

Learning finite state machine models of evolving systems: From evolution *over time* to variability *in space*

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Agenda

1. Introduction
2. Research Problem
3. Research Objectives
 - Learning to Reuse
 - Learning from Difference
 - Learning by Sampling
4. Final Remarks and Future Work

Introduction

Software maintenance [IEEE, 2006]

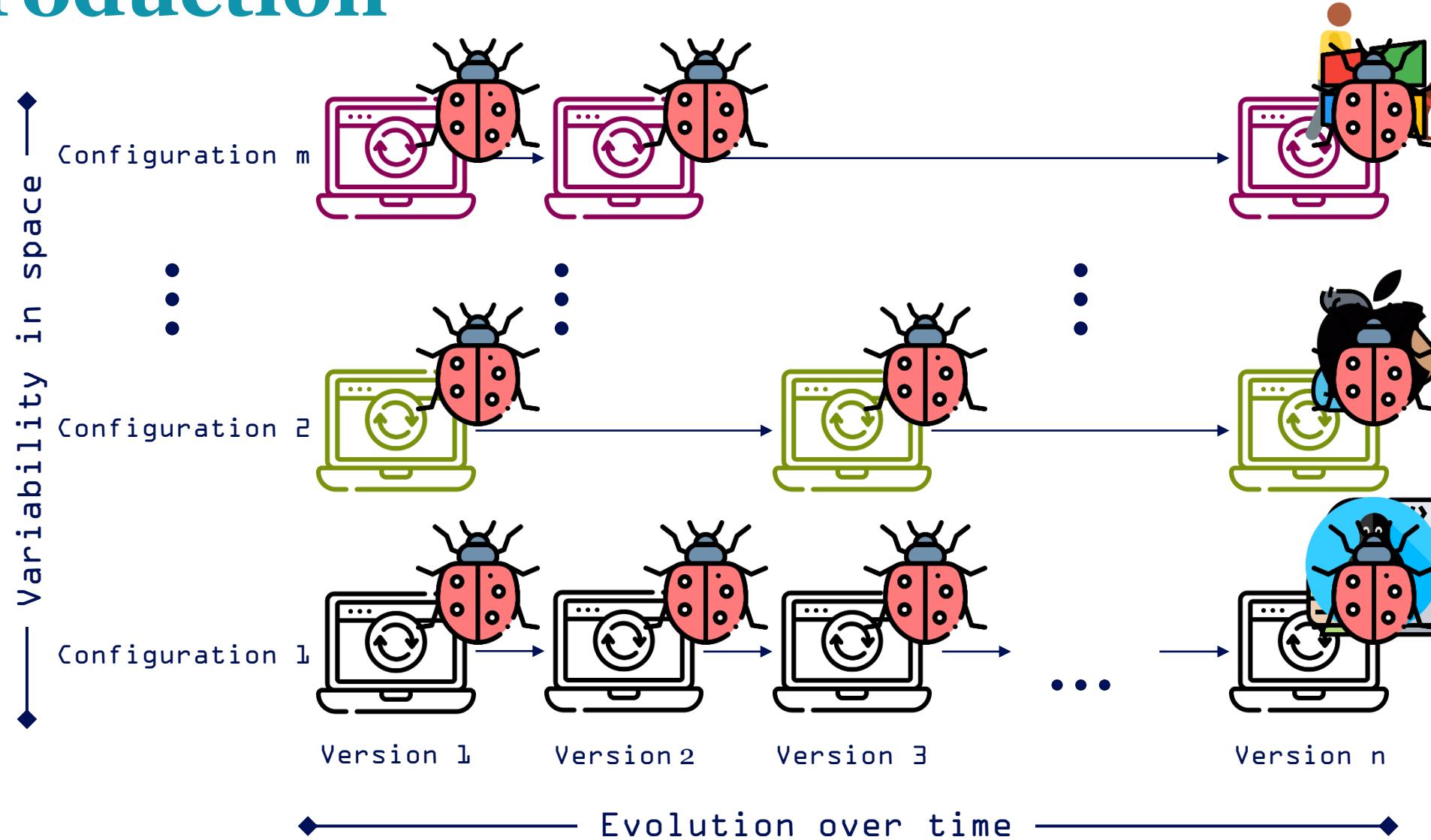
“... modifications after delivery to correct faults, to improve non-functional attributes ...”



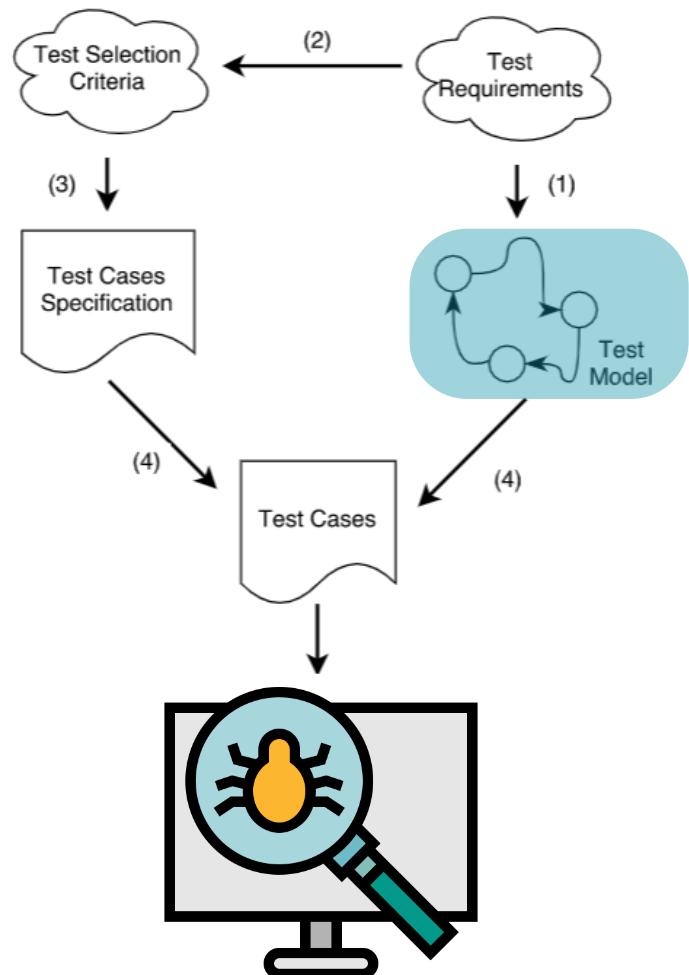
Software evolution [Lehman, 1979]

“... programs must be modified because they operate in or address problems in the real world ...”

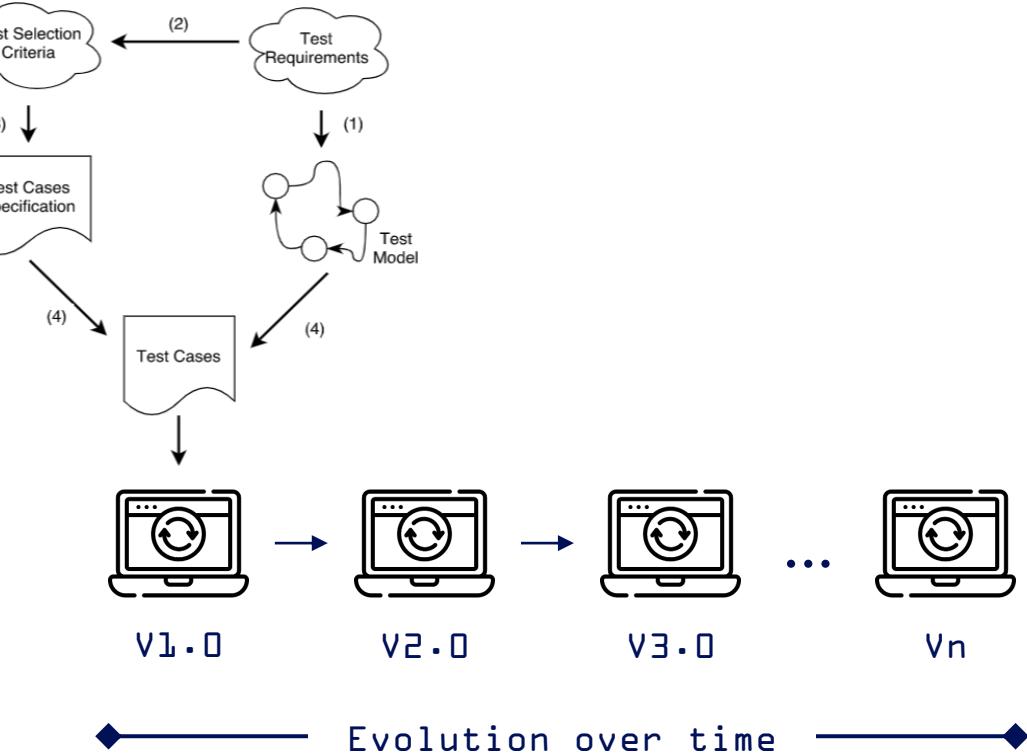
Introduction



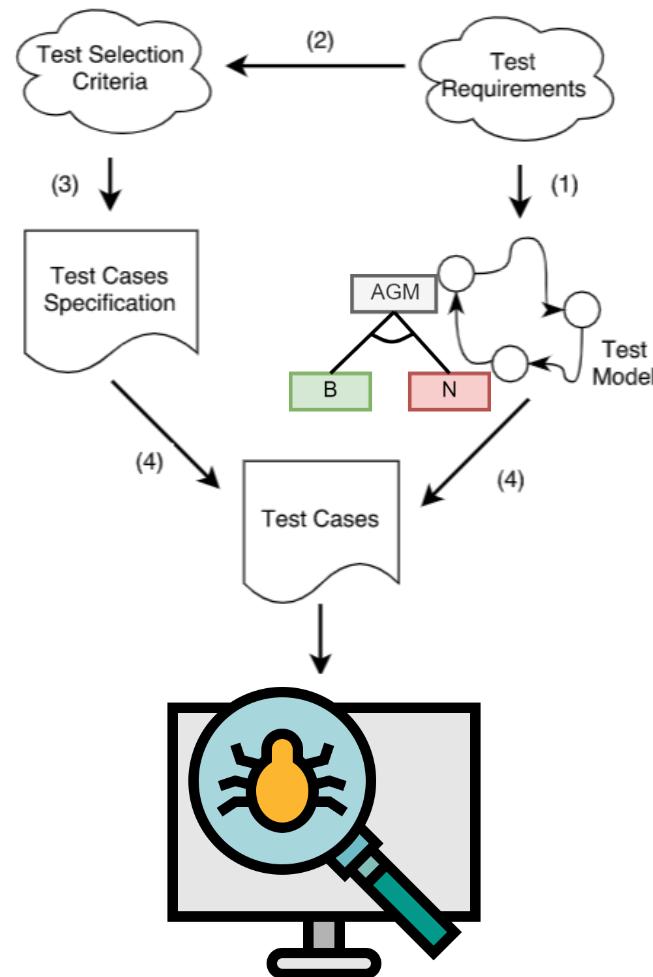
Introduction



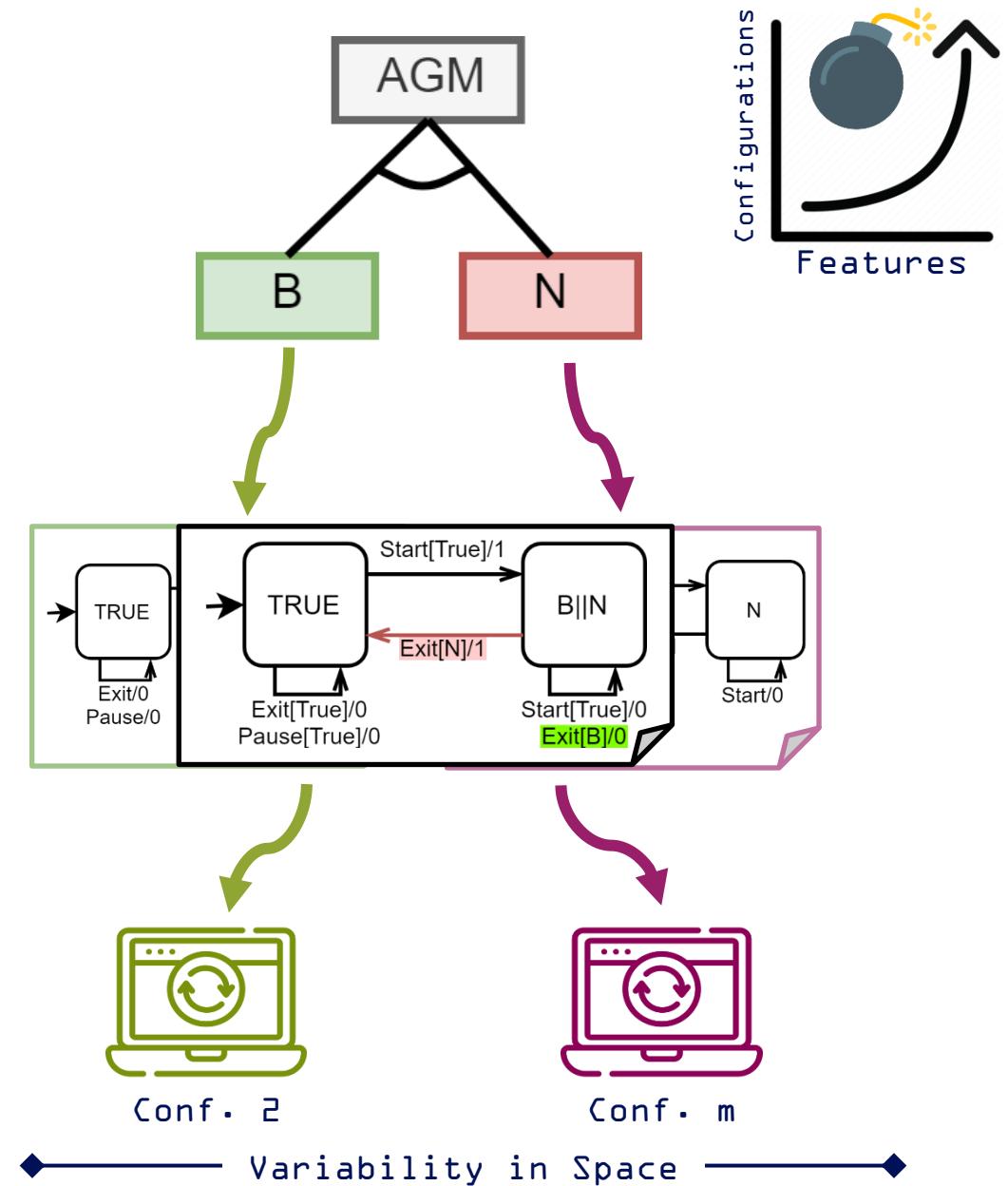
Model-Based Testing (MBT)



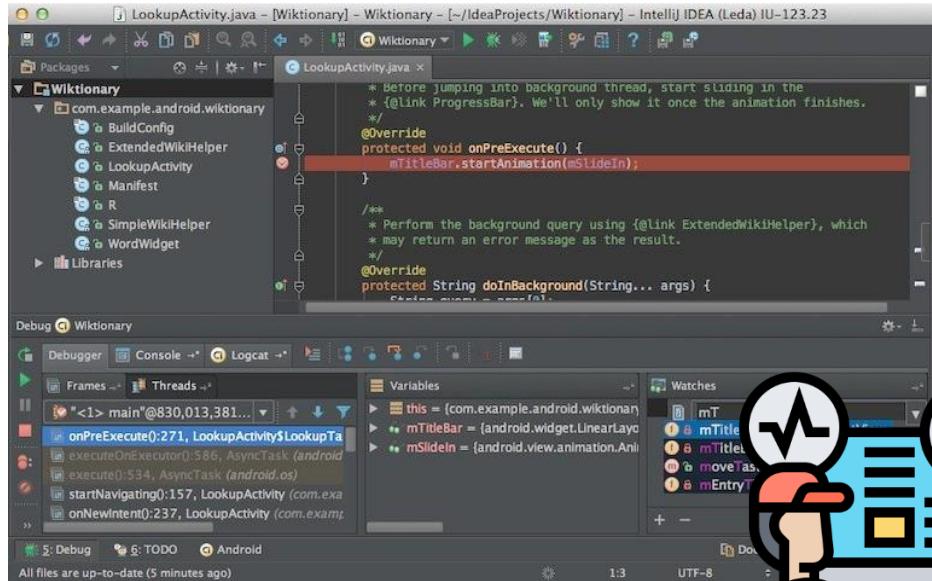
Introduction



Model-Based Testing

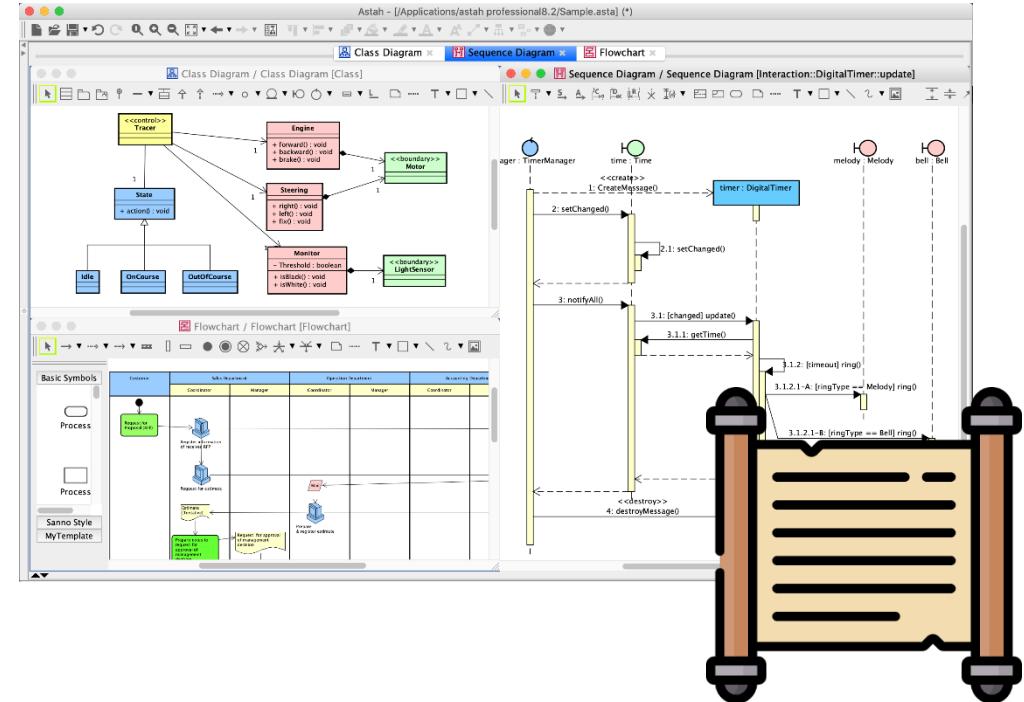
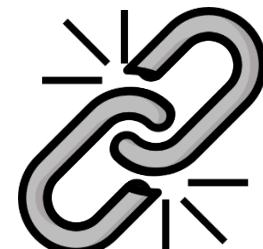


Introduction



```
 * Before jumping into background thread, start sliding in the
 * {@link ProgressBar}. We'll only show it once the animation finishes.
 */
@Override
protected void onPreExecute() {
    mTitleBar.startAnimation(mSlideIn);
}

/**
 * Perform the background query using {@link ExtendedWikiHelper}, which
 * may return an error message as the result.
 */
@Override
protected String doInBackground(String... args) {
    return mHelper.getSearchResults(args);
}
```

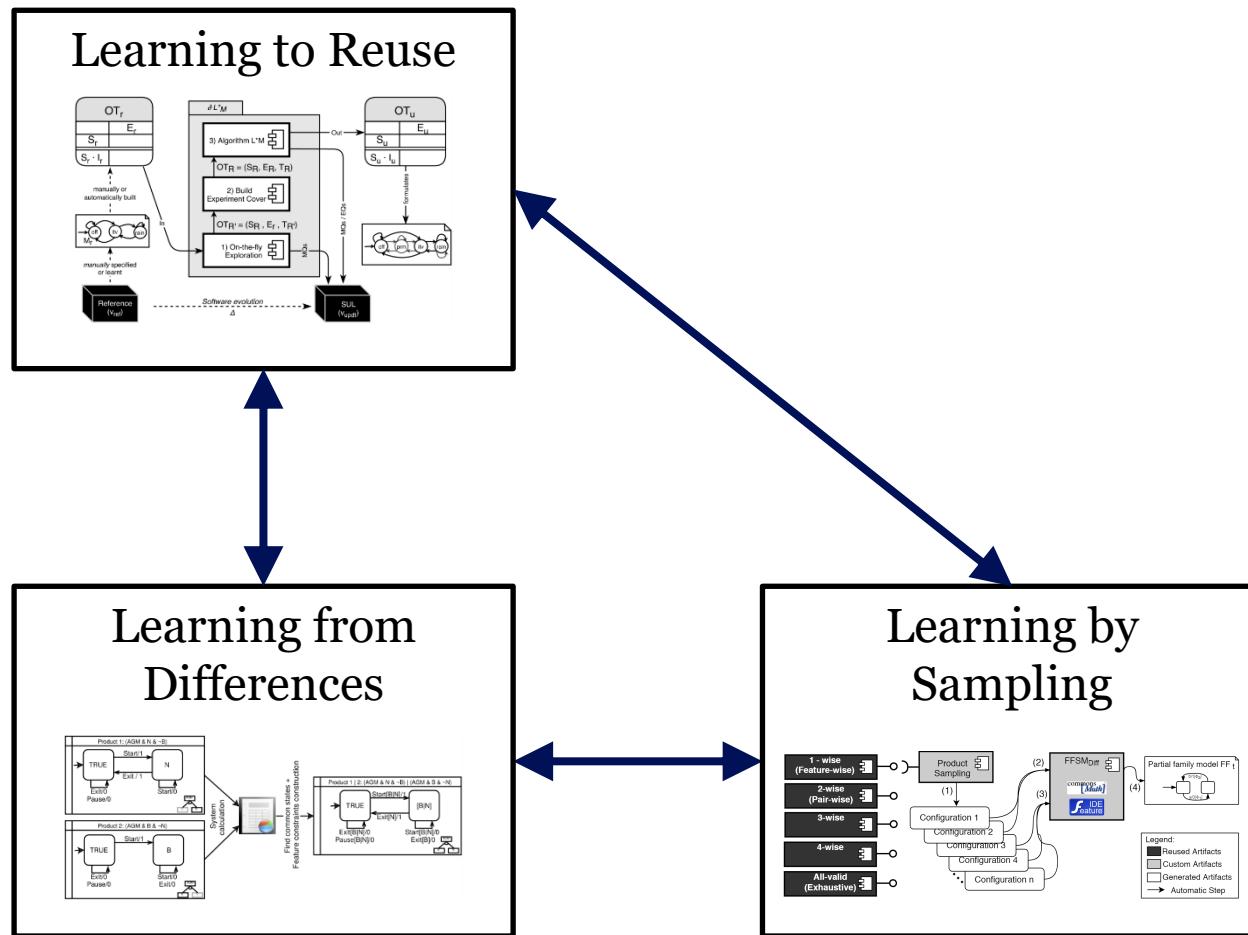


Source code and models should be maintained and evolve together!

Research Problem

How can we efficiently and effectively learn finite state machines specifying the behavior of an evolving system?

Research Objectives



Learning to Reuse

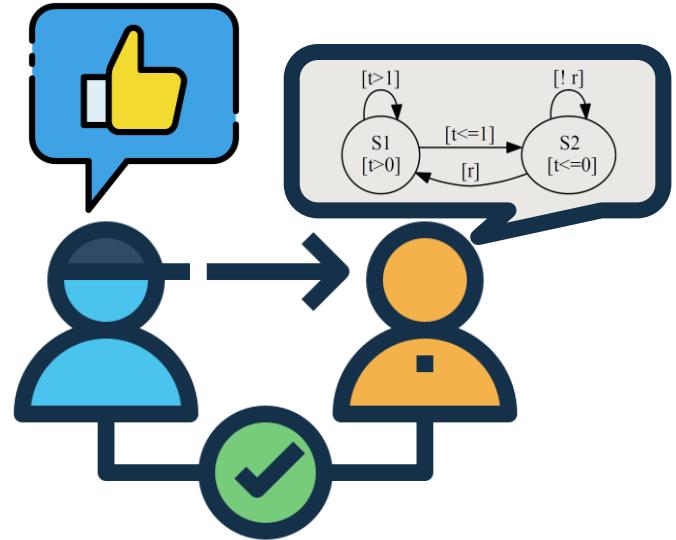
Adaptive Model Learning for Evolving Systems



Context (Learning to Reuse)

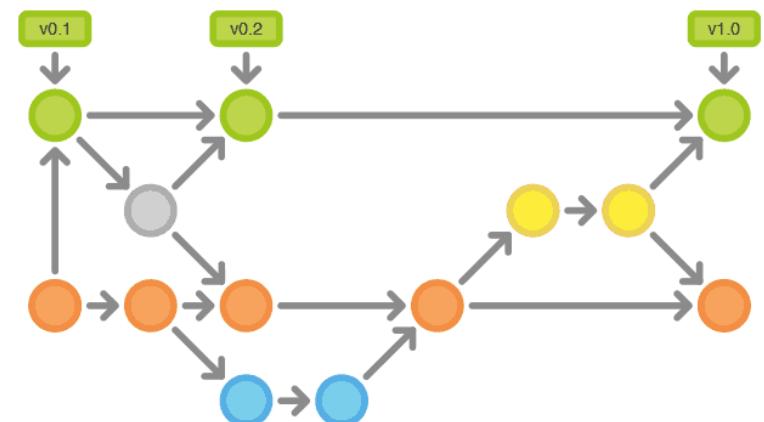
1. Software analysis is a *model-based* activity

- Models stuck to engineers' minds
- Formally denoted as explicit models

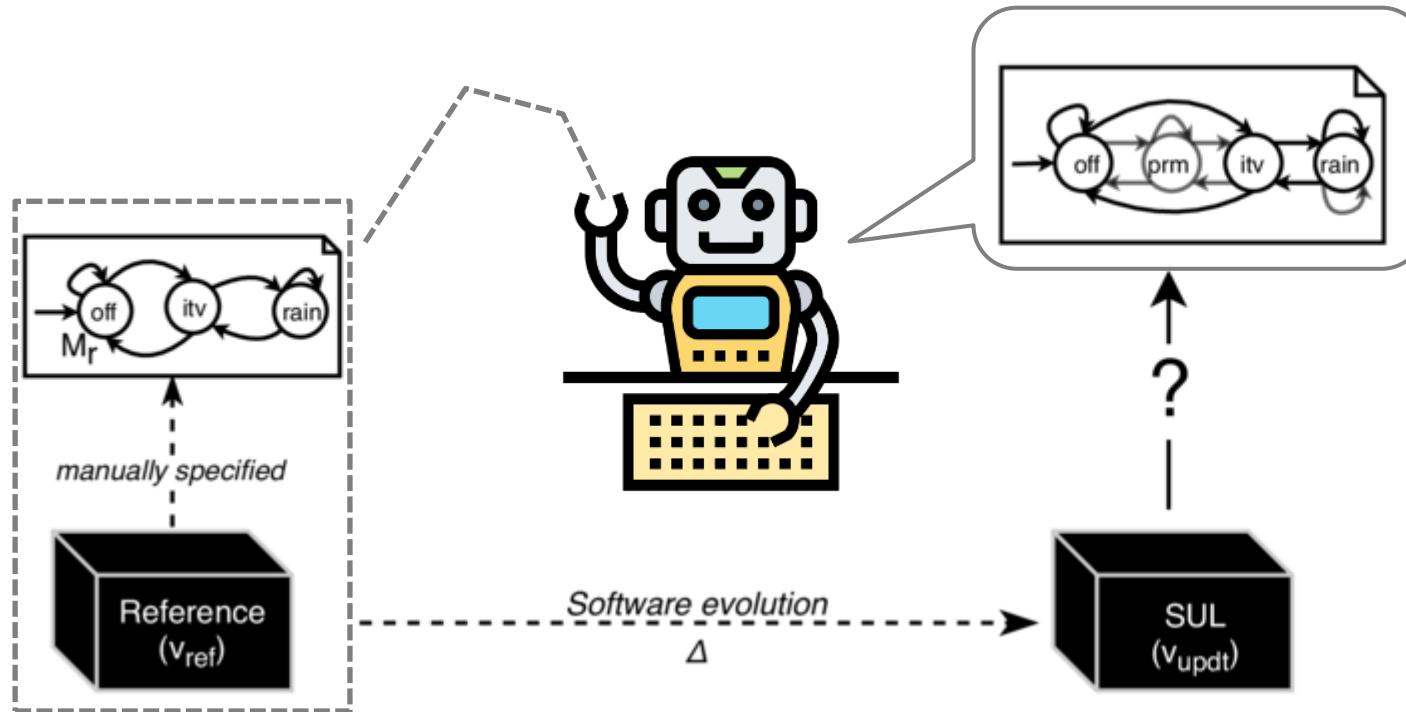


2. Software undergoes changes along the life-cycle

- Evolution over-time (e.g., update, upgrade)
- Models may become outdated

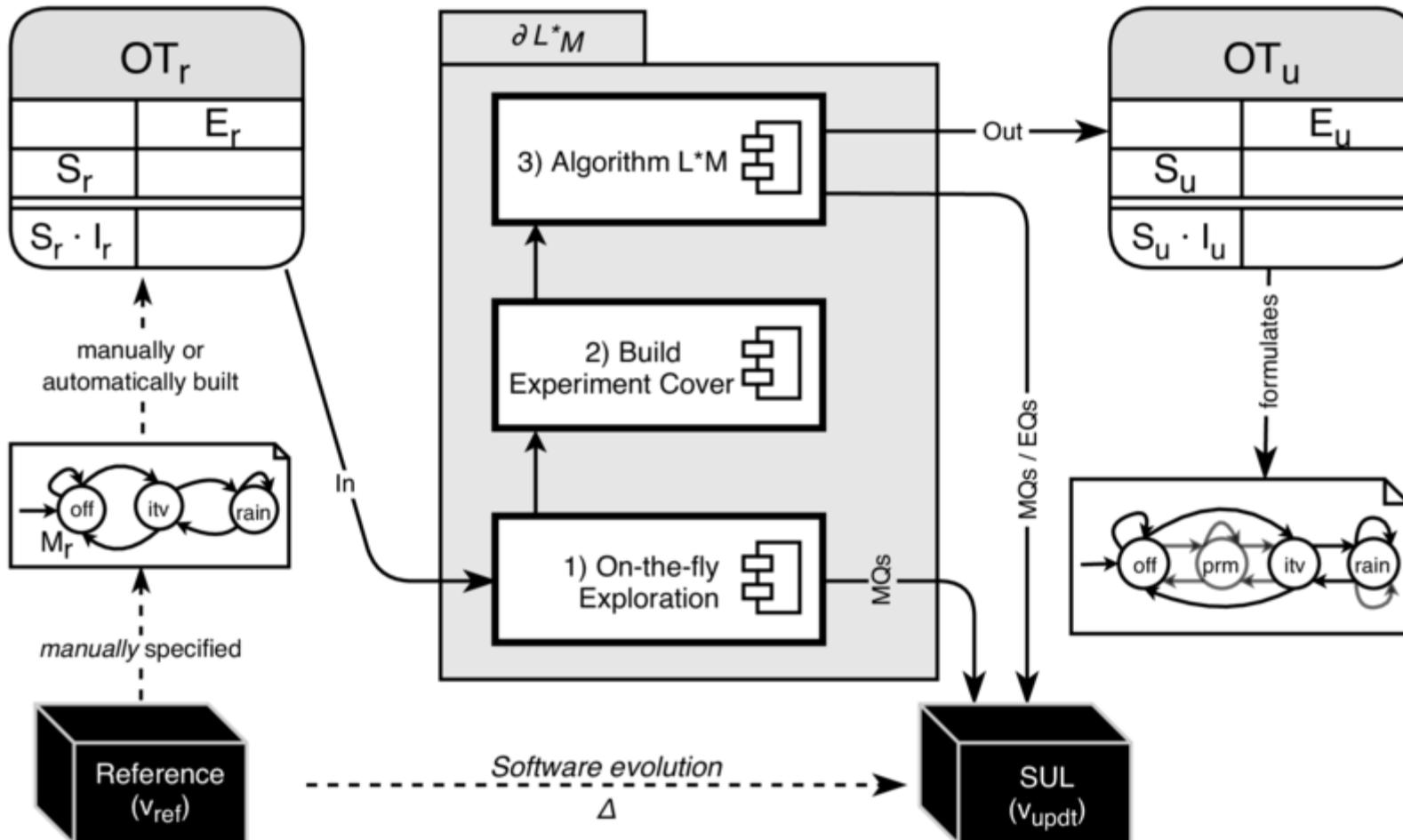


Research Problem (Learning to Reuse)



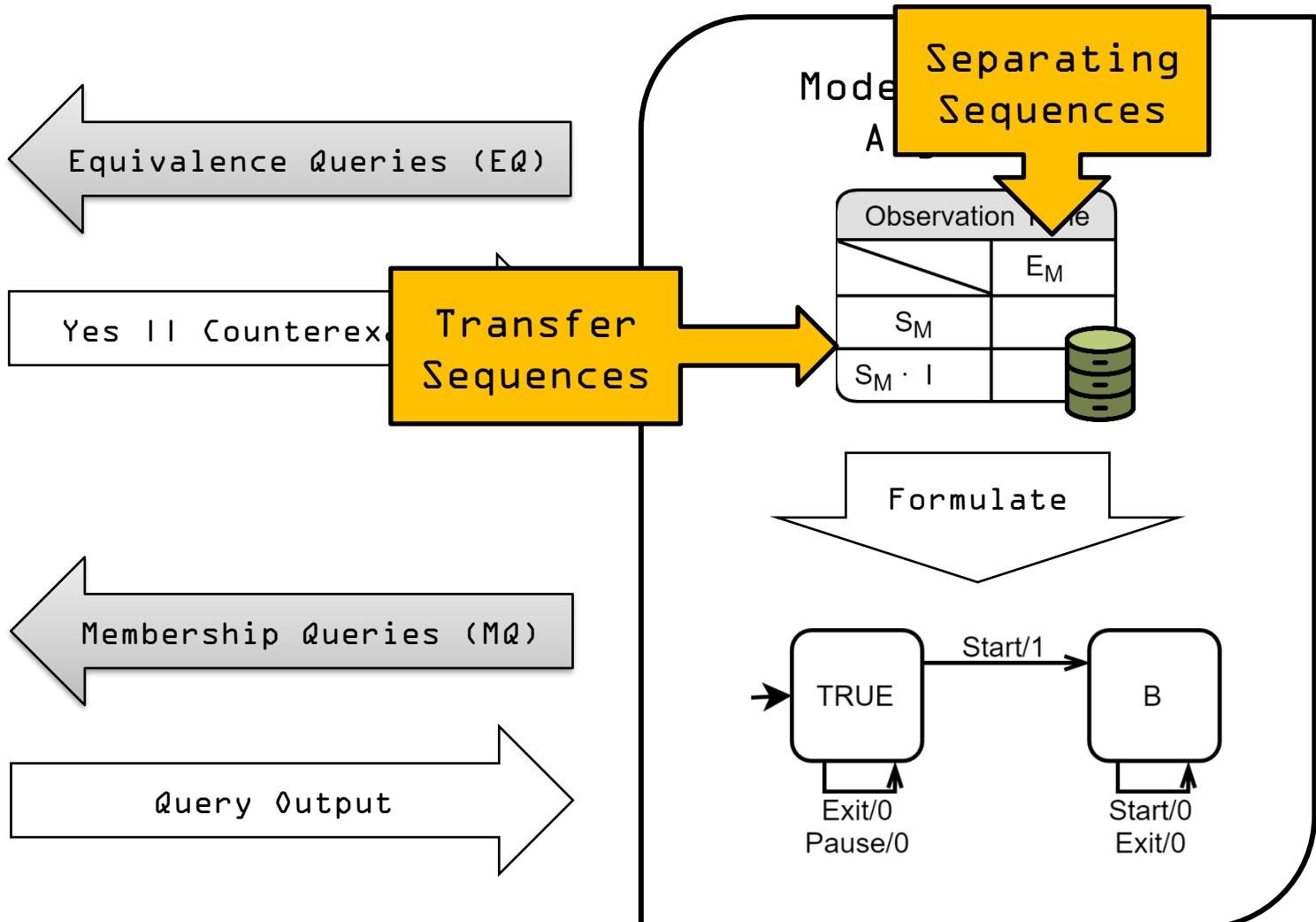
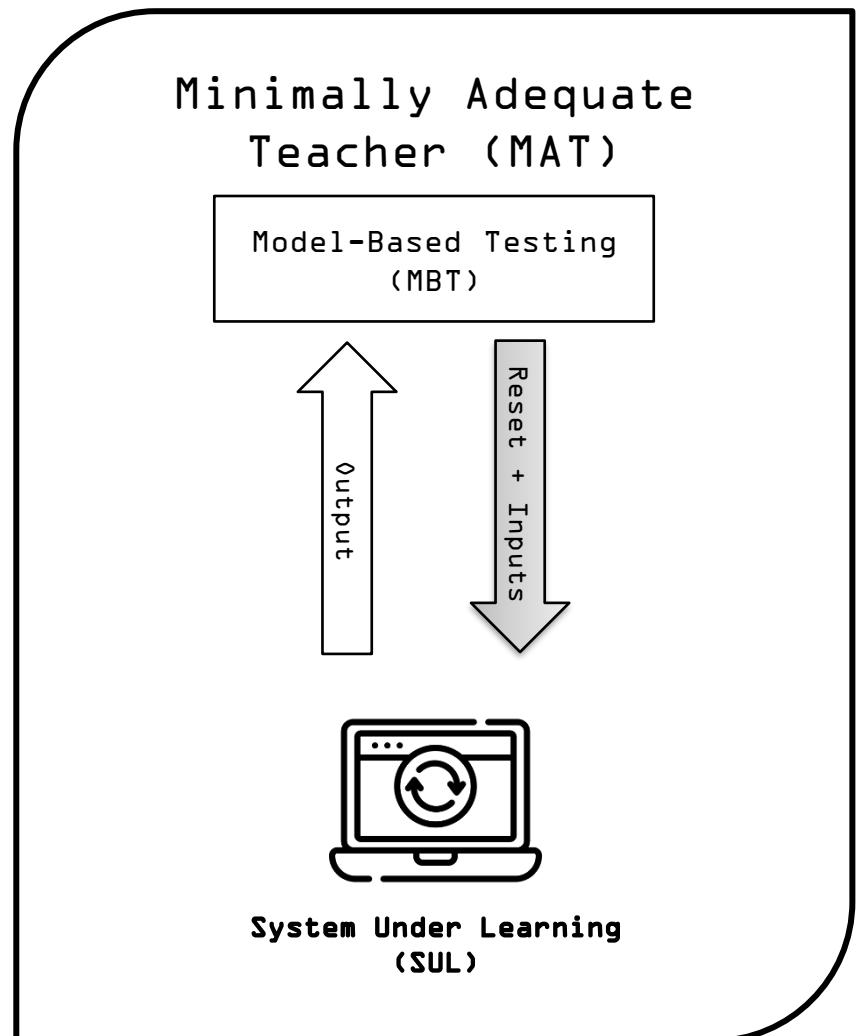
*How can we **efficiently** construct **behavioral models** from **evolving systems**?*

Contribution (Learning to Reuse)



An adaptive algorithm that is **more efficient** than the state-of-the-art for
learning behavioral models from **evolving systems**

Model Learning



System Under Learning

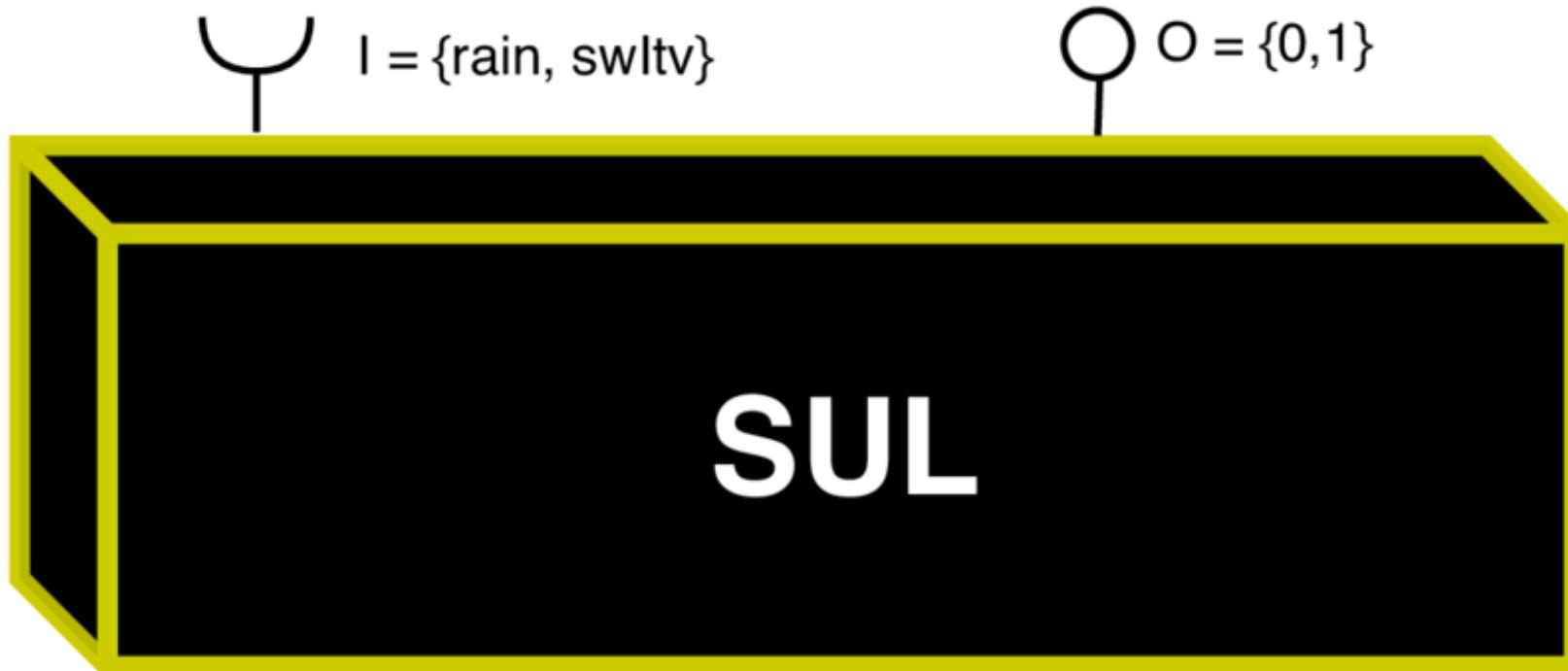


Figure: Windscreen wiper supporting intervalled and fast wiping

Model Learning

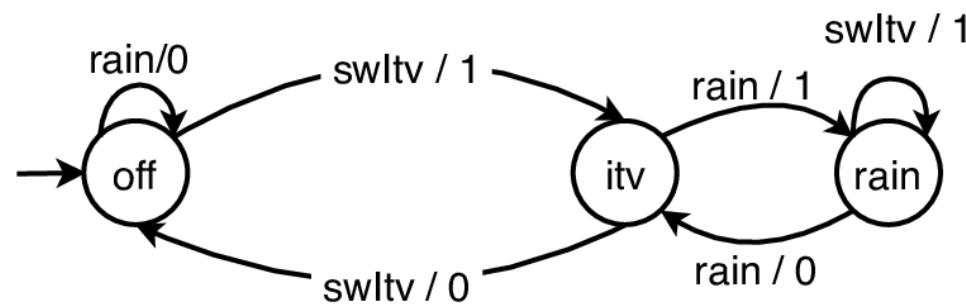


Figure: Final Hypothesis

		rain	swItv	rain · rain
S	ϵ	0	1	0 · 0
	swItv	1	0	1 · 0
	swItv · rain	0	1	0 · 1
S · I	rain	0	1	0 · 0
	swItv · swItv	0	1	0 · 0
	swItv · rain · rain	1	0	1 · 0
	swItv · rain · swItv	0	1	0 · 1

Table: Final OT

EQ = Yes

What if the SUL evolves?

Model Learning for Evolving Systems

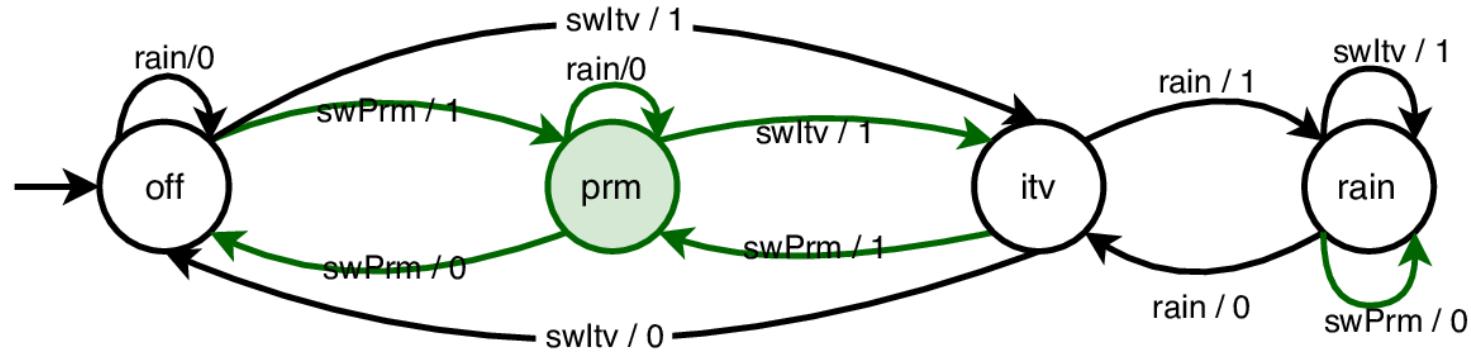
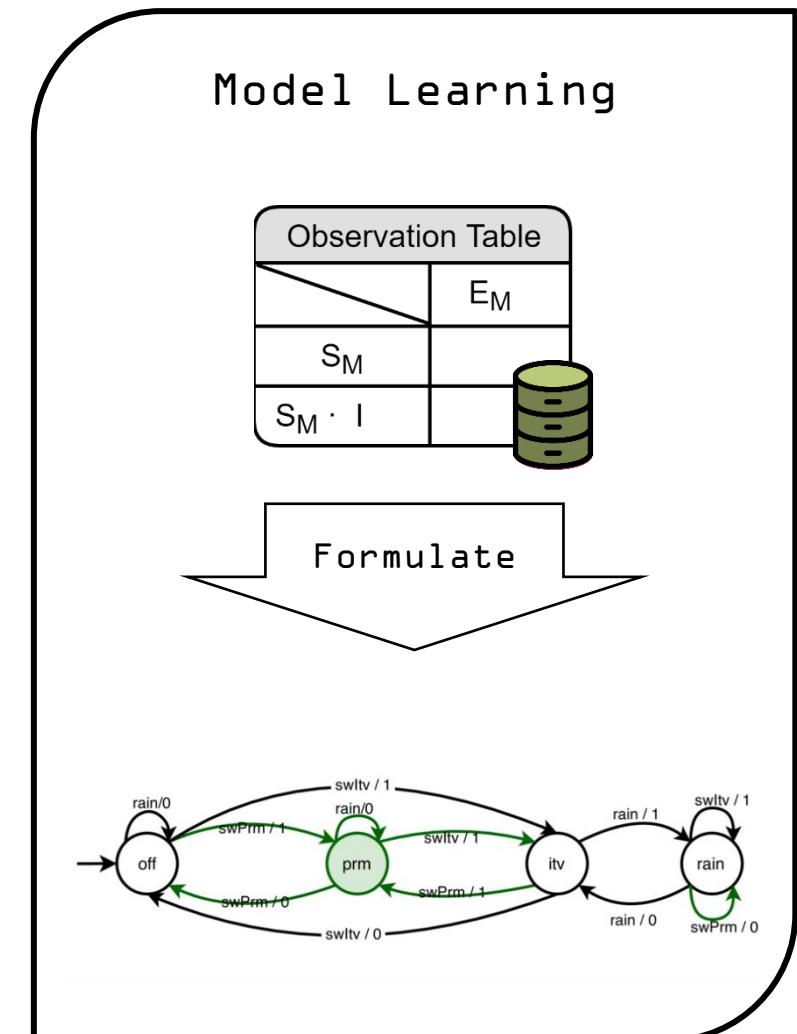
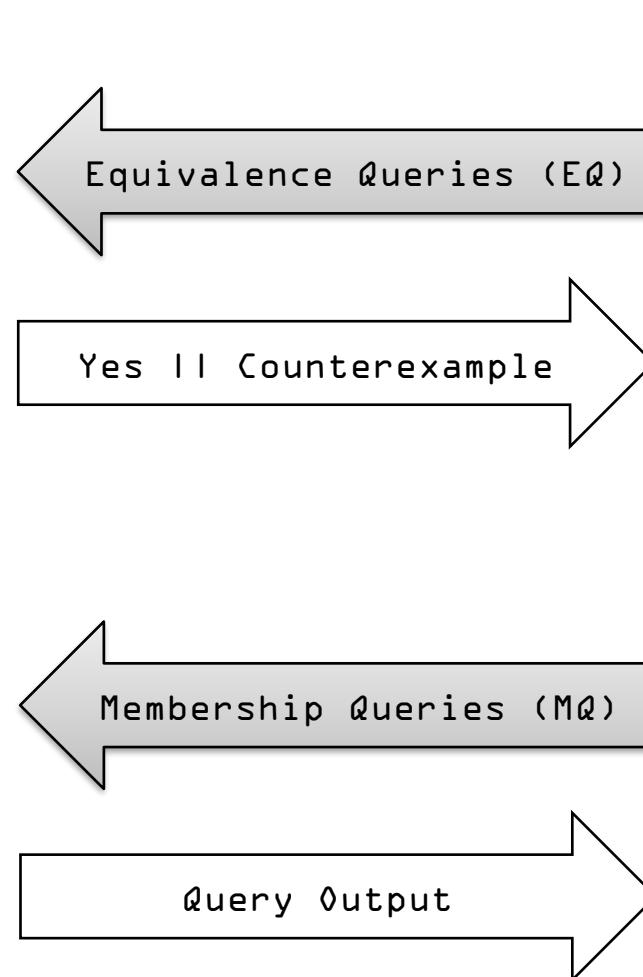
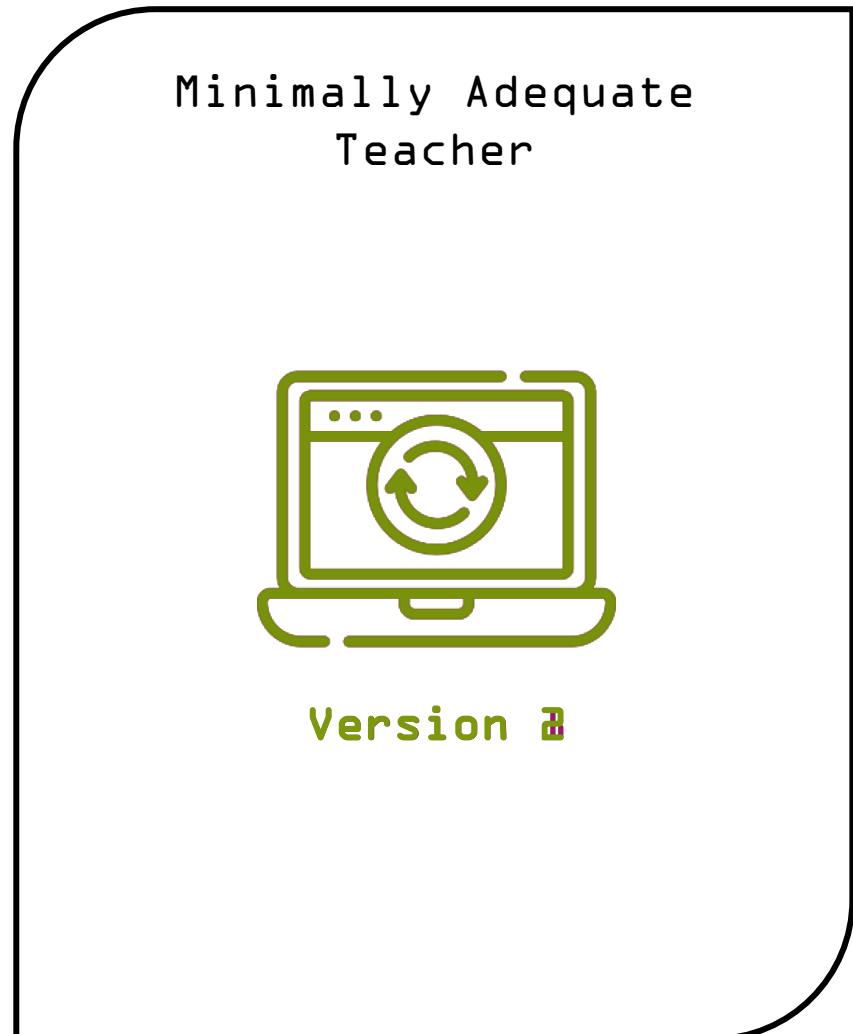


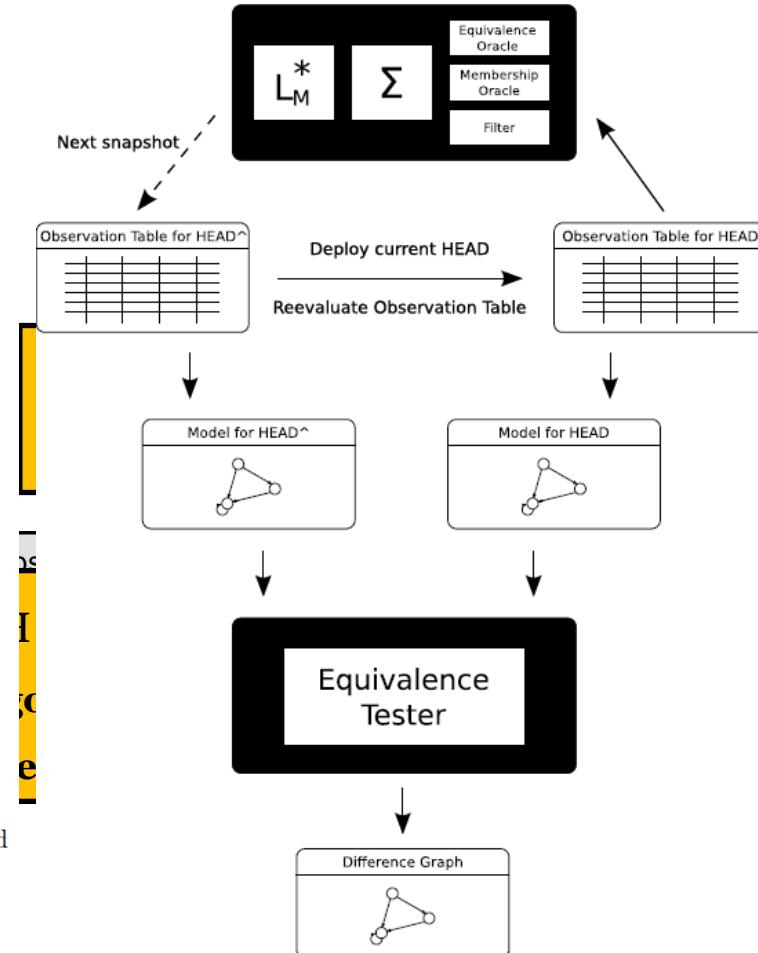
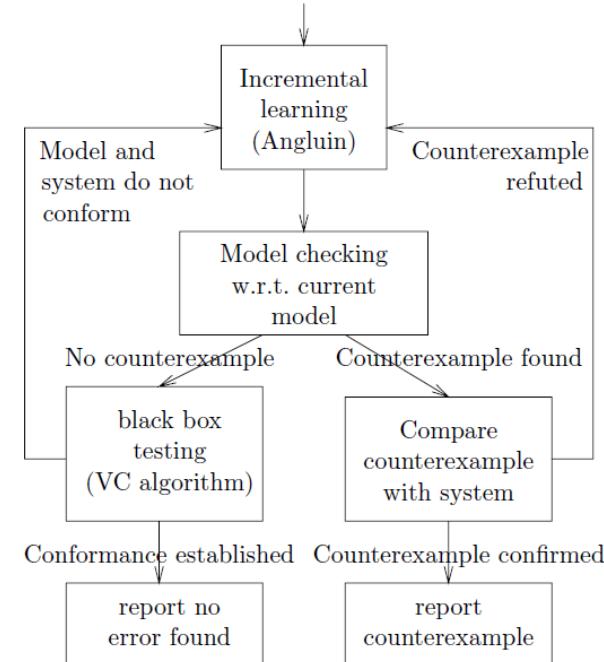
Figure: Windscreen wiper supporting intervalled and fast wiping + **permanent movement**

Model Learning for Evolving Systems

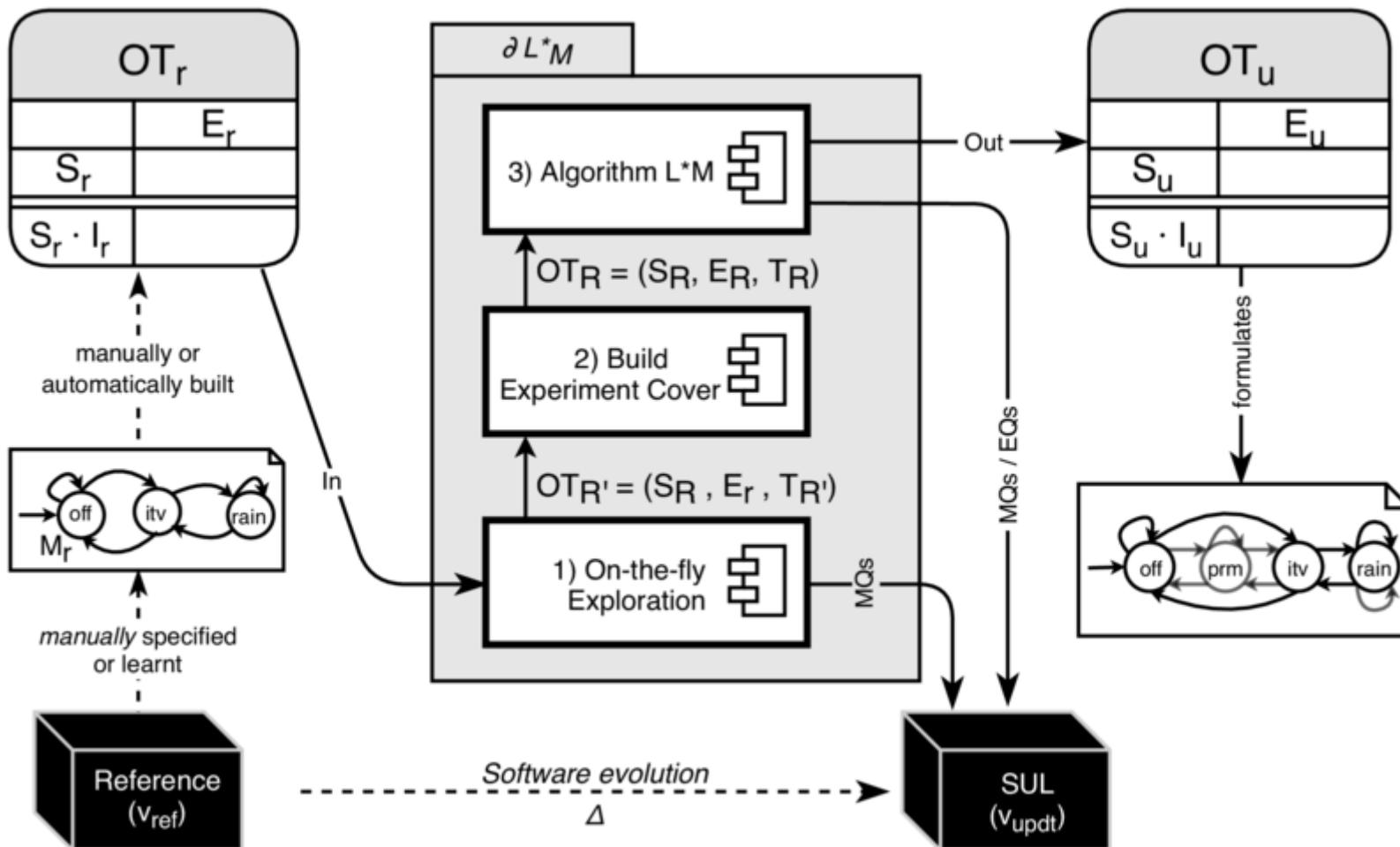


Adaptive Model Learning

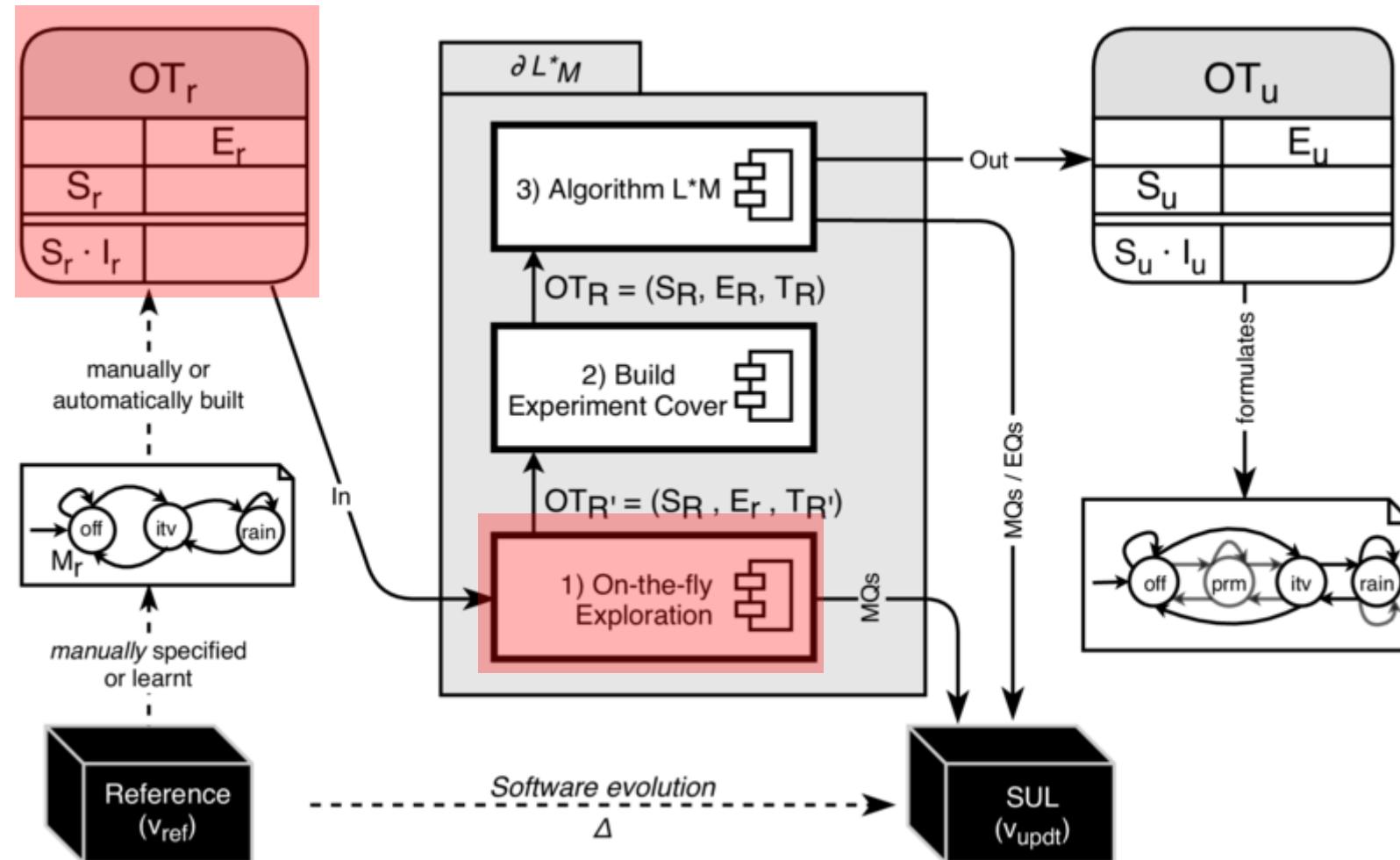
- **What:** Variant of model learning
- **How:** Reuse transfer/separating sequences from existing models
- **Why:** Speed up model learning
 - Find states maintained in newer versions
 - Reduce the time for model checking



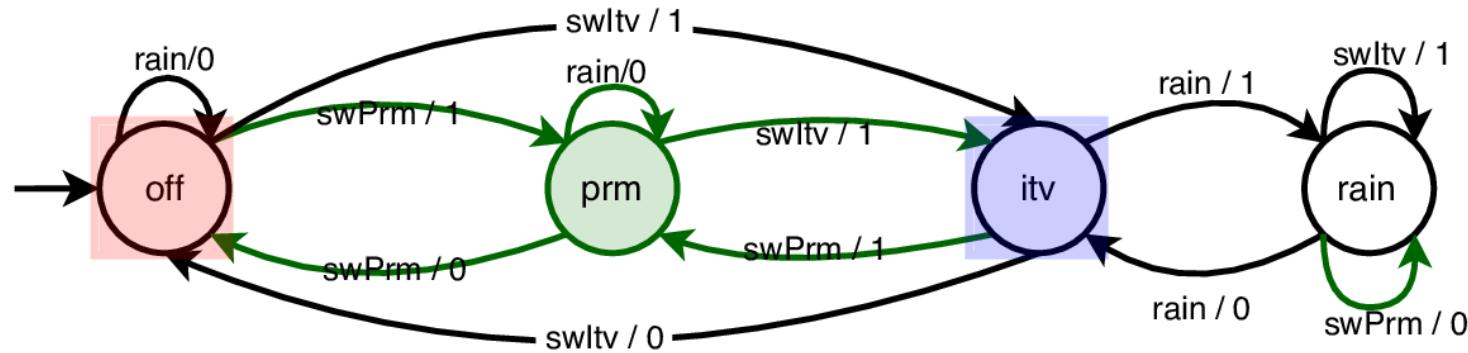
Partial-Dynamic $L^* M$ algorithm



1) On-the-fly exploration of the reused OT



1) On-the-fly exploration of the reused OT



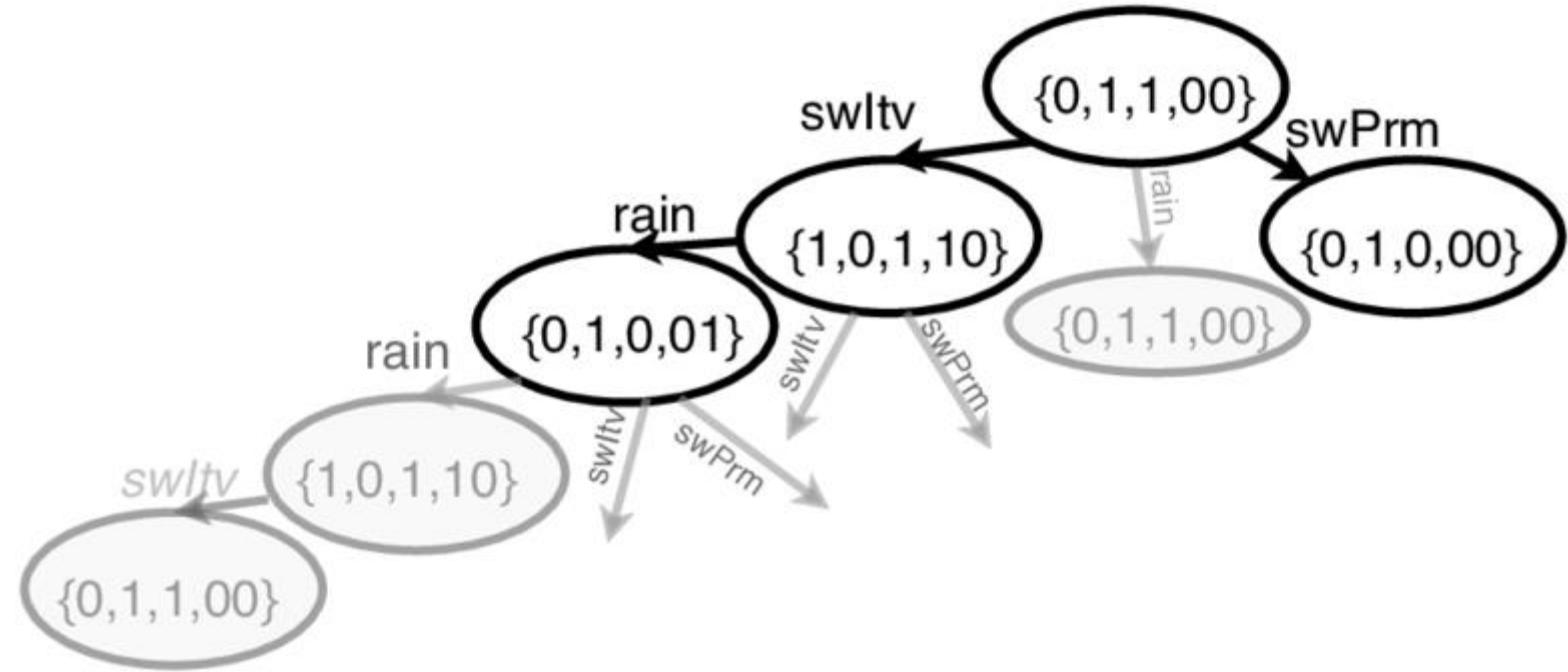
Let the sets of reused prefixes and suffixes be

$$S_r = \{ \epsilon, \text{swltv}, \text{swltv} \cdot \text{rain}, \text{swltv} \cdot \text{rain} \cdot \text{rain}, \text{swltv} \cdot \text{rain} \cdot \text{rain} \cdot \text{swltv}, \text{rain} \}$$

$$E_r = \{ \text{rain}, \text{swltv}, \text{swPrm}, \text{rain} \cdot \text{rain} \}$$

Goal: Find a $S_R \subseteq S_r$ with the same state coverage capability but less prefixes

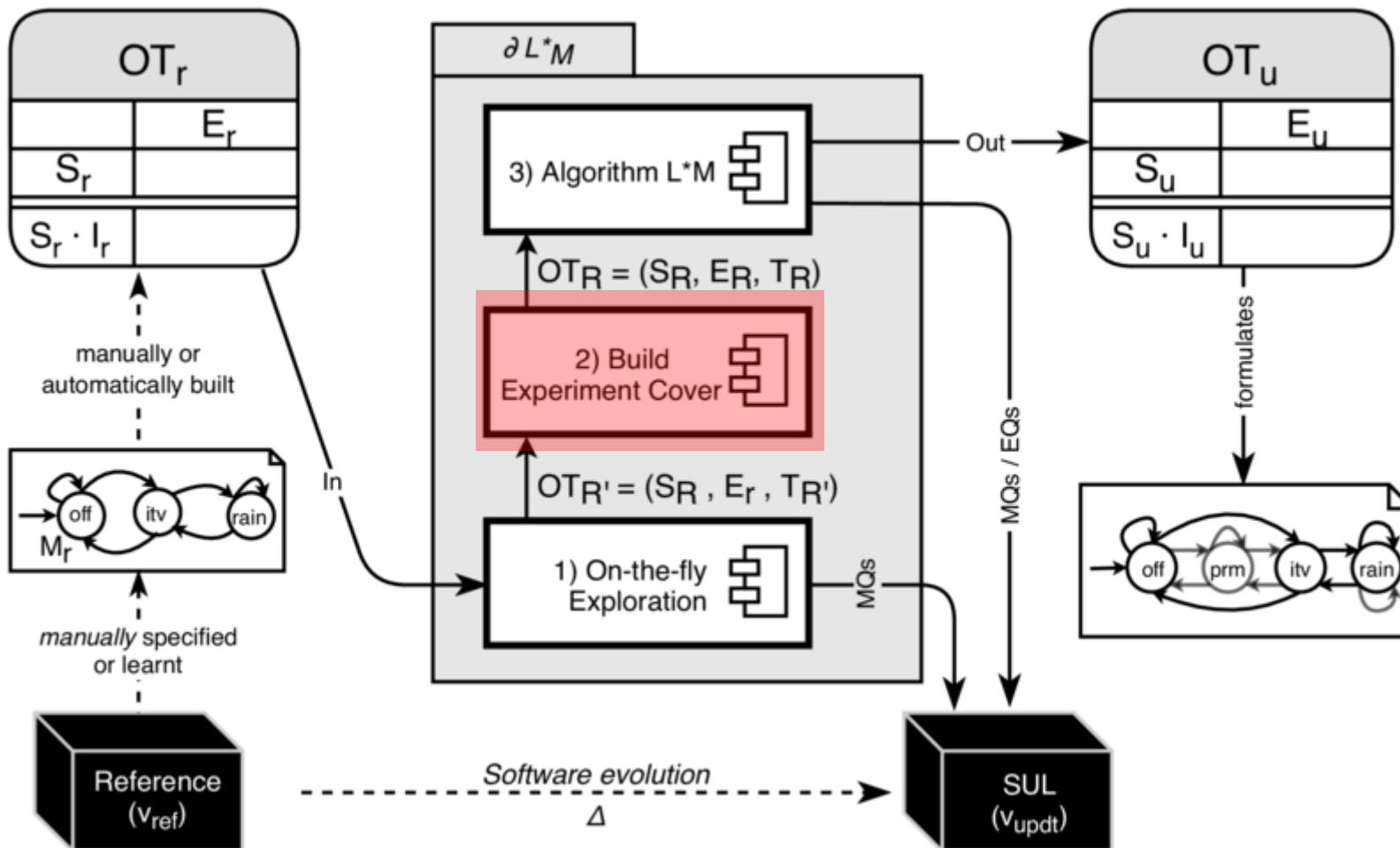
1) On-the-fly exploration of the reused OT



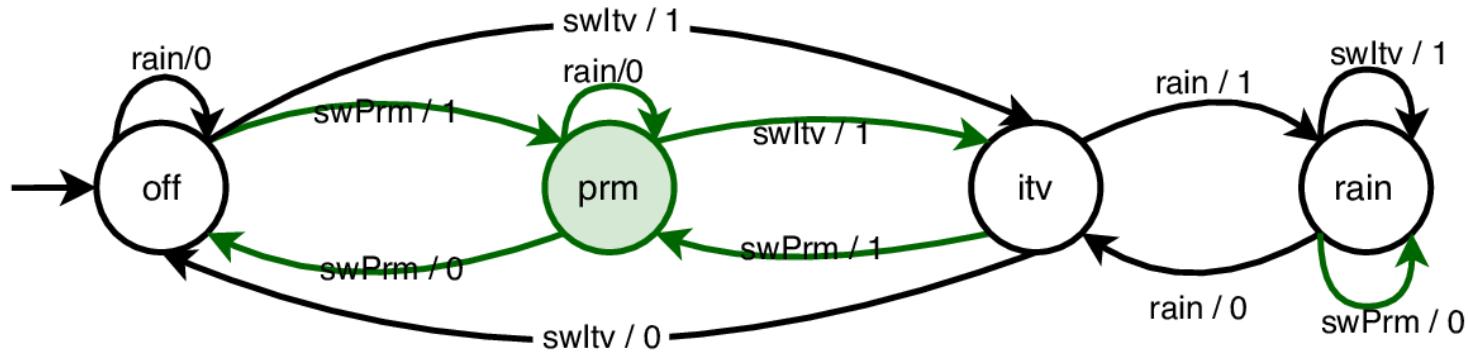
On-the-fly exploration of the tree representation of the set of transfer sequences

* On-the-fly: We alternate between the tree traversal steps and MQs

2) Build the experiment cover tree



2) Build the experiment cover tree



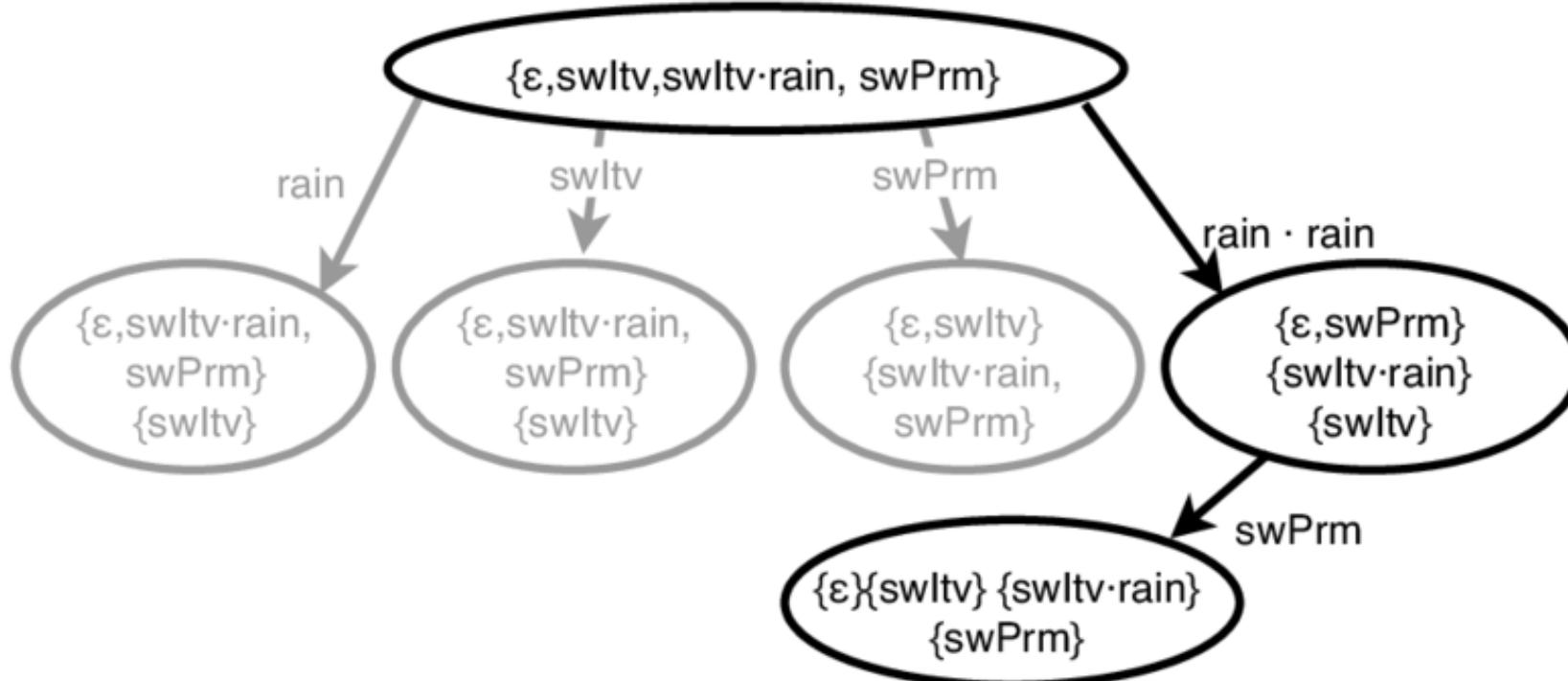
Let the sets of prefixes and suffixes be

$$S_R = \{ \epsilon, swltv, swltv \cdot rain, swPrm \}$$

$$E_r = \{ rain, swltv, swPrm, rain \cdot rain \}$$

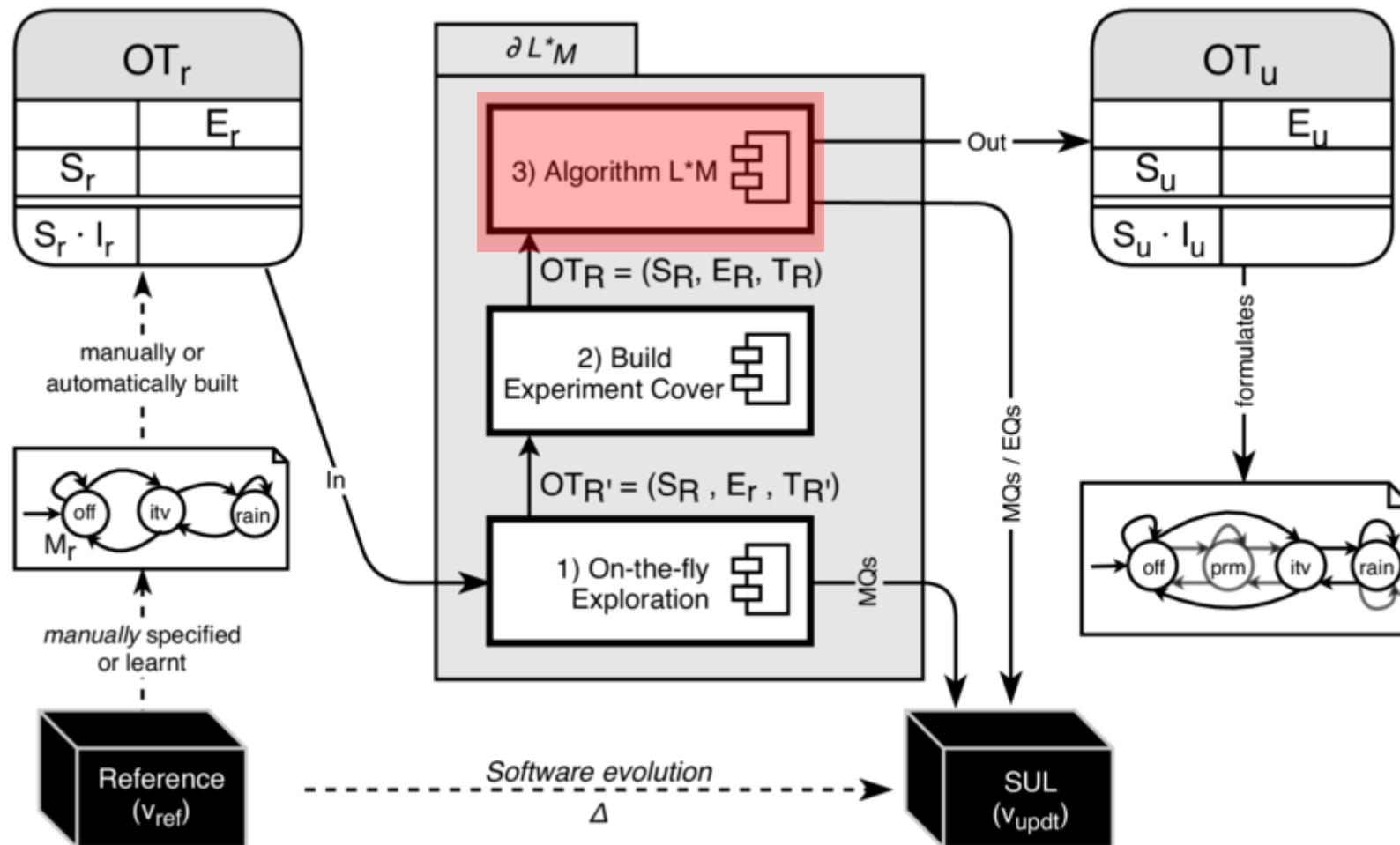
Goal: Find a **smaller subset** $E_R \subseteq E_r$ of **representative** separating sequences.

2) Build the experiment cover tree



Group transfer sequences into equivalence classes to find a smaller subset of separating sequences

3) Starting L^*_M using the outcomes of ∂L^*_M



Empirical Evaluation

Empirical Evaluation (Research Questions)

RQ1) Is our technique more efficient than the state-of-the-art of adaptive learning?

RQ2) Is the effectiveness of adaptive learning strongly affected by the temporal distance between versions?



D. Huijstra, J. Meijer, and J. van de Pol, 'Adaptive Learning for Learn-Based Regression Testing', in Formal Methods for Industrial Critical Systems, 2018

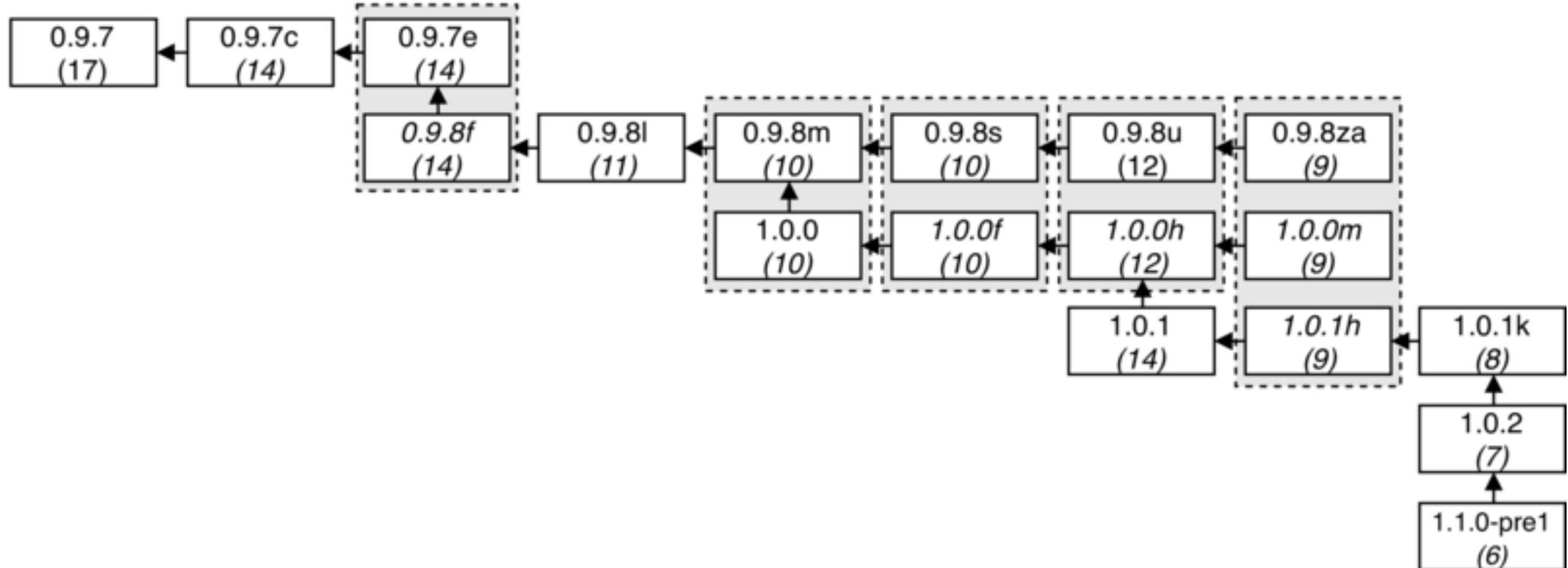
S. Windmüller, J. Neubauer, B. Steffen, F. Howar, and O. Bauer, 'Active Continuous Quality Control', in Proceedings of the CBSE 2013

A. Groce, D. Peled, and M. Yannakakis, 'Adaptive Model Checking', in Proceedings of the TACAS 2002

J. de Ruiter, 'A Tale of the OpenSSL State Machine: A Large-Scale Black-Box Analysis', in Secure IT Systems, vol. 10014, B. B. Brumley and J. Röning, Eds. Cham: Springer, 2016,

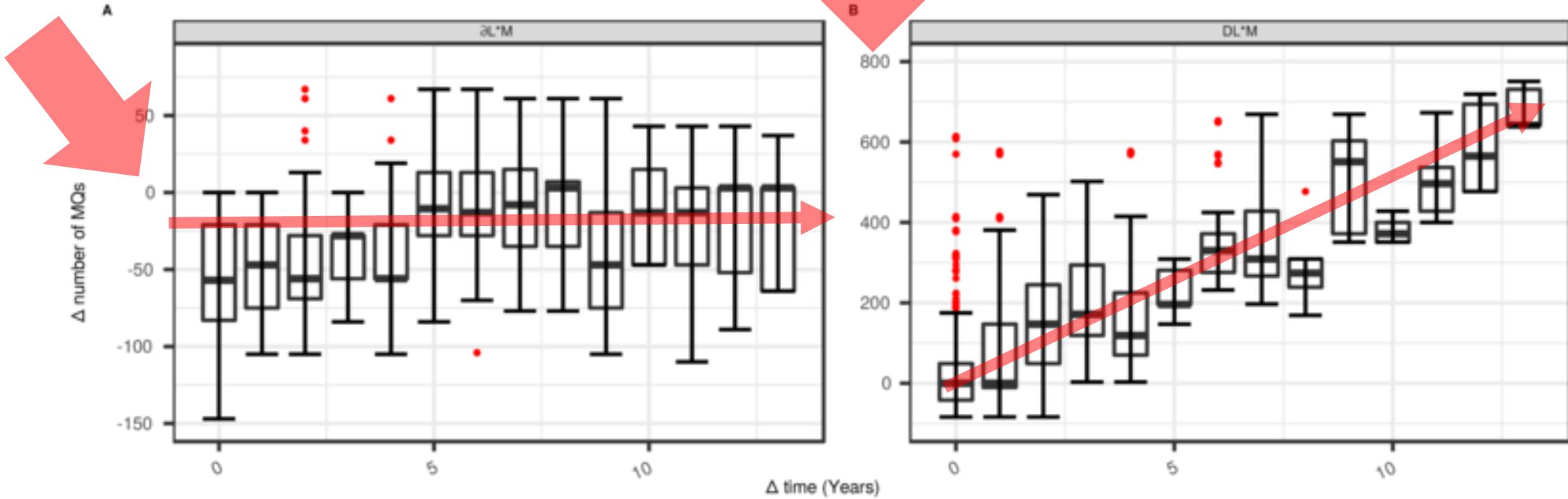
M. Isberner, F. Howar, and B. Steffen, 'The Open-Source LearnLib', in CAV 2015

Subject Systems



Subject systems: 18 state machines describing versions of the OpenSSL toolkit

Analysis of Results (Average number of MQs)



The temporal distance between few in MQs did not affect the performance of the algorithm

Summary (Learning to Reuse)



The state-of-the-art adaptive learning algorithms...

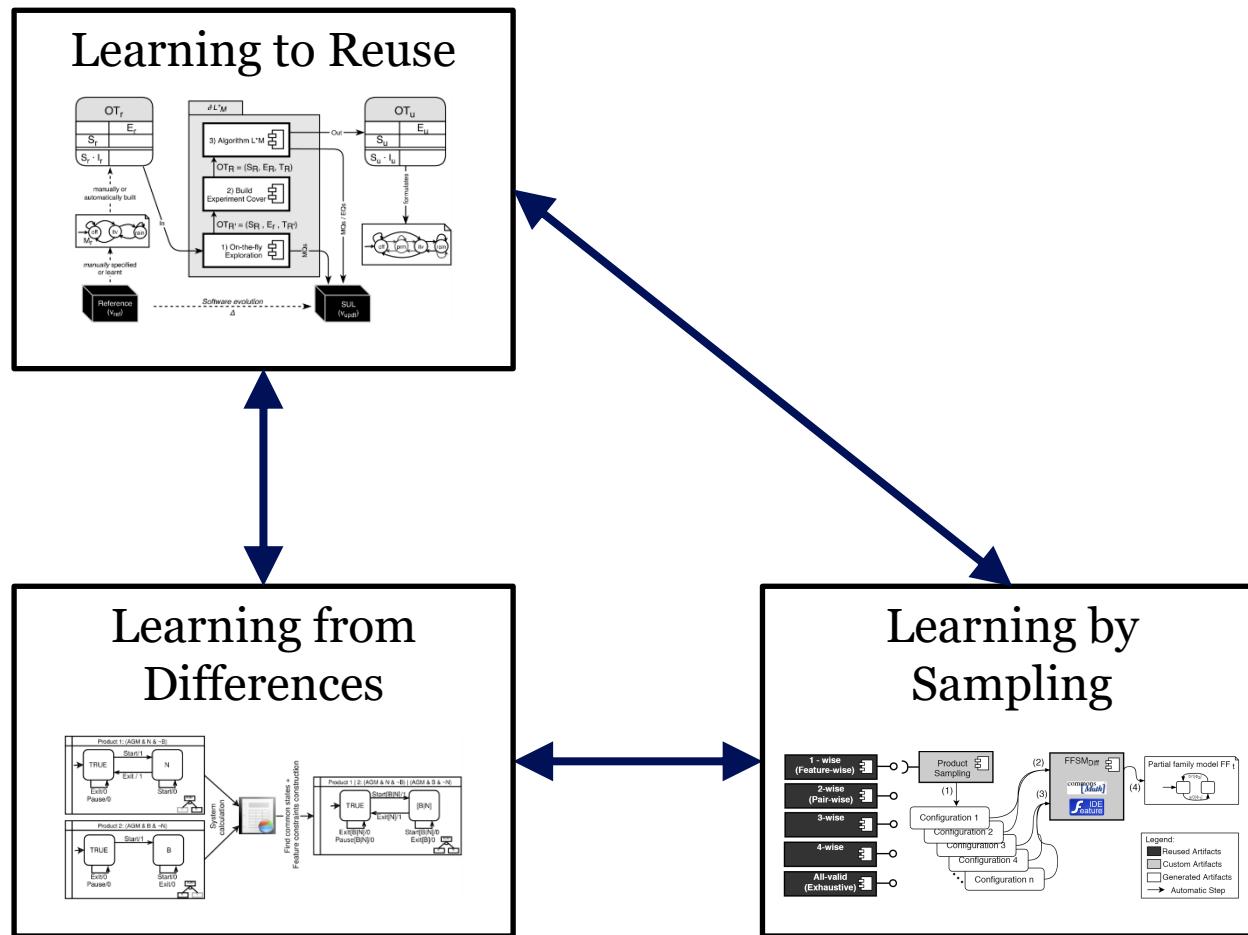
1. More sensitive to software evolution!

The ∂L^*_M algorithm ...



2. Required fewer MQs than the other techniques
3. Temporal distance did not affect its performance

Research Objectives



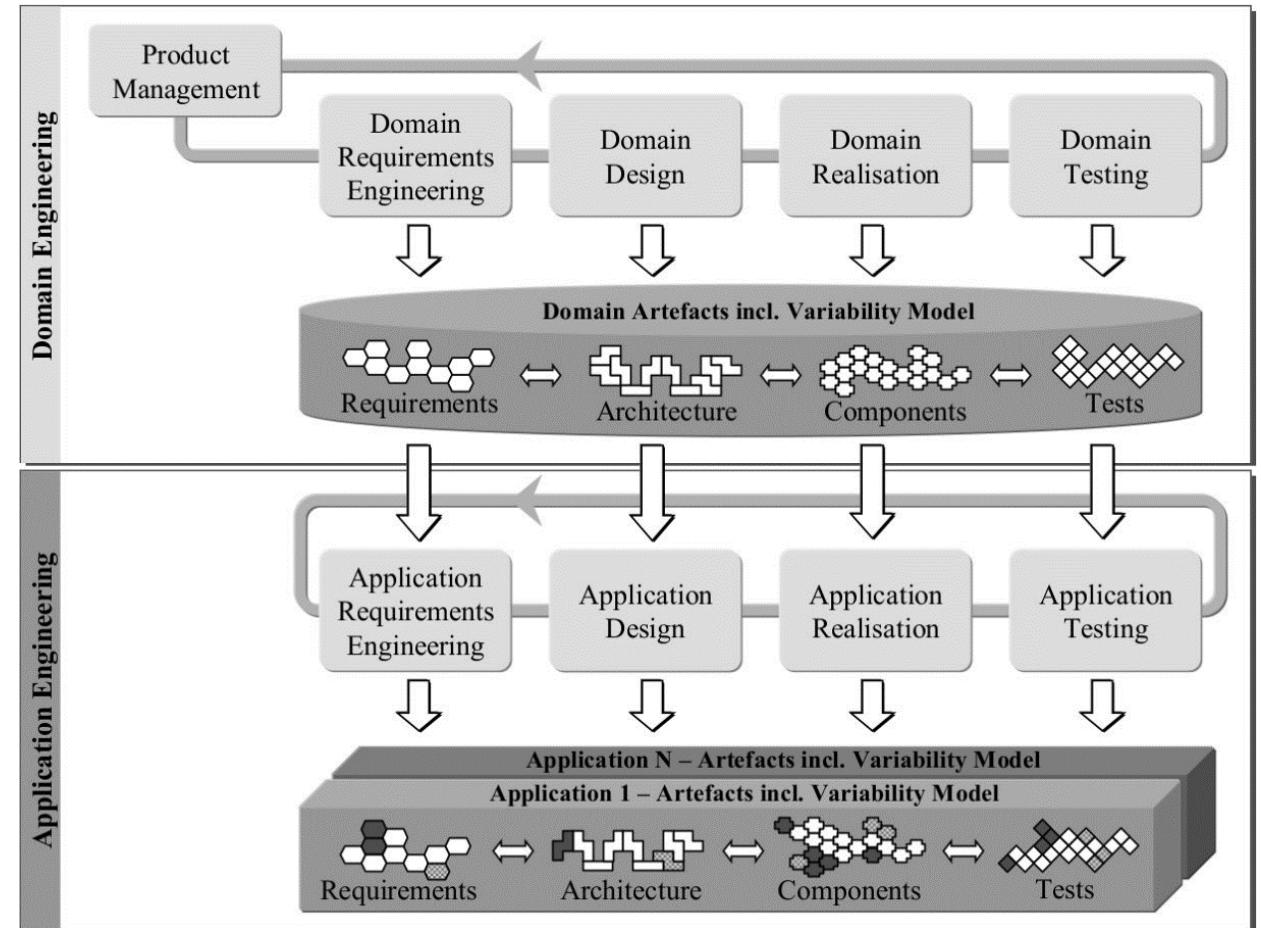
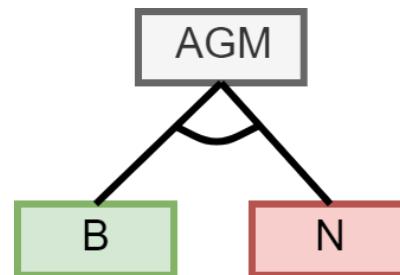
Learning from Difference

An Automated Approach for Learning Family Models from Software Product Lines



Context (Learning from Difference)

- Software product lines (SPL)
 - Variability *in space* (e.g., feature model)
 - Common set of reusable assets
 - Product configurations

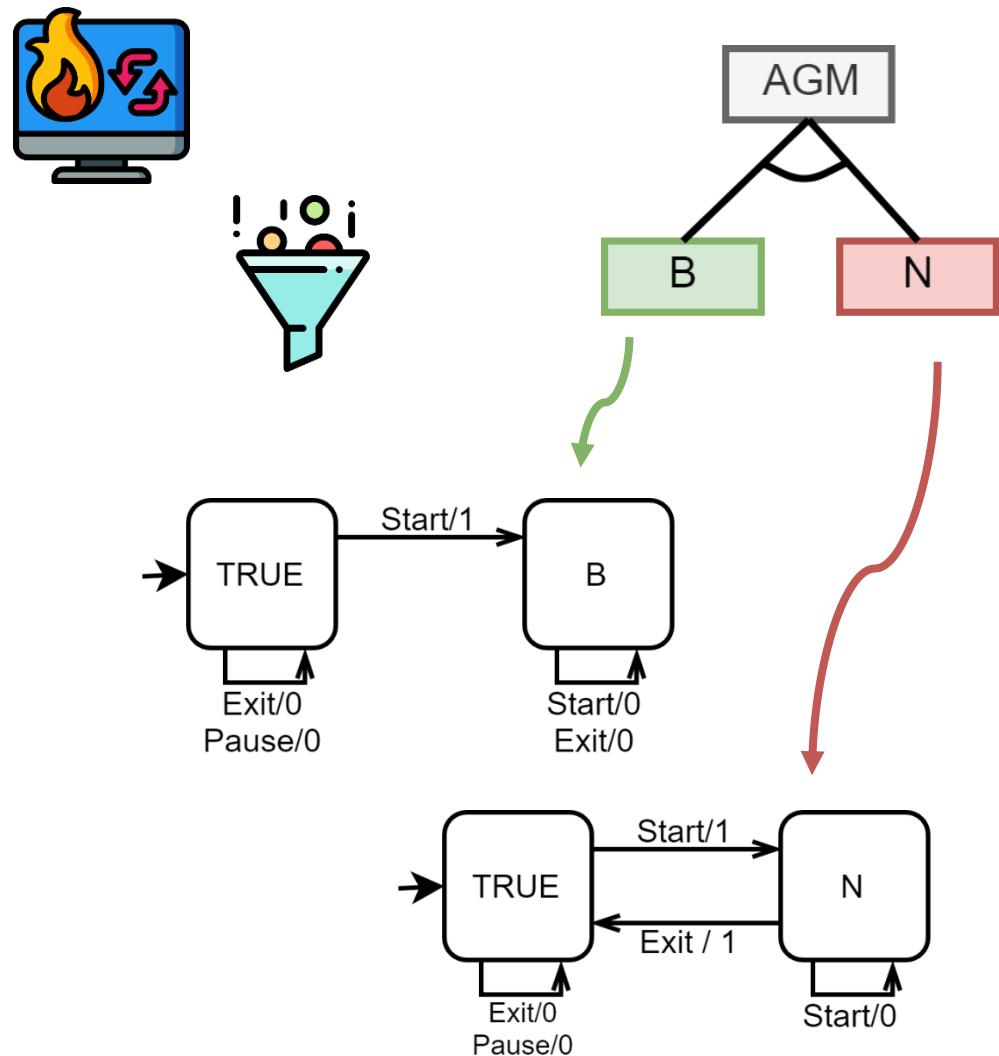


Context (Learning from Difference)

- Analysis and modeling of SPLs
 - Product-based strategies
 - Traditional MBT + Individual product specifications
 - E.g., exhaustive analysis, configuration sampling

ISSUES

- Redundant analysis
- Scalability (e.g., exponential)
- Feature interaction problem (e.g., T-wise)

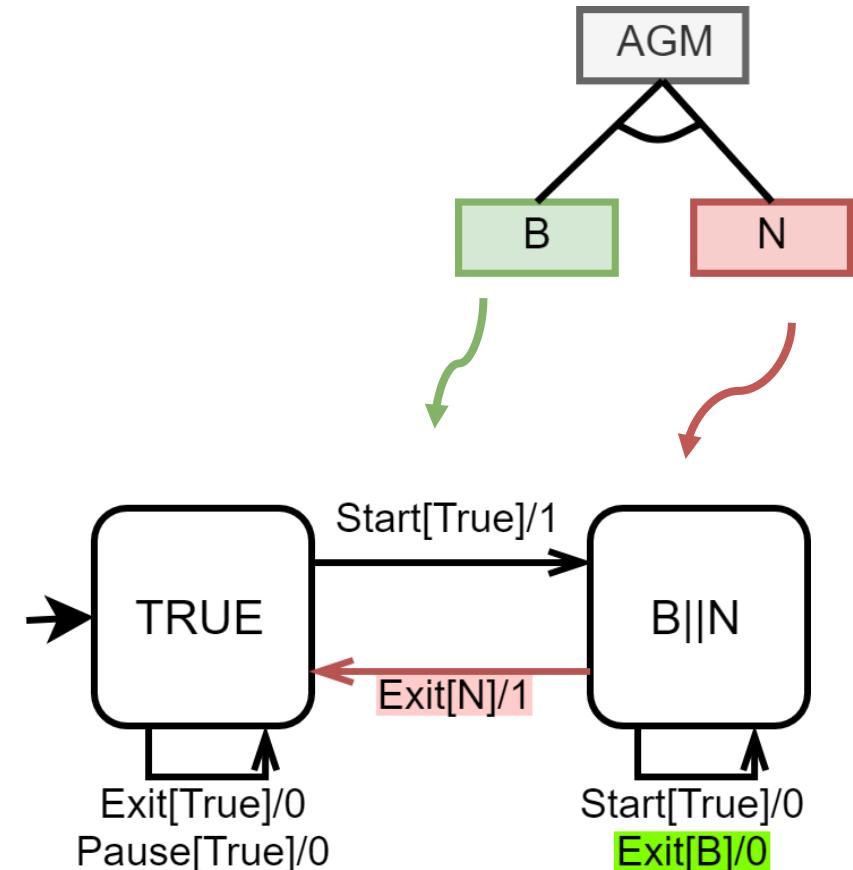


Context (Learning from Difference)

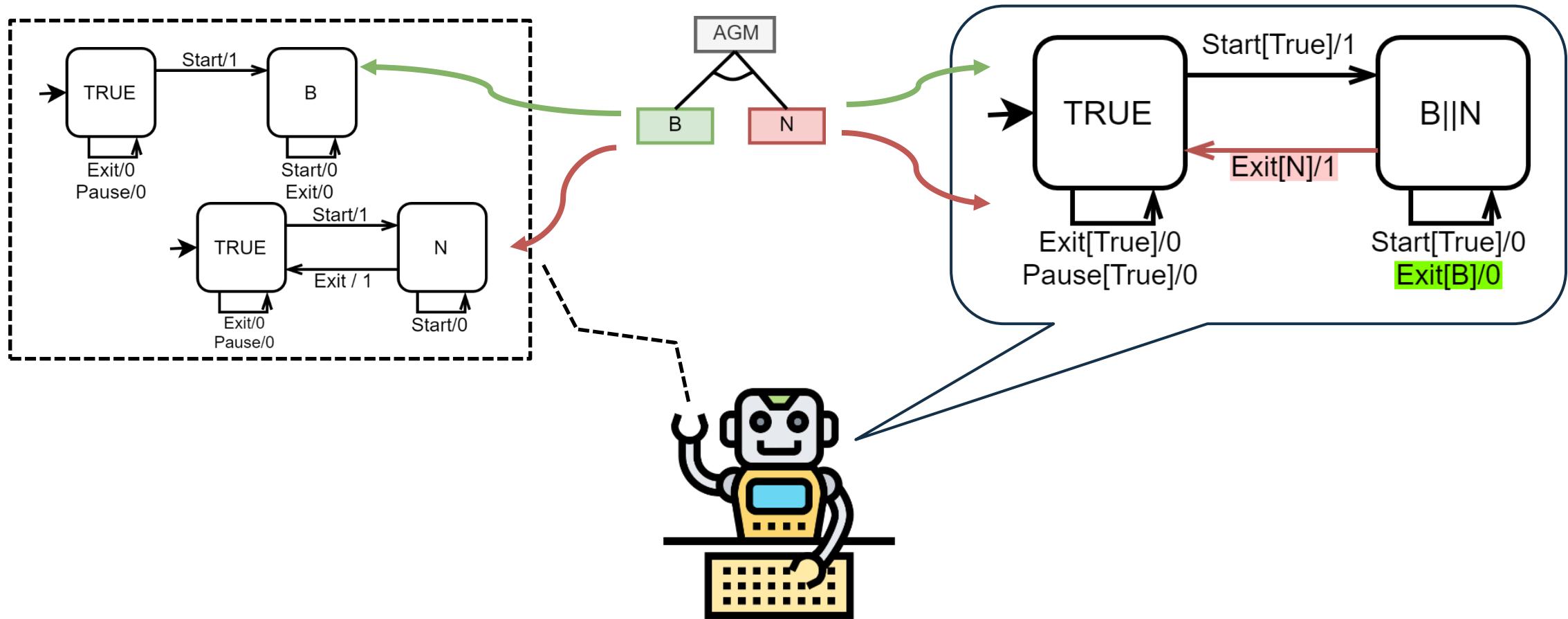
- Analysis and modeling of SPLs
 - Family-based strategies
 - Corner-stone of efficient model-based SPL analysis
 - Family models (e.g., Featured Finite State Machine - FFSM)

ISSUES

- Model maintenance and evolution
- Traceability vs. Crosscutting features
- Commonalities/variabilities are often unknown

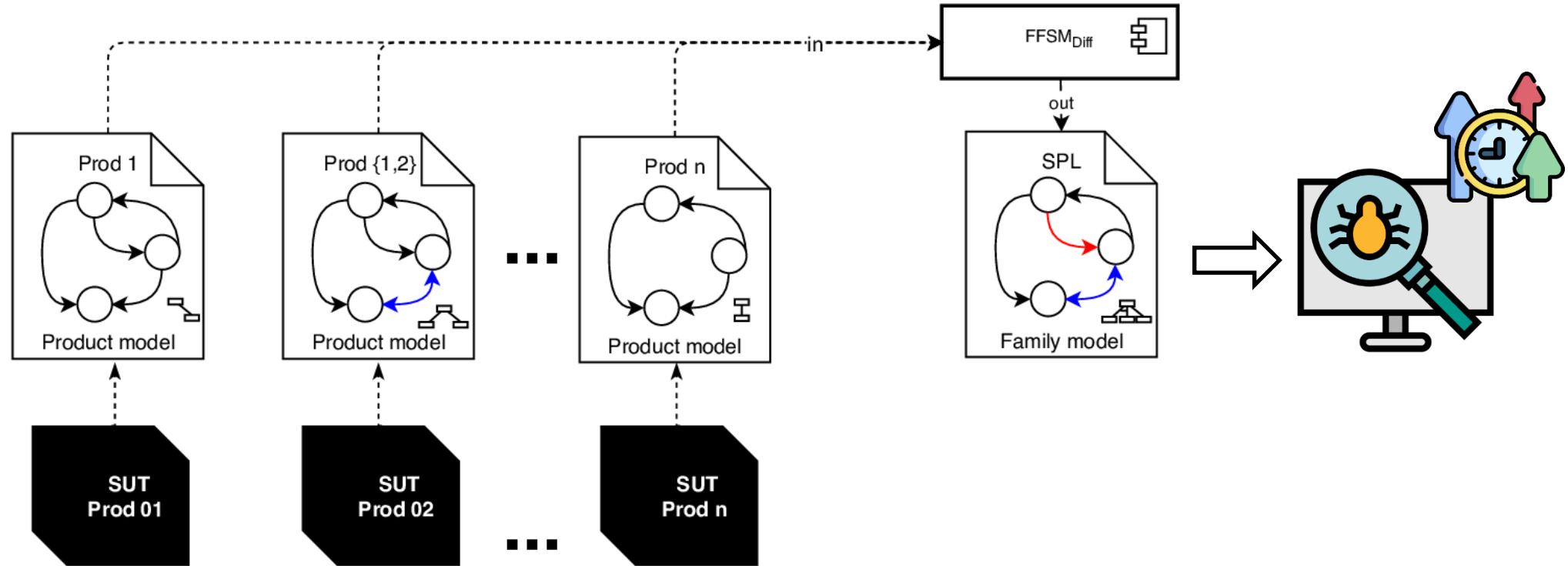


Research Problem (Learning from Difference)



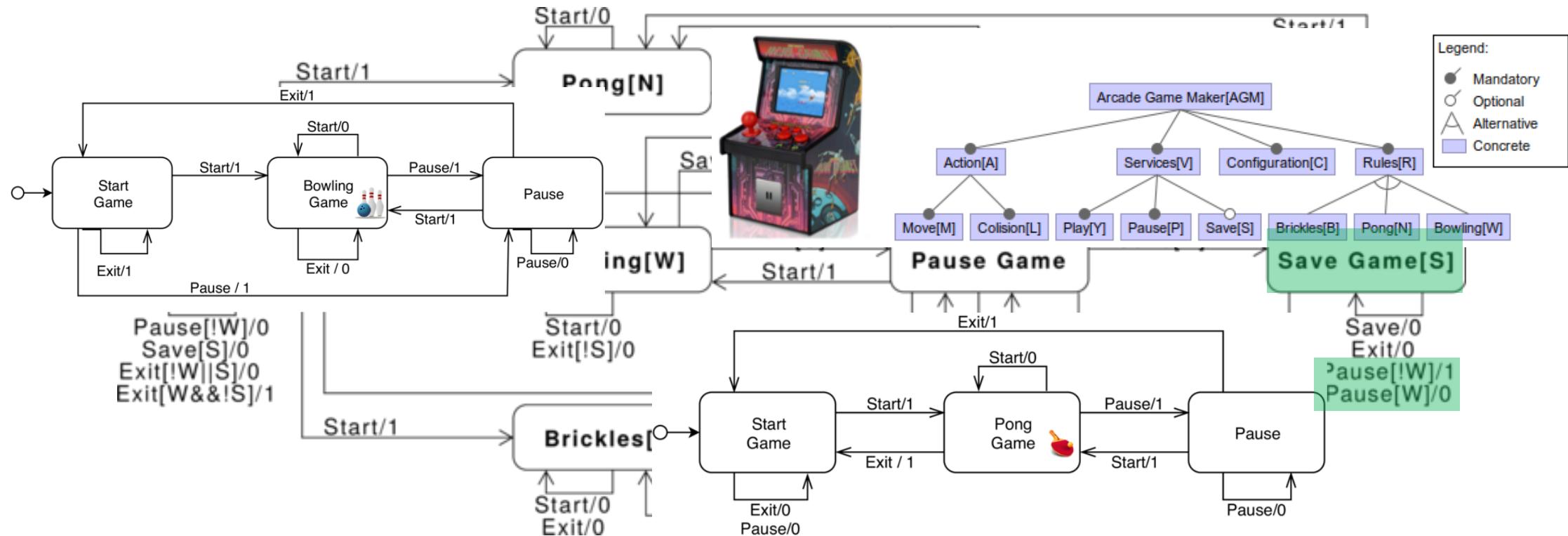
How can we **leverage** the concept of **model learning** to the task of **behavioral variability modeling**?

Contribution (Learning from Difference)



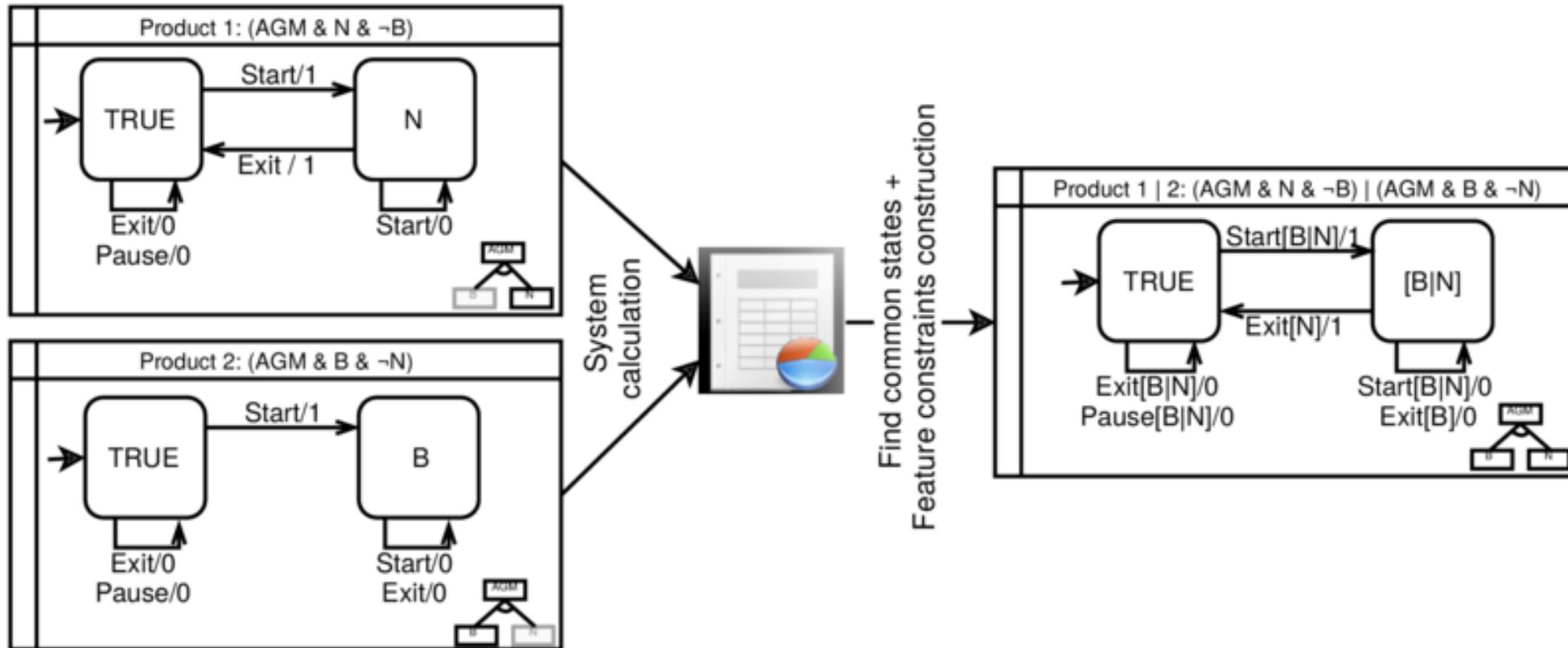
The FFSM Difference (FFSM_{Diff}) algorithm for **learning succinct family models** from individual product specifications of **software product lines**

Featured Finite State Machines (FFSM)



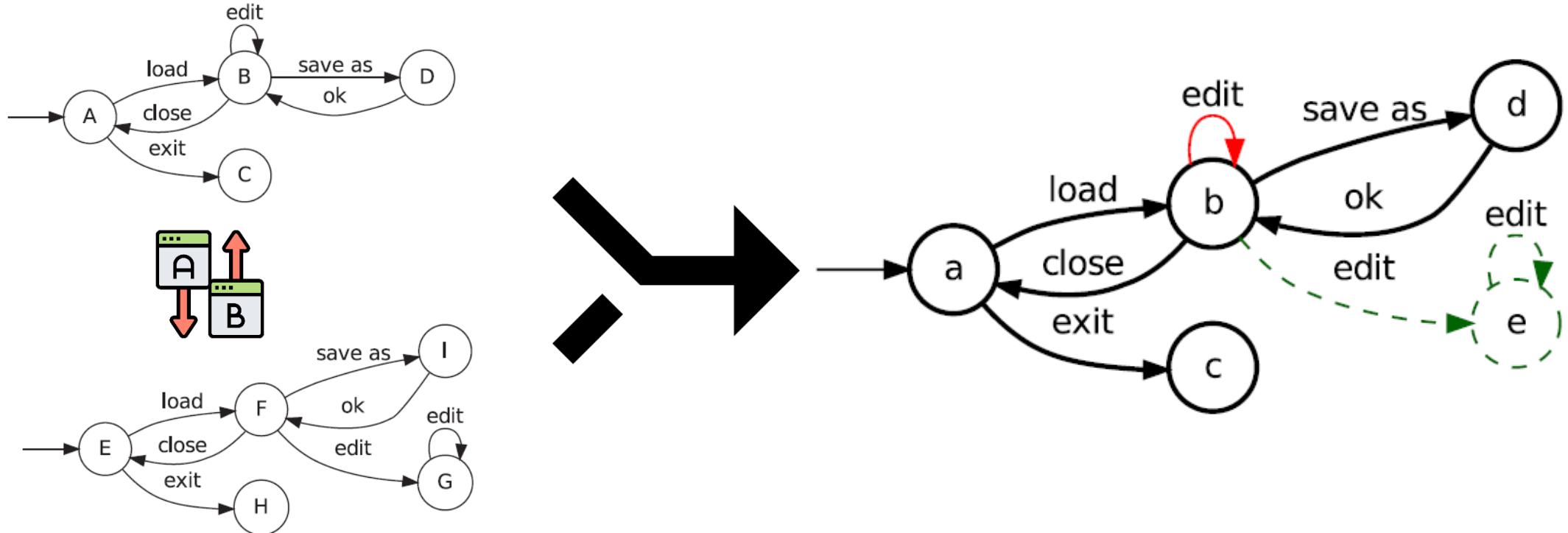
An FFSM is a family-based representation of a product-line that unifies product-specific Mealy machines and captures the functionality of features and their interactions in terms of conditional states/transitions

FFSM Difference (FFSM_{Diff})



The FFSM_{Diff} can learn FFSMs from a product models by employing state-based model comparison and express product-specific behaviors with feature constraints using feature model analysis

State-based model comparison (LTS_{Diff} algorithm)



Comparing the Structures of Two State Machines of a Text Editor

State-based model comparison (LTS_{Diff} algorithm)

$$S_{Succ}^G(a, b) = \frac{1}{2} \frac{\sum_{(c,d,i,o) \in Succ_{a,b}} (1 + k \times S_{Succ}^G(c, d))}{|\sum_r^{out}(a) - \sum_u^{out}(b)| + |\sum_r^{out}(b) - \sum_u^{out}(a)| + |Succ_{a,b}|}$$

Figure: Global similarity score ⁴

Global similarity score (Outgoing and incoming transitions)

- Pairwise similarity based on surrounding matching transitions and connected state pairs.
- Attenuation ratio k gives precedence to the closest state pairs.
- Matching transitions and **distinct transitions**.

State-based model comparison (LTS_{Diff} algorithm)

Pair	(St,St)	(St,Po)	(St,Pa)	(Bo,St)	(Bo,Po)	(Bo,Pa)	(Pa,St)	(Pa,Po)	(Pa,Pa)	#Match
(St,St)	10.0	0.0	0.0	0.0	-0.5	0.0	0.0	0.0	0.0	1
(St,Po)	-0.5	8.0	0.0	0.0	0.0	0.0	0.0	0.0	-0.5	2
(St,Pa)	-0.5	0.0	8.0	0.0	-0.5	0.0	0.0	0.0	0.0	2
(Bo,St)	0.0	0.0	0.0	9.5	0.0	0.0	0.0	0.0	0.0	1
(Bo,Po)	0.0	0.0	0.0	0.0	7.5	0.0	0.0	0.0	-0.5	2
(Bo,Pa)	0.0	0.0	0.0	0.0	0.0	12.0	0.0	0.0	0.0	0
(Pa,St)	0.0	0.0	0.0	0.0	-0.5	0.0	7.5	0.0	0.0	2
(Pa,Po)	-0.5	0.0	0.0	0.0	0.0	0.0	0.0	10.0	0.0	1
(Pa,Pa)	-0.5	0.0	0.0	0.0	-0.5	0.0	0.0	0.0	5.5	3

Table 1: Illustration of a system of linear equations

State-based model comparison (LTS_{Diff} algorithm)

$$S_{Succ}^G(Pa, Pa) = \frac{1}{2} \times \frac{3 + k \times [S_{Succ}^G(St, St) + S_{Succ}^G(Bo, Po) + S_{Succ}^G(Pa, Pa)]}{0 + 0 + 3} = 0.58$$

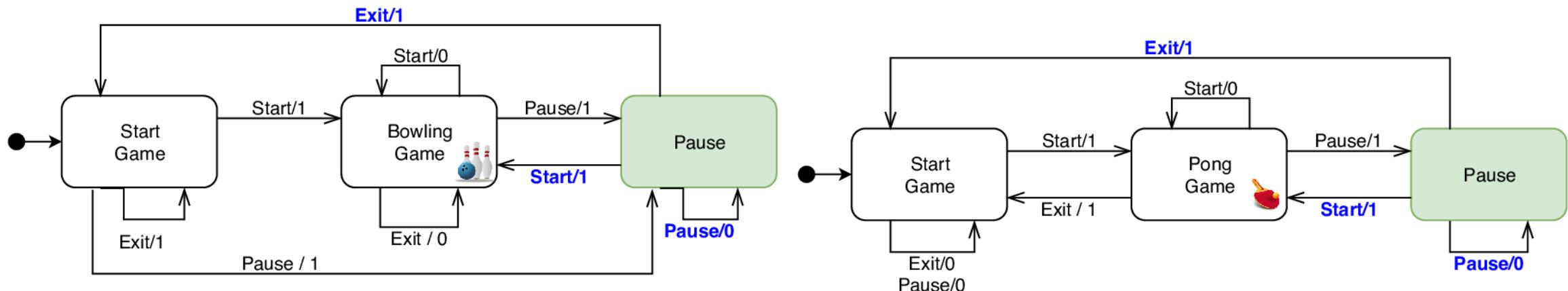


Figure: Two examples of product FSMs and their similarity scores

The FFSM Diff algorithm

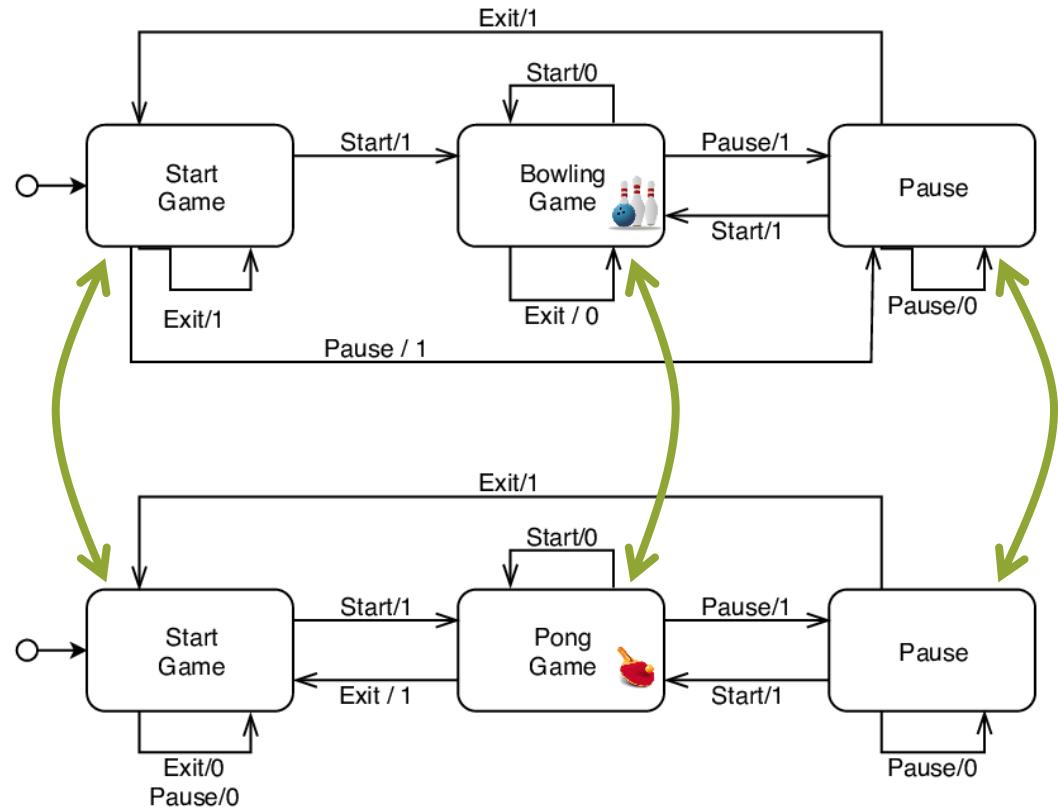


Figure: Two examples of product FSMs

$$\text{pair}(St, St) = 0.12$$

$$\text{pair}(St, Po) = 0.29$$

$$\text{pair}(St, Pa) = 0.28$$

$$\text{pair}(Bo, St) = 0.11$$

$$\text{pair}(Bo, Po) = 0.31$$

$$\text{pair}(Bo, Pa) = 0$$

$$\text{pair}(Pa, St) = 0.29$$

$$\text{pair}(Pa, Po) = 0.11$$

$$\text{pair}(Pa, Pa) = 0.58$$

Figure: Pairwise state similarity

Our modification #2: The state mapping is used to annotate conditional states/transitions

The FFSM Diff algorithm

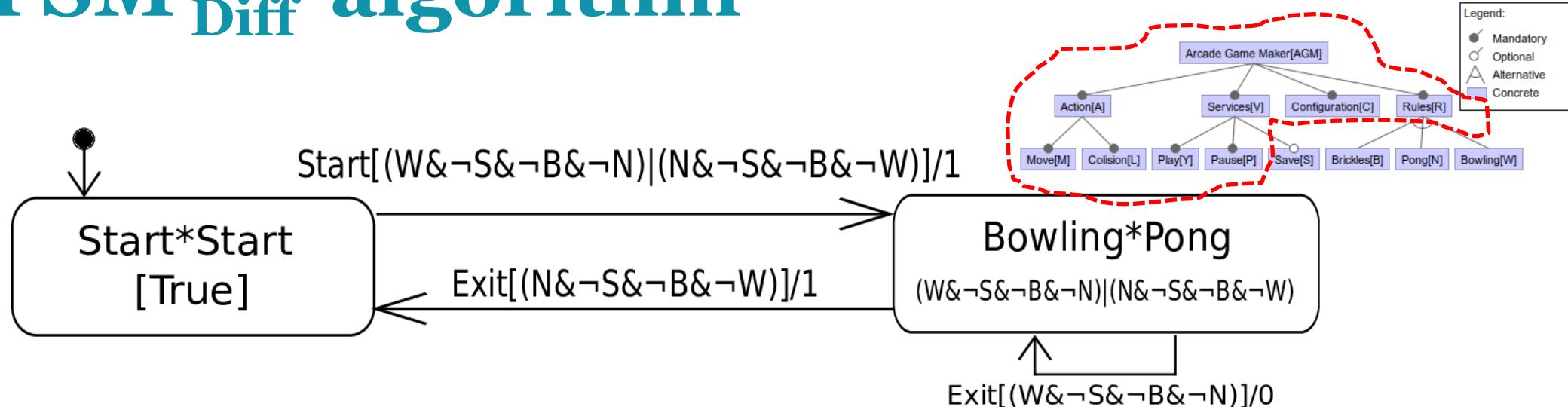


Figure: Fragment of the FFSM learnt from two products of the AGM SPL.

Simplified configuration – Example

$$\rho_{Bowling} = (W \wedge \neg S \wedge \neg B \wedge \neg N)$$

$$\rho_{Pong} = (N \wedge \neg S \wedge \neg B \wedge \neg W)$$

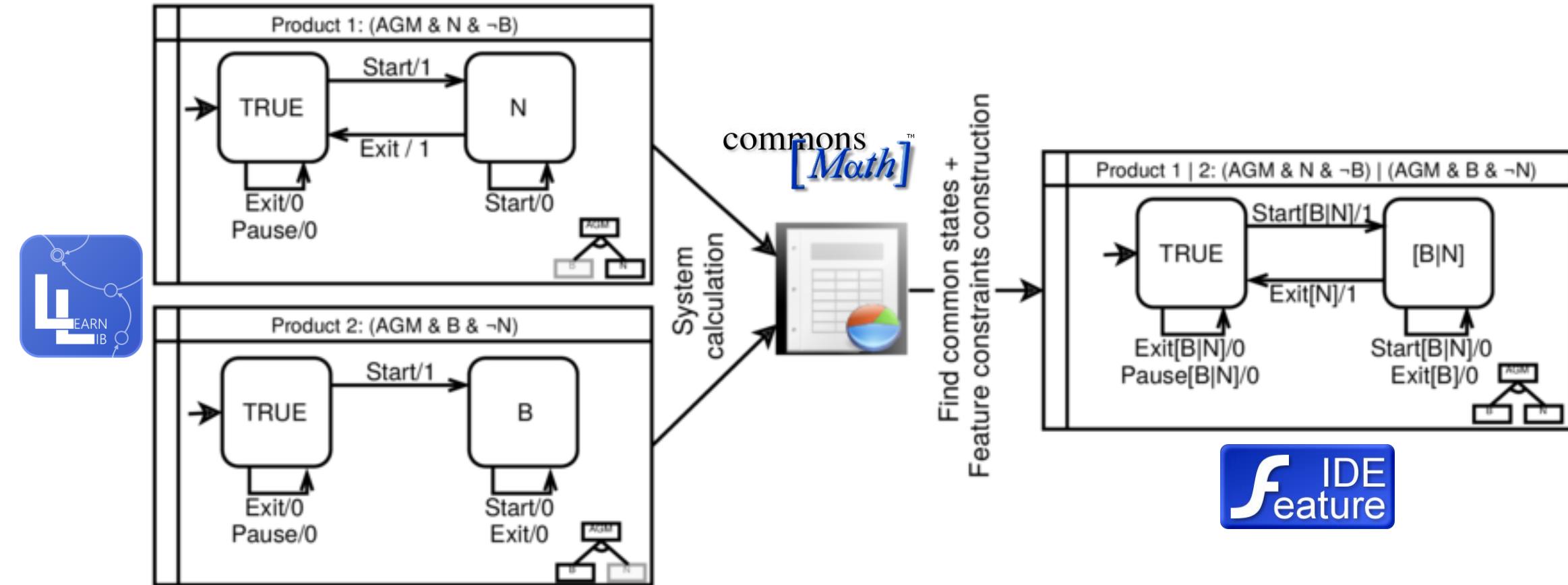
Our modification #3: We use **feature model analysis** to **identify core features** of the SPL and **simplify feature constraints**

Empirical Evaluation

Empirical Evaluation

- RQ1)** Is our approach effective in learning succinct family models compared to the total size of the product pairs under learning?
- RQ2)** Is the size of learned family models influenced by the configuration similarity degree of the products under learning?
- RQ3)** Is our approach effective in learning succinct family models compared to the total size of the hand-crafted models?

Empirical Evaluation



Subject Systems

SPL		Feature model		Family model	
ID	Name	Features	Valid conf.	States	Transitions
AGM	Arcade Game Maker	13	6	6	35
VM	Vending Machine	9	20	14	197
WS	Wiper System	8	8	13	112
AEROUC5	Aero UC5	7	9	25	450
CPTERMINAL	Card Payment	13	30	11	176
MINEPUMP	Minepump	9	32	25	575

Table 10 – Description of the SPLs under learning - Feature and family models

Analysis of Results (RQ1 – Size of Product Pairs)

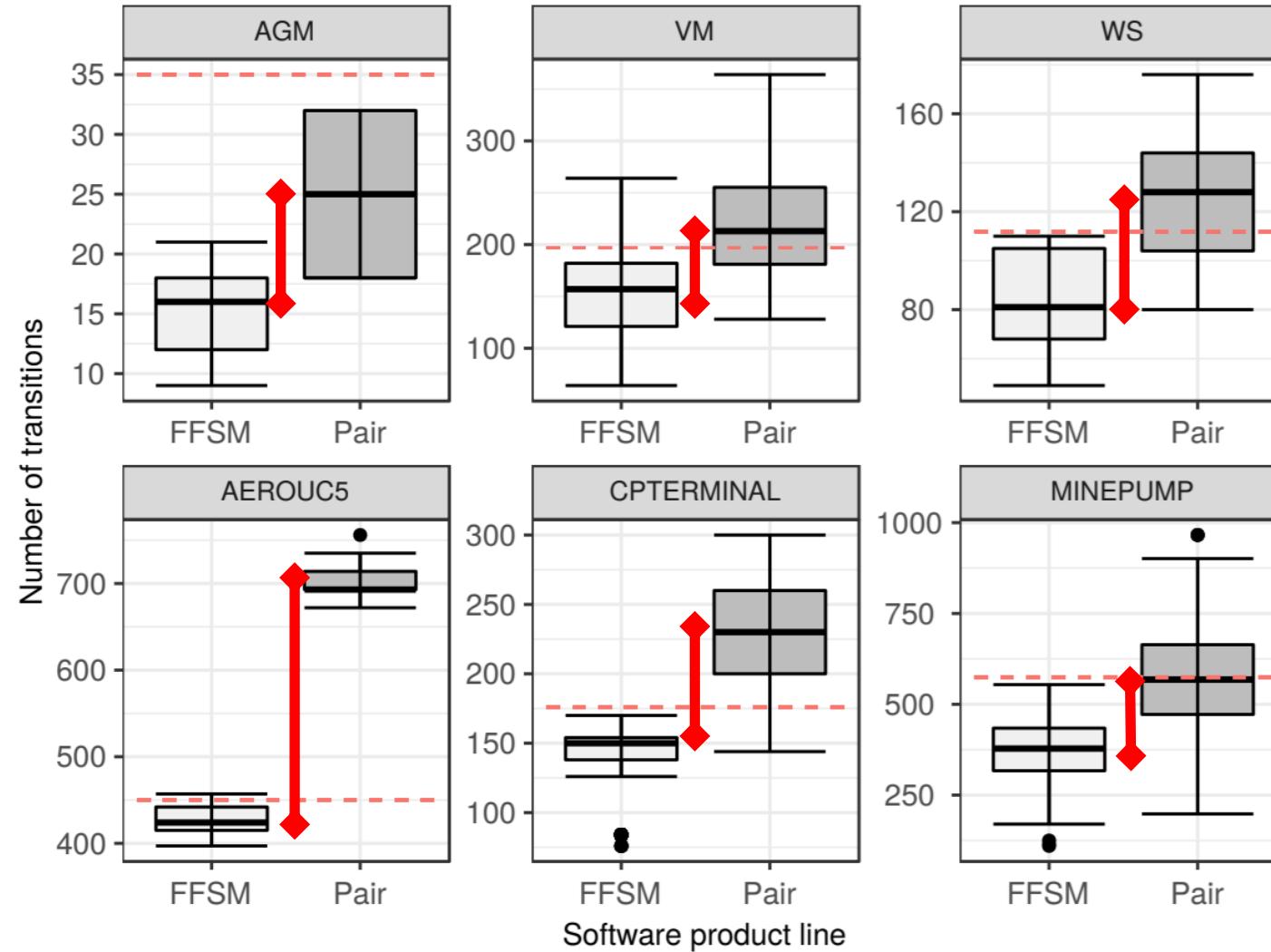


Figure 26 – Number of transitions in the learned FFSMs and pairs of products

Analysis of Results (RQ2 – Configuration similarity)

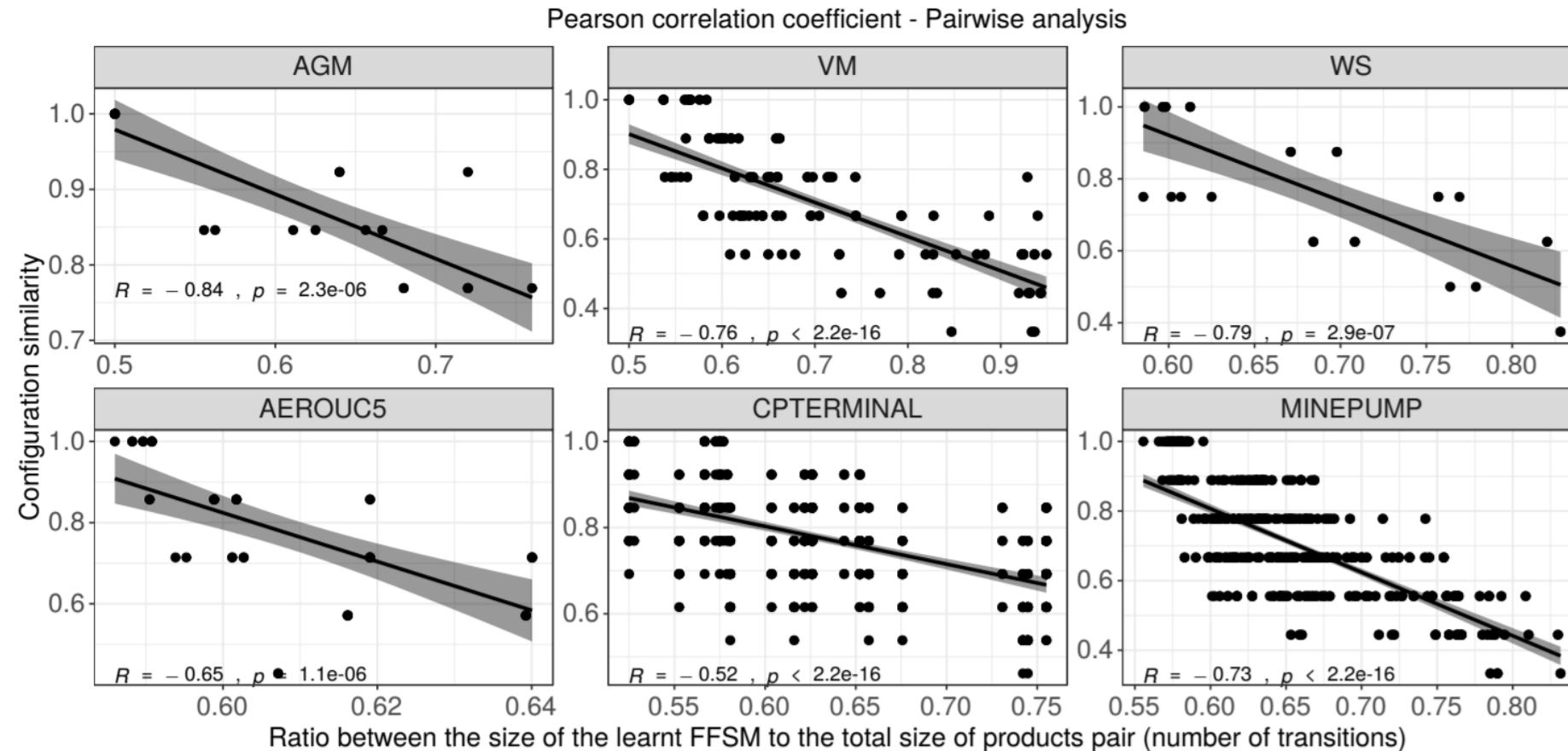


Figure 28 – Scatter plots for the relationship between the normalized size of the learned FFSM and configuration similarity

Analysis of Results (RQ3 – Size of Handcrafted models)

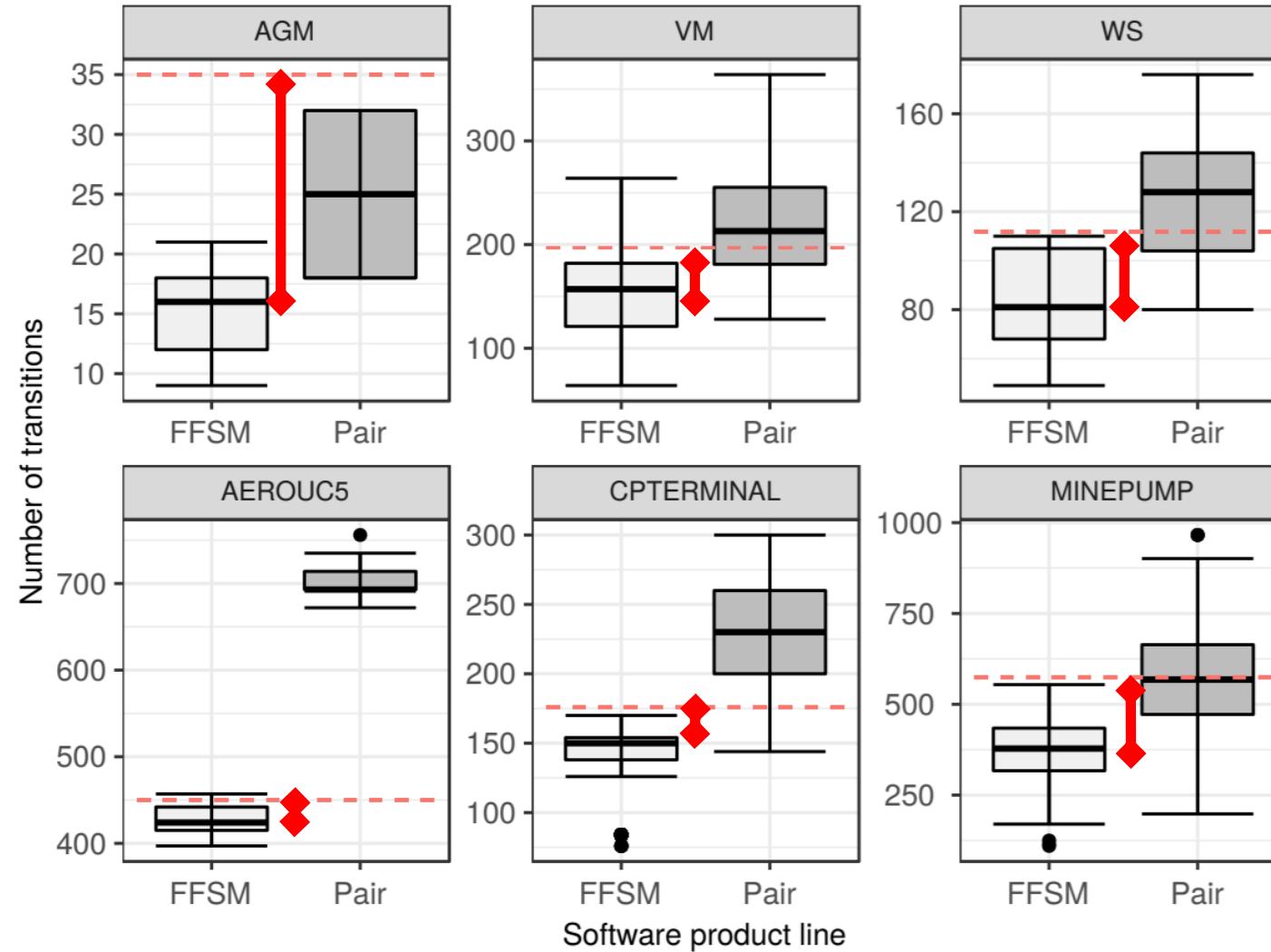


Figure 26 – Number of transitions in the learned FFSMs and pairs of products

Analysis of Results (RQ3 – Size of Handcrafted models)

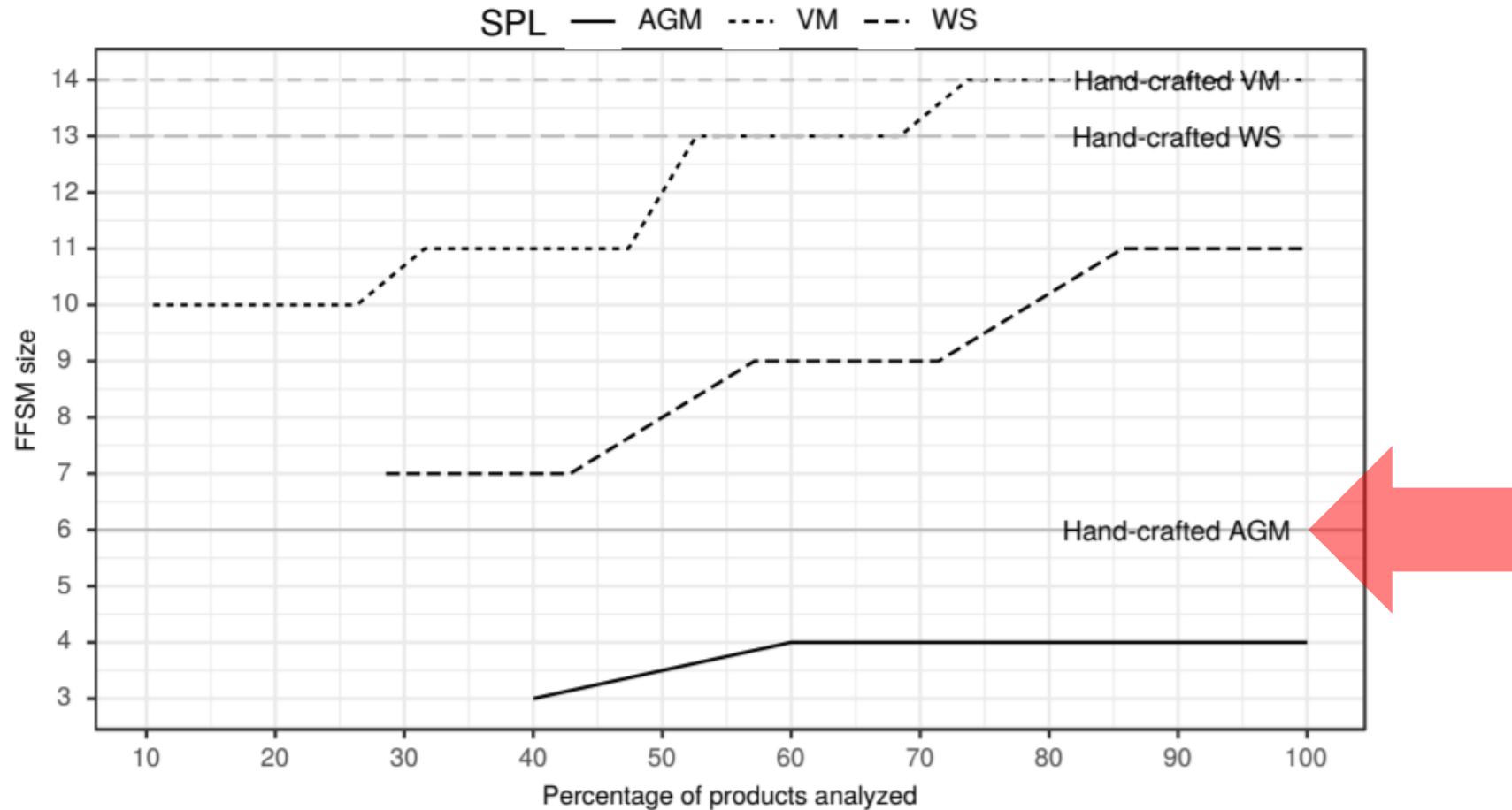
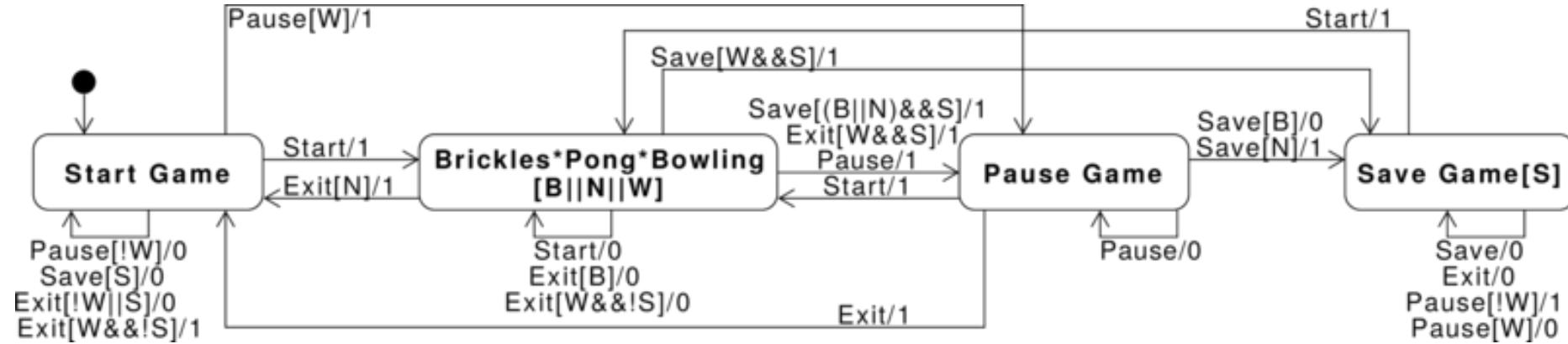


Figure 29 – Size of the recovered FFSMs

Analysis of Results (RQ3 – Size of Handcrafted models)



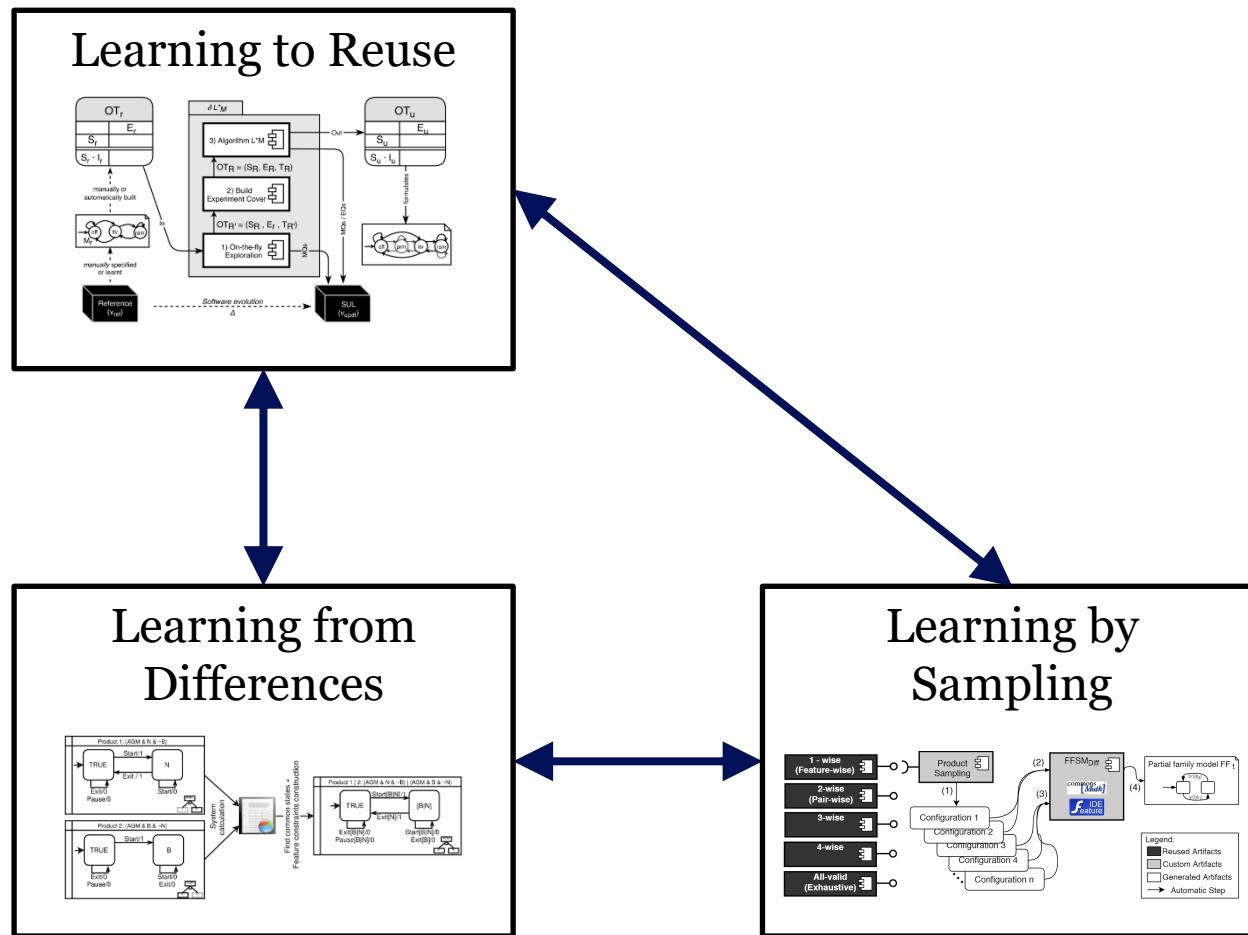
Summary (Learning from Difference)

The FFSM_{Diff} algorithm is able to...

1. Learn **fresh FFSMs** from products pairs
 - Especially if there is **high feature reuse** (i.e., configuration similarity)
2. Incorporate **new product behavior** into an existing FFSM
 - Family model recovery (e.g., reverse engineering, re-engineering)



Research Objectives



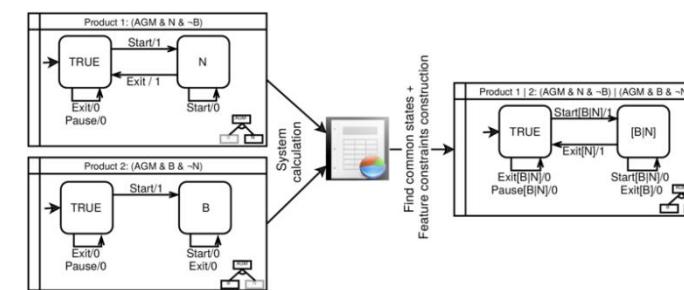
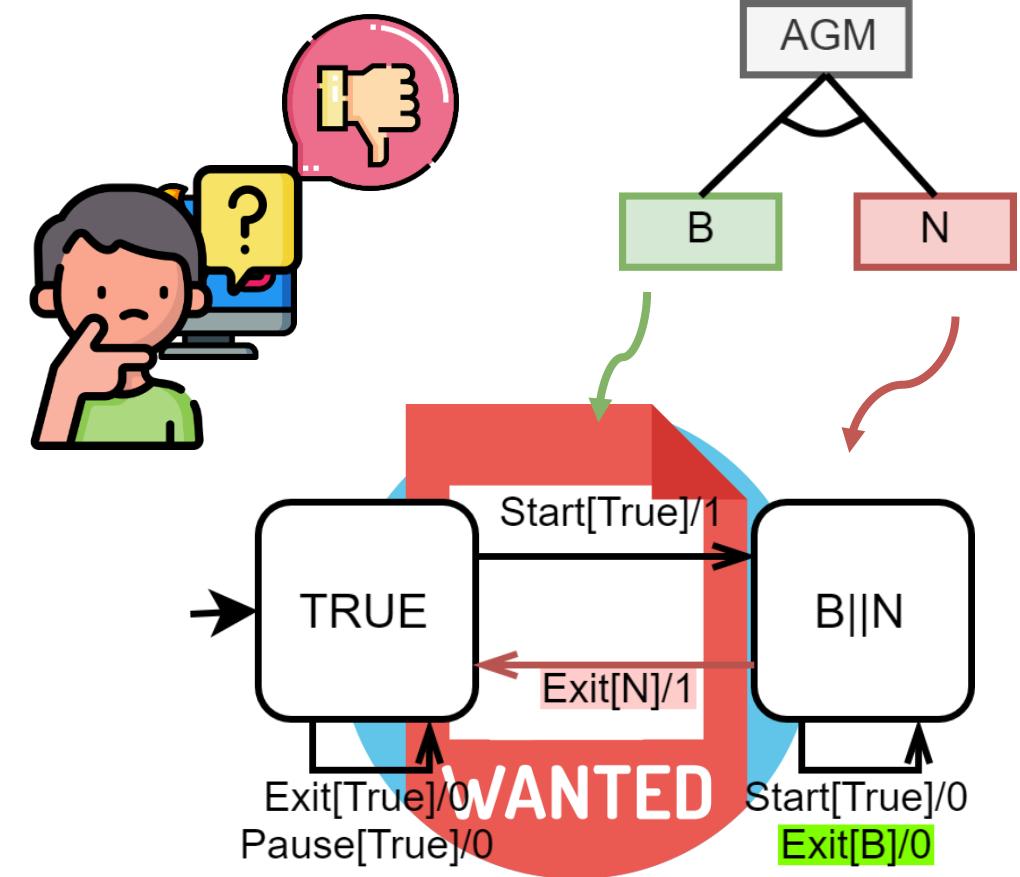
Learning by Sampling

Learning Behavioral Family Models from Software Product Lines

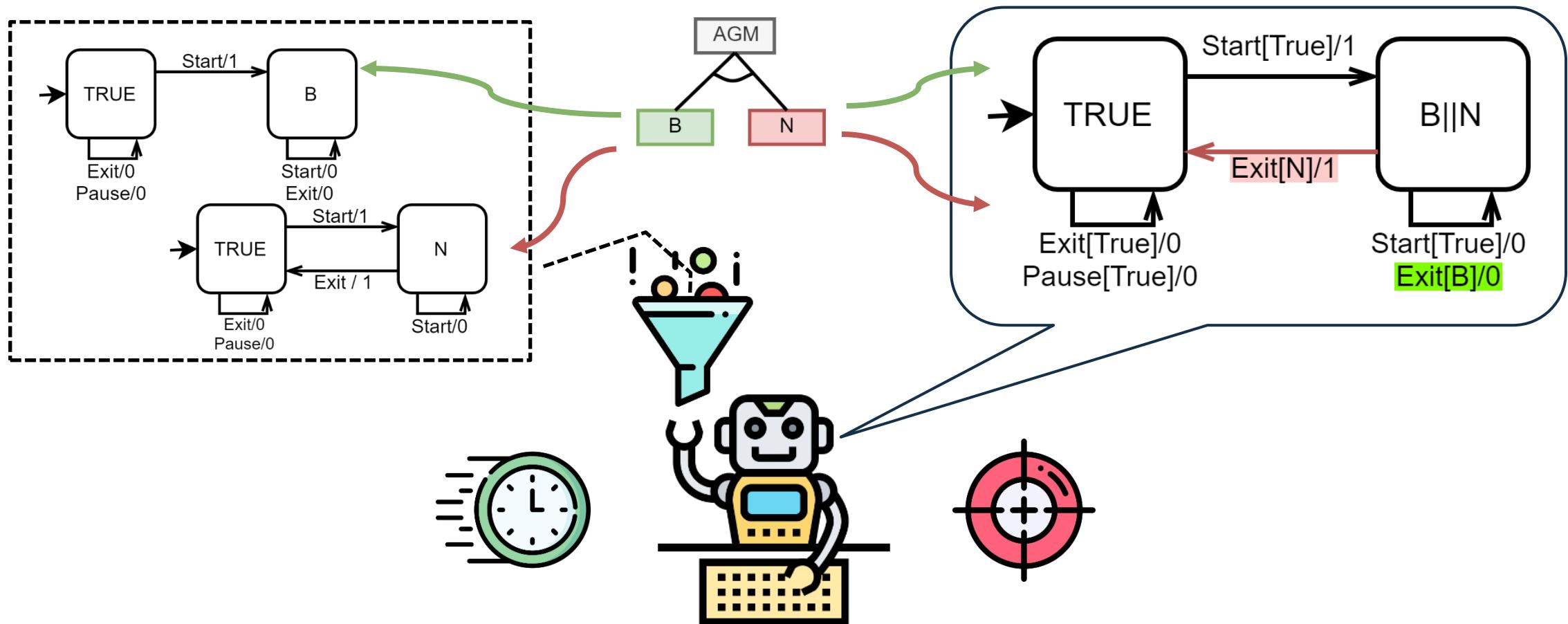


Context (Learning by Sampling)

- Software product lines (SPL)
 - Product-based strategies: *Impractical?*
 - Family-based strategies: *Models?*
- Family model learning \rightarrow FFSM_{Diff}
 - Exhaustive learning
 - Learning by Sampling



Research Problem (Learning by Sampling)



*How can we **optimize family model learning** to make it more **effective**?*

Contribution (Learning by Sampling)

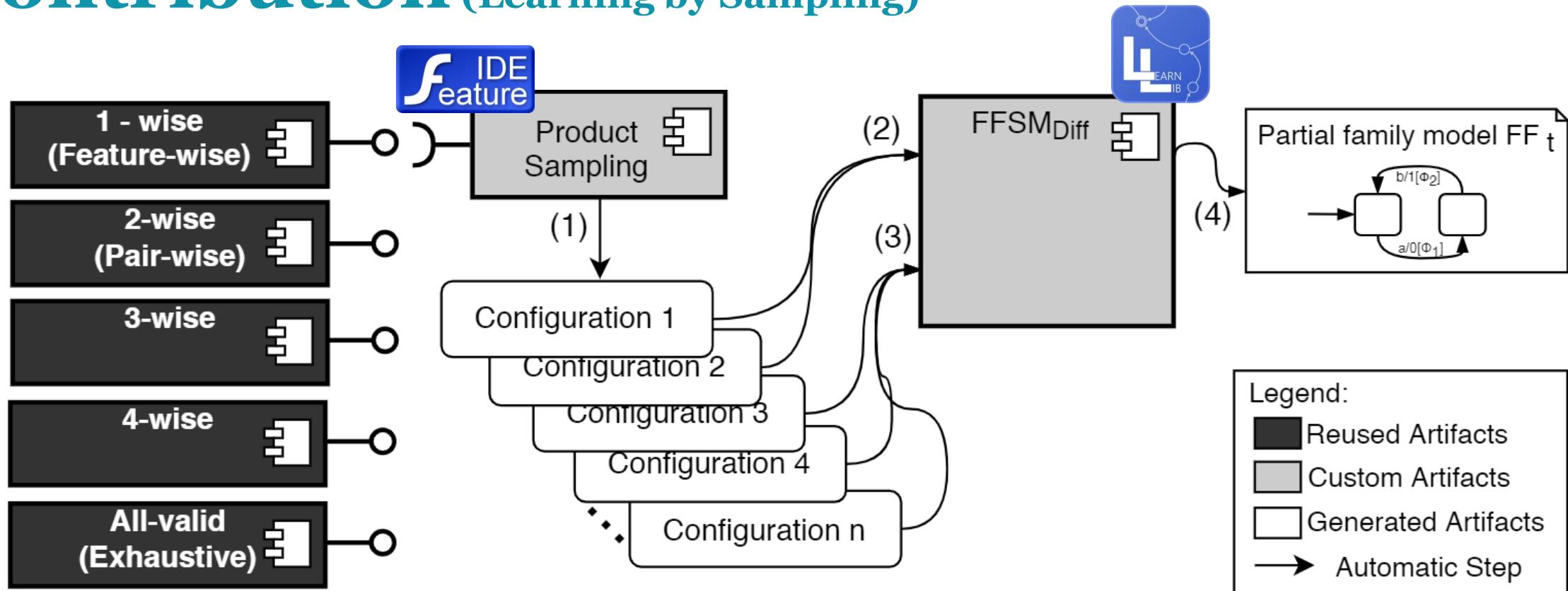


Fig. 8: Experiment design - Learning FFSMs by product sampling

Empirical Evaluation

Empirical Evaluation

RQ4) Is our approach effective in learning precise family models by sampling compared to exhaustive learning?

Subject Systems

SPL	Size of the sampled subset generated by T-wise				
	Feature-wise	Pair-wise	3-wise	4-wise	All-valid
AGM	3	6	6	6	6
VM	2	6	13	19	20
WS	2	5	8	8	8
AEROUC5	3	6	9	9	9
CPTERMINAL	3	8	16	24	30
MINEPUMP	3	7	13	24	32

Table 13 – Number of configurations in the subsets generated by each criteria

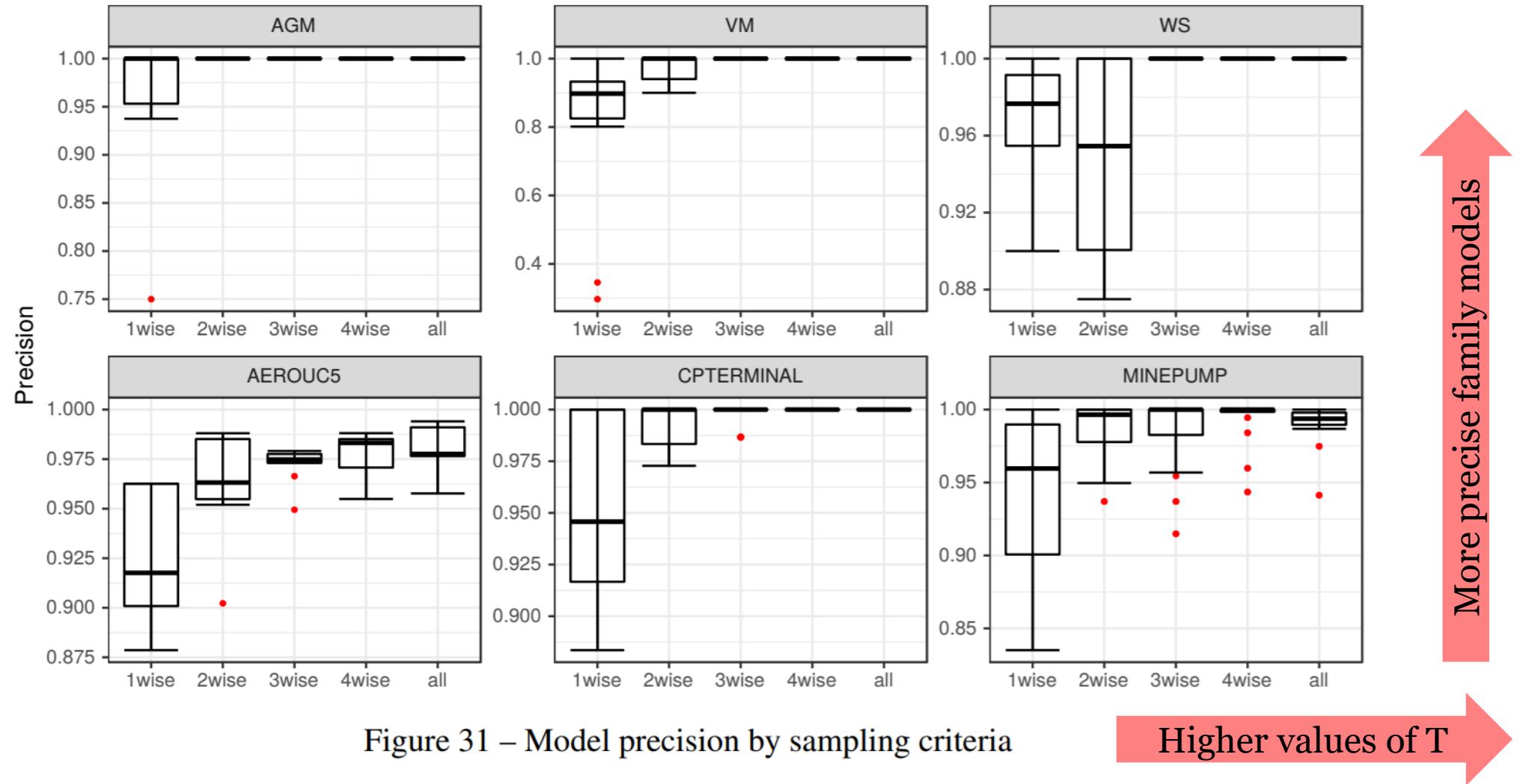
A. Classen, 'Modelling with FTS: a Collection of Illustrative Examples'. 2010, [Online]. Available: <https://researchportal.unamur.be/en/publications/modelling-with-fts-a-collection-of-illustrative-examples>

H. Samih, H. L. Guen, R. Bogusch, M. Acher, and B. Baudry, 'Deriving Usage Model Variants for Model-Based Testing: An Industrial Case Study', in Proceedings of the ICECCS 2014

X. Devroey, G. Perrouin, A. Legay, P.-Y. Schobbens, and P. Heymans, 'Search-based Similarity-driven Behavioural SPL Testing', in Proceedings of the VaMoS 2016

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Analysis of Results (RQ4 – Learning by Sampling)



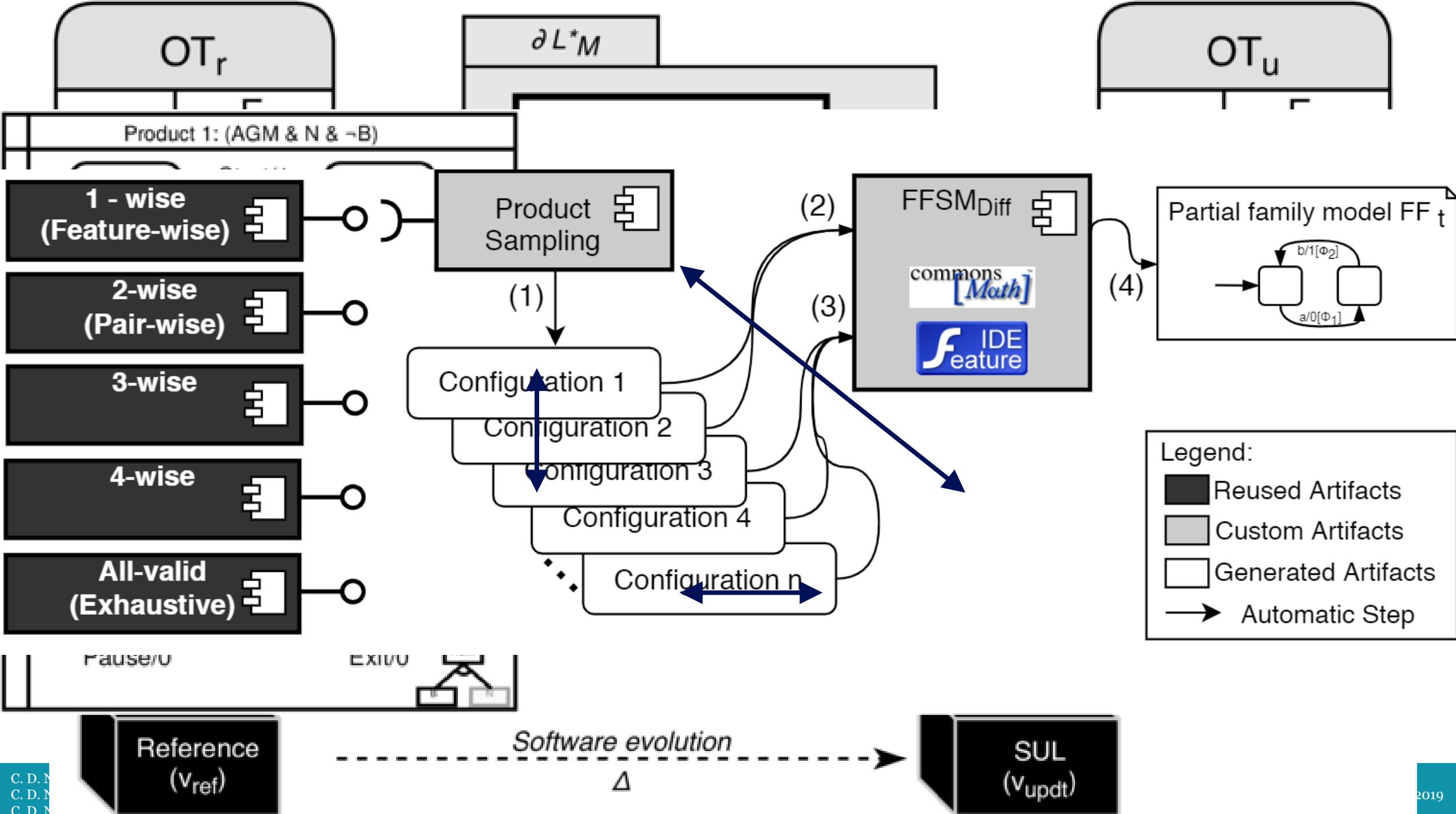
Summary (Learning by Sampling)

- 1. Learning by sampling** can lead to family models **as precise as** those obtained by **exhaustive analysis**
- 2. Higher interaction strengths** lead to higher coverage
- 3. We show evidences that product sampling can be helpful to family model learning and recovery**

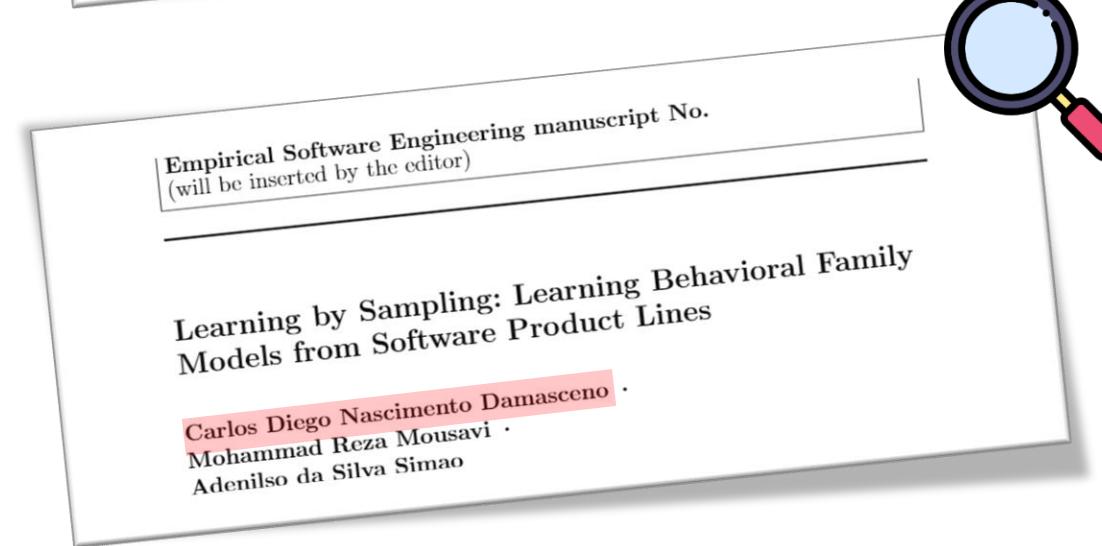
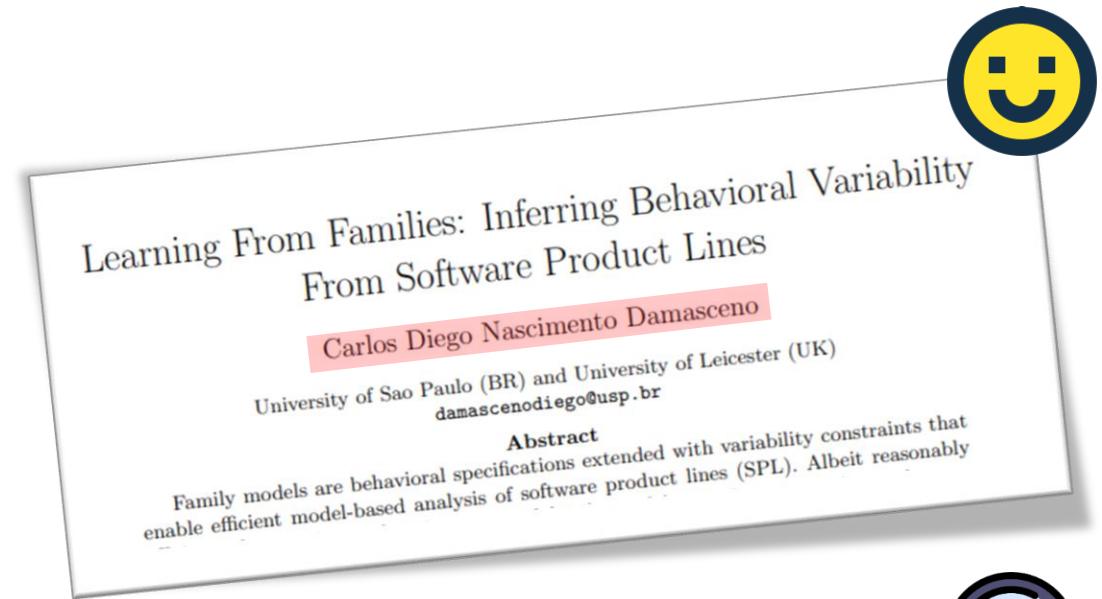
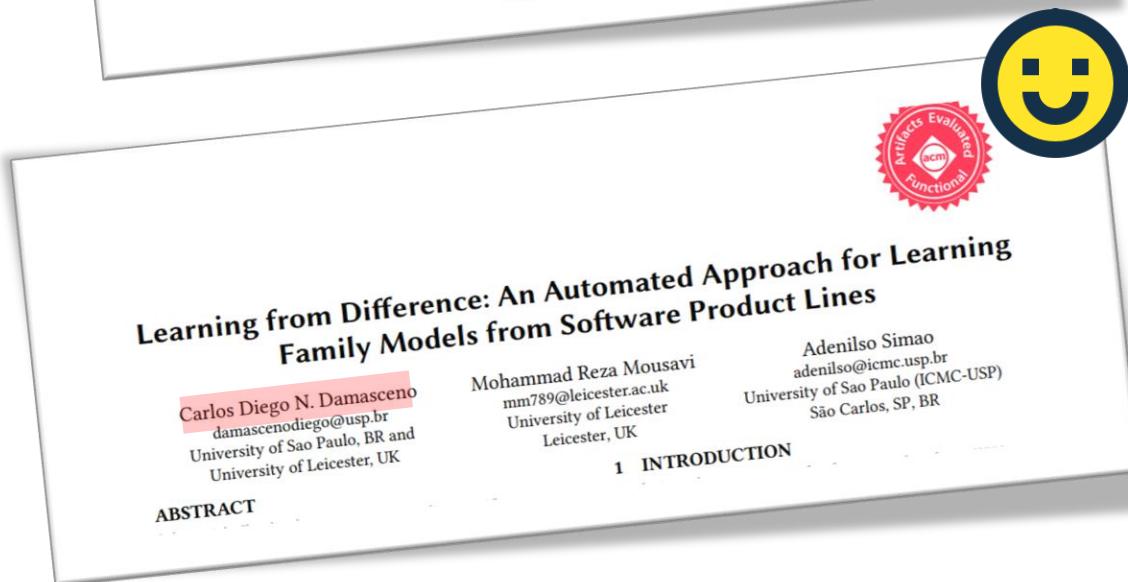
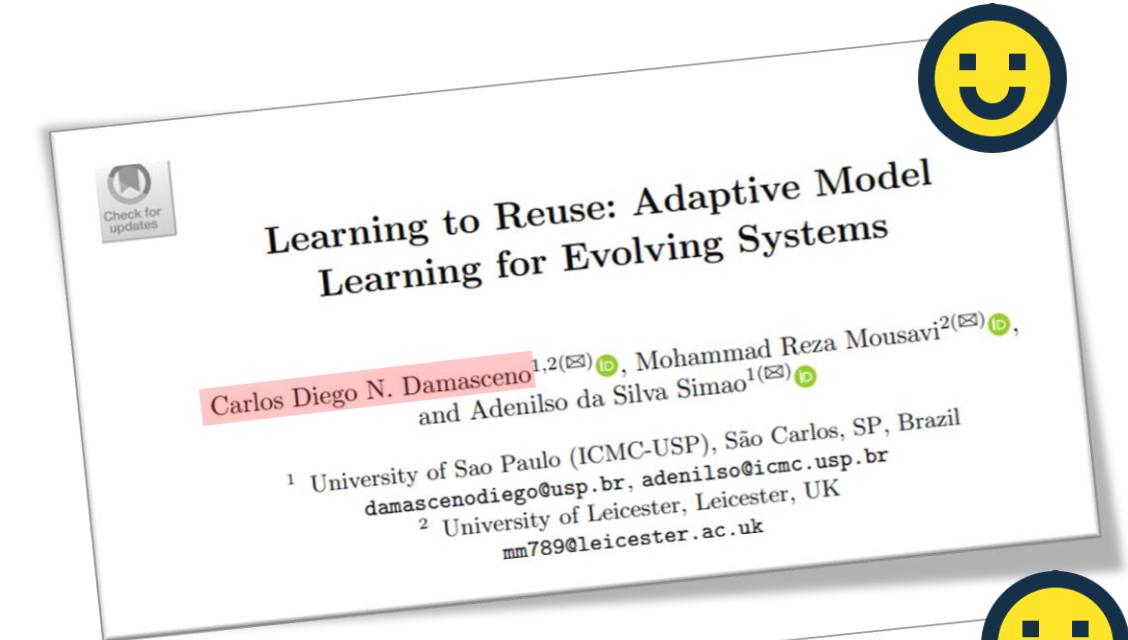


Final Remarks and Future Work

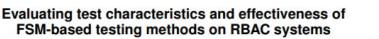
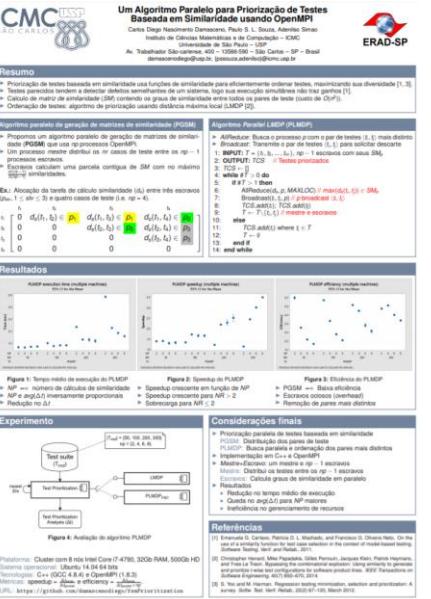




The main publications of this PhD Thesis



Other contributions



Trusted Autonomous Vehicles: an Interactive Exhibit



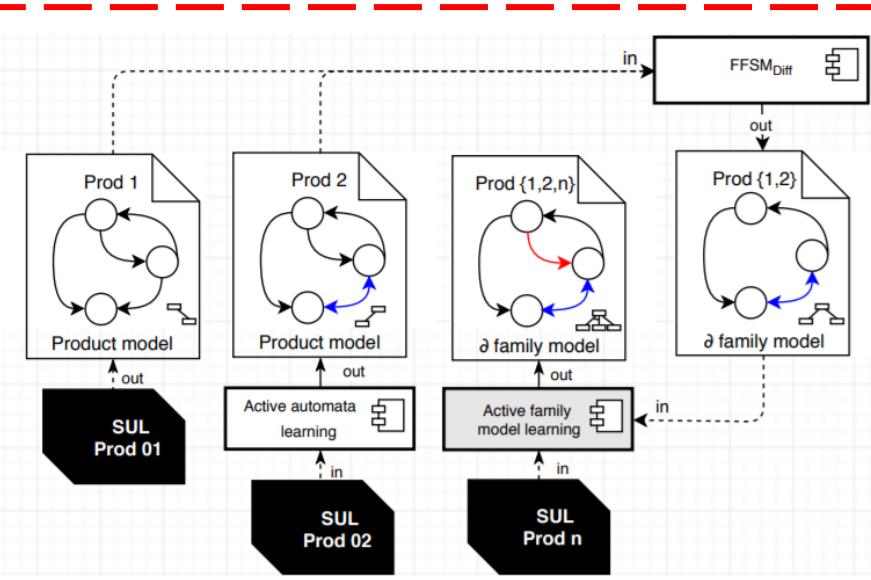
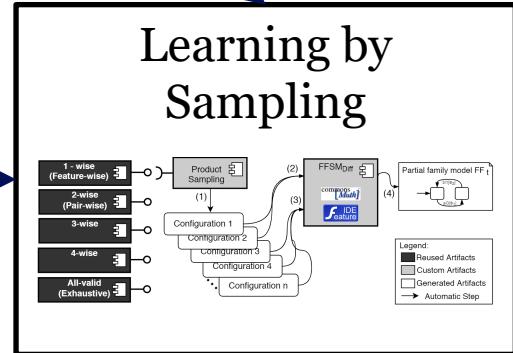
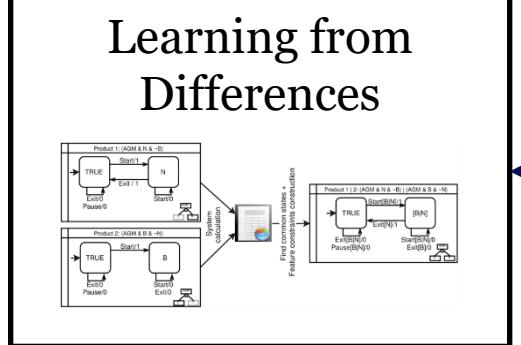
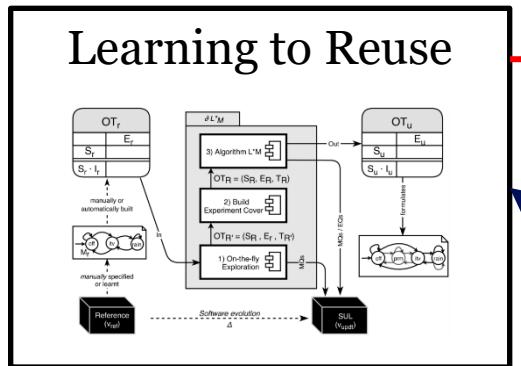
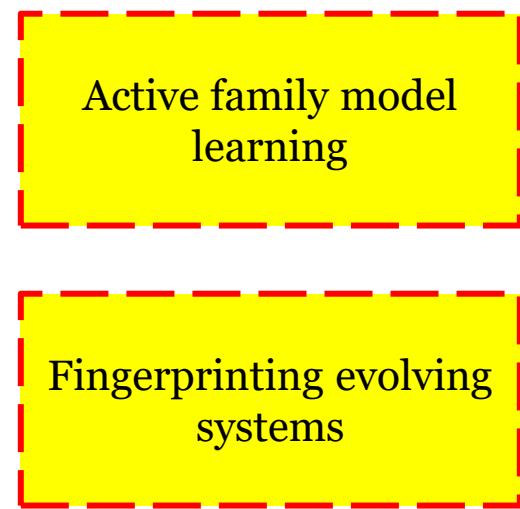
Data Analysis of Multiplex Sequencing at SOLiD Platform: A Probabilistic Approach to Characterization and Reliability Increase



American Journal of Molecular Biology, 2018, 8, 26-38
<http://www.scirp.org/journal/ajmb>
ISSN Online: 2161-6663
ISSN Print: 2161-6620



Future Work



Source: Damasceno (2019).

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G. Shu and D. Lee, 'Network Protocol System Fingerprinting - A Formal Approach', in Proceedings of the IEEE INFOCOM 2006

Thank you



Questions?

