Zon Aslett + Palasponer Physics 513R Linear Alyebra Group -u" + Vu' = f(x) V=8 U(0)=u(1)=0 f(x)=1 \$(x) is snooth
\$(0) = \$(1) = 0 - Jou"dx + Joru'dx = Jodx Sø'u'dx + V søu'dx = Sødx $A_{1}(u, \phi) = \int \phi' u' dx$ $A_{2}(u, \phi) = \int \phi \phi u' dx$ $F(\phi) = \int \phi dx$ $A(u, \phi) + A_2(u, \phi) = F(\phi) \Rightarrow A(u, \phi) = F(\phi)$ b) let $u(x) = \sum_{i=1}^{n} u_i \phi_i(x)$ A(\$ u. 4. (x) () = F(6) $\sum_{i} u_i A(\phi_i, \phi_i) = F(\phi_i) \qquad |e + \hat{A}_{i} = A(\phi_i, \phi_i)$ x: = u; b: = F(d;) & = b

X X: Y3-1 Y:-1 X;41 = (4' · 6' dx 011 $\phi'_{:}$ 1/4 y; _1 Xi -1/3 for j= i+1 for j=i-1 $\int_{i}^{d} dx = \frac{2}{h} \quad \text{for } j=i$ otherwise 0

A2 (0, 0) = 8 (0. 0, 0x ·- 1/h 2/ ۱-۱, ۱-ذ elsenhere 4. Ax = b let M = A,

M'Ax = M'b

Ax = B

let M'A = A

M'b = B

How Hese two equations

Pare equivalent. However they w:11 not necessarily

Produce He Some residuals.

b) even though they require a matrix invesse, A

can be chosen such that it's inverse is relatedly

Simple to Compute

· ...

```
function [A,b] = popMatrices(n, gamma)
    h = 1/n;
    A = diag((2/h)*ones(1,n)) + diag((-1/h-gamma/2)*ones(1,n-1),-1) +
diag((-1/h+gamma/2)*ones(1,n-1),1);
    b = zeros(n,1) + h;
    b(1) = h/2;
    b(end) = h/2;

Not enough input arguments.

Error in popMatrices (line 2)
    h = 1/n;
```

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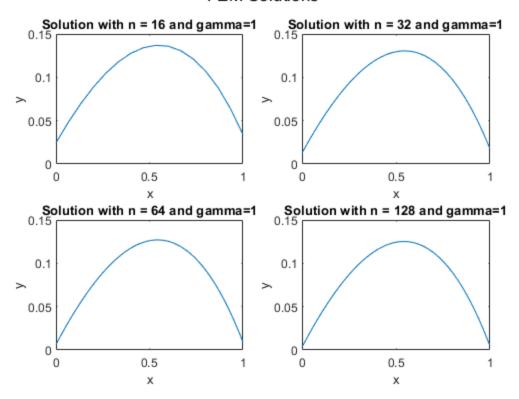
```
A=randi([10 100], 100, 100);
n = 100;
x0 = A(3,:)';
M = eye(100);

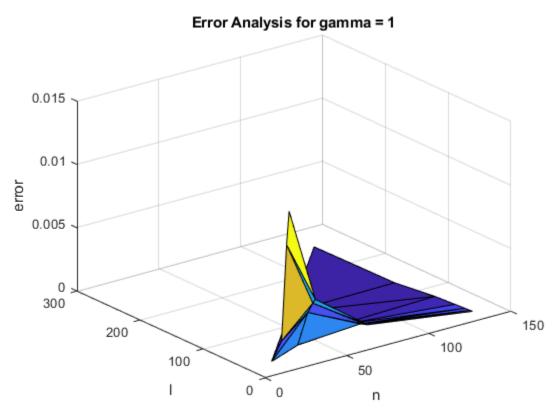
if det(A) ~=0
    b = randi([10 100],100, 1);
    maxit = 100;
    tol=1e-1;
    [sol,xs,ys,Vs,Hs] = gmres_matlab(A,b,maxit,x0, M, n);
end
diff = b - A*sol;
```

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```
gamma = 1
figure(1)
count = 1;
errMat = [];%[n l error]
sgtitle('FEM Solutions')
for n = [16, 32, 64, 128]
    1 = 2;
    error = 1;
    [A,b] = popMatrices(n,1);
    x0 = zeros(n,1);
    M = eye(n);
    while error > 10^(-6)
        [sol,xs,ys,Vs,Hs] = gmres_matlab(A,b,l,x0, M, n);
        res = b - A*sol;
        error = norm(res)/n;
        1 = 1 * 2;
        errMat(end+1,:) = [n l error];
    end
    x = linspace(0,1,n);
    subplot(2,2,count)
    plot(x,sol)
    title(sprintf('Solution with n = %d and gamma=1',n))
    xlabel('x')
    ylabel('y')
    count = count + 1;
end
figure(2)
x = errMat(:,1);
y = errMat(:,2);
z = errMat(:,3);
dt = delaunayTriangulation(x,y) ;
tri = dt.ConnectivityList ;
trisurf(tri,x,y,z)
title('Error Analysis for gamma = 1')
xlabel('n')
ylabel('1')
zlabel('error')
```

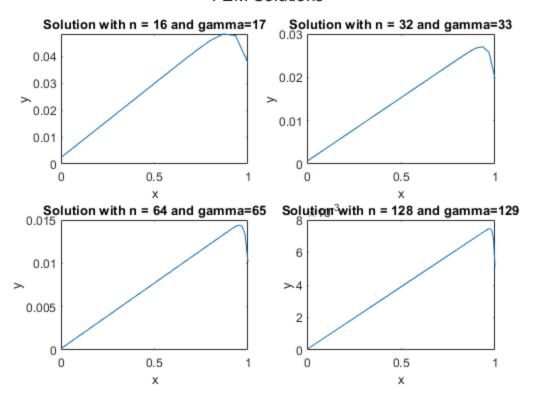
FEM Solutions

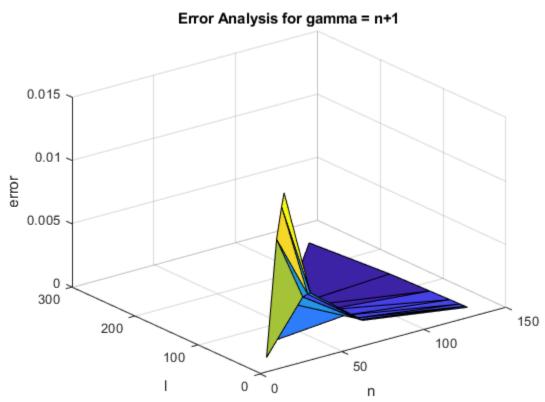




```
gamma = n + 1
figure(3)
count = 1;
errMat = [];%[n l error]
sgtitle('FEM Solutions')
for n = [16, 32, 64, 128]
    1 = 2;
    error = 1;
    [A,b] = popMatrices(n,n+1);
    x0 = zeros(n,1);
    M = eye(n);
    while error > 10^(-6)
        [sol,xs,ys,Vs,Hs] = gmres_matlab(A,b,l,x0, M, n);
        res = b - A*sol;
        error = norm(res)/n;
        1 = 1 * 2;
        errMat(end+1,:) = [n l error];
    end
    x = linspace(0,1,n);
    subplot(2,2,count)
    plot(x,sol)
    title(sprintf('Solution with n = %d and gamma=%d',n,n+1))
    xlabel('x')
    ylabel('y')
    count = count + 1;
end
figure(4)
x = errMat(:,1);
y = errMat(:,2);
z = errMat(:,3);
dt = delaunayTriangulation(x,y) ;
tri = dt.ConnectivityList ;
trisurf(tri,x,y,z)
title('Error Analysis for gamma = n+1')
xlabel('n')
ylabel('1')
zlabel('error')
```

FEM Solutions

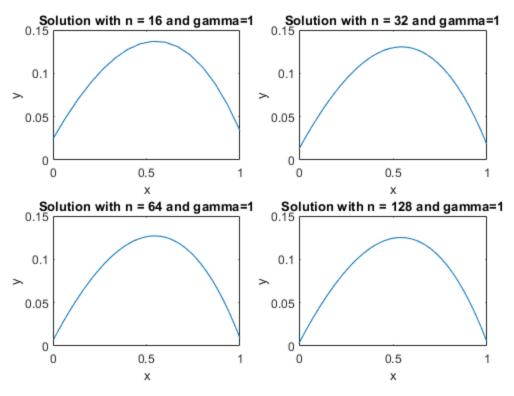


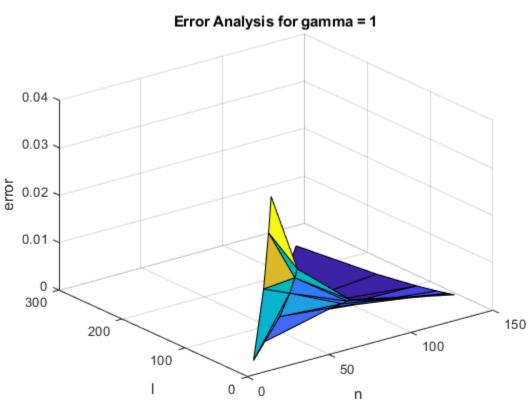




```
gamma = 1
figure(1)
count = 1;
errMat = [];%[n l error]
sgtitle('Conditioned FEM Solutions')
for n = [16, 32, 64, 128]
    1 = 2;
    error = 1;
    [A,b] = popMatrices(n,1);
    x0 = zeros(n,1);
    M = eye(n);
    [L,\sim] = ilu(sparse(A));
    while error > 10^(-6)
        [sol,xs,ys,Vs,Hs] = gmres_matlab(inv(L)*A,inv(L)*b,l,x0, M,
 n);
        res = b - A*sol;
        error = norm(res)/n;
        1 = 1 * 2;
        errMat(end+1,:) = [n l error];
    end
    x = linspace(0,1,n);
    subplot(2,2,count)
    plot(x,sol)
    title(sprintf('Solution with n = %d and gamma=1',n))
    xlabel('x')
    ylabel('y')
    count = count + 1;
end
figure(2)
x = errMat(:,1);
y = errMat(:,2);
z = errMat(:,3);
dt = delaunayTriangulation(x,y) ;
tri = dt.ConnectivityList ;
trisurf(tri,x,y,z)
title('Error Analysis for gamma = 1')
xlabel('n')
ylabel('1')
zlabel('error')
```

Conditioned FEM Solutions





```
gamma = n + 1
figure(3)
count = 1;
errMat = [];%[n l error]
sgtitle('Conditioned FEM Solutions')
for n = [16, 32, 64, 128]
    1 = 2;
    error = 1;
    [A,b] = popMatrices(n,n+1);
    x0 = zeros(n,1);
    M = eye(n);
    [L,\sim] = ilu(sparse(A));
    while error > 10^{(-6)}
        [sol,xs,ys,Vs,Hs] = gmres_matlab(inv(L)*A,inv(L)*b,l,x0, M,
 n);
        res = b - A*sol;
        error = norm(res)/n;
        1 = 1 * 2;
        errMat(end+1,:) = [n l error];
    end
    x = linspace(0,1,n);
    subplot(2,2,count)
    plot(x,sol)
    title(sprintf('Solution with n = %d and gamma=1',n))
    xlabel('x')
    ylabel('y')
    count = count + 1;
end
figure(4)
x = errMat(:,1);
y = errMat(:,2);
z = errMat(:,3);
dt = delaunayTriangulation(x,y) ;
tri = dt.ConnectivityList ;
trisurf(tri,x,y,z)
title('Error Analysis for gamma = n+1')
xlabel('n')
ylabel('1')
zlabel('error')
The conditioned method converges MUCH quicker than the nonconditioned
%method. This is because the condition number is greatly improved when
%left multiply by the triangular matrix L on both sides of the
 equation.
```

Conditioned FEM Solutions

