

The null space of a matrix

Recall that the columns of a matrix A are linearly independent if and only if the only solution of $Ax=0$ is $x=0$.

Well, what if there are interesting (nonzero) solutions of $Ax=0$?

This can only happen if the columns of A are not linearly independent (i.e. they are linearly dependent)

This is rare when A is tall or square

but always happens when A is wide.

Def: The null space of A is the set

$N(A)$ of all vectors x with $Ax = 0$.

(kernel)

$\boxed{0 \in N(A)}$

If $N(A) = \{0\}$

I'll say "the null space
is trivial"

Why care?

$$\begin{bmatrix} 1 & 3 & 7 \\ 2 & 4 & 10 \end{bmatrix} x = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

↑
A

one solution: $x = \begin{bmatrix} 4 \\ -1 \\ 0 \end{bmatrix}$

Consider $v = \begin{bmatrix} 1 \\ 2 \\ -1 \end{bmatrix}$ $A_v = 0$ $v \in N(A)$

Consider $x + v = \begin{bmatrix} 5 \\ -1 \\ -1 \end{bmatrix}$ $A(x+v) = Ax + Av$
 $= \begin{bmatrix} 1 \\ 4 \end{bmatrix} + 0$

$$A(x+2v) = \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

Principle 1) $c\mathbf{v} \in N(A)$ for all numbers c .

$$A\mathbf{v} = \mathbf{0} \quad A(c\mathbf{v}) = cA\mathbf{v} = c\mathbf{0} = \mathbf{0}.$$

2) If $A\mathbf{x} = \mathbf{b}$ and if $\mathbf{Av} = \mathbf{0}$

$$\text{then } A(\mathbf{x} + \mathbf{v}) = A\mathbf{x} + A\mathbf{v} = \mathbf{b}.$$

Identify: want to solve $A\mathbf{x} = \mathbf{b}$ $N(A)$ is
not trivial

1) Find one solution $\hat{\mathbf{x}}$

2) Determine all the things in $N(A)$

Every solution is $\hat{\mathbf{x}} + \mathbf{v}$ with $\mathbf{v} \in N(A)$,

$$\begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

$$N(A) = \mathbb{R}^2$$

↓
 \mathbb{R}^2

$$\begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 0$$

$$N(A) = \left\{ c \begin{bmatrix} 1 \\ -1 \end{bmatrix} : c \in \mathbb{R} \right\}$$

In general:

1) Suppose for some matrix A and some b
that x solves $Ax = b$.

For all $v \in N(A)$ $A(x+v) = b$ as well.

$$(A(x+v) = Ax + Av = b + 0 = b).$$

2) Suppose x_1 and x_2 are solutions of $Ax = b$.

Then let $v = x_2 - x_1$.

$$\begin{aligned} \text{Then } Av &= A(x_2 - x_1) = Ax_2 - Ax_1 \\ &= b - b = 0. \end{aligned}$$

So $v \in N(A)$. So $x_2 = x_1 + v$

with $v \in N(A)$.

$$Ax=0$$

That is: All solutions of $Ax=b$

are of the form $\hat{x} + v$

where \hat{x} is one solution and

where $v \in N(A)$ is arbitrary.

Some null spaces:

$$A = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \quad N(A) = ?$$

$$\begin{bmatrix} 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = 0 \quad x_1 = 0$$
$$N(A) = \left\{ \begin{bmatrix} 0 \\ x_2 \\ x_3 \end{bmatrix} : x_2, x_3 \in \mathbb{R} \right\}$$

It's a plane.

A 3D coordinate system is shown with three axes: e_1 (vertical), e_2 (horizontal), and e_3 (depth). A green plane represents the null space $N(A)$, which is the set of all vectors $\begin{bmatrix} 0 \\ x_2 \\ x_3 \end{bmatrix}$ where $x_2, x_3 \in \mathbb{R}$. This plane is perpendicular to the e_1 -axis at the origin.

$$x = \begin{bmatrix} 5 \\ 0 \\ 0 \end{bmatrix}$$

$$Ax = 5$$

$$A = \begin{bmatrix} 1 & 0 & 0 \end{bmatrix}$$

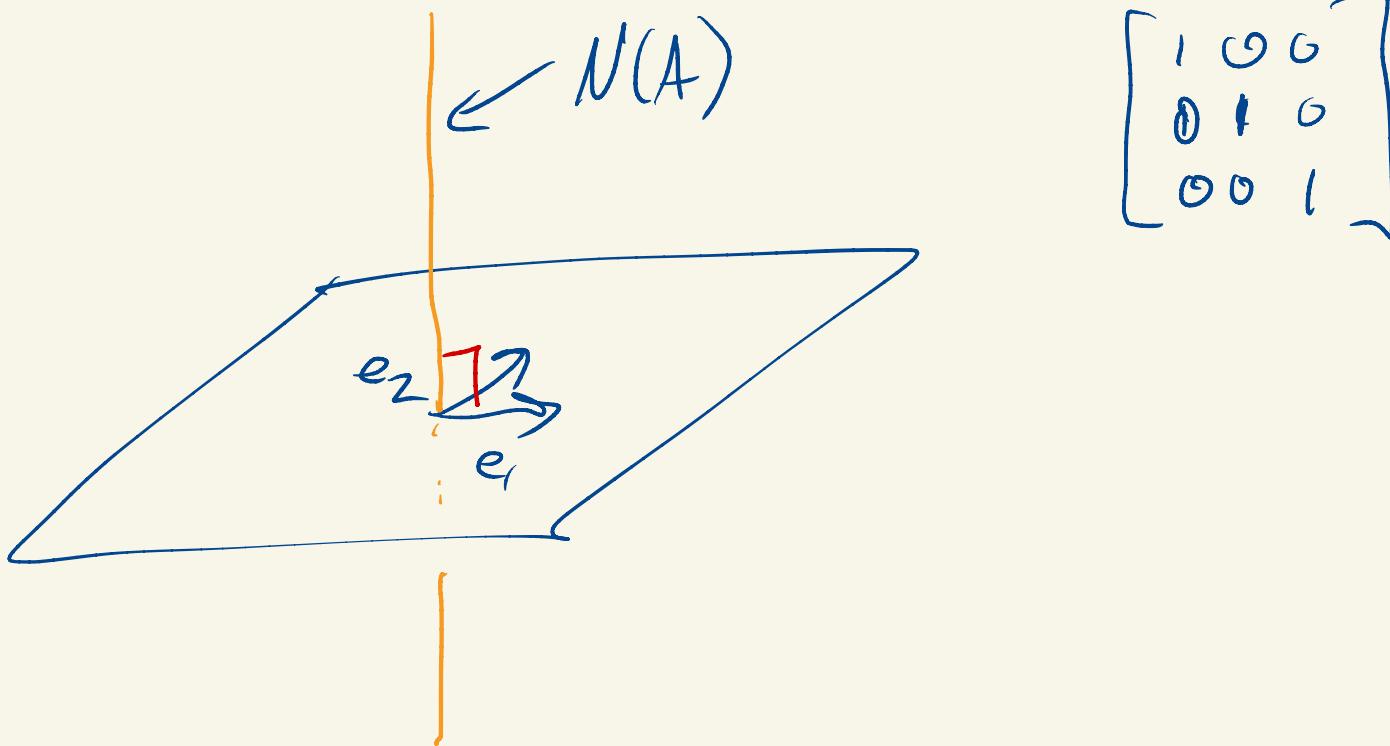
$$x = \begin{bmatrix} 5 \\ x_2 \\ x_3 \end{bmatrix}$$

$$Ax = 5$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \quad N(A) = ?$$

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

$$N(A) = \overbrace{\{(0, 0, x_3) : x_3 \in \mathbb{R}\}}^{(0, 0, 1)}$$



$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Observations:

The null space of A is the set of vectors that are perpendicular to all the rows of A . (By def)

Structure: Suppose $v_1, v_2 \in N(A)$

Then

$$1) v_1 + v_2 \in N(A)$$

$$A(v_1 + v_2) = Av_1 + Av_2 = 0 + 0 = 0$$

$$2) cv_1 \in N(A) \text{ for all numbers } c.$$

$$A(cv_1) = c(Av_1) = c0 = 0.$$

$$\alpha v_1 + \beta v_2 \in N(A)$$

A collection of vectors satisfies 1) and 2) above

If we want to solve $Ax = b$

then $\hat{x} = A^+b$ is a solution.

But there are many solutions.

\hat{x} has the smallest norm of all the
solutions of $Ax = b$.

