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Python for Data Analytics

NumPy II



Outline

- What is NumPy?
- Creating Arrays
- Manipulating Arrays
- **Universal Functions**
- **Statistical Operations**
- **Matrix Operations**

Universal Functions

Arithmetic Operations

- Shape of both operands must be same!
- One operand can be a constant

```
>>> a = np.array([1, 2, 3], float)
>>> b = np.array([4, 5, 6], float)
>>> a + b
array([5., 7., 9.])
>>> a - b
array([-3., -3., -3.])
>>> a * b
array([ 4., 10., 18.])
>>> b / a
array([4. , 2.5, 2. ])
```

```
>>> b % a
array([0., 1., 0.])
>>> b**a
array([ 4., 25., 216.])
>>> a * 0.5
array([0.5, 1. , 1.5])
>>> b > 5
array([False, False,  True])
>>> a + b == 5
array([ True, False, False])
```

Operations: Python List vs. NumPy Array

■ Operator *

- List * n: repetition of the whole list
- Array * n: multiply n to every element in the array

```
>>> L = [1, 2, 3]
>>> A = np.array([1, 2, 3])
>>> L * 2
[1, 2, 3, 1, 2, 3]
>>> A * 2
array([2, 4, 6])
```

■ Operator +

- List1 + List2: concatenation of two lists
- Array1 + Array2: Element-wise addition

```
>>> L + L
[1, 2, 3, 1, 2, 3]
>>> A + A
array([2, 4, 6])
```

Universal Functions (ufuncs)

- A function that operates on ndarrays in an element-by-element fashion
 - A "vectorized" wrapper for a function that takes a fixed number of specific inputs and produces a fixed number of specific outputs
 - Supports array broadcasting and type casting
- Available ufuncs
 - Math operations (add, subtract, multiply, divide, power, sqrt, exp, log,...)
 - Trigonometric functions (sin, cos, tan, arcsin, arccos, sinh, cosh, tanh,...)
 - Bit-twiddling functions (bitwise_and, invert, left_shift, right_shift,...)
 - Comparison functions (greater, less, equal, logical_and, maximum, fmax,...)
 - Floating functions (fabs, modf, floor, ceil, isnan, ifinf,...)

Unary Universal Functions

Function	Description
<code>abs</code> , <code>fabs</code>	Compute the absolute value element-wise for integer, floating-point, or complex values
<code>sqrt</code>	Compute the square root of each element (equivalent to <code>arr ** 0.5</code>)
<code>square</code>	Compute the square of each element (equivalent to <code>arr ** 2</code>)
<code>exp</code>	Compute the exponent e^x of each element
<code>log</code> , <code>log10</code> , <code>log2</code> , <code>log1p</code>	Natural logarithm (base e), log base 10, log base 2, and $\log(1 + x)$, respectively
<code>sign</code>	Compute the sign of each element: 1 (positive), 0 (zero), or -1 (negative)
<code>ceil</code>	Compute the ceiling of each element (i.e., the smallest integer greater than or equal to that number)
<code>floor</code>	Compute the floor of each element (i.e., the largest integer less than or equal to each element)
<code>rint</code>	Round elements to the nearest integer, preserving the <code>dtype</code>
<code>modf</code>	Return fractional and integral parts of array as a separate array
<code>isnan</code>	Return boolean array indicating whether each value is NaN (Not a Number)
<code>isfinite</code> , <code>isinf</code>	Return boolean array indicating whether each element is finite (non- <code>inf</code> , non-NaN) or infinite, respectively
<code>cos</code> , <code>cosh</code> , <code>sin</code> , <code>sinh</code> , <code>tan</code> , <code>tanh</code>	Regular and hyperbolic trigonometric functions
<code>arccos</code> , <code>arccosh</code> , <code>arcsin</code> , <code>arcsinh</code> , <code>arctan</code> , <code>arctanh</code>	Inverse trigonometric functions
<code>logical_not</code>	Compute truth value of <code>not x</code> element-wise (equivalent to <code>~arr</code>).

Binary Universal Functions

Function	Description
<code>add</code>	Add corresponding elements in arrays
<code>subtract</code>	Subtract elements in second array from first array
<code>multiply</code>	Multiply array elements
<code>divide</code> , <code>floor_divide</code>	Divide or floor divide (truncating the remainder)
<code>power</code>	Raise elements in first array to powers indicated in second array
<code>maximum</code> , <code>fmax</code>	Element-wise maximum; <code>fmax</code> ignores NaN
<code>minimum</code> , <code>fmin</code>	Element-wise minimum; <code>fmin</code> ignores NaN
<code>mod</code>	Element-wise modulus (remainder of division)
<code>copysign</code>	Copy sign of values in second argument to values in first argument
<code>greater</code> , <code>greater_equal</code> , <code>less</code> , <code>less_equal</code> , <code>equal</code> , <code>not_equal</code>	Perform element-wise comparison, yielding boolean array (equivalent to infix operators <code>></code> , <code>>=</code> , <code><</code> , <code><=</code> , <code>==</code> , <code>!=</code>)
<code>logical_and</code> , <code>logical_or</code> , <code>logical_xor</code>	Compute element-wise truth value of logical operation (equivalent to infix operators <code>&</code> , <code> </code> , <code>^</code>)

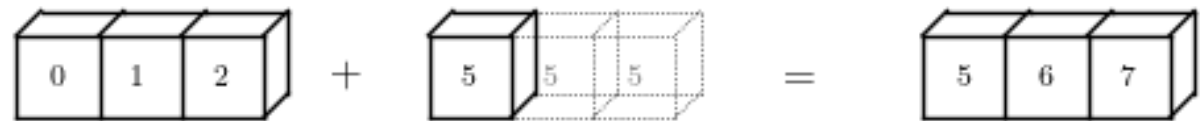
ufuncs: Examples

```
>>> a = np.arange(1, 5)
>>> a
array([1, 2, 3, 4])
>>> b = np.sqrt(a)
>>> b
array([1.          , 1.41421356, 1.73205081, 2.          ])
>>> np.ceil(b)
array([1., 2., 2., 2.])
>>> np.maximum(a/2, b)
array([1.          , 1.41421356, 1.73205081, 2.          ])
>>> f, i = np.modf(b)
>>> f
array([0.          , 0.41421356, 0.73205081, 0.          ])
>>> i
array([1., 1., 1., 2.])
```

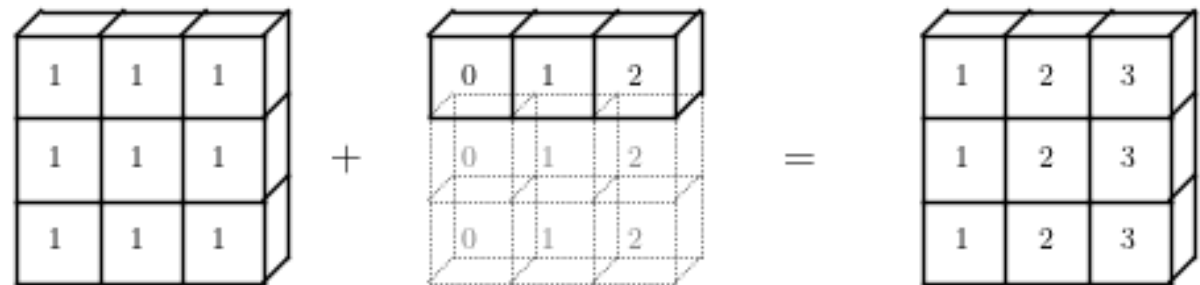
Array Broadcasting

- Allows arithmetic operations on arrays with different shapes
- The smaller array is "broadcast" across the larger array so that they have compatible shapes

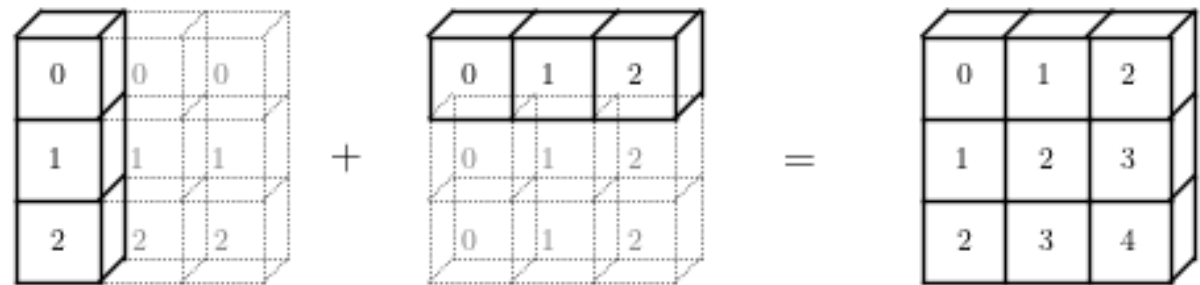
`np.arange(3) + 5`



`np.ones((3, 3)) + np.arange(3)`



`np.arange(3).reshape((3, 1)) + np.arange(3)`



Broadcasting Rule

- The size of the trailing axes for both arrays in an operation must either be the same size or one of them must be one

Image	(3d array)	256 x	256 x	3
Scale	(1d array)			3
Result	(3d array)	256 x	256 x	3

A	(4d array)	8 x	1 x	6 x	1
B	(3d array)		7 x	1 x	5
Result	(4d array)	8 x	7 x	6 x	5

Broadcasting Example (I)

```
>>> a = np.array([1, 2, 3])
>>> b = 2
>>> a * b
array([2, 4, 6])
>>> a = np.array([[ 0.0,  0.0,  0.0],
...               [10.0, 10.0, 10.0],
...               [20.0, 20.0, 20.0],
...               [30.0, 30.0, 30.0]])
>>> b = array([1.0, 2.0, 3.0])
>>> a + b
array([[ 1.,  2.,  3.],
       [11., 12., 13.],
       [21., 22., 23.],
       [31., 32., 33.]])
```

a:			3
b:			1
result:			3

a:	4	x	3
b:			3
result:	4	x	3

Broadcasting Example (2)

```
>>> a = np.array([0.0, 10.0, 20.0, 30.0])
```

```
>>> b = np.array([1.0, 2.0, 3.0])
```

```
>>> a[:, np.newaxis] + b
```

```
array([[ 1.,  2.,  3.],  
       [11., 12., 13.],  
       [21., 22., 23.],  
       [31., 32., 33.]])
```

*Increase a
dimension:
(4,) → (4, 1)*

```
>>> a = np.arange(12).reshape(4, 3)
```

```
>>> b = np.array([1, 2, 3, 4])
```

```
>>> a + b
```

Traceback (most recent call last):

File "<stdin>", line 1, in <module>

ValueError: operands could not be broadcast
together with shapes (4,3) (4,)

a: 4 x 1
b: 3
result: 4 x 3

 a: 4 x 3
b: 4
result:

Conditional Operation

- `np.where(condition, [x, y])`
 - When only `condition` is provided, return the indices of the elements that the condition is met
 - Otherwise return elements chosen from `x` or `y` depending on condition

```
>>> a = np.array([[1,2], [4,5]])
>>> np.where(a % 2 == 0)
(array([0, 1]), array([1, 0]))
>>> a[np.where(a % 2 == 0)]
array([2, 4])
>>> a[a % 2 == 0]
array([2, 4])
```

```
>>> b = np.array([[9,8], [7,6]])
>>> np.where(a % 2 == 0, a, b)
array([[9, 2],
       [4, 6]])
>>> np.where(a>2, a+1, 0)
array([[0, 0],
       [5, 6]])
```

Statistical Operations

Statistical Operations

- Mean

$$\text{Mean}(x) = \bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$

- Median

- The value in the middle
- If n is an even number, take the average of the two middle values

$$\text{Median}(x) = \frac{x_{[(n+1)/2]} + x_{[(n+1)/2]}}{2}$$

- Variance

$$\text{Var}(x) = \sigma^2 = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2$$

- Standard deviation

$$\text{Std}(x) = \sigma = \sqrt{\frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})^2}$$

sum() and prod()

- `a.sum([axis], [dtype], ...)`
 - Return the **sum** of the array elements over the given *axis*
 - If *axis* is not given, the sum of all the elements is computed
 - Similar to `np.sum(a, ...)`
- `a.prod([axis], [dtype], ...)`
 - Return the **product** of the array elements over a given *axis*
 - If *axis* is not given, the product of all the elements is computed
 - Similar to `np.prod(a, ...)`

```
>>> a = np.arange(1, 11)
>>> a.sum()
55
>>> a.prod()
3628800
>>> x = np.arange(1,13).reshape(3,4)
>>> x
array([[ 1,  2,  3,  4],
       [ 5,  6,  7,  8],
       [ 9, 10, 11, 12]])
>>> x.sum(axis=0) # along the rows
array([15, 18, 21, 24])
>>> x.sum(axis=1) # along the cols
array([10, 26, 42])
```

nansum() and nanprod()

- `np.nansum(a, [axis], [dtype], ...)`
 - Return the **sum** of the array elements over the **axis** treating NaNs as zero
 - If **axis** is not given, the sum of all the elements is computed
 - No `a.nansum(...)` form available!
- `np.nanprod(a, [axis], [dtype], ...)`
 - Return the **product** of the array elements treating NaNs as ones
 - If **axis** is not given, the product of all the elements is computed
 - No `a.nanprod(...)` form available!

```
>>> a = np.array([[1.0, 2.0, np.nan],  
[4.0, np.nan, 3.0]])  
>>> a  
array([[ 1.,  2., nan],  
       [ 4., nan,  3.]])  
>>> np.nansum(a)  
10.0  
>>> np.nansum(a, axis=1)  
array([3., 7.])  
>>> np.nanprod(a)  
24.0  
>>> np.nanprod(a, axis=0)  
array([4., 2., 3.]])
```

mean() and var()

- **`a.mean([axis], [dtype], ...)`**
 - Return the **average** of the array elements over the given **axis**
 - If **axis** is not given, compute the mean of the flattened array
 - Similar to **`np.mean(a, ...)`**
- **`a.var([axis], [dtype], ...)`**
 - Return the **variance** of the array elements over a given **axis**
 - If **axis** is not given, compute the variance of the flattened array
 - Similar to **`np.var(a, ...)`**

```
>>> a = np.arange(1, 11)
>>> a.mean()
5.5
>>> a.var()
8.25
>>> x = np.arange(1,13).reshape(3,4)
>>> x
array([[ 1,  2,  3,  4],
       [ 5,  6,  7,  8],
       [ 9, 10, 11, 12]])
>>> x.mean()
6.5
>>> x.var()
11.916666666666666
```

std() and median()

- `a.std([axis], [dtype], ...)`
 - Return the **standard deviation** of the array elements over the given *axis*
 - If *axis* is not given, compute the standard deviation of the flattened array
 - Similar to `np.std(a, ...)`
- `np.median(a, [axis], [dtype], ...)`
 - Return the **median** along the given *axis*
 - If *axis* is not given, compute the median of the flattened array
 - No `a.median(...)` form available!

```
>>> a = np.arange(1, 11)
>>> a.std()
2.8722813232690143
>>> a.median()
Traceback (most recent call last):
  File "<stdin>", line 1, in <module>
AttributeError: 'numpy.ndarray' object
has no attribute 'median'
>>> np.median(a)
5.5
x = np.arange(1,13).reshape(3,4)
>>> x.std()
3.452052529534663
>>> np.median(x)
6.5
```

Why NumPy?

- NumPy statistics is much easier than nested list statistics
- Python List vs. Numpy.array's sum() of 2D data

```
>>> a = np.arange(1,10).reshape(3,3)
>>> a
array([[1, 2, 3],
       [4, 5, 6],
       [7, 8, 9]])
>>> a.sum()
45
```

```
def nested_sum(L):
    sum = 0
    for i in L:
        if isinstance(i, list):
            sum += nested_sum(i)
        else:
            sum += i
    return sum;
>>> b = [[1,2,3], [4,5,6], [7,8,9]]
>>> nested_sum(b)
45
```

Covariance

- Covariance (공분산)

- A measure of the joint variability of two random variables

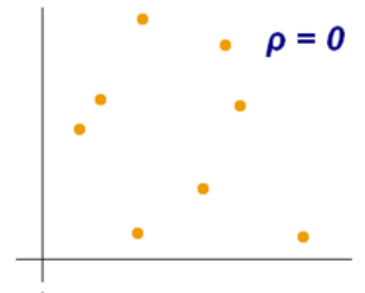
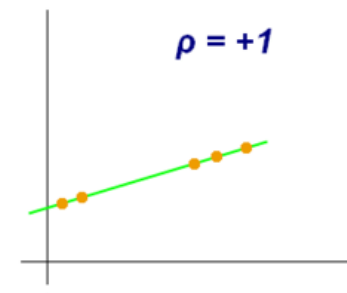
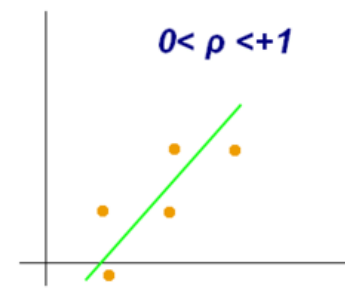
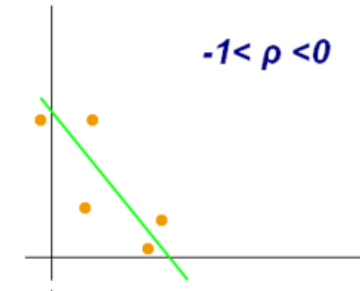
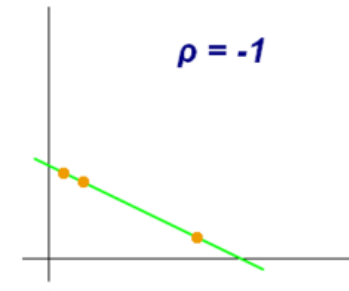
$$\text{Cov}(X, Y) = \frac{1}{n} \sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})$$

- If the greater values of one variable mainly correspond with the greater values of the other variable, and the same holds for the lesser values (i.e., the variables tend to show similar behavior), the covariance is positive
- In the opposite case, the covariance is negative
- The sign of the covariance therefore shows the tendency in the linear relationship between the variables

Correlation Coefficient

- Pearson (product-moment) correlation coefficient (상관계수), r
 - A measure of correlation between two variables X and Y
 - $-1 \leq r \leq 1$ where
 - 0: no linear correlation,
 - 1: total positive correlation,
 - 1: total negative correlation

$$r = \frac{\text{Cov}(X, Y)}{\sigma_X \sigma_Y}$$
$$= \frac{\sum_{i=1}^n (x_i - \bar{x})(y_i - \bar{y})}{\sqrt{\sum_{i=1}^n (x_i - \bar{x})^2} \sqrt{\sum_{i=1}^n (y_i - \bar{y})^2}}$$



cov() and corrcoef()

■ `np.cov(m, [bias], ...)`

- Estimate a covariance matrix, given data and weights
- Covariance indicates the level to which two variables vary together
- For N-dimensional samples, $X = [x_1, x_2, \dots, x_n]^T$, the covariance matrix element C_{ij} is the covariance of x_i and x_j . (C_{ii} is the variance of x_i)
- *m*: A 1-D or 2-D array containing multiple variables and observations
- *bias*: If False, **normalization is by $(N - 1)$** , otherwise by N (default: False)

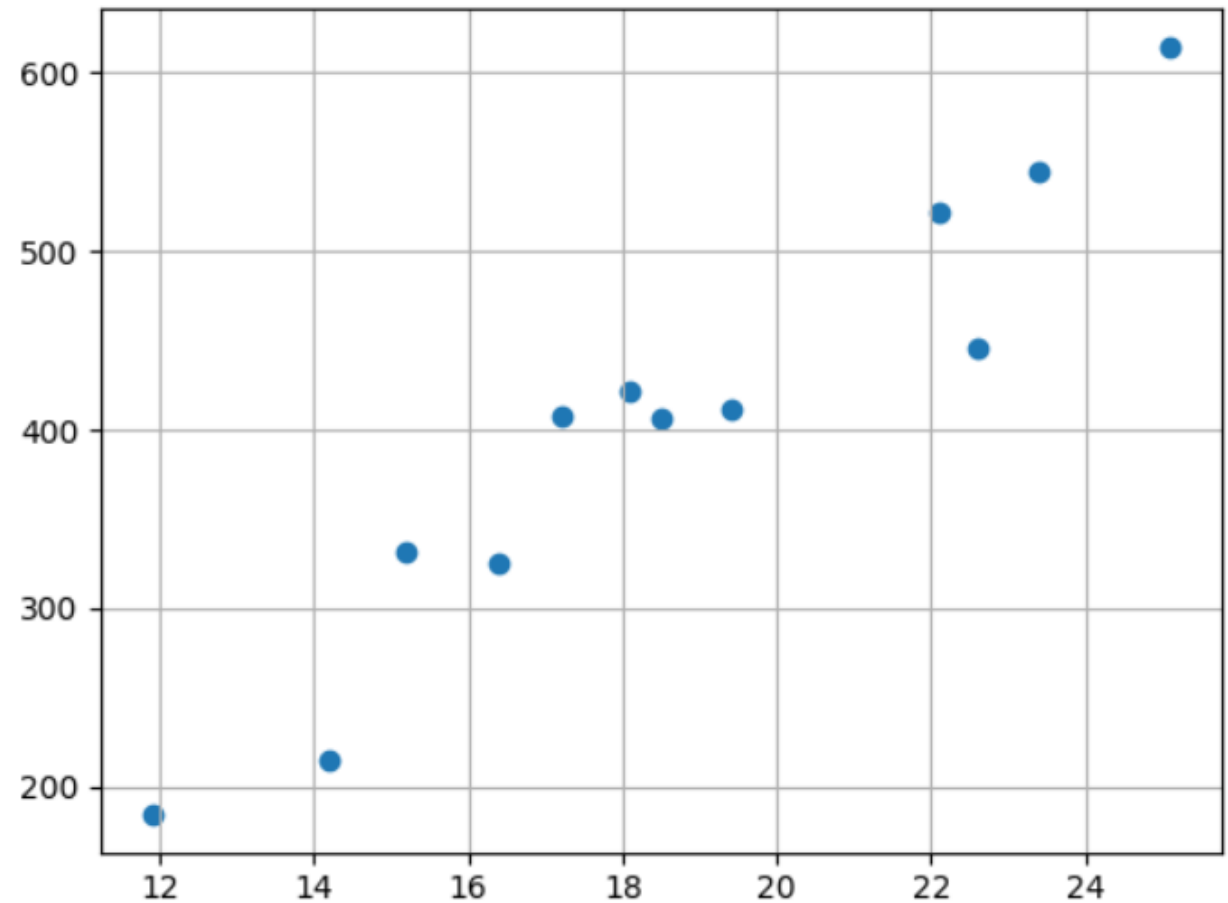
■ `a.corrcoef(x, ...)`

- Return Pearson product-moment correlation coefficients
- The relationship between the correlation coefficient matrix, R , and the covariance matrix, C , is:

$$R_{ij} = \frac{C_{ij}}{\sqrt{C_{ii} * C_{jj}}}$$

Example: Temperature vs. Ice Cream Sales

Temperature (°C)	Ice Cream Sales
14.2	\$215
16.4	\$325
11.9	\$185
15.2	\$332
18.5	\$406
22.1	\$522
19.4	\$412
25.1	\$614
23.4	\$544
18.1	\$421
22.6	\$445
17.2	\$408



Example: Temperature vs. Ice Cream Sales

```
t = np.array([14.2, 16.4, 11.9, 15.2,
              18.5, 22.1, 19.4, 25.1, 23.4,
              18.1, 22.6, 17.2])
s = np.array([215, 325, 185, 332, 406,
              522, 412, 614, 544, 421, 445, 408])
C = np.cov([t, s])
R = np.corrcoef([t, s])
print(C)
print(R)
# import matplotlib.pyplot as plt
# plt.scatter(t, s)
# plt.grid(True)
# plt.show()
```

```
[[16.08931818  484.09318182]
 [484.09318182 15886.81060606]]

[[1.          0.95750662]
 [0.95750662  1.          ]]
```

Matrix Operations

Array vs. Matrix

- Numpy matrices are strictly 2-dimensional, while numpy arrays (ndarrays) are N-dimensional
- Matrix objects are a subclass of ndarray, so they inherit all the attributes and methods of ndarrays
- Numpy matrices provide a convenient notation for matrix multiplication
 - If a and b are matrices, then $a*b$ is their matrix product

```
>>> a = np.array([[4, 3], [2, 1]])
>>> b = np.array([[1, 2], [3, 4]])
>>> a * b
array([[4, 6],
       [6, 4]])
```

```
>>> ma = np.mat(a)
>>> mb = np.mat(b)
>>> ma * mb
matrix([[13, 20],
        [ 5,  8]])
```

Creating Matrices

- `np.matrix(data[, dtype][, copy])`
 - Return a matrix from an array-like object, or from a string of data
 - If `data` is a string, it is interpreted as a matrix with commas or spaces separating columns, and semicolons separating rows
- `np.mat(data[, dtype])`
 - Interpret the input as a matrix
 - Unlike `matrix()`, `mat()` **does not make a copy** if the input is already a matrix or an ndarray

```
>>> m = np.matrix('1 2; 3 4')
>>> m
matrix([[1, 2],
        [3, 4]])
>>> np.matrix([[1, 2], [3, 4]])
matrix([[1, 2],
        [3, 4]])
>>> y = np.array([[1,2], [3,4]])
>>> my = np.mat(y)
>>> my
matrix([[1, 2],
        [3, 4]])
>>> np.asarray(my)
array([[1, 2],
       [3, 4]])
```

Array vs. Matrix: Comparison

To Be Depreciated

	array	matrix
Dimensions	Number of dimensions can be larger than 2	Exactly two dimensions
Operator *	Element-wise multiplication	Matrix multiplication
Operator @	Matrix multiplication	Matrix multiplication
np.multiply()	Element-wise multiplication	Element-wise multiplication
np.dot()	Matrix multiplication	Matrix multiplication
Handling vectors	1-dimensional	2-dimensional with 1xN (row vector) or Nx1 (column vector) shape
Attributes	.T (transpose)	.T (transpose), .A (asarray()), .H (conjugate transpose), .I (inverse)
Initialization	Can use Python sequences e.g., <code>array([[1,2,3], [4,5,6]])</code>	Additionally, can use a convenient string initializer e.g., <code>np.matrix('[1 2 3; 4 5 6]')</code>

Product Operations in Vector/Matrix

■ For vectors

- Inner product (벡터내적) Supported by `np.dot()` or `np.inner()`
- Outer product (벡터외적) Supported by `np.outer()`
- Cross product (벡터곱) Supported by `np.cross()`

■ For matrices

- Matrix multiplication (행렬곱) Supported by `np.dot()` or `np.matmul()`
- Inner product (행렬내적) Supported by `np.inner()`

Vector Inner Product (벡터내적)

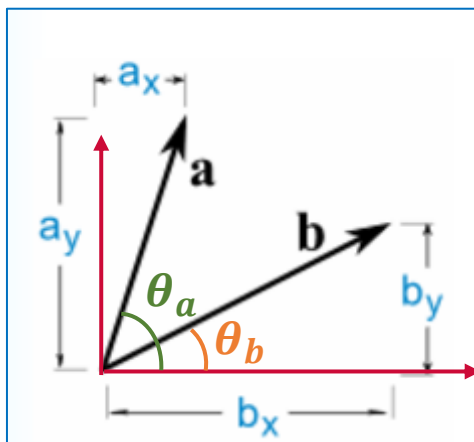
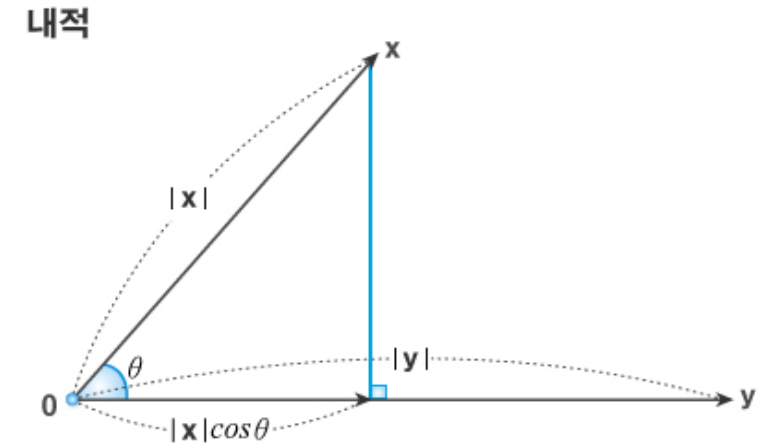
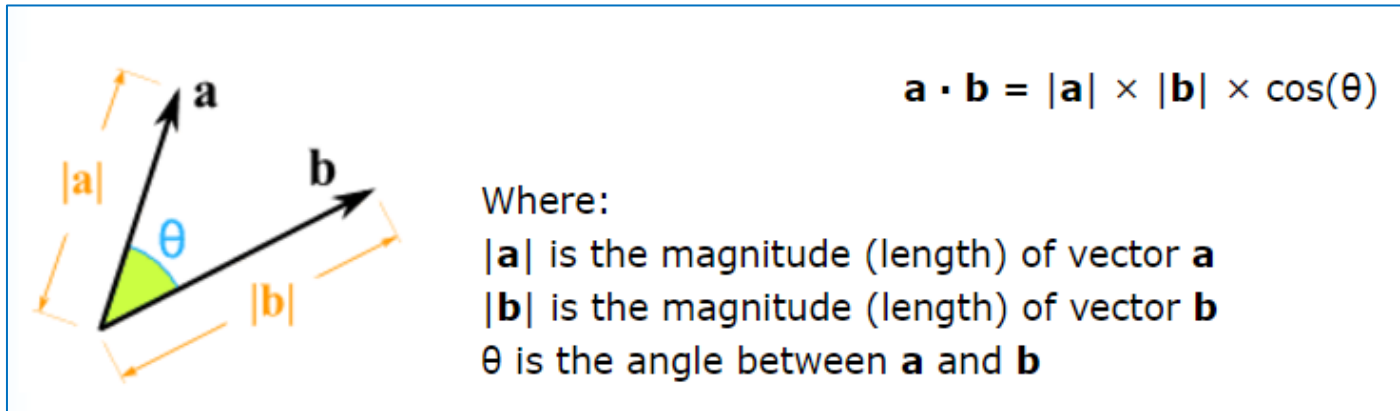
- Vector · Vector → Scalar
- The inner product of two vectors in matrix form:

$$\begin{aligned} a \cdot b &= a^T b \\ &= (a_1 \ a_2 \ \cdots \ a_n) \begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_n \end{pmatrix} \\ &= a_1 b_1 + a_2 b_2 + \cdots + a_n b_n \\ &= \sum_{i=1}^n a_i b_i \end{aligned}$$

$$(a \ b \ c) \begin{pmatrix} 1 \\ 4 \\ 7 \end{pmatrix} = a + 4b + 7c$$

Application of Vector Inner Product

- Compute the angle between two vectors



$$\begin{aligned} a_x &= |a| \cos \theta_a & b_x &= |b| \cos \theta_b \\ a_y &= |a| \sin \theta_a & b_y &= |b| \sin \theta_b \\ \mathbf{a} \cdot \mathbf{b} &= |a| |b| \cos(\theta_a - \theta_b) \\ &= |a| |b| (\cos \theta_a \cos \theta_b + \sin \theta_a \sin \theta_b) \\ &= |a| \cos \theta_a |b| \cos \theta_b + |a| \sin \theta_a |b| \sin \theta_b \\ &= a_x b_x + a_y b_y \end{aligned}$$

$$\cos \theta = \frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|}$$

$$\theta = \arccos \left(\frac{\mathbf{a} \cdot \mathbf{b}}{|\mathbf{a}| |\mathbf{b}|} \right)$$

dot() and inner()

- `np.dot(a, b, ...)`
 - If both `a` and `b` are 1-D arrays, return the inner product of vectors
 - Otherwise, return different results depending on the input dimensions
- `np.inner(a, b, ...)`
 - Return the inner product of vectors for 1-D arrays
 - In higher dimensions, return the sum product over the last axes
 - `== sum(a*b)`

```
>>> a = np.array([1, 2, 3], float)
>>> b = np.array([0, 1, 1], float)
>>> np.dot(a, b)
5.0
>> np.dot(a, 2)          # scalar
array([2., 4., 6.])
>>> np.inner(a, b)
5.0
>>> np.inner(3, b)       # scalar
array([0., 3., 3.])
>>> sum(a*b)
5.0
```

Vector Outer Product (벡터외적)

- Vector \cdot Vector \rightarrow Matrix
- The outer product of two vectors in matrix form:

$$\mathbf{a} \otimes \mathbf{b} = \mathbf{a} \mathbf{b}^T$$

$$= \begin{pmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{pmatrix} (b_1 \ b_2 \ \cdots \ b_n)$$

$$= \begin{pmatrix} a_1 b_1 & a_1 b_2 & \cdots & a_1 b_n \\ a_2 b_1 & a_2 b_2 & \cdots & a_2 b_n \\ \vdots & \vdots & \ddots & \vdots \\ a_n b_1 & a_n b_2 & \cdots & a_n b_n \end{pmatrix}$$

$$\begin{pmatrix} 1 \\ 4 \\ 7 \end{pmatrix} (a \ b) = \begin{pmatrix} 1a & 1b \\ 4a & 4b \\ 7a & 7b \end{pmatrix}$$

Application of Vector Outer Product

- Matrix multiplication can be implemented using vector outer product

$$\begin{aligned} \mathbf{AB} &= (\bar{\mathbf{a}}_1 \quad \bar{\mathbf{a}}_2 \quad \cdots \quad \bar{\mathbf{a}}_m) \begin{pmatrix} \bar{\mathbf{b}}_1 \\ \bar{\mathbf{b}}_2 \\ \vdots \\ \bar{\mathbf{b}}_m \end{pmatrix} \\ &= \bar{\mathbf{a}}_1 \otimes \bar{\mathbf{b}}_1 + \bar{\mathbf{a}}_2 \otimes \bar{\mathbf{b}}_2 + \cdots + \bar{\mathbf{a}}_m \otimes \bar{\mathbf{b}}_m \\ &= \sum_{i=1}^m \bar{\mathbf{a}}_i \otimes \bar{\mathbf{b}}_i \end{aligned}$$

where this time

$$\bar{\mathbf{a}}_i = \begin{pmatrix} A_{1i} \\ A_{2i} \\ \vdots \\ A_{ni} \end{pmatrix}, \quad \bar{\mathbf{b}}_i = (B_{i1} \quad B_{i2} \quad \cdots \quad B_{ip}).$$

$$\begin{aligned} \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \begin{pmatrix} a & d \\ b & e \\ c & f \end{pmatrix} &= \begin{pmatrix} 1 \\ 4 \\ 7 \end{pmatrix} \otimes (a \ d) + \begin{pmatrix} 2 \\ 5 \\ 8 \end{pmatrix} \otimes (b \ e) + \begin{pmatrix} 3 \\ 6 \\ 9 \end{pmatrix} \otimes (c \ f) \\ &= \begin{pmatrix} 1a & 1d \\ 4a & 4d \\ 7a & 7d \end{pmatrix} + \begin{pmatrix} 2b & 2e \\ 5b & 5e \\ 8b & 8e \end{pmatrix} + \begin{pmatrix} 3c & 3f \\ 6c & 6f \\ 9c & 9f \end{pmatrix} \\ &= \begin{pmatrix} 1a+2b+3c & 1d+2e+3f \\ 4a+5b+6c & 4d+5e+6f \\ 7a+8b+9c & 7d+8e+9f \end{pmatrix}. \end{aligned}$$

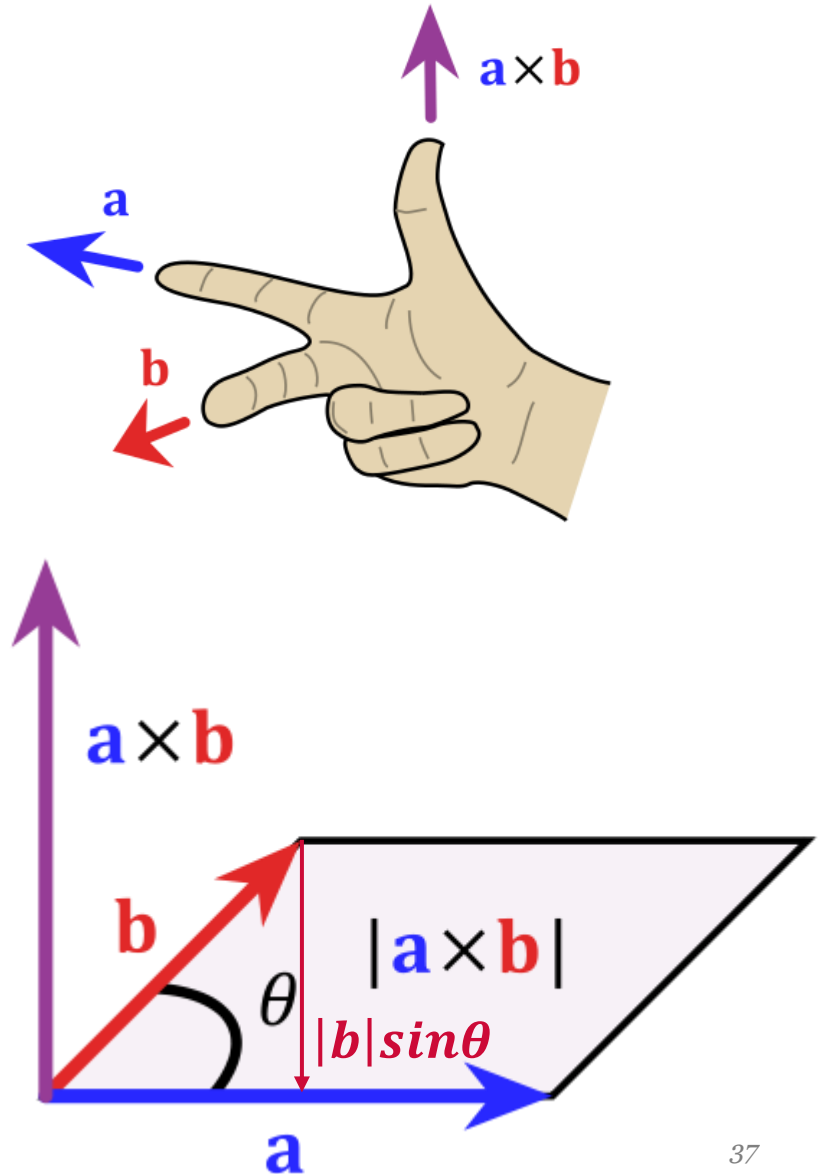
Vector Cross Product (벡터곱)

- Vector \times Vector \rightarrow Vector
- The cross product is defined by the formula

$$\mathbf{a} \times \mathbf{b} = |\mathbf{a}||\mathbf{b}|\sin\theta \mathbf{n}$$

where θ is the angle between \mathbf{a} and \mathbf{b} , and \mathbf{n} is a unit vector perpendicular to the plane containing \mathbf{a} and \mathbf{b} with a magnitude equal to the area of the parallelogram that the vectors span

$$|\mathbf{a} \times \mathbf{b}| = |\mathbf{a}||\mathbf{b}|\sin\theta$$



outer() and cross()

- `np.outer(a, b, ...)`
 - Compute the outer product of two vectors
- `np.cross(a, b, ...)`
 - Return the cross product of two vectors

```
>>> x = np.outer(np.ones((5,)),  
np.linspace(-2, 2, 5))  
>>> x  
array([[ -2.,  -1.,   0.,   1.,   2.],  
       [ -2.,  -1.,   0.,   1.,   2.],  
       [ -2.,  -1.,   0.,   1.,   2.],  
       [ -2.,  -1.,   0.,   1.,   2.],  
       [ -2.,  -1.,   0.,   1.,   2.]])
```

```
>>> x = np.array([1,4,0])  
>>> y = np.array([2,2,1])  
>>> np.cross(x,y)  
array([  4, -1, -6])
```

Matrix Multiplication (행렬곱)

$$\mathbf{A} = \begin{pmatrix} a & b & c \\ x & y & z \end{pmatrix}, \quad \mathbf{B} = \begin{pmatrix} \alpha & \rho \\ \beta & \sigma \\ \gamma & \tau \end{pmatrix},$$

their matrix products are:

$$\mathbf{AB} = \begin{pmatrix} a & b & c \\ x & y & z \end{pmatrix} \begin{pmatrix} \alpha & \rho \\ \beta & \sigma \\ \gamma & \tau \end{pmatrix} = \begin{pmatrix} a\alpha + b\beta + c\gamma & a\rho + b\sigma + c\tau \\ x\alpha + y\beta + z\gamma & x\rho + y\sigma + z\tau \end{pmatrix},$$

and

$$\mathbf{BA} = \begin{pmatrix} \alpha & \rho \\ \beta & \sigma \\ \gamma & \tau \end{pmatrix} \begin{pmatrix} a & b & c \\ x & y & z \end{pmatrix} = \begin{pmatrix} \alpha a + \rho x & \alpha b + \rho y & \alpha c + \rho z \\ \beta a + \sigma x & \beta b + \sigma y & \beta c + \sigma z \\ \gamma a + \tau x & \gamma b + \tau y & \gamma c + \tau z \end{pmatrix}.$$

dot() and matmul()

- `np.dot(a, b, ...)`
 - If both `a` and `b` are 2-D arrays, return the result of matrix multiplication
 - The use of `matmul()` or `a @ b` is preferred
- `np.matmul(a, b, ...)`
 - Return the matrix product of two arrays

```
>>> a = np.array([[0, 1], [2, 3]])
>>> b = np.array([2, 3])
>>> c = np.array([[1, 1], [4, 0]])
>>> np.dot(b, a)
array([ 6, 11])
>>> np.dot(a, b)
array([ 3, 13])
>>> np.matmul(a, c)
array([[ 4,  0],
       [14,  2]])
>>> c @ a
array([[2, 4],
       [0, 4]])
```

$$\begin{array}{l} b \bullet a \\ \rightarrow \begin{bmatrix} 2 & 3 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix} \\ a \bullet b \\ \rightarrow \begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix} \\ a \bullet c \\ \rightarrow \begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 4 & 0 \end{bmatrix} \\ c \bullet a \\ \rightarrow \begin{bmatrix} 1 & 1 \\ 4 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 2 & 3 \end{bmatrix} \end{array}$$

Summary

■ NumPy Core

- Array creation, Array manipulation, Binary operations, String operations, ...

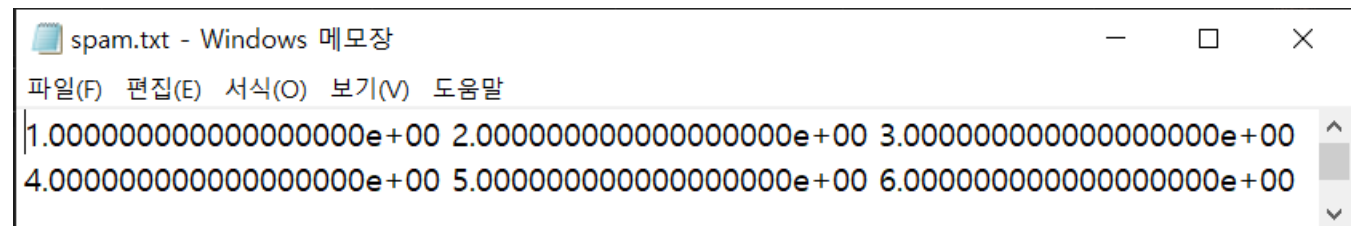
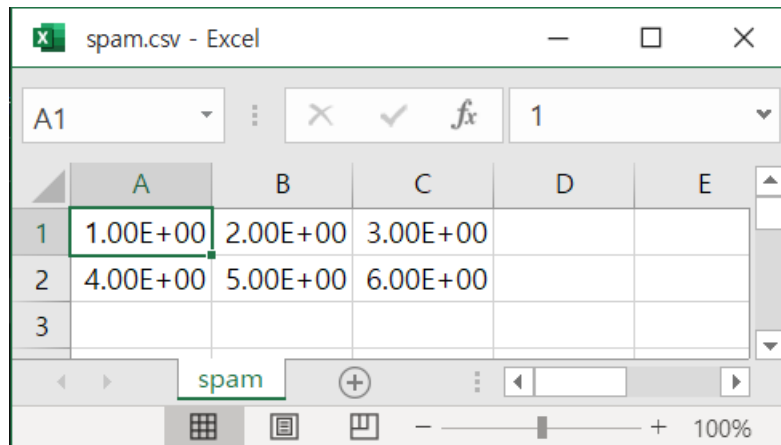
■ Submodules

- `numpy.rec`: Creating record arrays
- `numpy.char`: Creating character arrays
- `numpy.ctypeslib`: C-types Foreign Function Interface
- `numpy.dual`: Optionally Scipy-accelerated routines
- `numpy.emath`: Mathematical functions with automatic domain
- `numpy.fft`: Discrete Fourier Transform
- `numpy.linalg`: **Linear Algebra**
- `numpy.matlib`: Matrix Library
- `numpy.random`: Random sampling
- `numpy.testing`: Test support

File I/O

- `np.savetxt(fname, A[, delimiter], ...)`
 - Save an array to a text file named `fname`

```
a = np.array([[1, 2, 3], [4, 5, 6]])  
np.savetxt(r'C:\Users\jinsoo\Desktop\spam.csv', a, delimiter=',')  
np.savetxt(r'C:\Users\jinsoo\Desktop\spam.txt', a, delimiter=' ')
```



File I/O (cont'd)

- `np.loadtxt(fname[, dtype][, delimiter], ...)`
 - Load data from a text file named *fname*

```
b = np.loadtxt(r'C:\Users\jinsoo\Desktop\spam.csv', delimiter=',')
print(b)
c = np.loadtxt(r'C:\Users\jinsoo\Desktop\spam.txt', dtype=int,
delimiter=' ')
print(c)
```

```
[[1., 2., 3.]
 [4., 5., 6.]]
[[1, 2, 3]
 [4, 5, 6]]
```