mode
- int8\_t fps
- int8\_t rsvd

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### 4.42.1 Detailed Description

Definition at line 861 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.43 TY\_TRIGGER\_PARAM\_EX Struct Reference

#### **Public Attributes**

```
• TY_TRIGGER_MODE mode
•

union {
    struct {
        int8_t fps
        int8_t duty
        int32_t laser_stream
        int32_t led_stream
        int32_t led_expo
        int32_t led_gain
    }
    struct {
        int32_t ir_gain [2]
    }
    int32_t rsvd [32]
};
```

### 4.43.1 Detailed Description

Definition at line 869 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.44 TY\_TRIGGER\_TIMER\_LIST Struct Reference

### **Public Attributes**

```
• uint64_t start_time_us
```

- uint32\_t offset\_us\_count
- uint32\_t offset\_us\_list [50]

### 4.44.1 Detailed Description

Definition at line 892 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.45 TY\_TRIGGER\_TIMER\_PERIOD Struct Reference

### **Public Attributes**

- uint64\_t start\_time\_us
- uint32\_t trigger\_count
- uint32\_t period\_us

### 4.45.1 Detailed Description

Definition at line 900 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.46 TY\_VECT\_3F Struct Reference

### **Public Attributes**

- float x
- float y
- float z

### 4.46.1 Detailed Description

Definition at line 793 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.47 TY VERSION INFO Struct Reference

#### **Public Attributes**

- int32\_t major
- · int32\_t minor
- int32\_t patch
- int32\_t reserved

### 4.47.1 Detailed Description

Definition at line 686 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

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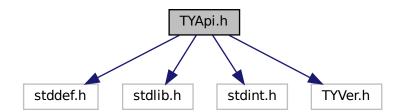
# **Chapter 5**

# **File Documentation**

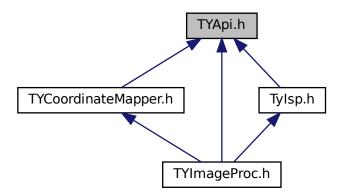
# 5.1 TYApi.h File Reference

TYApi.h includes camera control and data receiving interface, which supports configuration for image resolution, frame rate, exposure time, gain, working mode,etc.

```
#include <stddef.h>
#include <stdlib.h>
#include <stdint.h>
#include "TYVer.h"
Include dependency graph for TYApi.h:
```



This graph shows which files directly or indirectly include this file:



#### **Classes**

- struct TY\_VERSION\_INFO
- struct TY\_DEVICE\_NET\_INFO

device network information

- struct TY\_DEVICE\_USB\_INFO
- struct TY\_INTERFACE\_INFO
- struct TY\_DEVICE\_BASE\_INFO
- struct TY\_FEATURE\_INFO
- struct TY\_INT\_RANGE
- struct TY\_FLOAT\_RANGE

float range data structure

• struct TY\_BYTEARRAY\_ATTR

byte array data structure

- struct TY\_ENUM\_ENTRY
- struct TY\_VECT\_3F
- struct TY\_CAMERA\_INTRINSIC
- struct TY\_CAMERA\_EXTRINSIC
- struct TY\_CAMERA\_DISTORTION
- struct TY\_CAMERA\_CALIB\_INFO
- struct TY\_TRIGGER\_PARAM
- struct TY\_TRIGGER\_PARAM\_EX
- struct TY\_TRIGGER\_TIMER\_LIST
- struct TY\_TRIGGER\_TIMER\_PERIOD
- struct TY\_AEC\_ROI\_PARAM
- struct TY\_PHC\_GROUP\_ATTR
- struct TY\_PHC\_GROUP\_ATTR::phc\_group\_attr
- struct pattern\_sine\_param
- struct pattern\_gray\_param
- struct pattern\_bin\_param
- struct TY\_LASER\_PATTERN\_PARAM
- struct TY\_CAMERA\_STATISTICS
- struct TY\_IMU\_DATA

- struct TY\_ACC\_BIAS
- struct TY\_ACC\_MISALIGNMENT
- struct TY\_ACC\_SCALE
- struct TY GYRO BIAS
- struct TY GYRO MISALIGNMENT
- struct TY GYRO SCALE
- struct TY\_CAMERA\_TO\_IMU
- struct TY\_TOF\_FREQ
- struct TY LASER PARAM
- struct TY IMAGE DATA
- struct TY\_FRAME\_DATA
- struct TY\_EVENT\_INFO
- struct TY\_DO\_WORKMODE
- struct TY\_DI\_WORKMODE

#### **Macros**

- #define \_STDBOOL\_H
- #define \_\_bool\_true\_false\_are\_defined 1
- #define bool Bool
- #define true 1
- #define false 0
- #define TY\_DLLIMPORT \_\_attribute\_\_((visibility("default")))
- #define TY\_DLLEXPORT \_\_attribute\_\_((visibility("default")))
- #define TY\_STDC
- #define TY\_CDEC
- #define TY\_EXPORT TY\_DLLIMPORT
- #define TY\_EXTC
- #define TY\_INT\_SGBM\_COST\_PARAM TY\_INT\_SGBM\_UNIQUE\_MAX\_COST
- #define TY\_BOOL\_FLASHLIGHT TY\_BOOL\_IR\_FLASHLIGHT
- #define TY\_INT\_FLASHLIGHT\_INTENSITY TY\_INT\_IR\_FLASHLIGHT\_INTENSITY
- #define TY\_INT\_AE\_TARGET\_V TY INT AE TARGET Y
- #define TY\_DECLARE\_IMAGE\_MODE1(pix)
- #define TY\_CAPI TY\_EXTC TY\_EXPORT TY\_STATUS TY\_STDC

### **Typedefs**

- typedef enum TY\_STATUS\_LIST TY\_STATUS\_LIST
  - API call return status.
- typedef int32\_t TY\_STATUS
- typedef enum TY\_FW\_ERRORCODE\_LIST TY\_FW\_ERRORCODE\_LIST
- typedef uint32\_t TY\_FW\_ERRORCODE
- typedef enum TY\_EVENT\_LIST TY\_ENENT\_LIST
- typedef int32\_t TY\_EVENT
- typedef void \* TY\_INTERFACE\_HANDLE
  - Interface handle.
- typedef void \* TY\_DEV\_HANDLE
  - Device Handle.
- typedef enum TY\_DEVICE\_COMPONENT\_LIST TY\_DEVICE\_COMPONENT\_LIST
- typedef uint32\_t TY\_COMPONENT\_ID

component unique id

typedef enum TY\_FEATURE\_TYPE\_LIST TY\_FEATURE\_TYPE\_LIST

Feature Format Type definitions.

- typedef uint32 t TY FEATURE TYPE
- typedef enum TY FEATURE ID LIST TY FEATURE ID LIST

feature for component definitions

• typedef uint32\_t TY\_FEATURE\_ID

feature unique id

- typedef enum TY\_CONFIG\_MODE\_LIST TY\_CONFIG\_MODE\_LIST
- typedef uint32 t TY CONFIG MODE
- typedef enum TY\_DEPTH\_QUALITY\_LIST TY\_DEPTH\_QUALITY\_LIST
- typedef uint32 t TY\_DEPTH\_QUALITY
- typedef enum TY TRIGGER POL LIST TY TRIGGER POL LIST

set external trigger signal edge

- typedef uint32 t TY TRIGGER POL
- typedef enum TY\_INTERFACE\_TYPE\_LIST TY\_INTERFACE\_TYPE\_LIST
- typedef uint32 t TY INTERFACE TYPE
- typedef enum TY\_ACCESS\_MODE\_LIST TY\_ACCESS\_MODE\_LIST
- typedef uint8 t TY ACCESS MODE
- typedef enum TY\_STREAM\_ASYNC\_MODE\_LIST TY\_STREAM\_ASYNC\_MODE\_LIST

stream async mode

- typedef uint8\_t TY\_STREAM\_ASYNC\_MODE
- typedef enum TY PIXEL BITS LIST TY PIXEL BITS LIST
- typedef uint32 t TY PIXEL BITS
- typedef enum TY\_PIXEL\_FORMAT\_LIST TY\_PIXEL\_FORMAT\_LIST

pixel format definitions

- typedef uint32\_t TY\_PIXEL\_FORMAT
- typedef enum TY\_RESOLUTION\_MODE\_LIST TY\_RESOLUTION\_MODE\_LIST

predefined resolution list

- typedef int32\_t TY\_RESOLUTION\_MODE
- typedef enum TY IMAGE MODE LIST TY IMAGE MODE LIST

Predefined Image Mode List image mode controls image resolution & format predefined image modes named like TY\_IMAGE\_MODE\_MONO\_160x120,TY\_IMAGE\_MODE\_RGB\_1280x960.

- typedef uint32\_t TY\_IMAGE\_MODE
- typedef enum TY\_TRIGGER\_MODE\_LIST TY\_TRIGGER\_MODE\_LIST
- typedef int16\_t TY\_TRIGGER\_MODE
- typedef enum TY\_TIME\_SYNC\_TYPE\_LIST TY\_TIME\_SYNC\_TYPE\_LIST

type of time sync

- typedef uint32\_t TY\_TIME\_SYNC\_TYPE
- typedef uint32\_t TY\_E\_VOLT\_T
- typedef uint32\_t TY\_E\_DO\_MODE
- typedef uint32\_t TY\_E\_DI\_MODE
- typedef uint32\_t TY\_E\_DI\_INT\_ACTION
- typedef struct TY VERSION INFO TY\_VERSION INFO
- typedef struct TY\_DEVICE\_NET\_INFO TY\_DEVICE\_NET\_INFO

device network information

- typedef struct TY\_DEVICE\_USB\_INFO TY\_DEVICE\_USB\_INFO
- typedef struct TY\_INTERFACE\_INFO TY\_INTERFACE\_INFO
- typedef struct TY\_DEVICE\_BASE\_INFO
- typedef struct TY\_FEATURE\_INFO TY\_FEATURE\_INFO
- typedef struct TY\_INT\_RANGE TY\_INT\_RANGE
- typedef struct TY\_FLOAT\_RANGE TY\_FLOAT\_RANGE

float range data structure

- typedef struct TY\_BYTEARRAY\_ATTR TY\_BYTEARRAY\_ATTR
   byte array data structure
- typedef struct TY ENUM ENTRY TY ENUM ENTRY
- typedef struct TY VECT 3F TY\_VECT\_3F
- typedef struct TY CAMERA INTRINSIC TY CAMERA INTRINSIC
- typedef struct TY\_CAMERA\_EXTRINSIC TY\_CAMERA\_EXTRINSIC
- typedef struct TY\_CAMERA\_DISTORTION TY\_CAMERA\_DISTORTION
- typedef struct TY CAMERA CALIB INFO TY CAMERA CALIB INFO
- typedef struct TY TRIGGER PARAM TY TRIGGER PARAM
- typedef struct TY TRIGGER PARAM EX TY TRIGGER PARAM EX
- typedef struct TY\_TRIGGER\_TIMER\_LIST TY\_TRIGGER\_TIMER\_LIST
- typedef struct TY\_TRIGGER\_TIMER\_PERIOD TY\_TRIGGER\_TIMER\_PERIOD
- typedef struct TY\_AEC\_ROI\_PARAM TY\_AEC\_ROI\_PARAM
- typedef struct TY\_PHC\_GROUP\_ATTR TY\_PHC\_GROUP\_ATTR
- typedef struct TY LASER PATTERN PARAM TY LASER PATTERN PARAM
- typedef struct TY\_CAMERA\_STATISTICS TY\_CAMERA\_STATISTICS
- typedef struct TY IMU DATA TY IMU DATA
- typedef struct TY\_ACC\_BIAS TY\_ACC\_BIAS
- typedef struct TY\_ACC\_MISALIGNMENT TY\_ACC\_MISALIGNMENT
- typedef struct TY ACC SCALE TY ACC SCALE
- typedef struct TY GYRO BIAS TY GYRO BIAS
- typedef struct TY\_GYRO\_MISALIGNMENT TY\_GYRO\_MISALIGNMENT
- typedef struct TY GYRO SCALE TY GYRO SCALE
- typedef struct TY\_CAMERA\_TO\_IMU TY\_CAMERA\_TO\_IMU
- typedef struct TY TOF FREQ TY TOF FREQ
- typedef enum TY\_IMU\_FPS\_LIST TY\_IMU\_FPS\_LIST
- typedef struct TY LASER PARAM TY\_LASER\_PARAM
- typedef struct TY\_IMAGE\_DATA TY\_IMAGE\_DATA
- typedef struct TY\_FRAME\_DATA TY\_FRAME\_DATA
- typedef struct TY\_EVENT\_INFO TY\_EVENT\_INFO
- typedef struct TY\_DO\_WORKMODE TY\_DO\_WORKMODE
- typedef struct TY\_DI\_WORKMODE TY\_DI\_WORKMODE
- typedef void(\* TY EVENT CALLBACK) (TY EVENT INFO \*, void \*userdata)
- typedef void(\* TY\_IMU\_CALLBACK) (TY\_IMU\_DATA \*, void \*userdata)

### **Enumerations**

• enum TY\_STATUS\_LIST : int32\_t {

TY\_STATUS\_OK = 0, TY\_STATUS\_ERROR = -1001, TY\_STATUS\_NOT\_INITED = -1002, TY\_STATUS $\leftarrow$ \_NOT\_IMPLEMENTED = -1003,

TY\_STATUS\_NOT\_PERMITTED = -1004, TY\_STATUS\_DEVICE\_ERROR = -1005, TY\_STATUS\_INVA⇔ LID\_PARAMETER = -1006, TY\_STATUS\_INVALID\_HANDLE = -1007,

TY\_STATUS\_INVALID\_COMPONENT = -1008, TY\_STATUS\_INVALID\_FEATURE = -1009, TY\_STATU ← S WRONG TYPE = -1010, TY STATUS WRONG SIZE = -1011,

TY\_STATUS\_OUT\_OF\_MEMORY = -1012, TY\_STATUS\_OUT\_OF\_RANGE = -1013, TY\_STATUS\_TIM ← EOUT = -1014, TY\_STATUS\_WRONG\_MODE = -1015,

TY\_STATUS\_BUSY = -1016, TY\_STATUS\_IDLE = -1017, TY\_STATUS\_NO\_DATA = -1018, TY\_STATU ← S\_NO\_BUFFER = -1019,

TY\_STATUS\_NULL\_POINTER = -1020, TY\_STATUS\_READONLY\_FEATURE = -1021, TY\_STATUS\_I↔ NVALID\_DESCRIPTOR = -1022, TY\_STATUS\_INVALID\_INTERFACE = -1023,

TY\_STATUS\_FIRMWARE\_ERROR = -1024, TY\_STATUS\_DEV\_EPERM = -1, TY\_STATUS\_DEV\_EIO = -5, TY\_STATUS\_DEV\_ENOMEM = -12,

TY\_STATUS\_DEV\_EBUSY = -16, TY\_STATUS\_DEV\_EINVAL = -22 }

API call return status.

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- File Documentation enum TY FW ERRORCODE LIST: uint32 t { TY FW ERRORCODE CAMO NOT DETECTED = 0x00000001, TY FW ERRORCODE CAM1 NOT ← **DETECTED** = 0x00000002, **TY\_FW\_ERRORCODE\_CAM2\_NOT\_DETECTED** = 0x00000004, **TY\_FW\_E** ← RRORCODE POE NOT INIT = 0x00000008, TY FW ERRORCODE RECMAP NOT CORRECT = 0x00000010, TY FW ERRORCODE LOOKUPT ABLE NOT CORRECT = 0x00000020, TY FW ERRORCODE DRV8899 NOT INIT = 0x00000040, T← Y FW ERRORCODE FOC START ERR =  $0 \times 000000080$ . TY FW ERRORCODE CONFIG NOT FOUND = 0x00010000, TY FW ERRORCODE CONFIG NOT ← CORRECT = 0x00020000, TY FW ERRORCODE XML NOT FOUND = 0x00040000, TY FW ERRO RCODE XML NOT CORRECT = 0x00080000. TY FW ERRORCODE XML OVERRIDE FAILED = 0x00100000, TY FW ERRORCODE CAM INIT ←  $FAILED = 0x00200000, TY_FW_ERRORCODE_LASER_INIT_FAILED = 0x00400000$  enum TY\_EVENT\_LIST: int32\_t { TY\_EVENT\_DEVICE\_OFFLINE = -2001, TY\_EVENT\_LICENSE\_ERR ← **OR** = -2002, **TY\_EVENT\_FW\_INIT\_ERROR** = -2003 } enum TY DEVICE COMPONENT LIST: uint32 t { TY COMPONENT DEVICE = 0x80000000, TY COMPONENT DEPTH CAM = 0x00010000, TY COM PONENT IR CAM LEFT = 0x00040000, TY COMPONENT IR CAM RIGHT = 0x00080000, TY COMPONENT RGB CAM LEFT = 0x00100000, TY COMPONENT RGB CAM RIGHT = 0x00200000, TY COMPONENT LASER = 0x00400000, TY COMPONENT IMU = 0x00800000, TY COMPONENT BRIGHT HISTO = 0x01000000, TY COMPONENT STORAGE = 0x02000000, TY ↔ COMPONENT RGB CAM = TY COMPONENT RGB CAM LEFT } • enum TY\_FEATURE\_TYPE\_LIST : uint32\_t { TY\_FEATURE\_INT = 0x1000, TY\_FEATURE\_FLOAT = 0X2000, TY\_FEATURE\_ENUM = 0x3000, TY\_F← **EATURE BOOL** = 0x4000, TY FEATURE STRING = 0x5000, TY FEATURE BYTEARRAY = 0x6000, TY FEATURE STRUCT = 0x7000 } Feature Format Type definitions. • enum TY\_FEATURE\_ID\_LIST : uint32\_t { URE STRUCT, TY STRUCT CAM DISTORTION = 0x0006 | TY FEATURE STRUCT,
  - TY STRUCT CAM INTRINSIC = 0x0000 | TY FEATURE STRUCT, TY STRUCT EXTRINSIC TO DE ← PTH = 0x0001 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_EXTRINSIC\_TO\_IR\_LEFT = 0x0002 | TY\_FEAT↔ TY STRUCT CAM CALIB DATA = 0x0007 | TY FEATURE STRUCT, TY STRUCT CAM RECTIFIED ← INTRI = 0x0008 | TY FEATURE STRUCT, TY BYTEARRAY CUSTOM BLOCK = 0x000A | TY FEAT↔ URE BYTEARRAY, TY BYTEARRAY ISP BLOCK = 0x000B | TY FEATURE BYTEARRAY, TY\_INT\_PERSISTENT\_IP = 0x0010 | TY\_FEATURE\_INT, TY\_INT\_PERSISTENT\_SUBMASK = 0x0011 | TY FEATURE INT, TY INT PERSISTENT GATEWAY = 0x0012 | TY FEATURE INT, TY BOOL GVS↔ P\_RESEND = 0x0013 | TY FEATURE BOOL,
  - TY INT PACKET DELAY = 0x0014 | TY FEATURE INT, TY INT ACCEPTABLE PERCENT = 0x0015 | TY FEATURE INT, TY INT NTP SERVER IP = 0x0016 | TY FEATURE INT, TY INT PACKET SIZE = 0x0017 | TY FEATURE INT,
  - TY INT LINK CMD TIMEOUT = 0x0018 | TY FEATURE INT, TY STRUCT CAM STATISTICS = 0x00ff TY FEATURE STRUCT, TY INT WIDTH MAX = 0x0100 | TY FEATURE INT, TY INT HEIGHT MAX = 0x0101 | TY FEATURE INT,
  - TY INT OFFSET X = 0x0102 | TY FEATURE INT, TY INT OFFSET Y = 0x0103 | TY FEATURE INT, TY\_INT\_WIDTH = 0x0104 | TY\_FEATURE\_INT, TY\_INT\_HEIGHT = 0x0105 | TY\_FEATURE\_INT,
  - TY\_ENUM\_IMAGE\_MODE = 0x0109 | TY\_FEATURE\_ENUM, TY\_FLOAT\_SCALE\_UNIT = 0x010a | TY\_← FEATURE\_FLOAT, TY\_ENUM\_TRIGGER\_POL = 0x0201 | TY\_FEATURE\_ENUM, TY\_INT\_FRAME\_PE↔ R TRIGGER = 0x0202 | TY FEATURE INT,
  - TY\_STRUCT\_TRIGGER\_PARAM = 0x0523 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_TRIGGER\_PARA M\_EX = 0x0525 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_TRIGGER\_TIMER\_LIST = 0x0526 | TY\_FEAT↔ URE STRUCT, TY STRUCT TRIGGER TIMER PERIOD = 0x0527 | TY FEATURE STRUCT,
  - TY BOOL KEEP ALIVE ONOFF = 0x0203 | TY FEATURE BOOL, TY INT KEEP ALIVE TIMEOUT = 0x0204 | TY FEATURE INT, TY BOOL CMOS SYNC = 0x0205 | TY FEATURE BOOL, TY INT TRIG← GER DELAY US = 0x0206 | TY FEATURE INT,
  - TY BOOL TRIGGER OUT IO = 0x0207 | TY FEATURE BOOL, TY INT TRIGGER DURATION US = 0x0208 | TY FEATURE INT, TY ENUM STREAM ASYNC = 0x0209 | TY FEATURE ENUM, TY INT -CAPTURE TIME US = 0x0210 | TY FEATURE INT,
  - TY\_ENUM\_TIME\_SYNC\_TYPE = 0x0211 | TY\_FEATURE\_ENUM, TY\_BOOL\_TIME\_SYNC\_READY =

0x0212 | TY\_FEATURE\_BOOL, TY\_BOOL\_IR\_FLASHLIGHT = 0x0213 | TY\_FEATURE\_BOOL, TY\_INT

\_IR\_FLASHLIGHT\_INTENSITY = 0x0214 | TY\_FEATURE\_INT,

TY\_BOOL\_RGB\_FLASHLIGHT = 0x0221 | TY\_FEATURE\_BOOL, TY\_INT\_RGB\_FLASHLIGHT\_INTENS⇔ ITY = 0x0222 | TY\_FEATURE\_INT, TY\_STRUCT\_DO0\_WORKMODE = 0x0215 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DI0\_WORKMODE = 0x0216 | TY\_FEATURE\_STRUCT,

TY\_STRUCT\_DO1\_WORKMODE = 0x0217 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DI1\_WORKMODE = 0x0218 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DO2\_WORKMODE = 0x0219 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DI2\_WORKMODE = 0x0220 | TY\_FEATURE\_STRUCT,

TY\_ENUM\_CONFIG\_MODE = 0x0221 | TY\_FEATURE\_ENUM, TY\_FOC\_CALIB\_START = 0x0222 | TY\_FEATURE\_INT, TY\_BOOL\_AUTO\_EXPOSURE = 0x0300 | TY\_FEATURE\_BOOL, TY\_INT\_EXPOS← URE TIME = 0x0301 | TY\_FEATURE\_INT,

TY\_BOOL\_AUTO\_GAIN = 0x0302 | TY\_FEATURE\_BOOL, TY\_INT\_GAIN = 0x0303 | TY\_FEATURE\_INT, TY\_BOOL\_AUTO\_AWB = 0x0304 | TY\_FEATURE\_BOOL, TY\_STRUCT\_AEC\_ROI = 0x0305 | TY\_FEACURE\_STRUCT,

TY\_INT\_TOF\_HDR\_RATIO = 0x0306 | TY\_FEATURE\_INT, TY\_INT\_TOF\_JITTER\_THRESHOLD = 0x0307 | TY\_FEATURE\_INT, TY\_INT\_LASER\_POWER = 0x0500 | TY\_FEATURE\_INT, TY\_BOOL\_LASER\_AUT ← O CTRL = 0x0501 | TY\_FEATURE\_BOOL,

TY\_STRUCT\_LASER\_PATTERN = 0x0502 | TY\_FEATURE\_STRUCT, TY\_INT\_LASER\_CAM\_TRIG\_POS = 0x0503 | TY\_FEATURE\_INT, TY\_INT\_LASER\_CAM\_TRIG\_LEN = 0x0504 | TY\_FEATURE\_INT, TY\_I ↔ NT\_LASER\_LUT\_TRIG\_POS = 0x0505 | TY\_FEATURE\_INT,

**TY\_INT\_LASER\_LUT\_NUM** = 0x0506 | TY\_FEATURE\_INT, **TY\_INT\_LASER\_PATTERN\_OFFSET** = 0x0507 | TY\_FEATURE\_INT, **TY\_INT\_LASER\_MIRROR\_NUM** = 0x0508 | TY\_FEATURE\_INT, **TY\_IN** $\leftrightarrow$  **T\_LASER\_MIRROR\_SEL** = 0x0509 | TY\_FEATURE\_INT,

TY\_INT\_LASER\_LUT\_IDX = 0x050a | TY\_FEATURE\_INT, TY\_INT\_LASER\_FACET\_IDX = 0x050b | TY ← FEATURE\_INT, TY\_INT\_LASER\_FACET\_POS = 0x050c | TY\_FEATURE\_INT, TY\_INT\_LASER\_MODE = 0x050d | TY\_FEATURE\_INT,

TY\_INT\_CONST\_DRV\_DUTY = 0x050e | TY\_FEATURE\_INT, TY\_STRUCT\_LASER\_ENABLE\_BY\_IDX = 0x0530 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_LASER\_POWER\_BY\_IDX = 0x0531 | TY\_FEATURE\_S⇔ TRUCT, TY\_STRUCT\_FLOOD\_ENABLE\_BY\_IDX = 0x0532 | TY\_FEATURE\_STRUCT,

TY\_STRUCT\_FLOOD\_POWER\_BY\_IDX = 0x0533 | TY\_FEATURE\_STRUCT, TY\_BOOL\_UNDISTORTION = 0x0510 | TY\_FEATURE\_BOOL, TY\_BOOL\_BRIGHTNESS\_HISTOGRAM = 0x0511 | TY\_FEATURE\_B $\leftrightarrow$  OOL, TY\_BOOL\_DEPTH\_POSTPROC = 0x0512 | TY\_FEATURE\_BOOL,

TY\_INT\_R\_GAIN =  $0x0520 \mid TY_FEATURE_INT$ , TY\_INT\_G\_GAIN =  $0x0521 \mid TY_FEATURE_INT$ , TY\_I $\leftarrow$  NT\_B\_GAIN =  $0x0522 \mid TY_FEATURE_INT$ , TY\_INT\_ANALOG\_GAIN =  $0x0524 \mid TY_FEATURE_INT$ ,

TY\_BOOL\_HDR = 0x0525 | TY\_FEATURE\_BOOL, TY\_BYTEARRAY\_HDR\_PARAMETER = 0x0526 | TY\_FEATURE\_BYTEARRAY, TY\_INT\_AE\_TARGET\_Y = 0x0527 | TY\_FEATURE\_INT, TY\_BOOL\_IMU\_
DATA\_ONOFF = 0x0600 | TY\_FEATURE\_BOOL,

TY\_STRUCT\_IMU\_ACC\_BIAS = 0x0601 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_IMU\_ACC\_MISALIGN ← MENT = 0x0602 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_IMU\_ACC\_SCALE = 0x0603 | TY\_FEATURE\_← STRUCT, TY\_STRUCT\_IMU\_GYRO\_BIAS = 0x0604 | TY\_FEATURE\_STRUCT,

TY\_STRUCT\_IMU\_GYRO\_MISALIGNMENT = 0x0605 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_IMU\_G↔ YRO\_SCALE = 0x0606 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_IMU\_CAM\_TO\_IMU = 0x0607 | TY\_FE↔ ATURE STRUCT, TY\_ENUM\_IMU\_FPS = 0x0608 | TY\_FEATURE\_ENUM,

 $\label{ty_int_sgbm_image_num} TY\_INT\_SGBM\_IMAGE\_NUM = 0x0610 \mid TY\_FEATURE\_INT, TY\_INT\_SGBM\_DISPARITY\_NUM = 0x0611 \mid TY\_FEATURE\_INT, TY\_INT\_SGBM\_DISPARITY\_OFFSET = 0x0612 \mid TY\_FEATURE\_INT, TY\_INT\_SG \\ \\ BM\_MATCH\_WIN\_HEIGHT = 0x0613 \mid TY\_FEATURE\_INT, \\ \\ \\ DESCRIPTION = 0x0611 \\ DESCRIPTION = 0x06$ 

TY\_INT\_SGBM\_SEMI\_PARAM\_P1 = 0x0614 | TY\_FEATURE\_INT, TY\_INT\_SGBM\_SEMI\_PARAM\_P2 = 0x0615 | TY\_FEATURE\_INT, TY\_INT\_SGBM\_UNIQUE\_FACTOR = 0x0616 | TY\_FEATURE\_INT, TY\_IN TO SGBM\_UNIQUE\_ABSDIFF = 0x0617 | TY\_FEATURE\_INT, TY\_INT\_SGBM\_UNIQUE\_ABSDIFF = 0x0617 | TY\_FEATURE\_INT\_STAN\_

 $\begin{tabular}{ll} TY\_INT\_SGBM\_UNIQUE\_MAX\_COST = 0x0618 & TY\_FEATURE\_INT, TY\_BOOL\_SGBM\_HFILTER\_HA & LF\_WIN = 0x0619 & TY\_FEATURE\_BOOL, TY\_INT\_SGBM\_MATCH\_WIN\_WIDTH = 0x061A & TY\_FEAT & URE\_INT, TY\_BOOL\_SGBM\_MEDFILTER = 0x061B & TY\_FEATURE\_BOOL, \\ \end{tabular}$ 

TY\_BOOL\_SGBM\_LRC =  $0x061C \mid TY_FEATURE_BOOL$ , TY\_INT\_SGBM\_LRC\_DIFF =  $0x061D \mid TY_F \leftrightarrow EATURE_INT$ , TY\_INT\_SGBM\_MEDFILTER\_THRESH =  $0x061E \mid TY_FEATURE_INT$ , TY\_INT\_SGBM\_ $\leftrightarrow SEMI_PARAM_P1_SCALE = <math>0x061F \mid TY_FEATURE_INT$ ,

TY\_INT\_SGPM\_PHASE\_NUM =  $0x0620 \mid TY_FEATURE_INT, TY_INT_SGPM_NORMAL_PHASE_SCALE$  =  $0x0621 \mid TY_FEATURE_INT, TY_INT_SGPM_NORMAL_PHASE_OFFSET$  =  $0x0622 \mid TY_FEATURE\_$   $\longleftrightarrow$  INT, TY\_INT\_SGPM\_REF\_PHASE\_SCALE =  $0x0623 \mid TY_FEATURE_INT$ ,

```
TY_INT_SGPM_REF_PHASE_OFFSET = 0x0624 | TY_FEATURE_INT, TY_STRUCT_PHC_GROUP_A↔
 TTR = 0x0710 | TY FEATURE STRUCT, TY ENUM DEPTH QUALITY = 0x0900 | TY FEATURE ENUM,
 TY INT FILTER THRESHOLD = 0x0901 | TY FEATURE INT,
 TY_INT_TOF_CHANNEL = 0x0902 | TY_FEATURE_INT, TY_INT_TOF_MODULATION_THRESHOLD =
 0x0903 | TY FEATURE INT, TY STRUCT TOF FREQ = 0x0904 | TY FEATURE STRUCT, TY BOOL ←
 TOF ANTI INTERFERENCE = 0x0905 | TY FEATURE BOOL,
 TY INT TOF ANTI SUNLIGHT INDEX = 0x0906 | TY FEATURE INT, TY INT MAX SPECKLE SIZE =
 0x0907 | TY FEATURE INT, TY INT MAX SPECKLE DIFF = 0x0908 | TY FEATURE INT }
    feature for component definitions

    enum TY CONFIG MODE LIST: uint32 t {

 TY CONFIG MODE PRESETO = 0, TY CONFIG MODE PRESET1, TY CONFIG MODE PRESET2,
 TY CONFIG MODE USERSET0 = (1 << 16),
 TY CONFIG MODE USERSET1, TY CONFIG MODE USERSET2 }

    enum TY DEPTH QUALITY LIST: uint32 t { TY DEPTH QUALITY BASIC = 1, TY DEPTH QUALIT←

 Y_MEDIUM = 2, TY_DEPTH_QUALITY_HIGH = 4 }

    enum TY_TRIGGER_POL_LIST: uint32_t { TY_TRIGGER_POL_FALLINGEDGE = 0, TY_TRIGGER_P←

 OL_RISINGEDGE = 1 }
    set external trigger signal edge

    enum TY INTERFACE TYPE LIST: uint32 t {

 TY INTERFACE UNKNOWN = 0, TY INTERFACE RAW = 1, TY INTERFACE USB = 2, TY INTERF←
 ACE ETHERNET = 4.
 TY_INTERFACE_IEEE80211 = 8, TY_INTERFACE_ALL = 0xffff }
• enum TY ACCESS MODE LIST: uint32 t { TY ACCESS READABLE = 0x1, TY ACCESS WRITABLE
 = 0x2

    enum TY STREAM ASYNC MODE LIST: uint32 t {

 TY STREAM ASYNC OFF = 0, TY STREAM ASYNC DEPTH = 1, TY STREAM ASYNC RGB = 2, T↔
 Y STREAM ASYNC DEPTH RGB = 3,
 TY STREAM ASYNC ALL = 0xff }
    stream async mode
• enum TY PIXEL BITS LIST: uint32 t {
 TY PIXEL 8BIT = 0x1 << 28, TY PIXEL 16BIT = 0x2 << 28, TY PIXEL 24BIT = 0x3 << 28, TY PIX\leftrightarrow
 EL 32BIT = 0x4 << 28,
 TY PIXEL 10BIT = 0x5 << 28, TY PIXEL 12BIT = 0x6 << 28, TY PIXEL 14BIT = 0x7 << 28, TY PI\leftarrow
 XEL 48BIT = (uint32 t)0x8 << 28,
 TY_PIXEL_64BIT = (uint32_t)0xa << 28 }
• enum TY PIXEL FORMAT LIST: uint32 t {
 TY_PIXEL_FORMAT_UNDEFINED = 0, TY_PIXEL_FORMAT_MONO = (TY_PIXEL_8BIT | (0x0 << 24)),
 TY_PIXEL_FORMAT_BAYER8GB = (TY_PIXEL_8BIT | (0x1 << 24)), TY_PIXEL_FORMAT_BAYER8BG =
 (TY PIXEL 8BIT | (0x2 << 24)),
 TY PIXEL FORMAT BAYER8GR = (TY PIXEL 8BIT | (0x3 << 24)), TY PIXEL FORMAT BAYER8RG
 = (TY PIXEL 8BIT | (0x4 << 24)), TY PIXEL FORMAT BAYER8GRBG = TY PIXEL FORMAT BAYE
 R8GB, TY PIXEL FORMAT BAYER8RGGB = TY PIXEL FORMAT BAYER8BG,
 TY PIXEL FORMAT BAYER8GBRG = TY PIXEL FORMAT BAYER8GR, TY PIXEL FORMAT BAY↔
 ER8BGGR = TY_PIXEL_FORMAT_BAYER8RG, TY_PIXEL_FORMAT_CSI_MONO10 = (TY_PIXEL_10BIT
 |(0x0 << 24)), TY_PIXEL_FORMAT_CSI_BAYER10GRBG = (TY_PIXEL_10BIT |(0x1 << 24)),
 TY_PIXEL_FORMAT_CSI_BAYER10RGGB = (TY_PIXEL_10BIT | (0x2 << 24)), TY_PIXEL_FORMAT_←
 CSI BAYER10GBRG = (TY PIXEL 10BIT | (0x3 << 24)), TY PIXEL FORMAT CSI BAYER10BGGR =
 (TY_PIXEL_10BIT \mid (0x4 << 24)), TY_PIXEL_FORMAT_CSI_MONO12 = (TY_PIXEL_12BIT \mid (0x0 << 24)))
 24)),
 TY PIXEL FORMAT CSI BAYER12GRBG = (TY PIXEL 12BIT | (0x1 << 24)), TY PIXEL FORMAT ←
 CSI BAYER12RGGB = (TY PIXEL 12BIT | (0x2 << 24)), TY PIXEL FORMAT CSI BAYER12GBRG =
 (TY PIXEL 12BIT | (0x3 << 24)), TY PIXEL FORMAT CSI BAYER12BGGR = (TY PIXEL 12BIT | (0x4
 << 24)),
 TY PIXEL FORMAT DEPTH16 = (TY PIXEL 16BIT | (0x0 << 24)), TY PIXEL FORMAT YVYU = (TY↔
  PIXEL 16BIT | (0x1 << 24)), TY PIXEL FORMAT YUYV = (TY PIXEL 16BIT | (0x2 << 24)), TY PI\leftrightarrow
 XEL_FORMAT_MONO16 = (TY_PIXEL_16BIT | (0x3 << 24)),
 TY_PIXEL_FORMAT_TOF_IR_MONO16 = (TY_PIXEL_64BIT | (0x4 << 24)), TY_PIXEL_FORMAT_RGB
```

```
= (TY_PIXEL_24BIT | (0x0 << 24)), TY_PIXEL_FORMAT_BGR = (TY_PIXEL_24BIT | (0x1 << 24)), TY \leftarrow
   PIXEL FORMAT JPEG = (TY PIXEL 24BIT | (0x2 << 24)),
  TY_PIXEL_FORMAT_MJPG = (TY_PIXEL_24BIT \mid (0x3 << 24)), TY_PIXEL_FORMAT_RGB48 = (TY_P\leftrightarrow
  IXEL_48BIT | (0x0 << 24)), TY_PIXEL_FORMAT_BGR48 = (TY_PIXEL_48BIT | (0x1 << 24)), TY_PIX\leftarrow
  EL FORMAT XYZ48 = (TY PIXEL 48BIT | (0x2 << 24)) }
      pixel format definitions

    enum TY RESOLUTION MODE LIST: uint32 t {

  TY_RESOLUTION_MODE_160x100 = (160 << 12) + 100, TY_RESOLUTION_MODE_160x120 = (160 << 12) + 120,
  TY RESOLUTION MODE 240x320 = (240 << 12) +320, TY RESOLUTION MODE 320x180 = (320 << 12) +180,
  TY RESOLUTION MODE 320x200 = (320 << 12) + 200, TY RESOLUTION MODE 320x240 = (320 << 12) + 240,
  TY RESOLUTION MODE 480 \times 640 = (480 <<12) + 640, TY RESOLUTION MODE 640 \times 360 = (640 <<12) + 360,
  TY_RESOLUTION_MODE_640x400 = (640 << 12) + 400, TY_RESOLUTION_MODE_640x480 = (640 << 12) + 480, TY_RESOLUTION_MODE_640x40 = (640 << 12) + 480, TY_RESOLUTION_MODE_640x40 = (
  TY_RESOLUTION_MODE_960x1280 = (960 << 12) + 1280, TY_RESOLUTION_MODE_1280x720 =
  (1280 << 12) + 720,
  TY RESOLUTION MODE 1280x800 = (1280<<12)+800, TY RESOLUTION MODE 1280x960
  (1280<<12)+960, TY_RESOLUTION_MODE_1600×1200 = (1600<<12)+1200, TY_RESOLUTION_←
  MODE 800 \times 600 = (800 < <12) + 600,
  TY RESOLUTION MODE 1920x1080 = (1920<<12)+1080, TY RESOLUTION MODE 2560x1920 =
  (2560<<12)+1920, TY RESOLUTION MODE 2592x1944 = (2592<<12)+1944, TY RESOLUTION M↔
  ODE_{1920} \times 1440 = (1920 << 12) + 1440,
  TY_RESOLUTION_MODE_240x96 = (240<<12)+96, TY_RESOLUTION_MODE_2048x1536 = (2048<<12)+1536
  }
      predefined resolution list

    enum TY IMAGE MODE LIST: uint32 t {

  TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE .
  IMAGE MODE1 = (MONO), TY_DECLARE IMAGE MODE1 = (MONO),
  TY DECLARE IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO), TY DECLARE \
  IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO),
  TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE -
  IMAGE MODE1 = (MONO), TY_DECLARE_IMAGE_MODE1 = (MONO),
  TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE -
  IMAGE_MODE1 = (MONO), TY_DECLARE_IMAGE_MODE1 = (MONO),
  TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE .
  IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
  TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE -
  IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
  TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_ ↔
  IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
  TY DECLARE IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO) }
       Predefined Image Mode List image mode controls image resolution & format predefined image modes named like
       TY_IMAGE_MODE_MONO_160x120,TY_IMAGE_MODE_RGB_1280x960.
enum TY_TRIGGER_MODE_LIST : uint32_t {
  TY TRIGGER MODE OFF = 0, TY TRIGGER MODE SLAVE = 1, TY TRIGGER MODE M SIG = 2, T↔
  Y TRIGGER MODE M PER = 3,
  TY TRIGGER MODE SIG PASS = 18, TY TRIGGER MODE PER PASS = 19, TY TRIGGER MODE ↔
  _TIMER_LIST = 20, TY_TRIGGER_MODE_TIMER_PERIOD = 21,
TY_TRIGGER_MODE28 = 28, TY_TRIGGER_MODE29 = 29, TY_TRIGGER_MODE_PER_PASS2 = 30,
  TY TRIGGER WORK MODE31 = 31,
  TY_TRIGGER_MODE_SIG_LASER = 34 }

    enum TY TIME SYNC TYPE LIST: uint32 t {

  TY TIME SYNC TYPE NONE = 0, TY TIME SYNC TYPE HOST = 1, TY TIME SYNC TYPE NTP = 2,
  TY TIME SYNC TYPE PTP = 3.
  TY_TIME_SYNC_TYPE_CAN = 4, TY_TIME_SYNC_TYPE_PTP_MASTER = 5 }
       type of time sync

    enum { TY PATTERN SINE TYPE = 0, TY PATTERN GRAY TYPE, TY PATTERN BIN TYPE, TY ←

  PATTERN EMPTY TYPE = 0xffffffff }
• enum { TY_NORMAL_PHASE_TYPE = 0, TY_REFER_PHASE_TYPE }
enum TY_IMU_FPS_LIST { TY_IMU_FPS_100HZ = 0, TY_IMU_FPS_200HZ, TY_IMU_FPS_400HZ }
```

#### **Functions**

TY EXTC TY EXPORT const char \*TY STDC TYErrorString (TY STATUS errorID)

Get error information.

• TY CAPI TYDeinitLib (void)

Deinit this library.

• TY\_CAPI TYLibVersion (TY\_VERSION\_INFO \*version)

Get current library version.

TY CAPI TYUpdateInterfaceList ()

Update current interfaces. call before TYGetInterfaceList.

TY\_CAPI TYGetInterfaceNumber (uint32\_t \*pNumIfaces)

Get number of current interfaces.

TY\_CAPI TYGetInterfaceList (TY\_INTERFACE\_INFO \*plfaceInfos, uint32\_t bufferCount, uint32\_t \*filled ← Count)

Get interface info list.

• TY\_CAPI TYHasInterface (const char \*ifaceID, bool \*value)

Check if has interface.

TY CAPI TYOpenInterface (const char \*ifaceID, TY INTERFACE HANDLE \*outHandle)

Open specified interface.

• TY CAPI TYCloseInterface (TY INTERFACE HANDLE ifaceHandle)

Close interface.

TY\_CAPI TYUpdateDeviceList (TY\_INTERFACE\_HANDLE ifaceHandle)

Update current connected devices.

TY\_CAPI TYUpdateAllDeviceList ()

Update current connected devices.

• TY\_CAPI TYGetDeviceNumber (TY\_INTERFACE\_HANDLE ifaceHandle, uint32\_t \*deviceNumber)

Get number of current connected devices.

TY\_CAPI TYGetDeviceList (TY\_INTERFACE\_HANDLE ifaceHandle, TY\_DEVICE\_BASE\_INFO \*device ←
 Infos, uint32\_t bufferCount, uint32\_t \*filledDeviceCount)

Get device info list.

- TY\_CAPI TYHasDevice (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*deviceID, bool \*value)

  Check whether the interface has the specified device.
- TY\_CAPI TYOpenDevice (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*deviceID, TY\_DEV\_HAN ← DLE \*outDeviceHandle, TY\_FW\_ERRORCODE \*outFwErrorcode=NULL)

Open device by device ID.

• TY\_CAPI TYOpenDeviceWithIP (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*IP, TY\_DEV\_HANDLE \*deviceHandle)

Open device by device IP, useful when a device is not listed.

- TY\_CAPI TYGetDeviceInterface (TY\_DEV\_HANDLE hDevice, TY\_INTERFACE\_HANDLE \*plface)

  Get interface handle by device handle.
- TY\_CAPI TYForceDeviceIP (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*MAC, const char \*newIP, const char \*newNetMask, const char \*newGateway)

Force a ethernet device to use new IP address, useful when device use persistent IP and cannot be found.

• TY\_CAPI TYCloseDevice (TY\_DEV\_HANDLE hDevice, bool reboot=false)

Close device by device handle.

• TY CAPI TYGetDeviceInfo (TY DEV HANDLE hDevice, TY DEVICE BASE INFO \*info)

Get base info of the open device.

- TY\_CAPI TYGetComponentIDs (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID \*componentIDs)
   Get all components IDs.
- TY\_CAPI TYGetEnabledComponents (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID \*componentIDs) Get all enabled components IDs.
- TY CAPI TYEnableComponents (TY DEV HANDLE hDevice, TY COMPONENT ID componentIDs)

Enable components.

TY\_CAPI TYDisableComponents (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentIDs)

Disable components

• TY\_CAPI TYGetFrameBufferSize (TY\_DEV\_HANDLE hDevice, uint32\_t \*bufferSize)

Get total buffer size of one frame in current configuration.

• TY\_CAPI TYEnqueueBuffer (TY\_DEV\_HANDLE hDevice, void \*buffer, uint32\_t bufferSize)

Enqueue a user allocated buffer.

• TY CAPI TYClearBufferQueue (TY DEV HANDLE hDevice)

Clear the internal buffer queue, so that user can release all the buffer.

• TY\_CAPI TYStartCapture (TY\_DEV\_HANDLE hDevice)

Start capture.

TY\_CAPI TYStopCapture (TY\_DEV\_HANDLE hDevice)

Stop capture.

• TY\_CAPI TYSendSoftTrigger (TY\_DEV\_HANDLE hDevice)

Send a software trigger to capture a frame when device works in trigger mode.

 TY\_CAPI TYRegisterEventCallback (TY\_DEV\_HANDLE hDevice, TY\_EVENT\_CALLBACK callback, void \*userdata)

Register device status callback. Register NULL to clean callback.

 TY\_CAPI TYRegisterImuCallback (TY\_DEV\_HANDLE hDevice, TY\_IMU\_CALLBACK callback, void \*userdata)

Register imu callback. Register NULL to clean callback.

- TY\_CAPI TYFetchFrame (TY\_DEV\_HANDLE hDevice, TY\_FRAME\_DATA \*frame, int32\_t timeout)
   Fetch one frame.
- TY\_CAPI TYHasFeature (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATUR ←
   E ID featureID, bool \*value)

Check whether a component has a specific feature.

• TY\_CAPI TYGetFeatureInfo (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEAT ∪ URE\_ID featureID, TY\_FEATURE\_INFO \*featureInfo)

Get feature info.

• TY\_CAPI TYGetIntRange (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATU ← RE\_ID featureID, TY\_INT\_RANGE \*intRange)

Get value range of integer feature.

• TY\_CAPI TYGetInt (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, int32 t \*value)

Get value of integer feature.

TY\_CAPI TYSetInt (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, int32\_t value)

Set value of integer feature.

TY\_CAPI TYGetFloatRange (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEA
 — TURE\_ID featureID, TY\_FLOAT\_RANGE \*floatRange)

Get value range of float feature.

• TY\_CAPI TYGetFloat (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, float \*value)

Get value of float feature.

• TY\_CAPI TYSetFloat (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, float value)

Set value of float feature.

• TY\_CAPI TYGetEnumEntryCount (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_
FEATURE\_ID featureID, uint32\_t \*entryCount)

Get number of enum entries.

• TY\_CAPI TYGetEnumEntryInfo (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_F ← EATURE\_ID featureID, TY\_ENUM\_ENTRY \*entries, uint32\_t entryCount, uint32\_t \*filledEntryCount)

Get list of enum entries.

• TY\_CAPI TYGetEnum (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, uint32 t \*value)

Get current value of enum feature.

• TY\_CAPI TYSetEnum (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, uint32\_t value)

Set value of enum feature.

• TY\_CAPI TYGetBool (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, bool \*value)

Get value of bool feature.

• TY\_CAPI TYSetBool (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, bool value)

Set value of bool feature.

TY\_CAPI TYGetStringLength (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEA
 — TURE\_ID featureID, uint32\_t \*size)

Get internal buffer size of string feature.

• TY\_CAPI TYGetString (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, char \*buffer, uint32 t bufferSize)

Get value of string feature.

• TY\_CAPI TYSetString (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, const char \*buffer)

Set value of string feature.

• TY\_CAPI TYGetStruct (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, void \*pStruct, uint32\_t structSize)

Get value of struct.

• TY\_CAPI TYSetStruct (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, void \*pStruct, uint32\_t structSize)

Set value of struct.

Get the size of specified byte array zone .

 TY\_CAPI TYGetDeviceFeatureNumber (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, uint32\_t \*size)

Get the size of device features .

TY\_CAPI TYGetDeviceFeatureInfo (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY←
FEATURE INFO \*featureInfo, uint32 t entryCount, uint32 t \*filledEntryCount)

Get the all features by comp id.

• TY\_CAPI TYGetByteArray (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATU ← RE\_ID featureID, uint8\_t \*pBuffer, uint32\_t bufferSize)

Read byte array from device.

• TY\_CAPI TYSetByteArray (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATU ← RE\_ID featureID, const uint8\_t \*pBuffer, uint32\_t bufferSize)

Write byte array to device.

• TY\_CAPI TYGetByteArrayAttr (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FE

ATURE ID featureID, TY\_BYTEARRAY\_ATTR \*pAttr)

Write byte array to device.

• TY\_CAPI \_TYInitLib (void)

#### **Variables**

- · typedef enum
- typedef TY DO 5V = 1
- typedef TY\_DO\_12V = 2
- typedef TY\_E\_VOLT\_T\_LIST
- typedef TY\_DO\_HIGH = 1
- typedef TY\_DO\_PWM = 2
- typedef TY DO CAM TRIG = 3
- typedef TY E DO MODE LIST
- typedef TY\_DI\_NE\_INT = 1
- typedef **TY\_DI\_PE\_INT** = 2
- typedef TY\_E\_DI\_MODE\_LIST
- typedef TY\_DI\_INT\_TRIG\_CAP = 1
- typedef **TY\_DI\_INT\_EVENT** = 2
- typedef TY\_E\_DI\_INT\_ACTION\_LIST

#### 5.1.1 Detailed Description

TYApi.h includes camera control and data receiving interface, which supports configuration for image resolution, frame rate, exposure time, gain, working mode,etc.

#### 5.1.2 Macro Definition Documentation

#### 5.1.2.1 TY\_DECLARE\_IMAGE\_MODE1

```
#define TY_DECLARE_IMAGE_MODE1( pix )
```

### Value:

```
TY_DECLARE_IMAGE_MODE0(pix, 160x100), \
             TY_DECLARE_IMAGE_MODE0(pix, 160x120),
             TY_DECLARE_IMAGE_MODEO(pix, 320x180),
TY_DECLARE_IMAGE_MODEO(pix, 320x200),
             TY_DECLARE_IMAGE_MODE0(pix, 320x240),
             TY_DECLARE_IMAGE_MODE0(pix, 480x640),
             TY_DECLARE_IMAGE_MODE0(pix, 640x360),
             TY_DECLARE_IMAGE_MODE0(pix, 640x400),
             TY_DECLARE_IMAGE_MODE0(pix, 640x480),
             TY_DECLARE_IMAGE_MODE0(pix, 960x1280),
             TY_DECLARE_IMAGE_MODE0(pix, 1280x720),
             TY_DECLARE_IMAGE_MODE0(pix, 1280x960),
             TY_DECLARE_IMAGE_MODE0(pix, 1280x800),
             TY_DECLARE_IMAGE_MODE0(pix, 1600x1200),
             TY_DECLARE_IMAGE_MODEO(pix, 800x600), \
TY_DECLARE_IMAGE_MODEO(pix, 1920x1080),
             TY_DECLARE_IMAGE_MODE0(pix, 2560x1920),
             TY_DECLARE_IMAGE_MODE0(pix, 2592x1944),
             TY_DECLARE_IMAGE_MODE0(pix, 1920x1440),
             TY_DECLARE_IMAGE_MODE0(pix, 2048x1536),
             TY_DECLARE_IMAGE_MODE0(pix, 240x96)
```

Definition at line 544 of file TYApi.h.

# 5.1.3 Typedef Documentation

### 5.1.3.1 TY\_ACC\_BIAS

typedef struct TY\_ACC\_BIAS TY\_ACC\_BIAS

### a 3x3 matrix

•		•
BIASx	BIASy	BIASz

# 5.1.3.2 TY\_ACC\_MISALIGNMENT

typedef struct TY\_ACC\_MISALIGNMENT TY\_ACC\_MISALIGNMENT

a 3x3 matrix |.|.|.

1	-GAMAyz	GAMAzy
GAMAxz	1	-GAMAzx
-GAMAxy	GAMAyx	1

### 5.1.3.3 TY\_ACC\_SCALE

typedef struct TY\_ACC\_SCALE TY\_ACC\_SCALE

### a 3x3 matrix

		•
SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

### 5.1.3.4 TY\_ACCESS\_MODE\_LIST

typedef enum TY\_ACCESS\_MODE\_LIST TY\_ACCESS\_MODE\_LIST

Indicate a feature is readable or writable

See also

**TYGetFeatureInfo** 

```
5.1.3.5 TY_BYTEARRAY_ATTR
```

```
typedef struct TY_BYTEARRAY_ATTR TY_BYTEARRAY_ATTR
```

byte array data structure

See also

**TYGetByteArray** 

```
5.1.3.6 TY_CAMERA_CALIB_INFO
```

```
typedef struct TY_CAMERA_CALIB_INFO TY_CAMERA_CALIB_INFO
```

camera 's cailbration data

See also

**TYGetStruct** 

### 5.1.3.7 TY\_CAMERA\_DISTORTION

```
typedef struct TY_CAMERA_DISTORTION TY_CAMERA_DISTORTION
```

camera distortion parameters

See also

### TYGetStruct Usage:

#### 5.1.3.8 TY\_CAMERA\_EXTRINSIC

```
typedef struct TY_CAMERA_EXTRINSIC TY_CAMERA_EXTRINSIC
```

a 4x4 matrix

	•		
r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

### See also

### TYGetStruct Usage:

```
TY_CAMERA_EXTRINSIC extrinsic;
TYGetStruct(hDevice, some_compoent, TY_STRUCT_EXTRINSIC, &extrinsic, sizeof(extrinsic));
```

### 5.1.3.9 TY\_CAMERA\_INTRINSIC

typedef struct TY\_CAMERA\_INTRINSIC TY\_CAMERA\_INTRINSIC

### a 3x3 matrix

•	•	
fx	0	СХ
0	fy	су
0	0	1

### See also

### TYGetStruct Usage:

### 5.1.3.10 TY\_CAMERA\_TO\_IMU

typedef struct TY\_CAMERA\_TO\_IMU TY\_CAMERA\_TO\_IMU

### a 4x4 matrix

r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

```
5.1.3.11 TY_COMPONENT_ID
```

typedef uint32\_t TY\_COMPONENT\_ID

component unique id

See also

TY\_DEVICE\_COMPONENT\_LIST

Definition at line 209 of file TYApi.h.

```
5.1.3.12 TY_DEVICE_BASE_INFO
```

typedef struct TY\_DEVICE\_BASE\_INFO TY\_DEVICE\_BASE\_INFO

See also

**TYGetDeviceList** 

### 5.1.3.13 TY\_DEVICE\_COMPONENT\_LIST

```
typedef enum TY_DEVICE_COMPONENT_LIST TY_DEVICE_COMPONENT_LIST
```

Device Component list A device contains several component. Each component can be controlled by its own features, such as image width, exposure time, etc..

See also

To Know how to get feature information please refer to sample code DumpAllFeatures

```
5.1.3.14 TY_ENUM_ENTRY
```

typedef struct TY\_ENUM\_ENTRY TY\_ENUM\_ENTRY

enum feature entry information

See also

TYGetEnumEntryInfo

### 5.1.3.15 TY\_FEATURE\_ID

typedef uint32\_t TY\_FEATURE\_ID

feature unique id

See also

TY\_FEATURE\_ID\_LIST

Definition at line 376 of file TYApi.h.

### 5.1.3.16 TY\_FLOAT\_RANGE

typedef struct TY\_FLOAT\_RANGE TY\_FLOAT\_RANGE

float range data structure

See also

TYGetFloatRange

# 5.1.3.17 TY\_GYRO\_BIAS

typedef struct TY\_GYRO\_BIAS TY\_GYRO\_BIAS

a 3x3 matrix

BIASx	BIASy	BIASz

### 5.1.3.18 TY\_GYRO\_MISALIGNMENT

typedef struct TY\_GYRO\_MISALIGNMENT TY\_GYRO\_MISALIGNMENT

a 3x3 matrix

1	-ALPHAyz	ALPHAzy
0	1	-ALPHAzx
0	0	1

### 5.1.3.19 TY\_GYRO\_SCALE

typedef struct TY\_GYRO\_SCALE TY\_GYRO\_SCALE

#### a 3x3 matrix

SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

### 5.1.3.20 TY\_INTERFACE\_INFO

typedef struct TY\_INTERFACE\_INFO TY\_INTERFACE\_INFO

See also

**TYGetInterfaceList** 

### 5.1.3.21 TY\_INTERFACE\_TYPE\_LIST

typedef enum TY\_INTERFACE\_TYPE\_LIST TY\_INTERFACE\_TYPE\_LIST

Interface type definition

See also

TYGetInterfaceList

### 5.1.3.22 TY\_PIXEL\_BITS\_LIST

typedef enum TY\_PIXEL\_BITS\_LIST TY\_PIXEL\_BITS\_LIST

Pixel size type definitions to define the pixel size in bits

See also

TY\_PIXEL\_FORMAT\_LIST

### 5.1.3.23 TY\_TRIGGER\_MODE\_LIST

```
typedef enum TY_TRIGGER_MODE_LIST TY_TRIGGER_MODE_LIST
```

#### See also

refer to sample SimpleView TriggerMode for detail usage

# 5.1.4 Enumeration Type Documentation

### 5.1.4.1 TY\_ACCESS\_MODE\_LIST

```
enum TY_ACCESS_MODE_LIST : uint32_t
```

Indicate a feature is readable or writable

#### See also

**TYGetFeatureInfo** 

Definition at line 430 of file TYApi.h.

### 5.1.4.2 TY\_DEVICE\_COMPONENT\_LIST

```
enum TY_DEVICE_COMPONENT_LIST : uint32_t
```

Device Component list A device contains several component. Each component can be controlled by its own features, such as image width, exposure time, etc..

### See also

To Know how to get feature information please refer to sample code DumpAllFeatures

TY_COMPONENT_DEVICE	Abstract component stands for whole device, always enabled.	
TY_COMPONENT_DEPTH_CAM	Depth camera.	
TY_COMPONENT_IR_CAM_LEFT	Left IR camera.	
TY_COMPONENT_IR_CAM_RIGHT	Right IR camera.	
TY_COMPONENT_RGB_CAM_LEFT	Left RGB camera.	
TY_COMPONENT_RGB_CAM_RIGHT	Right RGB camera.	
TY_COMPONENT_LASER	Laser.	
TY_COMPONENT_IMU	Inertial Measurement Unit.	
TY_COMPONENT_BRIGHT_HISTO	virtual component for brightness histogram of ir	
TY_COMPONENT_STORAGE	virtual component for device storage	
TY_COMPONENT_RGB_CAM	Some device has only one RGB camera, map it to left merated by Do	xyger

Definition at line 194 of file TYApi.h.

# 5.1.4.3 TY\_FEATURE\_ID\_LIST

enum TY\_FEATURE\_ID\_LIST : uint32\_t

feature for component definitions

see TY_CAMERA_INTRINSIC
extrinsic between depth cam and current component, see TY_CAMERA_EXTRINSIC
extrinsic between left IR and current compoent, see
TY_CAMERA_EXTRINSIC
see TY_CAMERA_DISTORTION
see TY_CAMERA_CALIB_INFO
the rectified intrinsic. see TY_CAMERA_INTRINSIC
used for reading/writing custom block
used for reading/writing fpn block
microseconds
Ntp server IP.
milliseconds
statistical information, see TY_CAMERA_STATISTICS
Image width.
Image height.
Resolution-PixelFromat mode, see TY_IMAGE_MODE_LIST.
scale unit depth image is uint16 pixel format with default
millimeter unit ,for some device can output Sub-millimeter
accuracy data the acutal depth (mm)= PixelValue * ScaleUnit
Trigger POL, see TY_TRIGGER_POL_LIST.
Number of frames captured per trigger.
param of trigger, see TY_TRIGGER_PARAM
param of trigger, see TY_TRIGGER_PARAM_EX
param of trigger mode 20, see TY_TRIGGER_TIMER_LIST
param of trigger mode 21, see
TY_TRIGGER_TIMER_PERIOD
Keep Alive switch.
Keep Alive timeout.
Cmos sync switch.
Trigger delay time, in microseconds.
Trigger out IO.
Trigger duration time, in microseconds.
stream async switch, see TY_STREAM_ASYNC_MODE
capture time in multi-ir
see TY_TIME_SYNC_TYPE
time sync done status
Enable switch for floodlight used in ir component.

TY_INT_IR_FLASHLIGHT_INTENSITY	ir component flashlight intensity level
TY_BOOL_RGB_FLASHLIGHT	Enable switch for floodlight used in rgb component.
TY_INT_RGB_FLASHLIGHT_INTENSITY	rgb component flashlight intensity level
TY_STRUCT_DO0_WORKMODE	DO_0 workmode, see TY_DO_WORKMODE.
TY_STRUCT_DI0_WORKMODE	DI_0 workmode, see TY_DI_WORKMODE.
TY_STRUCT_DO1_WORKMODE	DO_1 workmode, see TY_DO_WORKMODE.
TY_STRUCT_DI1_WORKMODE	DI_1 workmode, see TY_DI_WORKMODE.
TY_STRUCT_DO2_WORKMODE	DO_2 workmode, see TY_DO_WORKMODE.
TY_STRUCT_DI2_WORKMODE	DI_2 workmode, see TY_DI_WORKMODE.
TY_BOOL_AUTO_EXPOSURE	Auto exposure switch.
TY_INT_EXPOSURE_TIME	Exposure time.
TY_BOOL_AUTO_GAIN	Auto gain switch.
TY_INT_GAIN	Sensor Gain.
TY_BOOL_AUTO_AWB	Auto white balance.
TY_STRUCT_AEC_ROI	region of aec statistics, see TY_AEC_ROI_PARAM
TY_INT_TOF_HDR_RATIO	tof sensor hdr ratio for depth
TY_INT_TOF_JITTER_THRESHOLD	tof jitter threshold for depth
TY_INT_LASER_POWER	Laser power level.
TY_BOOL_LASER_AUTO_CTRL	Laser auto ctrl.
TY_STRUCT_LASER_ENABLE_BY_IDX	Laser enable by device index.
TY_STRUCT_LASER_POWER_BY_IDX	Laser power by device index.
TY_STRUCT_FLOOD_ENABLE_BY_IDX	Flood enable by device index.
TY_STRUCT_FLOOD_POWER_BY_IDX	Flood power by device index.
TY_BOOL_UNDISTORTION	Output undistorted image.
TY_BOOL_BRIGHTNESS_HISTOGRAM	Output bright histogram.
TY_BOOL_DEPTH_POSTPROC	Do depth image postproc.
TY_INT_R_GAIN	Gain of R channel.
TY_INT_G_GAIN	Gain of G channel.
TY_INT_B_GAIN	Gain of B channel.
TY_INT_ANALOG_GAIN	Analog gain.
TY_BOOL_HDR	HDR func enable/disable.
TY_BYTEARRAY_HDR_PARAMETER	HDR parameters.
TY_BOOL_IMU_DATA_ONOFF	AE target y. IMU Data Onoff
TY_STRUCT_IMU_ACC_BIAS	IMU acc bias matrix, see TY_ACC_BIAS.
TY_STRUCT_IMU_ACC_MISALIGNMENT	IMU acc misalignment matrix, see
TV OTBLIOT INTL ACC COME	TY_ACC_MISALIGNMENT.
TY_STRUCT_IMU_ACC_SCALE	IMU acc scale matrix, see TY_ACC_SCALE.
TY_STRUCT_IMU_GYRO_BIAS  TY STRUCT IMU GYRO MISALIGNMENT	IMU gyro bias matrix, see TY_GYRO_BIAS.  IMU gyro misalignment matrix, see
TY_STRUCT_INIO_GYRO_MISALIGNMENT	TY_GYRO_MISALIGNMENT.
TY STRUCT IMU GYRO SCALE	IMU gyro scale matrix, see TY_GYRO_SCALE.
TY STRUCT IMU CAM TO IMU	IMU camera to imu matrix, see TY_CAMERA_TO_IMU.
TY_ENUM_IMU_FPS	IMU fps, see TY_IMU_FPS_LIST.
TY INT SGBM IMAGE NUM	SGBM image channel num.
TY INT SGBM DISPARITY NUM	SGBM disparity num.
TY_INT_SGBM_DISPARITY_OFFSET	SGBM disparity offset.
TY_INT_SGBM_MATCH_WIN_HEIGHT	SGBM match window height.
TY_INT_SGBM_SEMI_PARAM_P1	SGBM semi global param p1.

### Enumerator

TY_INT_SGBM_SEMI_PARAM_P2	SGBM semi global param p2.
TY_INT_SGBM_UNIQUE_FACTOR	SGBM uniqueness factor param.
TY_INT_SGBM_UNIQUE_ABSDIFF	SGBM uniqueness min absolute diff.
TY_INT_SGBM_UNIQUE_MAX_COST	SGBM uniqueness max cost param.
TY_BOOL_SGBM_HFILTER_HALF_WIN	SGBM enable half window size.
TY_INT_SGBM_MATCH_WIN_WIDTH	SGBM match window width.
TY_BOOL_SGBM_MEDFILTER	SGBM enable median filter.
TY_BOOL_SGBM_LRC	SGBM enable left right consist check.
TY_INT_SGBM_LRC_DIFF	SGBM max diff.
TY_INT_SGBM_MEDFILTER_THRESH	SGBM median filter thresh.
TY_INT_SGBM_SEMI_PARAM_P1_SCALE	SGBM semi global param p1 scale.
TY_INT_SGPM_PHASE_NUM	Phase num to calc a depth.
TY_INT_SGPM_NORMAL_PHASE_SCALE	phase scale when calc a depth
TY_INT_SGPM_NORMAL_PHASE_OFFSET	Phase offset when calc a depth.
TY_INT_SGPM_REF_PHASE_SCALE	Reference Phase scale when calc a depth.
TY_INT_SGPM_REF_PHASE_OFFSET	Reference Phase offset when calc a depth.
TY_STRUCT_PHC_GROUP_ATTR	Phase compute group attribute.
TY_ENUM_DEPTH_QUALITY	the quality of generated depth, see TY_DEPTH_QUALITY
TY_INT_FILTER_THRESHOLD	the threshold of the noise filter, 0 for disabled
TY_INT_TOF_CHANNEL	the frequency channel of tof
TY_INT_TOF_MODULATION_THRESHOLD	the threshold of the tof modulation
TY_STRUCT_TOF_FREQ	the frequency of tof, see TY_TOF_FREQ
TY_BOOL_TOF_ANTI_INTERFERENCE	cooperation if multi-device used
TY_INT_TOF_ANTI_SUNLIGHT_INDEX	the index of anti-sunlight
TY_INT_MAX_SPECKLE_SIZE	the max size of speckle
TY_INT_MAX_SPECKLE_DIFF	the max diff of speckle

Definition at line 228 of file TYApi.h.

# 5.1.4.4 TY\_INTERFACE\_TYPE\_LIST

enum TY\_INTERFACE\_TYPE\_LIST : uint32\_t

Interface type definition

See also

TYGetInterfaceList

Definition at line 417 of file TYApi.h.

# 5.1.4.5 TY\_PIXEL\_BITS\_LIST

```
enum TY_PIXEL_BITS_LIST : uint32_t
```

Pixel size type definitions to define the pixel size in bits

See also

```
TY_PIXEL_FORMAT_LIST
```

Definition at line 452 of file TYApi.h.

# 5.1.4.6 TY\_PIXEL\_FORMAT\_LIST

```
enum TY_PIXEL_FORMAT_LIST : uint32_t
```

pixel format definitions

TY_PIXEL_FORMAT_MONO	0x10000000
TY_PIXEL_FORMAT_BAYER8GB	0x11000000
TY_PIXEL_FORMAT_BAYER8BG	0x12000000
TY_PIXEL_FORMAT_BAYER8GR	0x13000000
TY_PIXEL_FORMAT_BAYER8RG	0x14000000
TY_PIXEL_FORMAT_CSI_MONO10	0x50000000
TY_PIXEL_FORMAT_CSI_BAYER10GRBG	0x51000000
TY_PIXEL_FORMAT_CSI_BAYER10RGGB	0x52000000
TY_PIXEL_FORMAT_CSI_BAYER10GBRG	0x53000000
TY_PIXEL_FORMAT_CSI_BAYER10BGGR	0x54000000
TY_PIXEL_FORMAT_CSI_MONO12	0x60000000
TY_PIXEL_FORMAT_CSI_BAYER12GRBG	0x61000000
TY_PIXEL_FORMAT_CSI_BAYER12RGGB	0x62000000
TY_PIXEL_FORMAT_CSI_BAYER12GBRG	0x63000000
TY_PIXEL_FORMAT_CSI_BAYER12BGGR	0x64000000
TY_PIXEL_FORMAT_DEPTH16	0x20000000
TY_PIXEL_FORMAT_YVYU	0x21000000, yvyu422
TY_PIXEL_FORMAT_YUYV	0x22000000, yuyv422
TY_PIXEL_FORMAT_MONO16	0x23000000,
TY_PIXEL_FORMAT_TOF_IR_MONO16	0xa4000000,
TY_PIXEL_FORMAT_RGB	0x30000000
TY_PIXEL_FORMAT_BGR	0x31000000
TY_PIXEL_FORMAT_JPEG	0x32000000
TY_PIXEL_FORMAT_MJPG	0x33000000
TY_PIXEL_FORMAT_RGB48	0x80000000
TY_PIXEL_FORMAT_BGR48	0x81000000
TY_PIXEL_FORMAT_XYZ48	0x82000000

Definition at line 470 of file TYApi.h.

### 5.1.4.7 TY\_RESOLUTION\_MODE\_LIST

```
enum TY_RESOLUTION_MODE_LIST : uint32_t
```

predefined resolution list

#### Enumerator

TY_RESOLUTION_MODE_160x100	0x000a0078
TY_RESOLUTION_MODE_160x120	0x000a0078
TY_RESOLUTION_MODE_240x320	0x000f0140
TY_RESOLUTION_MODE_320x180	0x001400b4
TY_RESOLUTION_MODE_320x200	0x001400c8
TY_RESOLUTION_MODE_320x240	0x001400f0
TY_RESOLUTION_MODE_480x640	0x001e0280
TY_RESOLUTION_MODE_640x360	0x00280168
TY_RESOLUTION_MODE_640x400	0x00280190
TY_RESOLUTION_MODE_640x480	0x002801e0
TY_RESOLUTION_MODE_960x1280	0x003c0500
TY_RESOLUTION_MODE_1280x720	0x005002d0
TY_RESOLUTION_MODE_1280x800	0x00500320
TY_RESOLUTION_MODE_1280x960	0x005003c0
TY_RESOLUTION_MODE_1600x1200	0x006404b0
TY_RESOLUTION_MODE_800x600	0x00320258
TY_RESOLUTION_MODE_1920x1080	0x00780438
TY_RESOLUTION_MODE_2560x1920	0x00a00780
TY_RESOLUTION_MODE_2592x1944	0x00a20798
TY_RESOLUTION_MODE_1920x1440	0x007805a0
TY_RESOLUTION_MODE_240x96	0x000f0060
TY_RESOLUTION_MODE_2048x1536	0x00800600

Definition at line 514 of file TYApi.h.

# 5.1.4.8 TY\_TRIGGER\_MODE\_LIST

```
enum TY_TRIGGER_MODE_LIST : uint32_t
```

#### See also

refer to sample SimpleView\_TriggerMode for detail usage

### Enumerator

TY_TRIGGER_MODE_OFF	not trigger mode, continuous mode
TY_TRIGGER_MODE_SLAVE	slave mode, receive soft/hardware triggers
TY_TRIGGER_MODE_M_SIG	master mode 1, sending one trigger signal once received a soft/hardware trigger
TY_TRIGGER_MODE_M_PER	master mode 2, periodic sending one trigger signals, 'fps' param should be set
TY_TRIGGER_MODE_SIG_PASS	discard, using TY_TRIGGER_MODE28
TY_TRIGGER_MODE_PER_PASS	discard, using TY_TRIGGER_MODE29
TY_TRIGGER_MODE_PER_PASS2	trigger mode 30,Alternate output depth image/ir image

Definition at line 615 of file TYApi.h.

### 5.1.5 Function Documentation

### 5.1.5.1 TYClearBufferQueue()

Clear the internal buffer queue, so that user can release all the buffer.

### **Parameters**

in <i>hDevi</i>	e Device handle.
-----------------	------------------

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_BUSY	Device is capturing.

# 5.1.5.2 TYCloseDevice()

Close device by device handle.

### **Parameters**

in <i>hDevice</i>	Device handle.
-------------------	----------------

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_IDLE	Device has been closed.

# 5.1.5.3 TYCloseInterface()

Close interface.

#### **Parameters**

in ifaceHandle Interface to be clo
------------------------------------

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Interface not found.

# 5.1.5.4 TYDeinitLib()

Deinit this library.

### Return values

```
TY_STATUS_OK Succeed.
```

### 5.1.5.5 TYDisableComponents()

```
{\tt TY\_CAPI} {\tt TYDisableComponents} (
```

```
TY_DEV_HANDLE hDevice,
TY_COMPONENT_ID componentIDs )
```

### Disable components.

### **Parameters**

in	hDevice	Device handle.
in	componentIDs	Components to be disabled.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Some components specified by componentIDs are invalid.
TY_STATUS_BUSY	Device is capturing.

### See also

```
TY_DEVICE_COMPONENT_LIST
```

### 5.1.5.6 TYEnableComponents()

```
TY_CAPI TYEnableComponents (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentIDs )
```

### Enable components.

#### **Parameters**

in	hDevice	Device handle.
in	componentIDs	Components to be enabled.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Some components specified by componentIDs are invalid.
TY_STATUS_BUSY	Device is capturing.

# 5.1.5.7 TYEnqueueBuffer()

```
TY_CAPI TYEnqueueBuffer (

TY_DEV_HANDLE hDevice,
```

```
void * buffer,
uint32_t bufferSize )
```

### Enqueue a user allocated buffer.

### **Parameters**

in	hDevice	Device handle.
in	buffer	Buffer to be enqueued.
in	bufferSize	Size of the input buffer.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	buffer is NULL.
TY_STATUS_WRONG_SIZE	The input buffer is not large enough.

# 5.1.5.8 TYErrorString()

```
TY_EXTC TY_EXPORT const char *TY_STDC TYErrorString ( {\tt TY\_STATUS}~errorID~)
```

Get error information.

### **Parameters**

in	errorID	Error id.

### Returns

Error string.

### 5.1.5.9 TYFetchFrame()

Fetch one frame.

#### **Parameters**

in	hDevice	Device handle.
out	frame	Frame data to be filled.
in	timeout	Timeout in milliseconds. <0 for infinite.

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### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	frame is NULL.
TY_STATUS_IDLE	Device capturing is not started.
TY_STATUS_WRONG_MODE	Callback has been registered, this function is disabled.
TY_STATUS_TIMEOUT	Timeout.

### 5.1.5.10 TYForceDeviceIP()

Force a ethernet device to use new IP address, useful when device use persistent IP and cannot be found.

#### **Parameters**

in	ifaceHandle	Interface handle.
in	MAC	Device MAC, should be "xx:xx:xx:xx:xx:xx".
in	newIP	New IP.
in	newNetMask	New subnet mask.
in	newGateway	New gateway.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_WRONG_TYPE	Wrong interface type, should be network.
TY_STATUS_NULL_POINTER	MAC or newIP/newNetMask/newGateway is NULL.
TY_STATUS_INVALID_PARAMETER	MAC is not valid.
TY_STATUS_TIMEOUT	No device found.
TY_STATUS_DEVICE_ERROR	Set new IP failed.

# 5.1.5.11 TYGetBool()

```
TY_CAPI TYGetBool (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,
```

```
TY_FEATURE_ID featureID,
bool * value )
```

### Get value of bool feature.

### **Parameters**

in	hDevice	Device handle.	
in	componentID	Component ID.	
in	featureID	Feature ID.	
out	value	Bool value.	

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BOOL.
TY_STATUS_NULL_POINTER	value is NULL.

### 5.1.5.12 TYGetByteArray()

```
TY_CAPI TYGetByteArray (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint8_t * pBuffer,

uint32_t bufferSize )
```

### Read byte array from device.

### Parameters

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pbuffer	byte buffer.
in	bufferSize	Size of buffer.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pbuffer is NULL.

### Return values

TY_STATUS_WRONG_SIZE   bufferSize incorrect.
--

### 5.1.5.13 TYGetByteArrayAttr()

```
TY_CAPI TYGetByteArrayAttr (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_BYTEARRAY_ATTR * pAttr )
```

Write byte array to device.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pAttr	byte array attribute to be filled.

#### **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pbuffer is NULL.

### 5.1.5.14 TYGetByteArraySize()

```
TY_CAPI TYGetByteArraySize (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint32_t * pSize )
```

Get the size of specified byte array zone .

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pSize	size of specified byte array zone.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pSize is NULL.

### 5.1.5.15 TYGetComponentIDs()

Get all components IDs.

#### **Parameters**

in	hDevice	Device handle.
out	componentIDs	All component IDs this device has. (bit flag).

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	componentIDs is NULL.

### See also

```
TY_DEVICE_COMPONENT_LIST
```

### 5.1.5.16 TYGetDeviceFeatureInfo()

Get the all features by comp id.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
out	featureInfo	Output feature info.
in	entryCount	Array size of input parameter "featureInfo".
out	filledEntryCount	Number of filled featureInfo.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	featureInfo or filledEntryCount is NULL.

### 5.1.5.17 TYGetDeviceFeatureNumber()

Get the size of device features .

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
out	pSize	size of all feature cnt.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	pSize is NULL.

### 5.1.5.18 TYGetDeviceInfo()

```
TY_CAPI TYGetDeviceInfo (

TY_DEV_HANDLE hDevice,

TY_DEVICE_BASE_INFO * info )
```

Get base info of the open device.

### **Parameters**

in	hDevice	Device handle.
out	info	Base info out.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	componentIDs is NULL.

### 5.1.5.19 TYGetDeviceInterface()

Get interface handle by device handle.

### **Parameters**

in	hDevice	Device handle.
out	plface	Interface handle.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	plface is NULL.

### 5.1.5.20 TYGetDeviceList()

```
TY_CAPI TYGetDeviceList (

TY_INTERFACE_HANDLE ifaceHandle,

TY_DEVICE_BASE_INFO * deviceInfos,

uint32_t bufferCount,

uint32_t * filledDeviceCount )
```

Get device info list.

#### **Parameters**

in	ifaceHandle	Interface handle.
out	deviceInfos	Device info array to be filled.
in	bufferCount	Array size of deviceInfos.
out	filledDeviceCount	Number of filled TY DEVICE BASE INFO.

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### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	deviceInfos or filledDeviceCount is NULL.

### 5.1.5.21 TYGetDeviceNumber()

Get number of current connected devices.

### **Parameters**

in	ifaceHandle	Interface handle.
out	deviceNumber	Number of connected devices.

### Return values

Succeed.
TYInitLib not called.
Invalid interface handle.
deviceNumber is NULL.

### 5.1.5.22 TYGetEnabledComponents()

Get all enabled components IDs.

### **Parameters**

in	hDevice	Device handle.
out	componentIDs	Enabled component IDs.(bit flag)

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.

### **Return values**

### See also

```
TY_DEVICE_COMPONENT_LIST
```

### 5.1.5.23 TYGetEnum()

Get current value of enum feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Enum value.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_NULL_POINTER	value is NULL.

### 5.1.5.24 TYGetEnumEntryCount()

Get number of enum entries.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	entryCount	Entry count.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_NULL_POINTER	entryCount is NULL.

### 5.1.5.25 TYGetEnumEntryInfo()

```
TY_CAPI TYGetEnumEntryInfo (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_ENUM_ENTRY * entries,

uint32_t entryCount,

uint32_t * filledEntryCount)
```

### Get list of enum entries.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	entries	Output entries.
in	entryCount	Array size of input parameter "entries".
out	filledEntryCount	Number of filled entries.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_NULL_POINTER	entries or filledEntryCount is NULL.

### 5.1.5.26 TYGetFeatureInfo()

#### Get feature info.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	featureInfo	Feature info.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	featureInfo is NULL.

### 5.1.5.27 TYGetFloat()

```
TY_CAPI TYGetFloat (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

float * value )
```

### Get value of float feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Float value.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_FLOAT.
TY_STATUS_NULL_POINTER	value is NULL.

### 5.1.5.28 TYGetFloatRange()

```
TY_CAPI TYGetFloatRange (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_FLOAT_RANGE * floatRange )
```

Get value range of float feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	floatRange	Float range to be filled.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_FLOAT.
TY_STATUS_NULL_POINTER	floatRange is NULL.

### 5.1.5.29 TYGetFrameBufferSize()

Get total buffer size of one frame in current configuration.

### **Parameters**

in	hDevice	Device handle.
out	bufferSize	Buffer size per frame.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	bufferSize is NULL.

### 5.1.5.30 TYGetInt()

### Get value of integer feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Integer value.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_INT.
TY_STATUS_NULL_POINTER	value is NULL.

### 5.1.5.31 TYGetInterfaceList()

### Get interface info list.

### **Parameters**

out	plfaceInfos	Array of interface infos to be filled.
in	bufferCount	Array size of interface infos.
out	filledCount	Number of filled TY_INTERFACE_INFO.

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.

### Return values

TY_STATUS_NULL_POINTER   plfaceInfos or filledCount is NULL.
--

### 5.1.5.32 TYGetInterfaceNumber()

```
TY_CAPI TYGetInterfaceNumber ( \mbox{uint32\_t} \ * \ pNumIfaces \ )
```

Get number of current interfaces.

#### **Parameters**

out <i>pNumlfaces</i> Number o	f interfaces.
--------------------------------	---------------

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_NULL_POINTER	deviceNumber is NULL.

### 5.1.5.33 TYGetIntRange()

Get value range of integer feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	intRange	Integer range to be filled.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.

### **Return values**

TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_INT.
TY_STATUS_NULL_POINTER	intRange is NULL.

### 5.1.5.34 TYGetString()

### Get value of string feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID Component ID.	
in	featureID	Feature ID.
out	buffer	String buffer.
in	bufferSize	Size of buffer.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRING.
TY_STATUS_NULL_POINTER	buffer is NULL.

### See also

TYGetStringLength

### 5.1.5.35 TYGetStringLength()

```
TY_CAPI TYGetStringLength (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint32_t * size )
```

Get internal buffer size of string feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	size	String length including '\0'.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRING.
TY_STATUS_NULL_POINTER	size is NULL.

### See also

**TYGetString** 

### 5.1.5.36 TYGetStruct()

```
TY_CAPI TYGetStruct (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

void * pStruct,

uint32_t structSize )
```

### Get value of struct.

### Parameters

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pStruct	Pointer of struct.
in	structSize	Size of input buffer pStruct

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRUCT.
TY_STATUS_NULL_POINTER	pStruct is NULL.

### Return values

TY_STATUS_WRONG_SIZE	structSize incorrect.
----------------------	-----------------------

### 5.1.5.37 TYHasDevice()

Check whether the interface has the specified device.

#### **Parameters**

in	ifaceHandle	Interface handle.
in	deviceID	Device ID string, can be get from TY_DEVICE_BASE_INFO.
out	value	True if the device exists.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	deviceID or value is NULL.

### 5.1.5.38 TYHasFeature()

```
TY_CAPI TYHasFeature (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

bool * value )
```

Check whether a component has a specific feature.

### **Parameters**

	in	hDevice	Device handle.	
	in	componentID	Component ID.	
	in	featureID	Feature ID.	
ĺ	out	value	Whether has feature.	

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	value is NULL.

### 5.1.5.39 TYHasInterface()

Check if has interface.

#### **Parameters**

in	ifaceID	Interface ID string, can be get from TY_INTERFACE_INFO.	
out value True if the interface exists.			

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_NULL_POINTER	ifaceID or outHandle is NULL.

### See also

TYGetInterfaceList

### 5.1.5.40 TYLibVersion()

Get current library version.

#### **Parameters**

out	version	Version infomation to be filled.

TY_STATUS_OK	Succeed.

### Return values

|--|

### 5.1.5.41 TYOpenDevice()

### Open device by device ID.

#### **Parameters**

in	ifaceHandle	Interface handle.	
in	deviceID Device ID string, can be get from TY_DEVICE_BASE_INFO.		
out	out deviceHandle Handle of opened device. Valid only if TY_STATUS_OK or TY_FW_ERRORCOL		
	returned.		
out	outFwErrorcode	Firmware errorcode. Valid only if TY_FW_ERRORCODE returned.	

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	deviceID or deviceHandle is NULL.
TY_STATUS_INVALID_PARAMETER	Device not found.
TY_STATUS_BUSY	Device has been opened.
TY_STATUS_DEVICE_ERROR	Open device failed.

### 5.1.5.42 TYOpenDeviceWithIP()

Open device by device IP, useful when a device is not listed.

### Parameters

in	ifaceHandle	Interface handle.
in <i>IP</i>		Device IP.
out	deviceHandle	Handle of opened device.

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### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	IP or deviceHandle is NULL.
TY_STATUS_INVALID_PARAMETER	Device not found.
TY_STATUS_BUSY	Device has been opened, may occupied somewhere else.
TY_STATUS_DEVICE_ERROR	Open device failed.

### 5.1.5.43 TYOpenInterface()

### Open specified interface.

### **Parameters**

in	ifaceID	Interface ID string, can be get from TY_INTERFACE_INFO.	
out	outHandle	Handle of opened interface.	

#### Return values

	TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED		TYInitLib not called.
Ī	TY_STATUS_NULL_POINTER	ifaceID or outHandle is NULL.
Ī	TY_STATUS_INVALID_INTERFACE	Interface not found.

### See also

TYGetInterfaceList

### 5.1.5.44 TYRegisterEventCallback()

Register device status callback. Register NULL to clean callback.

#### **Parameters**

in	hDevice	Device handle.
in	callback	Callback function.
in	userdata	User private data.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_BUSY	Device is capturing.

### 5.1.5.45 TYRegisterImuCallback()

```
TY_CAPI TYRegisterImuCallback (

TY_DEV_HANDLE hDevice,

TY_IMU_CALLBACK callback,

void * userdata )
```

Register imu callback. Register NULL to clean callback.

#### **Parameters**

in	hDevice	Device handle.
in	callback	Callback function.
in	userdata	User private data.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_BUSY	Device is capturing.

### 5.1.5.46 TYSendSoftTrigger()

Send a software trigger to capture a frame when device works in trigger mode.

### **Parameters**

in	hDevice	Device handle.
----	---------	----------------

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_FEATURE	Not support soft trigger.
TY_STATUS_IDLE	Device has not started capture.
TY_STATUS_WRONG_MODE	Not in trigger mode.

### 5.1.5.47 TYSetBool()

```
TY_CAPI TYSetBool (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

bool value )
```

Set value of bool feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Bool value.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BOOL.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.48 TYSetByteArray()

```
TY_CAPI TYSetByteArray (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

const uint8_t * pBuffer,

uint32_t bufferSize )
```

Write byte array to device.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pbuffer	byte buffer.
in	bufferSize	Size of buffer.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pbuffer is NULL.
TY_STATUS_WRONG_SIZE	bufferSize incorrect.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.49 TYSetEnum()

```
TY_CAPI TYSetEnum (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint32_t value )
```

### Set value of enum feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Enum value.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_INVALID_PARAMETER	value is invalid.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.50 TYSetFloat()

```
TY_CAPI TYSetFloat (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

float value )
```

Set value of float feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Float value.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_FLOAT.
TY_STATUS_OUT_OF_RANGE	value is out of range.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.51 TYSetInt()

```
TY_CAPI TYSetInt (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

int32_t value)
```

Set value of integer feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Integer value.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_INT.
TY_STATUS_OUT_OF_RANGE	value is out of range.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.52 TYSetString()

```
TY_CAPI TYSetString (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

const char * buffer )
```

### Set value of string feature.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	buffer	String buffer.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRING.
TY_STATUS_NULL_POINTER	buffer is NULL.
TY_STATUS_OUT_OF_RANGE	Input string is too long.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.53 TYSetStruct()

```
TY_CAPI TYSetStruct (

TY_DEV_HANDLE hDevice,
```

```
TY_COMPONENT_ID componentID,
TY_FEATURE_ID featureID,
void * pStruct,
uint32_t structSize )
```

### Set value of struct.

### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	pStruct	Pointer of struct.
in	structSize	Size of struct.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRUCT.
TY_STATUS_NULL_POINTER	pStruct is NULL.
TY_STATUS_WRONG_SIZE	structSize incorrect.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

### 5.1.5.54 TYStartCapture()

### Start capture.

### **Parameters**

in	hDevice	Device handle.
----	---------	----------------

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	No components enabled.
TY_STATUS_BUSY	Device has been started.
TY_STATUS_DEVICE_ERROR	Start capture failed.

### 5.1.5.55 TYStopCapture()

Stop capture.

### **Parameters**

in	hDevice	Device handle.
----	---------	----------------

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_IDLE	Device is not capturing.
TY_STATUS_DEVICE_ERROR	Stop capture failed.

### 5.1.5.56 TYUpdateAllDeviceList()

```
TY_CAPI TYUpdateAllDeviceList ( )
```

Update current connected devices.

#### Return values

TY_STATUS_OK	Succeed.
TY STATUS NOT INITED	TYInitLib not called.

### 5.1.5.57 TYUpdateDeviceList()

Update current connected devices.

### **Parameters**

in <i>ifaceHand</i>	le Interface handle.
---------------------	----------------------

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.

### Return values

TY STATUS INVALID INTERFACE	Invalid interface handle.
-----------------------------	---------------------------

### 5.1.5.58 TYUpdateInterfaceList()

TY\_CAPI TYUpdateInterfaceList ( )

Update current interfaces. call before TYGetInterfaceList.

#### Return values

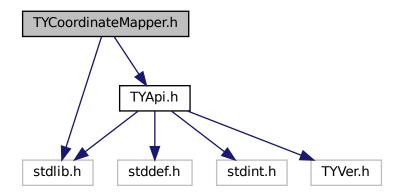
TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.

# 5.2 TYCoordinateMapper.h File Reference

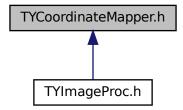
Coordinate Conversion API.

```
#include <stdlib.h>
#include "TYApi.h"
```

Include dependency graph for TYCoordinateMapper.h:



This graph shows which files directly or indirectly include this file:



#### Classes

- struct TY PIXEL DESC
- struct TY PIXEL COLOR DESC

### **Macros**

• #define TYMAP\_CHECKRET(f, bufToFree)

#### **Typedefs**

- typedef struct TY PIXEL DESC TY PIXEL DESC
- typedef struct TY\_PIXEL\_COLOR\_DESC TY\_PIXEL\_COLOR\_DESC

### **Functions**

TY\_CAPI TYInvertExtrinsic (const TY\_CAMERA\_EXTRINSIC \*orgExtrinsic, TY\_CAMERA\_EXTRINSIC \*invExtrinsic)

Calculate 4x4 extrinsic matrix's inverse matrix.

Map pixels on depth image to 3D points.

TY\_CAPI TYMapPoint3dToDepth (const TY\_CAMERA\_CALIB\_INFO \*dst\_calib, const TY\_VECT\_3F \*point3d, uint32\_t count, uint32\_t depthW, uint32\_t depthH, TY\_PIXEL\_DESC \*depth, float f\_scale\_
 unit=1.0f)

Map 3D points to pixels on depth image. Reverse operation of TYMapDepthToPoint3d.

TY\_CAPI TYMapDepthImageToPoint3d (const TY\_CAMERA\_CALIB\_INFO \*src\_calib, int32\_t imageW, int32\_t imageH, const uint16\_t \*depth, TY\_VECT\_3F \*point3d, float f\_scale\_unit=1.0f)

Map depth image to 3D points. 0 depth pixels maps to (NAN, NAN, NAN).

- TY\_CAPI TYDepthImageFillEmptyRegion (uint16\_t \*depth, uint32\_t depthW, uint32\_t depthH) Fill depth image empty region.
- TY\_CAPI TYMapPoint3dToDepthImage (const TY\_CAMERA\_CALIB\_INFO \*dst\_calib, const TY\_VECT\_3F \*point3d, uint32\_t count, uint32\_t depthW, uint32\_t depthH, uint16\_t \*depth, float f\_target\_scale=1.0f)
- Map 3D points to depth image. (NAN, NAN, NAN) will be skipped.
   TY\_CAPI TYMapPoint3dToPoint3d (const TY\_CAMERA\_EXTRINSIC \*extrinsic, const TY\_VECT\_3F \*point3dFrom, int32\_t count, TY\_VECT\_3F \*point3dTo)

Map 3D points to another coordinate.

• void TYPixelsOverlapRemove (TY\_PIXEL\_DESC \*lut, uint32\_t count, uint32\_t imageW, uint32\_t imageH)

### 5.2.1 Detailed Description

Coordinate Conversion API.

Note

Considering performance, we leave the responsibility of parameters check to users.

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### 5.2.2 Macro Definition Documentation

### 5.2.2.1 TYMAP\_CHECKRET

Value:

Definition at line 274 of file TYCoordinateMapper.h.

### 5.2.3 Function Documentation

### 5.2.3.1 TYDepthImageFillEmptyRegion()

Fill depth image empty region.

### **Parameters**

in	depth	Depth image pixels.
in	depthW	Width of current depth image.
in	depthH	Height of current depth image.

### 5.2.3.2 TYInvertExtrinsic()

Calculate 4x4 extrinsic matrix's inverse matrix.

#### **Parameters**

in	orgExtrinsic	Input extrinsic matrix.
out	invExtrinsic	Inverse matrix.

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_ERROR	Calculation failed.

### 5.2.3.3 TYMapDepthImageToPoint3d()

Map depth image to 3D points. 0 depth pixels maps to (NAN, NAN, NAN).

### **Parameters**

in	src_calib	Depth image's calibration data.
in	depthW	Width of depth image.
in	depthH	Height of depth image.
in	depth	Depth image.
out	point3d	Output point3D image.

#### Return values

```
TY_STATUS_OK Succeed.
```

#### 5.2.3.4 TYMapDepthToPoint3d()

Map pixels on depth image to 3D points.

#### **Parameters**

in	src_calib	Depth image's calibration data.
in	depthW	Width of depth image.
in	depthH	Height of depth image.
in	depthPixels	Pixels on depth image.
in	count	Number of depth pixels.
out	point3d	Output point3D.

#### **Return values**

```
TY_STATUS_OK Succeed.
```

#### 5.2.3.5 TYMapPoint3dToDepth()

Map 3D points to pixels on depth image. Reverse operation of TYMapDepthToPoint3d.

### **Parameters**

in	dst_calib	Target depth image's calibration data.

#### **Parameters**

in	point3d	Input 3D points.
in	count	Number of points.
in	depthW	Width of target depth image.
in	depthH	Height of target depth image.
out	depth	Output depth pixels.

#### **Return values**

TY_STATUS_OK
--------------

### 5.2.3.6 TYMapPoint3dToDepthImage()

Map 3D points to depth image. (NAN, NAN, NAN) will be skipped.

### **Parameters**

in	dst_calib	Target depth image's calibration data.
in	point3d	Input 3D points.
in	count	Number of points.
in	depthW	Width of target depth image.
in	depthH	Height of target depth image.
in,out	depth	Depth image buffer.

### Return values

```
TY_STATUS_OK Succeed.
```

### 5.2.3.7 TYMapPoint3dToPoint3d()

```
int32_t count,
TY_VECT_3F * point3dTo )
```

Map 3D points to another coordinate.

### **Parameters**

in	extrinsic	Extrinsic matrix.
in	point3dFrom	Source 3D points.
in	count	Number of source 3D points.
out	point3dTo	Target 3D points.

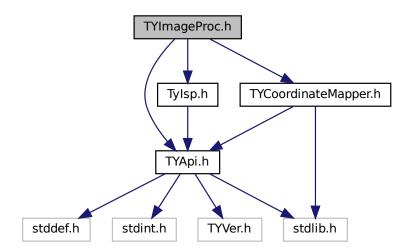
#### Return values

TY_STATUS_OK	Succeed.
--------------	----------

# 5.3 TYImageProc.h File Reference

```
#include "TYApi.h"
#include "TYCoordinateMapper.h"
#include "TyIsp.h"
```

Include dependency graph for TYImageProc.h:



### Classes

- struct DepthSpeckleFilterParameters default parameter value definition
- struct DepthEnhenceParameters default parameter value definition

### **Macros**

- #define DepthSpeckleFilterParameters\_Initializer {150, 64}
- #define DepthEnhenceParameters\_Initializer {10, 20, 10, 0.1f}

#### **Functions**

• TY CAPI TYImageProcesAcceEnable (bool en)

Image processing acceleration switch.

TY\_CAPI TYUndistortImage (const TY\_CAMERA\_CALIB\_INFO \*srcCalibInfo, const TY\_IMAGE\_DATA \*srcImage, const TY\_CAMERA\_INTRINSIC \*cameraNewIntrinsic, TY\_IMAGE\_DATA \*dstImage)

Do image undistortion, only support  $TY\_PIXEL\_FORMAT\_MONO$ ,  $TY\_PIXEL\_FORMAT\_RGB$ ,  $TY\_PIXEL\_FORM \leftarrow AT BGR$ .

TY\_CAPI TYDepthSpeckleFilter (TY\_IMAGE\_DATA \*depthImage, const DepthSpeckleFilterParameters \*param)

Remove speckles on depth image.

• TY\_CAPI TYDepthEnhenceFilter (const TY\_IMAGE\_DATA \*depthImages, int imageNum, TY\_IMAGE\_DATA \*guide, TY\_IMAGE\_DATA \*output, const DepthEnhenceParameters \*param)

Remove speckles on depth image.

### 5.3.1 Detailed Description

Image post-process API

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### 5.3.2 Function Documentation

### 5.3.2.1 TYDepthEnhenceFilter()

Remove speckles on depth image.

#### **Parameters**

in	depthlmage	Pointer to depth image array.
in	imageNum	Depth image array size.
in,out	guide	Guide image.
out	output	Output depth image.
in	param	Algorithm parameters.

Generated by Doxygen

### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NULL_POINTER	Any depthImage, param, output or output->buffer is NULL.
TY_STATUS_INVALID_PARAMETER	imageNum >= 11 or imageNum <= 0, or any image invalid
TY_STATUS_OUT_OF_MEMORY	Output image not suitable.

### 5.3.2.2 TYDepthSpeckleFilter()

Remove speckles on depth image.

### **Parameters**

in,out	depthImage	Depth image to be processed.
in	param	Algorithm parameters.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NULL_POINTER	Any depth, param or depth->buffer is NULL.
TY_STATUS_INVALID_PARAMETER	param->max_speckle_size <= 0 or param->max_speckle_diff <= 0

### 5.3.2.3 TYImageProcesAcceEnable()

```
TY_CAPI TYImageProcesAcceEnable ( bool en )
```

Image processing acceleration switch.

#### **Parameters**

```
in en Enable image process acceleration switch
```

### 5.3.2.4 TYUndistortImage()

```
const TY_IMAGE_DATA * srcImage,
const TY_CAMERA_INTRINSIC * cameraNewIntrinsic,
TY_IMAGE_DATA * dstImage )
```

Do image undistortion, only support TY\_PIXEL\_FORMAT\_MONO , TY\_PIXEL\_FORMAT\_RGB, TY\_PIXEL\_FORMAT\_BGR.

#### **Parameters**

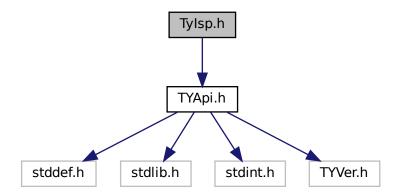
in	srcCalibInfo	Image calibration data.
in	srcImage	Source image.
in	cameraNewIntrinsic	Expected new image intrinsic, will use srcCalibInfo for new image intrinsic if set to NULL.
		to NOLL.
out	dstImage	Output image.

### Return values

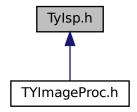
TY_STATUS_OK	Succeed.
TY_STATUS_NULL_POINTER	Any srcCalibInfo, srcImage, dstImage, srcImage->buffer, dstImage->buffer is NULL.
TY_STATUS_INVALID_PARAMETER	Invalid srcImage->width, srcImage->height, dstImage->width, dstImage->height or unsupported pixel format.

# 5.4 Tylsp.h File Reference

```
#include "TYApi.h"
Include dependency graph for Tylsp.h:
```



This graph shows which files directly or indirectly include this file:



#### **Classes**

struct TY\_ISP\_FEATURE\_INFO

#### **Macros**

• #define TYISP\_CAPI TY\_CAPI

#### **Typedefs**

typedef void \* TY\_ISP\_HANDLE

### **Enumerations**

• enum TY ISP FEATURE ID {

**TY\_ISP\_FEATURE\_CAM\_MODEL** = 0x000000, TY\_ISP\_FEATURE\_CAM\_DEV\_HANDLE = 0x000001, TY\_ISP\_FEATURE\_CAM\_DEV\_COMPONENT = 0x000002, TY\_ISP\_FEATURE\_IMAGE\_SIZE = 0x000100,

TY\_ISP\_FEATURE\_WHITEBALANCE\_GAIN = 0x000200, TY\_ISP\_FEATURE\_ENABLE\_AUTO\_WHIT  $\leftarrow$  EBALANCE = 0x000300, TY\_ISP\_FEATURE\_SHADING = 0x000400, TY\_ISP\_FEATURE\_SHADING\_C  $\leftarrow$  ENTER = 0x000500,

TY\_ISP\_FEATURE\_BLACK\_LEVEL = 0x000600, TY\_ISP\_FEATURE\_BLACK\_LEVEL\_COLUMN = 0x000610, TY\_ISP\_FEATURE\_BLACK\_LEVEL\_GAIN = 0x000700, TY\_ISP\_FEATURE\_BLACK\_LEV $\leftarrow$  EL GAIN COLUMN = 0x000710,

TY\_ISP\_FEATURE\_CCM = 0x000C00, TY\_ISP\_FEATURE\_CCM\_ENABLE = 0x000C10, TY\_ISP\_FEAT ← URE\_BRIGHT = 0x000D00, TY\_ISP\_FEATURE\_CONTRAST = 0x000E00,

TY\_ISP\_FEATURE\_AUTOBRIGHT = 0x000F00, TY\_ISP\_FEATURE\_INPUT\_RESAMPLE\_SCALE = 0x001000, TY\_ISP\_FEATURE\_ENABLE\_AUTO\_EXPOSURE\_GAIN = 0x001100, TY\_ISP\_FEATUR ← E\_AUTO\_EXPOSURE\_RANGE = 0x001200,

TY\_ISP\_FEATURE\_AUTO\_GAIN\_RANGE = 0x001300, TY\_ISP\_FEATURE\_AUTO\_EXPOSURE\_UPDA

TE INTERVAL = 0x001400, TY ISP FEATURE DEBUG LOG = 0xff000000 }

- enum TY\_ISP\_BAYER\_PATTERN {
   TY\_ISP\_BAYER\_GB = 0, TY\_ISP\_BAYER\_BG = 1, TY\_ISP\_BAYER\_RG = 2, TY\_ISP\_BAYER\_GR = 3,
   TY\_ISP\_BAYER\_AUTO = 0xff }
- enum TY\_DEMOSAIC\_METHOD { TY\_DEMOSAIC\_METHOD\_SIMPLE = 0, TY\_DEMOSAIC\_METHOD ←
   \_BILINEAR = 1, TY\_DEMOSAIC\_METHOD\_HQLINEAR = 2, TY\_DEMOSAIC\_METHOD\_EDGESENSE =
   3 }

#### **Functions**

- TYISP\_CAPI TYISPCreate (TY\_ISP\_HANDLE \*handle)
- TYISP\_CAPI **TYISPRelease** (TY\_ISP\_HANDLE \*handle)
- TYISP\_CAPI TYISPLoadConfig (TY\_ISP\_HANDLE handle, const uint8\_t \*config, uint32\_t config\_size)
- TYISP\_CAPI TYISPUpdateDevice (TY\_ISP\_HANDLE handle)
  - called by main thread to update & control device status for ISP
- TYISP\_CAPI **TYISPSetFeature** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_ID feature\_id, const uint8 ← \_\_t \*data, int32\_t size)
- TYISP\_CAPI **TYISPGetFeature** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_ID feature\_id, uint8\_← t \*data\_buff, int32\_t buff\_size)
- TYISP\_CAPI **TYISPGetFeatureSize** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_ID feature\_id, int32\_t \*size)
- TYISP CAPI TYISPHasFeature (TY ISP HANDLE handle, TY ISP FEATURE ID feature id)
- TYISP\_CAPI **TYISPGetFeatureInfoList** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_INFO \*info\_buffer, int buffer size)
- TYISP\_CAPI TYISPGetFeatureInfoListSize (TY\_ISP\_HANDLE handle, int32\_t \*buffer\_size)

convert bayer raw image to rgb image, output buffer is allocated by invoker

### 5.4.1 Detailed Description

this file Include interface declare for raw color image (bayer format) process functions

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### 5.4.2 Enumeration Type Documentation

### 5.4.2.1 TY\_ISP\_FEATURE\_ID

enum TY\_ISP\_FEATURE\_ID

#### **Enumerator**

TY_ISP_FEATURE_CAM_DEV_HANDLE	device handle for device control
TY_ISP_FEATURE_CAM_DEV_COMPONENT	the component to control
TY_ISP_FEATURE_IMAGE_SIZE	image size width&height
TY_ISP_FEATURE_BLACK_LEVEL	global black level
TY_ISP_FEATURE_BLACK_LEVEL_COLUMN	to set different black level for each image column
TY_ISP_FEATURE_BLACK_LEVEL_GAIN	global pixel gain
TY_ISP_FEATURE_BLACK_LEVEL_GAIN_COLUMN	to set different gain for each image column
TY_ISP_FEATURE_CCM_ENABLE	ENABLE CCM.
TY_ISP_FEATURE_AUTO_EXPOSURE_RANGE	exposure range ,default no limit
TY_ISP_FEATURE_AUTO_GAIN_RANGE	gain range ,default no limit
TY_ISP_FEATURE_AUTO_EXPOSURE_UPDATE_INT↔	update device exposure interval, default 5 frame
ERVAL	
TY_ISP_FEATURE_DEBUG_LOG	display detail log information

Definition at line 17 of file Tylsp.h.

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