

# On the Necessity of Adaptive Regularisation: Optimal Anytime Online Learning on $\ell_p$ -Balls

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Emmeran Johnson (Imperial College London)

David Martínez-Rubio (Carlos III University of Madrid)

Ciara Pike-Burke (Imperial College London)

Patrick Rebeschini (University of Oxford)

# Online Convex Optimisation (OCO)

- A sequential game over  $T$  rounds where in each round  $t = 1, \dots, T$ :
  - A learner picks a point  $x_t$  in a convex set  $V \subset \mathbb{R}^d$ .
  - An adversary chooses a convex loss function  $\ell_t : V \rightarrow [-1, 1]$ , it is revealed to the learner who suffers a loss of  $\ell_t(x_t)$ .
- The goal is to minimize cumulative regret:

$$R_T = \sum_{t=1}^T \ell_t(x_t) - \inf_{u \in V} \sum_{t=1}^T \ell_t(u).$$

# OCO on $\ell_p$ -balls

- $V = \mathcal{B}_p = \{x \in \mathbb{R}^d : \|x\|_p \leq 1\}$ ,  $p > 2$ .
- Follow The Regularised Leader (FTRL) algorithm:

$$x_{t+1} = \arg \min_{x \in V} \left\{ \psi(x) + \eta_t \sum_{s=1}^t \ell_s(x) \right\}.$$

- $\psi(x) = \frac{1}{2}\|x\|_2^2 \implies R_T = O(\sqrt{T}d^{1-2/p})$ .
  - Optimal for  $d \leq T$  (low-dimensional setting).
- $\psi(x) = \frac{1}{p}\|x\|_p^p \implies R_T = O(T^{1-1/p})$ .
  - Optimal for  $d > T$  (high-dimensional setting).

# Optimal Regret with Adaptive Regularisation

- If  $T$  is unknown, how to choose  $\psi$  ?
- FTRL using  $\frac{1}{p}\|x\|_p^p$  until  $t_0 \approx d$  and then switching to  $\frac{1}{2}\|x\|_2^2$  guarantees anytime optimality.
- Anytime optimal = optimal without knowledge of  $T$ .
- Adaptive Regularisation = switching regulariser.

# Necessity of Adaptive Regularisation

- FTRL with  $\frac{1}{2}\|x\|_2^2$  and any decreasing step-size  $\eta_t$  suffers

$$R_T = \Omega\left(\min(T, \sqrt{Td^{1-2/p}})\right).$$

- FTRL with  $\frac{1}{p}\|x\|_p^p$  and any decreasing step-size  $\eta_t$  suffers

$$R_T = \Omega(T^{1-1/p}).$$

- **Main result (separable regularisers):** consider  $\psi(x) = \sum_{i=1}^d g(x_i)$ , where  $g$  is a 1-dimensional regulariser. FTRL with  $\psi$  and any sequence of decreasing  $\eta_t$  cannot be optimal across all dimensions.

# Linear Bandit Setting

- Bandit setting: learner only observes  $\ell_t(x_t)$ , not  $\ell_t$ .
- High-dimensional linear bandit problem is not learnable:

Fix  $p \geq 1$ . For  $d$  large enough and any OCO algorithm with bandit feedback on  $V = \mathcal{B}_p$ , there exists a sequence of random linear losses such that  $\mathbb{E}[\bar{R}_T] = \Omega(T)$ .

# Conclusion

Thank you!