

Detailed Instructions for CO2016 Coursework 1

Please note: the demonstration video is an example of image effect linearBox and phase-Shift.

When the template code ImageManipulation.java is run, an image appears on the screen as part of a GUI. The image coordinates of your mouse are (x,y); and note that x and y are also code variables. We define A(x,y) to be a square of width 2*size with center (x,y), where size is also a code variable. There is a code variable n too; more on that later.

You are going to write code for methods linearBox and linearOct. These should both produce image effects, as discussed in the lectures: thus they have one input parameter being the image, but also input parameters x, y, size, and n. Each ``effect'' is determined by ALL these parameters. The original image should change as you move your mouse around the image (see video): the value of (x,y) alters, and for each new value one of the methods is called, producing an image effect.

These effects involve moving/recoloring pixels as outlined in the lectures. Please read the slides carefully! Each method should not go through each pixel q and "move" it to its new position q' = Move(q). Each method should, however, go through each pixel p and either color it correctly, or calculate which pixel prep "will be moved" to the position of p. We call prep the PREIMAGE of p, so prep = MoveInverse(p). We then perform the ``move'' by setting the RGB of p to be the RGB of prep.

Both of these methods apply a specific image transformation, IMGTRANS. To explain IMGTRANS, consider a pixel-line with end-points O and P, and a point D on the line:

0
i
D
P
 xxxxxxxxxxxxyyyyyyyzzzzzAAAAAAAAAAAAAAAAABBBCCCCCCCCCCCCCCCCCCCC

After applying the transformation, the (new) pixels between 0 and D are coloured GRAY (g below). The original pixel at 0 moves to P, the pixel at D is fixed, and the pixels in between 0 and D are MOVED AND SCALED LINEARLY (*), each i to mi. So the output looks like

0
D
mi
P
 gggggggggggggggggggggggggggggggzzzzzyyyyyyyyyyyxxxxxxxxxxxxxxxxxxxxxxxx

and (*) means by definition that either of the ratios of distances below are equal

$$\begin{array}{lcl}
 \text{mi to P : D to P} & = & \text{0 to i : 0 to D} \quad (*) \\
 \text{D to mi : D to P} & = & \text{i to D : 0 to D} \quad (*)
 \end{array}$$

Note that, informally, the output pixels from D to P are like a stretched reflection (mirror at D facing 0) of the input pixels from 0 to D - this idea will help you visually when testing your code. mi is the reflection of i.

**** linearBox ****

linearBox parameters are

@param image	the image you are transforming
@param x	the x-coordinate of the centre of the square A(x,y)
@param y	the y-coordinate of the centre of the square A(x,y)
@param size	half the length/width of the square
@param n	see below

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linearBox SPECIFICATION: Check if $A(x,y)$ is contained within the given image.

If not the method has no effect (i.e. identity effect).

If $A(x,y)$ is contained within the image, then visible changes should be seen (i.e. a non-identity effect) but ONLY within $A(x,y)$. These changes result from applying IMGTRANS to each horizontal line of pixels in $A(x,y)$.

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To code up the SPECIFICATION

(i) Write code to check the containment of $A(x,y)$

(ii) Hence, if required, use a loop to visit each pixel (i,j) in $A(x,y)$.

(iii) Apply IMGTRANS: For (i,j) there is a horizontal line of pixels in $A(x,y)$ where

O is at the left side of the square $A(x,y)$

D is at $x+n$ (for a parameter $int\ n$)

P is at the right side of the square $A(x,y)$

and each pixel in the line has a downwards image coordinate j .

The tricky part is calculating the pixel movements; selecting and coloring grey pixels is easy. For the movements, if pixel p (on the line) at coordinate (i,j) is between D and P , then pixel $prep$ (on the line between O and D) has coordinate $(prei,j)$. Thus, crucial to the coding is working out $prei$ in terms of i , and this is what `linTrans` does.

Exercise: Work out prei in terms of i and 0, D and P. EITHER

--- by making use of (*) OR

--- since the scaling is LINEAR this means that

$$\text{prei} = g*i + k$$

a STRAIGHT LINE GRAPH with gradient g and ``prei intercept'' k. You know that if i=D then prei=D and if i=P then prei=0; from this you can work out g and k.

This should give you the code for method linTrans.

Note: Due to rounding/integer division effects you should compute prei with doubles and return the final result for prei as an int.

Note: prei is calculated ONLY for pixels between D and P. The original pixels between 0 and D are changed to gray.

Note: In the skeleton program, a copy, called temp, of the BufferedImage is made. Use the temp image to get the RGB values of pixels prep and set the RGB values of the BufferedImage image pixels p to these values; see lecture slides.

**** linear Oct ****

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linearOct SPECIFICATION: Check if $A(x,y)$ is contained within the given image.

If not the method has no effect (i.e. identity effect).

If $A(x,y)$ is contained within the image, then visible changes should be seen (i.e. a non-identity effect) but ONLY within $A(x,y)$. These changes result from applying IMGTRANS to each line of pixels ODP in $A(x,y)$ where (see DIAGRAM 1)

O is at the center of the square $A(x,y)$

P ranges from point G to H, and from F to K. P is given by the intersection of the line from O passing through (i,j) , and the left or right sides of $A(x,y)$ (ie GH and FK).

D is at the intersection of a circle centered at O with radius size/3.

This means that each of the four octants OGV, OVH, OKU and OUF are visibly transformed.

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To code up the SPECIFICATION

(i) Write code to check the containment of $A(x,y)$

(ii) Hence, if required, use a loop to visit each pixel (i,j) in $A(x,y)$.

(iii) Apply IMGTRANS to each line ODP specified by an (i,j) .

Again, the tricky part is calculating the pixel movements; selecting and coloring grey pixels is easy.

For the movements, if pixel p (on the line) at coordinate (i,j) is

between D and P, then pixel prep (on the line between O and D) has coordinate (prei,prej). So we must calculate (prei,prej) from (i,j); you can then "perform the move". If (i,j) is on OD make it gray.

To do so we need to use mathematical cartesian coordinate geometry! You can see this in DIAGRAM2.

And all calculations will be easier if we translate A(x,y) (with image coordinates), to A(0,0) in the Cartesian coordinate system. The axes are now labelled I and J. We write (I,J) for the cartesian coords in A(0,0) of image coordinate (i,j) in A(x,y).

We then compute (preI,PreJ) with cartesian coords in A(0,0) and translate back to image coords (prei,prej) in A(x,y). The special method octlinTrans computes (preI,preJ) from (I,J).

The remaining paragraphs elaborate on these basic ideas.

Translating A(x,y) in image coords to A(0,0) in cartesian coords:

Example: suppose items Q and T are on a straight line with origin O (say at distances D and E from O)

-----O-----Q-----T

and Q is translated to O, with T moved relative to Q. Then T is now at ** distance E-D ** from the origin with Q at distance D-D=0.

-----X-----Y-----

Q moves distance D to 0; so all other distances change by relative amount D too.

In the case of A(x,y), the pixel at (x,y) is translated to cartesian coords, and THEN to (0,0). All other points of A(x,y) are also translated to cartesian coordinates, and then translated relative to

(0,0). In the case of (x,y) we have (x,y) --> (x,-y) --> (x-x,(-y)-y) --> (0+x,0+(-y)) --> (x,-(-y)) ie (x,y). You'll need to work out the same process for (i,j).

We can now work with cartesian coordinates (I,J) and the pixels inside the square A(0,0) at the origin.

More on octlinTrans.

Now consider DIAGRAM2, and only octant OGV. We have to look at each pixel at (I,J) on its line DP and work out (preI,preJ).

In DIAGRAM3 picturing OPV, if we know the distances of D, (I,J) and P from O, we can then apply linTrans, and work out (preI,preJ). Note: a slight cheat here: let's write d for the distance of (I,J), but overload O, D, P as variables for the distances. Then

theta = arctan(J/I)	
O = 0	ie O is at the origin
P = ?	ie distance O to P
D = size/3	ie distance O to D
d = ??	

Use some coord geometry to compute P and d. Then call linTrans to compute pred. And finally use coord geometry to compute preI and preJ. You can then complete the method octlinTrans. Don't forget to calculate preI and preJ using doubles and finally coerce to int.

For each (I,J) you should work out which octant it is in, and change coordinates so that (I,J) "moves to" OGV. Note that octant OGV is defined by $0 < J < I$, which is codeable. See DIAGRAM2 for hints on one other quadrant. For the move, here is one example. If (I,J) is in OVH then (I,-J) is in OGV: so you can call octlinTrans on (I,-J).

We should now be able to write code to apply IMGTRANS in all octants.

Note: The parameter n is not actually used in linearOct.

**** phaseShift ****

phaseShift performs a shift of color on a specified area.

The specified area is a subset S of a square $A(x,y)$ with center (x,y) and corners $(x-size, y-size)$, $(x+size,y-size)$, $(x+size, y+size)$, $(x-size, y+size)$. The subset S is $A(x,y)$ intersect (image - boundary), where boundary consists of those pixels that are less than $2*n$ pixels away from any image edge. The pixels p of S will be changed in the following way: If p is at (i,j) and $i \geq 300$ then the RGB of p should be set to PURE maximum blue. Otherwise the red, green and blue components of p will all be equal to the green component of the pixel that is $2*n$ pixels vertically up from p . Thus the changed pixels of will always be RGB grayscale if $i < 300$.

@param image if the image you are transforming

@param n as defined above

@param x the x-coordinate of the centre of the square $A(x,y)$

@param y the y-coordinate of the centre of the square $A(x,y)$

@param size half the length/width of the square