

A classical solution of

$$-u_{xx} = f$$

satisfies

$$\int_0^L u_x \phi_x - f \phi = 0 \quad \text{if } \phi \text{ is}$$

a test function

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$$\int_0^L u_x \phi_x - f \phi = 0 \quad \text{for } \phi \text{ a test function}$$

$$[\text{or } C, \phi|_0^L = 0]$$

A classical solution of

$$-u_{xx} = f$$

satisfies

$$\int_0^L u_x \phi_x - f \phi = 0 \quad \text{for } \phi \in \mathcal{B}$$

a test function

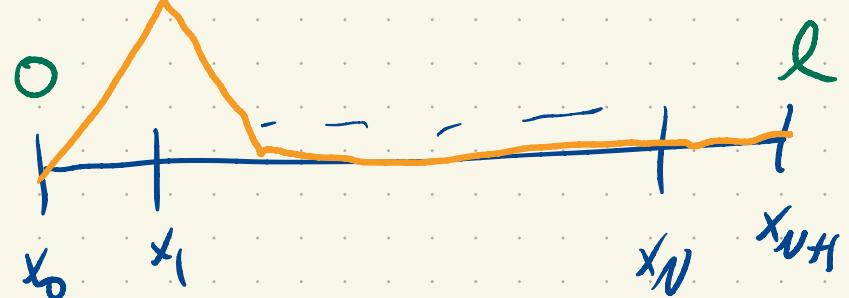
$$[\text{or } C^1, \phi|_0^L = 0]$$

$$H_0'$$

$$[\text{or } \begin{matrix} \text{piecewise linear!} \\ C^0 \end{matrix}]$$

Modified problem:

$$\mathcal{V}_h = \text{span} \{ \varphi_1, \dots, \varphi_N \}$$



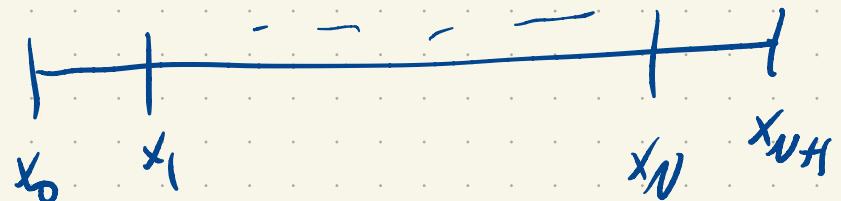
True solution

$$\int u_x \phi_x - u \phi = 0 \quad \text{if test functions } \phi$$

(including piecewise linear!)

Modified problem:

$$\mathcal{V}_h = \text{span} \{ \varphi_1, \dots, \varphi_N \}$$



True solution: $\int u_x \phi_x - u \phi = 0$ if test functions ϕ

Approx: Find $u^h \in \mathcal{V}_h$ with

$$\int u_x^h \phi_x - u^h \phi = 0 \quad \forall \phi \in \mathcal{V}_h$$

$$\int u_x^h \phi_x - f \phi = 0 \quad \forall \phi \in \mathcal{V}_h$$

$$u^h = \sum_{j=1}^N u_j^{\text{number}} \psi_j$$

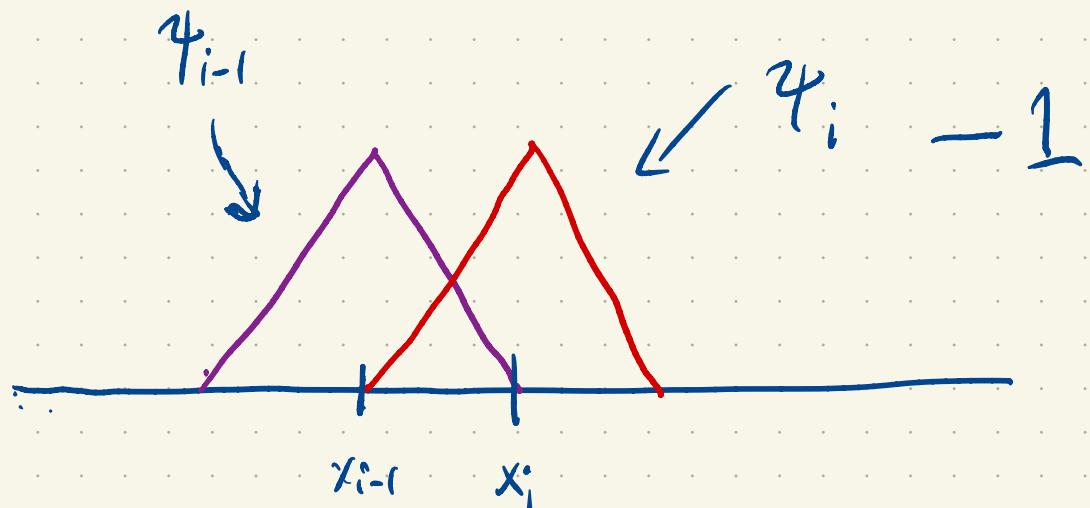
$$\int u_x^h \phi_x - f \phi = 0 \quad \forall \phi \in \mathcal{V}_h$$

$$u^h = \sum_{j=1}^N u_j \psi_j$$

↓
 number

$$\int \sum_{j=1}^N u_j [\partial_x \psi_i \partial_x \psi_j] = \int f \psi_i \quad i = 1, \dots, N$$

$$A_{ij} = \int \partial_x \psi_i \partial_x \psi_j$$



$$\int [f_i - f_{i-1}] dx = ?$$

$-1/h^2$

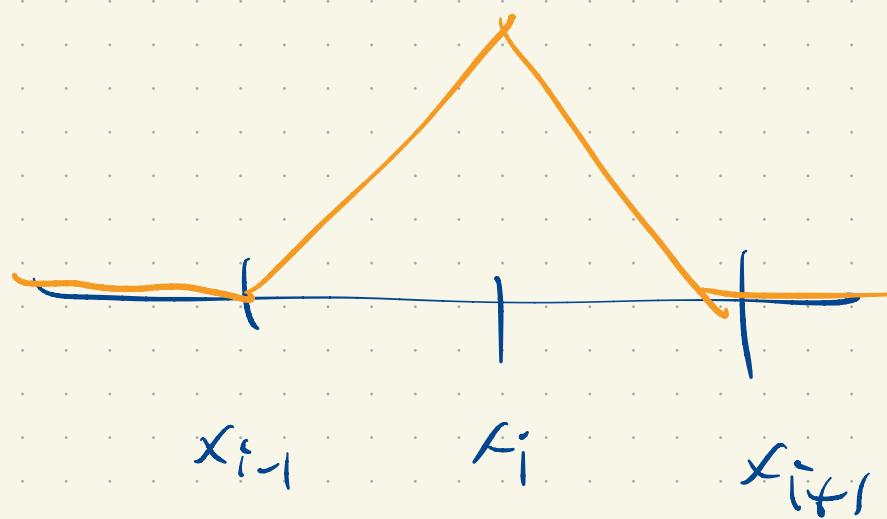
$$h$$

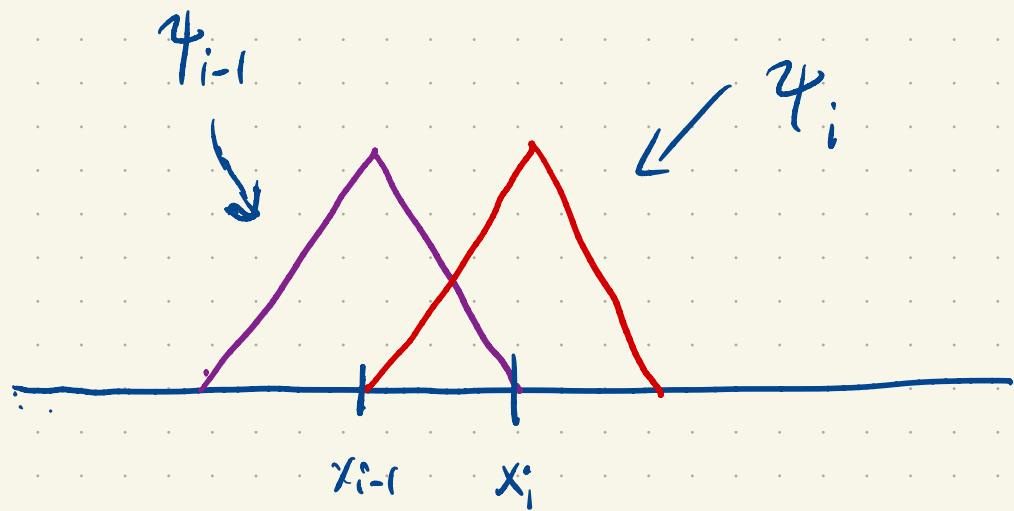
$\partial_x f_i$

$$\int \partial_x f_{i-1} \partial_x f_i dx = \frac{-1}{h}$$

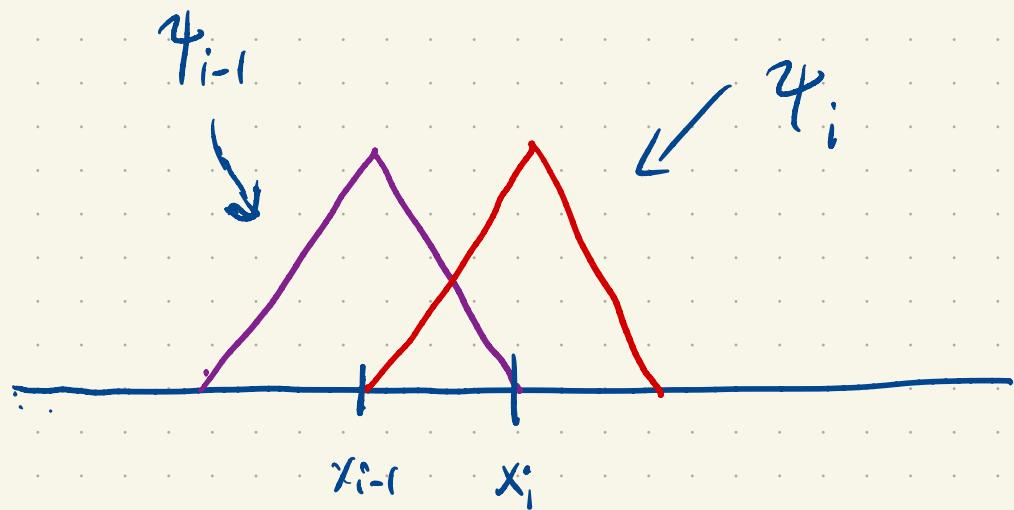
$$\int_{x_{i-1}}^{x_{i+1}} \partial_x f_i \partial_x f_{i-1} dx$$

$\frac{2}{h}$





$$\int_{x_{i-1}}^{x_i} \partial_x \psi_{i-1} \partial_x \psi_i = -\frac{1}{h^2} h = -\frac{1}{h}$$



$$\int_{x_{i-1}}^{x_i} \partial_x \psi_{i-1} \partial_x \psi_i = -\frac{1}{h^2} h = -\frac{1}{h}$$

$$\int_{x_{i-1}}^{x_{i+1}} \partial_x \psi_i \partial_x \psi_i = \frac{1}{h^2} \cdot 2h = \frac{2}{h}$$

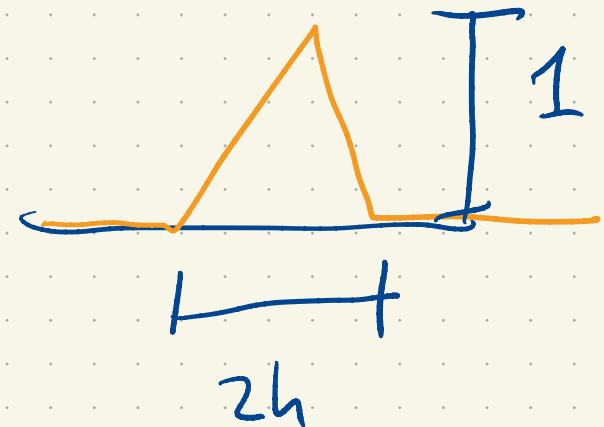
$$\int \partial_x \psi_i \partial_x \psi_j : \frac{1}{h} \begin{bmatrix} 2 & -1 & 0 & & \\ -1 & 2 & -1 & 0 & \cdots \\ 0 & -1 & 2 & -1 & 0 & \cdots \\ & \cdots & & \cdots & 0 & -1 & 2 \end{bmatrix} = A$$


stiffness
matrix

$$\sum_{j=1}^n A_{ij} u_j = \int_{x_{i-1}}^{x_{i+1}} f \psi_i$$


approximate by numerical quadrature

$$\int_{x_{i-1}}^{x_i} f \varphi_i \approx f(x_i) \int_{x_{i-1}}^{x_i} \varphi_i$$



$$\int_{x_{i-1}}^{x_i} f \varphi_i \approx f(x_i) \int_{x_{i-1}}^{x_i} \varphi_i = f(x_i) \frac{1}{2} \cdot 2h \cdot 1 = h f(x_i)$$

$$\int_{x_{i-1}}^{x_{i+1}} f \varphi_i \approx f(x_i) \int_{x_{i-1}}^{x_{i+1}} \varphi_i = f(x_i) \frac{1}{2} \cdot 2h \cdot 1 = h f(x_i)$$
$$(= h f(x_i) + O(h^3))$$

$$\int_{x_{i-1}}^{x_{i+1}} f \varphi_i \approx f(x_i) \int_{x_{i-1}}^{x_{i+1}} \varphi_i = f(x_i) \frac{1}{2} \cdot 2h \cdot 1 = h f(x_i)$$

$$(= h f(x_i) + O(h^3))$$

Or interpolate

$$\sum_{j=1}^n f(x_j) \varphi_j$$

$$\int \varphi_i \varphi_j dx = \begin{cases} \frac{2}{3}h & i=j \\ \frac{1}{6}h & |i-j|=1 \\ 0 & \text{otherwise} \end{cases}$$

A

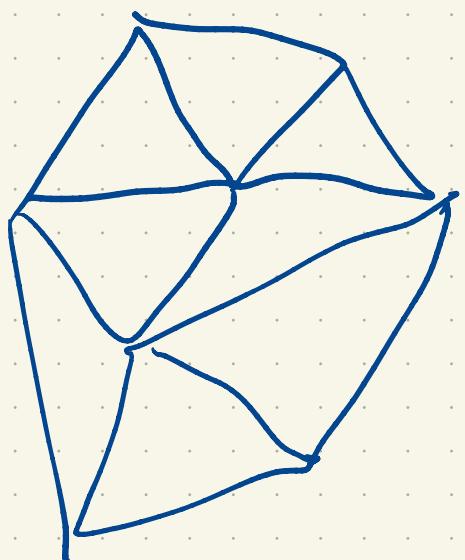
$$\int_0^1 x(1-x) dx$$

$$\int_0^1 x^2 dx$$

$$\int f \varphi_i$$

So solving a modification of

$$\frac{1}{h} \begin{bmatrix} 2 & -1 & 0 & \dots \\ -1 & 2 & -1 & 0 & \dots \\ 0 & \ddots & \ddots & \ddots & \ddots \\ \vdots & & & \ddots & \ddots \\ 0 & \dots & \dots & \dots & 2 & -1 & 0 \end{bmatrix} \vec{u} = h \begin{bmatrix} f(x_1) \\ \vdots \\ f(x_n) \end{bmatrix}$$



$$\frac{1}{h^2} \begin{bmatrix} * & & & \\ & * & & \\ & & * & \\ & & & * \end{bmatrix} \vec{u} = \vec{f} + O(h^2)$$

Convergence?

$$H_0^1 \text{ norm: } \left[\int_0^l (v_x)^2 \right]^{1/2} \quad (\text{this is a norm}).$$

$$-a_{xx} = f$$

$$\int u_x \phi_x - f \phi = 0 \quad \forall \phi \in H_0^1$$

$$H_0^1 \text{ norm: } \left[\int_0^l (v_x)^2 \right]^{1/2} \quad (\text{this is a norm}).$$

H'

$$\int u_x \phi_x - f\phi = 0 \quad \forall \phi \in H_0^1$$

$$\int u_x^h \phi_x - f\phi = 0 \quad \forall \phi \in \mathcal{V}_h \subseteq H_0^1$$

$$\int_0^l e_x^h \phi_x = 0 \quad \forall \phi \in \mathcal{V}_h.$$

$$H_0^1 \text{ norm: } \left[\int_0^l (v_x)^2 \right]^{1/2} \quad (\text{this is a norm}).$$

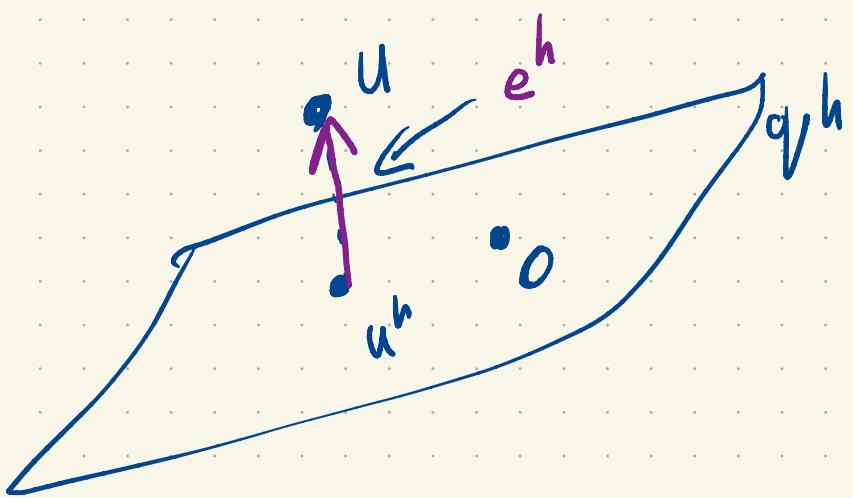
$$\int u_x \phi_x - f \phi = 0 \quad \forall \phi \in H_0^1$$

$$\int u_x^h \phi_x - f \phi = 0 \quad \forall \phi \in V_h \subseteq H_0^1$$

$$\int e_x^h \phi_x = 0 \quad \forall \phi \in V_h.$$

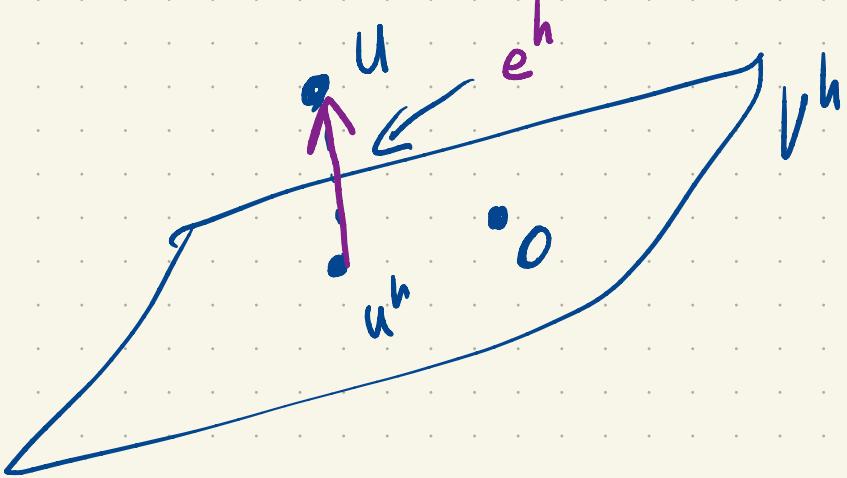
The error
solves an
equation!

u^h is closest (in \mathcal{V}_h) to u :



$$\|u^h - u\|_{H_0^1} \left[\int_0^L \alpha(u^h - u) \partial_x(u_h - u) \right]$$

u^h is closest ($\text{in } \mathcal{V}_h$) to u :

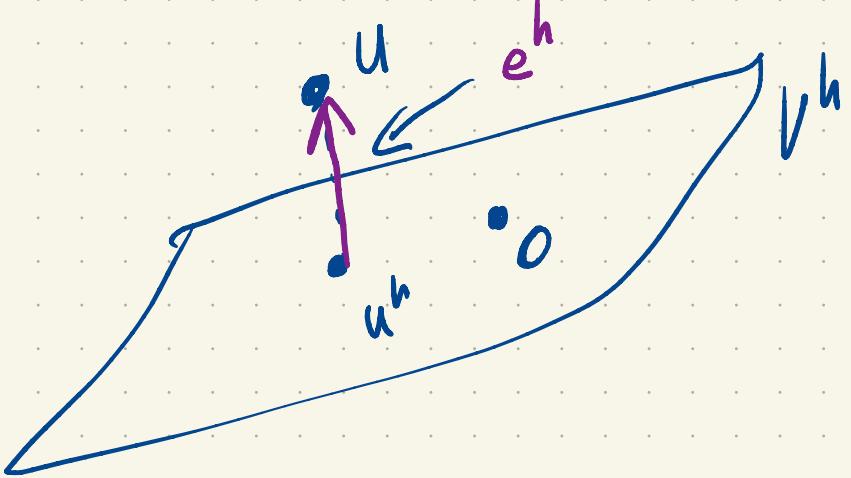


$$e^h \perp \mathcal{V}^h \quad H_0^1$$
$$\int \partial_x v \partial_x w$$

$$\int \partial_x e^h \partial_x w = 0$$

$$\forall w \in \mathcal{V}^h$$

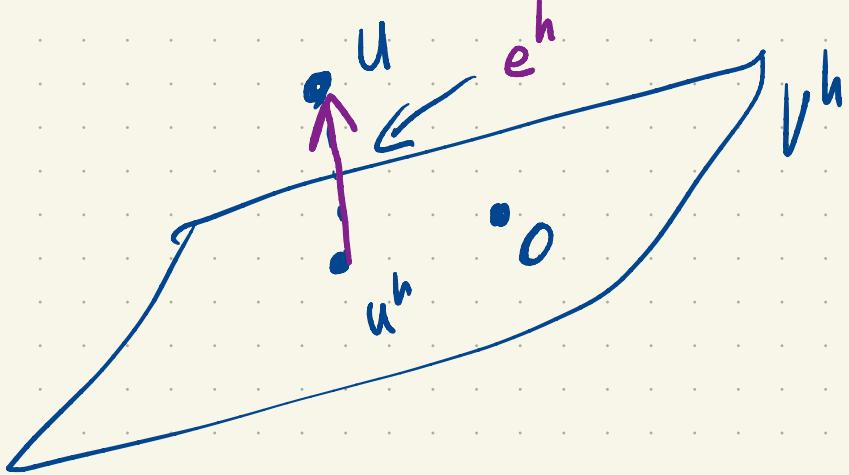
u^h is closest (in \mathcal{V}_h) to u :



$$e^h \perp V^h$$

$$\int e_x^h \phi_x = 0 \quad \forall \phi \in \mathcal{V}_h$$

u^h is closest ($\text{in } \mathcal{V}_h$) to u :

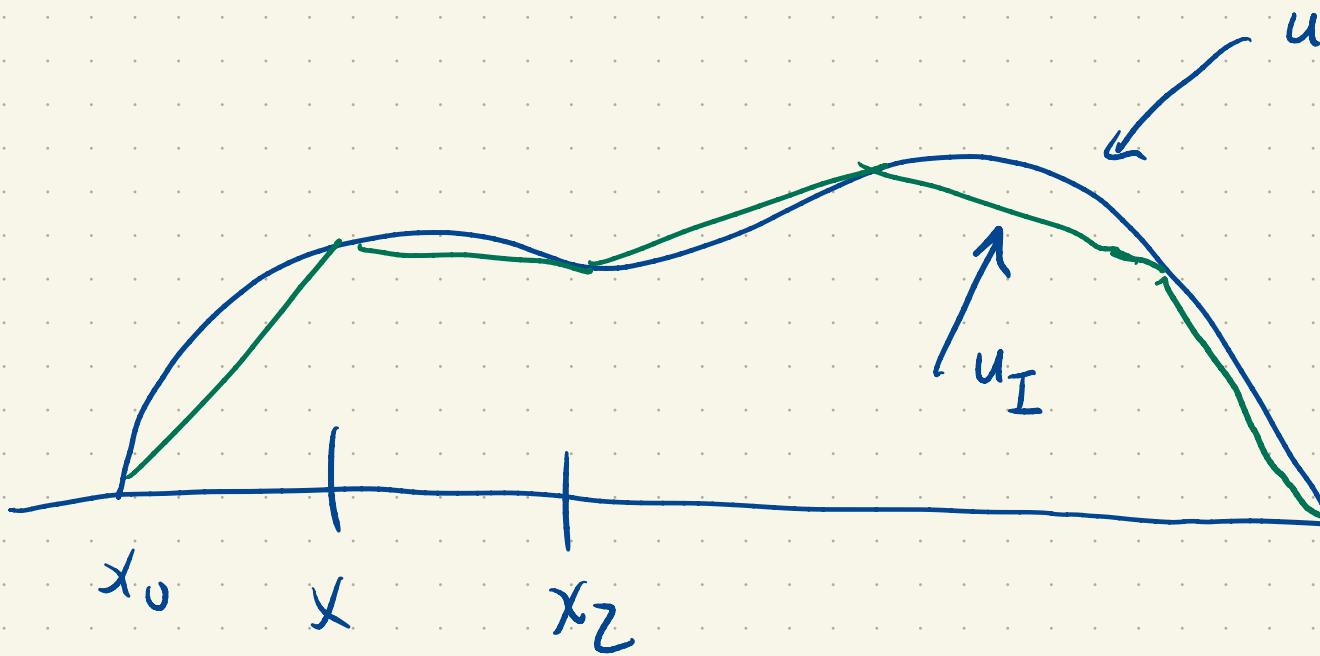


$$e^h \perp V^h$$

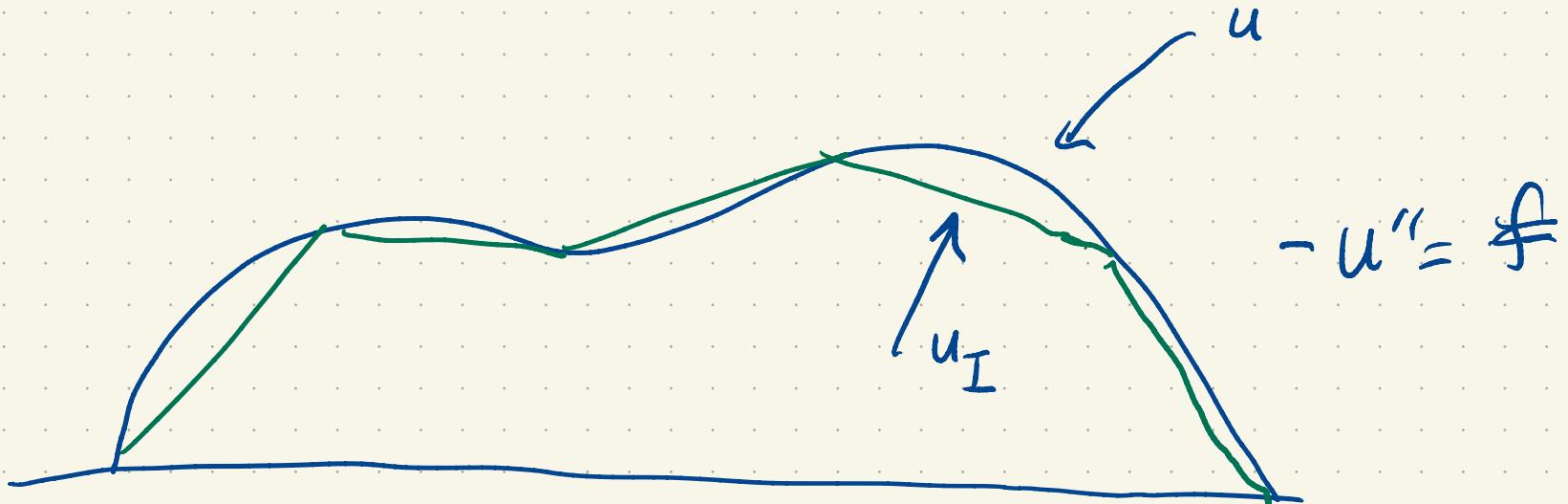
$$\int e_x^h \phi_x = 0 \quad \forall \phi \in \mathcal{V}_h$$

So we can estimate the error by finding anybody in V^h who is close to u .

Reasonable choice: the linear interpolant:



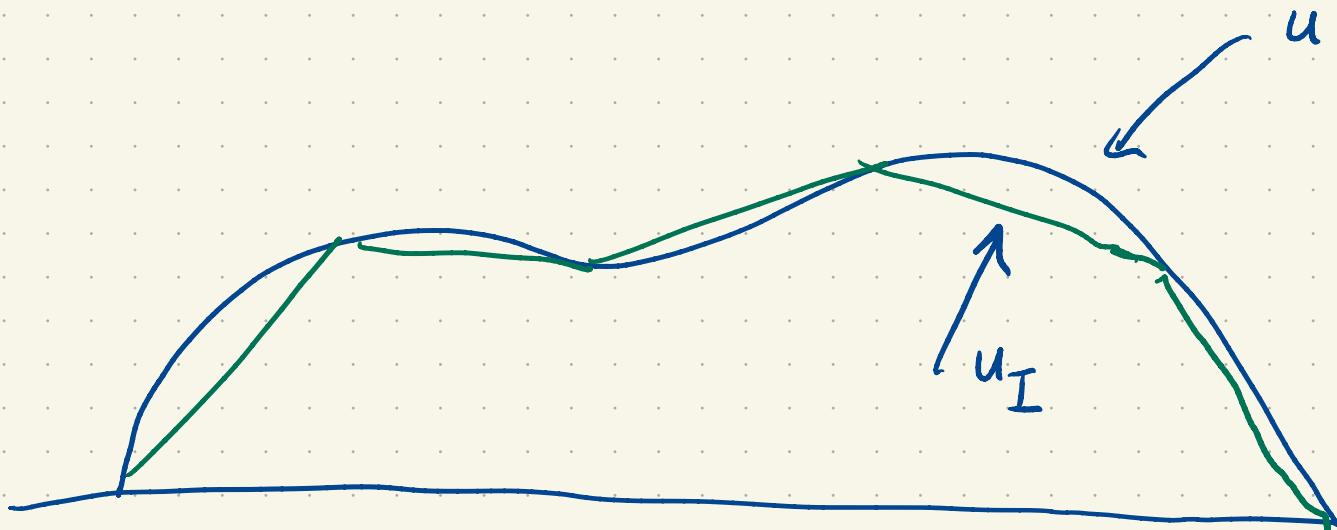
Reasonable choice: the linear interpolant:



Facts: $\|u_I - u\|_{H_0^1} \leq C h \|u''\|_{L^2}$

$$\left([u] [x]^{-1} [x]^2 \right)^{1/2} \quad \times \left((([u] [x]^{-2}) [x])^2 \right)^{1/2}$$

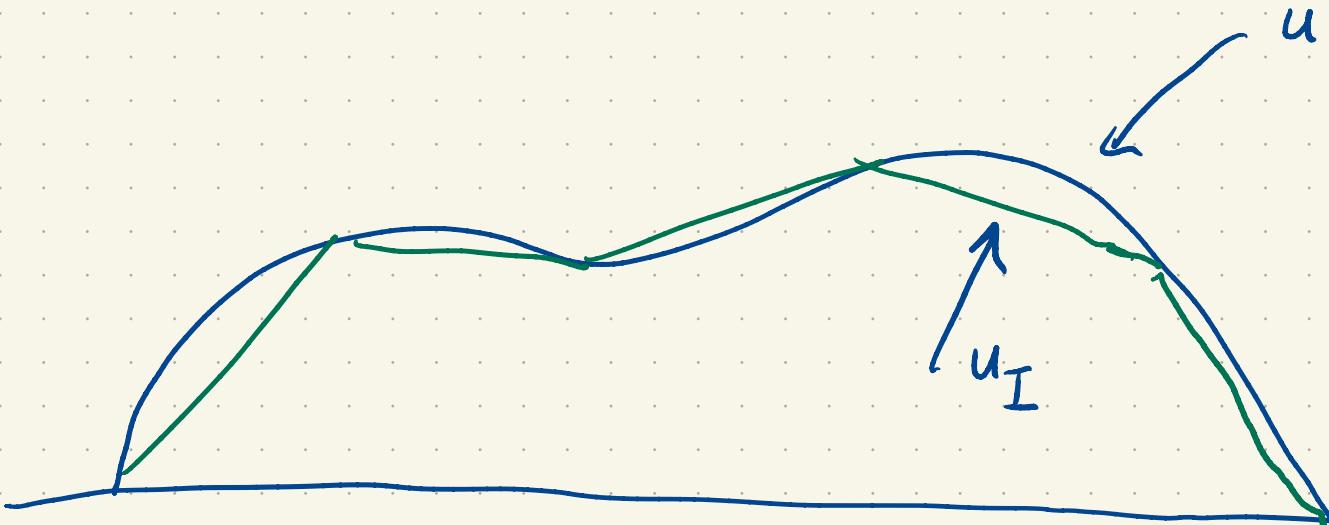
Reasonable choice: the linear interpolant:



Facts: $\|u_I - u\|_{H_0^1} \leq C h \|u''\|_{L^2}$

$$\max |u_I - u| \leq C h^2 \max |u''|$$

Reasonable choice: the linear interpolant:

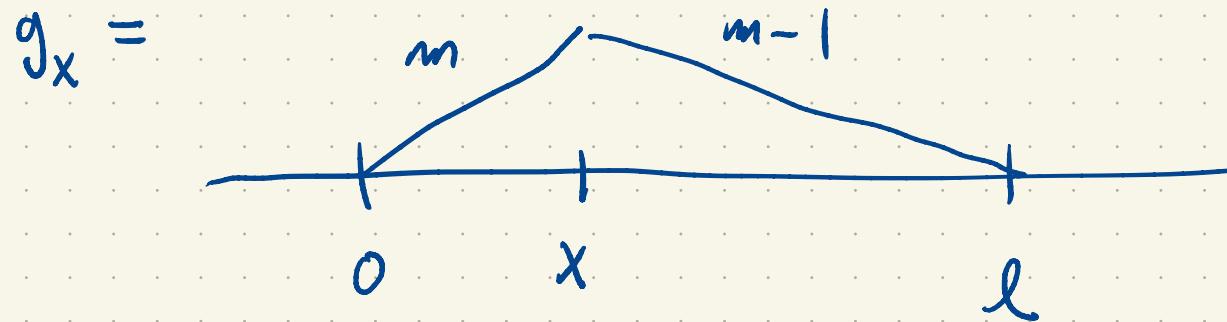


Facts:

$$\|u_I - u\|_{H_0^1} \leq C h \|u''\|_{L^2}$$
$$\max |u_I - u| \leq C h^2 \max |u''|$$

$$\|u^h - u\|_{H_0^1} \leq \|u_I - u\|_{H_0^1} \leq C h \|u''\|_{L^2}^f$$

$u^h \rightarrow u$ $O(h)$ in H_0^1 norm



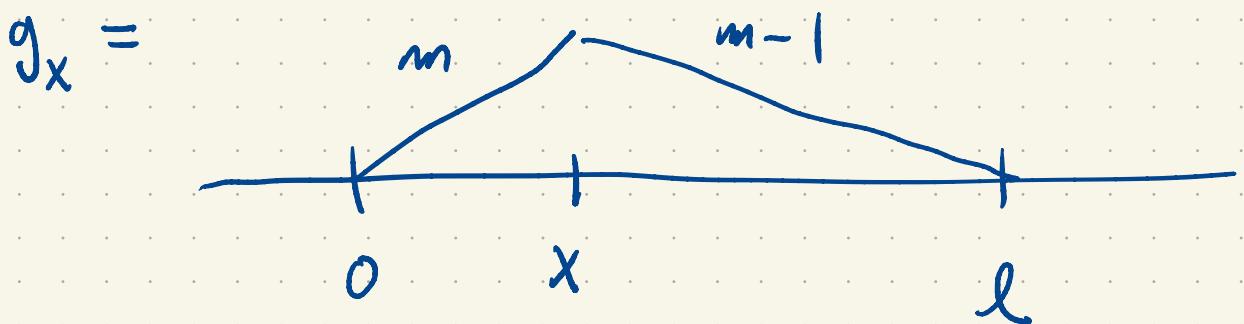
$$-g''_x = \delta \quad (\text{Baby Green's Function!})$$

$$U_h \rightarrow U \quad O(h)$$

$$\Gamma \in H_0^1$$

$$O(h^2)$$

$\|u\|_{H_0^1}$
max
norm.



$$-g''_x = \delta$$

$$(u_h - u)(x_i) = \int (u - u_h)'(s) \ g'_{x_i}(s) \ ds$$

$$= 0 \quad \text{since} \quad g_{x_i} \in \mathcal{V}_h$$

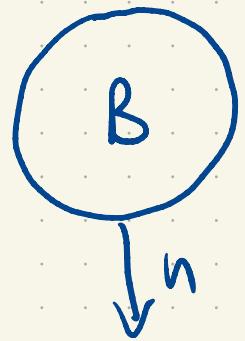
$$u_h \triangleq \text{linear interpolant}, \quad \max |u_h - u| \leq C h^2 \max |f|$$

Elliptic Problems in Higher Dimensions

$\partial_x^4 u$

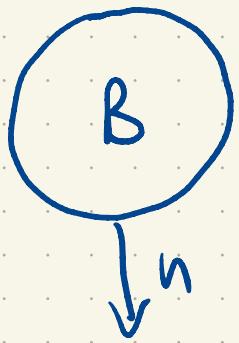
Heat flux is proportional to ∇u ,

points in opposite direction.



$$\text{Flux} : -k \nabla u.$$

Elliptic Problems in Higher Dimensions



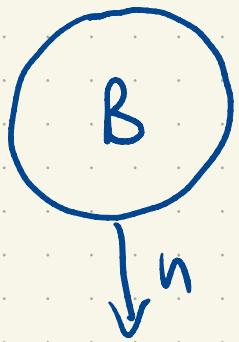
Heat flux is proportional to ∇u ,

points in opposite directions.

$$\text{Flux} = -K \nabla u.$$

$$\text{Net flux: } \int_{\partial B} -K \nabla u \cdot \hat{n} = - \int_B \operatorname{div}(K \nabla u)$$

Elliptic Problems in Higher Dimensions



Heat flux is proportional to ∇u ,

points in opposite directions.

$$\text{Flux} = -K \nabla u.$$

$$\text{Net flux: } \int_B -K \nabla u \cdot \vec{n} = - \int_B \operatorname{div}(K \nabla u)$$

(leaving)

$$\frac{d}{dt} \int_B u = + \int_B \operatorname{div}(K \nabla u)$$

Heat-equation

$$u_t = \Delta (k u_x)$$

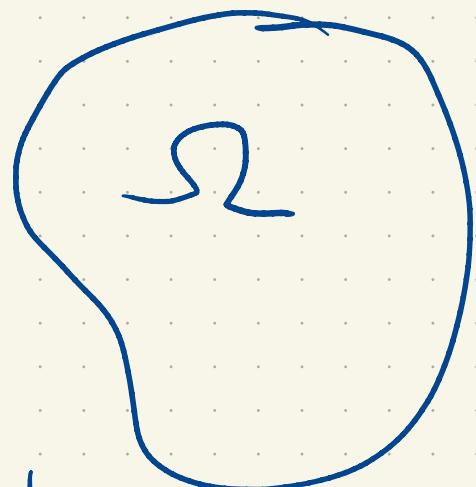
$$u_t = \operatorname{div} (k \nabla u)$$

Steady state: $\operatorname{div} (k \nabla u) = 0$

(k constant: $\Delta u = 0$)

$$\left. \begin{array}{l} \Delta u = 0 \\ u|_{\partial\Omega} = g \end{array} \right\}$$

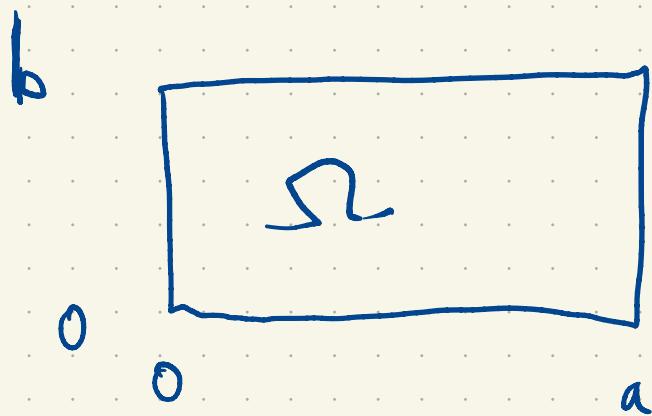
Basic
Dirichlet
problem.



Poisson Equation:

$$-\Delta u = f$$

$$u|_{\partial\Omega} = 0$$



Poisson Equation:

$$-\Delta u = f$$

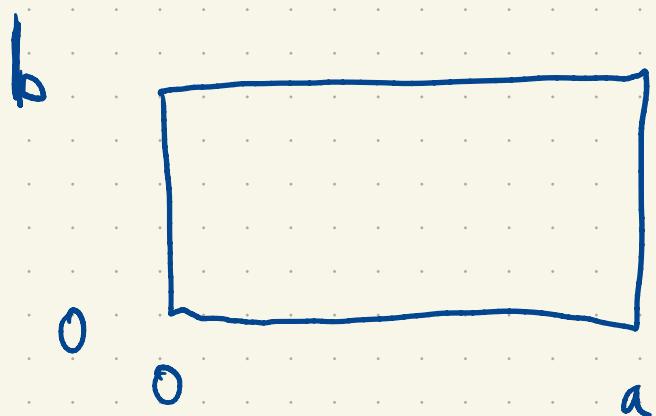
$$u|_{\partial\Omega} = 0$$

$$k, l=1, 2, 3 \dots$$

$$-\Delta u = \lambda u$$

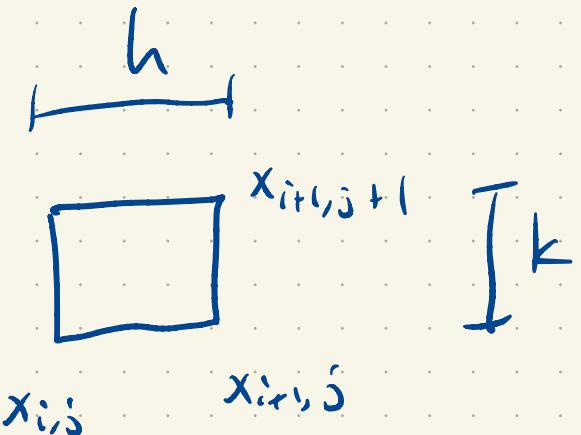
$$u = \sin\left(k\pi\frac{x}{a}\right) \sin\left(l\pi\frac{y}{b}\right)$$

$$\lambda = \pi^2 \left[\left(\frac{k}{a}\right)^2 + \left(\frac{l}{b}\right)^2 \right]$$



Numerical Strategy:

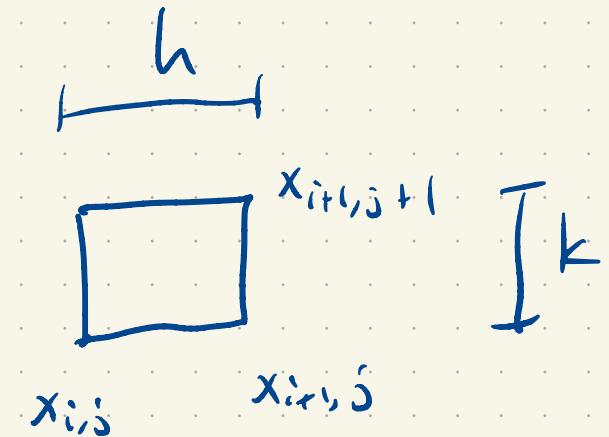
Centered Differences.



$$0 \leq i \leq N-1 \quad 0 \leq j \leq M+1$$

Numerical Strategy:

Centered Differences.



$$0 \leq i \leq N, 0 \leq j \leq M$$

$$-\Delta u \approx \frac{-u_{i+1,j} + 2u_{i,j} - u_{i-1,j}}{h^2} + \frac{-u_{i,j+1} + 2u_{i,j} - u_{i,j-1}}{k^2}$$

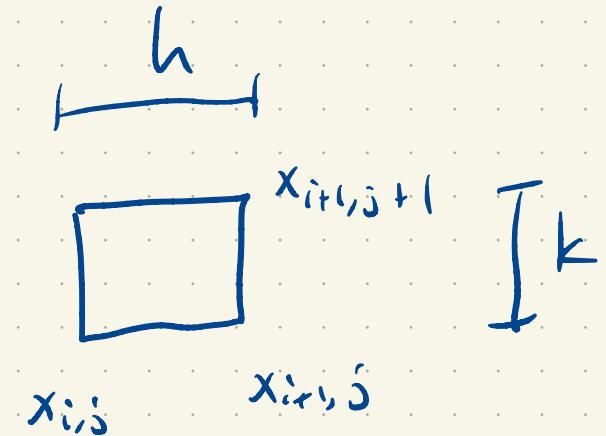
$$-\Delta u = -\partial_x^2 u - \partial_y^2 u \approx -u_{xx} - u_{yy}$$



Numerical Strategy:

$$-\Delta u = f \uparrow \\ f(x_{i,j})$$

Centered Differences.



$$0 \leq i \leq N, 0 \leq j \leq M$$

$$-\Delta u \approx \frac{-u_{i+1,j} + 2u_{i,j} - u_{i-1,j}}{h^2} + \frac{-u_{i,j+1} + 2u_{i,j} - u_{i,j-1}}{k^2}$$

$$= \frac{1}{h^2} \left[-\lambda^2 (u_{i+1,j} + u_{i-1,j}) + 2(1+\lambda^2) u_{i,j} - (u_{i,j-1} + u_{i,j+1}) \right]$$

$$\lambda = \frac{k}{h} \quad (\beta = 2(1+\lambda^2))$$