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Least-Square function approximation.

Interpolation vs curve fitting:

In function interpolation our goal was to find a function f that fits some given points $\{ (x_i, y_i) = 1, 2, \dots, n \}$

Assume we have $n+1$ points $(x_1, y_1), \dots, (x_{n+1}, y_{n+1})$.
(given $x_i \neq x_j$ if $i \neq j$). A polynomial of degree n is of the form $P_n(x) = a_n x^n + \dots + a_1 x + a_0$. To study the existence and uniqueness of such polynomial consider the system of linear equations,

$$\begin{aligned} y_1 &= a_0 + a_1 x_1 + \dots + a_n x_1^n \\ &\vdots \\ y_{n+1} &= a_0 + a_1 x_{n+1} + \dots + a_n x_{n+1}^n \end{aligned}$$

We ~~will~~ write system as

$$\begin{pmatrix} x_1^n & x_1^{n-1} & \dots & 1 \\ \vdots & \vdots & \ddots & \vdots \\ x_{n+1}^n & x_{n+1}^{n-1} & \dots & 1 \end{pmatrix} \begin{pmatrix} a_n \\ \vdots \\ a_1 \\ a_0 \end{pmatrix} = \begin{pmatrix} y_1 \\ \vdots \\ y_{n+1} \end{pmatrix}$$

Since matrix of coefficients of the system is non-singular (by fact Vandermonde matrix) the system have unique solution, that is there exist one polynomial of degree n through the $(n+1)$ given points and it is unique.

Discarding the points that is most different from other points is good idea. ⁽²⁾

Paramaterized Functions and Measure of fitness :-

Let f_θ be a function paramaterized ~~function~~ θ , which can be scalar, vector fitness or countable sequence,

$$f_\theta(x) = \sin(\theta x) \quad \text{or} \quad f_\theta(x) = \sum_{i=0}^k \theta_i x^i$$

Natural measure of fit,

$$\sum_{i=1}^m (y_i - f_\theta(x_i))^2 \quad \dots \quad (\text{LSMA})$$

We can find best fit ~~curve~~ ^{curve} as follows,

$$\min_{\theta} \sum_{i=1}^m (y_i - f_\theta(x_i))^2$$

for best fit ~~curve~~ line,

$$\min_{a_0, a_1} \sum_{i=1}^m [y_i - (a_0 + a_1 x_i)]^2$$

We want to minimize,

$$E = \sqrt{\frac{1}{n} \sum_{i=1}^n [f(x_i) - y_i]^2}$$

When considering all possible functions,

$$f(x) = mx + b,$$

Note that minimizing b is equivalent to ~~min~~ minimizing sum, ~~althoug~~ i.e. to minimize

$$G(b, m) = \sum_{i=1}^n [mx_i + b - y_i]^2$$

as b and m are allowed vary arbitrarily

$$\therefore \frac{\partial G(b, m)}{\partial b} = 0 \quad , \quad \frac{\partial G(b, m)}{\partial m} = 0$$

Use $\frac{\partial G}{\partial b} = \sum_{i=1}^n 2 [mx_i + b - y_i]$ (3)

$$\frac{\partial G}{\partial b} = \sum_{i=1}^n 2 [mx_i + b - y_i] x_i = \sum_{i=1}^n 2 [mx_i^2 + bx_i - x_i y_i]$$

This leads to Linear equation,

$$nb + \left(\sum_{i=1}^n x_i \right) m = \sum_{i=1}^n y_i$$

in other words:

$$\left(\sum_{i=1}^n x_i \right) b + \left(\sum_{i=1}^n x_i^2 \right) m = \sum_{i=1}^n x_i y_i$$

$$\therefore \left(\sum_{i=1}^n x_i \right) b + \left(\sum_{i=1}^n x_i^2 \right) m = \sum_{i=1}^n x_i y_i$$

In other words, $a_0 \sum_{i=1}^m x_i + a_1 \sum_{i=1}^m x_i^2 = \sum_{i=1}^m x_i y_i$

⇒ Equation for best fit polynomial will be of form,

$$\min_{a_0, a_1, \dots, a_n} \sum_{i=1}^m \left[y_i - \sum_{j=0}^n a_j x_i^j \right]^2$$

can be proved using similar methods above mentioned.

* Least-Square approximations using of a function using monomial polynomials:-

Given a function $f(x)$ continuous [a,b] find a polynomial $P_n(x)$ of degree at most n .

$$P_n(x) = a_0 + a_1 x + \dots + a_n x^n$$

such that integral of square is minimized,

$$\min_{a_0, a_1, \dots, a_n} \int_a^b (f(x) - P_n(x))^2 dx$$

We would need to solve following equations

$$\sum_{k=0}^n a_k \int_a^b x^{j+k} dx = \int_a^b x^j f(x) dx \quad \forall j \in \{0, 1, \dots, n\}$$

we have.

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ILL conditioned matrix:-

The Normal equations have following form,

$$S a = b$$

Every matrix can be written in SVD form,

$$M = U \Sigma V^T \text{ where } \Sigma \text{ has diagonal entries}$$

having singular values.

condition number is matrix ratio to max. Σ to min Σ .

⊕ A matrix is said to be ill-conditioned if condition number is large.

We can use such matrix for finding error when solving system of linear equations.

orthogonal functions:-

A set of functions $\{\phi_1, \phi_2, \dots, \phi_n\}$ in $[a, b]$ are called orthogonal functions wrt $w(x)$ if,

$$\int_a^b w(x) \phi_i(x) \phi_j(x) dx = \begin{cases} 0 & \text{if } i \neq j \\ c_j & \text{if } i = j \end{cases}$$

Where c_j is +ve number. if $c_j = 1 \forall j$ then set is called orthonormal set.

using orthogonal functions:-

We are interested in ~~LSE~~ LSEA of $f(x)$ on $[a, b]$ by means of polynomial form,

$$Q_n(x) = \sum_{i=0}^n a_i \phi_i(x)$$

where $\{\phi_i\}_{i=0}^n$ is a set of orthogonal polynomial

$$[a, b] \text{ s.t. } \min_{a_0, a_1, \dots, a_n} \int_a^b w(x) \cdot (f(x) - Q_n(x))^2 dx.$$

Using orthogonal functions,

$$\int_a^b w(x) \phi_j(x) f(x) dx = \int_a^b w(x) \phi_j(x) \left(\sum_{i=0}^n a_i \phi_i(x) \right) dx = g_j a_j$$

or we have,

$$a_j = \frac{1}{g_j} \int_a^b w(x) \phi_j(x) f(x) dx \quad \forall j$$

Where, $g_j = \int_a^b w(x) \phi_j^2 dx$.

Legendre Polynomial

$$L_n(x) = \frac{1}{2^n n!} \frac{d^n}{dx^n} (x^2-1)^n$$

The above polynomial is orthogonal in $[-1, 1]$ wrt weight function $w(x) = 1$.

$$L_1(x) = \frac{1}{2^1 1!} \frac{d^1}{dx^1} (x^2-1)^1 = x$$

$$L_2(x) = \frac{1}{2^2 2!} \frac{d^2}{dx^2} (x^2-1)^2 = \frac{3}{2} x^2 - \frac{1}{2}$$

$$L_3(x) = \frac{5}{2} x^3 - \frac{3}{2} x$$

consider, $L_1(x) \cdot L_2(x)$ we get $\left(\frac{3}{2} x^3 - \frac{1}{2} x\right)$

by integrating this function in range $[-1, 1]$ we ~~get~~ ~~as it still get even function~~ will get 0.

Chebyshev Polynomial:-

$$T_n(x) = \cos(n \cos^{-1}(x))$$

is $T_n(x)$ is really polynomial, in fact we

have, $T_0(x) = 1$ and $T_1(x) = x$,

further we have, $T_{n+1}(x) = 2x T_n(x) - T_{n-1}(x)$

Recall trigonometric addition formulas,

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$$\cos(\alpha \pm \beta) = \cos(\alpha) \cos(\beta) \mp \sin(\alpha) \sin(\beta)$$

Let $n \geq 1$ apply these identities to get,

$$\begin{aligned} \text{i) } T_{n+1}(x) &= \cos[(n+1)\theta] = \cos(n\theta + \theta) \\ &= \cos(n\theta) \cos\theta - \sin(n\theta) \sin\theta \end{aligned}$$

$$\begin{aligned} \text{ii) } T_{n-1}(x) &= \cos[(n-1)\theta] = \cos(n\theta - \theta) \\ &= \cos(n\theta) \cos\theta + \sin(n\theta) \sin\theta \end{aligned}$$

Add above two equations & we will get

$$T_{n+1}(x) + T_{n-1}(x) = 2 \cos(n\theta) \cos\theta = 2x T_n(x)$$

Hence, $T_{n+1}(x) = 2x T_n(x) - T_{n-1}(x), n \geq 1$

Fourier Series:-

For any positive integer n , the set of functions $\{1, \cos(x), \dots, \cos(nx), \sin(x), \dots, \sin(nx)\}$ is orthogonal in interval $[-\pi, \pi]$ wrt weight function $w(x) = 1$.

for any two $\cos(ax) \cdot \sin(bx)$ & a & b we have,
we have, $\cos(ax) \sin(bx) = \frac{1}{2} (\sin(ax+bx) - \sin(ax-bx))$

On Integration, $= \int_0^{2\pi} \cos(ax) \sin(bx) dx$

$$= \int_0^{2\pi} \frac{1}{2} (\sin(ax+bx) - \sin(ax-bx)) dx$$

$$= \left[\frac{\cos(a-b)x}{2(a-b)} - \frac{\cos(a+b)x}{2(a+b)} \right]_0^{2\pi} = 0$$

Let, $S_n(x) = \frac{a_0}{2} + \sum_{k=1}^n a_k \cos(kx) + \sum_{k=1}^n b_k \sin(kx)$

Such that least square is minimized i.e.

$$\min \int_{-\pi}^{\pi} (f(x) - S_n(x))^2 dx$$

Equating partial derivatives to zero,
due to orthogonality we get,

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$$a_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \cos(kx) dx, \quad b_k = \frac{1}{\pi} \int_{-\pi}^{\pi} f(x) \sin(kx) dx$$

Suppose we have $2m$ data points x_k, y_k ~~we have~~,
where,

$$x_k = -\pi + \frac{k\pi}{m} \quad \text{and} \quad y_k = f(x_k), \quad k = \{0, 1, \dots, 2m-1\}$$

The discrete least square trigonometric polynomial
does the following,

$$\min \sum_{k=0}^{2m-1} (S_n(x_k) - y_k)^2$$

DFT

if r is not multiple of $2m$

$$\sum_{k=0}^{2m-1} \cos(rx_k) = \sum_{k=0}^{2m-1} \sin(rx_k) = 0$$

if $r \neq 0$ is not multiple of m ,

$$\sum_{k=0}^{2m-1} [\cos(rx_k)]^2 = \sum_{k=0}^{2m-1} [\sin(rx_k)]^2 = m$$

if $r \neq l$ and $r+l$ is not a multiple of $2m$,

$$\sum_{k=0}^{2m-1} \cos(rx_k) \cos(lx_k) = \sum_{k=0}^{2m-1} \sin(rx_k) \sin(lx_k) = 0$$

$$\sum_{k=0}^{2m-1} \cos(rx_k) \sin(lx_k) = \sum_{k=0}^{2m-1} \sin(rx_k) \cos(lx_k) = 0$$

then for any $n < m$ the best approximation is

$$S_n(x) = \frac{a_0}{2} + \sum_{k=1}^n a_k \cos(kx) + \sum_{k=1}^n b_k \sin(kx)$$

due to previous 3 lemma, we have

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$$a_k = \frac{1}{m} \sum_{j=0}^{2m-1} y_j \cos(k n_j) \text{ and } b_k = \frac{1}{m} \sum_{j=0}^{2m-1} y_j \sin(k n_j)$$

let $h = m-1$ Then

$$\{y_j\}_{j=0}^{2m-1} \xrightarrow{\text{DFT}} \{(a_k, b_k)\}_{k=0}^{m-1}$$

if $n \geq m$ ~~then~~? we may not have enough equations to solve for all different values of a_k and b_k since every value of m gave one pair of values a_k and b_k .