

Wiring Diagram Book



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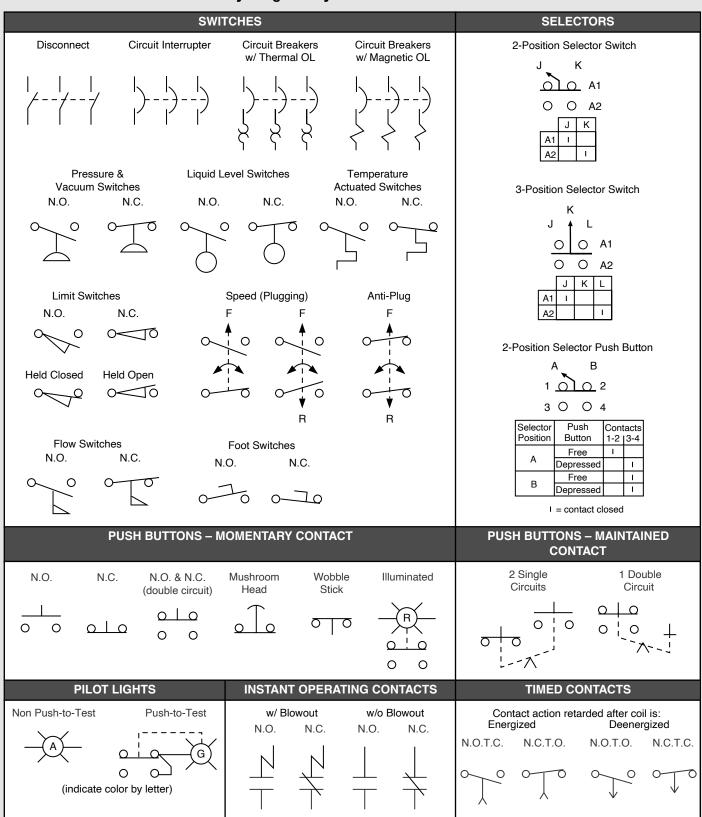
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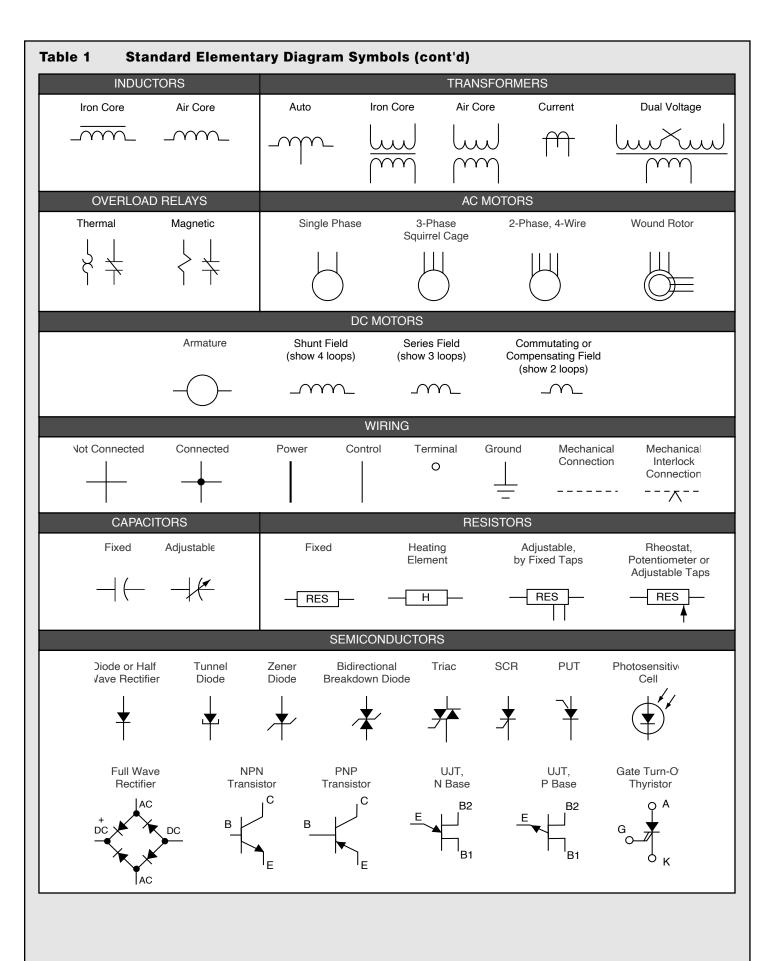
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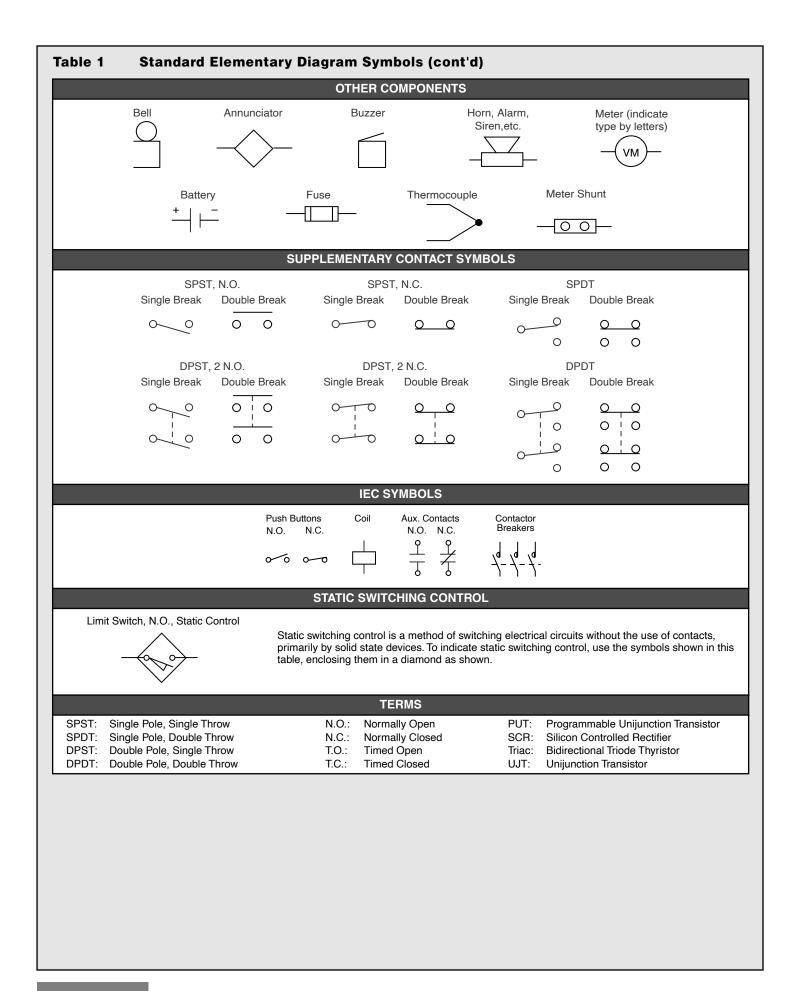


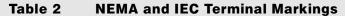
The diagram symbols in Table 1 are used by Square D and, where applicable, conform to NEMA (National Electrical Manufacturers Association) standards.

Table 1 Standard Elementary Diagram Symbols









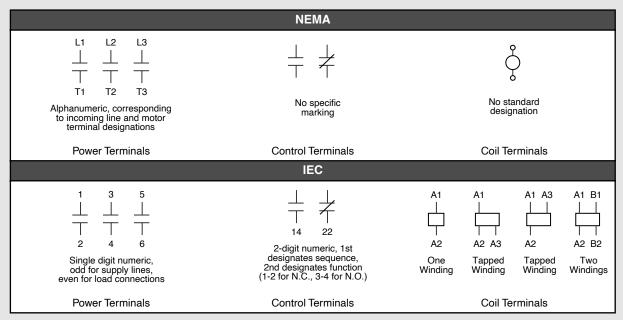


Table 3 NEMA and IEC Controller Markings and Elementary Diagrams

Table 4 Control and Power Connections for Across-the-Line Starters, 600 V or less (From NEMA standard ICS 2-321A.60)

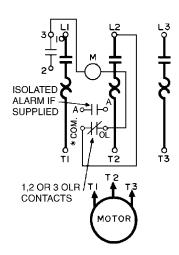
		1-Phase	2-Phase, 4-Wire	3-Phase
Line Markings		L1, L2	L1, L3: Phase 1 L2, L4: Phase 2	L1, L2, L3
Ground, when used		L1 is always ungrounded	_	L2
Motor Running	1 element	L1	_	_
Overcurrent,	2 element	_	L1, L4	_
units in:	3 element	_	_	L1, L2, L3
Control Circuit Connected to		L1, L2	L1, L3	L1, L2
For Reversing, Interchange Lines		_	L1, L3	L1, L3

WIRING DIAGRAM

A wiring diagram shows, as closely as possible, the actual location of all component parts of the device. The open terminals (marked by an open circle) and arrows represent connections made by the user.

Since wiring connections and terminal markings are shown, this type of diagram is helpful when wiring the device or tracing wires when troubleshooting. Bold lines denote the power circuit and thin lines are used to show the control circuit. Black wires are conventionally used in power circuits and red wire in control circuits for AC magnetic equipment.

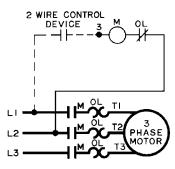
A wiring diagram is limited in its ability to completely convey the controller's sequence of operation. The elementary diagram is used where an illustration of the circuit in its simplest form is desired.



ELEMENTARY DIAGRAM

An elementary diagram is a simplified circuit illustration. Devices and components are not shown in their actual positions. All control circuit components are shown as directly as possible, between a pair of vertical lines representing the control power supply. Components are arranged to show the sequence of operation of the devices and how the device operates. The effect of operating various auxiliary contacts and control devices can be readily seen. This helps in troubleshooting, particularly with the more complex controllers.

This form of electrical diagram is sometimes referred to as a "schematic" or "line" diagram.



Examples of Control Circuits

2- and 3-Wire Control Elementary Diagrams

Low Voltage Release and Low Voltage Protection are the basic control circuits encountered in motor control applications. The simplest schemes are shown below. Other variations shown in this section may appear more complicated, but can always be resolved into these two basic schemes

Note: The control circuits shown in this section may not include overcurrent protective devices required by applicable electrical codes. See page 11 for examples of control circuit overcurrent protective devices and their use.

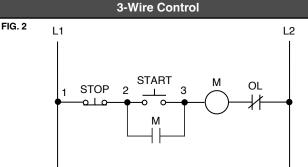
FIG. 1 L1 L2 PILOT DEVICE SUCH AS LIMIT SWITCH, PRESSURE SWITCH, ETC.

Low voltage release is a 2-wire control scheme using a maintained contact pilot device in series with the starter coil.

This scheme is used when a starter is required to function automatically without the attention of an operator. If a power failure occurs while the contacts of the pilot device are closed, the starter will drop out. When power is restored, the starter will automatically pickup through the closed contacts of the pilot device.

The term "2-wire" control is derived from the fact that in the basic circuit, only two wires are required to connect the pilot device to the starter.

Low Voltage Protection:

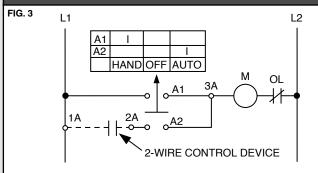


Low voltage protection is a 3-wire control scheme using momentary contact push buttons or similar pilot devices to energize the starter coil.

This scheme is designed to prevent the unexpected starting of motors, which could result in injury to machine operators or damage to the driven machinery. The starter is energized by pressing the Start button. An auxiliary holding circuit contact on the starter forms a parallel circuit around the Start button contacts, holding the starter in after the button is released. If a power failure occurs, the starter will drop out and will open the holding circuit contact. When power is restored, the Start button must be operated again before the motor will restart.

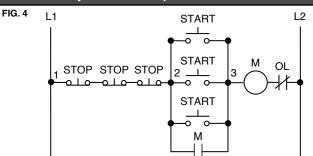
The term "3-wire" control is derived from the fact that in the basic circuit, at least three wires are required to connect the pilot devices to the starter.

2-Wire Control: Maintained Contact Hand-OFF-Auto Selector Switch



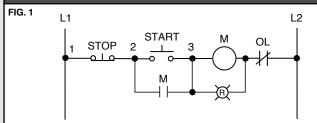
A Hand-Off-Auto selector switch is used on 2-wire control applications where it is desirable to operate the starter manually as well as automatically. The starter coil is manually energized when the switch is turned to the Hand position and is automatically energized by the pilot device when the switch is in the Auto position.

3-Wire Control: Momentary Contact Multiple Push Button Station



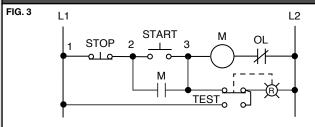
When a motor must be started and stopped from more than one location, any number of Start and Stop push buttons may be wired together. It is also possible to use only one Start-Stop station and have several Stop buttons at different locations to serve as an emergency stop.

3-Wire Control: Pilot Light Indicates when Motor is Running



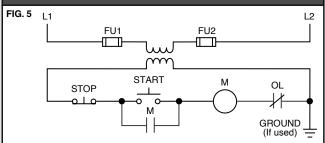
A pilot light can be wired in parallel with the starter coil to indicate when the starter is energized, indicating the motor is running.

3-Wire Control: Push-to-Test Pilot Light Indicates when Motor is Running



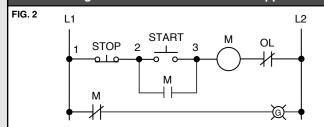
When the Motor Running pilot light is not lit, there may be doubt as to whether the circuit is open or whether the pilot light bulb is burned out. To test the bulb, push the color cap of the Pushto-Test pilot light.

3-Wire Control: Fused Control Circuit Transformer



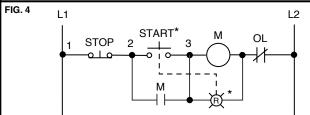
As an operator safety precaution, a step-down transformer can be used to provide a control circuit voltage lower than line voltage. The diagram above shows one way to provide overcurrent protection for control circuits.

3-Wire Control: Pilot Light Indicates when Motor is Stopped



A pilot light may be required to indicate when the motor is stopped. This can be implemented by wiring a normally-closed auxiliary contact on the starter in series with the pilot light, as shown above. When the starter is deenergized, the pilot light illuminates. When the starter picks up, the auxiliary contact opens, turning off the light.

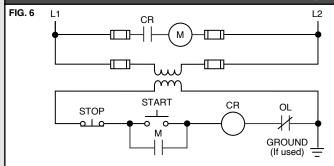
3-Wire Control: Illuminated Push Button Indicates when Motor is Running



* Pushing on pilot light operates Start contacts.

The illuminated push button combines a Start button and pilot light in one unit. Pressing the pilot light lens operates the Start contacts. Space is saved by using a two-unit push button station instead of three.

3-Wire Control: Fused Control Circuit Transformer and Control Relay



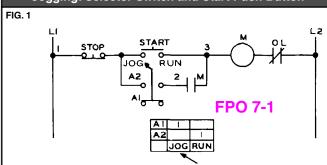
A starter coil with a high VA rating may require a control transformer of considerable size. A control relay and a transformer with a low VA rating can be connected so the normally-open relay contact controls the starter coil on the primary or line side. Square D Size 5 Combination Starter Form F4T starters use this scheme.

Examples of Control Circuits

3-Wire Control

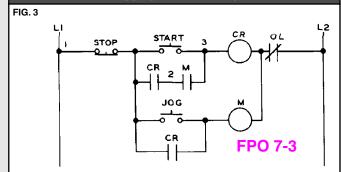
Elementary Diagrams

Jogging: Selector Switch and Start Push Button



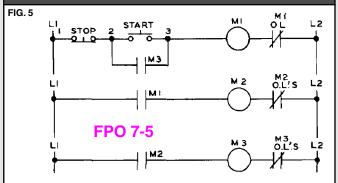
Jogging, or inching, is defined by NEMA as the momentary operation of a motor from rest for the purpose of accomplishing small movements of the driven machine. One method of jogging is shown above. The selector switch disconnects the holding circuit contact and jogging may be accomplished by pressing the Start push button.

Jogging: Control Relay



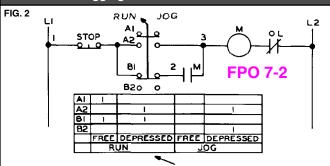
When the Start push button is pressed, the control relay is energized, which in turn energizes the starter coil. The normally-open starter auxiliary contact and relay contact then form a holding circuit around the Start push button. When the Jog push button is pressed, the starter coil is energized (independent of the relay) and no holding circuit forms, thus jogging can be obtained.

3-Wire Control: More than 1 Starter, 1 Push Button Station Controls all



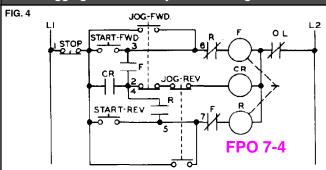
When one Start-Stop station is required to control more than one starter, the scheme above can be used. A maintained overload on any one of the motors will drop out all three starters.

Jogging: Selector Push Button



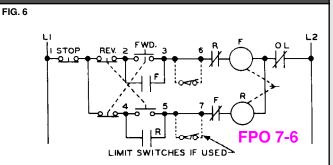
A selector push button may be used to obtain jogging, as shown above. In the Run position, the selector-push button provides normal 3-wire control. In the Jog position, the holding circuit is broken and jogging is accomplished by depressing the push button.

Jogging: Control Relay for Reversing Starter



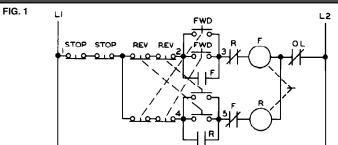
This control scheme permits jogging the motor either in the forward or reverse direction, whether the motor is at standstill or rotating. Pressing the Start-Forward or Start-Reverse push button energizes the corresponding starter coil, which closes the circuit to the control relay. The relay picks up and completes the holding circuit around the Start button. As long as the relay is energized, either the forward or reverse contactor remains energized. Pressing either Jog push button will deenergize the relay, releasing the closed contactor. Further pressing of the Jog button permits jogging in the desired direction.

3-Wire Control: Reversing Starter



3-wire control of a reversing starter can be implemented with a Forward-Reverse-Stop push button station as shown above. Limit switches may be added to stop the motor at a certain point in either direction. Jumpers 6 to 3 and 7 to 5 must then be removed.

3-Wire Control: Reversing Starter Multiple Push Button Station

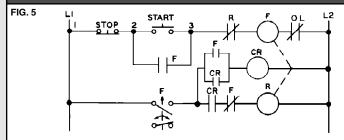


More than one Forward-Reverse-Stop push button station may be required and can be connected in the manner shown above.

3-Wire Control: 2-Speed Starter

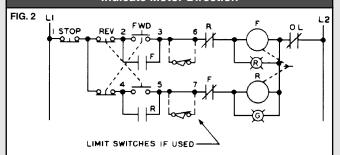
3-wire control of a 2-speed starter with a High-Low-Stop push button station is shown above. This scheme allows the operator to start the motor from rest at either speed or to change from low to high speed. The Stop button must be operated before it is possible to change from high to low speed. This arrangement is intended to prevent excessive line current and shock to motor and driven machinery, which results when motors running at high speed are reconnected for a lower speed.

Plugging: Plugging a Motor to a Stop from 1 Direction Only



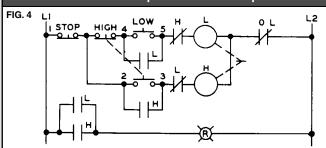
Plugging is defined by NEMA as a braking system in which the motor connections are reversed so the motor develops a counter torque, thus exerting a retarding force. In the above scheme, forward rotation of the motor closes the normally-open plugging switch contact and energizing control relay CR. When the Stop push button is operated, the forward contactor drops out, the reverse contactor is energized through the plugging switch, control relay contact and normally-closed forward auxiliary contact. This reverses the motor connections and the motor is braked to a stop. The plugging switch then opens and disconnects the reverse contactor. The control relay also drops out. The control relay makes it impossible for the motor to be plugged in reverse by rotating the motor rotor closing the plugging switch. This type of control is not used for running in reverse.

3-Wire Control: Reversing Starter w/ Pilot Lights to Indicate Motor Direction



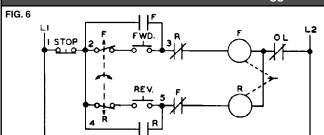
Pilot lights may be connected in parallel with the forward and reverse contactor coils, indicating which contactor is energized and thus which direction the motor is running.

3-Wire Control: 2-Speed Starter w/ 1 Pilot Light to Indicate Motor Operation at Each Speed



One pilot light may be used to indicate operation at both low and high speeds. One extra normally-open auxiliary contact on each contactor is required. Two pilot lights, one for each speed, may be used by connecting pilot lights in parallel with high and low coils (see reversing starter diagram above).

Anti-Plugging: Motor to be Reversed but Must Not be Plugged



Anti-plugging protection is defined by NEMA as the effect of a device that operates to prevent application of counter-torque by the motor until the motor speed has been reduced to an acceptable value. In the scheme above, with the motor operating in one direction, a contact on the anti-plugging switch opens the control circuit of the contactor used for the opposite direction. This contact will not close until the motor has slowed down, after which the other contactor can be energized.

Examples of Control Circuits

Shunting Thermal Units During Starting Period Elementary Diagrams

Shunting Thermal Units During Starting Period

Article 430-35 of the NEC describes circumstances under which it is acceptable to shunt thermal units during abnormally long accelerating periods.

430-35. Shunting During Starting Period.

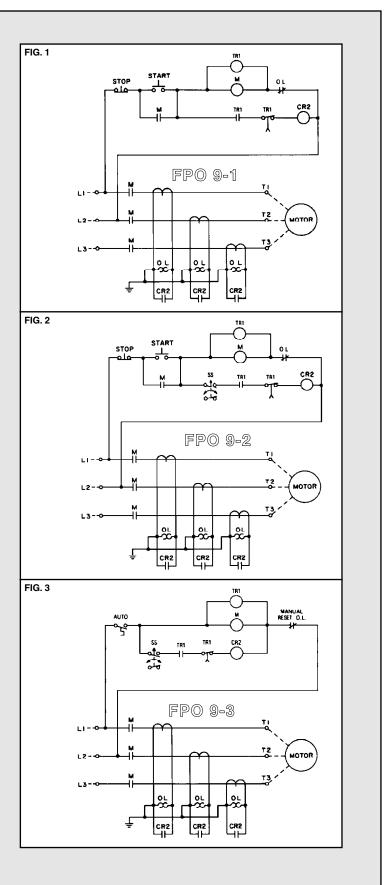
- (a) Nonautomatically Started. For a nonautomatically started motor, the overload protection shall be permitted to be shunted or cut out of the circuit during the starting period of the motor if the device by which the overload protection is shunted or cut out cannot be left in the starting position and if fuses or inverse time circuit breakers rated or set at not over 400 percent of the full-load current of the motor are so located in the circuit as to be operative during the starting period of the motor.
- (b) Automatically Started. The motor overload protection shall not be shunted or cut out during the starting period if the motor is automatically started.

Exception. The motor overload protection shall be permitted to be shunted or cut out during the starting period on an automatically started motor where:

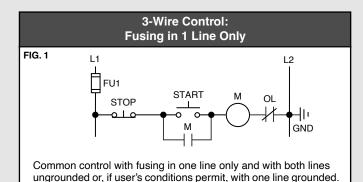
- (1) The motor starting period exceeds the time delay of available motor overload protective devices, and
- (2) Listed means are provided to:
 - Sense motor rotation and to automatically prevent the shunting or cut out in the event that the motor fails to start, and
 - Limit the time of overload protection shunting or cut out to less than the locked rotor time rating of the protected motor, and
 - c. Provide for shutdown and manual restart if motor running condition is not reached.

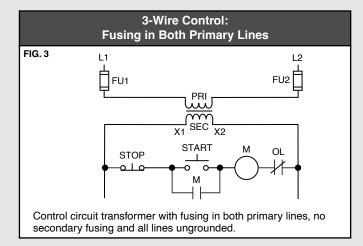
Figures 1 and 2 show possible circuits for use in conjunction with 3-wire control schemes. Figure 1 complies with NEC requirements. Figure 2 exceeds NEC requirements, but the additional safety provided by the zero speed switch might be desirable.

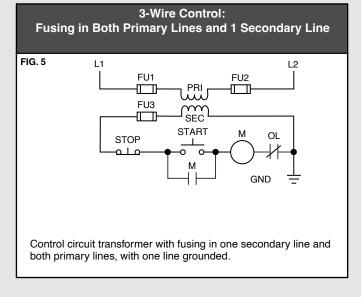
Figure 3 shows a circuit for use with a 2-wire, automatically started control scheme that complies with NEC requirements. UL or other listed devices must be used in this arrangement.

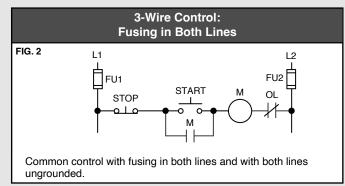


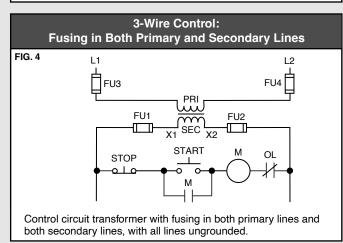
Overcurrent Protection for 3-Wire Control Circuits Elementary Diagrams

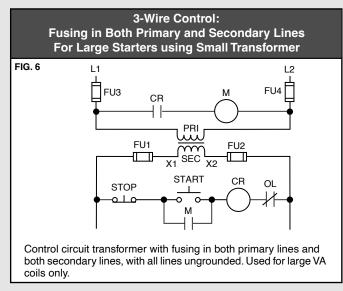




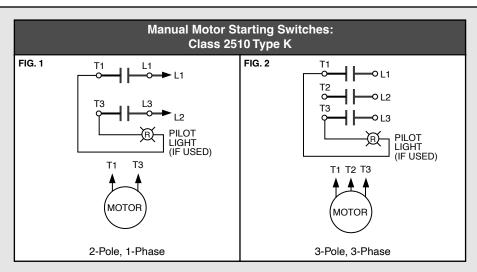


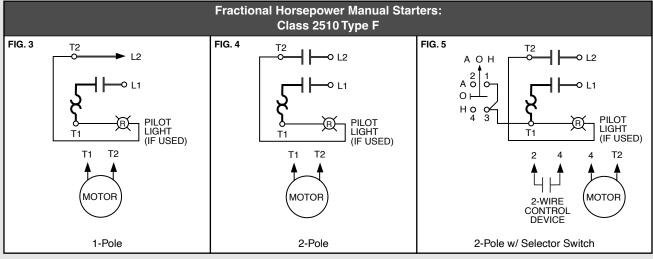


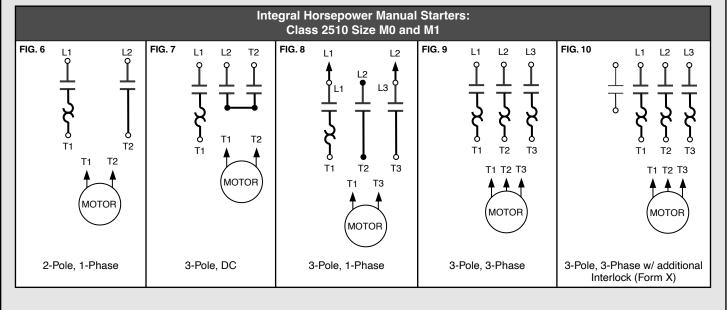


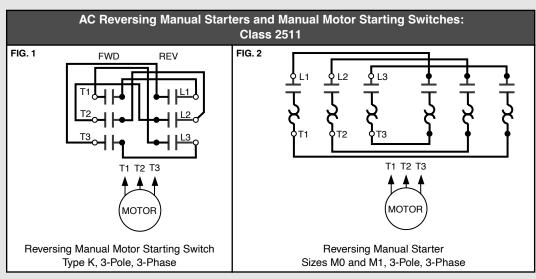


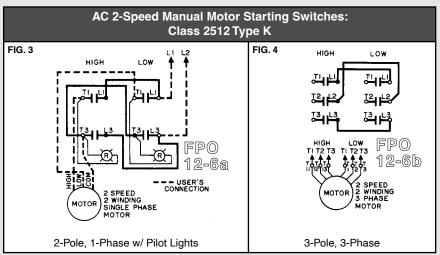
Class 2510

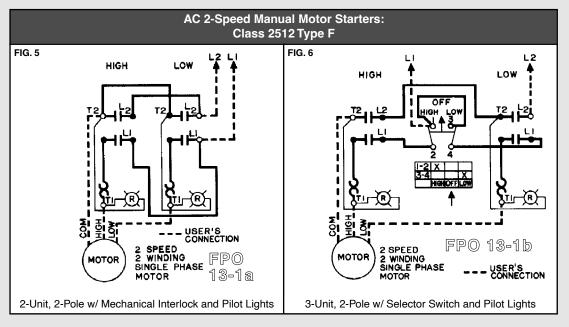






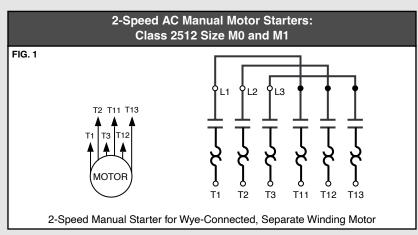


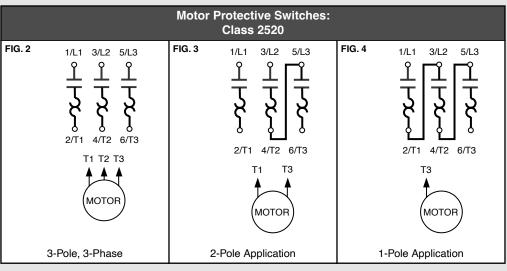


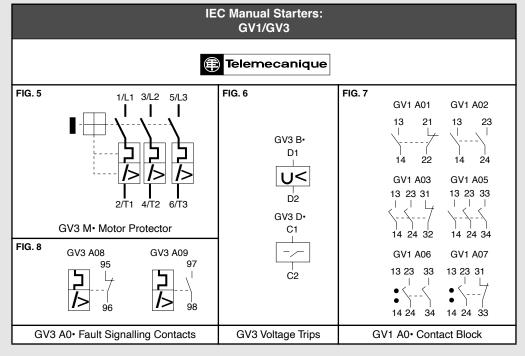


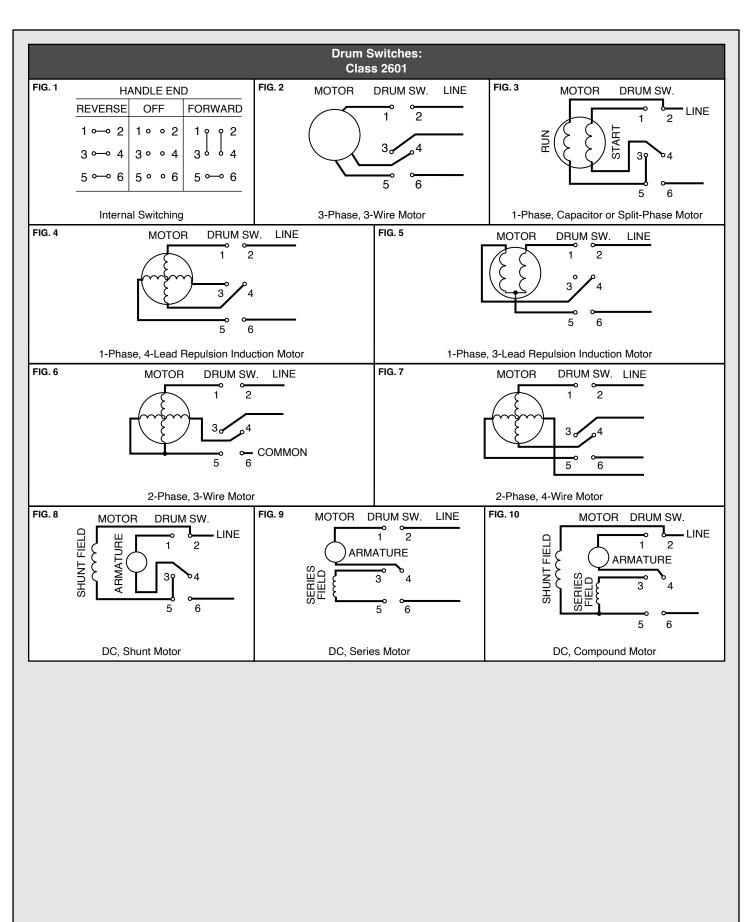
2-Speed AC Manual Starters and IEC Motor Protectors

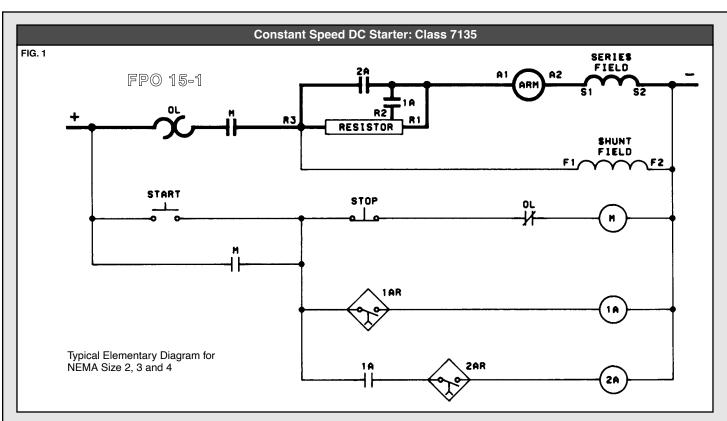
Class 2512 and 2520 and Telemecanique GV1/GV3

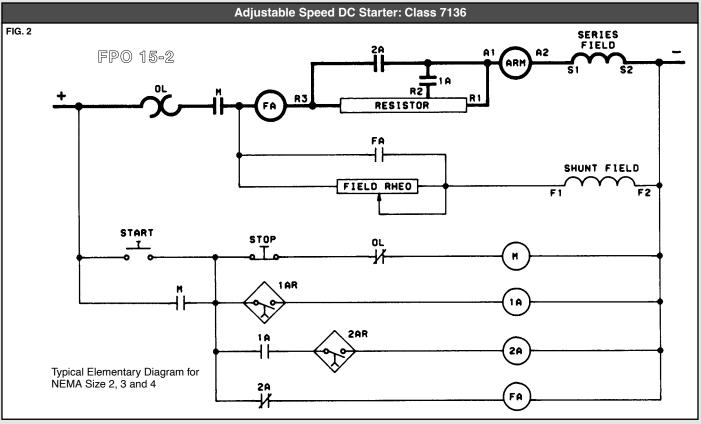




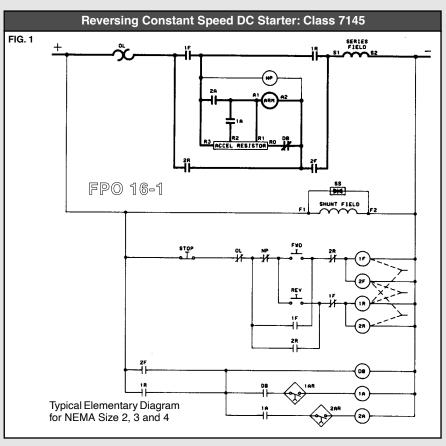


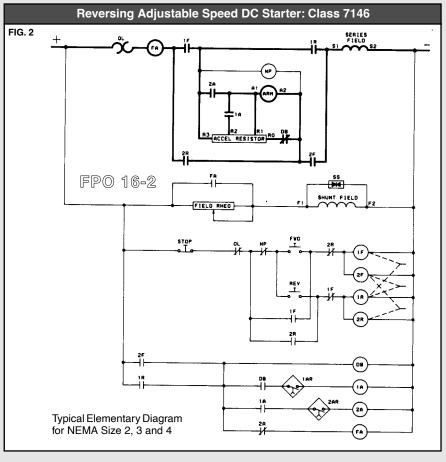




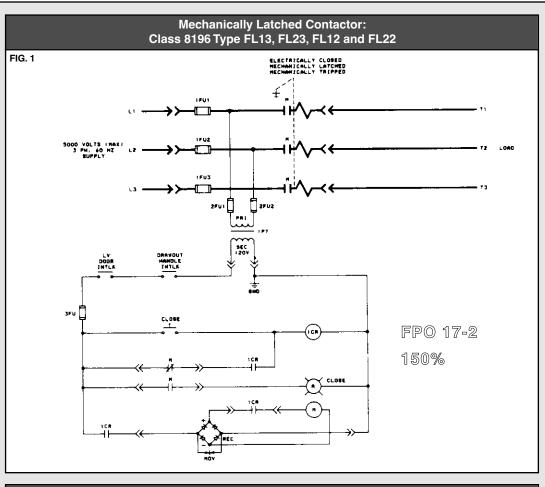


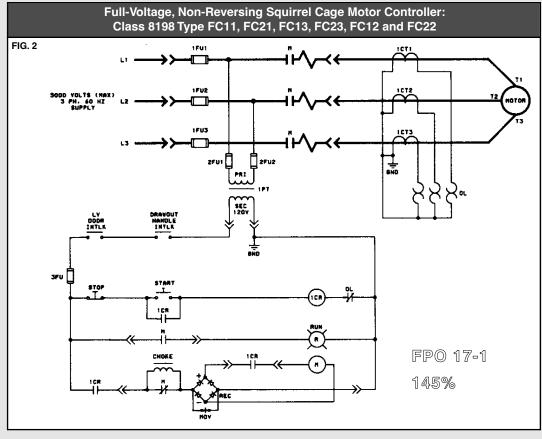
Acceleration Contactors: Class 7135, 7136, 7145 and 7146						
NEMA Size	1	2	3	4	5	
No. of Acceleration Contactors	1	2	2	2	3	

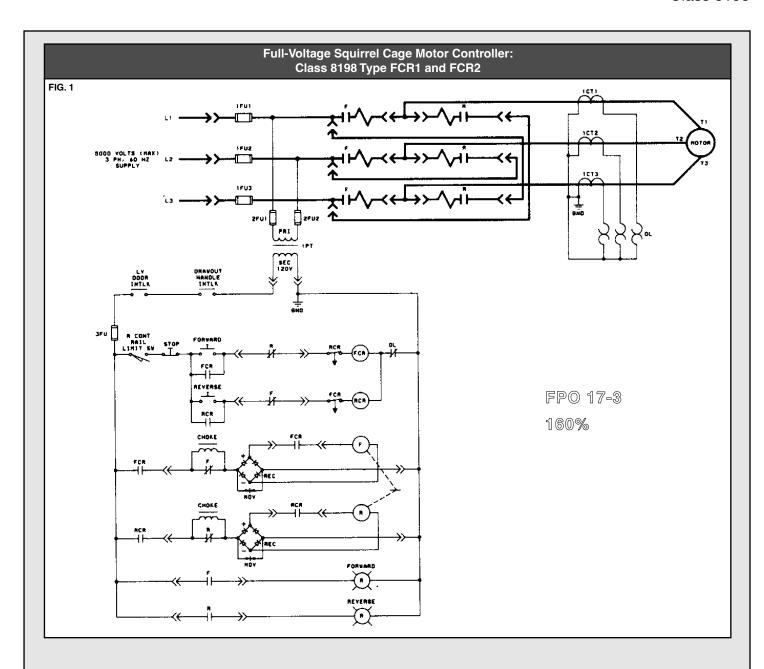




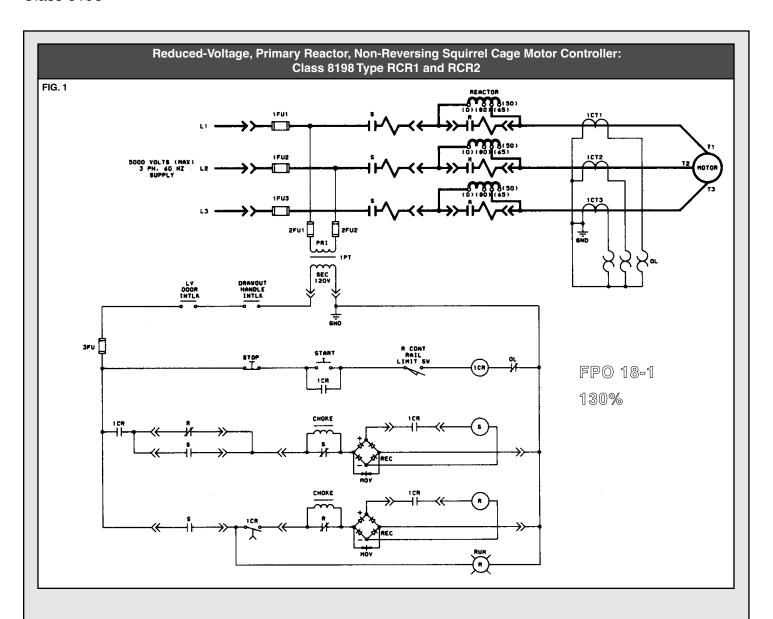
Class 8196 and 8198

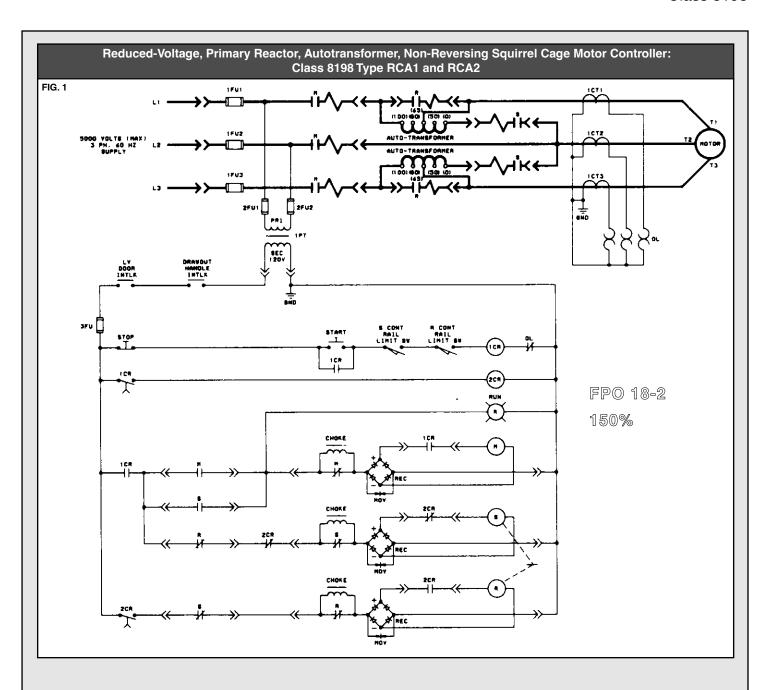




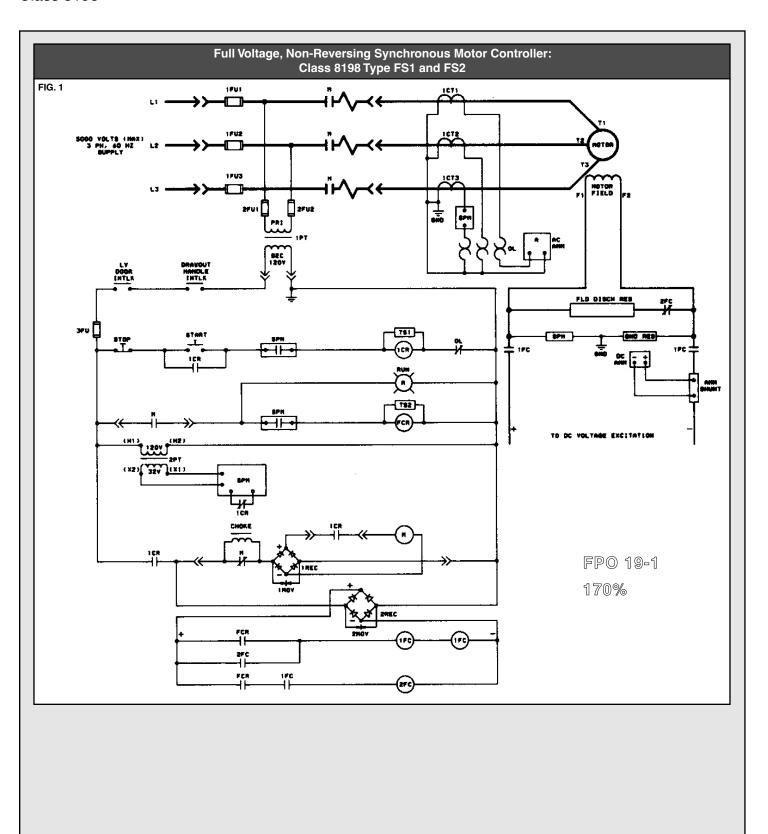


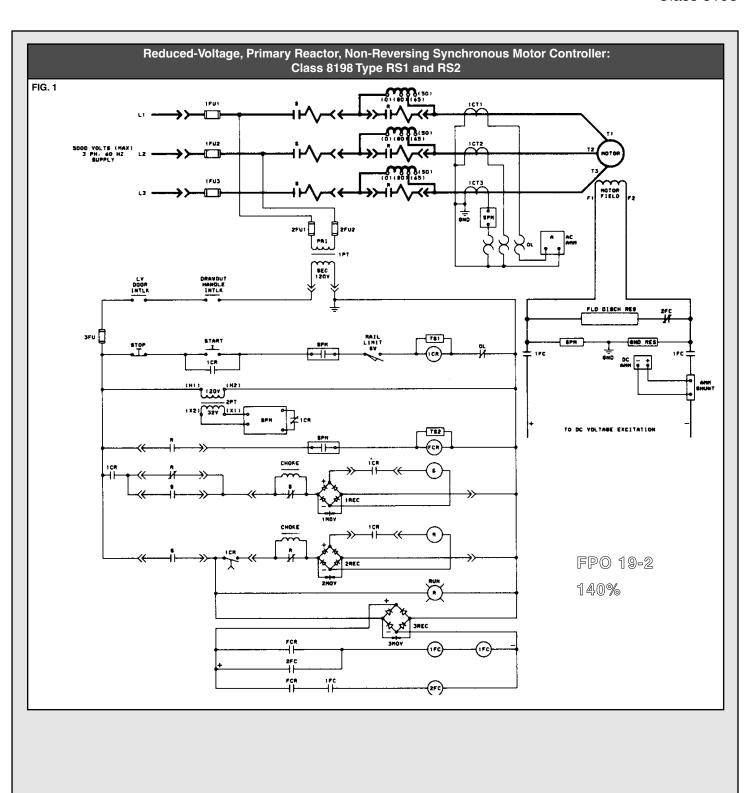
Class 8198

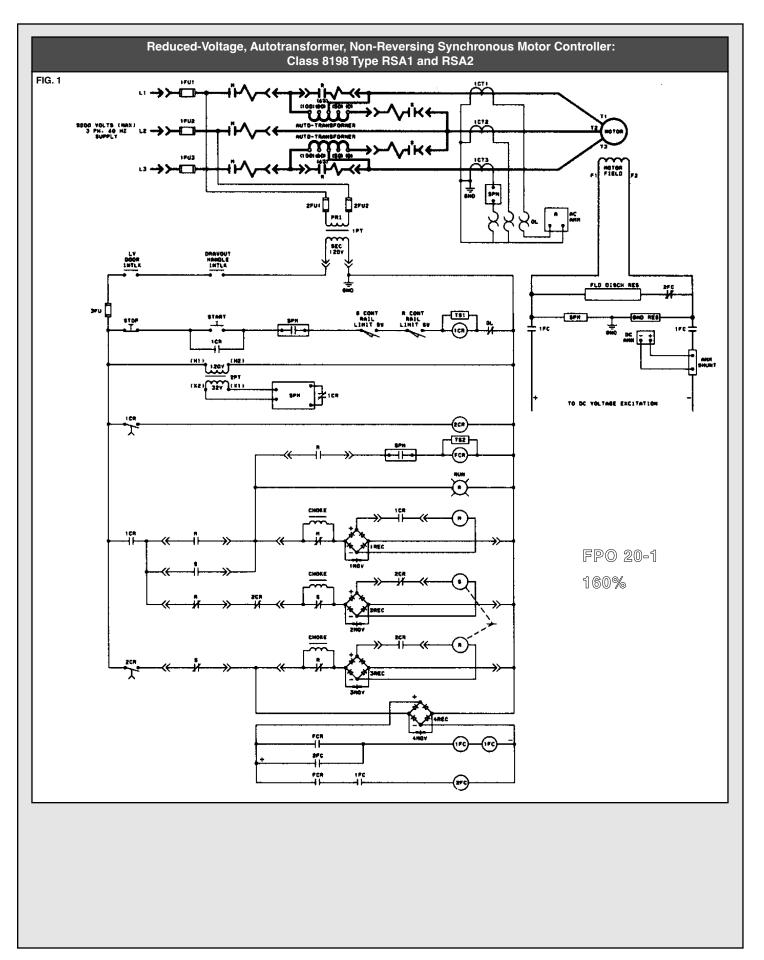


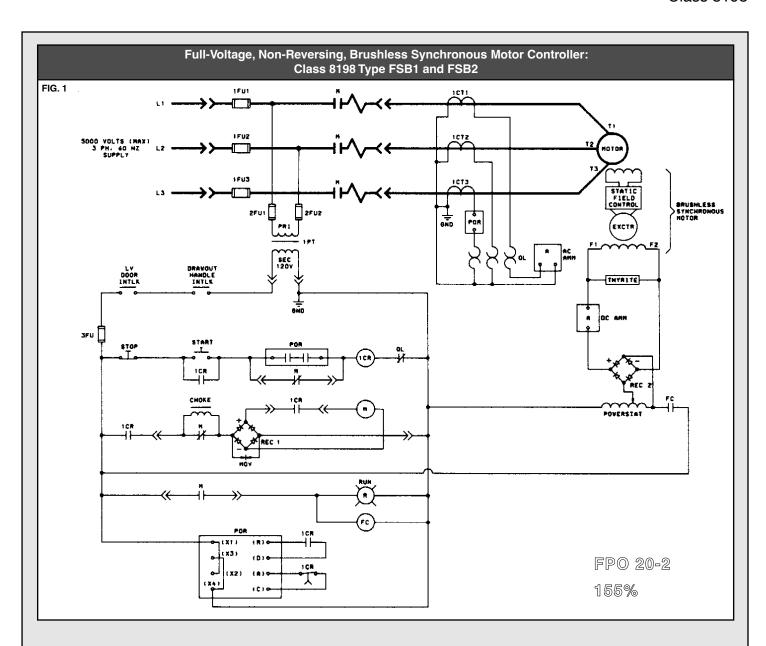


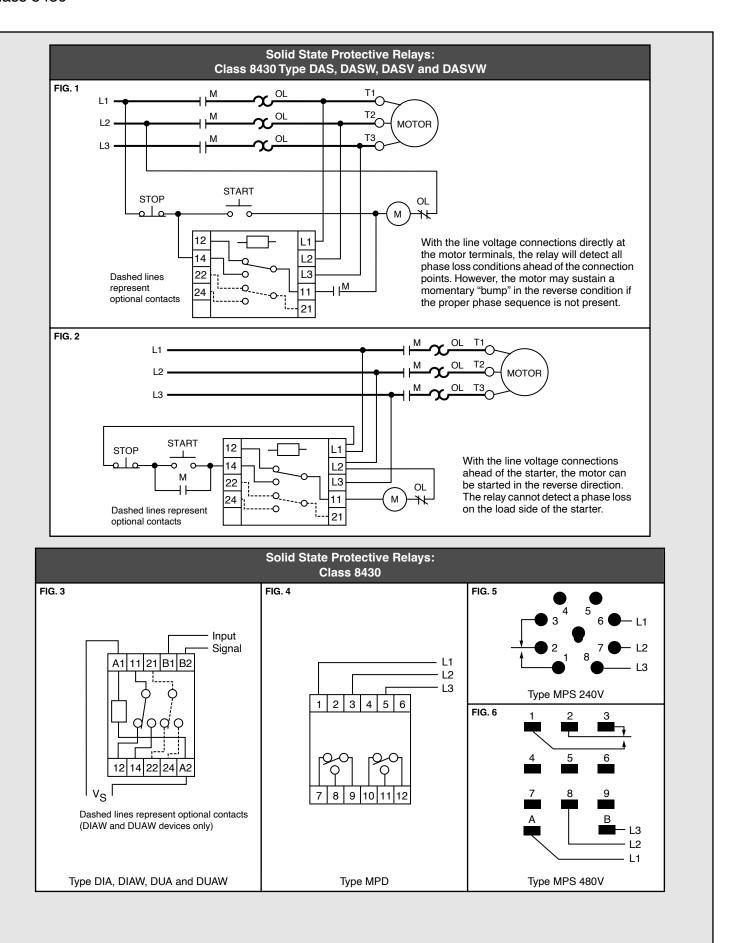
Class 8198

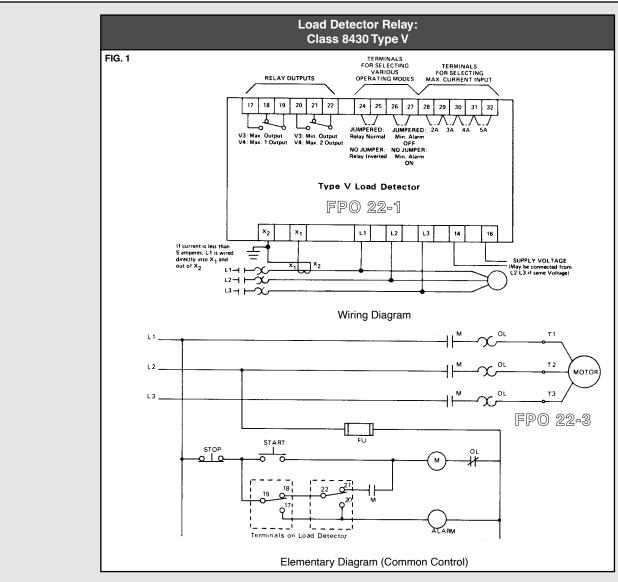


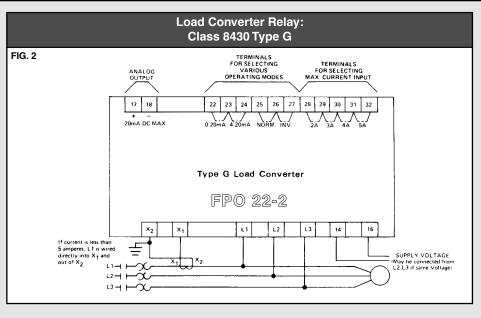


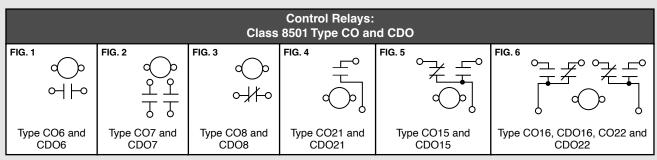


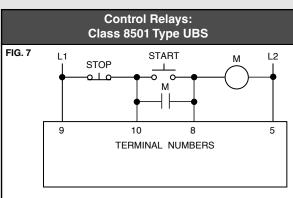


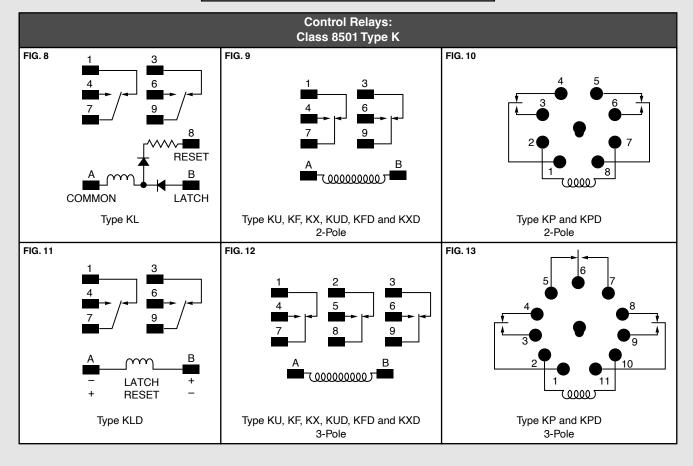


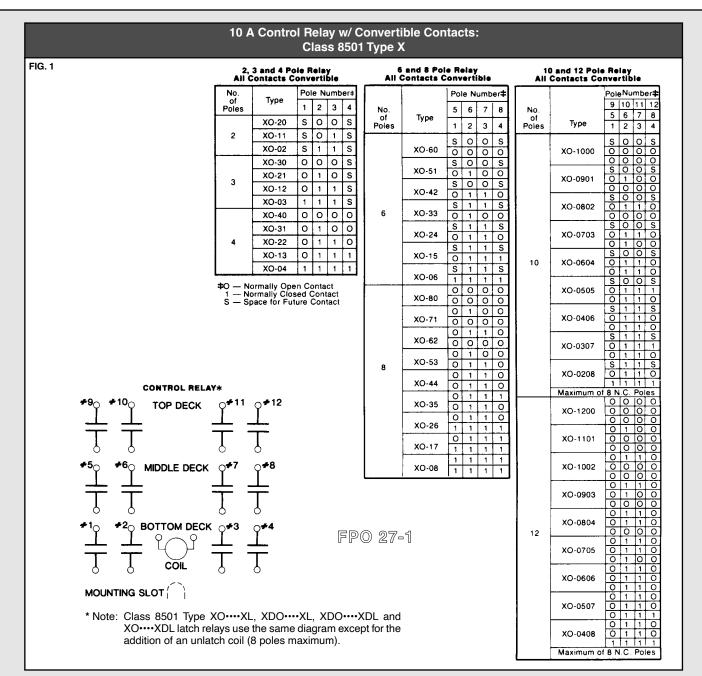


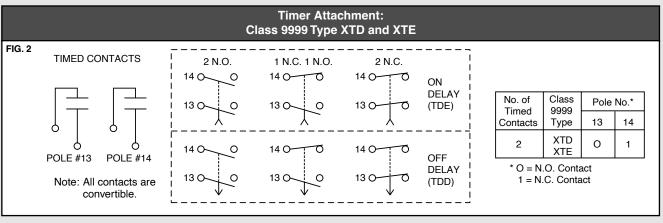






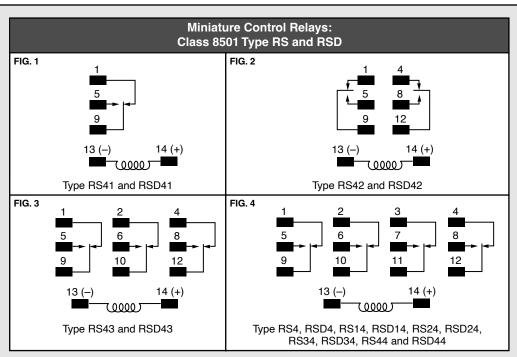


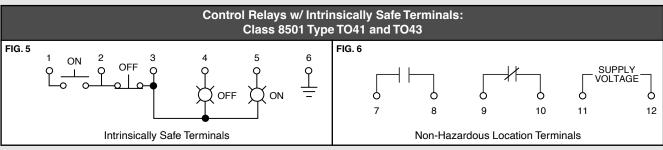


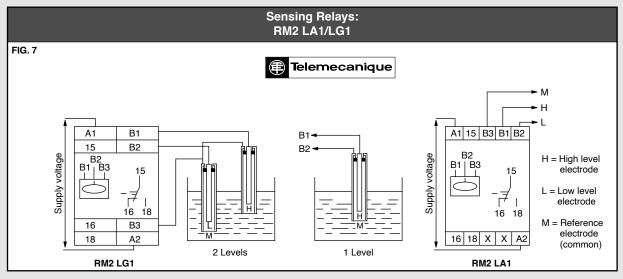


General Purpose Relays and Sensing Relays

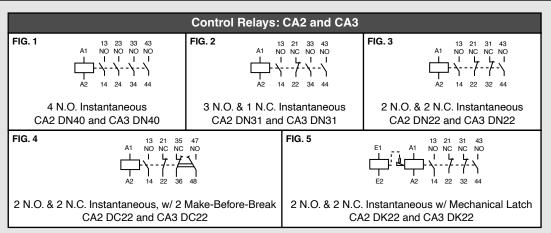
Class 8501 and Telemecanique RM2 LA1/LG1





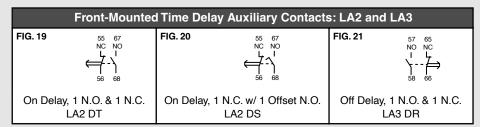


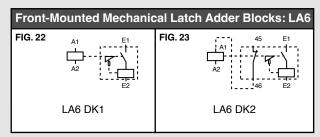


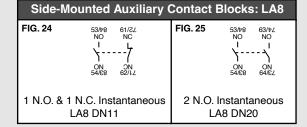


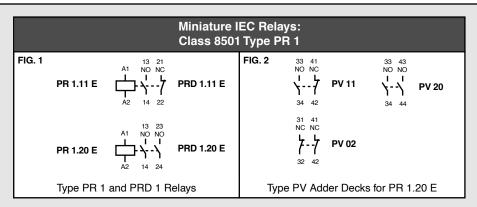
Front-Mounted Standard Instantaneous Auxiliary Contact Blocks: LA1					
FIG. 6 53 61 NO NC 1 L L L L L L L L L L L L L L L L L L	FIG. 7 53 63 NO NO 1 1 1 54 64	FIG. 8 51 61 NC NC 1-7 52 62	FIG. 9 53 61 71 83 NO NC NC NO NO NC NC NO NO NC NC NO NO NC NC NO NC	FIG. 10 53 61 71 81 NO NC	
1 N.O. & 1 N.C. LA1 DN11	2 N.O. LA1 DN20	2 N.C. LA1 DN02	2 N.O. & 2 N.C. LA1 DN22	1 N.O. & 3 N.C. LA1 DN13	
FIG. 11 53 61 75 87 NO NC		G. 12 53 63 73 83 NO NO NO NO I I I I \\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\	FIG. 13 51 61 71 81 NC	FIG. 14 53 61 73 83 NO NC NO NO 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	
2 N.O. & 2 N.C. w/ 2 Make-Before-Break LA1 DC22		4 N.O. LA1 DN40	4 N.C. LA1 DN04	3 N.O. & 1 N.C. LA1 DN31	

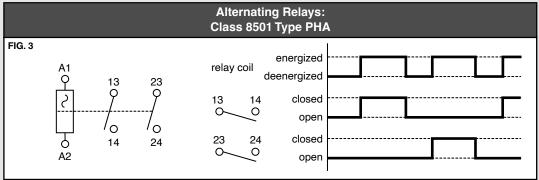
Front-Mounted Damp- and Dust-Protected Instantaneous Auxiliary Contact Blocks: LA1							
FIG. 15	53 63 NO NO 54 64	FIG. 16 53 NO NO 54 63 NO 64	FIG. 17 53 63 73 83 NO NO NO NO 54 64 74 84	FIG. 18 53 61 73 83 NO NC NO NO 54 62 74 84			
L	2 N.O. A1 DX20	2 N.O. w/ Grounding Screw LA1 DY20	2 Dusttight N.O. & 2 N.O. LA1 DZ40	2 Dusttight N.O. & 1 N.O. & 1 N.C. LA1 DZ31			









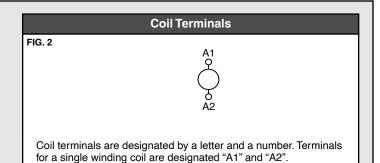


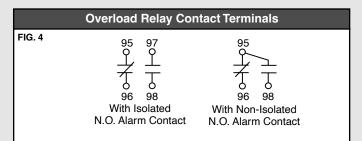
Power Terminals 1 3 5 0 0 0 1 0 0 2 4 6

Power terminals on contactors, overloads and switches are single digits – odd for line side terminals and even for load side terminals.

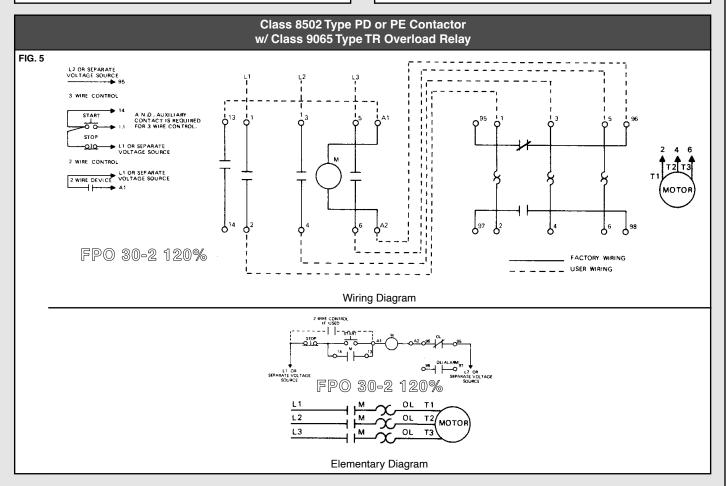
Auxiliary Contact Terminals FIG. 3 Location 13 21 31 43 53 (N.O. or N.C.) 14 22 32 44 54

Auxiliary contacts on contactors, relays and push button contacts use 2-digit terminal designations, as shown in the diagram above. The first digit indicates the location of the contact on the device. The second digit indicates the status of the contacts, N.O. or N.C. "1" and "2" indicate N.C. contacts. "3" and "4" indicate N.O. contacts.

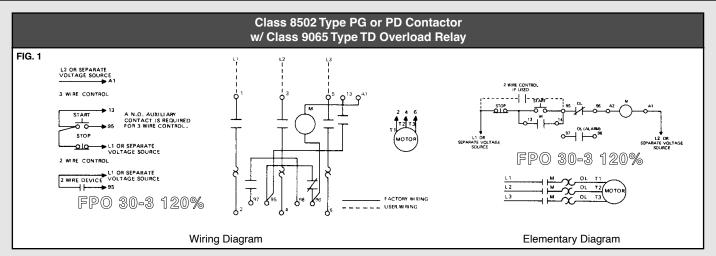


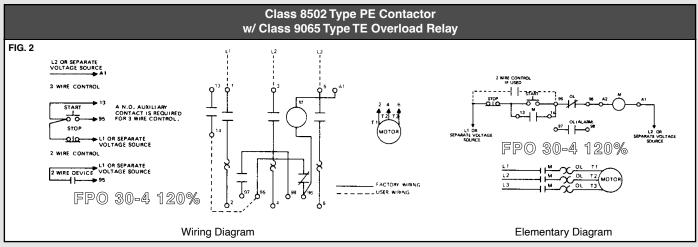


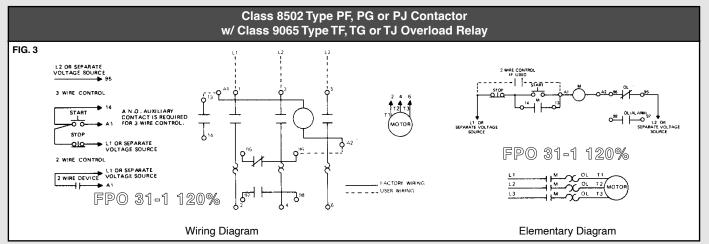
Overload contact terminals are marked with two digits. The first digit is "9". The second digits are "5" and "6" for a N.C. and "7" and "8" for a N.O. isolated contact. If the device has a non-isolated alarm contact (single pole), the second digits of the N.O. terminals are "5" and "8".

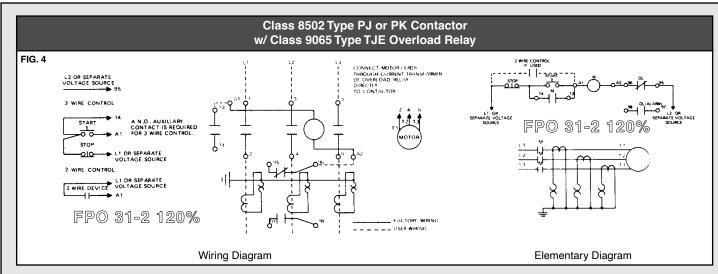


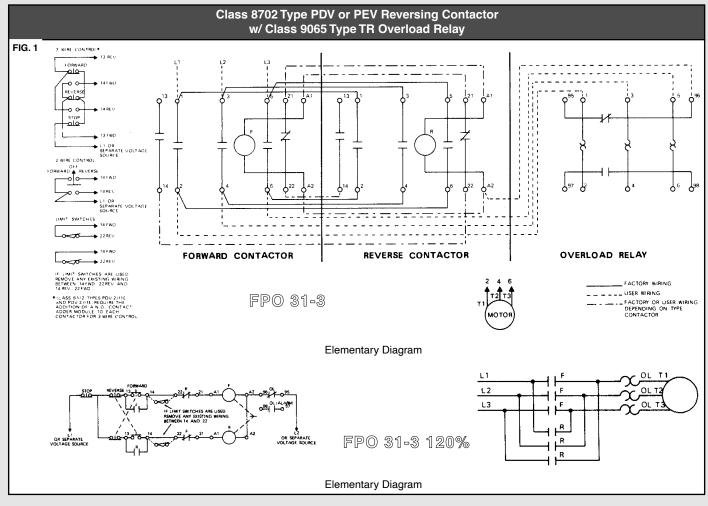
Class 8502 and 9065

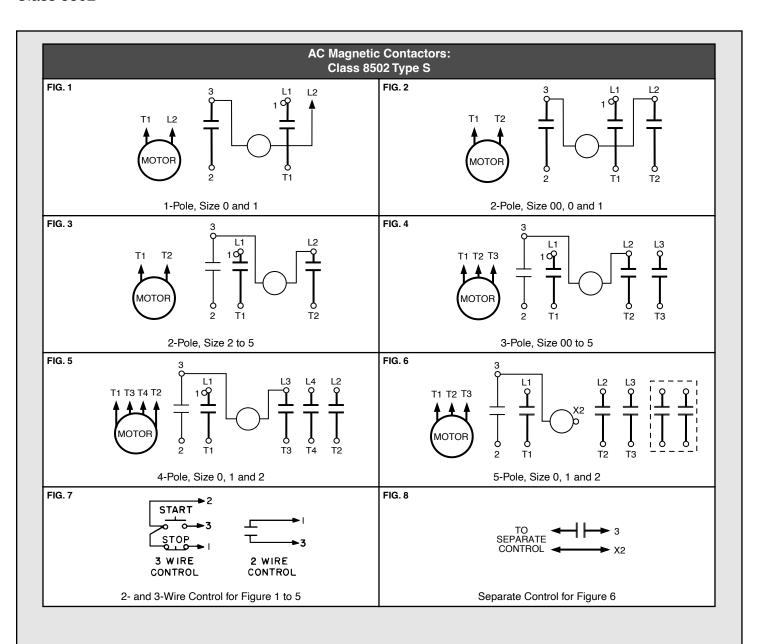


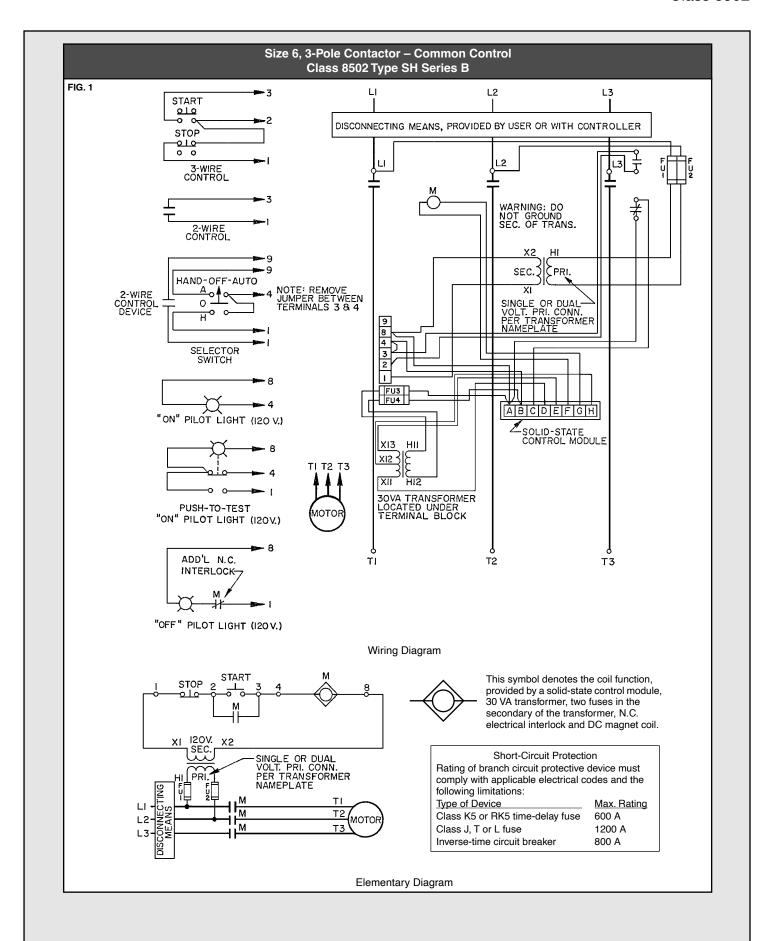


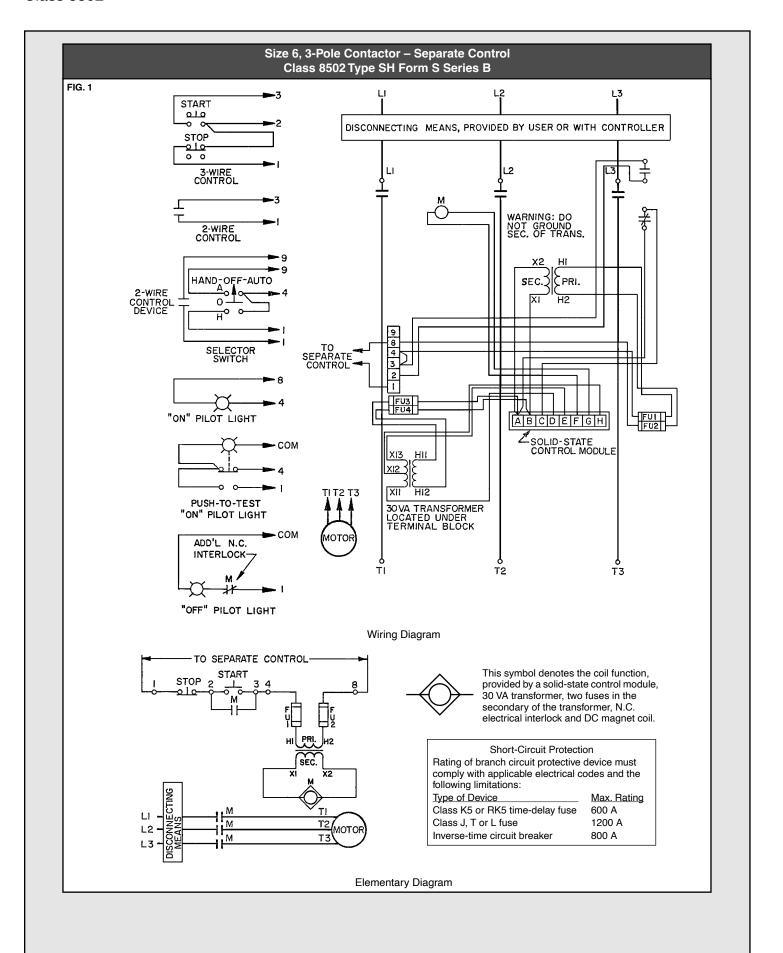


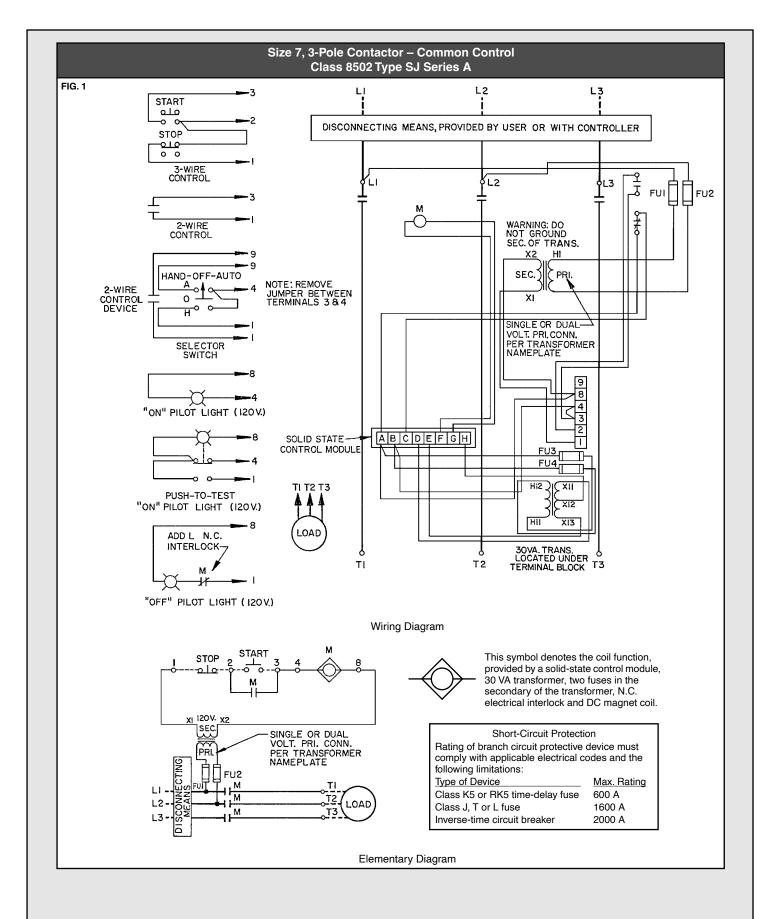


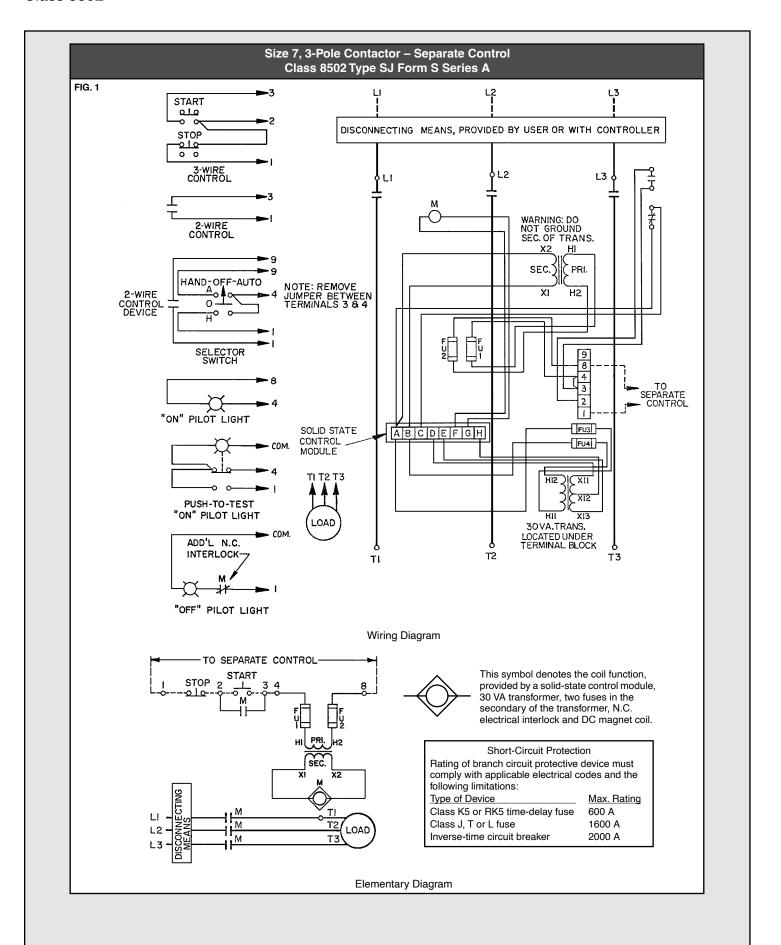




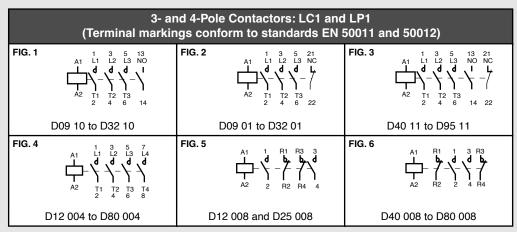




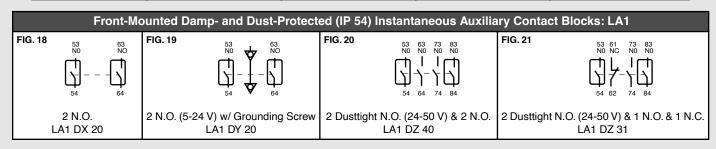


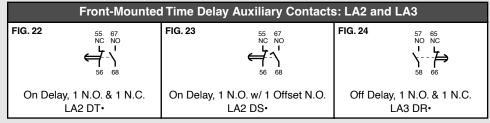


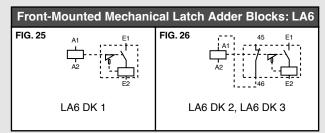




	Front-Mounted Standard Instantaneous Auxiliary Contact Blocks: LA1												
FIG. 7 43 16 NO 1 44 86 1 N.O.	FIG. 8 53 61 NO NC 1 1 7 62 1 N.O. & 1 N.C	FIG. 9 53 63 NO NO 1 1 1 54 64 2 N.O.	FIG. 10 51 61 NO	7	53 61 71 83 NO NC NC NO -1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	1 N.O. & 3 N.C.							
LA1 DN 10	LA1 DN 11	LA1 DN 20	LA1 DN 02		DN 22	LA1 DN 13							
FIG. 13 41 76 NO L 42 16	FIG. 14 53 61 NO NC 1 - 1 54 62	75 87 NC NO 76 88	53 63 73 83 NC NC NC NC 1 1 1 1 54 64 74 84	<u>ት </u>	1 71 81 C NC NC 7 - 7 7 62 72 82	G. 17 53 61 73 83 NO NC NO							
1 N.C. LA1 DN 01	2 N.O. & 2 N. 2 Make-Before LA1 DC 2	-Break I	4 N.O. _A1 DN 40	4 N.C LA1 DN		3 N.O. & 1 N.C. LA1 DN 31							

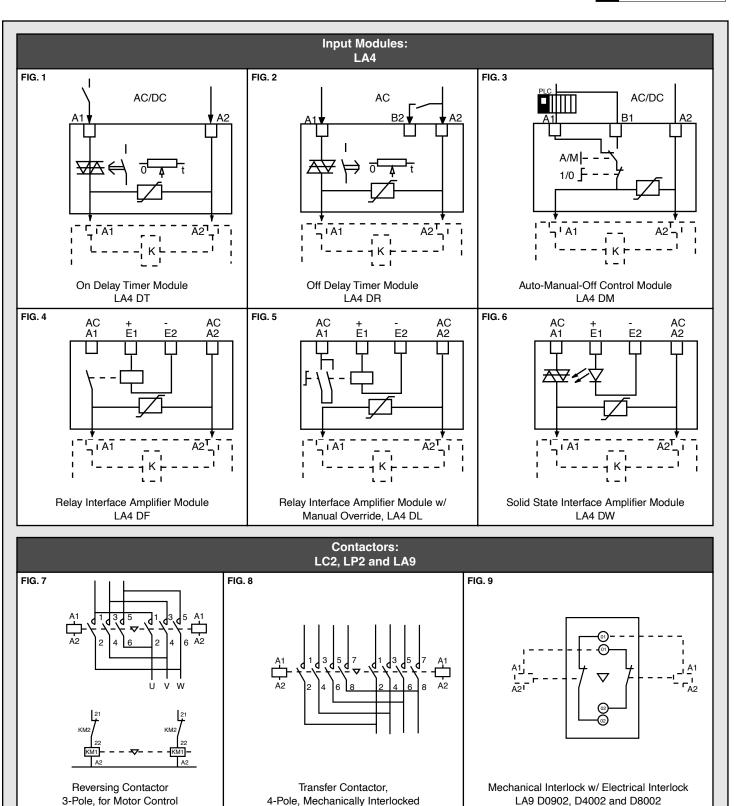






Side-	Mounted Auxiliary	/ Contact Blocks: LA8
FIG. 27	53/r8 61/2/ NO NC \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	FIG. 28 53/98 63/94 NO NO I I I I I I I I I I I I I I I I I
	N.C. Instantaneous LA8 DN 11	2 N.O. Instantaneous LA8 DN 20

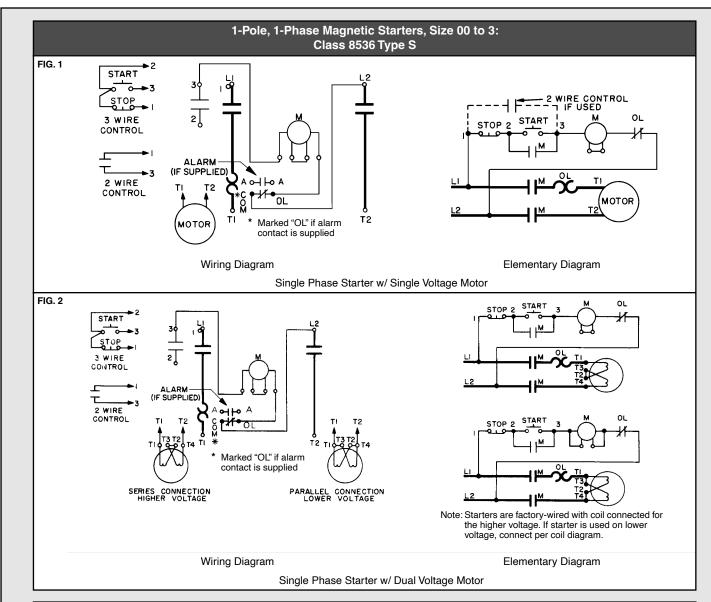


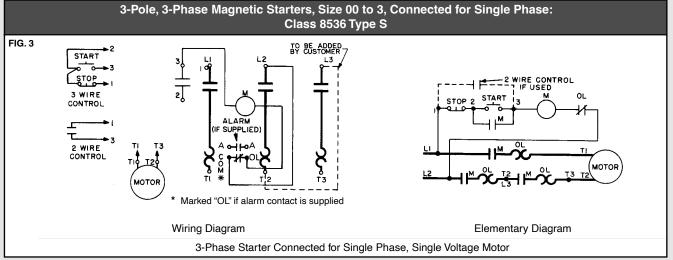


LC2, LP2 D12004 to D8004

LC2, LP2 D0901 to D3201

1-Phase, Size 00 to 3

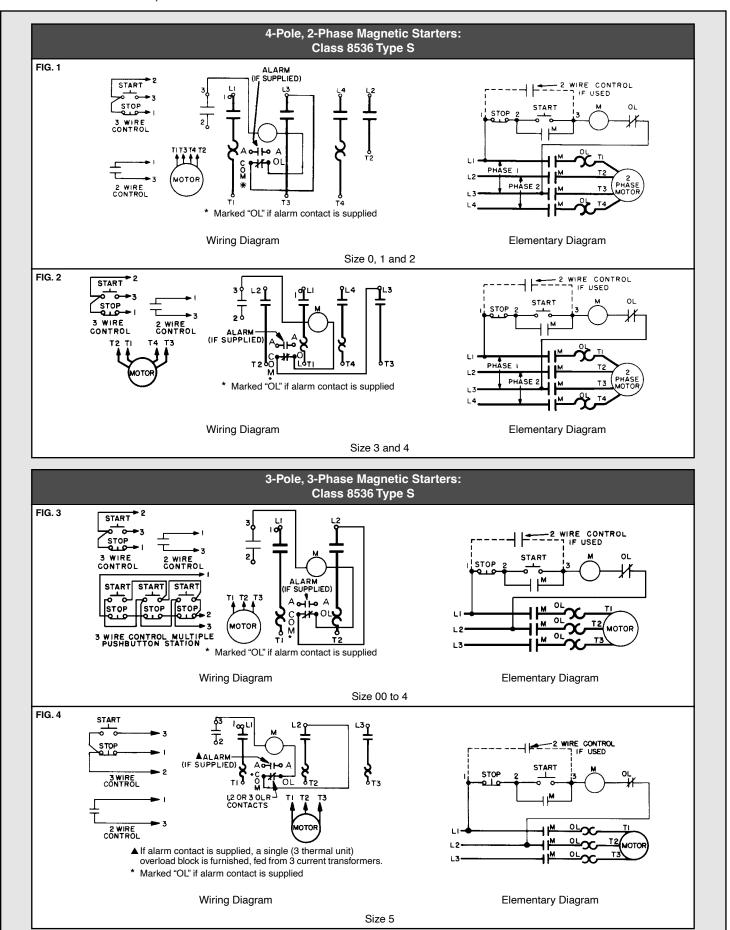




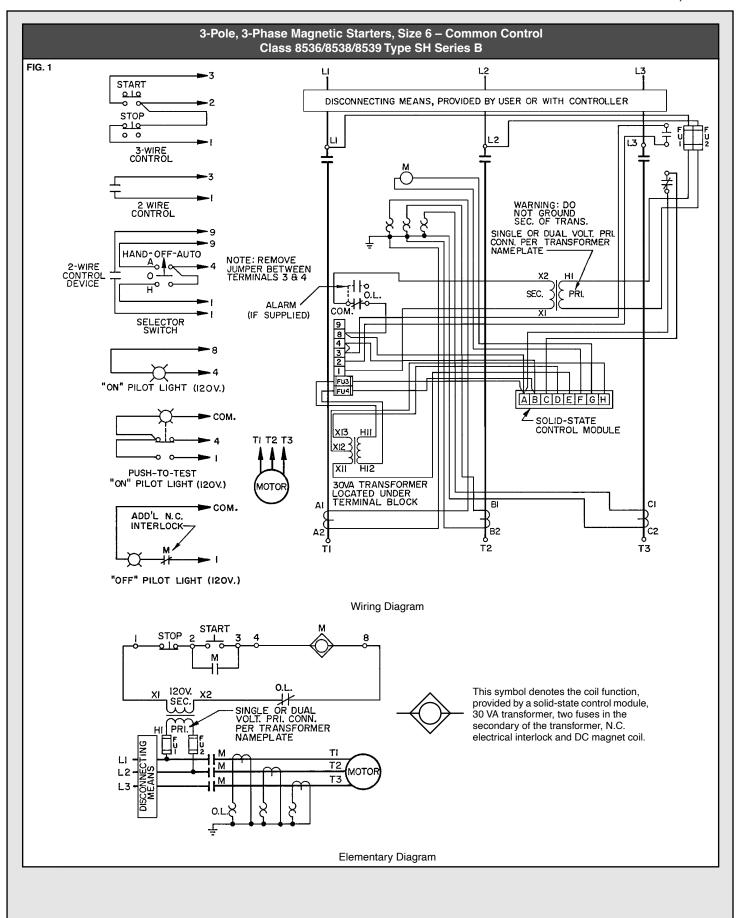
Type S AC Magnetic Starters

Class 8536

2-Phase and 3-Phase, Size 00 to 5



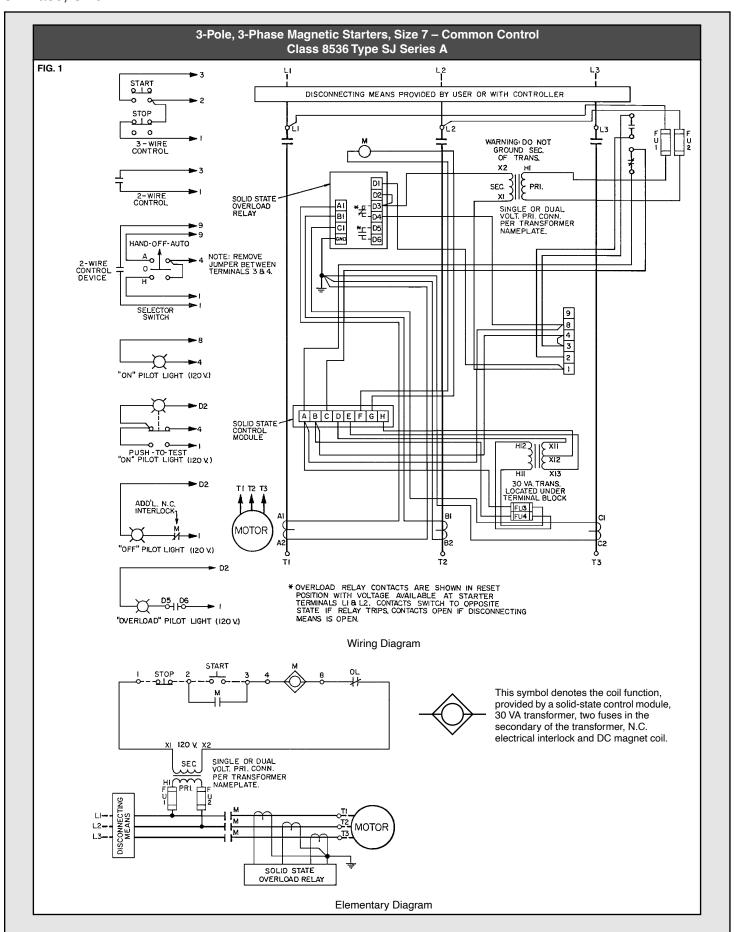
Class 8536, 8538 and 8539 3-Phase, Size 6

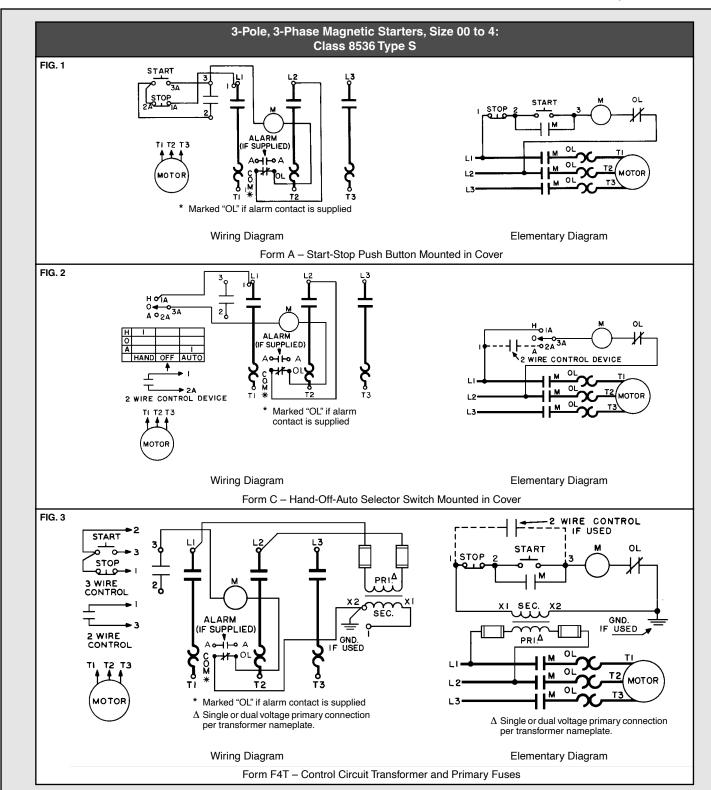


Type S AC Magnetic Starters

Class 8536

3-Phase, Size 7

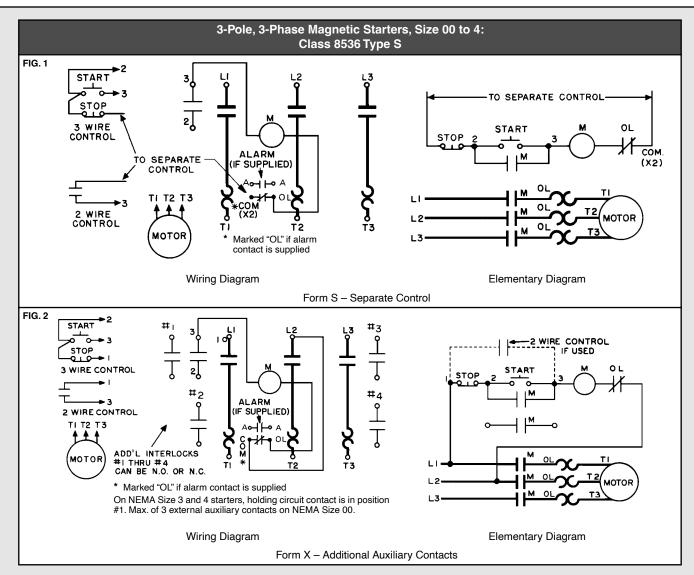


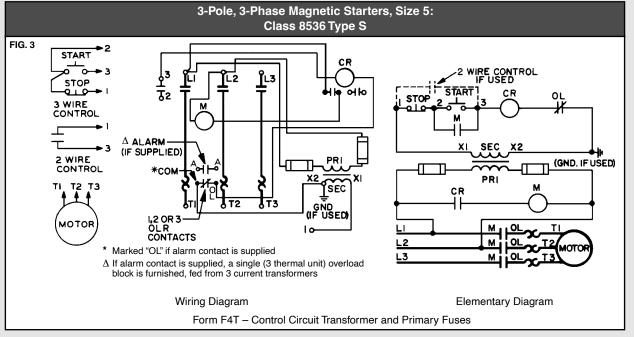


Type S AC Magnetic Starters

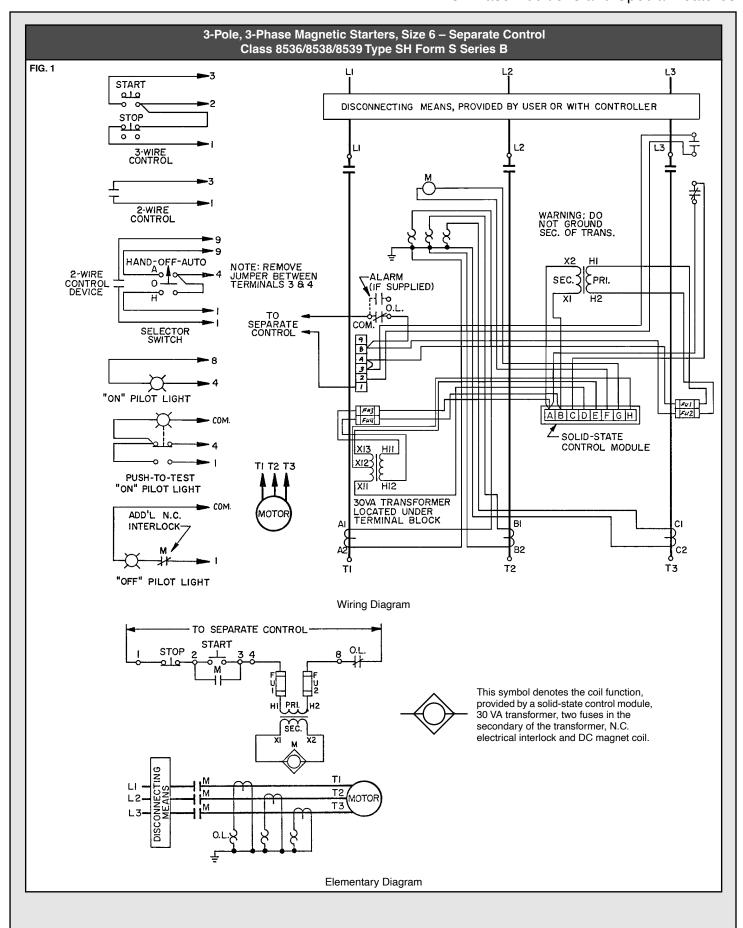
Class 8536

3-Phase Additions and Special Features





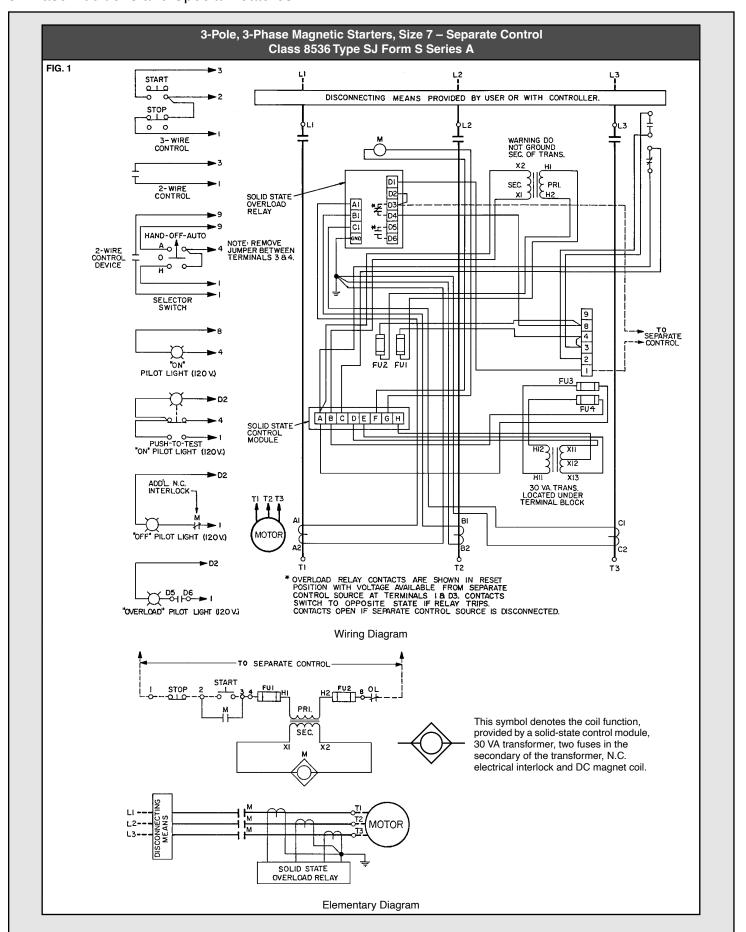
Class 8536, 8538 and 8539 3-Phase Additions and Special Features



Type S AC Magnetic Starters

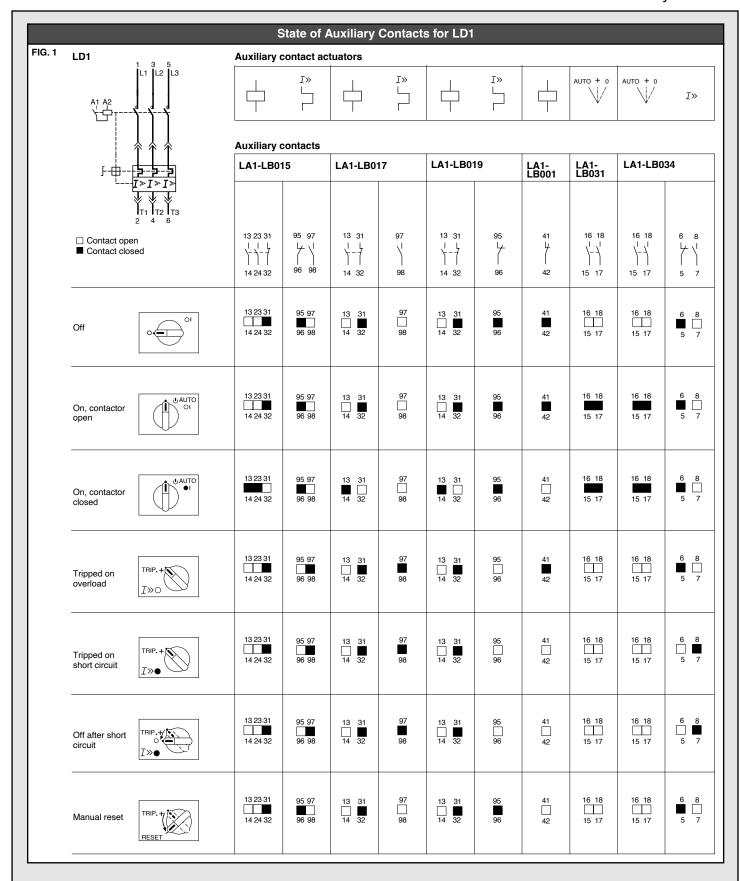
Class 8536

3-Phase Additions and Special Features





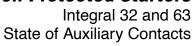
Integral 18
State of Auxiliary Contacts



Integral 18
State of Auxiliary Contacts



State of Auxiliary Contacts for LD5													
FIG. 1	LD5		Auxilia	ry contac	t actuator	rs .	1			1		ı	1
	1 1 1 2 L3 A1 A2	A1A2 -\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\-\	<u> </u>	I»	<u> </u>	I»	+	7			AUTO + 0		I»
			Auxilia LA1-LB	ry contac	LA1-LB017		LA1-LB019		LA1- LB001	LA1-LB021		LA1- LB001	On Integral
	☐ Contact open ■ Contact close	$ \begin{array}{c c} I > I > I \\ \downarrow \downarrow \downarrow \\ T1 & T2 & T3 \\ 2 & 4 & 6 \end{array} $	13 23 31	95 97 L- 1 96 98	13 31 - 14 32	97 \ \ \ 98	13 31 	95 	41 <u>4</u> 	13 23 31	16 18 \\-_\-_\-\	41 	6 8 L I
	Off	O	13 23 31 14 24 32	95 97 96 98	13 31	97 98	13 31 14 32	95 96	41 42	13 23 31 14 24 32	16 18 15 17	41	6 8
	On, contactor open	SAUTO OI	13 23 31 14 24 32	95 97 96 98	13 31	97 	13 31 14 32	95 96	41	13 23 31 14 24 32	16 18 15 17	41	6 8
	On, contactor II closed	ØAUTO ● II	13 23 31 14 24 32	95 97 96 98	13 31 14 32	97 98	13 31	95 96	41 	13 23 31 14 24 32	16 18 15 17	41 42	6 8
	On, contactor I closed	ØAUTO ● I	13 23 31 14 24 32	95 97 96 98	13 31 14 32	97 98	13 31	95 96	41 42	13 23 31 14 24 32	16 18 15 17	41 42	6 8
	Tripped on overload	TRIP.+	13 23 31 14 24 32	95 97 96 98	13 31	97 98	13 31	95 96	41 42	13 23 31 14 24 32	16 18 15 17	41 42	6 8 5 7
	Tripped on short circuit	TRIP.+	13 23 31 14 24 32	95 97 96 98	13 31	97 98	13 31 14 32	95 96	41 42	13 23 31 14 24 32	16 18 15 17	41 42	6 8 5 7
	Off after short circuit	TRIP.+	13 23 31 14 24 32	95 97 96 98	13 31	97 98	13 31 14 32	95 96	41 	13 23 31 14 24 32	16 18 15 17	41 42	6 8 5 7
	Manual reset	TRIP. +	13 23 31 14 24 32	95 97 96 98	13 31 14 32	97 98	13 31 14 32	95 96	41 	13 23 31 14 24 32	16 18 15 17	41 42	6 8 5 7





State of Auxiliary Contacts for LD4												
LD4	Auxilia	ry conta	ct actua	tors	ı		Т		I			
1 3 5 1 3 A1 A2 L		AUTO + 0	<u>I</u> »–		+	Ī»-	[»] [> U< -/-	+	777			
	Auxiliary contacts											
- 5 5 5 - 5 5 5 5 5 5 5 5 5 5 5 5	LA1-LC	LA1-LC010 L						LA1-LC020	LA1-LC030			
2 4 6 ☐ Contact open ■ Contact closed LD4	13 23 31	16 18	06 08 L 1 05	96 98 L, I 95	13 23 31	08 	98 	13 23 31 	(63) 53 			
Off + isolation	13 23 31 14 24 32	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 			
Off d	13 23 31 14 24 32	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
On, contactor open	13 23 31	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
On, contactor closed	13 23 31 14 24 32	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
Tripped, on overload	13 23 31	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
Off, after overload	13 23 31	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
Tripped, on short circuit	13 23 31	16 18 15	06 08	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
Off, after short circuit	13 23 31 14 24 32	16 18 15	06 08	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			
Manual reset	13 23 31 14 24 32	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	53 54			

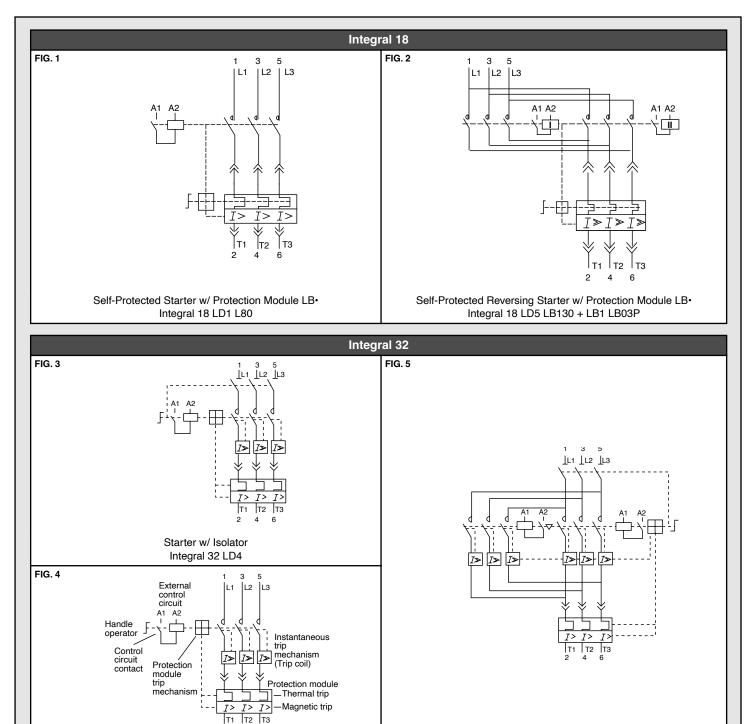
Integral Self-Protected Starters

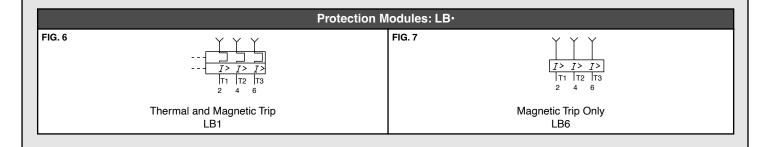
Integral 32 and 63
State of Auxiliary Contacts



LD5 1 2 5	Auxilia	ry conta	ct actua	itors						
1.3 5 1.1213 1.1213 1.1 A2 A1	+	AUTO + 0	Ī»–			Ī»–	[»]]> 	11	+	777
	Auxilia	ry conta	cts		LA1-LC	012		LA1-LC020	LA1-LC021	LA1-LC03
	13 23 31	1618 L H	06 08 L I 05	96 98 L ₂ I 95	13 23 31 	08 	98 	13 23 31 	13 23 31	53 63 1 1 54 64
□ Contact open■ Contact closed										
Off + isolation	13 23 31 14 24 32	16 18	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
Off OI	13 23 31 14 24 32	16 18	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
On, both contactors open	13 23 31 14 24 32	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
On, contactor open output Onicontactor open Onicontactor output Onic	13 23 31	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
On, contactor closed	13 23 31 14 24 32	16 18 15	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
Tripped on overload	13 23 31	16 18	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
Off, after overload	13 23 31	16 18	06 08 05	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
Tripped on short circuit	13 23 31 14 24 32	16 18 15	06 08	96 98 95	13 23 31 14 24 32	08	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
Off after short circuit	13 23 31	16 18	06 08	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64
Manual reset	13 23 31 14 24 32	16 18	06 08	96 98 95	13 23 31 14 24 32	08 05	98 95	13 23 31 14 24 32	13 23 31 14 24 32	53 63 54 64







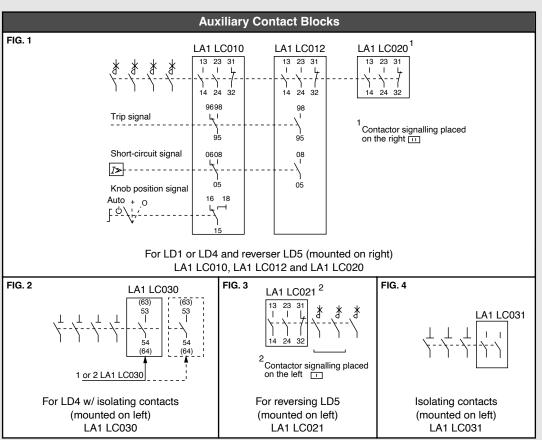
Reversing Starter w/ Isolator

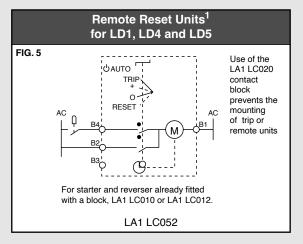
Integral 32 LD5

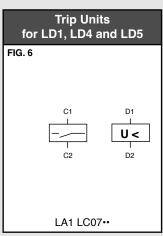
Starter w/o Isolator

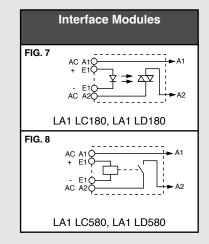
Integral 32 LD1



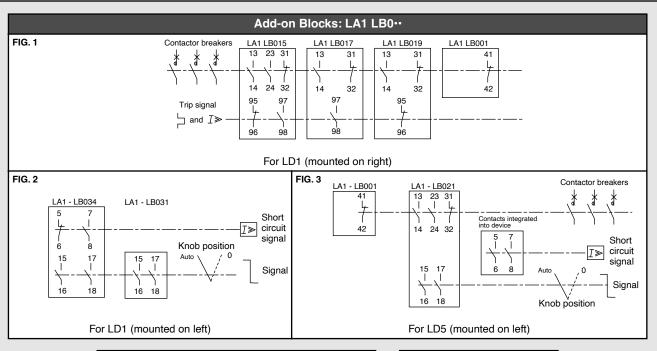


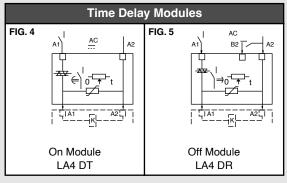


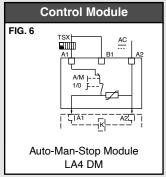


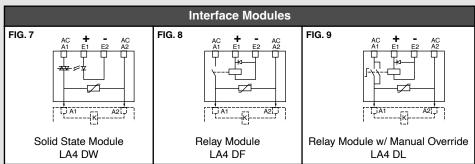


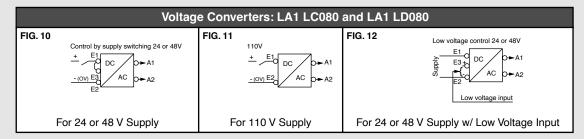








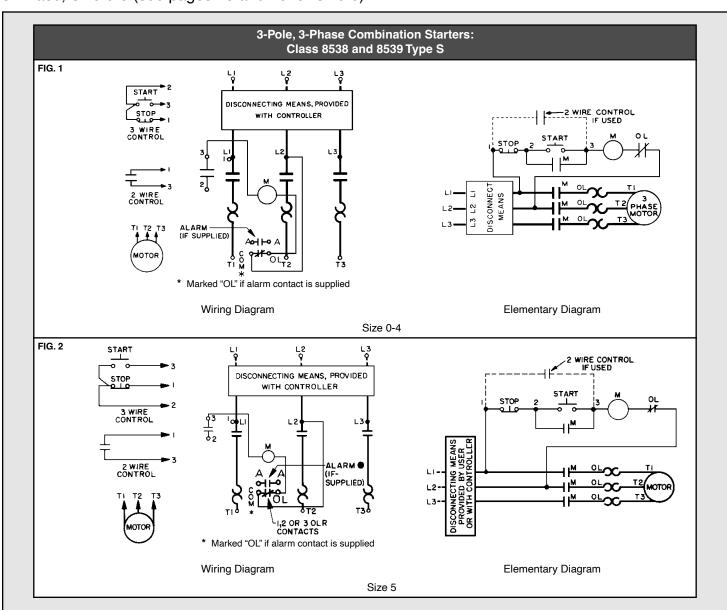




Type S AC Combination Magnetic Starters

Class 8538 and 8539

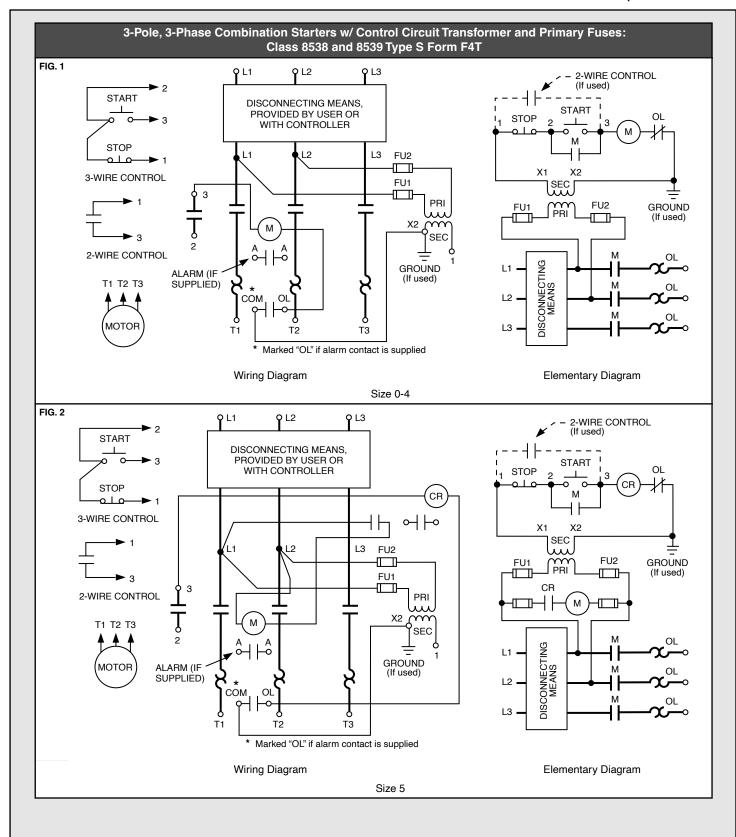
3-Phase, Size 0-5 (see pages 45 and 49 for Size 6)



Type S AC Combination Magnetic Starters

Class 8538 and 8539

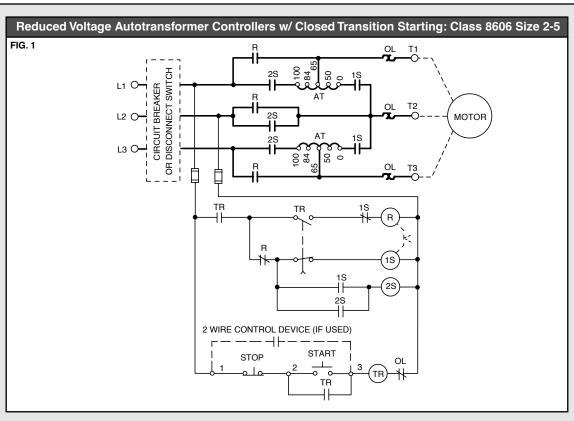
3-Phase Additions and Special Features

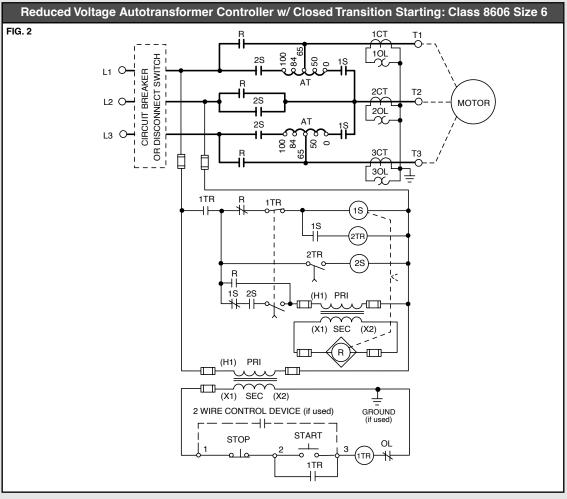


Reduced Voltage Controllers

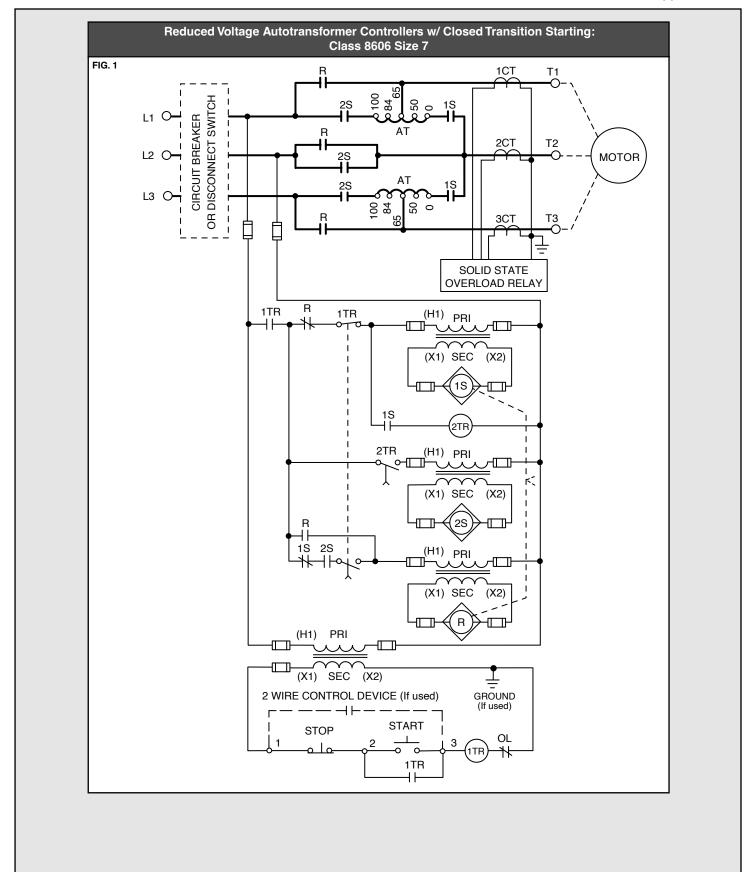
Class 8606

Autotransformer Type, Size 2-6





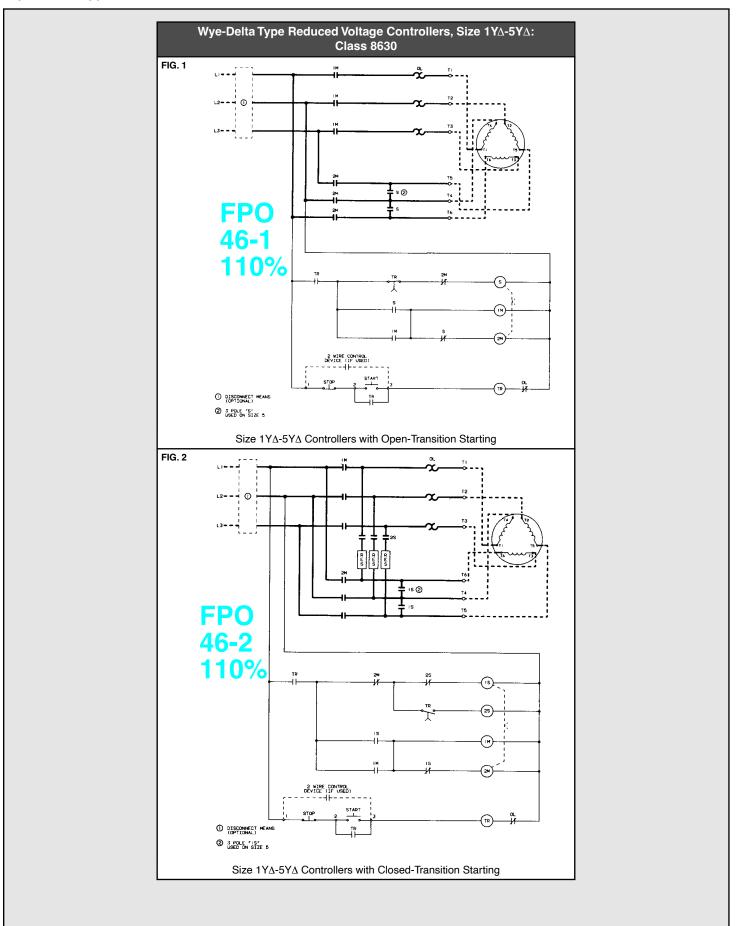
Autotransformer Type, Size 7



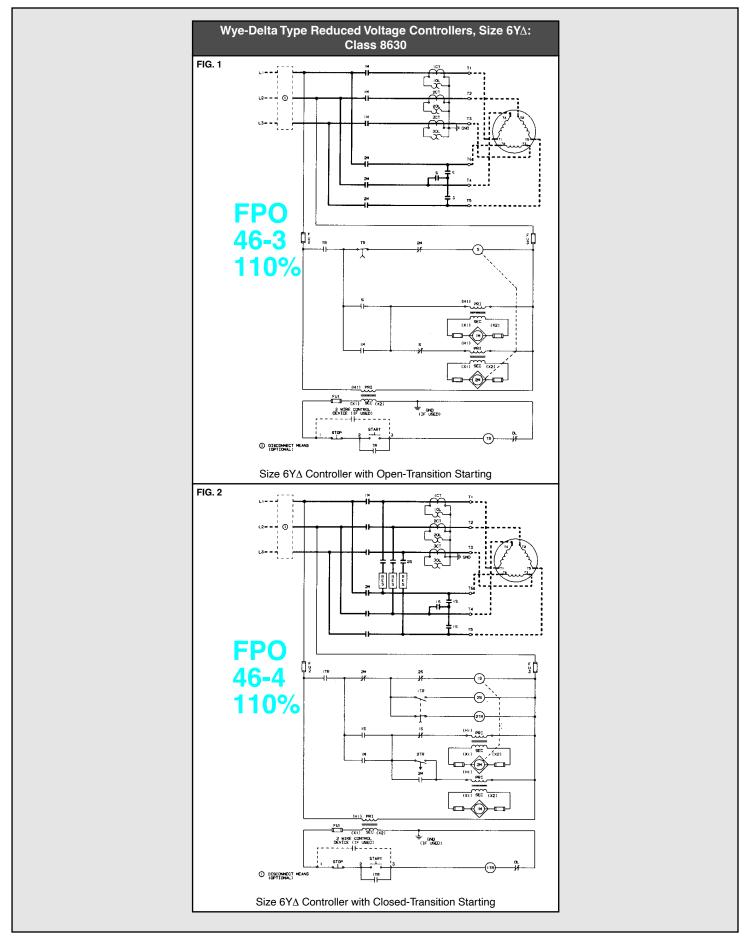
Reduced Voltage Controllers

Class 8630

Wye-Delta Type, Size $1Y\Delta$ - $5Y\Delta$



Wye-Delta Type, Size $6Y\Delta$



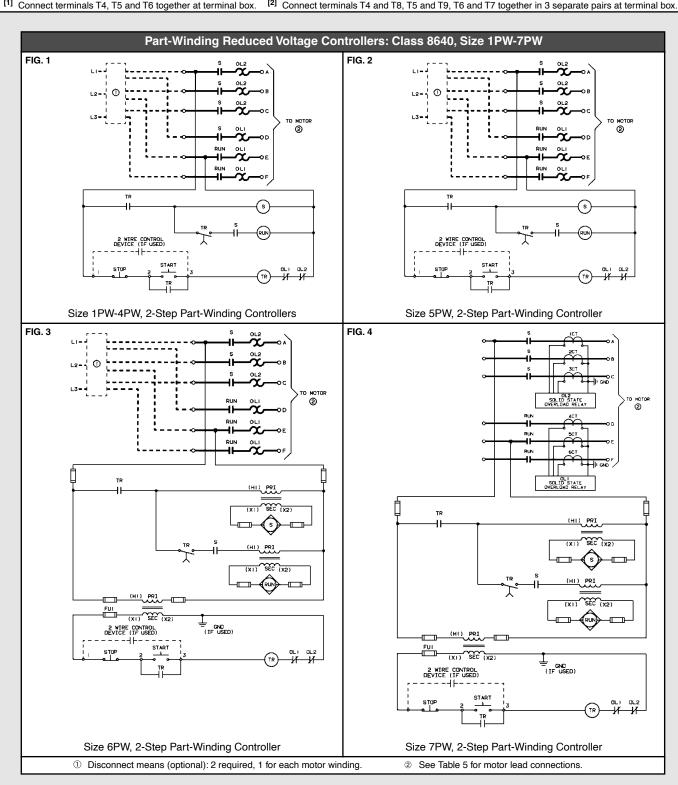
Reduced Voltage Controllers

Class 8640

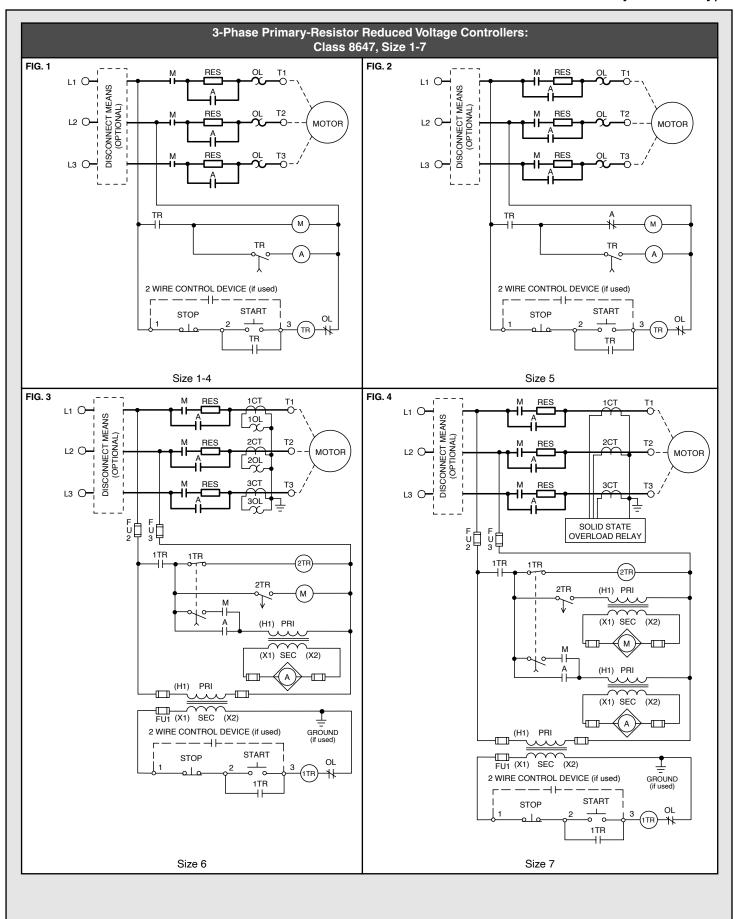
2-Step, Part-Winding Type

Table 5 Motor Lead Connections

Part Winding Schemes	Lettered Terminals in Panel						Part Winding Schemes	Lettered Terminals in Panel					
	Α	В	С	D	E	F		Α	В	С	D	Е	F
1/2 Wye or Delta 6 Leads	T1	T2	T3	T7	T8	T9	2/3 Wye or Delta 6 Leads	T1	T2	T9	T7	T8	T3
1/2 Wye 9 Leads ^[1]	T1	T2	T3	T7	T8	T9	2/3 Wye 9 Leads ^[1]	T1	T2	T9	T7	T8	T3
1/2 Delta 9 Leads [2]	T1	T8	T3	T6	T2	T9	2/3 Delta 9 Leads [2]	T1	T4	T9	T6	T2	T3
[1] Connect terminals T4 T5 and	TC to a	*****	io umaim al	hav [2	21 Cann		nals T4 and T9 T5 and T0 T6 and T	7 40 00 04 10					l bay

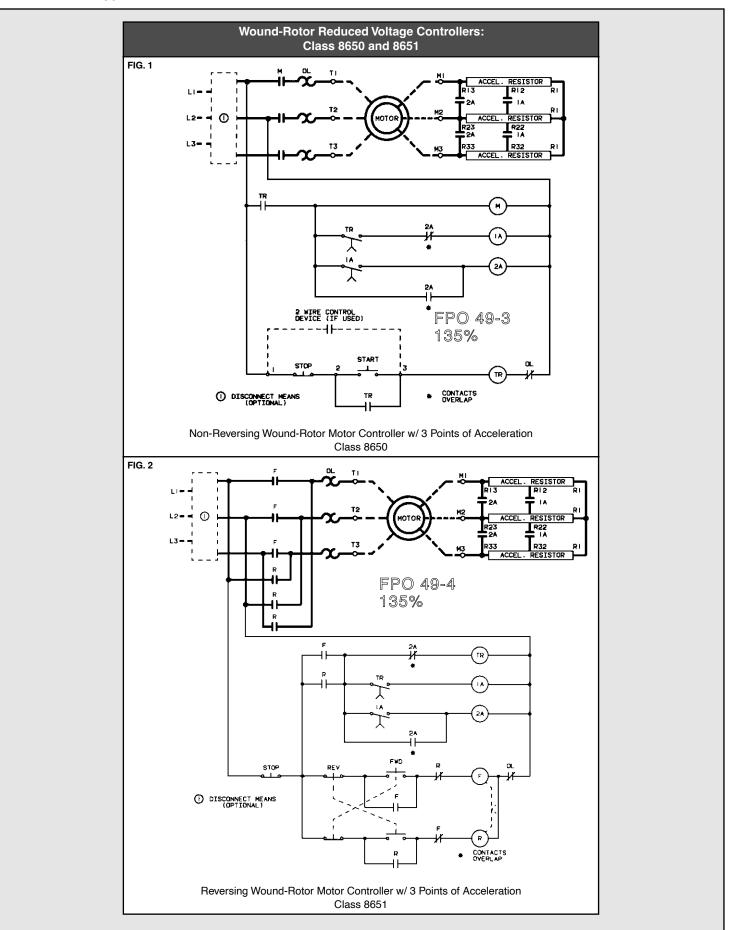


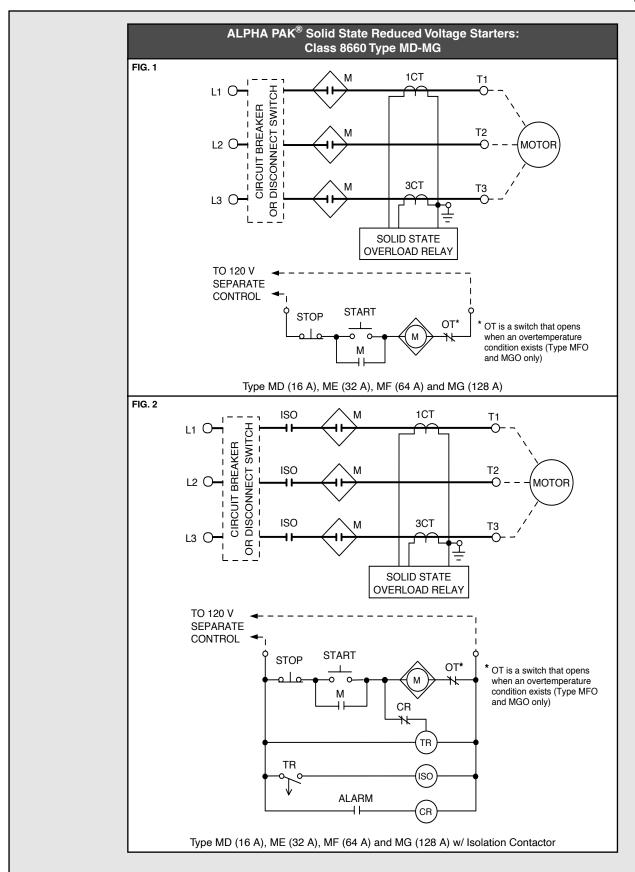
Primary-Resistor Type



Reduced Voltage Controllers

Class 8650 and 8651 Wound-Rotor Type

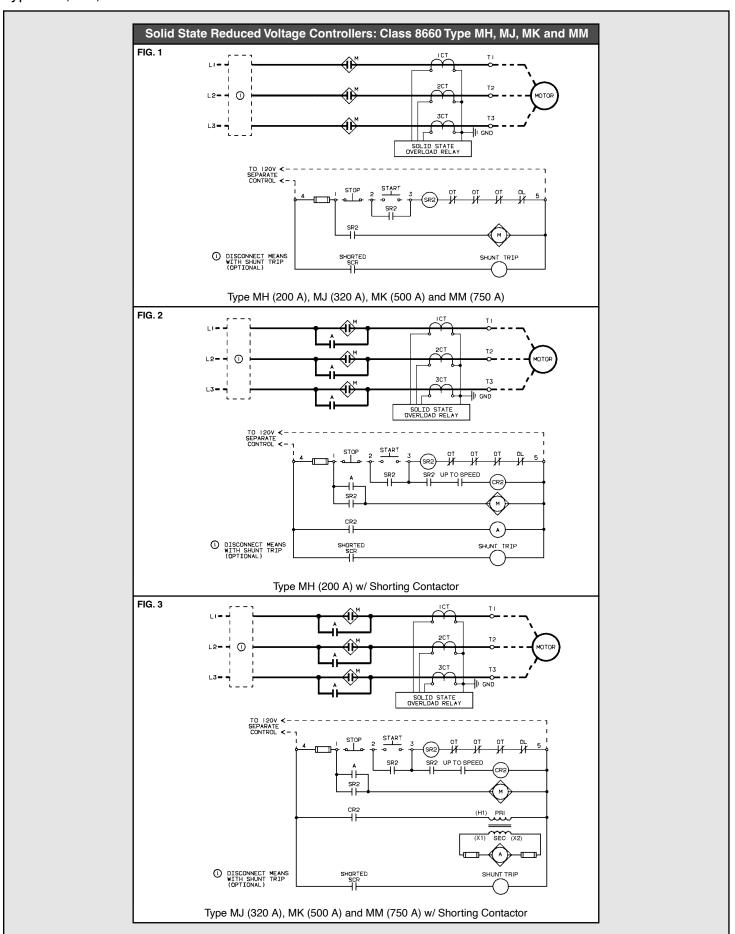




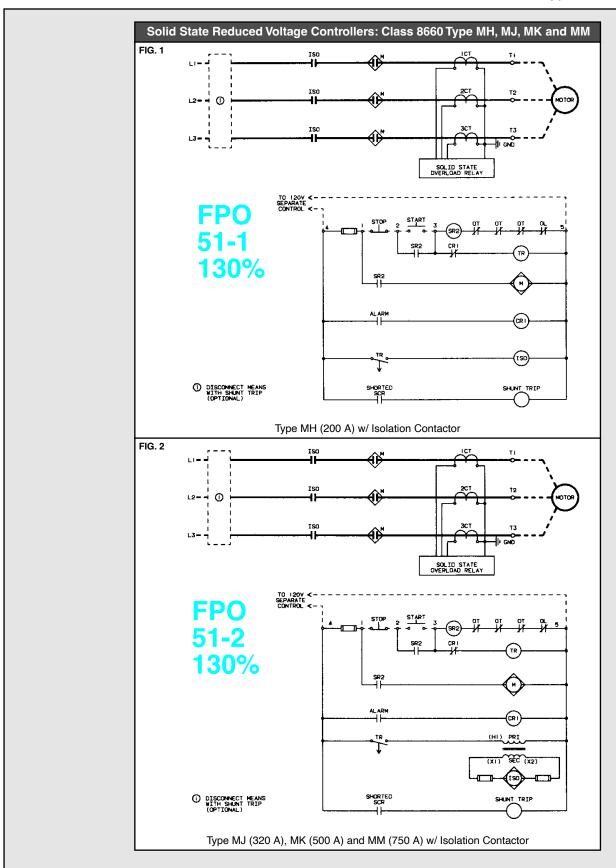
Solid State Reduced Voltage Controllers

Class 8660

Type MH, MJ, MK and MM



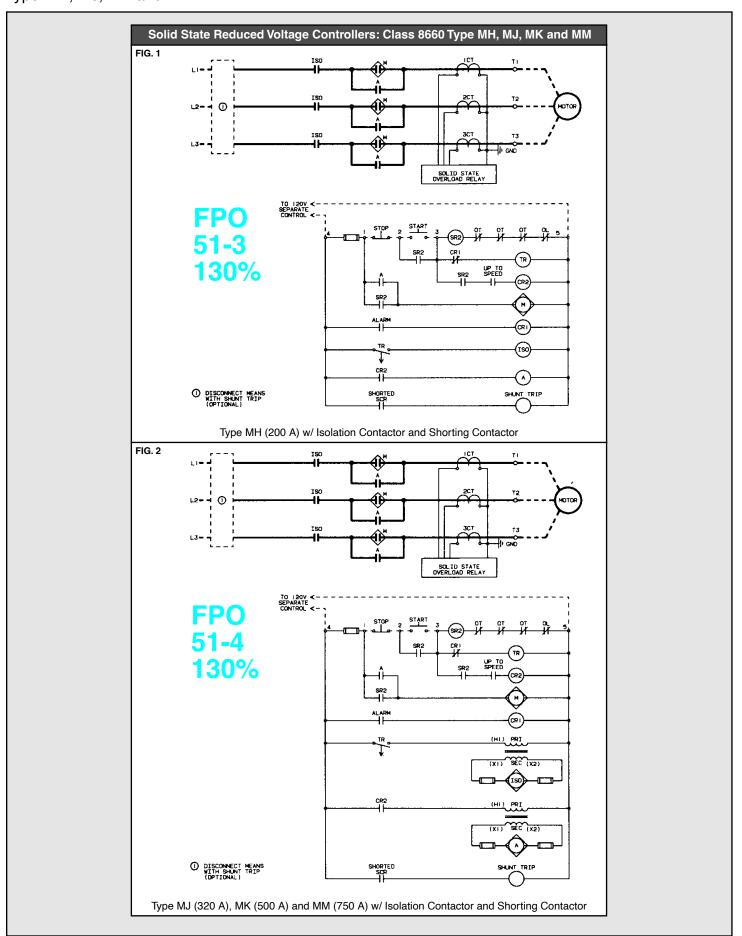
Type MH, MJ, MK and MM



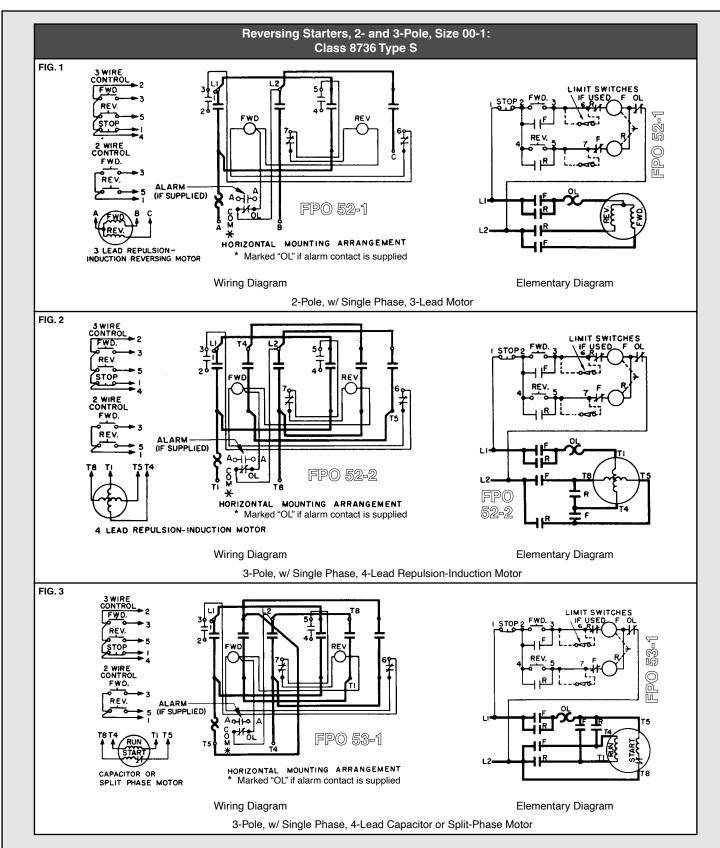
Solid State Reduced Voltage Controllers

Class 8660

Type MH, MJ, MK and MM

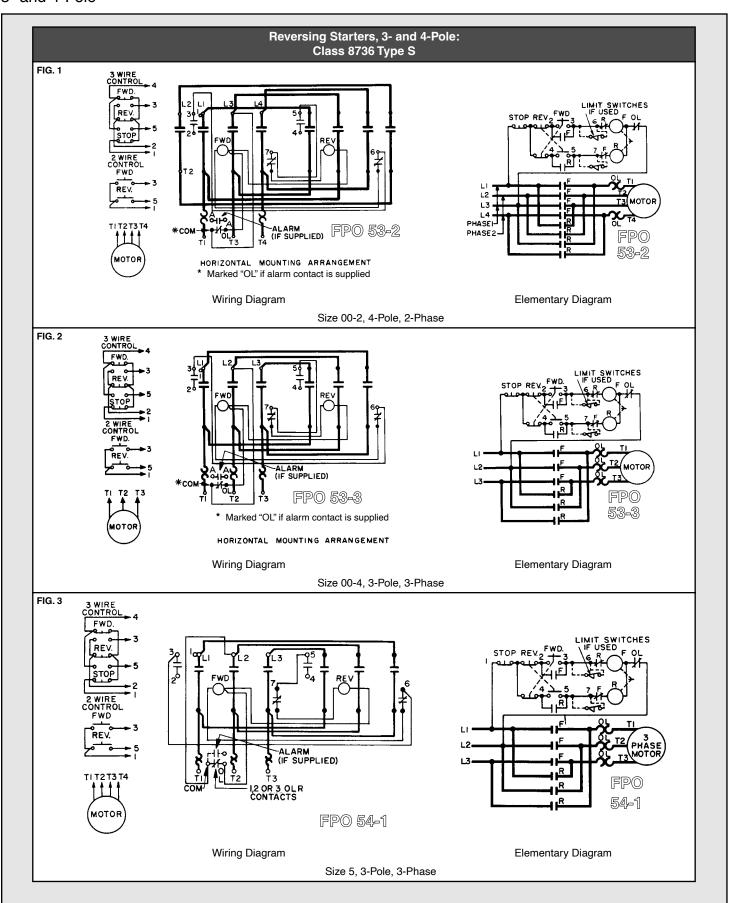


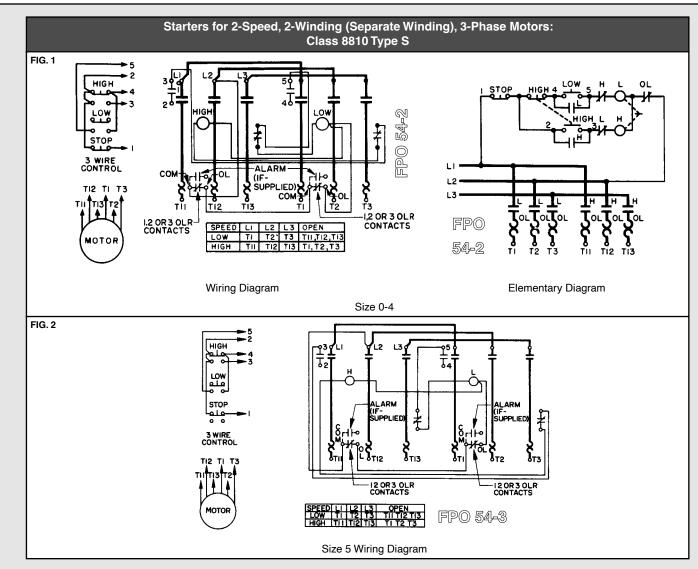
2- and 3-Pole

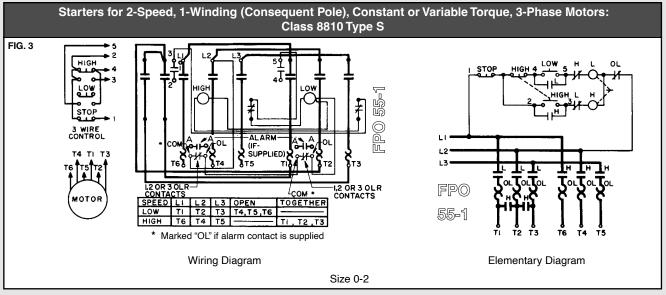


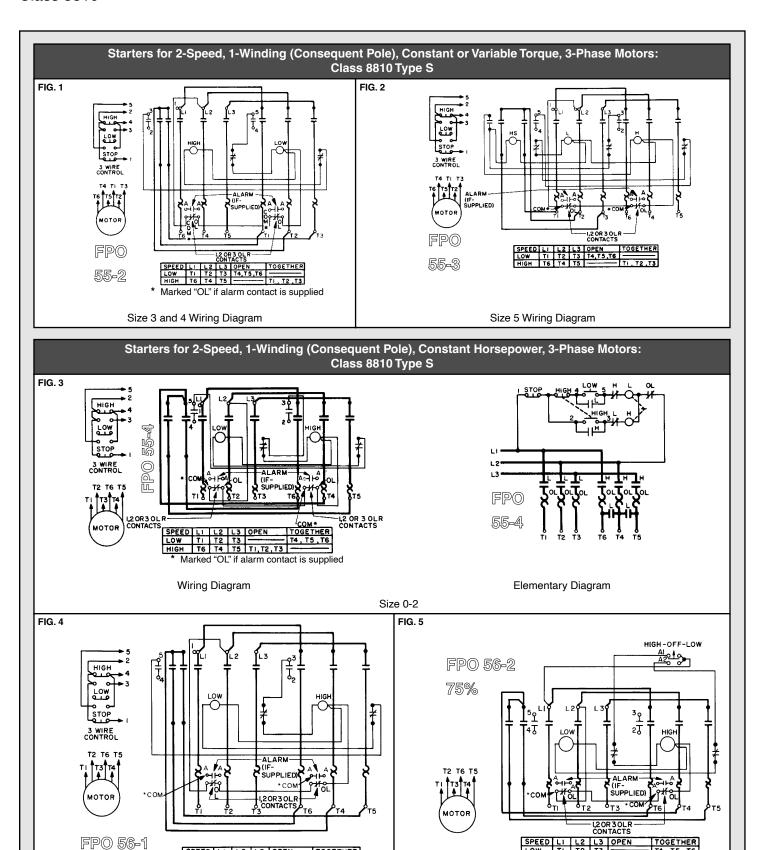
Class 8736

3- and 4-Pole









Marked "OL" if alarm contact is supplied

Size 0, w/ High-Off-Low Selector Switch (Form C7) Wiring Diagram

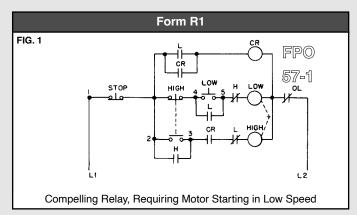
75%

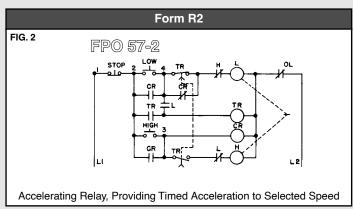
Marked "OL" if alarm contact is supplied

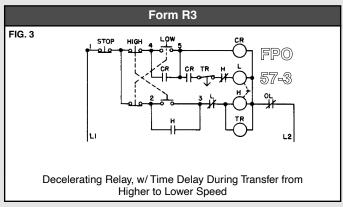
Size 3 and 4 Wiring Diagram

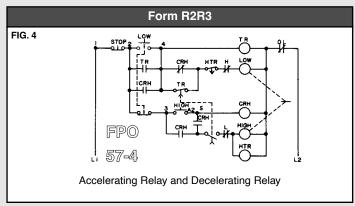
2-Speed Magnetic Starters

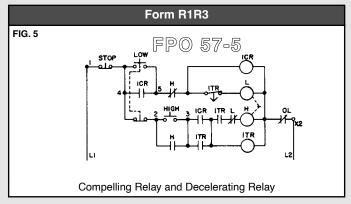
Class 8810 Special Control Circuits

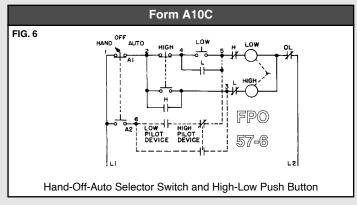


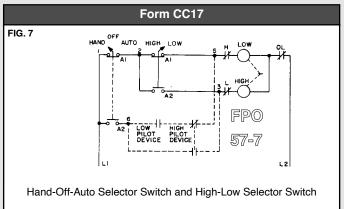


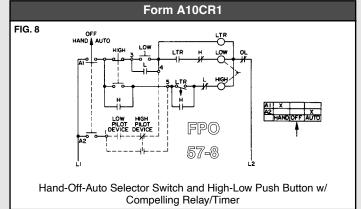








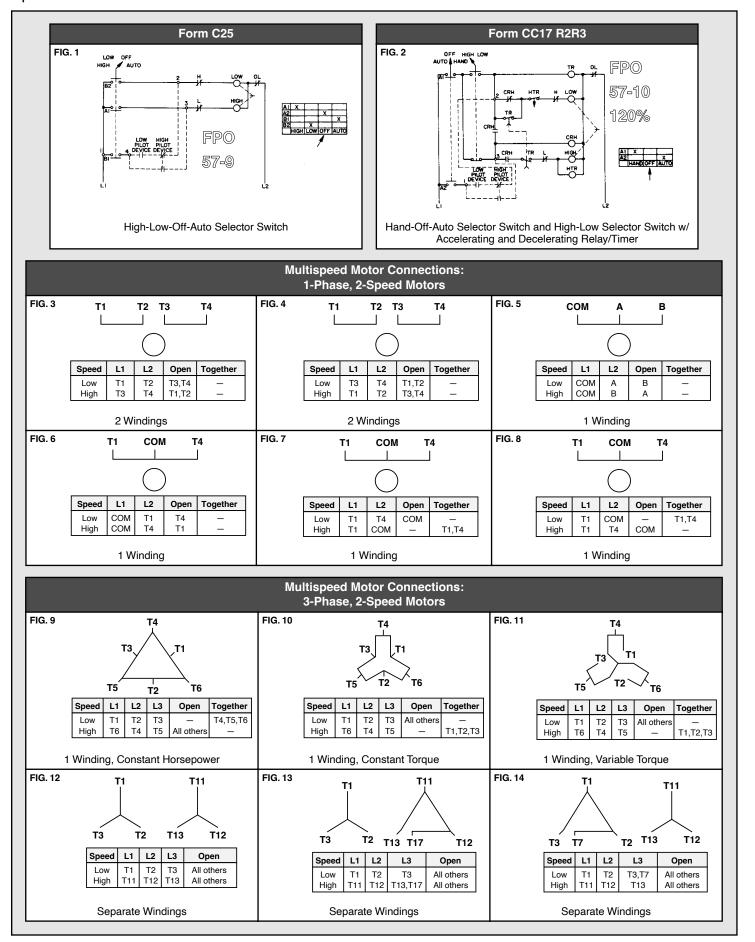


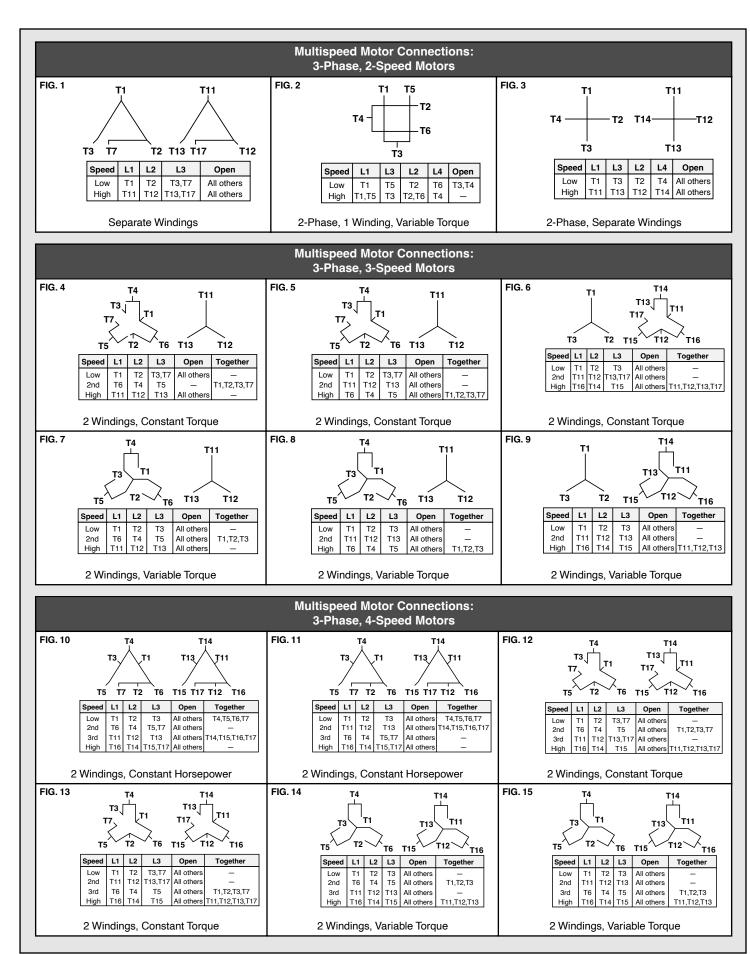


2-Speed Magnetic Starters and Multispeed Motor Connections

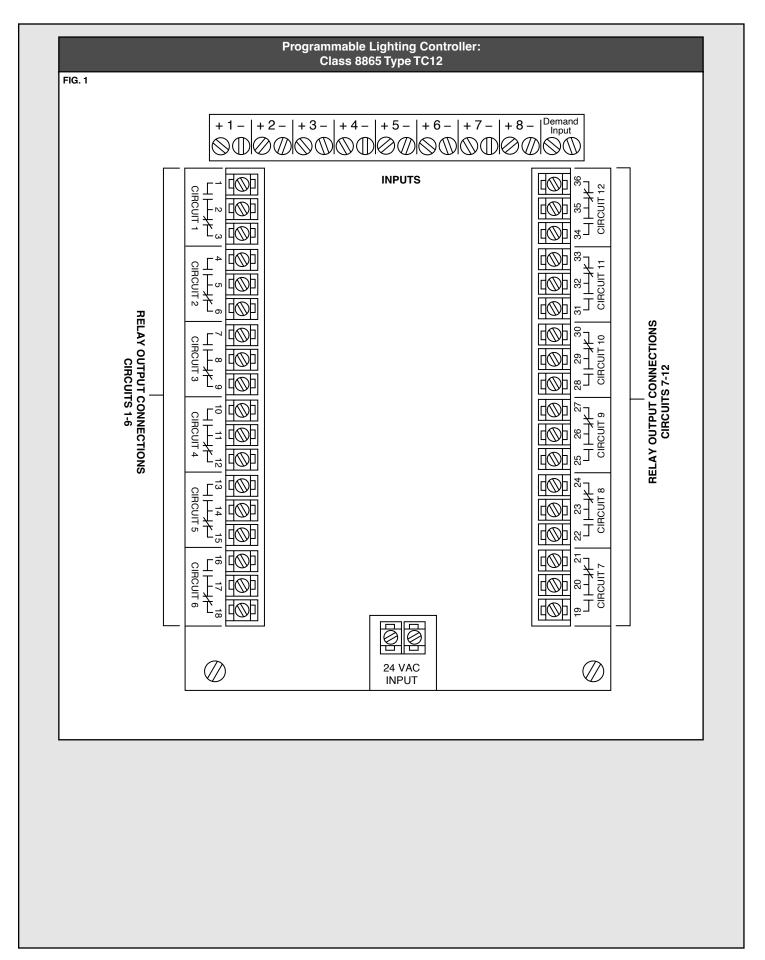
Class 8810

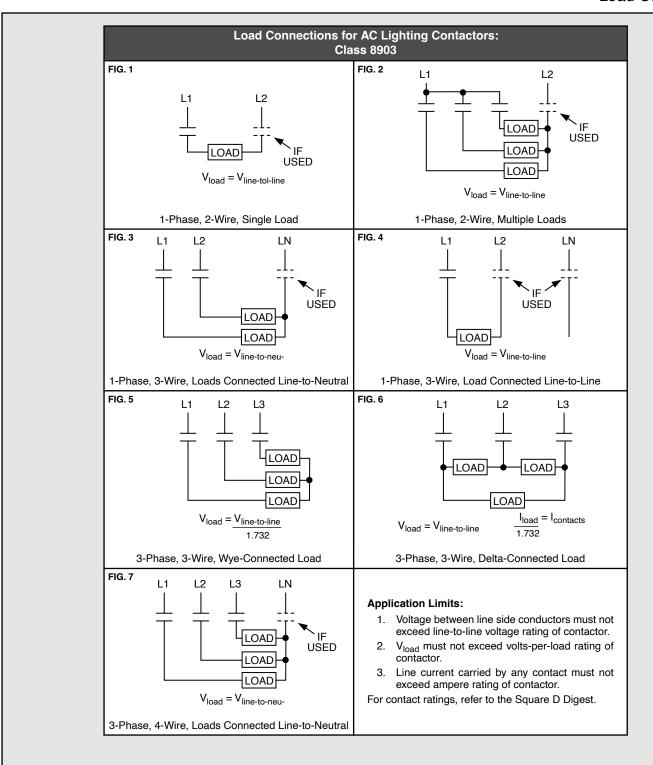
Special Control Circuits and 1- and 3-Phase Motor Connections





Class 8865

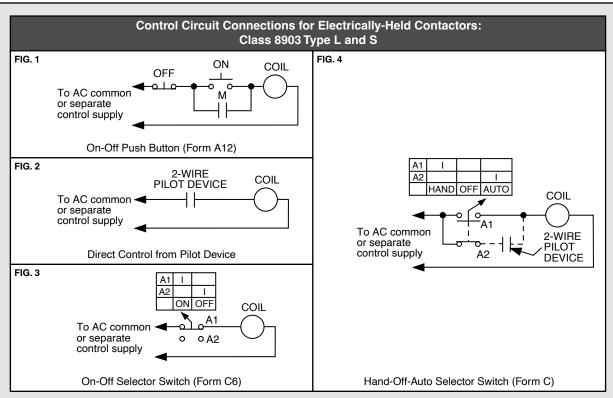


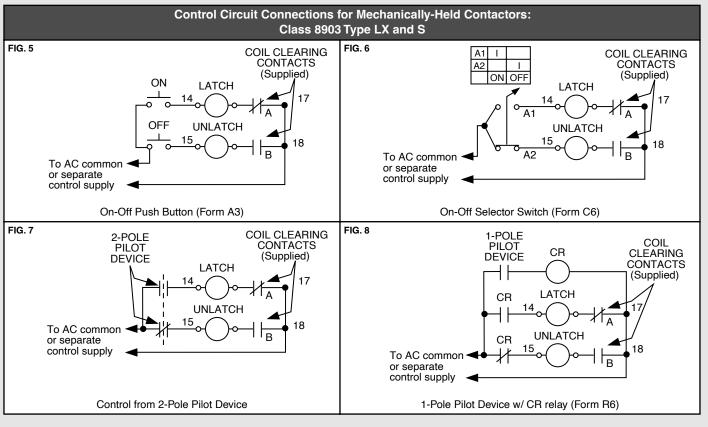


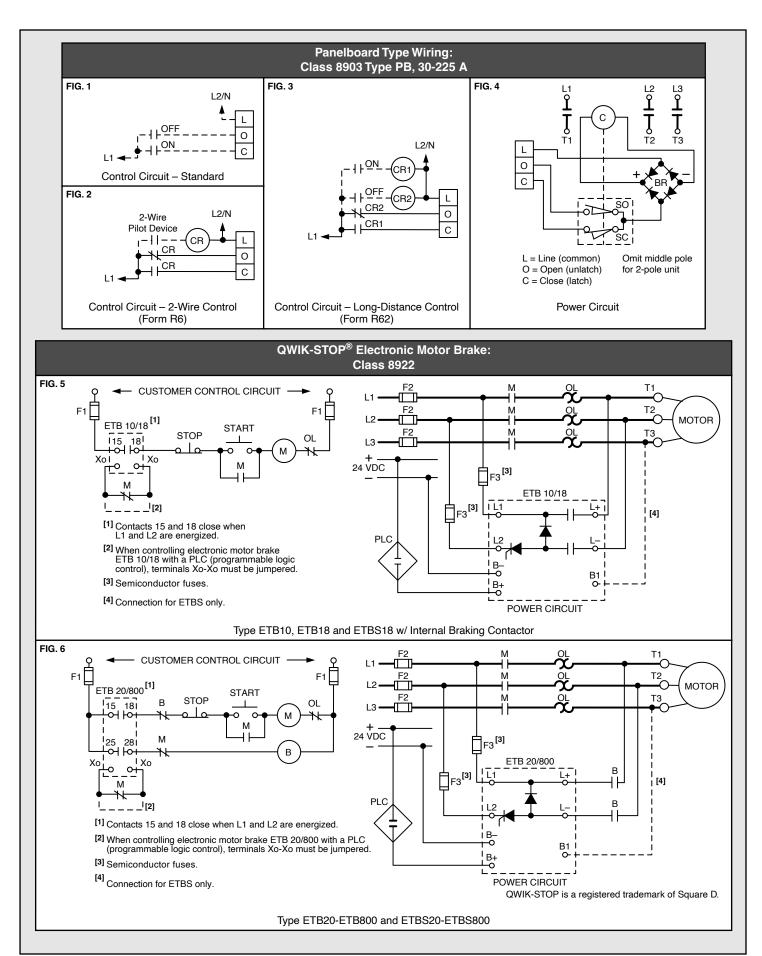
AC Lighting Contactors

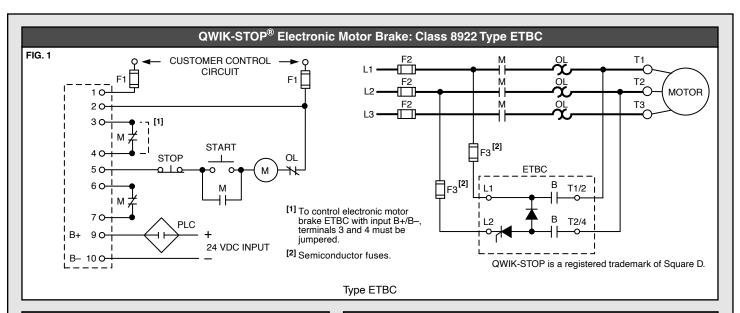
Class 8903

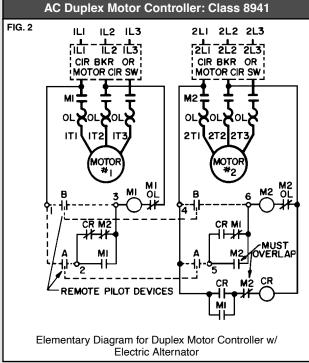
Control Circuit Connections

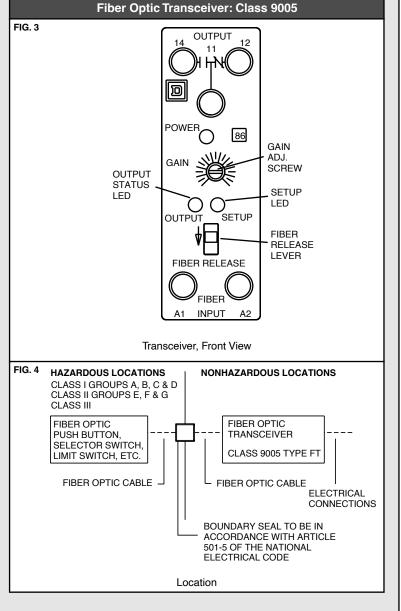


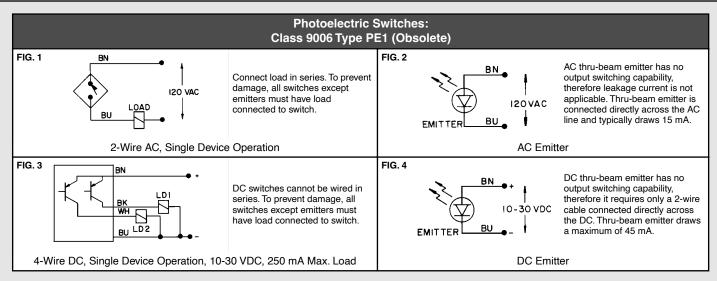


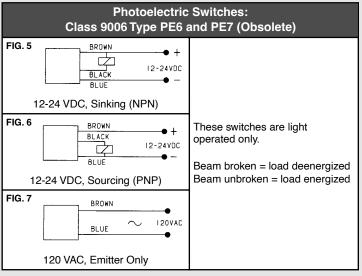


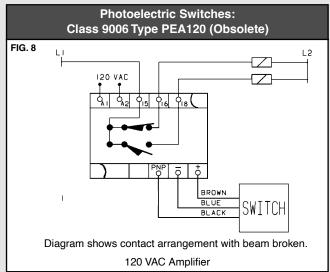


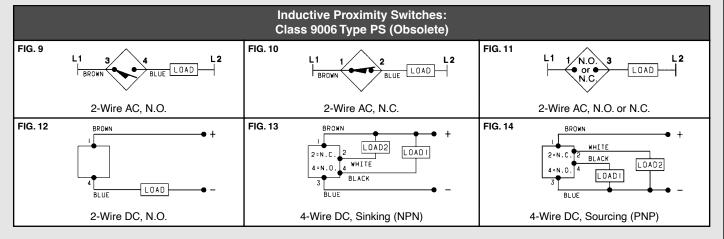




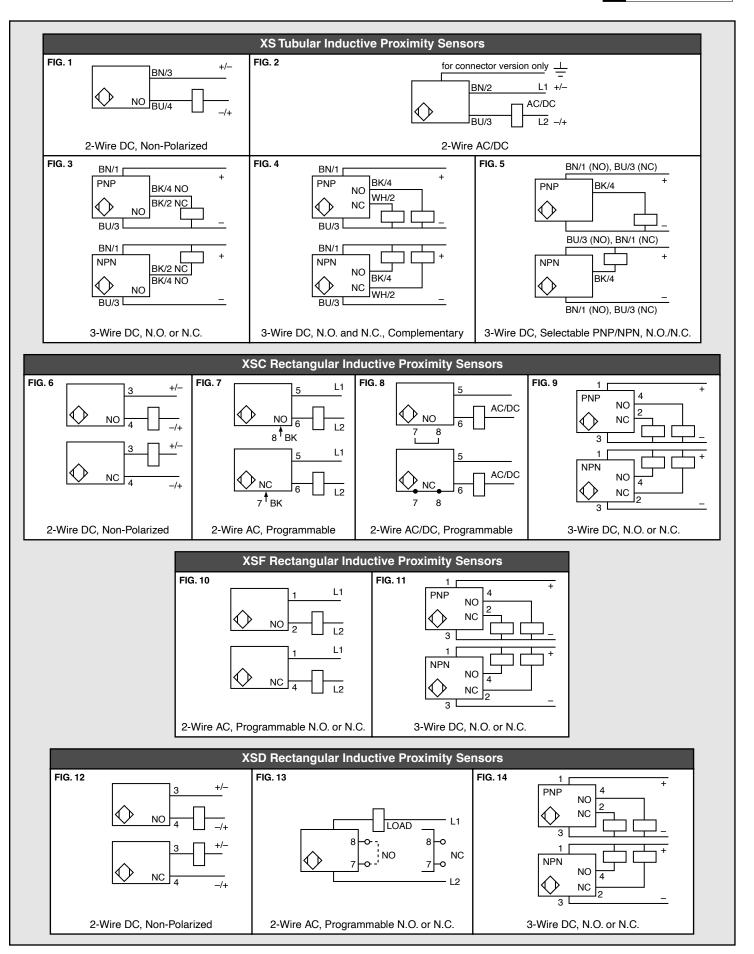




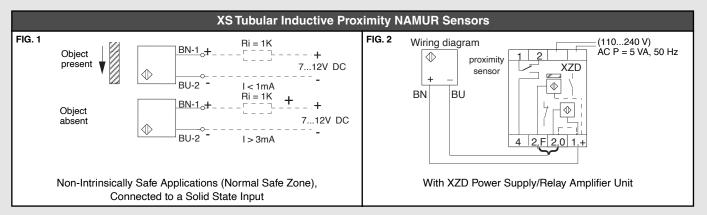


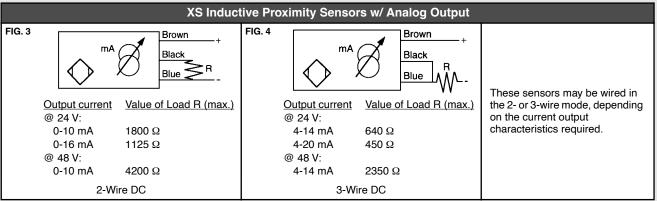


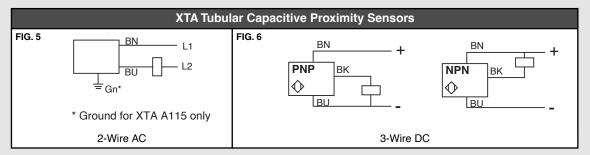




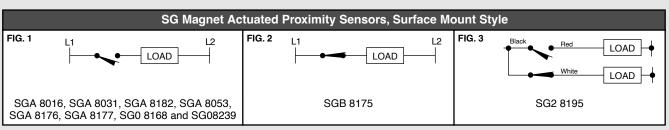


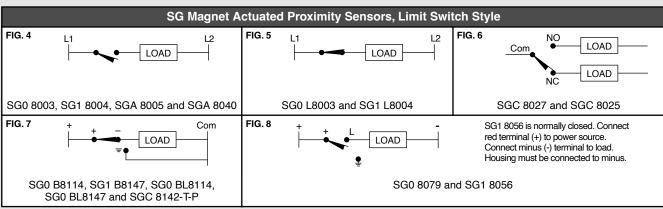


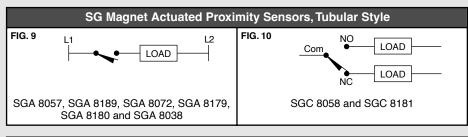


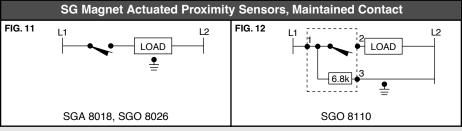


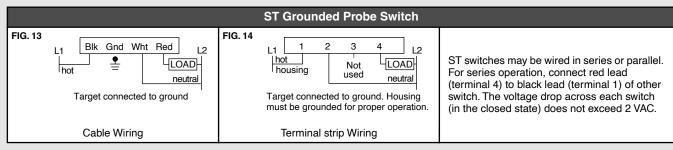


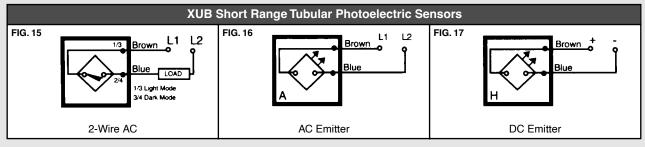




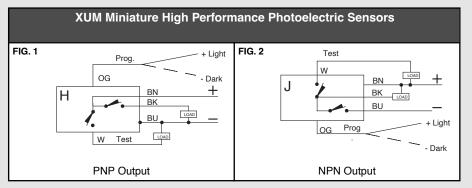


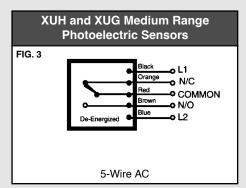


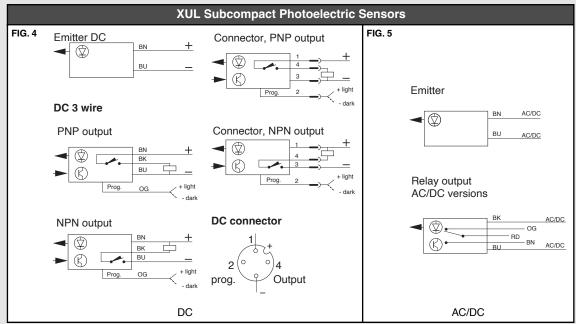


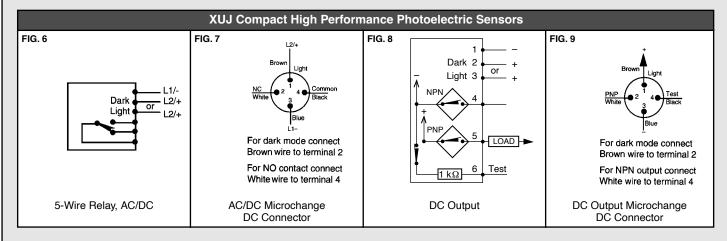




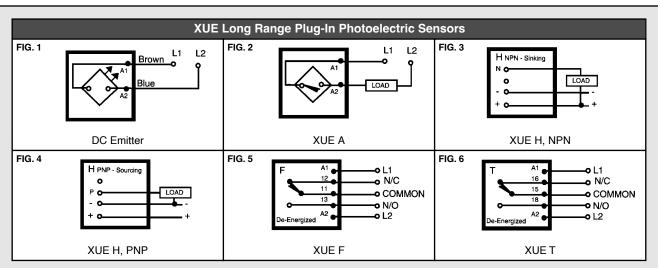


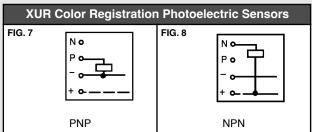


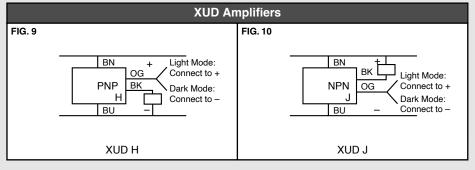


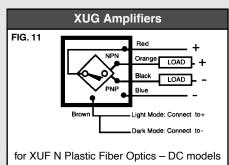


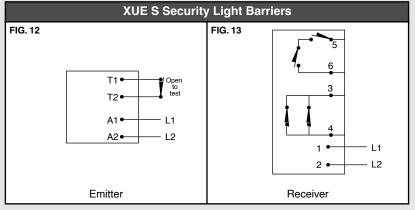




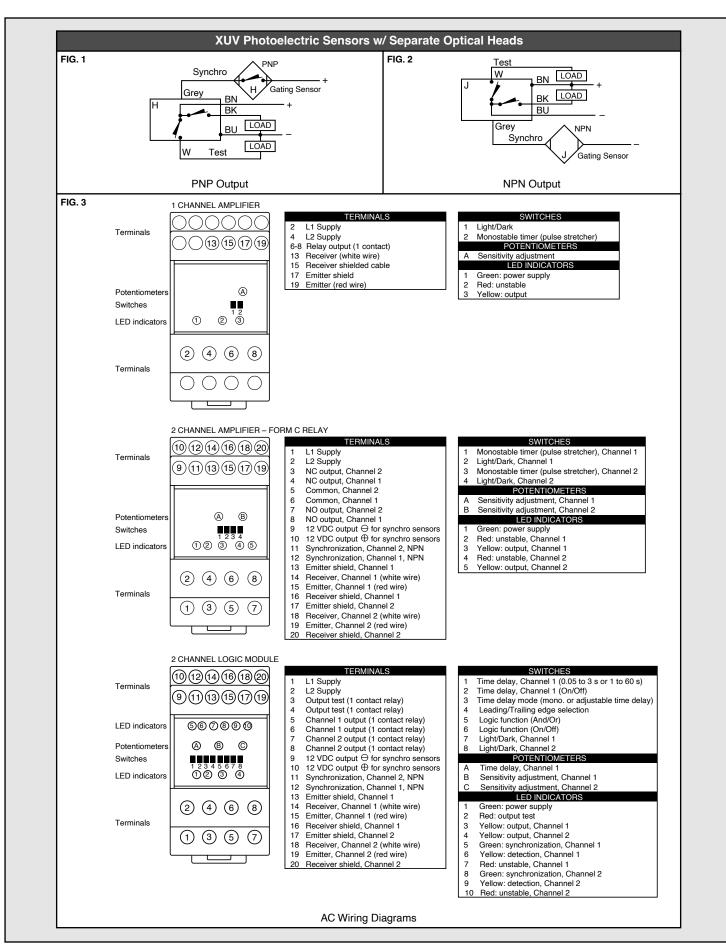


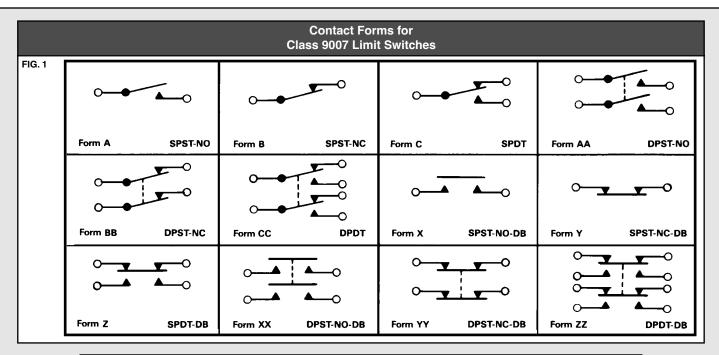


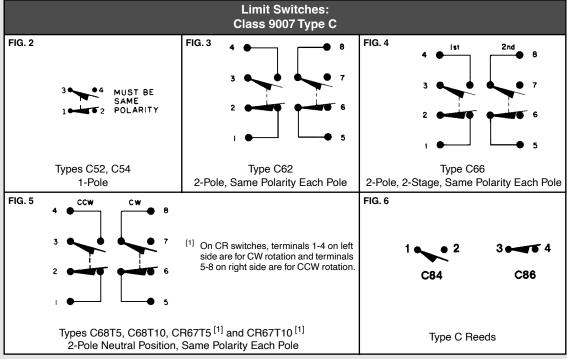


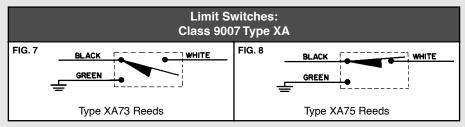


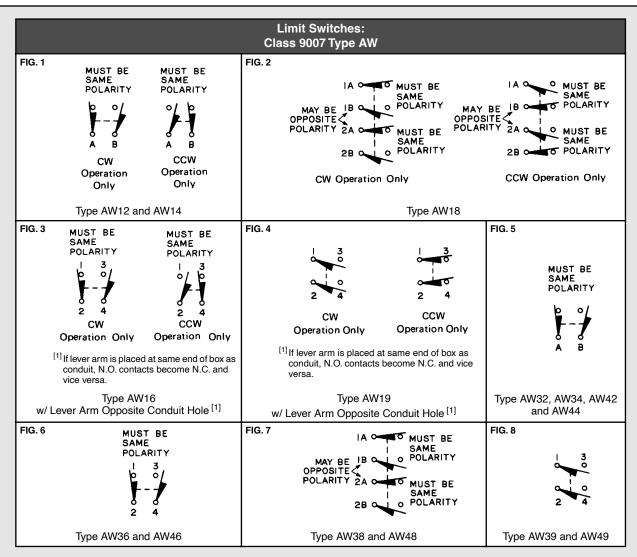


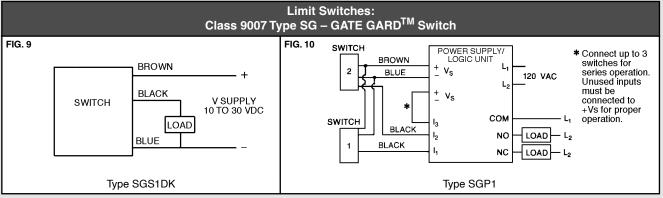




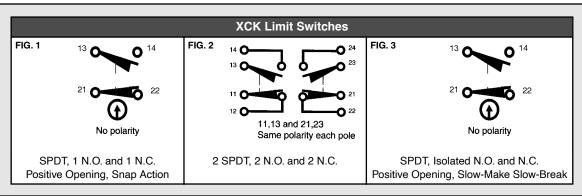


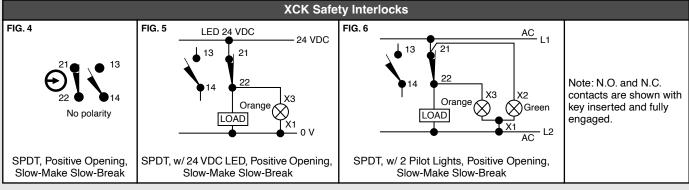


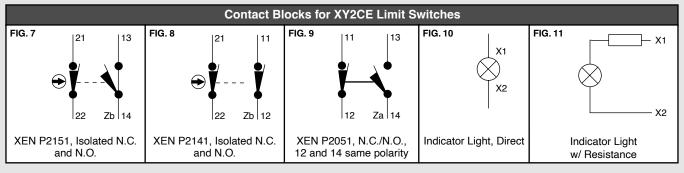


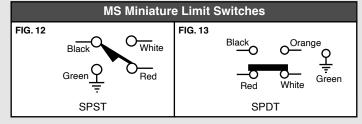


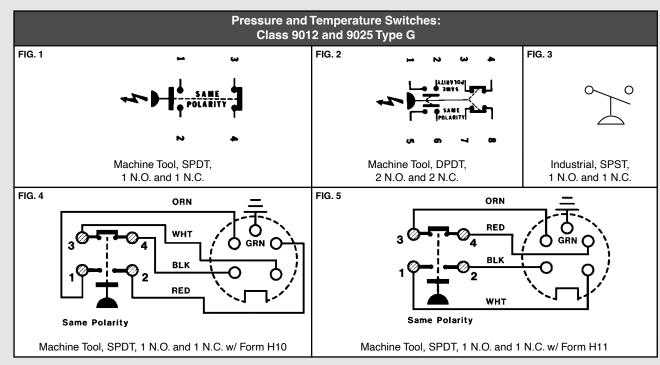


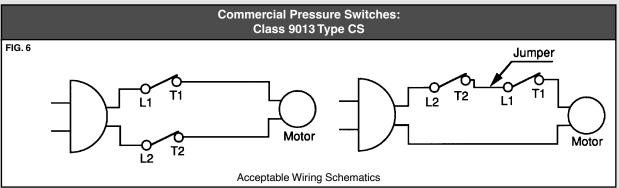


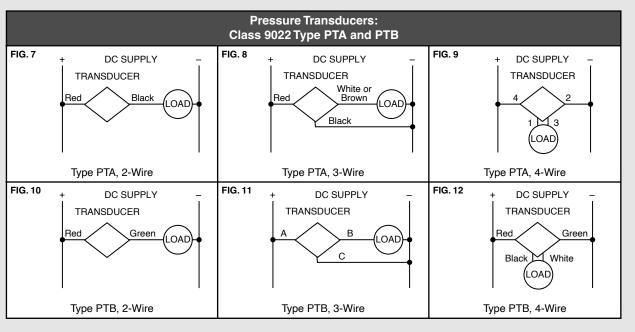


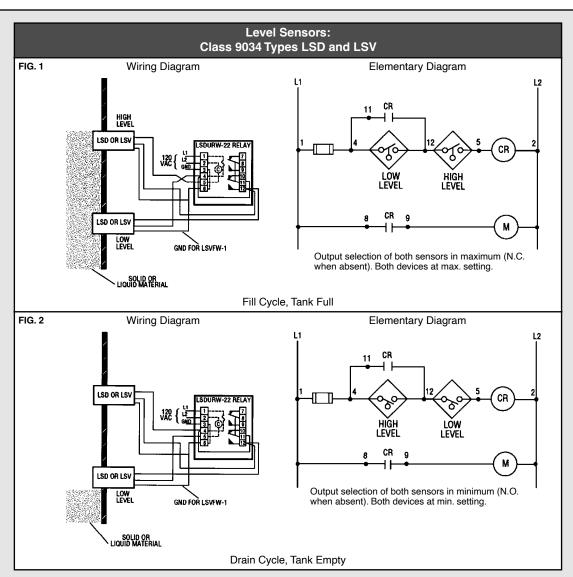


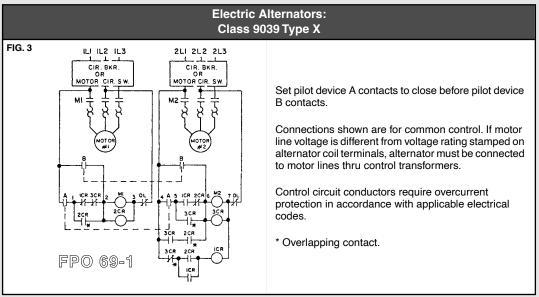




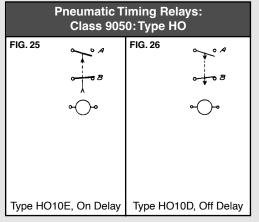


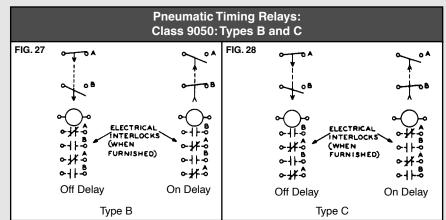




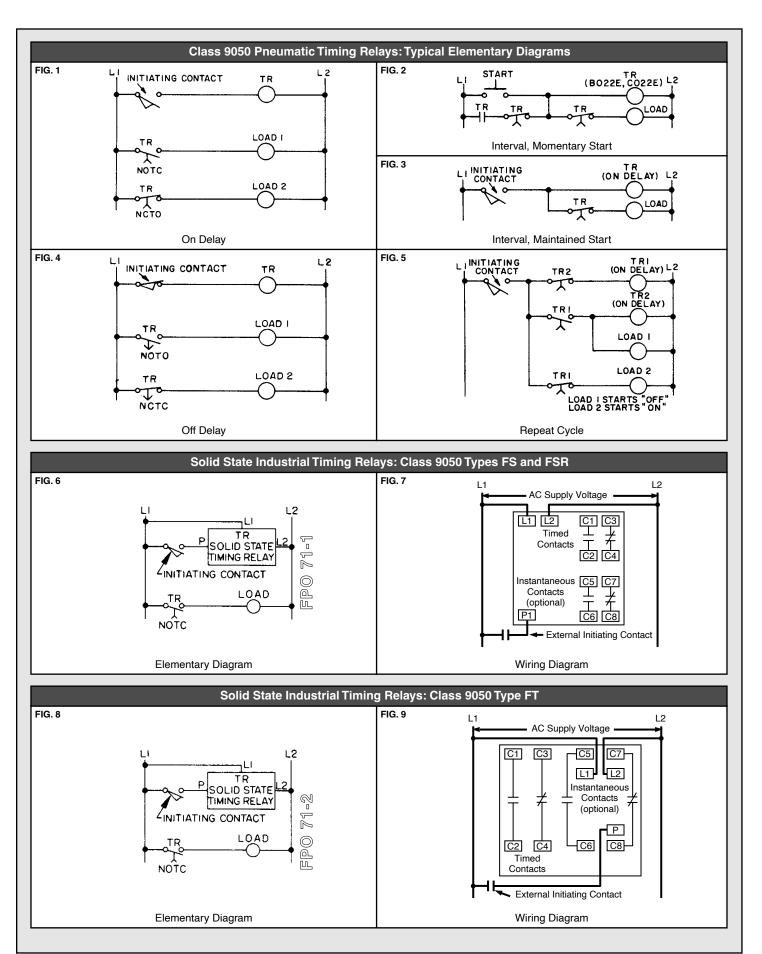


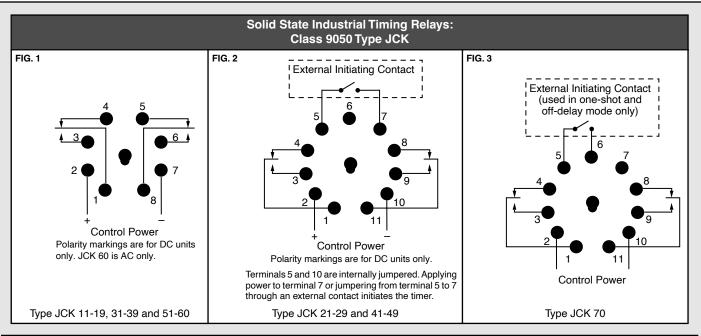
			iming Relays:		
		T	0:Type AO	ī	1
FIG. 1	FIG. 2	FIG. 3 18 1A 2A 2B	FIG. 4 /8 /A 2A 28	FIG. 5	FIG. 6
•——	•——	•—	- ─-	•—•	•—○—•
				- C	28 24 1A 18 4/0 1 0 16
Type AO10E	Type AO10D	Type AO20E	Type AO20D	Type AO110DE	Type AO120DE
FIG. 7	FIG. 8	FIG. 9 18 18 28 28	FIG. 10 /8 /A 2A 2B	FIG. 11	FIG. 12
	•—•	•——	•——	○ —○	
0—11—0 11 0—11—0 12	•—○• •— -•* •— -•*	•—V—° •—V—°	0-1 -0 <i>B</i> 0 ∤-0 <i>A</i>	0-1-02 0-1-04	0-11-0B 0-11-0A
					25 24 1/5
Type AO11E	Type AO11D	Type AO21E	Type AO21D	Type AO111DE	Type AO121DE
FIG. 13	FIG. 14	FIG. 15 /B /A 2A 2B	FIG. 16 /8 /2 28	FIG. 17	FIG. 18
18 19 29 22 2 2 2 2 3 4 5 5	28 29 19 18 1 9 9 9 7 7 7 7	18 18 28 28 9 9 9 9 7 7 7 7	25 29 19 19 1 7 7 1	28 29 19 18 1 4 4 1 7 7 7 7	28 2A /A /B
					28 2A /A /B
Type AO12E	Type AO12D	Type AO22E	Type AO22D	Type AO112DE	Type AO122DE
FIG. 19	FIG. 20	FIG. 21 /B /A 2A 2B	FIG. 22	FIG. 23 /8 /A 2A 28	FIG. 24 /8 /A 2A 2B
0 0 8	0	28 2A /A /B 1	28 2A 1A 1B	0-1-0-8 0-1-0-8 0-1-0-8	28 29 19 19 17 4 4 17
*		0 T B 0 A	28 29 19 18	28 24 14 18	28 29 19 18
Type AO210DE	Type AO211DE	Type AO212DE	Type AO220DE	Type AO221DE	Type AO222DE

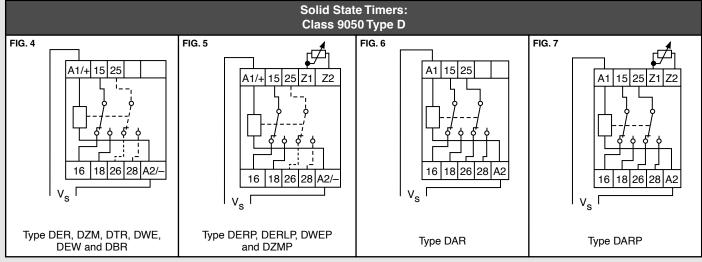


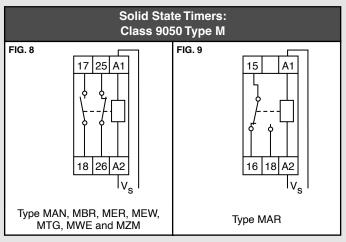


Class 9050









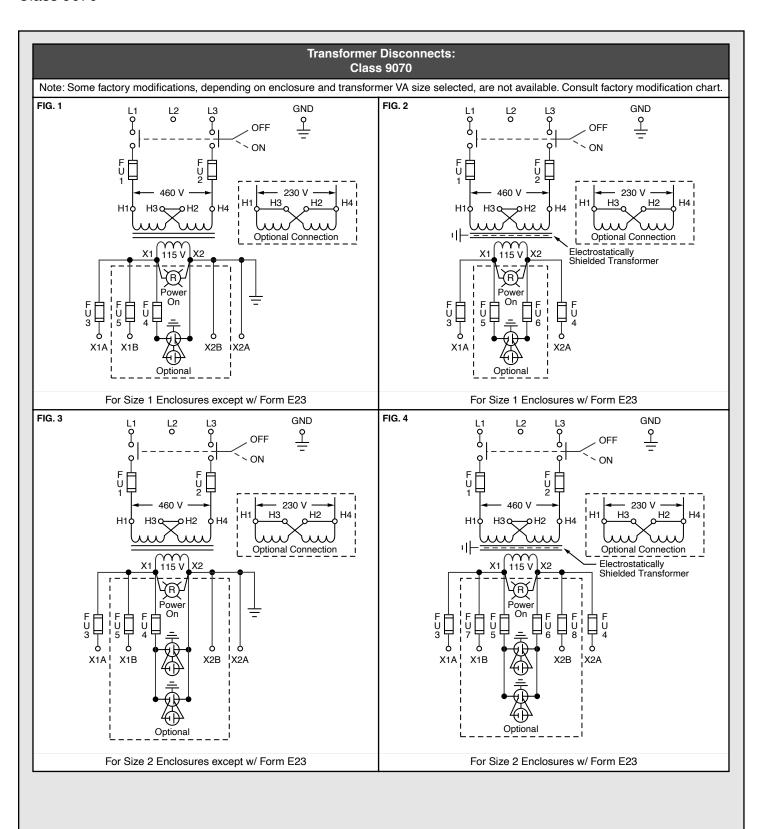


Table 6 Enclosures for Non-Hazardous Locations

Provides Protection Against	NEMA Type 1	NEMA Type 3 ^[1]	NEMA Type 3R ^[1]	NEMA Type 4 ^[2]	NEMA Type 4X ^[2]	Type 5	NEMA Type 12 ^[3]	Type 12K	NEMA Type 13
Accidental contact w/ enclosed equipment	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Falling dirt	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes	Yes
Falling liquids and light splashing		Yes	Yes	Yes	Yes		Yes	Yes	Yes
Dust, lint, fibers and flyings				Yes	Yes	Yes	Yes	Yes	Yes
Hosedown and splashing water			***	Yes	Yes	***	•••		
Oil and coolant seepage							Yes	Yes	Yes
Oil and coolant spraying and splashing			***		***	***	•••		Yes
Corrosive agents					Yes				
Rain, snow and sleet [4]		Yes	Yes	[5]	Yes				
Windblown dust		Yes		[5]	Yes	Yes			

^[1] Intended for outdoor use.

Table 7 Enclosures for Hazardous Locations

			Enclosure						
Provides Protection Against	Class ^[1]	Group ^[1]	N	ЕМА Туре	7	NEMA Type 9			
			7B	7C	7D	9E	9F	9G	
Hydrogen, manufactured gas	I	В	Yes						
Ethyl ether, ethylene, cyclopropane	I	С	Yes	Yes					
Gasoline, hexane, naphtha, benzine, butane, propane, alcohol, acetone, benzol, natural gas, lacquer solvent	ı	D	Yes	Yes	Yes				
Metal dust	II	E				Yes			
Carbon black, coal dust, coke dust	II	F					Yes		
Flour, starch, grain dust	II	G					Yes	Yes	

^[1] As described in Article 500 of the National Electrical Code.

^[2] Intended for indoor and outdoor use.

^[3] Square D Industrial Control design NEMA Type 12 enclosures may be field modified for outdoor applications.

^[4] External operating mechanisms are not required to be operable when the enclosure is ice covered.

^[5] Square D Industrial Control design NEMA Type 4 enclosures provide protection against these environments.

Ampacity Based on NEC[®] Table 310-16 — Allowable Ampacities of Insulated Conductors Rated 0-2000 Volts, Not More Than Three Conductors in Raceway or Cable. Based on 30 °C Ambient Temperature. Trade Size of Conduit or Tubing Based on NEC Chapter 9, Table 1 and Tables 3A, 3B, 3C, 4 and 5B. Refer to Chapter 9 for Maximum Number of Conductors in Trade Sizes of Conduit or Tubing. Dimensions of Insulated Conductors for Conduit Fill Determined from NEC Chapter 9 Tables 5 and 5A.

For information on temperature ratings of terminations to equipment, see NEC Section 110-14c. Underlined conductor insulation types indicates ampacity is for WET locations. See NEC Table 310-13.

Table 8 Conductor Ampacity based on NEC Table 310-16

			COPPE	R COND	UCTOR	S			ALUMINUM CONDUCTORS								
		75 Conduc	°C (167 ctor Insu	°F) lation ^[1]			°C (194 ctor Insu	°F) lation ^[1]			75 Condu	°C (167 ctor Insu	°F) lation ^[1]	l		°C (194 ctor Insu	°F) ılation ^[1]
Wire Size AWG	0-16 city Copper		, THW, USE	THWN,	XHHW	310-16 bacity	THHN,	XHHW	Wire Size AWG	0-16 city Copper		, THW, SE	<u>XH</u>	<u>IHW</u>	0-16 city Copper	THHN,	, XHHW
kcmil	Table 310-16 Ampacity Insulated Copper	Conduit 3W	Conduit 4W [2]	Conduit 3W	Conduit 4W [2]	Table 310-16 Ampacity Insulated Copper	Conduit 3W	Conduit 4W [2]	kcmil	Table 310-16 Ampacity Insulated Copper	Conduit 3W	Conduit 4W [2]	Conduit 3W	Conduit 4W [2]	Table 310-16 Ampacity Insulated Copper	Conduit 3W	Conduit 4W [2]
†14	20			1/2	1/2	25	1/2	1/2									
† 12	25			1/2	1/2	30	1/2	1/2	† 12	20			1/2	1/2	25	1/2	1/2
† 10	35			1/2	1/2	40	1/2	1/2	† 10	30			1/2	1/2	35	1/2	1/2
8	50	3/4	1	1/2 [3]	3/4	55	1/2 [3]	3/4	8	40	3/4	3/4	1/2	3/4	45	1/2	3/4
6	65	1	1	3/4	3/4 [4]	75	3/4	3/4 [4]	6	50	3/4	1	3/4	3/4	60	3/4	3/4
4	85	1	1-1/4	1	1	95	1	1	4	65	1	1	3/4	1	75	3/4	1
3	100	1-1/4	1-1/4	1	1-1/4	110	1	1-1/4	3	75					85		
2	115	1-1/4	1-1/4	1	1-1/4	130	1	1-1/4	2	90	1	1-1/4	1	1-1/4	100	1	1-1/4
1	130	1-1/4	1-1/2	1-1/4	1-1/2	150	1-1/4	1-1/2	1	100	1-1/4	1-1/2	1-1/4	1-1/2	115	1-1/4	1-1/2
1/0	150	1-1/2	2	1-1/4	1-1/2	170	1-1/4	1-1/2	1/0	120	1-1/4	1-1/2	1-1/4	1-1/2	135	1-1/4	1-1/2
2/0	175	1-1/2	2	1-1/2	2	195	1-1/2	2	2/0	135	1-1/2	2	1-1/4	1-1/2	150	1-1/4	1-1/2
3/0	200	2	2	1-1/2	2	225	1-1/2	2	3/0	155	1-1/2	2	1-1/2	2	175	1-1/2	2
4/0	230	2	2-1/2	2	2	260	2	2	4/0	180	2	2	1-1 /2	2	205	1-1/2	2
250	255	2-1/2	2-1/2	2	2-1/2	290	2	2-1/2	250	205	2	2-1/2	2	2	230	2	2
300	285	2-1/2	3	2	2-1/2	320	2	2-1/2	300	230	2	2-1/2	2	2-1/2	255	2	2-1/2
350	310	2-1/2	3	2-1/2	3	350	2-1/2	3	350	250	2-1/2	3	2-1/2	3	280	2-1/2	3
400	335	3	3	2-1/2	3	380	2-1/2	3	400	270	2-1/2	3	2-1/2	2-1/2 ^[5]	305	2-1/2	2-1/2 ^[5]
500	380	3	3-1/2	3	3	430	3	3	500	310	3	3	2-1/2	3	350	2-1/2	3
600	420	3	3-1/2	3	3-1/2	475	3	3-1/2	600	340	3	3-1/2	3	3	385	3	3
700	460	3-1/2	4	3	3-1/2	520	3	3-1/2	700	375	3	3-1/2	3	3-1/2	420	3	3-1/2
750	475	3-1/2	4	3-1/2	4	535	3-1/2	4	750	385	3	3-1/2	3	3-1/2	435	3	3-1/2
800	490	3-1/2	4	3-1/2	4	555	3-1/2	4	800	395					450		
900	520	4	5	3-1/2	4	585	3-1/2	4	900	425					480		
1000	545	4	5	3-1/2	5	615	3-1/2	5	1000	445	3-1/2	4	3-1/2	4	500	3-1/2	4

^[1] Unless otherwise permitted in the Code, the overcurrent protection for conductor types marked with an with an obelisk (†) shall not exceed 15 A for No. 14, 20 A for No. 12 and 30 A for No. 10 copper, or 15 A for No. 12 and 25 A for No. 10 aluminum after any correction factors for ambient temperature and number of conductors have been applied.

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^[2] On a 4-wire, 3-phase wye circuit where the major portion of the load consists of nonlinear loads such as electric discharge lighting, electronic computer/data processing, or similar equipment there are harmonic currents present in the neutral conductor and the neutral shall be considered to be a current-carrying conductor.

^{[3] #8} XHHW copper wire requires 3/4" conduit for 3W.

^{[4] #6} XHHW copper wire requires 1" conduit for 3Ø4W.

 $^{^{\}text{[5]}}$ 400 kcmil aluminum wire requires 3" conduit for 3Ø4W.

Ampacity Correction Factors:

For ambient temperatures other than 30 °C (86 °F), multiply the ampacities listed in Table 8 by the appropriate factor listed in Table 9.

Adjustment Factors:

Where the number of current-carrying conductors in a raceway or cable exceeds three, reduce the allowable ampacities as shown in Table 9.

Table 9 Ampacity Correction Factors

Ambient Temperature (°C)	75 °C (167 °F) Conductors	90 °C (194 °F) Conductors	Ambient Temperature (°F)
21-25	1.05	1.04	70-77
26-30	1.00	1.00	78-86
31-35	.94	.96	87-95
36-40	.88	.91	96-104
41-45	.82	.87	105-113
46-50	.75	.82	114-122
51-55	.67	.76	123-131
56-60	.58	.71	132-140
61-70	.33	.58	141-158
71-80		.41	159-176

Table 10 Adjustment Factors

No. of Current-Carrying Inductors	Values in Tables as Adjusted for Ambient Temperature
4-6	80%
7-9	70%
10-20	50%
21-30	45%
31-40	40%
41 and above	35%
For exceptions, see exceptions	to Note 8 of NEC [®] Table 310-16.

Ratings for 120/240 V, 3-Wire, Single-Phase Dwelling Services:

The ratings in Table 11 are permitted ratings for dwelling unit service and feeder conductors which carry the total load of the dwelling. The grounded conductor (neutral) shall be permitted to be not more than 2 AWG sizes smaller than the ungrounded conductors, provided the requirements of 215-2, 220-22 and 230-42 are met.

Table 11 Ratings for 120/240 V, 3-Wire, Single-Phase Dwelling Services – see NEC 310-16 Note 3

Rating (A)	100	110	125	150	175	200	225	250	300	350	400
Copper	4 AWG	3 AWG	2 AWG	1 AWG	1/0 AWG	2/0 AWG	3/0 AWG	4/0 AWG	250 kcmil	350 kcmil	400 kcmil
Aluminum	2 AWG	1 AWG	1/0 AWG	2/0 AWG	3/0 AWG	4/0 AWG	250 kcmil	300 kcmil	350 kcmil	500 kcmil	600 kcmil

NEC 240-3 Protection of Conductors:

Conductors, other than flexible cords and fixture wires, shall be protected against overcurrent in accordance with their ampacities as specified in NEC Section 310-15, unless otherwise permitted in parts (a) through (m).

NEC 220-3 (a) Continuous and Noncontinuous Loads:

The branch circuit rating shall not be less than the noncontinuous load plus 125% of the continuous load (see exception for 100% rated devices).

NEC 220-10 (b) Continuous and Noncontinuous Loads:

Where a feeder supplies continuous loads or any combination of continuous and noncontinuous loads, the rating of the overcurrent device shall not be less than the noncontinuous load plus 125% of the continuous load (see exception for 100% rated devices).

NEC 430-22 (a) Single Motor Circuit Conductors:

Branch circuit conductors supplying a single motor shall have an ampacity not less than 125% of the motor full-load current rating (see exceptions).

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Table 12 AWG and Metric Wire Data

AWG	Conductor	Conductor	Resistance @	² 20 °C (68 °F)	AWG	Conductor	Conductor	Resistance @	² 20 °C (68 °F)
Size	dia. (mm)	dia. (in)	Ohm per ft	Ohm per m	Size	dia. (mm)	dia. (in)	Ohm per ft	Ohm per m
29		.01126	.08180	.2684	13	1.900	.07480	.001853	.006081
	.315	.01240	.06743	.2212		2.000	.07874	.001673	.005488
28		.01264	.06491	.2130	12		.08081	.001588	.005210
	.355	.01398	.05309	.1742		2.120	.08346	.001489	.004884
27		.01420	.05143	.1687		2.240	.08819	.001333	.004375
	.400	.01575	.04182	.1372	11		.09074	.001260	.004132
26		.01594	.04082	.1339		2.360	.09291	.001201	.003941
	.450	.01772	.03304	.1084		2.500	.09843	.001071	.003512
25		.01790	.03237	.1062	10		.1019	.0009988	.003277
	.500	.01969	.02676	.08781		2.650	.1043	.0009528	.003126
24		.02010	.02567	.08781		2.800	.1102	.0008534	.002800
	.560	.02205	.02134	.07000	9		.1144	.0007924	.002500
23		.02257	.02036	.06679		3.000	.1181	.0007434	.002439
	.630	.02480	.01686	.05531		3.150	.1240	.0006743	.002212
22		.02535	.01614	.05531	8		.1285	.0006281	.002061
	.710	.02795	.01280	.04201		3.350	.1319	.0005662	.001956
21		.02846	.01280	.04201		3.550	.1398	.0005309	.001742
	.750	.02953	.01190	.03903	7		.1443	.0004981	.001634
	.800	.03150	.01045	.03430		3.750	.1476	.0004758	.001561
20		.03196	.01015	.03331		4.000	.1575	.0004182	.001372
	.850	.03346	.009261	.05038	6		.1620	.0003952	.001296
	.900	.03543	.008260	.02642		4.250	.1673	.0003704	.001215
19		.03589	.008051	.02642		4.500	.1772	.0003304	.001084
	.950	.03740	.007414	.02432	5		.1819	.0003134	.001028
	1.000	.03937	.006991	.02195		4.750	.1870	.0002966	.0009729
18		.04030	.006386	.02095		5.000	.1968	.0002676	.0008781
	1.060	.04173	.005955	.01954	4		.2043	.0002485	.0008152
	1.120	.04409	.005334	.01750		5.600	.2205	.0002134	.0007000
17		.04526	.005063	.01661	3		.2294	.0001971	.0006466
	1.180	.04646	.004805	.01577		6.300	.2480	.0001686	.0005531
	1.250	.04921	.004282	.01405	2		.2576	.0001563	0005128
16		.05082	.004016	.01317		7.100	.2795	.0001327	.0004355
	1.320	.05197	.003840	.01260	1		.2893	.0001239	.0004065
	1.400	.05512	.004016	.01317		8.000	.3150	.0001045	.0003430
15		.05707	.003414	.01045	0		.3249	.00009825	.0003223
	1.500	.05906	.002974	.009756		9.000	.3543	.00008260	.0002710
	1.600	.06299	.002526	.008286	2/0		.3648	.00007793	.0002557
14		.06408	.002315	.007596		10.000	.3937	.00006691	.0002195
	1.700	.06693	.002315	.007596	3/0		.4096	.00006182	.0002195
	1.800	.07087	.002065	.006775	4/0		.4600	.00004901	.0001608
13		.07196	.002003	.006571		11.800	.4646	.00004805	.0001577

Table 13 Electrical formulas for Amperes, Horsepower, Kilowatts and KVA

To find	Single phase	3-phase	Direct current
Kilowatts	<u>I x E x PF</u>	<u>I x E x 1.73 x PF</u>	<u>l x F</u>
	1000	1000	1000
KVA	<u>I x E</u> 1000	<u>I x E x 1.73</u> 1000	_
Horsepower (output)	<u>I x E x % Eff x PF</u>	<u>I x E x 1.73 x %Eff x PF</u>	<u>I x E x %Eff</u>
	746	746	746
Amperes when Horsepower is known	<u>HP x 746</u>	<u>HP x 746</u>	<u>HP x 746</u>
	E x %Eff x PF	1.73 x E x %Eff x PF	E x %Eff
Amperes when Kilowatts is known	<u>KW x 1000</u>	<u>KW x 1000</u>	<u>KW x 1000</u>
	E x PF	1.73 x E x PF	E
Amperes	<u>KVA x 1000</u> E	<u>KVA x 1000</u> 1.73 x E	_
E=Volts I = Amperes	%Eff = Percent efficiency	PF = Power factor HP = Horsepower	KVA = Kilovolt-Amps

Average Efficiency and Power Factor Values of Motors:

When actual efficiencies and power factors of the motors to be controlled are not known, the following approximations may be used:

Efficiencies:

DC motors, 35 hp and less: 80% to 85% DC motors, above 35 hp: 85% to 90% Synchronous motors (at 100% PF): 92% to 95%

"Apparent" efficiencies (Efficiency x PF):

3-phase induction motors, 25 hp and less: 70% 3-phase induction motors above 25 hp: 80%

Decrease these figures slightly for single phase induction motors.

Table 14 Ratings for 3-Phase, Single-Speed, Full-Voltage Magnetic Controllers for Nonplugging and Nonjogging Duty

Size of	Continous		Horsepower at ^[1]							
Controller	Current Rating (A)	60 Hz 200 V	60 Hz 230 V	50 Hz 380 V	60 Hz 460 or 575 V	Current Rating (A)				
00	9	1-1/2	1-1/2	1-1/2	2	11				
0	18	3	3	5	5	21				
1	27	7-1/2	7-1/2	10	10	32				
2	45	10	15	25	25	52				
3	90	25	30	50	50	104				
4	135	40	50	75	100	156				
5	270	75	100	150	200	311				
6	540	150	200	300	400	621				
7	810	_	300	_	600	932				

^[1] These horsepower ratings are based on typical locked-rotor current ratings. For motors having higher locked-rotor currents, use a larger controller to ensure its locked-rotor current rating is not exceeded.

Table 15 Ratings for 3-Phase, Single-Speed, Full-Voltage Magnetic Controllers for Plug-Stop, Plug-Reverse or Jogging Duty

Size of	Continous		Horsepower at [1]						
Controller	Current Rating (A)	60 Hz 200 V	60 Hz 230 V	50 Hz 380 V	60 Hz 460 or 575 V	Current Rating (A)			
0	18	1-1/2	1-1/2	1-1/2	2	21			
1	27	3	3	5	5	32			
2	45	7-1/2	10	15	15	52			
3	90	15	20	30	30	104			
4	135	25	30	50	60	156			
5	270	60	75	125	150	311			
6	540	125	150	250	300	621			

These horsepower ratings are based on typical locked-rotor current ratings. For motors having higher locked-rotor currents, use a larger controller to ensure its locked-rotor current rating is not exceeded.

Table 16 Power Conversions

From	to kW	to PS	to hp	to ft-lb/s
1 kW (kilowatt) = 10 ¹⁰ erg/s	1	1.360	1.341	737.6
1 PS (metric horsepower)	0.7355	1	0.9863	542.5
1 hp (horsepower)	0.7457	1.014	1	550.0
1 ft-lb/s (foot-pound per sec)	1.356 x 10 ⁻³	1.843 x 10 ⁻³	1.818 x 10 ⁻³	1

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