

Arduino Distance Driver

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1 Hierarchical Index

1.1 Class Hierarchy

This inheritance list is sorted roughly, but not completely, alphabetically:

DistanceSensor	2
-----------------------	----------

UltrasoundDistanceSensor	3
---------------------------------	----------

2 Class Index

2.1 Class List

Here are the classes, structs, unions and interfaces with brief descriptions:

DistanceSensor	
Arduino - Distance sensor	2
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3 File Index

3.1 File List

Here is a list of all files with brief descriptions:

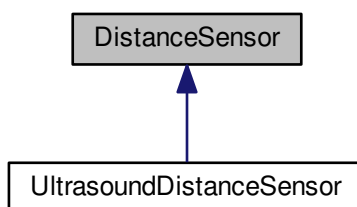
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4 Class Documentation

4.1 DistanceSensor Class Reference

```
#include <DistanceSensor.h>
```

Inheritance diagram for DistanceSensor:



Public Member Functions

- virtual float [getDistance](#) ()=0

4.1.1 Detailed Description

Arduino - Distance sensor.

[DistanceSensor.h](#)

The abstract class for the distance sensors.

Author

Dalmir da Silva dalmirdasilva@gmail.com

Definition at line 14 of file [DistanceSensor.h](#).

4.1.2 Member Function Documentation

4.1.2.1 virtual float DistanceSensor::getDistance () [pure virtual]

Gets the distance o the device from whatever is in front of it.

The distance in centimeters.

Implemented in [UltrasoundDistanceSensor](#).

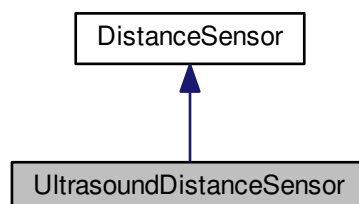
The documentation for this class was generated from the following file:

- [DistanceSensor.h](#)

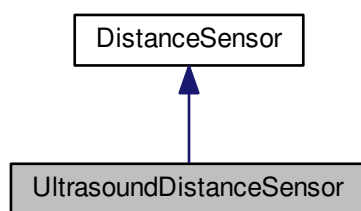
4.2 **UltrasoundDistanceSensor Class Reference**

```
#include <UltrasoundDistanceSensor.h>
```

Inheritance diagram for UltrasoundDistanceSensor:



Collaboration diagram for `UltrasoundDistanceSensor`:



Public Member Functions

- `UltrasoundDistanceSensor` (unsigned char `echoPin`, unsigned char `trigPin`)
- unsigned long `getEchoTime` ()
- float `getDistance` ()

Private Attributes

- unsigned char `echoPin`
- unsigned char `trigPin`

4.2.1 Detailed Description

Definition at line 44 of file `UltrasoundDistanceSensor.h`.

4.2.2 Constructor & Destructor Documentation

4.2.2.1 `UltrasoundDistanceSensor::UltrasoundDistanceSensor` (unsigned char `echoPin`, unsigned char `trigPin`)

Public constructor.

Parameters

<code>echoPin</code>	The echo pin.
<code>trigPin</code>	The trigger pin.

Definition at line 17 of file `UltrasoundDistanceSensor.cpp`.

4.2.3 Member Function Documentation

4.2.3.1 float `UltrasoundDistanceSensor::getDistance` () [virtual]

Gets the distance o the device from whatever is in front of it.

The distance in centimeters.

Implements `DistanceSensor`.

Definition at line 29 of file `UltrasoundDistanceSensor.cpp`.

4.2.3.2 unsigned long UltrasoundDistanceSensor::getEchoTime ()

Gets the time between the send and reice the sound.

The time between the send and reice the sound.

Definition at line 22 of file [UltrasoundDistanceSensor.cpp](#).

4.2.4 Member Data Documentation

4.2.4.1 unsigned char UltrasoundDistanceSensor::echoPin [private]

The echo pin.

Definition at line 50 of file [UltrasoundDistanceSensor.h](#).

4.2.4.2 unsigned char UltrasoundDistanceSensor::trigPin [private]

The trig pin.

Definition at line 55 of file [UltrasoundDistanceSensor.h](#).

The documentation for this class was generated from the following files:

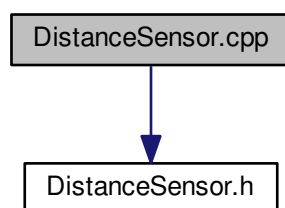
- [UltrasoundDistanceSensor.h](#)
- [UltrasoundDistanceSensor.cpp](#)

5 File Documentation

5.1 DistanceSensor.cpp File Reference

```
#include <DistanceSensor.h>
```

Include dependency graph for DistanceSensor.cpp:



Macros

- `#define __ARDUINO_DRIVER_DISTANCE_SENSOR_CPP__ 1`

5.1.1 Macro Definition Documentation

5.1.1.1 `#define __ARDUINO_DRIVER_DISTANCE_SENSOR_CPP__ 1`

Arduino - Distance sensor.

DistanceSensor.cpp

The abstract class for the distance sensors.

Author

Dalmir da Silva dalmirdasilva@gmail.com

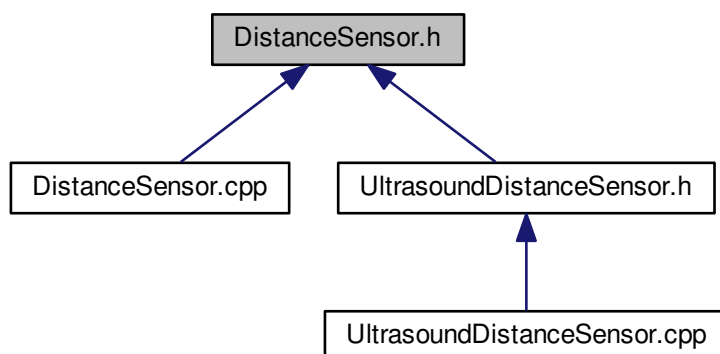
Definition at line 12 of file [DistanceSensor.cpp](#).

5.2 DistanceSensor.cpp

```
00001
00011 #ifndef __ARDUINO_DRIVER_DISTANCE_SENSOR_CPP__
00012 #define __ARDUINO_DRIVER_DISTANCE_SENSOR_CPP__ 1
00013
00014 #include <DistanceSensor.h>
00015
00016 #endif /* __ARDUINO_DRIVER_DISTANCE_SENSOR_CPP__ */
```

5.3 DistanceSensor.h File Reference

This graph shows which files directly or indirectly include this file:



Classes

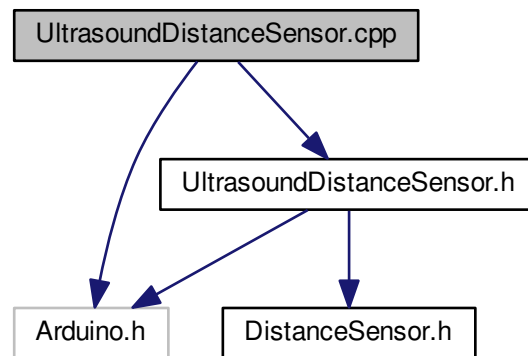
- class [DistanceSensor](#)

5.4 DistanceSensor.h

```
00001
00011 #ifndef __ARDUINO_DRIVER_DISTANCE_SENSOR_H__
00012 #define __ARDUINO_DRIVER_DISTANCE_SENSOR_H__ 1
00013
00014 class DistanceSensor {
00015 public:
00016     virtual float getDistance() = 0;
00023 };
00024
00025 #endif /* __ARDUINO_DRIVER_DISTANCE_SENSOR_H__ */
```

5.5 UltrasoundDistanceSensor.cpp File Reference

```
#include <Arduino.h>
#include <UltrasoundDistanceSensor.h>
Include dependency graph for UltrasoundDistanceSensor.cpp:
```



Macros

- `#define __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_CPP__ 1`

5.5.1 Macro Definition Documentation

5.5.1.1 `#define __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_CPP__ 1`

Arduino - Ultrasound distance sensor.

[UltrasoundDistanceSensor.cpp](#)

The abstract class for the ultrasound distance sensor.

Author

Dalmir da Silva dalmirdasilva@gmail.com

Definition at line 12 of file [UltrasoundDistanceSensor.cpp](#).

5.6 UltrasoundDistanceSensor.cpp

```
00001
00011 #ifndef __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_CPP__
00012 #define __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_CPP__ 1
00013
00014 #include <Arduino.h>
00015 #include <UltrasoundDistanceSensor.h>
00016
00017 UltrasoundDistanceSensor::UltrasoundDistanceSensor(
00018     unsigned char echoPin, unsigned char trigPin) : echoPin(echoPin), trigPin(trigPin) {
00019     pinMode(echoPin, INPUT);
00019     pinMode(trigPin, OUTPUT);
00020 }
00021
00022 unsigned long UltrasoundDistanceSensor::getEchoTime() {
00023     digitalWrite(trigPin, HIGH);
```



```

00024     delayMicroseconds(100);
00025     digitalWrite(trigPin, LOW);
00026     return pulseIn(echoPin, HIGH, US_SENSOR_PULSE_IN_TIMEOUT);
00027 }
00028
00029 float UltrasoundDistanceSensor::getDistance() {
00030     float time = (float) getEchoTime();
00031     return time / US_SENSOR_2_TIMES_US_PER_CM;
00032 }
00033
00034 #endif /* __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_CPP__ */

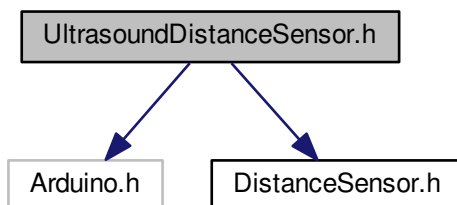
```

5.7 UltrasoundDistanceSensor.h File Reference

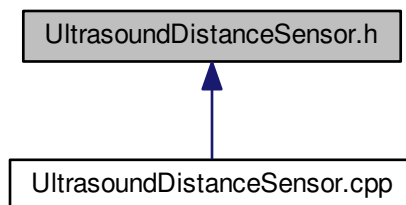
```
#include <Arduino.h>
```

```
#include <DistanceSensor.h>
```

Include dependency graph for UltrasoundDistanceSensor.h:



This graph shows which files directly or indirectly include this file:



Classes

- class [UltrasoundDistanceSensor](#)

Macros

- #define [US_SENSOR_CM_PER_US](#) 0.03463
- #define [US_SENSOR_US_PER_CM](#) 28.8
- #define [US_SENSOR_2_TIMES_US_PER_CM](#) 57.7
- #define [US_SENSOR_PULSE_IN_TIMEOUT](#) 11540.0

5.7.1 Macro Definition Documentation

5.7.1.1 `#define US_SENSOR_2_TIMES_US_PER_CM 57.7`

Doubles the time, counting the time to go and back.

$(US_SENSOR_US_PER_CM * 2)$

Definition at line 34 of file [UltrasoundDistanceSensor.h](#).

5.7.1.2 `#define US_SENSOR_CM_PER_US 0.03463`

Arduino - Ultrasound distance sensor.

[UltrasoundDistanceSensor.h](#)

The abstract class for the ultrasound distance sensor.

Author

Dalmir da Silva dalmirdasilva@gmail.com Centimeters per microsecond.

Definition at line 20 of file [UltrasoundDistanceSensor.h](#).

5.7.1.3 `#define US_SENSOR_PULSE_IN_TIMEOUT 11540.0`

2 meters How many microseconds can wait.

Enough to go and back 2 meters of distance.

$(US_SENSOR_2_TIMES_US_PER_CM * 2 * 100)$

Definition at line 42 of file [UltrasoundDistanceSensor.h](#).

5.7.1.4 `#define US_SENSOR_US_PER_CM 28.8`

Microseconds in 1 centimeter.

$(1 / US_SENSOR_CM_PER_US)$

Definition at line 27 of file [UltrasoundDistanceSensor.h](#).

5.8 UltrasoundDistanceSensor.h

```

00001
00011 #ifndef __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_H__
00012 #define __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_H__ 1
00013
00014 #include <Arduino.h>
00015 #include <DistanceSensor.h>
00016
00020 #define US_SENSOR_CM_PER_US 0.03463
00021
00027 #define US_SENSOR_US_PER_CM 28.8
00028
00034 #define US_SENSOR_2_TIMES_US_PER_CM 57.7
00035
00042 #define US_SENSOR_PULSE_IN_TIMEOUT 11540.0
00043
00044 class UltrasoundDistanceSensor : public DistanceSensor {
00045 private:
00046
00050     unsigned char echoPin;
00051
00055     unsigned char trigPin;
00056
00057 public:
00058
00065     UltrasoundDistanceSensor(unsigned char echoPin, unsigned char trigPin);
00066
00072     unsigned long getEchoTime();
00073
00079     float getDistance();

```

```
00080 };  
00081  
00082 #endif /* __ARDUINO_DRIVER_ULTRASOUND_DISTANCE_SENSOR_H__ */
```

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