Alternative Methods for Implementing Explicit and Finding Implicit Sharing in embedded DSLs

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Abstract. TODO The abstract should briefly summarize the contents of the paper in 150–250 words.

Keywords: First keyword · Second keyword · Another keyword.

1 Introduction

TODO describe sharing problem (mention observable sharing [4] and implicit/explicit sharing [5] papers)

TODO describe finally tagless [1]

We present methods for implementing embedded DSLs with sharing that are both safe and maintain all the benefits of being embedded in the Haskell ecosystem. This means DSL functions are type-safe, do not require the use of unsafe referencing (i.e., via unsafePerformIO) and can return Haskell's container types (i.e., tuples, lists, etc) without breaking sharing.

2 Detecting Sharing

A naive DSL implementation of an expression in Haskell can be done via standard Haskell data types, for example:

Note the DSL generates a tree, or to be more specific an Abstract Syntax Tree (AST). Common features a DSL implementer might implement would include code generation or pretty printing. Simple traversal of the AST for either of these operations would result in duplication, for example in the above code snippet the AST for **exp0** will be traversed twice. For code generation in particular this

would be problematic, in order to circumvent this problem in general we need to perform common subexpression elimination by converting the AST into a directed acyclic graph.

TODO describe DAG conversion by pointer comparison in the state monad

2.1 Detecting Sharing In Finally Tagless DSLs

Monads are useful, but don't make for a very user friendly DSL. It would be nice to make use of monadic state when we need it (i.e., for converting to a DAG) while hiding it behind a nice pure interface. The final tagless approach of [1] is popular for accomplishing this. In this approach, DSL expressions are built using typeclass methods that wrap the DSL in a parameterized representation. For example, the previous data type based DSL could be written in finally tagless as

```
class Exp repr where
  add :: repr Int -> repr Int -> repr Int
  variable :: String -> repr Int
  constant :: Int -> repr Int
```

We can then create different instances to implement different functionality. For example, we can generate the AST from the previous DSL like so

```
newtype ExpR a = ExpR { unExpR :: Exp }
instance Exp ExpR where
  constant = ExpR . Constant
  variable = ExpR . Variable
  add (ExpR x) (ExpR y) = ExpR (Add x y)
  Or we can implement pretty printing
newtype Pretty a = Pretty { unPretty :: String }
instance Exp Pretty where
  add x y = Pretty \ "("++unPretty x++") + ("++unPretty y++")"
  variable x = Pretty x
  constant x = Pretty $ show x
  And use the same DSL code to run either implementation
exp :: Exp repr => repr Int -> repr Int
exp v0 =
 let
    exp0 = add v0 (constant 0)
 in add exp0 exp0
expR = unExpR $ exp $ variable "v0"
expP = unPretty $ exp $ variable "v0"
```

Finally tagless style provides extensible, user friendly DSLs. However there are still some complications when using it to implement sharing.

2.2 Implicit Sharing Via Hash-Consing

TODO cite Ershov's original description of hash-consing [2] cite Type safe consing implementation (with performance benchmarks) [3]

In [5], a solution for detection implicit sharing in finally tagless style is presented via the method of hash-consing. You can find a more throrough explanation of the method there, but we'll give an overview here. This method first involves defining a DAG type, for example

Note the purpose of the BiMap type is to be able to quickly insert and lookup nodes by their NodeID (i.e., a bijection of Node's and their NodeID's), and is most optimally implemented as a hash table with linear probing. The representation for the finally tagless instance is then a wrapper around a State monad that holds DAG in its state and returns the current (top) NodeID.

The trick to uncovering sharing in the implementation is implemented via the **hashcons** function, which inserts a new node into the current DAG, but not before checking if it is already there.

```
hashcons :: Node -> State DAG NodeID
hashcons e = do
```

2.3 Limitations of Hash-Consing

When we wrap our State monad in finally tagless style, we lose some of Haskell's built-in sharing capability. Consider the following code, note that the use of local variables explicitly defines the computation x + y to only be computed once

```
haskellSharing x y=
let
  z = x + y
in z + z
```

Implicit sharing via hash-consing prevents duplication in the resulting DAG, but unfortunately doesn't prevent redundant computation. Consider the following equivalent attempt at using Haskell's built-in sharing in the finally tagless DSL.

```
dslSharing :: Exp Graph -> Exp Graph -> Exp Graph
dslSharing x y =
  let
    z = add x y
  in add z z
```

Note \mathbf{z} is a wrapper around a State monad. Recall the implementation of \mathbf{add} via hash consing

The values **h1** and **h2** need to be explicitly evaluated through the State monad, meaning even if **e1** and **e2** are the same shared Haskell value, their underlying computations will be performed twice. Hash-consing will prevent these redundencies from appearing in the resulting DAG, but the entire unshared AST will still be traversed, performing a hash-cons on each node.

Consider a chain of add's with sharing, for example

```
addChains :: Exp repr => Expr Int -> Expr Int
addChains x0 = let
    x1 = add x0 x0
    x2 = add x1 x1
    ...
in xn
```

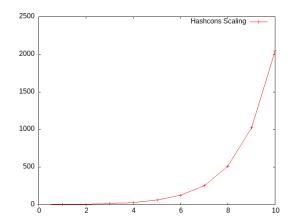


Fig. 1. Number of hashcons to add operations performed

As you can see from figure 1, this code will perform approximately 2^{n+1} hashcons operations, where n is the number of **add**'s.

2.4 Explicit Sharing and Limitations

[5] acknowledges the amount of computation with hash-consing can get out of control, and proposes an ad-hoc solution, explicit sharing via a custom let construct

This makes the code a bit clunky and adds an extra burden on the DSL writer, but it prevents unnecessary hash-consing in our example. However the method has it's limitations, suppose we want to write a DSL function that returns multiple outputs, such as tuples or container types like lists (for example vadd :: (repr Int,repr Int) -> (repr First of all, we need to implement different versions of the custom let construct to correspond to the number of outputs

```
class ExpLet repr where
let_ :: repr a -> (repr a -> repr b) -> repr b
```

If need be, its possible to enumerate custom let instances for every amount of outputs or container types we would need, we could even use template Haskell to accomplish this. However, this custom let construct now has a new source of redundancy in its outputs. Each output it returns will now have to individually evaluate it's input, so a chain of DSL functions that output 2 or more values will suffer from the same exponential scaling of hashcons.

One solution to this issue is to integrate container types such as tuples and lists into the DSL language. However doing this will take away form the advantages of having an embedded language, manipulating tuple values will be cumbersome constantly requiring calls to custom implementations of fst/snd etc. And for lists you'll lose all access to built-in Haskell list functionality.

3 Implicit Sharing Via ByteString ASTs

The heart of our problem is whenever we need to sequence the state of the inputs for one of our DSL functions we want to first check if it's already been evaluated. But how do we do that without first evaluating it to gain access to it's unique NodeID. We need some other way to uniquely identify it.

Our proposed solution is too build an AST using byte strings along with our DAG, but hold it outside of the State monad. We can then build our DAG using a Trie, using the byte string AST to lookup our node identifiers instead.

The Trie essentially serves as our new BiMap, the resulting DAG contained in its lookup values. We essentially still perform the hash-consing technique but using the AST to perform the lookup

```
hashcons :: ByteString -> Node -> State DAG NodeID
hashcons sAST node = do
```

```
DAG trie maxID <- get</pre>
case Trie.lookup sAST trie of
  Nothing -> let maxID' = maxID+1
                  trie' = Trie.insert sAST (node,maxID+1) trie
               in do put $ DAG trie' maxID'
                     return maxID'
   Just (_,nodeID) -> return nodeID
instance Exp Graph where
  constant x = let
    node = NConstant x
    sAST = buildStringAST node []
    in Graph (hashcons sAST $ NConstant x) sAST
  variable x = let
    node = NVariable x
    sAST = buildStringAST node []
    in Graph (hashcons sAST $ NVariable x) sAST
  add e1 e2 = let
      sAST = buildStringAST (NAdd undefined undefined) [unStringAST e1,unStringAST e2]
      sT = do ns <- seqArgs [e1,e2]
              case ns of
                [n1,n2] -> hashcons sAST $ NAdd n1 n2
                _ -> error "black magic"
    in Graph sT sAST
```

The instance implementations for constant and variable work roughly the same, the novelty of the method is in how we handle DSL functions that take other DSL State as input like add. First we need to construct a byte string AST from it's input ASTs, there's a lot of ways we could go about this to attempt to minimize memory. A naive implementation would look similar to a pretty printer. Then we need to sequence it's inputs without evaluating the inner state if unnecessary. We do this through the implementation of seqArgs

```
seqArgs :: [Graph a] -> State DAG [NodeID]
seqArgs inps =
  let
    seqArg (Graph sT sAST) =
    do DAG trie _ <- get
        case Trie.lookup sAST trie of
        Nothing -> sT
        Just (_,nodeID) -> return nodeID
  in sequence $ map seqArg inps
```

We only evaluate the inner state sT of each argument if we fail to look up its corresponding byte string AST in the Trie. This will prevent redundant hashconsing without the need for explicit sharing. However this method suffers from its own drawbacks.

3.1 Memory Limitations

The byte string AST being built will itself suffer from lack of sharing. We're essentially trading extra computation for extra memory. This is often a good tradeoff, since memory is so plentiful in modern hardware. But under the right conditions it can become an issue

TODO include heap profiling analysis

4 Explicit Sharing Of ByteString ASTs

We propose another solution to this issue, taking inspiration again from the [5], we can introduce an explicit construct for specifying sharing. This time, the construct will substitute the current byte string for a more compact label. For safety purposes, we need to keep track of a table of these labels and their corresponding ASTs, to make sure we don't insert of the same labels.

The cache operation replaces the current byte string AST with a new label, and we'll define a new operation runCache that will check if the label already exists in the cache map before inserting it.

```
runCache :: ByteString -> Maybe ByteString -> Trie ByteString -> State DAG ()
runCache sAST mAddCache cacheMap = do
  case mAddCache of
   Nothing -> return ()
   Just sASTO ->
```

We need to make sure we don't attempt to insert the same cache label for two different ASTs. Unfortunately, if there is a collision there's no way to escape the State monad to prevent or modify the subtitution. The best we can do is crash the program, or if we use a monad tansformer, we ould use Control.Monad.Except to through an exception. Either way it's up to the DSL writer to insure they don't reuse the same label.

5 Conclusion

TODO

Acknowledgements Please place your acknowledgments at the end of the paper, preceded by an unnumbered run-in heading (i.e. 3rd-level heading).

References

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