

Now 3 space dimensions.

We'll assume coordinate transformations are affine
(so non-acceleration is preserved).

We'll assume that if one observer says E and F
lie on the path of a non accelerating particle
traveling at the speed of light, all observers
say so.

$$\begin{aligned} E &= (t_0, x_0) \rightarrow |c\Delta t| = |\Delta x| \\ F &= (t_1, x_1) \quad |c\Delta t'| = |\Delta x'| \end{aligned}$$

Let us deal with linear case first

$$\begin{pmatrix} t' \\ x' \end{pmatrix} = A \begin{pmatrix} t \\ x \end{pmatrix}$$

↓
 $C^{-1}LC$

$$C = \begin{bmatrix} c_{11} & c_{12} \\ c_{21} & c_{22} \end{bmatrix}$$

F lies on path of a photon from O :

$$c|t| = |x|$$

$$c^2(t)^2 = |x|^2$$

$$(CF)^T G CF = O \quad G = \begin{bmatrix} 1 & & \\ -1 & 1 & \\ & -1 & 1 \end{bmatrix}$$

We require

$$(CAF)^T G CAF = O$$

$$\text{whence } (CF)^T G CF = O$$

$$A = C^T L C \quad (CF)^T L^T G L CF = O \quad \underbrace{\text{whence}}_{\uparrow}$$

I.e. $X^T L^T G L X = O \quad \text{whence}$

$$X^T G X = O \quad (X = CF)$$

$$\text{e.g.: } X = \begin{bmatrix} 1 \\ U \end{bmatrix} \quad |U|^2 = 1$$

$$L^T G L = \begin{bmatrix} \alpha & a \\ a & S \end{bmatrix} \quad \text{for some } \alpha, a, S \in \mathbb{R}^2$$

(why?)

$$\begin{aligned} X^T L^T G L X &= \alpha + 2a \cdot U + U^T S U \\ &= U^T (\alpha I) U + 2a \cdot U + U^T S U \\ &= U^T [\alpha I + S] U + 2a \cdot U \end{aligned}$$

$$\text{So } U^T [\alpha I + S] U + 2a \cdot U = 0 \quad \text{and } |U| = 1$$

$$U \rightarrow -U \quad U^T [\alpha I + S] U - 2a \cdot U = 0 \quad \text{also } 0$$

So $a \cdot U = 0$ for all unit vectors U ,

and therefore all vectors. So $a \cdot a = 0$ and $a = 0$.

Also:

$$U^T [\alpha I + S] U = 0 \text{ for all unit vectors } U.$$

But any $w = \lambda U$, U a unit vector, so

$$W^T [\alpha I + S] W = \lambda^2 U^T [\alpha I + S] U = 0$$

for all vectors $W \in \mathbb{R}^3$.

$B(W, Y) = W^T [\alpha I + S] Y$ is bilinear and

agrees on diagonal with 0. So $W^T [\alpha I + S] Y = 0$

for all vectors W, Y . So $\alpha I + S = 0$ (use e_i, e_j).

$$\text{So } S = -\alpha I$$

We conclude: $a = 0$ ($a \cdot a = 0!$)

$$S + \alpha I = 0, \quad S = -\alpha I$$

(polarization)

$$L^T G L = \alpha \begin{bmatrix} 1 & \\ & -I \end{bmatrix} = \alpha G.$$

Now $L = \begin{bmatrix} \gamma & - \\ 1 & \gamma \end{bmatrix}$

$$L \begin{bmatrix} ct \\ 0 \\ \vdots \\ 0 \end{bmatrix} = \underbrace{\begin{bmatrix} \gamma \\ 1 \end{bmatrix}}_{\text{path of } O.} ct$$

$$ct' = \gamma ct$$

↑ encodes time dilation.

Relativity hypothesis: time dilation between the two coordinate systems is the same.

$$L^{-1} = \begin{bmatrix} \gamma & - \\ 1 & \gamma \end{bmatrix} \text{ also, for other stuff.}$$

$$L^T G L = \alpha G \Rightarrow$$

$$L^T = \alpha G L^{-1} G$$

↑
upper left
entry is γ

$$G \begin{bmatrix} \gamma \\ * \end{bmatrix} = \begin{bmatrix} \gamma \\ -* \end{bmatrix}$$

↑
upper left entry is $\alpha \gamma$

$$\text{So } \alpha = 1.$$

We assumed:

- 1) Linear
- 2) path of photons preserved
- 3) relativity of time dilation

$$\begin{bmatrix} u \\ x' \end{bmatrix} \rightarrow A \begin{bmatrix} u \\ x \end{bmatrix} \quad A = C^{-1} L C \quad L^T G L = G$$



These are the
(natural) Lorentz transformations.

physical Lorentz transf.

$O(1,3)$: subgroups of $GL(4, \mathbb{R})$ $L^T G L = G$.

[Exercise:

The affine transformations are

$$C^{-1} L C + Z \quad Z \in \mathbb{R}^4$$

$$L \in O(1,3)$$

As in 2-d case, interval:

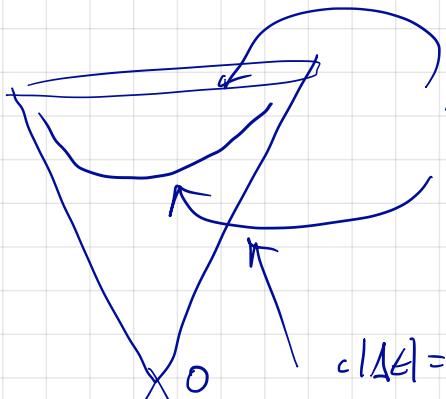
$$X - C(F - E)$$

$$\text{Int}(E, F) = X^T G X \quad ((\Delta t)^2 - (\Delta x)^2 - (\Delta y)^2 - (\Delta z)^2)$$

physical Lorentz transformations preserve interval in
physical coords

when

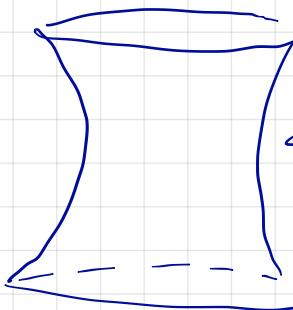
natural coords



interval positive

$$\text{interval} = \lambda^2 \quad (\text{proper time d-SF} \leq \frac{\lambda}{c})$$

$$c|\Delta t| = |\Delta \vec{x}|, \text{ interval is } 0$$



hyperboloid
for

$$\text{int}(O, P) = -1$$

call the
things that
are space
distance 1 from
origin

Def: The future light cone at origin is set of events $E = \left[\begin{smallmatrix} \mathbb{R} \\ x \end{smallmatrix} \right]$ with $\text{Int}(O, E) = 0$ and $x > 0$.

^{4x4}
Def: A matrix L is a Lorentz transf, if

$$L^T G L = G.$$

- a) It is orthochronous if in addition it sends the future light cone at the origin to itself.
- b) It is proper if $\det(L) = 1$.
- c) It is restricted if both proper + orthochronous

a) $O^+(1, 3)$

b) $SO(1, 3)$

c) $SO^+(1, 3)$

Lamma: Let $L \in O(1, 3)$. If L is orthochrrous
then

$$L^{\circ} > 0. \quad (L_{00}; I'll explain why
your book does this later)$$

Pf: $L \begin{pmatrix} 2 \\ \vdots \\ 0 \end{pmatrix} = L \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix} + L \begin{bmatrix} -1 \\ \vdots \\ 0 \end{bmatrix}$

$$= \begin{bmatrix} ct_0 \\ * \end{bmatrix} + \begin{bmatrix} ct_1 \\ * \end{bmatrix}$$

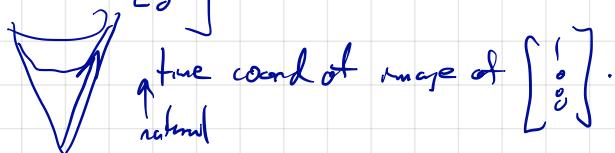
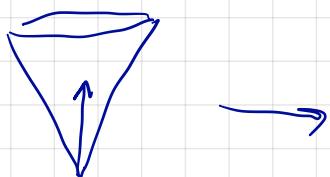
with $\epsilon_0, \epsilon_1 > 0$. But $L \begin{pmatrix} 2 \\ \vdots \\ 0 \end{pmatrix} = \begin{pmatrix} 2L^{\circ} \\ * \end{pmatrix}$.

$\therefore 2L^{\circ} = c(\epsilon_0 + \epsilon_1) > 0$.

In fact, the converse is true; we'll wait a bit for
this. But in the mean time, o.c. $\Leftrightarrow L^{\circ} > 0$ is fine.

Meaning of $L^{\circ}:$

$$L \begin{bmatrix} 1 \\ \vdots \\ 0 \end{bmatrix} = \begin{bmatrix} L^{\circ} \\ L^{\circ} \\ L^{\circ} \\ L^{\circ} \end{bmatrix}$$



e.g.

$$\mathcal{L}_4 = \begin{bmatrix} C & S \\ S & -C \\ 0 & 0 \\ 0 & I \end{bmatrix}$$

(boost in $x-t$ plane)

$$C > 0, \det \leq (C^2 - S^2) \cdot 1^2 = 1.$$

e.g.

$$\begin{bmatrix} 1 & 0 \\ 0 & H \end{bmatrix} + H \in SO(3)$$

$$\begin{bmatrix} 1 & 0 \\ 0 & H^\top \end{bmatrix} \underbrace{\begin{bmatrix} +1 & 0 \\ 0 & -I \end{bmatrix}}_{\text{det } \leq 1} \begin{bmatrix} 1 & 0 \\ 0 & H \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & -H \end{bmatrix} \checkmark$$

$$\det \leq 1 \cdot \det(H) = 1$$

$$1 > 0,$$

1.7.

v any unit vector in \mathbb{R}^3

K any element of $SO(3)$, $K e_1 = v$

$$\begin{bmatrix} v & | & \dots & | \end{bmatrix}$$

$$L = \begin{bmatrix} 1 & 0 \\ 0 & K \end{bmatrix} \mathcal{L}_K \begin{bmatrix} 1 & 0 \\ 0 & K^T \end{bmatrix}$$

exercise: if $w \in \mathbb{R}^3$, $w \cdot v = 0$

$L \begin{bmatrix} 0 \\ w \end{bmatrix} = 0$. As for v , this is a boost in the $v-t$ plane.

More generally:

$$\begin{pmatrix} 1 & 0 \\ 0 & H \end{pmatrix} \mathcal{L}_H \begin{bmatrix} 1 & 0 \\ 0 & K^T \end{bmatrix} \quad H, K \in SO(3)$$

Exercise (next Hw?)

$$L \in SO^+(1,3) \Leftrightarrow L = \begin{bmatrix} 1 & \\ & H \end{bmatrix} \mathcal{D}_x \begin{bmatrix} 1 & \\ & K^T \end{bmatrix}$$

for some $\mathbf{x} \in \mathbb{R}^3$, $H \in BO(3)$, $K \in SO(3)$.

They are compositions of spatial rotations and boosts.

(4)-vectors