TYCamport3

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## **Chapter 1**

# Main Page

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## 1.1 Note

Depth camera, called "device", consists of several components. Each component is a hardware module or virtual module, such as RGB sensor, depth sensor. Each component has its own features, such as image width, exposure time, etc..

NOTE: The component TY\_COMPONENT\_DEVICE is a virtual component that contains all features related to the whole device, such as trigger mode, device IP.

Each frame consists of several images. Normally, all the images have identical timestamp, means they are captured at the same time.

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# Chapter 2

# **Class Index**

## 2.1 Class List

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## 3.1 File List

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## **Chapter 4**

## **Class Documentation**

## 4.1 DepthEnhenceParameters Struct Reference

default parameter value definition

```
#include <TYImageProc.h>
```

#### **Public Attributes**

- float sigma\_s
  - filter param on space
- · float sigma\_r
  - filter param on range
- int outlier\_win\_sz
  - outlier filter windows ize
- float outlier\_rate

## 4.1.1 Detailed Description

default parameter value definition

Definition at line 54 of file TYImageProc.h.

The documentation for this struct was generated from the following file:

• TYImageProc.h

## 4.2 DepthSpeckleFilterParameters Struct Reference

default parameter value definition

```
#include <TYImageProc.h>
```

## **Public Attributes**

- int max\_speckle\_size
- int max\_speckle\_diff

## 4.2.1 Detailed Description

default parameter value definition

Definition at line 34 of file TYImageProc.h.

The documentation for this struct was generated from the following file:

• TYImageProc.h

## 4.3 TY\_ACC\_BIAS Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float **data** [3]

## 4.3.1 Detailed Description

a 3x3 matrix

•	•	
BIASx	BIASy	BIASz

Definition at line 884 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.4 TY\_ACC\_MISALIGNMENT Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

float data [3 \*3]

## 4.4.1 Detailed Description

a 3x3 matrix |.|.|.|

•		•
1	-GAMAyz	GAMAzy
GAMAxz	1	-GAMAzx
-GAMAxy	GAMAyx	1

Definition at line 896 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.5 TY\_ACC\_SCALE Struct Reference

#include <TYApi.h>

#### **Public Attributes**

• float data [3 \*3]

## 4.5.1 Detailed Description

a 3x3 matrix

•	•	•
SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

Definition at line 907 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.6 TY\_AEC\_ROI\_PARAM Struct Reference

## **Public Attributes**

- uint32\_t x
- uint32\_t y
- uint32\_t w
- uint32\_t h

## 4.6.1 Detailed Description

Definition at line 850 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.7 TY\_BYTEARRAY\_ATTR Struct Reference

byte array data structure

```
#include <TYApi.h>
```

#### **Public Attributes**

- int32\_t size

  Bytes array size in bytes.
- int32\_t unit\_size
- int32\_t valid\_size

## 4.7.1 Detailed Description

byte array data structure

See also

**TYGetByteArray** 

Definition at line 718 of file TYApi.h.

#### 4.7.2 Member Data Documentation

#### 4.7.2.1 unit\_size

```
int32_t TY_BYTEARRAY_ATTR::unit_size
```

unit size in bytes for special parse

Definition at line 721 of file TYApi.h.

#### 4.7.2.2 valid\_size

```
int32_t TY_BYTEARRAY_ATTR::valid_size
```

valid size in bytes in case has reserved member, Must be multiple of unit\_size, mem\_length = valid\_size/unit\_size

Definition at line 724 of file TYApi.h.

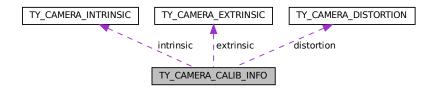
The documentation for this struct was generated from the following file:

• TYApi.h

## 4.8 TY\_CAMERA\_CALIB\_INFO Struct Reference

#include <TYApi.h>

Collaboration diagram for TY\_CAMERA\_CALIB\_INFO:



#### **Public Attributes**

- int32 t intrinsicWidth
- int32\_t intrinsicHeight
- TY\_CAMERA\_INTRINSIC intrinsic
- TY\_CAMERA\_EXTRINSIC extrinsic
- TY\_CAMERA\_DISTORTION distortion

#### 4.8.1 Detailed Description

camera 's cailbration data

See also

**TYGetStruct** 

Definition at line 793 of file TYApi.h.

The documentation for this struct was generated from the following file:

TYApi.h

## 4.9 TY\_CAMERA\_DISTORTION Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [12]

Definition is compatible with opencv3.0+:k1,k2,p1,p2,k3,k4,k5,k6,s1,s2,s3,s4.

## 4.9.1 Detailed Description

camera distortion parameters

See also

#### TYGetStruct Usage:

Definition at line 785 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.10 TY\_CAMERA\_EXTRINSIC Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [4 \*4]

## 4.10.1 Detailed Description

a 4x4 matrix

•			-
r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

#### See also

#### TYGetStruct Usage:

```
TY_CAMERA_EXTRINSIC extrinsic;
TYGetStruct(hDevice, some_compoent, TY_STRUCT_EXTRINSIC, &extrinsic, sizeof(extrinsic));
```

Definition at line 773 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.11 TY\_CAMERA\_INTRINSIC Struct Reference

```
#include <TYApi.h>
```

#### **Public Attributes**

• float data [3 \*3]

## 4.11.1 Detailed Description

a 3x3 matrix

fx	0	сх
0	fy	су
0	0	1

#### See also

## TYGetStruct Usage:

Definition at line 755 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.12 TY\_CAMERA\_STATISTICS Struct Reference

#### **Public Attributes**

- · uint64\_t packetReceived
- uint64\_t packetLost
- · uint64 t imageOutputed
- uint64\_t imageDropped
- uint8\_t rsvd [1024]

## 4.12.1 Detailed Description

Definition at line 858 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.13 TY\_CAMERA\_TO\_IMU Struct Reference

#include <TYApi.h>

## **Public Attributes**

• float data [4 \*4]

## 4.13.1 Detailed Description

a 4x4 matrix

•		•	
r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

Definition at line 950 of file TYApi.h.

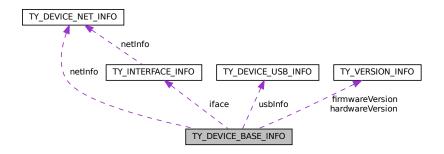
The documentation for this struct was generated from the following file:

• TYApi.h

## 4.14 TY\_DEVICE\_BASE\_INFO Struct Reference

#include <TYApi.h>

Collaboration diagram for TY\_DEVICE\_BASE\_INFO:



#### **Public Attributes**

```
• TY_INTERFACE_INFO iface
```

• char id [32]

device serial number

- char vendorName [32]
- char userDefinedName [32]
- char modelName [32]

device model name

TY\_VERSION\_INFO hardwareVersion

deprecated

• TY\_VERSION\_INFO firmwareVersion

deprecated

```
union {
    TY_DEVICE_NET_INFO netInfo
    TY_DEVICE_USB_INFO usbInfo
};
```

- · char buildHash [256]
- char configVersion [256]
- · char reserved [256]

#### 4.14.1 Detailed Description

See also

**TYGetDeviceList** 

Definition at line 666 of file TYApi.h.

The documentation for this struct was generated from the following file:

TYApi.h

## 4.15 TY\_DEVICE\_NET\_INFO Struct Reference

device network information

#include <TYApi.h>

#### **Public Attributes**

- char mac [32]
- char ip [32]
- · char netmask [32]
- char gateway [32]
- char broadcast [32]
- char reserved [96]

## 4.15.1 Detailed Description

device network information

Definition at line 638 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.16 TY\_DEVICE\_USB\_INFO Struct Reference

#### **Public Attributes**

- int bus
- int addr
- char reserved [248]

## 4.16.1 Detailed Description

Definition at line 648 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.17 TY\_DI\_WORKMODE Struct Reference

#### **Public Attributes**

- TY\_E\_DI\_MODE mode
- TY\_E\_DI\_INT\_ACTION int\_act
- uint32\_t mode\_supported
- uint32\_t int\_act\_supported
- uint32\_t status
- uint32\_t reserved [3]

## 4.17.1 Detailed Description

Definition at line 1025 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.18 TY\_DO\_WORKMODE Struct Reference

## **Public Attributes**

- TY\_E\_DO\_MODE mode
- TY E VOLT T volt
- uint32\_t freq
- uint32\_t duty
- uint32\_t mode\_supported
- uint32\_t volt\_supported
- uint32\_t reserved [3]

#### 4.18.1 Detailed Description

Definition at line 1002 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.19 TY\_ENUM\_ENTRY Struct Reference

#include <TYApi.h>

#### **Public Attributes**

- char description [64]
- · uint32 t value
- uint32\_t reserved [3]

#### 4.19.1 Detailed Description

enum feature entry information

See also

#### **TYGetEnumEntryInfo**

Definition at line 729 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.20 TY\_EVENT\_INFO Struct Reference

#### **Public Attributes**

- · TY EVENT eventId
- · char message [124]

#### 4.20.1 Detailed Description

Definition at line 996 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.21 TY\_FEATURE\_INFO Struct Reference

#### **Public Attributes**

bool isValid

true if feature exists, false otherwise

• TY\_ACCESS\_MODE accessMode

feature access privilege

· bool writableAtRun

feature can be written while capturing

- char reserved0 [1]
- TY\_COMPONENT\_ID componentID

owner of this feature

TY\_FEATURE\_ID featureID

feature unique id

• char name [32]

describe string

TY\_COMPONENT\_ID bindComponentID

component ID current feature bind to

TY\_FEATURE\_ID bindFeatureID

feature ID current feature bind to

char reserved [252]

## 4.21.1 Detailed Description

Definition at line 684 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.22 TY\_FLOAT\_RANGE Struct Reference

float range data structure

#include <TYApi.h>

#### **Public Attributes**

- float min
- · float max
- float inc increaing step
- · float reserved [1]

## 4.22.1 Detailed Description

float range data structure

See also

TYGetFloatRange

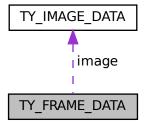
Definition at line 708 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.23 TY\_FRAME\_DATA Struct Reference

Collaboration diagram for TY\_FRAME\_DATA:



## **Public Attributes**

void \* userBuffer

Pointer to user enqueued buffer, user should enqueue this buffer in the end of callback.

· int32\_t bufferSize

Size of userBuffer.

int32\_t validCount

Number of valid data.

• int32\_t reserved [6]

Reserved: reserved[0],laser\_val;.

• TY\_IMAGE\_DATA image [10]

Buffer data, max to 10 images per frame, each buffer data could be an image or something else.

## 4.23.1 Detailed Description

Definition at line 986 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.24 TY\_GYRO\_BIAS Struct Reference

#include <TYApi.h>

#### **Public Attributes**

• float data [3]

## 4.24.1 Detailed Description

a 3x3 matrix

•	•	•
BIASx	BIASy	BIASz

Definition at line 916 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.25 TY\_GYRO\_MISALIGNMENT Struct Reference

#include <TYApi.h>

## **Public Attributes**

• float data [3 \*3]

## 4.25.1 Detailed Description

a 3x3 matrix

1	-ALPHAyz	ALPHAzy
0	1	-ALPHAzx
0	0	1

Definition at line 927 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.26 TY\_GYRO\_SCALE Struct Reference

#include <TYApi.h>

## **Public Attributes**

• float data [3 \*3]

## 4.26.1 Detailed Description

a 3x3 matrix

SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

Definition at line 938 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.27 TY\_IMAGE\_DATA Struct Reference

#### **Public Attributes**

· uint64 t timestamp

Timestamp in microseconds.

int32\_t imageIndex

image index used in trigger mode

· int32\_t status

Status of this buffer.

• int32\_t componentID

Where current data come from.

int32\_t size

Buffer size.

void \* buffer

Pointer to data buffer.

· int32 t width

Image width in pixels.

• int32\_t height

Image height in pixels.

int32\_t pixelFormat

Pixel format, see TY\_PIXEL\_FORMAT\_LIST.

• int32\_t reserved [9]

Reserved.

#### 4.27.1 Detailed Description

Definition at line 971 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.28 TY\_IMU\_DATA Struct Reference

#### **Public Attributes**

- uint64\_t timestamp
- float acc\_x
- float acc\_y
- float acc\_z
- float gyro\_x
- float gyro\_y
- float gyro\_z
- · float temperature
- float reserved [1]

## 4.28.1 Detailed Description

Definition at line 867 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.29 TY\_INT\_RANGE Struct Reference

## **Public Attributes**

- int32\_t min
- int32\_t max
- int32\_t inc

increaing step

• int32\_t reserved [1]

## 4.29.1 Detailed Description

Definition at line 698 of file TYApi.h.

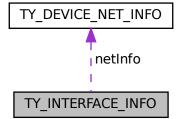
The documentation for this struct was generated from the following file:

• TYApi.h

## 4.30 TY\_INTERFACE\_INFO Struct Reference

#include <TYApi.h>

Collaboration diagram for TY\_INTERFACE\_INFO:



#### **Public Attributes**

- char **name** [32]
- char id [32]
- TY\_INTERFACE\_TYPE type
- char reserved [4]
- TY\_DEVICE\_NET\_INFO netInfo

## 4.30.1 Detailed Description

See also

**TYGetInterfaceList** 

Definition at line 656 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.31 TY\_ISP\_FEATURE\_INFO Struct Reference

#### **Public Attributes**

- TY\_ISP\_FEATURE\_ID id
- int32\_t size
- const char \* name
- const char \* value\_type
- TY\_ACCESS\_MODE mode

## 4.31.1 Detailed Description

Definition at line 63 of file Tylsp.h.

The documentation for this struct was generated from the following file:

• Tylsp.h

## 4.32 TY\_PIXEL\_COLOR\_DESC Struct Reference

#### **Public Attributes**

- int16\_t x
- int16\_t y
- uint8\_t bgr\_ch1
- uint8\_t bgr\_ch2
- uint8\_t bgr\_ch3
- uint8\_t rsvd

## 4.32.1 Detailed Description

Definition at line 20 of file TYCoordinateMapper.h.

The documentation for this struct was generated from the following file:

TYCoordinateMapper.h

## 4.33 TY\_PIXEL\_DESC Struct Reference

## **Public Attributes**

- int16\_t x
- int16\_t y
- uint16\_t depth
- uint16\_t rsvd

## 4.33.1 Detailed Description

Definition at line 12 of file TYCoordinateMapper.h.

The documentation for this struct was generated from the following file:

• TYCoordinateMapper.h

## 4.34 TY\_TOF\_FREQ Struct Reference

#### **Public Attributes**

- uint32\_t freq1
- uint32\_t freq2

## 4.34.1 Detailed Description

Definition at line 955 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

## 4.35 TY\_TRIGGER\_PARAM Struct Reference

#### **Public Attributes**

- TY\_TRIGGER\_MODE mode
- int8\_t **fps**
- int8\_t rsvd

## 4.35.1 Detailed Description

Definition at line 804 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.36 TY\_TRIGGER\_PARAM\_EX Struct Reference

#### **Public Attributes**

```
• TY_TRIGGER_MODE mode
•

union {
    struct {
        int8_t fps
        int8_t duty
        int32_t laser_stream
        int32_t led_stream
        int32_t led_expo
        int32_t led_gain
    }
    struct {
        int32_t ir_gain [2]
    }
    int32_t rsvd [32]
};
```

## 4.36.1 Detailed Description

Definition at line 812 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.37 TY\_TRIGGER\_TIMER\_LIST Struct Reference

#### **Public Attributes**

```
• uint64_t start_time_us
```

- uint32\_t offset\_us\_count
- uint32\_t offset\_us\_list [50]

28 Class Documentation

## 4.37.1 Detailed Description

Definition at line 835 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.38 TY\_TRIGGER\_TIMER\_PERIOD Struct Reference

#### **Public Attributes**

- uint64\_t start\_time\_us
- uint32\_t trigger\_count
- uint32\_t period\_us

## 4.38.1 Detailed Description

Definition at line 843 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.39 TY\_VECT\_3F Struct Reference

## **Public Attributes**

- float x
- float y
- float z

## 4.39.1 Detailed Description

Definition at line 736 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

# 4.40 TY VERSION INFO Struct Reference

#### **Public Attributes**

- int32\_t major
- · int32\_t minor
- int32\_t patch
- int32\_t reserved

#### 4.40.1 Detailed Description

Definition at line 629 of file TYApi.h.

The documentation for this struct was generated from the following file:

• TYApi.h

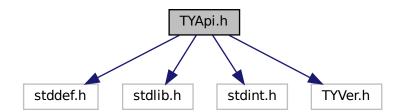
# **Chapter 5**

# **File Documentation**

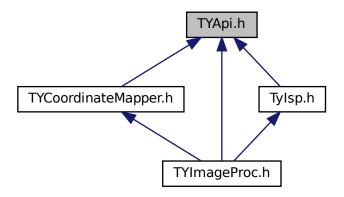
# 5.1 TYApi.h File Reference

TYApi.h includes camera control and data receiving interface, which supports configuration for image resolution, frame rate, exposure time, gain, working mode,etc.

```
#include <stddef.h>
#include <stdlib.h>
#include <stdint.h>
#include "TYVer.h"
Include dependency graph for TYApi.h:
```



This graph shows which files directly or indirectly include this file:



#### **Classes**

- struct TY\_VERSION\_INFO
- struct TY\_DEVICE\_NET\_INFO

device network information

- struct TY\_DEVICE\_USB\_INFO
- struct TY\_INTERFACE\_INFO
- struct TY\_DEVICE\_BASE\_INFO
- struct TY\_FEATURE\_INFO
- struct TY\_INT\_RANGE
- struct TY\_FLOAT\_RANGE

float range data structure

struct TY\_BYTEARRAY\_ATTR

byte array data structure

- struct TY\_ENUM\_ENTRY
- struct TY\_VECT\_3F
- struct TY\_CAMERA\_INTRINSIC
- struct TY\_CAMERA\_EXTRINSIC
- struct TY\_CAMERA\_DISTORTION
- struct TY\_CAMERA\_CALIB\_INFO
- struct TY\_TRIGGER\_PARAM
- struct TY\_TRIGGER\_PARAM\_EX
- struct TY\_TRIGGER\_TIMER\_LIST
- struct TY\_TRIGGER\_TIMER\_PERIOD
- struct TY\_AEC\_ROI\_PARAM
- struct TY\_CAMERA\_STATISTICS
- struct TY\_IMU\_DATA
- struct TY\_ACC\_BIAS
- struct TY\_ACC\_MISALIGNMENT
- struct TY\_ACC\_SCALE
- struct TY\_GYRO\_BIAS
- struct TY\_GYRO\_MISALIGNMENT
- struct TY\_GYRO\_SCALE

- struct TY\_CAMERA\_TO\_IMU
- struct TY\_TOF\_FREQ
- struct TY IMAGE DATA
- struct TY FRAME DATA
- struct TY EVENT INFO
- struct TY\_DO\_WORKMODE
- struct TY\_DI\_WORKMODE

#### **Macros**

- #define \_STDBOOL\_H
- #define \_\_bool\_true\_false\_are\_defined 1
- #define bool Bool
- #define true 1
- #define false 0
- #define TY\_DLLIMPORT \_\_attribute\_\_((visibility("default")))
- #define TY\_DLLEXPORT \_\_attribute\_\_((visibility("default")))
- #define TY\_STDC
- #define TY CDEC
- #define TY\_EXPORT TY\_DLLIMPORT
- · #define TY\_EXTC
- #define TY\_DECLARE\_IMAGE\_MODE0(pix, res) TY\_IMAGE\_MODE\_##pix##\_##res = TY\_PIXEL\_FOR←
  MAT\_##pix | TY\_RESOLUTION\_MODE\_##res
- #define TY\_DECLARE\_IMAGE\_MODE1(pix)
- #define TY\_CAPI TY\_EXTC TY\_EXPORT TY\_STATUS TY\_STDC

#### **Typedefs**

typedef enum TY\_STATUS\_LIST TY\_STATUS\_LIST

API call return status.

- typedef int32\_t TY\_STATUS
- typedef enum TY FW ERRORCODE LIST TY FW ERRORCODE LIST
- typedef uint32\_t TY\_FW\_ERRORCODE
- typedef enum TY\_EVENT\_LIST TY\_ENENT\_LIST
- typedef int32\_t TY\_EVENT
- typedef void \* TY\_INTERFACE\_HANDLE

Interface handle.

typedef void \* TY\_DEV\_HANDLE

Device Handle.

- typedef enum TY\_DEVICE\_COMPONENT\_LIST TY\_DEVICE\_COMPONENT\_LIST
- typedef uint32\_t TY\_COMPONENT\_ID

component unique id

typedef enum TY\_FEATURE\_TYPE\_LIST TY\_FEATURE\_TYPE\_LIST

Feature Format Type definitions.

- typedef uint32\_t TY\_FEATURE\_TYPE
- typedef enum TY\_FEATURE\_ID\_LIST TY\_FEATURE\_ID\_LIST

feature for component definitions

typedef uint32\_t TY\_FEATURE\_ID

feature unique id

- typedef enum TY\_DEPTH\_QUALITY\_LIST TY\_DEPTH\_QUALITY\_LIST
- typedef uint32\_t TY\_DEPTH\_QUALITY

• typedef enum TY\_TRIGGER\_POL\_LIST TY\_TRIGGER\_POL\_LIST

set external trigger signal edge

- typedef uint32\_t TY\_TRIGGER\_POL
- typedef enum TY INTERFACE TYPE LIST TY INTERFACE TYPE LIST
- typedef uint32\_t TY\_INTERFACE\_TYPE
- typedef enum TY\_ACCESS\_MODE\_LIST TY\_ACCESS\_MODE\_LIST
- typedef uint8 t TY\_ACCESS\_MODE
- typedef enum TY STREAM ASYNC MODE LIST TY STREAM ASYNC MODE LIST

stream async mode

- typedef uint8\_t TY\_STREAM\_ASYNC\_MODE
- typedef enum TY\_PIXEL\_BITS\_LIST TY\_PIXEL\_BITS\_LIST
- typedef uint32 t TY\_PIXEL\_BITS
- typedef enum TY PIXEL FORMAT LIST TY PIXEL FORMAT LIST

pixel format definitions

- typedef uint32\_t TY\_PIXEL\_FORMAT
- typedef enum TY\_RESOLUTION\_MODE\_LIST TY\_RESOLUTION\_MODE\_LIST

predefined resolution list

- typedef int32 t TY\_RESOLUTION\_MODE
- typedef enum TY\_IMAGE\_MODE\_LIST TY\_IMAGE\_MODE\_LIST

Predefined Image Mode List image mode controls image resolution & format predefined image modes named like TY\_IMAGE\_MODE\_MONO\_160x120,TY\_IMAGE\_MODE\_RGB\_1280x960.

- typedef uint32 t TY\_IMAGE MODE
- typedef enum TY\_TRIGGER\_MODE\_LIST TY\_TRIGGER\_MODE\_LIST
- typedef int16\_t TY\_TRIGGER\_MODE
- typedef enum TY\_TIME\_SYNC\_TYPE\_LIST TY\_TIME\_SYNC\_TYPE\_LIST

type of time sync

- typedef uint32\_t TY\_TIME\_SYNC\_TYPE
- typedef uint32 t TY E VOLT T
- typedef uint32 t TY E DO MODE
- typedef uint32\_t TY\_E\_DI\_MODE
- typedef uint32\_t TY\_E\_DI\_INT\_ACTION
- typedef struct TY\_VERSION\_INFO TY\_VERSION\_INFO
- typedef struct TY\_DEVICE\_NET\_INFO TY\_DEVICE\_NET\_INFO

device network information

- typedef struct TY\_DEVICE\_USB\_INFO TY\_DEVICE\_USB\_INFO
- typedef struct TY INTERFACE INFO TY INTERFACE INFO
- typedef struct TY\_DEVICE\_BASE\_INFO TY\_DEVICE\_BASE\_INFO
- typedef struct TY FEATURE INFO TY FEATURE INFO
- typedef struct TY\_INT\_RANGE TY\_INT\_RANGE
- typedef struct TY\_FLOAT\_RANGE TY\_FLOAT\_RANGE

float range data structure

• typedef struct TY\_BYTEARRAY\_ATTR TY\_BYTEARRAY\_ATTR

byte array data structure

- typedef struct TY\_ENUM\_ENTRY TY\_ENUM\_ENTRY
- typedef struct TY\_VECT\_3F TY\_VECT\_3F
- typedef struct TY\_CAMERA\_INTRINSIC TY\_CAMERA\_INTRINSIC
- typedef struct TY\_CAMERA\_EXTRINSIC TY\_CAMERA\_EXTRINSIC
- typedef struct TY\_CAMERA\_DISTORTION TY\_CAMERA\_DISTORTION
- typedef struct TY\_CAMERA\_CALIB\_INFO TY\_CAMERA\_CALIB\_INFO
- typedef struct TY TRIGGER PARAM TY\_TRIGGER\_PARAM
- typedef struct TY\_TRIGGER\_PARAM\_EX TY\_TRIGGER\_PARAM\_EX
- typedef struct TY TRIGGER TIMER LIST TY TRIGGER TIMER LIST
- typedef struct TY\_TRIGGER\_TIMER\_PERIOD TY\_TRIGGER\_TIMER\_PERIOD

- typedef struct TY\_AEC\_ROI\_PARAM TY\_AEC\_ROI\_PARAM
- typedef struct TY\_CAMERA\_STATISTICS TY\_CAMERA\_STATISTICS
- typedef struct TY IMU DATA TY\_IMU\_DATA
- typedef struct TY\_ACC\_BIAS TY\_ACC\_BIAS
- typedef struct TY\_ACC\_MISALIGNMENT TY\_ACC\_MISALIGNMENT
- typedef struct TY\_ACC\_SCALE TY\_ACC\_SCALE
- typedef struct TY GYRO BIAS TY GYRO BIAS
- typedef struct TY GYRO MISALIGNMENT TY\_GYRO\_MISALIGNMENT
- typedef struct TY\_GYRO\_SCALE TY\_GYRO\_SCALE
- typedef struct TY CAMERA TO IMU TY CAMERA TO IMU
- typedef struct TY TOF FREQ TY\_TOF\_FREQ
- typedef enum TY\_IMU\_FPS\_LIST TY\_IMU\_FPS\_LIST
- typedef struct TY IMAGE DATA TY IMAGE DATA
- typedef struct TY\_FRAME\_DATA TY\_FRAME\_DATA
- typedef struct TY\_EVENT\_INFO TY\_EVENT\_INFO
- typedef struct TY DO WORKMODE TY DO WORKMODE
- typedef struct TY\_DI\_WORKMODE TY\_DI\_WORKMODE
- typedef void(\* TY\_EVENT\_CALLBACK) (TY\_EVENT\_INFO \*, void \*userdata)
- typedef void(\* TY\_IMU\_CALLBACK) (TY\_IMU\_DATA \*, void \*userdata)

#### **Enumerations**

- enum TY STATUS LIST: int32 t {
  - TY\_STATUS\_OK = 0, TY\_STATUS\_ERROR = -1001, TY\_STATUS\_NOT\_INITED = -1002, TY\_STATUS $\leftarrow$  NOT IMPLEMENTED = -1003,
  - TY\_STATUS\_NOT\_PERMITTED = -1004, TY\_STATUS\_DEVICE\_ERROR = -1005, TY\_STATUS\_INVA
    LID\_PARAMETER = -1006, TY\_STATUS\_INVALID\_HANDLE = -1007,
  - TY\_STATUS\_INVALID\_COMPONENT = -1008, TY\_STATUS\_INVALID\_FEATURE = -1009, TY\_STATU ← S\_WRONG\_TYPE = -1010, TY\_STATUS\_WRONG\_SIZE = -1011,
  - TY\_STATUS\_OUT\_OF\_MEMORY = -1012, TY\_STATUS\_OUT\_OF\_RANGE = -1013, TY\_STATUS\_TIM ← EOUT = -1014, TY\_STATUS\_WRONG\_MODE = -1015,
- TY\_STATUS\_BUSY = -1016, TY\_STATUS\_IDLE = -1017, TY\_STATUS\_NO\_DATA = -1018, TY\_STATU $\leftrightarrow$  S\_NO\_BUFFER = -1019,
- TY\_STATUS\_NULL\_POINTER = -1020, TY\_STATUS\_READONLY\_FEATURE = -1021, TY\_STATUS\_I ← NVALID\_DESCRIPTOR = -1022, TY\_STATUS\_INVALID\_INTERFACE = -1023,
- TY\_STATUS\_FIRMWARE\_ERROR = -1024, TY\_STATUS\_DEV\_EPERM = -1, TY\_STATUS\_DEV\_EIO = -5, TY\_STATUS\_DEV\_ENOMEM = -12,
- TY\_STATUS\_DEV\_EBUSY = -16, TY\_STATUS\_DEV\_EINVAL = -22 }

API call return status.

- enum TY\_FW\_ERRORCODE\_LIST : uint32\_t {
- TY\_FW\_ERRORCODE\_CAM0\_NOT\_DETECTED = 0x000000001, TY\_FW\_ERRORCODE\_CAM1\_NOT\_ $\hookleftarrow$  DETECTED = 0x00000002, TY\_FW\_ERRORCODE\_CAM2\_NOT\_DETECTED = 0x000000004, TY\_FW\_E $\hookleftarrow$  RRORCODE\_POE\_NOT\_INIT = 0x000000008,
- $\label{ty_fw_errorcode_config_not_correct} \textbf{TY\_FW\_ERRORCODE\_XML\_NOT\_} \leftarrow \textbf{FOUND} = 0x00040000, \ \textbf{TY\_FW\_ERRORCODE\_XML\_NOT\_CORRECT} = 0x00080000, \ \textbf{TY\_FW\_ERROR} \leftarrow \textbf{CODE\_XML\_OVERRIDE\_FAILED} = 0x00100000,$
- enum TY\_EVENT\_LIST: int32\_t { TY\_EVENT\_DEVICE\_OFFLINE = -2001, TY\_EVENT\_LICENSE\_ERR ← OR = -2002, TY\_EVENT\_FW\_INIT\_ERROR = -2003 }

```
    enum TY_DEVICE_COMPONENT_LIST: uint32_t {
        TY_COMPONENT_DEVICE = 0x80000000, TY_COMPONENT_DEPTH_CAM = 0x00010000, TY_COM←
        PONENT_IR_CAM_LEFT = 0x00040000, TY_COMPONENT_IR_CAM_RIGHT = 0x00080000,
        TY_COMPONENT_RGB_CAM_LEFT = 0x00100000, TY_COMPONENT_RGB_CAM_RIGHT = 0x00200000,
        TY_COMPONENT_LASER = 0x00400000, TY_COMPONENT_IMU = 0x00800000,
        TY_COMPONENT_BRIGHT_HISTO = 0x01000000, TY_COMPONENT_STORAGE = 0x02000000, TY_COMPONENT_RGB_CAM = TY_COMPONENT_RGB_CAM_LEFT }
    enum TY_FEATURE_TYPE_LIST: uint32_t {
        TY_FEATURE_INT = 0x1000, TY_FEATURE_FLOAT = 0X2000, TY_FEATURE_ENUM = 0x3000, TY_F←
        EATURE_BOOL = 0x4000,
        TY_FEATURE_STRING = 0x5000, TY_FEATURE_BYTEARRAY = 0x6000, TY_FEATURE_STRUCT = 0x7000 }
```

Feature Format Type definitions. enum TY FEATURE ID LIST: uint32 t { TY\_STRUCT\_CAM\_INTRINSIC = 0x0000 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_EXTRINSIC\_TO\_DE ↔ PTH = 0x0001 | TY FEATURE STRUCT, TY STRUCT EXTRINSIC TO IR LEFT = 0x0002 | TY FEAT ↔ URE STRUCT, TY STRUCT CAM DISTORTION = 0x0006 | TY FEATURE STRUCT, TY STRUCT CAM CALIB DATA = 0x0007 | TY FEATURE STRUCT, TY STRUCT CAM RECTIFIED ← INTRI = 0x0008 | TY FEATURE STRUCT, TY BYTEARRAY CUSTOM BLOCK = 0x000A | TY FEAT URE\_BYTEARRAY, TY\_BYTEARRAY\_ISP\_BLOCK = 0x000B | TY FEATURE BYTEARRAY, TY INT PERSISTENT IP = 0x0010 | TY FEATURE INT. TY INT PERSISTENT SUBMASK = 0x0011 | TY\_FEATURE\_INT, TY\_INT\_PERSISTENT\_GATEWAY = 0x0012 | TY\_FEATURE INT, TY\_BOOL GVS P\_RESEND = 0x0013 | TY FEATURE BOOL, TY INT PACKET DELAY = 0x0014 | TY FEATURE INT, TY INT ACCEPTABLE PERCENT = 0x0015 | TY FEATURE INT, TY INT NTP SERVER IP = 0x0016 | TY FEATURE INT, TY INT PACKET SIZE = 0x0017 | TY\_FEATURE\_INT, TY\_INT\_LINK\_CMD\_TIMEOUT = 0x0018 | TY\_FEATURE\_INT, TY\_STRUCT\_CAM\_STATISTICS = 0x00ff TY\_FEATURE\_STRUCT, TY\_INT\_WIDTH\_MAX = 0x0100 | TY\_FEATURE\_INT, TY\_INT\_HEIGHT\_MAX = 0x0101 | TY FEATURE INT, TY\_INT\_OFFSET\_X = 0x0102 | TY\_FEATURE\_INT, TY\_INT\_OFFSET\_Y = 0x0103 | TY\_FEATURE INT, TY INT WIDTH = 0x0104 | TY FEATURE INT, TY INT HEIGHT = 0x0105 | TY FEATURE INT, TY ENUM IMAGE MODE = 0x0109 | TY FEATURE ENUM, TY FLOAT SCALE UNIT = 0x010a | TY ← FEATURE FLOAT, TY ENUM TRIGGER POL = 0x0201 | TY FEATURE ENUM, TY INT FRAME PE↔ R TRIGGER = 0x0202 | TY FEATURE INT, TY\_STRUCT\_TRIGGER\_PARAM = 0x0523 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_TRIGGER\_PARA M EX = 0x0525 | TY FEATURE STRUCT, TY STRUCT TRIGGER TIMER LIST = 0x0526 | TY FEAT↔ URE STRUCT, TY STRUCT TRIGGER TIMER PERIOD = 0x0527 | TY FEATURE STRUCT, TY\_BOOL\_KEEP\_ALIVE\_ONOFF = 0x0203 | TY\_FEATURE\_BOOL, TY\_INT\_KEEP\_ALIVE\_TIMEOUT = 0x0204 | TY FEATURE INT, TY BOOL CMOS SYNC = 0x0205 | TY FEATURE BOOL, TY INT TRIG← GER DELAY US = 0x0206 | TY FEATURE INT, TY BOOL TRIGGER OUT IO = 0x0207 | TY FEATURE BOOL, TY INT TRIGGER DURATION US = 0x0208 | TY FEATURE INT, TY ENUM STREAM ASYNC = 0x0209 | TY FEATURE ENUM, TY INT -CAPTURE TIME US = 0x0210 | TY FEATURE INT, TY ENUM TIME SYNC TYPE = 0x0211 | TY FEATURE ENUM, TY BOOL TIME SYNC READY = 0x0212 | TY\_FEATURE\_BOOL, TY\_BOOL\_FLASHLIGHT = 0x0213 | TY\_FEATURE\_BOOL, TY\_INT\_FL↔ ASHLIGHT\_INTENSITY = 0x0214 | TY\_FEATURE\_INT, TY\_STRUCT\_DO0\_WORKMODE = 0x0215 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DI0\_WORKMODE = 0x0216 | TY FEATURE STRUCT, TY STRUCT DO1 WORKMODE = 0x0217 | TY FEATURE STRUCT, TY\_STRUCT\_DI1\_WORKMODE = 0x0218 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DO2\_WORKMODE = 0x0219 | TY\_FEATURE\_STRUCT, TY\_STRUCT\_DI2\_WORKMODE = 0x0220 | TY FEATURE STRUCT, TY BOOL AUTO EXPOSURE = 0x0300 | TY FEATURE BOOL, TY INT EXPOSURE TIME = 0x0301 | TY FEATURE INT, TY\_BOOL\_AUTO\_GAIN = 0x0302 | TY\_FEATURE\_BOOL, TY\_INT\_GAIN = 0x0303 | TY\_FEATURE\_INT, TY BOOL AUTO AWB = 0x0304 | TY FEATURE BOOL, TY STRUCT AEC ROI = 0x0305 | TY FEA↔ TURE STRUCT.

TY\_INT\_TOF\_HDR\_RATIO = 0x0306 | TY\_FEATURE\_INT, TY\_INT\_TOF\_JITTER\_THRESHOLD = 0x0307 | TY\_FEATURE\_INT, TY\_INT\_LASER\_POWER = 0x0500 | TY\_FEATURE\_INT, TY\_BOOL\_LASER\_AUT↔

O\_CTRL = 0x0501 | TY\_FEATURE\_BOOL,

\_\_\_\_

Generated by Doxygen

```
TY_BOOL_UNDISTORTION = 0x0510 | TY_FEATURE_BOOL, TY_BOOL_BRIGHTNESS_HISTOGRAM =
 0x0511 | TY FEATURE BOOL, TY BOOL DEPTH POSTPROC = 0x0512 | TY FEATURE BOOL, TY ←
 INT R GAIN = 0x0520 | TY FEATURE INT,
 TY_INT_G_GAIN = 0x0521 | TY_FEATURE_INT, TY_INT_B_GAIN = 0x0522 | TY_FEATURE_INT, TY_I↔
 NT ANALOG GAIN = 0x0524 | TY FEATURE INT, TY BOOL HDR = 0x0525 | TY FEATURE BOOL,
 TY BYTEARRAY HDR PARAMETER = 0x0526 | TY FEATURE BYTEARRAY, TY BOOL IMU DATA ←
 ONOFF = 0x0600 | TY FEATURE BOOL, TY STRUCT IMU ACC BIAS = 0x0601 | TY FEATURE ST ←
 RUCT, TY STRUCT IMU ACC MISALIGNMENT = 0x0602 | TY FEATURE STRUCT,
 TY STRUCT IMU ACC SCALE = 0x0603 | TY_FEATURE_STRUCT, TY_STRUCT_IMU_GYRO_BIAS =
 0x0604 | TY FEATURE STRUCT, TY STRUCT IMU GYRO MISALIGNMENT = 0x0605 | TY FEATUR ←
 E_STRUCT, TY_STRUCT_IMU_GYRO_SCALE = 0x0606 | TY_FEATURE_STRUCT,
 TY_STRUCT_IMU_CAM_TO_IMU = 0x0607 | TY_FEATURE_STRUCT, TY_ENUM_IMU_FPS = 0x0608 |
 TY_FEATURE_ENUM, TY_INT_SGBM_IMAGE_NUM = 0x0610 | TY_FEATURE_INT, TY_INT_SGBM_D←
 ISPARITY NUM = 0x0611 | TY FEATURE INT,
 TY_INT_SGBM_DISPARITY_OFFSET = 0x0612 | TY_FEATURE_INT, TY_INT_SGBM_MATCH_WIN_H↔
 EIGHT = 0x0613 | TY_FEATURE_INT, TY_INT_SGBM_SEMI_PARAM_P1 = 0x0614 | TY_FEATURE_INT,
 TY INT SGBM SEMI PARAM P2 = 0x0615 | TY FEATURE INT,
 TY INT SGBM UNIQUE FACTOR = 0x0616 | TY FEATURE INT, TY INT SGBM UNIQUE ABSDIFF =
 0x0617 | TY_FEATURE_INT, TY_INT_SGBM_COST_PARAM = 0x0618 | TY_FEATURE_INT, TY_BOOL ←
 SGBM HFILTER HALF WIN = 0x0619 | TY FEATURE BOOL,
 TY INT SGBM MATCH WIN WIDTH = 0x061A | TY FEATURE INT, TY BOOL SGBM MEDFILTER =
 0x061B | TY FEATURE BOOL, TY BOOL SGBM LRC = 0x061C | TY FEATURE BOOL, TY INT SG↔
 BM LRC DIFF = 0x061D | TY FEATURE INT,
 TY INT SGBM MEDFILTER THRESH = 0x061E | TY FEATURE INT, TY INT SGBM SEMI PARAM↔
 P1 SCALE = 0x061F | TY FEATURE INT, TY ENUM DEPTH QUALITY = 0x0900 | TY FEATURE E↔
 NUM, TY INT FILTER THRESHOLD = 0x0901 | TY FEATURE INT,
 TY_INT_TOF_CHANNEL = 0x0902 | TY_FEATURE_INT, TY_INT_TOF_MODULATION_THRESHOLD =
 0x0903 | TY FEATURE INT, TY STRUCT TOF FREQ = 0x0904 | TY FEATURE STRUCT, TY BOOL ←
 TOF ANTI INTERFERENCE = 0x0905 | TY FEATURE BOOL }
    feature for component definitions

    enum TY_DEPTH_QUALITY_LIST: uint32_t { TY_DEPTH_QUALITY_BASIC = 1, TY_DEPTH_QUALIT

 Y_MEDIUM = 2, TY_DEPTH_QUALITY_HIGH = 4 }

    enum TY TRIGGER POL LIST: uint32 t { TY TRIGGER POL FALLINGEDGE = 0, TY TRIGGER P↔

 OL_RISINGEDGE = 1 }
    set external trigger signal edge
enum TY_INTERFACE_TYPE_LIST : uint32_t {
 TY_INTERFACE_UNKNOWN = 0, TY_INTERFACE_RAW = 1, TY_INTERFACE_USB = 2, TY_INTERF ←
 ACE ETHERNET = 4,
 TY INTERFACE IEEE80211 = 8, TY INTERFACE ALL = 0xffff }
• enum TY_ACCESS_MODE_LIST : uint32_t { TY_ACCESS_READABLE = 0x1, TY_ACCESS_WRITABLE
 = 0x2
enum TY_STREAM_ASYNC_MODE_LIST : uint32_t {
 TY STREAM ASYNC OFF = 0, TY STREAM ASYNC DEPTH = 1, TY STREAM ASYNC RGB = 2, T↔
 Y_STREAM_ASYNC_DEPTH_RGB = 3,
 TY_STREAM_ASYNC_ALL = 0xff }
    stream async mode
enum TY_PIXEL_BITS_LIST : uint32_t {
 TY_PIXEL_8BIT = 0x1 << 28, TY_PIXEL_16BIT = 0x2 << 28, TY_PIXEL_24BIT = 0x3 << 28, TY_PIX\leftarrow
 EL 32BIT = 0x4 << 28,
 TY_PIXEL_10BIT = 0x5 << 28, TY_PIXEL_12BIT = 0x6 << 28, TY_PIXEL_14BIT = 0x7 << 28, TY_PI\leftarrow
 XEL_48BIT = (uint32_t)0x8 << 28,
 TY PIXEL 64BIT = (uint32 t)0xa << 28 }
• enum TY PIXEL FORMAT LIST: uint32 t {
 TY PIXEL FORMAT UNDEFINED = 0, TY PIXEL FORMAT MONO = (TY PIXEL 8BIT | (0x0 << 24)),
 TY PIXEL FORMAT BAYER8GB = (TY PIXEL 8BIT | (0x1 << 24)), TY PIXEL FORMAT BAYER8BG =
 (TY PIXEL 8BIT | (0x2 << 24)),
 TY_PIXEL_FORMAT_BAYER8GR = (TY_PIXEL_8BIT | (0x3 << 24)), TY_PIXEL_FORMAT_BAYER8RG
```

```
= (TY PIXEL 8BIT | (0x4 << 24)), TY PIXEL FORMAT BAYER8GRBG = TY PIXEL FORMAT BAYE\leftrightarrow
   R8GB, TY PIXEL FORMAT BAYER8RGGB = TY PIXEL FORMAT BAYER8BG,
   TY PIXEL FORMAT BAYER8GBRG = TY PIXEL FORMAT BAYER8GR, TY PIXEL FORMAT BAY
   ER8BGGR = TY_PIXEL_FORMAT_BAYER8RG, TY_PIXEL_FORMAT_CSI_MONO10 = (TY_PIXEL_10BIT
   | (0x0 << 24)), TY_PIXEL_FORMAT_CSI_BAYER10GRBG = (TY_PIXEL_10BIT | (0x1 << 24)),
   TY PIXEL FORMAT CSI BAYER10RGGB = (TY PIXEL 10BIT | (0x2 << 24)), TY PIXEL FORMAT ←
   CSI BAYER10GBRG = (TY PIXEL 10BIT | (0x3 << 24)), TY PIXEL FORMAT CSI BAYER10BGGR =
   (TY PIXEL 10BIT | (0x4 << 24)), TY PIXEL FORMAT CSI MONO12 = (TY PIXEL 12BIT | (0x0 <<
   TY PIXEL FORMAT CSI BAYER12GRBG = (TY PIXEL 12BIT | (0x1 << 24)), TY PIXEL FORMAT ↔
   CSI BAYER12RGGB = (TY PIXEL 12BIT | (0x2 << 24)), TY PIXEL FORMAT CSI BAYER12GBRG =
   (TY_PIXEL_12BIT | (0x3 << 24)), TY_PIXEL_FORMAT_CSI_BAYER12BGGR = (TY_PIXEL_12BIT | (0x4
   TY PIXEL FORMAT DEPTH16 = (TY PIXEL 16BIT | (0x0 << 24)), TY PIXEL FORMAT YVYU = (TY↔
   _PIXEL_16BIT \mid (0x1 << 24)), <code>TY_PIXEL_FORMAT_YUYV</code> = (<code>TY_PIXEL_16BIT</code> \mid (0x2 << 24)), <code>TY_PI</code>\leftrightarrow
   XEL_FORMAT_MONO16 = (TY_PIXEL_16BIT | (0x3 << 24)),
   TY PIXEL FORMAT TOF IR MONO16 = (TY PIXEL 64BIT | (0x4 << 24)), TY PIXEL FORMAT RGB
   = (TY PIXEL 24BIT | (0x0 << 24)), TY PIXEL FORMAT BGR = (TY PIXEL 24BIT | (0x1 << 24)), TY \leftarrow
   \_PIXEL\_FORMAT\_JPEG = (TY\_PIXEL\_24BIT | (0x2 << 24)),
   TY_PIXEL_FORMAT_MJPG = (TY_PIXEL_24BIT | (0x3 << 24)), TY_PIXEL_FORMAT_RGB48 = (TY_P↔
   IXEL 48BIT | (0x0 << 24)), TY PIXEL FORMAT BGR48 = (TY PIXEL 48BIT | (0x1 << 24)), TY PIX↔
   EL FORMAT XYZ48 = (TY PIXEL 48BIT \mid (0x2 << 24)) }
        pixel format definitions
enum TY_RESOLUTION_MODE_LIST : uint32_t {
   TY RESOLUTION MODE 160 \times 100 < (160 < (12) + 100. TY RESOLUTION MODE 160 \times (12) = (160 < (12) + 120.
   TY RESOLUTION MODE 240x320 = (240 << 12) +320, TY RESOLUTION MODE 320x180 = (320 << 12) +180,
   TY RESOLUTION MODE 320x200 = (320 << 12) + 200, TY RESOLUTION MODE 320x240 = (320 << 12) + 240,
   TY RESOLUTION MODE 480 \times 640 = (480 <<12) + 640, TY RESOLUTION MODE 640 \times 360 = (640 <<12) + 360,
   TY RESOLUTION MODE 640 \times 400 = (640 <<12) + 400, TY RESOLUTION MODE 640 \times 480 = (640 <<12) + 480,
   TY RESOLUTION MODE 960 \times 1280 = (960 < <12) + 1280, TY RESOLUTION MODE 1280 \times 720 = 1280 \times 1280 
   (1280 << 12) + 720
   TY RESOLUTION MODE 1280 \times 800 = (1280 < < 12) + 800, TY RESOLUTION MODE 1280 \times 960 = 1280 \times 960
   (1280<<12)+960, TY RESOLUTION MODE 1920×1080 = (1920<<12)+1080, TY RESOLUTION ↔
   MODE_2560 \times 1920 = (2560 < < 12) + 1920,
   TY_RESOLUTION_MODE_2592x1944 = (2592<<12)+1944, TY_RESOLUTION MODE 1920x1440 =
   (1920<<12)+1440, TY RESOLUTION MODE 240x96 = (240<<12)+96, TY RESOLUTION MODE ←
   2048 \times 1536 = (2048 < < 12) + 1536
        predefined resolution list

    enum TY IMAGE MODE LIST : uint32 t {

   TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE -
   IMAGE_MODE1 = (MONO), TY_DECLARE_IMAGE_MODE1 = (MONO),
   TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE -
   IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
   TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE IMAGE MODE1 =(MONO), TY DECLARE -
   IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO),
   TY DECLARE IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO), TY DECLARE -
   IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
   TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_←
   IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO),
   TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_ ↔
   IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
   TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_IMAGE_MODE1 =(MONO), TY_DECLARE_ ↔
   IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO),
   TY DECLARE IMAGE MODE1 = (MONO), TY DECLARE IMAGE MODE1 = (MONO) }
        Predefined Image Mode List image mode controls image resolution & format predefined image modes named like
```

TY\_IMAGE\_MODE\_MONO\_160x120,TY\_IMAGE\_MODE\_RGB\_1280x960.

• enum TY TRIGGER MODE LIST: uint32 t {  $TY\_TRIGGER\_MODE\_OFF = 0, TY\_TRIGGER\_MODE\_SLAVE = 1, TY\_TRIGGER\_MODE\_M\_SIG = 2, T \leftarrow$ 

```
Y_TRIGGER_MODE_M_PER = 3,

TY_TRIGGER_MODE_SIG_PASS = 18, TY_TRIGGER_MODE_PER_PASS = 19, TY_TRIGGER_MODE

_TIMER_LIST = 20, TY_TRIGGER_MODE_TIMER_PERIOD = 21,

TY_TRIGGER_MODE_PER_PASS2 = 30, TY_TRIGGER_WORK_MODE31 = 31, TY_TRIGGER_MODE

_SIG_LASER = 34 }

• enum TY_TIME_SYNC_TYPE_LIST : uint32_t {

TY_TIME_SYNC_TYPE_NONE = 0, TY_TIME_SYNC_TYPE_HOST = 1, TY_TIME_SYNC_TYPE_NTP = 2,

TY_TIME_SYNC_TYPE_PTP = 3,

TY_TIME_SYNC_TYPE_CAN = 4, TY_TIME_SYNC_TYPE_PTP_MASTER = 5 }

type of time sync
```

enum TY IMU FPS LIST { TY IMU FPS 100HZ = 0, TY IMU FPS 200HZ, TY IMU FPS 400HZ }

# Functions

 $\bullet \ \ \mathsf{TY} \underline{\mathsf{EXTC}} \ \mathsf{TY} \underline{\mathsf{EXPORT}} \ \mathsf{const} \ \mathsf{char} \ * \mathsf{TY} \underline{\mathsf{STDC}} \ \underline{\mathsf{TYErrorString}} \ (\mathsf{TY} \underline{\mathsf{STATUS}} \ \mathsf{errorID})$ 

Get error information.

TY\_CAPI TYDeinitLib (void)

Deinit this library.

TY\_CAPI TYLibVersion (TY\_VERSION\_INFO \*version)

Get current library version.

• TY\_CAPI TYUpdateInterfaceList ()

Update current interfaces. call before TYGetInterfaceList.

TY\_CAPI TYGetInterfaceNumber (uint32\_t \*pNumIfaces)

Get number of current interfaces.

TY\_CAPI TYGetInterfaceList (TY\_INTERFACE\_INFO \*plfaceInfos, uint32\_t bufferCount, uint32\_t \*filled ← Count)

Get interface info list.

• TY\_CAPI TYHasInterface (const char \*ifaceID, bool \*value)

Check if has interface.

TY\_CAPI TYOpenInterface (const char \*ifaceID, TY\_INTERFACE\_HANDLE \*outHandle)

Open specified interface.

• TY\_CAPI TYCloseInterface (TY\_INTERFACE\_HANDLE ifaceHandle)

Close interface.

TY\_CAPI TYUpdateDeviceList (TY\_INTERFACE\_HANDLE ifaceHandle)

Update current connected devices.

TY\_CAPI TYUpdateAllDeviceList ()

Update current connected devices.

TY\_CAPI TYGetDeviceNumber (TY\_INTERFACE\_HANDLE ifaceHandle, uint32\_t \*deviceNumber)

Get number of current connected devices.

TY\_CAPI TYGetDeviceList (TY\_INTERFACE\_HANDLE ifaceHandle, TY\_DEVICE\_BASE\_INFO \*device ←
 Infos, uint32\_t bufferCount, uint32\_t \*filledDeviceCount)

Get device info list.

• TY\_CAPI TYHasDevice (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*deviceID, bool \*value)

Check whether the interface has the specified device.

Open device by device ID.

• TY\_CAPI TYOpenDeviceWithIP (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*IP, TY\_DEV\_HANDLE \*deviceHandle)

Open device by device IP, useful when a device is not listed.

• TY\_CAPI TYGetDeviceInterface (TY\_DEV\_HANDLE hDevice, TY\_INTERFACE\_HANDLE \*plface)

Get interface handle by device handle.

 TY\_CAPI TYForceDeviceIP (TY\_INTERFACE\_HANDLE ifaceHandle, const char \*MAC, const char \*newIP, const char \*newNetMask, const char \*newGateway)

Force a ethernet device to use new IP address, useful when device use persistent IP and cannot be found.

• TY\_CAPI TYCloseDevice (TY\_DEV\_HANDLE hDevice, bool reboot=false)

Close device by device handle.

TY\_CAPI TYGetDeviceInfo (TY\_DEV\_HANDLE hDevice, TY\_DEVICE\_BASE\_INFO \*info)
 Get base info of the open device.

- TY\_CAPI TYGetComponentIDs (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID \*componentIDs) Get all components IDs.
- TY\_CAPI TYGetEnabledComponents (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID \*componentIDs)

  Get all enabled components IDs.
- TY\_CAPI TYEnableComponents (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentIDs)
   Enable components.
- TY\_CAPI TYDisableComponents (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentIDs)
   Disable components.
- TY\_CAPI TYGetFrameBufferSize (TY\_DEV\_HANDLE hDevice, uint32\_t \*bufferSize)

  Get total buffer size of one frame in current configuration.
- TY\_CAPI TYEnqueueBuffer (TY\_DEV\_HANDLE hDevice, void \*buffer, uint32\_t bufferSize)

  Enqueue a user allocated buffer.
- TY CAPI TYClearBufferQueue (TY DEV HANDLE hDevice)

Clear the internal buffer queue, so that user can release all the buffer.

- TY\_CAPI TYStartCapture (TY\_DEV\_HANDLE hDevice)
  - Start capture.
- TY CAPI TYStopCapture (TY DEV HANDLE hDevice)

Stop capture.

TY\_CAPI TYSendSoftTrigger (TY\_DEV\_HANDLE hDevice)

Send a software trigger to capture a frame when device works in trigger mode.

 TY\_CAPI TYRegisterEventCallback (TY\_DEV\_HANDLE hDevice, TY\_EVENT\_CALLBACK callback, void \*userdata)

Register device status callback. Register NULL to clean callback.

 TY\_CAPI TYRegisterImuCallback (TY\_DEV\_HANDLE hDevice, TY\_IMU\_CALLBACK callback, void \*userdata)

Register imu callback. Register NULL to clean callback.

- TY\_CAPI TYFetchFrame (TY\_DEV\_HANDLE hDevice, TY\_FRAME\_DATA \*frame, int32\_t timeout)
   Fetch one frame.
- TY\_CAPI TYHasFeature (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATUR ← E\_ID featureID, bool \*value)

Check whether a component has a specific feature.

TY\_CAPI TYGetFeatureInfo (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEAT
 URE\_ID featureID, TY\_FEATURE\_INFO \*featureInfo)

Get feature info.

• TY\_CAPI TYGetIntRange (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATU ← RE\_ID featureID, TY\_INT\_RANGE \*intRange)

Get value range of integer feature.

• TY\_CAPI TYGetInt (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, int32\_t \*value)

Get value of integer feature.

• TY\_CAPI TYSetInt (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, int32 t value)

Set value of integer feature.

• TY\_CAPI TYGetFloatRange (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEA

TURE\_ID featureID, TY\_FLOAT\_RANGE \*floatRange)

Get value range of float feature.

• TY\_CAPI TYGetFloat (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, float \*value)

Get value of float feature.

TY\_CAPI TYSetFloat (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, float value)

Set value of float feature.

Get number of enum entries.

• TY\_CAPI TYGetEnumEntryInfo (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_F ← EATURE\_ID featureID, TY\_ENUM\_ENTRY \*entries, uint32\_t entryCount, uint32\_t \*filledEntryCount)

Get list of enum entries.

• TY\_CAPI TYGetEnum (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, uint32\_t \*value)

Get current value of enum feature.

• TY\_CAPI TYSetEnum (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, uint32 t value)

Set value of enum feature.

• TY\_CAPI TYGetBool (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, bool \*value)

Get value of bool feature.

• TY\_CAPI TYSetBool (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, bool value)

Set value of bool feature.

TY\_CAPI TYGetStringLength (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEA
 — TURE\_ID featureID, uint32\_t \*size)

Get internal buffer size of string feature.

• TY\_CAPI TYGetString (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, char \*buffer, uint32 t bufferSize)

Get value of string feature.

• TY\_CAPI TYSetString (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, const char \*buffer)

Set value of string feature.

• TY\_CAPI TYGetStruct (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, void \*pStruct, uint32\_t structSize)

Get value of struct.

• TY\_CAPI TYSetStruct (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATURE\_ID featureID, void \*pStruct, uint32\_t structSize)

Set value of struct.

• TY\_CAPI TYGetByteArraySize (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FE

ATURE ID featureID, uint32 t \*pSize)

Get the size of specified byte array zone .

• TY\_CAPI TYGetDeviceFeatureNumber (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, uint32 t \*size)

Get the size of device features .

TY\_CAPI TYGetDeviceFeatureInfo (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY
 — FEATURE\_INFO \*featureInfo, uint32\_t entryCount, uint32\_t \*filledEntryCount)

Get the all features by comp id.

• TY\_CAPI TYGetByteArray (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATU ← RE ID featureID, uint8 t \*pBuffer, uint32 t bufferSize)

Read byte array from device.

TY\_CAPI TYSetByteArray (TY\_DEV\_HANDLE hDevice, TY\_COMPONENT\_ID componentID, TY\_FEATU

RE\_ID featureID, const uint8\_t \*pBuffer, uint32\_t bufferSize)

Write byte array to device.

Write byte array to device.

TY\_CAPI \_TYInitLib (void)

#### **Variables**

- typedef enum
- typedef **TY DO 5V** = 1
- typedef **TY\_DO\_12V** = 2
- typedef TY\_E\_VOLT\_T\_LIST
- typedef TY\_DO\_HIGH = 1
- typedef TY\_DO\_PWM = 2
- typedef TY\_DO\_CAM\_TRIG = 3
- typedef TY\_E\_DO\_MODE\_LIST
- typedef TY\_DI\_NE\_INT = 1
- typedef **TY\_DI\_PE\_INT** = 2
- · typedef TY E DI MODE LIST
- typedef TY\_DI\_INT\_TRIG\_CAP = 1
- typedef TY\_DI\_INT\_EVENT = 2
- typedef TY\_E\_DI\_INT\_ACTION\_LIST

#### 5.1.1 Detailed Description

TYApi.h includes camera control and data receiving interface, which supports configuration for image resolution, frame rate, exposure time, gain, working mode,etc.

#### 5.1.2 Macro Definition Documentation

# 5.1.2.1 TY\_DECLARE\_IMAGE\_MODE1

#### Value:

```
TY_DECLARE_IMAGE_MODE0(pix, 160x100), \
            TY_DECLARE_IMAGE_MODE0(pix, 160x120),
            TY_DECLARE_IMAGE_MODE0(pix, 320x180),
            TY_DECLARE_IMAGE_MODE0(pix, 320x200),
            TY_DECLARE_IMAGE_MODE0(pix, 320x240),
            TY_DECLARE_IMAGE_MODE0(pix, 480x640),
            TY_DECLARE_IMAGE_MODE0(pix, 640x360),
            TY_DECLARE_IMAGE_MODE0(pix, 640x400),
            TY_DECLARE_IMAGE_MODE0(pix, 640x480),
            TY_DECLARE_IMAGE_MODE0(pix, 960x1280),
            TY_DECLARE_IMAGE_MODE0(pix, 1280x720),
            TY_DECLARE_IMAGE_MODE0(pix, 1280x960),
            TY_DECLARE_IMAGE_MODE0(pix, 1280x800),
             TY_DECLARE_IMAGE_MODE0(pix, 1920x1080),
            TY_DECLARE_IMAGE_MODE0(pix, 2560x1920),
            TY_DECLARE_IMAGE_MODE0(pix, 2592x1944),
            TY_DECLARE_IMAGE_MODE0(pix, 1920x1440),
TY_DECLARE_IMAGE_MODE0(pix, 2048x1536),
            TY_DECLARE_IMAGE_MODE0(pix, 240x96)
```

Definition at line 491 of file TYApi.h.

# 5.1.3 Typedef Documentation

## 5.1.3.1 TY\_ACC\_BIAS

typedef struct TY\_ACC\_BIAS TY\_ACC\_BIAS

#### a 3x3 matrix

BIASx	BIASy	BIASz

# 5.1.3.2 TY\_ACC\_MISALIGNMENT

typedef struct TY\_ACC\_MISALIGNMENT TY\_ACC\_MISALIGNMENT

## a 3x3 matrix |.|.|.

1	-GAMAyz	GAMAzy
GAMAxz	1	-GAMAzx
-GAMAxy	GAMAyx	1

#### 5.1.3.3 TY\_ACC\_SCALE

typedef struct TY\_ACC\_SCALE TY\_ACC\_SCALE

#### a 3x3 matrix

		•
SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

# 5.1.3.4 TY\_ACCESS\_MODE\_LIST

 $\verb|typedef| enum TY\_ACCESS\_MODE\_LIST| TY\_ACCESS\_MODE\_LIST|$ 

Indicate a feature is readable or writable

See also

**TYGetFeatureInfo** 

```
5.1.3.5 TY_BYTEARRAY_ATTR
```

typedef struct TY\_BYTEARRAY\_ATTR TY\_BYTEARRAY\_ATTR

byte array data structure

See also

**TYGetByteArray** 

```
5.1.3.6 TY_CAMERA_CALIB_INFO
```

typedef struct TY\_CAMERA\_CALIB\_INFO TY\_CAMERA\_CALIB\_INFO

camera 's cailbration data

See also

**TYGetStruct** 

## 5.1.3.7 TY\_CAMERA\_DISTORTION

typedef struct TY\_CAMERA\_DISTORTION TY\_CAMERA\_DISTORTION

camera distortion parameters

See also

## TYGetStruct Usage:

#### 5.1.3.8 TY\_CAMERA\_EXTRINSIC

typedef struct TY\_CAMERA\_EXTRINSIC TY\_CAMERA\_EXTRINSIC

a 4x4 matrix

	•		
r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

#### See also

## TYGetStruct Usage:

```
TY_CAMERA_EXTRINSIC extrinsic;
TYGetStruct(hDevice, some_compoent, TY_STRUCT_EXTRINSIC, &extrinsic, sizeof(extrinsic));
```

## 5.1.3.9 TY\_CAMERA\_INTRINSIC

```
typedef struct TY_CAMERA_INTRINSIC TY_CAMERA_INTRINSIC
```

#### a 3x3 matrix

fx	0	СХ
0	fy	су
0	0	1

#### See also

# TYGetStruct Usage:

#### 5.1.3.10 TY\_CAMERA\_TO\_IMU

```
typedef struct TY_CAMERA_TO_IMU TY_CAMERA_TO_IMU
```

#### a 4x4 matrix

r11	r12	r13	t1
r21	r22	r23	t2
r31	r32	r33	t3
0	0	0	1

## 5.1.3.11 TY\_COMPONENT\_ID

```
typedef uint32_t TY_COMPONENT_ID
```

component unique id

See also

TY\_DEVICE\_COMPONENT\_LIST

Definition at line 208 of file TYApi.h.

## 5.1.3.12 TY\_DEVICE\_BASE\_INFO

```
typedef struct TY_DEVICE_BASE_INFO TY_DEVICE_BASE_INFO
```

See also

**TYGetDeviceList** 

## 5.1.3.13 TY\_DEVICE\_COMPONENT\_LIST

```
typedef enum TY_DEVICE_COMPONENT_LIST TY_DEVICE_COMPONENT_LIST
```

Device Component list A device contains several component. Each component can be controlled by its own features, such as image width, exposure time, etc..

See also

To Know how to get feature information please refer to sample code DumpAllFeatures

#### 5.1.3.14 TY\_ENUM\_ENTRY

```
typedef struct TY_ENUM_ENTRY TY_ENUM_ENTRY
```

enum feature entry information

See also

TYGetEnumEntryInfo

5.1.3.15 TY\_FEATURE\_ID

typedef uint32\_t TY\_FEATURE\_ID

feature unique id

See also

TY\_FEATURE\_ID\_LIST

Definition at line 346 of file TYApi.h.

5.1.3.16 TY\_FLOAT\_RANGE

typedef struct TY\_FLOAT\_RANGE TY\_FLOAT\_RANGE

float range data structure

See also

TYGetFloatRange

5.1.3.17 TY\_GYRO\_BIAS

typedef struct TY\_GYRO\_BIAS TY\_GYRO\_BIAS

a 3x3 matrix

BIASx	BIASy	BIASz

5.1.3.18 TY\_GYRO\_MISALIGNMENT

typedef struct TY\_GYRO\_MISALIGNMENT TY\_GYRO\_MISALIGNMENT

a 3x3 matrix

1	-ALPHAyz	ALPHAzy
0	1	-ALPHAzx
0	0	1

#### 5.1.3.19 TY\_GYRO\_SCALE

typedef struct TY\_GYRO\_SCALE TY\_GYRO\_SCALE

#### a 3x3 matrix

•		•
SCALEx	0	0
0	SCALEy	0
0	0	SCALEz

## 5.1.3.20 TY\_INTERFACE\_INFO

typedef struct TY\_INTERFACE\_INFO TY\_INTERFACE\_INFO

See also

TYGetInterfaceList

# 5.1.3.21 TY\_INTERFACE\_TYPE\_LIST

typedef enum TY\_INTERFACE\_TYPE\_LIST TY\_INTERFACE\_TYPE\_LIST

Interface type definition

See also

TYGetInterfaceList

#### 5.1.3.22 TY\_PIXEL\_BITS\_LIST

typedef enum TY\_PIXEL\_BITS\_LIST TY\_PIXEL\_BITS\_LIST

Pixel size type definitions to define the pixel size in bits

See also

TY\_PIXEL\_FORMAT\_LIST

#### 5.1.3.23 TY\_TRIGGER\_MODE\_LIST

```
typedef enum TY_TRIGGER_MODE_LIST TY_TRIGGER_MODE_LIST
```

#### See also

refer to sample SimpleView TriggerMode for detail usage

# 5.1.4 Enumeration Type Documentation

## 5.1.4.1 TY\_ACCESS\_MODE\_LIST

```
enum TY_ACCESS_MODE_LIST : uint32_t
```

Indicate a feature is readable or writable

#### See also

**TYGetFeatureInfo** 

Definition at line 379 of file TYApi.h.

## 5.1.4.2 TY\_DEVICE\_COMPONENT\_LIST

```
enum TY_DEVICE_COMPONENT_LIST : uint32_t
```

Device Component list A device contains several component. Each component can be controlled by its own features, such as image width, exposure time, etc..

# See also

To Know how to get feature information please refer to sample code DumpAllFeatures

TY_COMPONENT_DEVICE	Abstract component stands for whole device, always enabled.
TY_COMPONENT_DEPTH_CAM	Depth camera.
TY_COMPONENT_IR_CAM_LEFT	Left IR camera.
TY_COMPONENT_IR_CAM_RIGHT	Right IR camera.
TY_COMPONENT_RGB_CAM_LEFT	Left RGB camera.
TY_COMPONENT_RGB_CAM_RIGHT	Right RGB camera.
TY_COMPONENT_LASER	Laser.
TY_COMPONENT_IMU	Inertial Measurement Unit.
TY_COMPONENT_BRIGHT_HISTO	virtual component for brightness histogram of ir
TY_COMPONENT_STORAGE	virtual component for device storage
Generated by ToxygenMPONENT_RGB_CAM	Some device has only one RGB camera, map it to left.

Definition at line 193 of file TYApi.h.

# 5.1.4.3 TY\_FEATURE\_ID\_LIST

enum TY\_FEATURE\_ID\_LIST : uint32\_t

feature for component definitions

TY_STRUCT_CAM_INTRINSIC	see TY_CAMERA_INTRINSIC
TY_STRUCT_EXTRINSIC_TO_DEPTH	extrinsic between depth cam and current component , see TY_CAMERA_EXTRINSIC
TY_STRUCT_EXTRINSIC_TO_IR_LEFT	extrinsic between left IR and current compoent, see TY_CAMERA_EXTRINSIC
TY_STRUCT_CAM_DISTORTION	see TY_CAMERA_DISTORTION
TY_STRUCT_CAM_CALIB_DATA	see TY_CAMERA_CALIB_INFO
TY_STRUCT_CAM_RECTIFIED_INTRI	the rectified intrinsic. see TY_CAMERA_INTRINSIC
TY_BYTEARRAY_CUSTOM_BLOCK	used for reading/writing custom block
TY_BYTEARRAY_ISP_BLOCK	used for reading/writing fpn block
TY_INT_PACKET_DELAY	microseconds
TY_INT_NTP_SERVER_IP	Ntp server IP.
TY_INT_LINK_CMD_TIMEOUT	milliseconds
TY_STRUCT_CAM_STATISTICS	statistical information, see TY_CAMERA_STATISTICS
TY_INT_WIDTH	Image width.
TY_INT_HEIGHT	Image height.
TY_ENUM_IMAGE_MODE	Resolution-PixelFromat mode, see TY_IMAGE_MODE_LIST.
TY_FLOAT_SCALE_UNIT	scale unit depth image is uint16 pixel format with default
	millimeter unit ,for some device can output Sub-millimeter
TV 5.004 TD1005 D01	accuracy data the acutal depth (mm)= PixelValue * ScaleUnit
TY_ENUM_TRIGGER_POL	Trigger POL, see TY_TRIGGER_POL_LIST.
TY_INT_FRAME_PER_TRIGGER	Number of frames captured per trigger.
TY_STRUCT_TRIGGER_PARAM	param of trigger, see TY_TRIGGER_PARAM
TY_STRUCT_TRIGGER_PARAM_EX	param of trigger, see TY_TRIGGER_PARAM_EX
TY_STRUCT_TRIGGER_TIMER_LIST	param of trigger mode 20, see TY_TRIGGER_TIMER_LIST
TY_STRUCT_TRIGGER_TIMER_PERIOD	param of trigger mode 21, see TY_TRIGGER_TIMER_PERIOD
TY_BOOL_KEEP_ALIVE_ONOFF	Keep Alive switch.
TY_INT_KEEP_ALIVE_TIMEOUT	Keep Alive timeout.
TY_BOOL_CMOS_SYNC	Cmos sync switch.
TY_INT_TRIGGER_DELAY_US	Trigger delay time, in microseconds.
TY_BOOL_TRIGGER_OUT_IO	Trigger out IO.
TY_INT_TRIGGER_DURATION_US	Trigger duration time, in microseconds.
TY_ENUM_STREAM_ASYNC	stream async switch, see TY_STREAM_ASYNC_MODE
TY_INT_CAPTURE_TIME_US	capture time in multi-ir
TY_ENUM_TIME_SYNC_TYPE	see TY_TIME_SYNC_TYPE
TY_BOOL_TIME_SYNC_READY	time sync done status
TY_BOOL_FLASHLIGHT	flashlight on/off control

TY_INT_FLASHLIGHT_INTENSITY	flashlight intensity level [0, 63]
TY_STRUCT_DO0_WORKMODE	DO_0 workmode, see TY_DO_WORKMODE.
TY_STRUCT_DI0_WORKMODE	DI_0 workmode, see TY_DI_WORKMODE.
TY_STRUCT_DO1_WORKMODE	DO_1 workmode, see TY_DO_WORKMODE.
TY_STRUCT_DI1_WORKMODE	DI_1 workmode, see TY_DI_WORKMODE.
TY_STRUCT_DO2_WORKMODE	DO_2 workmode, see TY_DO_WORKMODE.
TY_STRUCT_DI2_WORKMODE	DI_2 workmode, see TY_DI_WORKMODE.
TY_BOOL_AUTO_EXPOSURE	Auto exposure switch.
TY_INT_EXPOSURE_TIME	Exposure time in percentage.
TY_BOOL_AUTO_GAIN	Auto gain switch.
TY_INT_GAIN	Sensor Gain.
TY_BOOL_AUTO_AWB	Auto white balance.
TY_STRUCT_AEC_ROI	region of aec statistics, see TY_AEC_ROI_PARAM
TY_INT_TOF_HDR_RATIO	tof sensor hdr ratio for depth
TY_INT_TOF_JITTER_THRESHOLD	tof jitter threshold for depth
TY_INT_LASER_POWER	Laser power level.
TY_BOOL_LASER_AUTO_CTRL	Laser auto ctrl.
TY_BOOL_UNDISTORTION	Output undistorted image.
TY_BOOL_BRIGHTNESS_HISTOGRAM	Output bright histogram.
TY_BOOL_DEPTH_POSTPROC	Do depth image postproc.
TY_INT_R_GAIN	Gain of R channel.
TY_INT_G_GAIN	Gain of G channel.
TY_INT_B_GAIN	Gain of B channel.
TY_INT_ANALOG_GAIN	Analog gain.
TY BOOL HDR	HDR func enable/disable.
TY_BYTEARRAY_HDR_PARAMETER	HDR parameters.
TY_BOOL_IMU_DATA_ONOFF	IMU Data Onoff.
TY_STRUCT_IMU_ACC_BIAS	IMU acc bias matrix, see TY_ACC_BIAS.
TY_STRUCT_IMU_ACC_MISALIGNMENT	IMU acc misalignment matrix, see
	TY_ACC_MISALIGNMENT.
TY_STRUCT_IMU_ACC_SCALE	IMU acc scale matrix, see TY_ACC_SCALE.
TY_STRUCT_IMU_GYRO_BIAS	IMU gyro bias matrix, see TY_GYRO_BIAS.
TY_STRUCT_IMU_GYRO_MISALIGNMENT	IMU gyro misalignment matrix, see
	TY_GYRO_MISALIGNMENT.
TY_STRUCT_IMU_GYRO_SCALE	IMU gyro scale matrix, see TY_GYRO_SCALE.
TY_STRUCT_IMU_CAM_TO_IMU	IMU camera to imu matrix, see TY_CAMERA_TO_IMU.
TY_ENUM_IMU_FPS	IMU fps, see TY_IMU_FPS_LIST.
TY_INT_SGBM_IMAGE_NUM	SGBM image channel num.
TY_INT_SGBM_DISPARITY_NUM	SGBM disparity num.
TY_INT_SGBM_DISPARITY_OFFSET	SGBM disparity offset.
TY_INT_SGBM_MATCH_WIN_HEIGHT	SGBM match window height.
TY_INT_SGBM_SEMI_PARAM_P1	SGBM semi global param p1.
TY_INT_SGBM_SEMI_PARAM_P2	SGBM semi global param p2.
TY_INT_SGBM_UNIQUE_FACTOR	SGBM uniqueness factor param.
TY INT SGBM UNIQUE ABSDIFF	SGBM uniqueness min absolute diff.
TY INT SGBM COST PARAM	SGBM cost param.
TY_BOOL_SGBM_HFILTER_HALF_WIN	SGBM enable half window size.
TY_INT_SGBM_MATCH_WIN_WIDTH	SGBM match window width.
335	

# Enumerator

TY_BOOL_SGBM_MEDFILTER	SGBM enable median filter.
TY_BOOL_SGBM_LRC	SGBM enable left right consist check.
TY_INT_SGBM_LRC_DIFF	SGBM max diff.
TY_INT_SGBM_MEDFILTER_THRESH	SGBM median filter thresh.
TY_INT_SGBM_SEMI_PARAM_P1_SCALE	SGBM semi global param p1 scale.
TY_ENUM_DEPTH_QUALITY	the quality of generated depth, see TY_DEPTH_QUALITY
TY_INT_FILTER_THRESHOLD	the threshold of the noise filter, 0 for disabled
TY_INT_TOF_CHANNEL	the frequency channel of tof
TY_INT_TOF_MODULATION_THRESHOLD	the threshold of the tof modulation
TY_STRUCT_TOF_FREQ	the frequency of tof, see TY_TOF_FREQ
TY_BOOL_TOF_ANTI_INTERFERENCE	cooperation if multi-device used

Definition at line 227 of file TYApi.h.

## 5.1.4.4 TY\_INTERFACE\_TYPE\_LIST

```
enum TY_INTERFACE_TYPE_LIST : uint32_t
```

Interface type definition

See also

TYGetInterfaceList

Definition at line 366 of file TYApi.h.

```
5.1.4.5 TY_PIXEL_BITS_LIST
```

```
enum TY_PIXEL_BITS_LIST : uint32_t
```

Pixel size type definitions to define the pixel size in bits

See also

```
TY_PIXEL_FORMAT_LIST
```

Definition at line 401 of file TYApi.h.

# 5.1.4.6 TY\_PIXEL\_FORMAT\_LIST

```
enum TY_PIXEL_FORMAT_LIST : uint32_t
```

pixel format definitions

## Enumerator

TY_PIXEL_FORMAT_MONO	0x10000000
TY_PIXEL_FORMAT_BAYER8GB	0x11000000
TY_PIXEL_FORMAT_BAYER8BG	0x12000000
TY_PIXEL_FORMAT_BAYER8GR	0x13000000
TY_PIXEL_FORMAT_BAYER8RG	0x14000000
TY_PIXEL_FORMAT_CSI_MONO10	0x50000000
TY_PIXEL_FORMAT_CSI_BAYER10GRBG	0x51000000
TY_PIXEL_FORMAT_CSI_BAYER10RGGB	0x52000000
TY_PIXEL_FORMAT_CSI_BAYER10GBRG	0x53000000
TY_PIXEL_FORMAT_CSI_BAYER10BGGR	0x54000000
TY_PIXEL_FORMAT_CSI_MONO12	0x60000000
TY_PIXEL_FORMAT_CSI_BAYER12GRBG	0x61000000
TY_PIXEL_FORMAT_CSI_BAYER12RGGB	0x62000000
TY_PIXEL_FORMAT_CSI_BAYER12GBRG	0x63000000
TY_PIXEL_FORMAT_CSI_BAYER12BGGR	0x64000000
TY_PIXEL_FORMAT_DEPTH16	0x20000000
TY_PIXEL_FORMAT_YVYU	0x21000000, yvyu422
TY_PIXEL_FORMAT_YUYV	0x22000000, yuyv422
TY_PIXEL_FORMAT_MONO16	0x23000000,
TY_PIXEL_FORMAT_TOF_IR_MONO16	0xa4000000,
TY_PIXEL_FORMAT_RGB	0x30000000
TY_PIXEL_FORMAT_BGR	0x31000000
TY_PIXEL_FORMAT_JPEG	0x32000000
TY_PIXEL_FORMAT_MJPG	0x33000000
TY_PIXEL_FORMAT_RGB48	0x80000000
TY_PIXEL_FORMAT_BGR48	0x81000000
TY_PIXEL_FORMAT_XYZ48	0x82000000

Definition at line 419 of file TYApi.h.

# 5.1.4.7 TY\_RESOLUTION\_MODE\_LIST

enum TY\_RESOLUTION\_MODE\_LIST : uint32\_t

predefined resolution list

TY_RESOLUTION_MODE_160x100	0x000a0078
TY_RESOLUTION_MODE_160x120	0x000a0078
TY_RESOLUTION_MODE_240x320	0x000f0140
TY_RESOLUTION_MODE_320x180	0x001400b4
TY_RESOLUTION_MODE_320x200	0x001400c8
TY_RESOLUTION_MODE_320x240	0x001400f0
TY_RESOLUTION_MODE_480x640	0x001e0280
TY_RESOLUTION_MODE_640x360	0x00280168

#### Enumerator

TY_RESOLUTION_MODE_640x400	0x00280190
TY_RESOLUTION_MODE_640x480	0x002801e0
TY_RESOLUTION_MODE_960x1280	0x003c0500
TY_RESOLUTION_MODE_1280x720	0x005002d0
TY_RESOLUTION_MODE_1280x800	0x00500320
TY_RESOLUTION_MODE_1280x960	0x005003c0
TY_RESOLUTION_MODE_1920x1080	0x00780438
TY_RESOLUTION_MODE_2560x1920	0x00a00780
TY_RESOLUTION_MODE_2592x1944	0x00a20798
TY_RESOLUTION_MODE_1920x1440	0x007805a0
TY_RESOLUTION_MODE_240x96	0x000f0060
TY_RESOLUTION_MODE_2048x1536	0x00800600

Definition at line 463 of file TYApi.h.

## 5.1.4.8 TY\_TRIGGER\_MODE\_LIST

```
enum TY_TRIGGER_MODE_LIST : uint32_t
```

#### See also

refer to sample SimpleView\_TriggerMode for detail usage

#### Enumerator

TY_TRIGGER_MODE_OFF	not trigger mode, continuous mode
TY_TRIGGER_MODE_SLAVE	slave mode, receive soft/hardware triggers
TY_TRIGGER_MODE_M_SIG	master mode 1, sending one trigger signal once received a soft/hardware trigger
TY_TRIGGER_MODE_M_PER	master mode 2, periodic sending one trigger signals, 'fps' param should be set
TY_TRIGGER_MODE_PER_PASS2	trigger mode 30,Alternate output depth image/ir image

Definition at line 560 of file TYApi.h.

# 5.1.5 Function Documentation

#### 5.1.5.1 TYClearBufferQueue()

Clear the internal buffer queue, so that user can release all the buffer.

## **Parameters**

in <i>hDevice</i>	Device handle.
-------------------	----------------

#### **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_BUSY	Device is capturing.

#### 5.1.5.2 TYCloseDevice()

```
TY_CAPI TYCloseDevice (

TY_DEV_HANDLE hDevice,

bool reboot = false )
```

Close device by device handle.

#### **Parameters**

in <i>hDevice</i>	Device handle.
-------------------	----------------

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_IDLE	Device has been closed.

## 5.1.5.3 TYCloseInterface()

Close interface.

#### **Parameters**

in <i>ifaceHandle</i> Ir	terface to be closed.
--------------------------	-----------------------

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Interface not found.

#### 5.1.5.4 TYDeinitLib()

Deinit this library.

Return values

```
TY_STATUS_OK Succeed.
```

## 5.1.5.5 TYDisableComponents()

```
TY_CAPI TYDisableComponents (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentIDs )
```

Disable components.

#### **Parameters**

in	hDevice	Device handle.
in	componentIDs	Components to be disabled.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Some components specified by componentIDs are invalid.
TY_STATUS_BUSY	Device is capturing.

See also

```
TY_DEVICE_COMPONENT_LIST
```

# 5.1.5.6 TYEnableComponents()

Enable components.

#### **Parameters**

in	hDevice	Device handle.
in	componentIDs	Components to be enabled.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Some components specified by componentIDs are invalid.
TY_STATUS_BUSY	Device is capturing.

# 5.1.5.7 TYEnqueueBuffer()

Enqueue a user allocated buffer.

#### **Parameters**

in	hDevice	Device handle.
in	buffer	Buffer to be enqueued.
in	bufferSize	Size of the input buffer.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	buffer is NULL.
TY_STATUS_WRONG_SIZE	The input buffer is not large enough.

## 5.1.5.8 TYErrorString()

Get error information.

#### **Parameters**

in	errorID	Error id.

#### Returns

Error string.

## 5.1.5.9 TYFetchFrame()

```
TY_CAPI TYFetchFrame (

TY_DEV_HANDLE hDevice,

TY_FRAME_DATA * frame,

int32_t timeout )
```

Fetch one frame.

#### **Parameters**

in	hDevice	Device handle.	
out	frame	Frame data to be filled.	
in	timeout	Timeout in milliseconds. <0 for infinite.	

#### Return values

TY_STATUS_OK	Succeed.	
TY_STATUS_INVALID_HANDLE Invalid device handle.		
TY_STATUS_NULL_POINTER   frame is NULL.		
TY_STATUS_IDLE	Device capturing is not started.	
TY_STATUS_WRONG_MODE	Callback has been registered, this function is disabled.	
TY_STATUS_TIMEOUT	Timeout.	

# 5.1.5.10 TYForceDeviceIP()

```
TY_CAPI TYForceDeviceIP (

TY_INTERFACE_HANDLE ifaceHandle,

const char * MAC,

const char * newIP,

const char * newNetMask,

const char * newGateway )
```

Force a ethernet device to use new IP address, useful when device use persistent IP and cannot be found.

# Parameters

in	ifaceHandle	Interface handle.	
in	MAC	Device MAC, should be "xx:xx:xx:xx:xx:xx".	
in	newIP	New IP.	
in	newNetMask	New subnet mask.	
in	newGateway	New gateway.	

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED  TYInitLib not called.	
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_WRONG_TYPE	Wrong interface type, should be network.
TY_STATUS_NULL_POINTER	MAC or newIP/newNetMask/newGateway is NULL.
TY_STATUS_INVALID_PARAMETER	MAC is not valid.
TY_STATUS_TIMEOUT	No device found.
TY_STATUS_DEVICE_ERROR	Set new IP failed.

# 5.1.5.11 TYGetBool()

```
TY_CAPI TYGetBool (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

bool * value )
```

Get value of bool feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Bool value.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BOOL.
TY_STATUS_NULL_POINTER	value is NULL.

# 5.1.5.12 TYGetByteArray()

```
TY_CAPI TYGetByteArray (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint8_t * pBuffer,

uint32_t bufferSize )
```

Read byte array from device.

## **Parameters**

in	n hDevice Device handle.	
in	componentID	Component ID.
in	featureID	Feature ID.
out	pbuffer	byte buffer.
in	bufferSize	Size of buffer.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pbuffer is NULL.
TY_STATUS_WRONG_SIZE	bufferSize incorrect.

## 5.1.5.13 TYGetByteArrayAttr()

```
TY_CAPI TYGetByteArrayAttr (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_BYTEARRAY_ATTR * pAttr )
```

Write byte array to device.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pAttr	byte array attribute to be filled.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pbuffer is NULL.

# 5.1.5.14 TYGetByteArraySize()

```
TY_CAPI TYGetByteArraySize (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint32_t * pSize )
```

Get the size of specified byte array zone .

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pSize	size of specified byte array zone.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pSize is NULL.

## 5.1.5.15 TYGetComponentIDs()

Get all components IDs.

#### **Parameters**

in	hDevice	Device handle.
out	componentIDs	All component IDs this device has. (bit flag).

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	componentIDs is NULL.

#### See also

```
TY_DEVICE_COMPONENT_LIST
```

## 5.1.5.16 TYGetDeviceFeatureInfo()

```
TY_CAPI TYGetDeviceFeatureInfo (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_INFO * featureInfo,

uint32_t entryCount,

uint32_t * filledEntryCount)
```

Get the all features by comp id.

#### **Parameters**

in	hDevice	Device handle.
in componentID Component ID.		Component ID.
out	featureInfo	Output feature info.
in	entryCount	Array size of input parameter "featureInfo".
out	filledEntryCount	Number of filled featureInfo.

#### Return values

TY_STATUS_OK	Succeed.	
TY_STATUS_INVALID_HANDLE	Invalid device handle.	
TY_STATUS_INVALID_COMPONENT	Invalid component ID.	
TY_STATUS_NULL_POINTER	featureInfo or filledEntryCount is NULL.	

# 5.1.5.17 TYGetDeviceFeatureNumber()

```
TY_CAPI TYGetDeviceFeatureNumber (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

uint32_t * size )
```

Get the size of device features .

#### **Parameters**

in	hDevice	Device handle.	
in <i>componentID</i>		Component ID.	
out	pSize	size of all feature cnt.	

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	pSize is NULL.

## 5.1.5.18 TYGetDeviceInfo()

Get base info of the open device.

#### **Parameters**

in	hDevice	Device handle.
out	info	Base info out.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	componentIDs is NULL.

## 5.1.5.19 TYGetDeviceInterface()

Get interface handle by device handle.

#### **Parameters**

in	hDevice	Device handle.
out	plface	Interface handle.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	plface is NULL.

## 5.1.5.20 TYGetDeviceList()

```
TY_CAPI TYGetDeviceList (

TY_INTERFACE_HANDLE ifaceHandle,

TY_DEVICE_BASE_INFO * deviceInfos,

uint32_t bufferCount,

uint32_t * filledDeviceCount )
```

#### Get device info list.

# **Parameters**

in	ifaceHandle	Interface handle.
out	deviceInfos	Device info array to be filled.
in	bufferCount	Array size of deviceInfos.
out	filledDeviceCount	Number of filled TY_DEVICE_BASE_INFO.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	deviceInfos or filledDeviceCount is NULL.

## 5.1.5.21 TYGetDeviceNumber()

# Get number of current connected devices.

## **Parameters**

in	ifaceHandle	Interface handle.
out	deviceNumber	Number of connected devices.

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY STATUS NULL POINTER	deviceNumber is NULL.

# 5.1.5.22 TYGetEnabledComponents()

Get all enabled components IDs.

## **Parameters**

in	hDevice	Device handle.
out	componentIDs	Enabled component IDs.(bit flag)

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	componentIDs is NULL.

# See also

```
TY_DEVICE_COMPONENT_LIST
```

# 5.1.5.23 TYGetEnum()

Get current value of enum feature.

# **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Enum value.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY STATUS NULL POINTER	value is NULL.

## 5.1.5.24 TYGetEnumEntryCount()

```
TY_CAPI TYGetEnumEntryCount (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint32_t * entryCount )
```

#### Get number of enum entries.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.

## **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_NULL_POINTER	entryCount is NULL.

# 5.1.5.25 TYGetEnumEntryInfo()

```
TY_CAPI TYGetEnumEntryInfo (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_ENUM_ENTRY * entries,

uint32_t entryCount,

uint32_t * filledEntryCount)
```

## Get list of enum entries.

# **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	entries	Output entries.
in	entryCount	Array size of input parameter "entries".
out	filledEntryCount	Number of filled entries.

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_NULL_POINTER	entries or filledEntryCount is NULL.

# 5.1.5.26 TYGetFeatureInfo()

```
TY_CAPI TYGetFeatureInfo (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_FEATURE_INFO * featureInfo )
```

# Get feature info.

#### **Parameters**

in	hDevice	Device handle.	
in	componentID	Component ID.	
in	featureID	Feature ID.	
out	featureInfo	featureInfo Feature info.	

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	featureInfo is NULL.

# 5.1.5.27 TYGetFloat()

```
TY_CAPI TYGetFloat (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

float * value )
```

## Get value of float feature.

#### **Parameters**

in	hDevice	Device handle.
----	---------	----------------

# **Parameters**

in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Float value.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_FLOAT.
TY_STATUS_NULL_POINTER	value is NULL.

# 5.1.5.28 TYGetFloatRange()

```
TY_CAPI TYGetFloatRange (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

TY_FLOAT_RANGE * floatRange )
```

Get value range of float feature.

## **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	floatRange	Float range to be filled.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_FLOAT.
TY_STATUS_NULL_POINTER	floatRange is NULL.

# 5.1.5.29 TYGetFrameBufferSize()

```
{\tt TY\_CAPI\ TYGetFrameBufferSize\ (}
```

```
TY_DEV_HANDLE hDevice,
uint32_t * bufferSize )
```

Get total buffer size of one frame in current configuration.

## **Parameters**

in	hDevice	Device handle.
out	bufferSize	Buffer size per frame.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_NULL_POINTER	bufferSize is NULL.

# 5.1.5.30 TYGetInt()

Get value of integer feature.

# Parameters

in	hDevice	Device handle.	
in	componentID	Component ID.	
in	featureID	Feature ID.	
out	value	Integer value.	

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_INT.
TY_STATUS_NULL_POINTER	value is NULL.

# 5.1.5.31 TYGetInterfaceList()

```
uint32_t bufferCount,
uint32_t * filledCount )
```

## Get interface info list.

## **Parameters**

out	plfaceInfos	Array of interface infos to be filled.
in	bufferCount	Array size of interface infos.
out	filledCount	Number of filled TY_INTERFACE_INFO.

## **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_NULL_POINTER	plfaceInfos or filledCount is NULL.

# 5.1.5.32 TYGetInterfaceNumber()

```
TY_CAPI TYGetInterfaceNumber ( \mbox{uint32\_t} \ * \ p\mbox{\it NumIfaces} \ )
```

## Get number of current interfaces.

## **Parameters**

out	pNumlfaces	Number of interfaces.

## **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_NULL_POINTER	deviceNumber is NULL.

## 5.1.5.33 TYGetIntRange()

Get value range of integer feature.

# **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	intRange	Integer range to be filled.

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_INT.
TY_STATUS_NULL_POINTER	intRange is NULL.

# 5.1.5.34 TYGetString()

# Get value of string feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	buffer	String buffer.
in	bufferSize	Size of buffer.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRING.
TY_STATUS_NULL_POINTER	buffer is NULL.

## See also

TYGetStringLength

# 5.1.5.35 TYGetStringLength()

Get internal buffer size of string feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	size	String length including '\0'.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRING.
TY_STATUS_NULL_POINTER	size is NULL.

#### See also

**TYGetString** 

# 5.1.5.36 TYGetStruct()

```
TY_CAPI TYGetStruct (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

void * pStruct,

uint32_t structSize )
```

Get value of struct.

## **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pStruct	Pointer of struct.
in	structSize	Size of input buffer pStruct

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRUCT.
TY_STATUS_NULL_POINTER	pStruct is NULL.
TY_STATUS_WRONG_SIZE	structSize incorrect.

# 5.1.5.37 TYHasDevice()

Check whether the interface has the specified device.

## **Parameters**

in	ifaceHandle	Interface handle.
in	deviceID	Device ID string, can be get from TY_DEVICE_BASE_INFO.
out	value	True if the device exists.

#### **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	deviceID or value is NULL.

# 5.1.5.38 TYHasFeature()

```
TY_CAPI TYHasFeature (

TY_DEV_HANDLE hDevice,
```

```
TY_COMPONENT_ID componentID,
TY_FEATURE_ID featureID,
bool * value )
```

Check whether a component has a specific feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	value	Whether has feature.

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_NULL_POINTER	value is NULL.

# 5.1.5.39 TYHasInterface()

Check if has interface.

## **Parameters**

in	ifaceID	Interface ID string, can be get from TY_INTERFACE_INFO.
out	value	True if the interface exists.

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_NULL_POINTER	ifaceID or outHandle is NULL.

## See also

TYGetInterfaceList

# 5.1.5.40 TYLibVersion()

Get current library version.

## **Parameters**

out	version	Version infomation to be filled.
-----	---------	----------------------------------

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NULL_POINTER	buffer is NULL.

# 5.1.5.41 TYOpenDevice()

Open device by device ID.

#### **Parameters**

in	ifaceHandle	Interface handle.
in	deviceID	Device ID string, can be get from TY_DEVICE_BASE_INFO.
out	deviceHandle	Handle of opened device. Valid only if TY_STATUS_OK or TY_FW_ERRORCODE returned.
out	outFwErrorcode	Firmware errorcode. Valid only if TY_FW_ERRORCODE returned.

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	deviceID or deviceHandle is NULL.
TY_STATUS_INVALID_PARAMETER	Device not found.
TY_STATUS_BUSY	Device has been opened.
TY_STATUS_DEVICE_ERROR	Open device failed.

# 5.1.5.42 TYOpenDeviceWithIP()

Open device by device IP, useful when a device is not listed.

#### **Parameters**

in	ifaceHandle	Interface handle.
in	IP	Device IP.
out	deviceHandle	Handle of opened device.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.
TY_STATUS_NULL_POINTER	IP or deviceHandle is NULL.
TY_STATUS_INVALID_PARAMETER	Device not found.
TY_STATUS_BUSY	Device has been opened, may occupied somewhere else.
TY_STATUS_DEVICE_ERROR	Open device failed.

## 5.1.5.43 TYOpenInterface()

Open specified interface.

## **Parameters**

in	ifaceID	Interface ID string, can be get from TY_INTERFACE_INFO.
out	outHandle	Handle of opened interface.

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_NULL_POINTER	ifaceID or outHandle is NULL.
TY_STATUS_INVALID_INTERFACE	Interface not found.

## See also

## **TYGetInterfaceList**

# 5.1.5.44 TYRegisterEventCallback()

Register device status callback. Register NULL to clean callback.

#### **Parameters**

in	hDevice	Device handle.
in	callback	Callback function.
in	userdata	User private data.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_BUSY	Device is capturing.

# 5.1.5.45 TYRegisterImuCallback()

Register imu callback. Register NULL to clean callback.

## **Parameters**

in	hDevice	Device handle.
in	callback	Callback function.
in	userdata	User private data.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_BUSY	Device is capturing.

# 5.1.5.46 TYSendSoftTrigger()

Send a software trigger to capture a frame when device works in trigger mode.

## **Parameters**

in <i>hDevice</i>	Device handle.
-------------------	----------------

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_FEATURE	Not support soft trigger.
TY_STATUS_IDLE	Device has not started capture.
TY_STATUS_WRONG_MODE	Not in trigger mode.

# 5.1.5.47 TYSetBool()

```
TY_CAPI TYSetBool (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

bool value )
```

Set value of bool feature.

## **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Bool value.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BOOL.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

# 5.1.5.48 TYSetByteArray()

```
TY_CAPI TYSetByteArray (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

const uint8_t * pBuffer,

uint32_t bufferSize )
```

Write byte array to device.

# **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
out	pbuffer	byte buffer.
in	bufferSize	Size of buffer.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_BYTEARRAY.
TY_STATUS_NULL_POINTER	pbuffer is NULL.
TY_STATUS_WRONG_SIZE	bufferSize incorrect.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

## 5.1.5.49 TYSetEnum()

```
TY_CAPI TYSetEnum (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

uint32_t value )
```

Set value of enum feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Enum value.

# Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_ENUM.
TY_STATUS_INVALID_PARAMETER	value is invalid.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

# 5.1.5.50 TYSetFloat()

```
TY_CAPI TYSetFloat (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

float value )
```

## Set value of float feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Float value.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_FLOAT.
TY_STATUS_OUT_OF_RANGE	value is out of range.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

# 5.1.5.51 TYSetInt()

```
TY_CAPI TYSetInt (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,
```

```
TY_FEATURE_ID featureID,
int32_t value )
```

# Set value of integer feature.

## **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	value	Integer value.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_INT.
TY_STATUS_OUT_OF_RANGE	value is out of range.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

# 5.1.5.52 TYSetString()

```
TY_CAPI TYSetString (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

const char * buffer )
```

# Set value of string feature.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	buffer	String buffer.

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRING.

# Return values

TY_STATUS_NULL_POINTER	buffer is NULL.	
TY_STATUS_OUT_OF_RANGE	Input string is too long.	
TY_STATUS_BUSY	Device is capturing, the feature is locked.	

# 5.1.5.53 TYSetStruct()

```
TY_CAPI TYSetStruct (

TY_DEV_HANDLE hDevice,

TY_COMPONENT_ID componentID,

TY_FEATURE_ID featureID,

void * pStruct,

uint32_t structSize )
```

#### Set value of struct.

#### **Parameters**

in	hDevice	Device handle.
in	componentID	Component ID.
in	featureID	Feature ID.
in	pStruct	Pointer of struct.
in	structSize	Size of struct.

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	Invalid component ID.
TY_STATUS_INVALID_FEATURE	Invalid feature ID.
TY_STATUS_NOT_PERMITTED	The feature is not writable.
TY_STATUS_WRONG_TYPE	The feature's type is not TY_FEATURE_STRUCT.
TY_STATUS_NULL_POINTER	pStruct is NULL.
TY_STATUS_WRONG_SIZE	structSize incorrect.
TY_STATUS_BUSY	Device is capturing, the feature is locked.

# 5.1.5.54 TYStartCapture()

# Start capture.

# **Parameters**

in	hDevice	Device handle.
in	hDevice	Device handle.

## **Return values**

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_INVALID_COMPONENT	No components enabled.
TY_STATUS_BUSY	Device has been started.
TY_STATUS_DEVICE_ERROR	Start capture failed.

# 5.1.5.55 TYStopCapture()

# Stop capture.

## **Parameters**

in	hDevice	Device handle.
----	---------	----------------

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_INVALID_HANDLE	Invalid device handle.
TY_STATUS_IDLE	Device is not capturing.
TY_STATUS_DEVICE_ERROR	Stop capture failed.

# 5.1.5.56 TYUpdateAllDeviceList()

```
TY_CAPI TYUpdateAllDeviceList ( )
```

Update current connected devices.

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.

# 5.1.5.57 TYUpdateDeviceList()

Update current connected devices.

## **Parameters**

in	ifaceHandle	Interface handle.
----	-------------	-------------------

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.
TY_STATUS_INVALID_INTERFACE	Invalid interface handle.

# 5.1.5.58 TYUpdateInterfaceList()

```
TY_CAPI TYUpdateInterfaceList ( )
```

Update current interfaces. call before TYGetInterfaceList.

# Return values

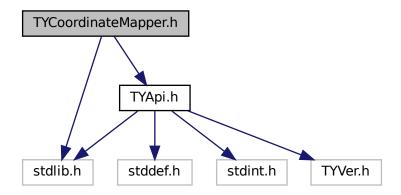
TY_STATUS_OK	Succeed.
TY_STATUS_NOT_INITED	TYInitLib not called.

# 5.2 TYCoordinateMapper.h File Reference

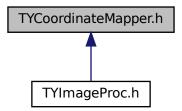
Coordinate Conversion API.

```
#include <stdlib.h>
#include "TYApi.h"
```

Include dependency graph for TYCoordinateMapper.h:



This graph shows which files directly or indirectly include this file:



## **Classes**

- struct TY\_PIXEL\_DESC
- struct TY\_PIXEL\_COLOR\_DESC

# **Macros**

• #define TYMAP\_CHECKRET(f, bufToFree)

# **Typedefs**

- typedef struct TY\_PIXEL\_DESC TY\_PIXEL\_DESC
- typedef struct TY\_PIXEL\_COLOR\_DESC TY\_PIXEL\_COLOR\_DESC

#### **Functions**

TY\_CAPI TYInvertExtrinsic (const TY\_CAMERA\_EXTRINSIC \*orgExtrinsic, TY\_CAMERA\_EXTRINSIC \*invExtrinsic)

Calculate 4x4 extrinsic matrix's inverse matrix.

TY\_CAPI TYMapDepthToPoint3d (const TY\_CAMERA\_CALIB\_INFO \*src\_calib, uint32\_t depthW, uint32
 \_t depthH, const TY\_PIXEL\_DESC \*depthPixels, uint32\_t count, TY\_VECT\_3F \*point3d, float f\_scale\_
 unit=1.0f)

Map pixels on depth image to 3D points.

TY\_CAPI TYMapPoint3dToDepth (const TY\_CAMERA\_CALIB\_INFO \*dst\_calib, const TY\_VECT\_3F \*point3d, uint32\_t count, uint32\_t depthW, uint32\_t depthH, TY\_PIXEL\_DESC \*depth, float f\_scale\_← unit=1.0f)

Map 3D points to pixels on depth image. Reverse operation of TYMapDepthToPoint3d.

TY\_CAPI TYMapDepthImageToPoint3d (const TY\_CAMERA\_CALIB\_INFO \*src\_calib, int32\_t imageW, int32\_t imageH, const uint16\_t \*depth, TY\_VECT\_3F \*point3d, float f\_scale\_unit=1.0f)

Map depth image to 3D points. 0 depth pixels maps to (NAN, NAN, NAN).

TY\_CAPI TYMapPoint3dToDepthImage (const TY\_CAMERA\_CALIB\_INFO \*dst\_calib, const TY\_VECT\_3F \*point3d, uint32\_t count, uint32\_t depthW, uint32\_t depthH, uint16\_t \*depth, float f\_target\_scale=1.0f)

Map 3D points to depth image. (NAN, NAN, NAN) will be skipped.

TY\_CAPI TYMapPoint3dToPoint3d (const TY\_CAMERA\_EXTRINSIC \*extrinsic, const TY\_VECT\_3F \*point3dFrom, int32\_t count, TY\_VECT\_3F \*point3dTo)

Map 3D points to another coordinate.

## 5.2.1 Detailed Description

Coordinate Conversion API.

Note

Considering performance, we leave the responsibility of parameters check to users.

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#### 5.2.2 Macro Definition Documentation

#### 5.2.2.1 TYMAP\_CHECKRET

```
#define TYMAP_CHECKRET(
     f,
     bufToFree )
```

#### Value:

```
do{
    TY_STATUS err = (f); \
    if(err){ \
        if(bufToFree) \
            free(bufToFree); \
        return err; \
    } \
    while(0)
```

Definition at line 268 of file TYCoordinateMapper.h.

# 5.2.3 Function Documentation

# 5.2.3.1 TYInvertExtrinsic()

Calculate 4x4 extrinsic matrix's inverse matrix.

## **Parameters**

in	orgExtrinsic	Input extrinsic matrix.	
out	invExtrinsic	Inverse matrix.	

## Return values

TY_STATUS_OK	Succeed.
TY_STATUS_ERROR	Calculation failed.

# 5.2.3.2 TYMapDepthImageToPoint3d()

Map depth image to 3D points. 0 depth pixels maps to (NAN, NAN, NAN).

## **Parameters**

in	src_calib	Depth image's calibration data.
in	depthW	Width of depth image.
in	depthH	Height of depth image.
in	depth	Depth image.
out	point3d	Output point3D image.

TY_STATUS_OK S	Succeed.
----------------	----------

## 5.2.3.3 TYMapDepthToPoint3d()

Map pixels on depth image to 3D points.

#### **Parameters**

in	src_calib	Depth image's calibration data.
in	depthW	Width of depth image.
in	depthH	Height of depth image.
in	depthPixels	Pixels on depth image.
in	count	Number of depth pixels.
out	point3d	Output point3D.

#### Return values

TY_STATUS_OK	Succeed.
--------------	----------

# 5.2.3.4 TYMapPoint3dToDepth()

Map 3D points to pixels on depth image. Reverse operation of TYMapDepthToPoint3d.

#### **Parameters**

in	dst_calib	Target depth image's calibration data.
in	point3d	Input 3D points.
in	count	Number of points.
in	depthW	Width of target depth image.
in	depthH	Height of target depth image.
out	depth	Output depth pixels.

#### Return values

```
TY_STATUS_OK Succeed.
```

## 5.2.3.5 TYMapPoint3dToDepthImage()

Map 3D points to depth image. (NAN, NAN, NAN) will be skipped.

#### **Parameters**

in	dst_calib	Target depth image's calibration data.
in	point3d	Input 3D points.
in	count	Number of points.
in	depthW	Width of target depth image.
in	depthH	Height of target depth image.
in,out	depth	Depth image buffer.

#### **Return values**

```
TY_STATUS_OK Succeed.
```

## 5.2.3.6 TYMapPoint3dToPoint3d()

Map 3D points to another coordinate.

## **Parameters**

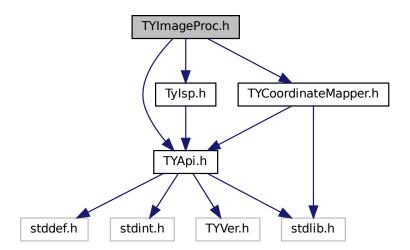
in	extrinsic	Extrinsic matrix.
in	point3dFrom	Source 3D points.
in	count	Number of source 3D points.
out	point3dTo	Target 3D points.

## Return values

TY STATUS OK	Succeed.
--------------	----------

# 5.3 TYImageProc.h File Reference

```
#include "TYApi.h"
#include "TYCoordinateMapper.h"
#include "TyIsp.h"
Include dependency graph for TYImageProc.h:
```



## Classes

- struct DepthSpeckleFilterParameters default parameter value definition
- struct DepthEnhenceParameters default parameter value definition

# Macros

- #define DepthSpeckleFilterParameters\_Initializer {150, 64}
- #define DepthEnhenceParameters\_Initializer {10, 20, 10, 0.1f}

#### **Functions**

• TY\_CAPI TYImageProcesAcceEnable (bool en)

Image processing acceleration switch.

• TY\_CAPI TYUndistortImage (const TY\_CAMERA\_CALIB\_INFO \*srcCalibInfo, const TY\_IMAGE\_DATA \*srcImage, const TY\_CAMERA\_INTRINSIC \*cameraNewIntrinsic, TY\_IMAGE\_DATA \*dstImage)

Do image undistortion, only support  $TY\_PIXEL\_FORMAT\_MONO$ ,  $TY\_PIXEL\_FORMAT\_RGB$ ,  $TY\_PIXEL\_FORM \leftarrow AT\_BGR$ .

TY\_CAPI TYDepthSpeckleFilter (TY\_IMAGE\_DATA \*depthImage, const DepthSpeckleFilterParameters \*param)

Remove speckles on depth image.

TY\_CAPI TYDepthEnhenceFilter (const TY\_IMAGE\_DATA \*depthImages, int imageNum, TY\_IMAGE\_DATA \*guide, TY\_IMAGE\_DATA \*output, const DepthEnhenceParameters \*param)

Remove speckles on depth image.

# 5.3.1 Detailed Description

Image post-process API

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#### 5.3.2 Function Documentation

#### 5.3.2.1 TYDepthEnhenceFilter()

Remove speckles on depth image.

## **Parameters**

in	depthlmage	Pointer to depth image array.
in	imageNum	Depth image array size.
in,out	guide	Guide image.
out	output	Output depth image.
in	param	Algorithm parameters.

TY STATUS OK	Succeed.

## Return values

TY_STATUS_NULL_POINTER	Any depthImage, param, output or output->buffer is NULL.
TY_STATUS_INVALID_PARAMETER	imageNum >= 11 or imageNum <= 0, or any image invalid
TY_STATUS_OUT_OF_MEMORY	Output image not suitable.

## 5.3.2.2 TYDepthSpeckleFilter()

Remove speckles on depth image.

#### **Parameters**

in,out	depthImage	Depth image to be processed.
in	param	Algorithm parameters.

#### Return values

TY_STATUS_OK	Succeed.
TY_STATUS_NULL_POINTER	Any depth, param or depth->buffer is NULL.
TY_STATUS_INVALID_PARAMETER	param->max_speckle_size <= 0 or param->max_speckle_diff <= 0

## 5.3.2.3 TYImageProcesAcceEnable()

```
TY_CAPI TYImageProcesAcceEnable ( bool en )
```

Image processing acceleration switch.

## **Parameters**

```
in en Enable image process acceleration switch
```

# 5.3.2.4 TYUndistortImage()

```
const TY_IMAGE_DATA * srcImage,
const TY_CAMERA_INTRINSIC * cameraNewIntrinsic,
TY_IMAGE_DATA * dstImage )
```

Do image undistortion, only support TY\_PIXEL\_FORMAT\_MONO , TY\_PIXEL\_FORMAT\_RGB, TY\_PIXEL\_FOR  $\mbox{\ \ }$  MAT\_BGR.

#### **Parameters**

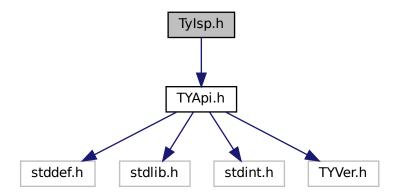
in	srcCalibInfo	Image calibration data.
in	srcImage	Source image.
in	cameraNewIntrinsic	Expected new image intrinsic, will use srcCalibInfo for new image intrinsic if set to NULL.
out	dstImage	Output image.

## Return values

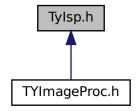
TY_STATUS_OK	Succeed.
TY_STATUS_NULL_POINTER	Any srcCalibInfo, srcImage, dstImage, srcImage->buffer, dstImage->buffer is NULL.
TY_STATUS_INVALID_PARAMETER	Invalid srcImage->width, srcImage->height, dstImage->width, dstImage->height or unsupported pixel format.

# 5.4 Tylsp.h File Reference

#include "TYApi.h"
Include dependency graph for Tylsp.h:



This graph shows which files directly or indirectly include this file:



#### **Classes**

struct TY\_ISP\_FEATURE\_INFO

#### **Macros**

• #define TYISP\_CAPI TY\_CAPI

#### **Typedefs**

typedef void \* TY\_ISP\_HANDLE

## **Enumerations**

• enum TY ISP FEATURE ID {

**TY\_ISP\_FEATURE\_CAM\_MODEL** = 0x0000000, TY\_ISP\_FEATURE\_CAM\_DEV\_HANDLE = 0x0000001, TY\_ISP\_FEATURE\_CAM\_DEV\_COMPONENT = 0x0000002, TY\_ISP\_FEATURE\_IMAGE\_SIZE = 0x000100,

TY\_ISP\_FEATURE\_WHITEBALANCE\_GAIN = 0x000200, TY\_ISP\_FEATURE\_ENABLE\_AUTO\_WHIT  $\leftarrow$  EBALANCE = 0x000300, TY\_ISP\_FEATURE\_SHADING = 0x000400, TY\_ISP\_FEATURE\_SHADING\_C  $\leftarrow$  ENTER = 0x000500,

TY\_ISP\_FEATURE\_BLACK\_LEVEL = 0x000600, TY\_ISP\_FEATURE\_BLACK\_LEVEL\_COLUMN = 0x000610, TY\_ISP\_FEATURE\_BLACK\_LEVEL\_GAIN = 0x000700, TY\_ISP\_FEATURE\_BLACK\_LEV \( \) EL GAIN COLUMN = 0x000710,

TY\_ISP\_FEATURE\_CCM = 0x000C00, TY\_ISP\_FEATURE\_CCM\_ENABLE = 0x000C10, TY\_ISP\_FEAT ← URE BRIGHT = 0x000D00, TY\_ISP\_FEATURE\_CONTRAST = 0x000E00,

TY\_ISP\_FEATURE\_AUTOBRIGHT = 0x000F00, TY\_ISP\_FEATURE\_INPUT\_RESAMPLE\_SCALE = 0x001000, TY\_ISP\_FEATURE\_ENABLE\_AUTO\_EXPOSURE\_GAIN = 0x001100, TY\_ISP\_FEATUR ← E\_AUTO\_EXPOSURE\_RANGE = 0x001200,

TY\_ISP\_FEATURE\_AUTO\_GAIN\_RANGE = 0x001300, TY\_ISP\_FEATURE\_AUTO\_EXPOSURE\_UPDA ← TE\_INTERVAL = 0x001400, TY\_ISP\_FEATURE\_DEBUG\_LOG = 0xff000000 }

- enum TY\_ISP\_BAYER\_PATTERN {
   TY\_ISP\_BAYER\_GB = 0, TY\_ISP\_BAYER\_BG = 1, TY\_ISP\_BAYER\_RG = 2, TY\_ISP\_BAYER\_GR = 3,
   TY\_ISP\_BAYER\_AUTO = 0xff }
- enum TY\_DEMOSAIC\_METHOD { TY\_DEMOSAIC\_METHOD\_SIMPLE = 0, TY\_DEMOSAIC\_METHOD ←
   \_BILINEAR = 1, TY\_DEMOSAIC\_METHOD\_HQLINEAR = 2, TY\_DEMOSAIC\_METHOD\_EDGESENSE =
   3 }

#### **Functions**

- TYISP\_CAPI TYISPCreate (TY\_ISP\_HANDLE \*handle)
- TYISP\_CAPI **TYISPRelease** (TY\_ISP\_HANDLE \*handle)
- TYISP\_CAPI TYISPLoadConfig (TY\_ISP\_HANDLE handle, const uint8\_t \*config, uint32\_t config\_size)
- TYISP\_CAPI TYISPUpdateDevice (TY\_ISP\_HANDLE handle)
  - called by main thread to update & control device status for ISP
- TYISP\_CAPI **TYISPSetFeature** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_ID feature\_id, const uint8 ← \_\_t \*data, int32\_t size)
- TYISP\_CAPI **TYISPGetFeature** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_ID feature\_id, uint8\_← t \*data\_buff, int32\_t buff\_size)
- TYISP\_CAPI **TYISPGetFeatureSize** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_ID feature\_id, int32\_t \*size)
- TYISP CAPI TYISPHasFeature (TY ISP HANDLE handle, TY ISP FEATURE ID feature id)
- TYISP\_CAPI **TYISPGetFeatureInfoList** (TY\_ISP\_HANDLE handle, TY\_ISP\_FEATURE\_INFO \*info\_buffer, int buffer size)
- TYISP CAPI **TYISPGetFeatureInfoListSize** (TY\_ISP\_HANDLE handle, int32\_t \*buffer\_size)

convert bayer raw image to rgb image, output buffer is allocated by invoker

## 5.4.1 Detailed Description

this file Include interface declare for raw color image (bayer format) process functions

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# 5.4.2 Enumeration Type Documentation

#### 5.4.2.1 TY\_ISP\_FEATURE\_ID

enum TY\_ISP\_FEATURE\_ID

#### Enumerator

TV ICD FEATURE CAM DEV HANDLE	davias bandla for davias santral
TY_ISP_FEATURE_CAM_DEV_HANDLE	device handle for device control
TY_ISP_FEATURE_CAM_DEV_COMPONENT	the component to control
TY_ISP_FEATURE_IMAGE_SIZE	image size width&height
TY_ISP_FEATURE_BLACK_LEVEL	global black level
TY_ISP_FEATURE_BLACK_LEVEL_COLUMN	to set different black level for each image column
TY_ISP_FEATURE_BLACK_LEVEL_GAIN	global pixel gain
TY_ISP_FEATURE_BLACK_LEVEL_GAIN_COLUMN	to set different gain for each image column
TY_ISP_FEATURE_CCM_ENABLE	ENABLE CCM.
TY_ISP_FEATURE_AUTO_EXPOSURE_RANGE	exposure range ,default no limit
TY_ISP_FEATURE_AUTO_GAIN_RANGE	gain range ,default no limit
TY_ISP_FEATURE_AUTO_EXPOSURE_UPDATE_INT↔	update device exposure interval, default 5 frame
ERVAL	
TY_ISP_FEATURE_DEBUG_LOG	display detail log information

Definition at line 17 of file Tylsp.h.

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