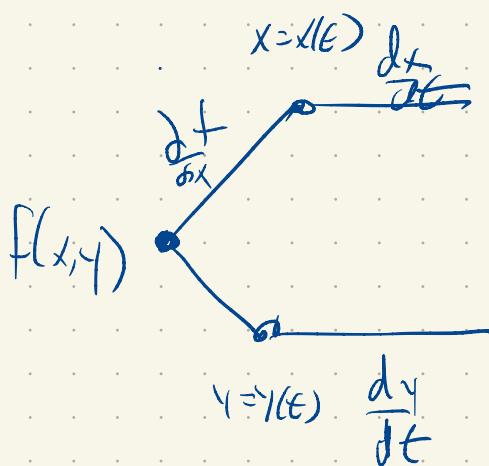


$$\frac{dy}{dt} = \sin \theta \frac{dx}{dt} + \cos \theta \frac{d\theta}{dt}$$

Chain rule applies to each u term.

So we'll focus on the case of one output variable.



$$\frac{df}{dt} = \frac{\partial f}{\partial x} \frac{dx}{dt} + \frac{\partial f}{\partial y} \frac{dy}{dt}$$

x

y

f

What if f depends on x, y but

$$x = x(u,v)$$

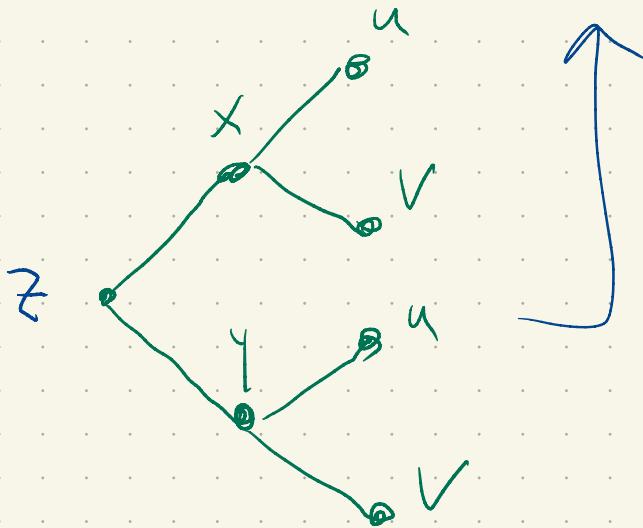
?

$$y = y(u,v)$$

$$z = f(x(u,v), y(u,v))$$

$$\frac{\partial z}{\partial u} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial u} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial u}$$

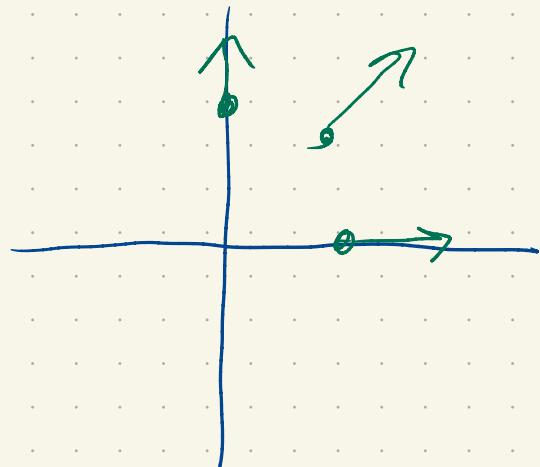
$$\frac{\partial z}{\partial v} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial v} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial v}$$



$$h(x, y) = xy$$

$$x = r \cos \theta$$

$$y = r \sin \theta$$



$$\frac{\partial h}{\partial r} = \frac{\partial h}{\partial x} \frac{\partial x}{\partial r} + \frac{\partial h}{\partial y} \frac{\partial y}{\partial r}$$

$$= y \cos \theta + x \sin \theta$$

$$= r \sin \theta \cos \theta + r \cos \theta \sin \theta$$

Directional Derivatives + the Gradient

$$T(x,y) \quad \vec{r}(t) = \langle x(t), y(t) \rangle$$

$$\frac{d}{dt} T(\vec{r}(t)) = \frac{\partial T}{\partial x} \frac{dx}{dt} + \frac{\partial T}{\partial y} \frac{dy}{dt} \quad (\text{chain rule})$$

$$\vec{r}'(t) = \left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle$$

$$w = \langle a, b \rangle$$

$$w \cdot \vec{r}'(t) = a \frac{dx}{dt} + b \frac{dy}{dt}$$

That is, $\frac{d}{dt} T(\vec{r}(t)) = \left\langle \frac{\partial T}{\partial x}, \frac{\partial T}{\partial y} \right\rangle \cdot \left\langle \frac{dx}{dt}, \frac{dy}{dt} \right\rangle$

We call $\left\langle \frac{\partial T}{\partial x}, \frac{\partial T}{\partial y} \right\rangle$ the gradient of T

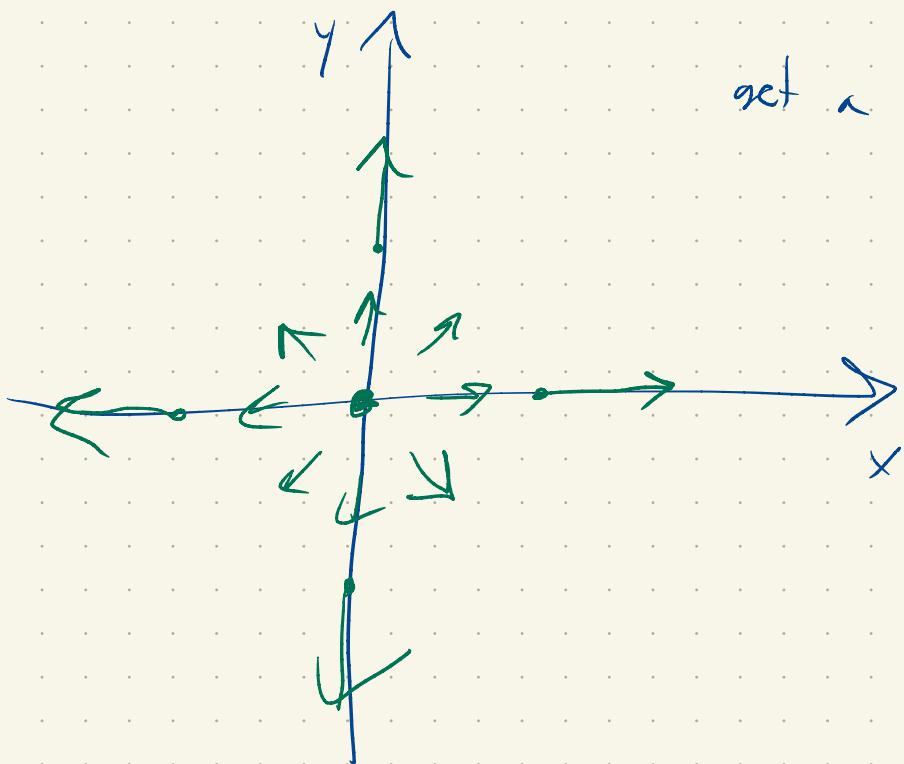
and write it as ∇T .

To set a better sense,

$$T(x,y) = x^2 + y^2$$

$$\nabla T = \langle z_x, z_y \rangle$$

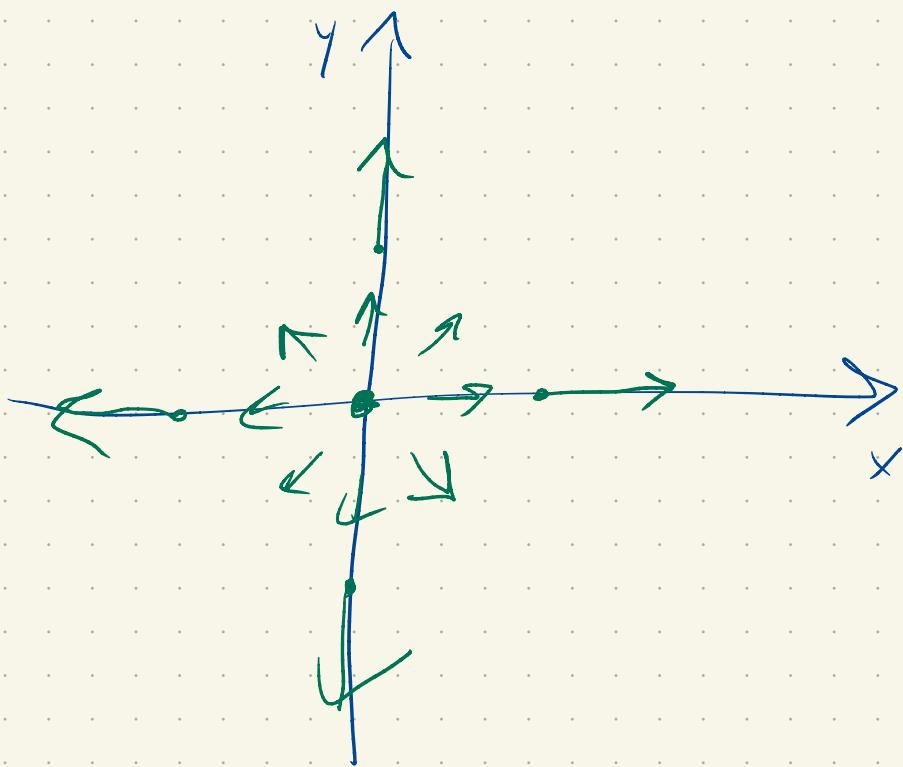
At position $\langle x, y \rangle$
get a vector $(\langle z_x, z_y \rangle)$
In this case,



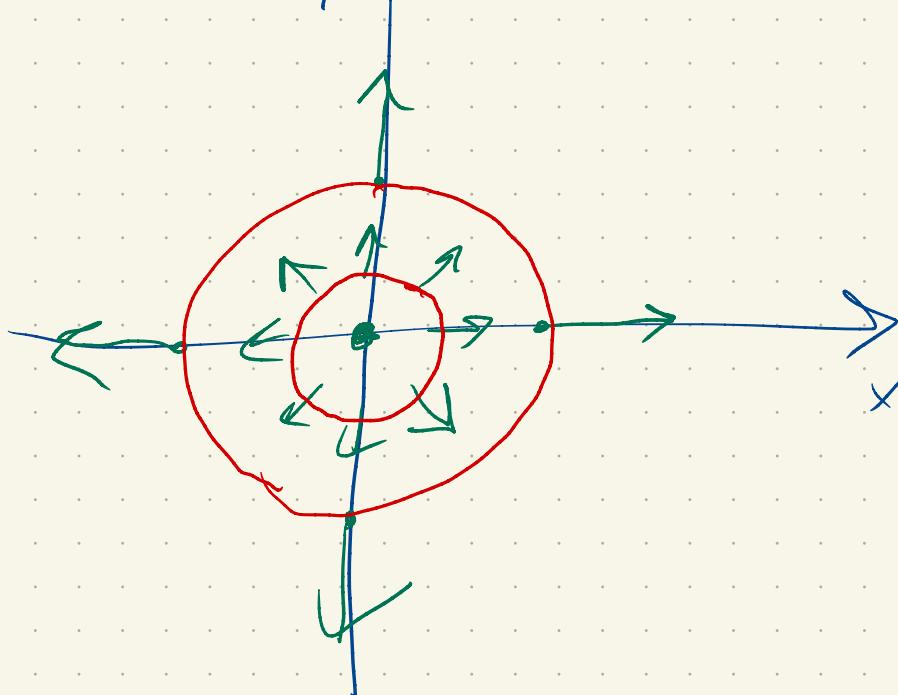
This is the job of Gradient:

If you are travelling with velocity \vec{v} ,

$\nabla T \circ \vec{v}$ tells you the rate of change
you see in T .



Let's add some level sets



And:



Some key points:

- 1) $\vec{\nabla}f = \langle f_x, f_y \rangle$ is a vector field
- 2) It points in the direction of steepest ascent ("up"!)
- 3) It is perpendicular to the level sets of f
- 4) Its length tells you about steepness of the graph
Note that $\nabla f = 0$ at O , the flat part
- 5) Most important: for a curve $\vec{r}(t)$ in x - y space,
 $\nabla f \cdot \vec{r}'$ tells you about the rate of change of f along the curve.

5) Was how we introduced it.

Why 3)?



If f is a curve on a level set, $f \circ \vec{r}(t)$ is const.

$$\text{so } \frac{d}{dt} f(\vec{r}(t)) = 0$$

$$\nabla f \cdot \vec{r}'(t)$$

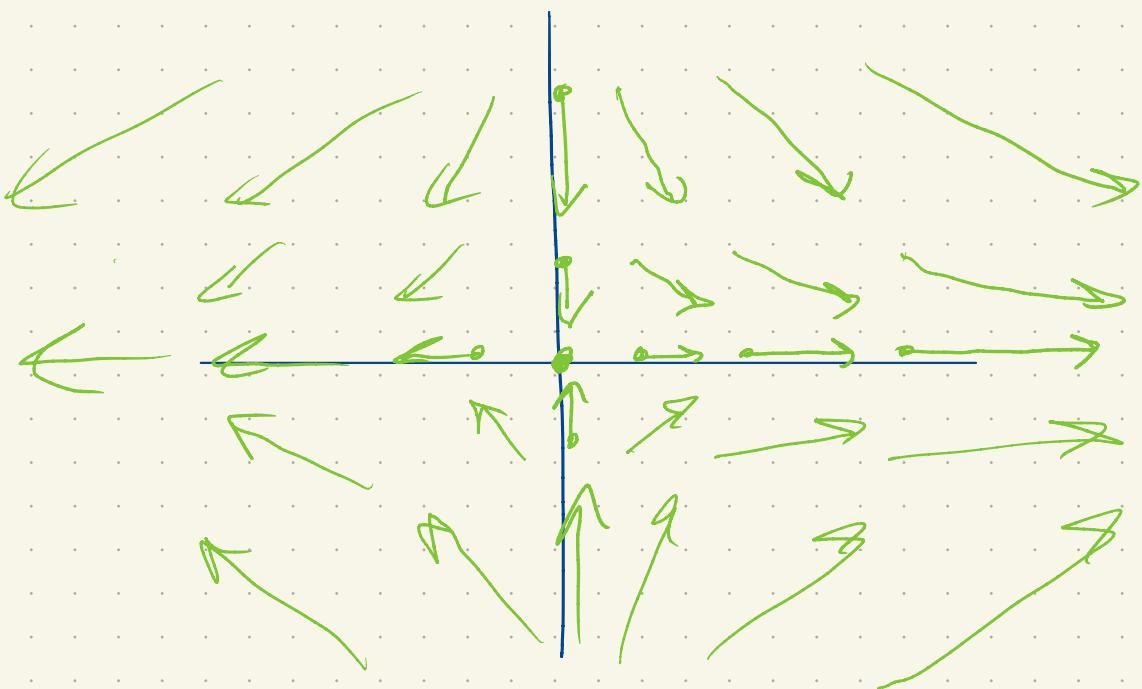
We'll come back to 2) shortly

Another example:

$$h(x, y) = x^2 - y^2 \quad (\text{saddle})$$

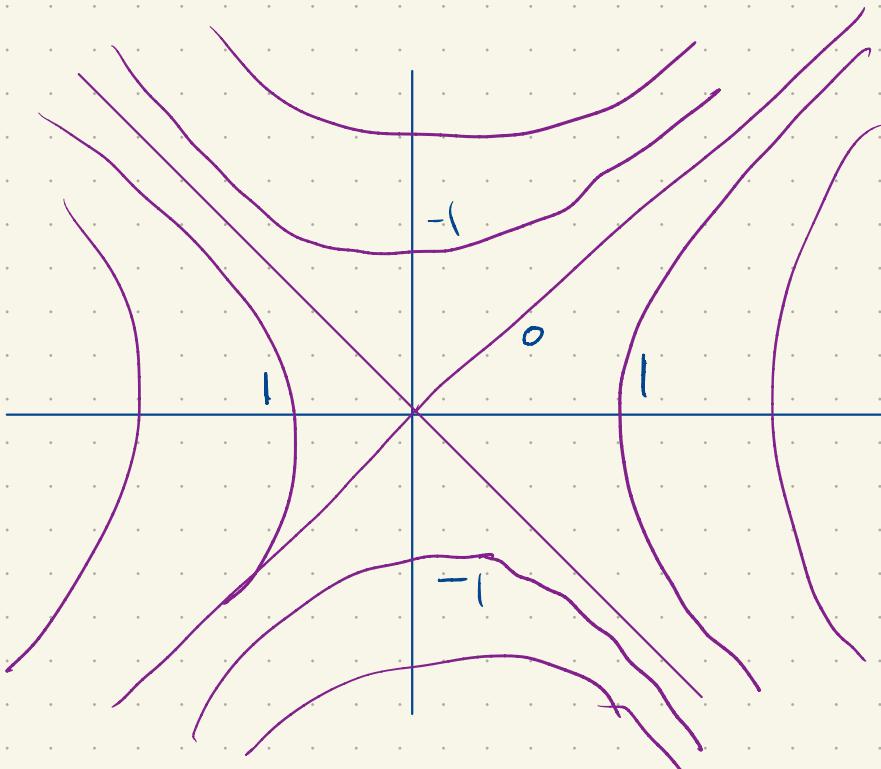
$$\vec{\nabla} h = \langle 2x, -2y \rangle$$

$$\vec{\nabla} h$$

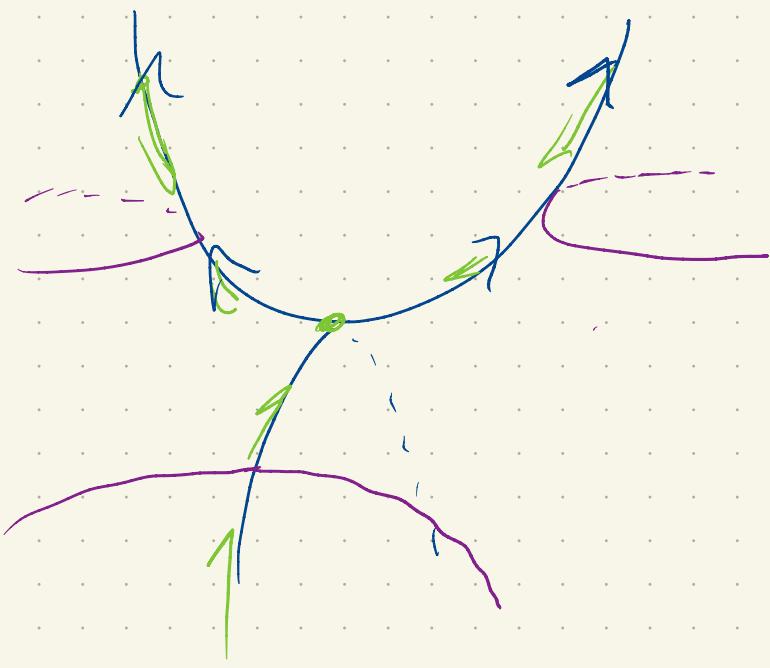


Note:

$\nabla h = 0$
at the
saddle
point.

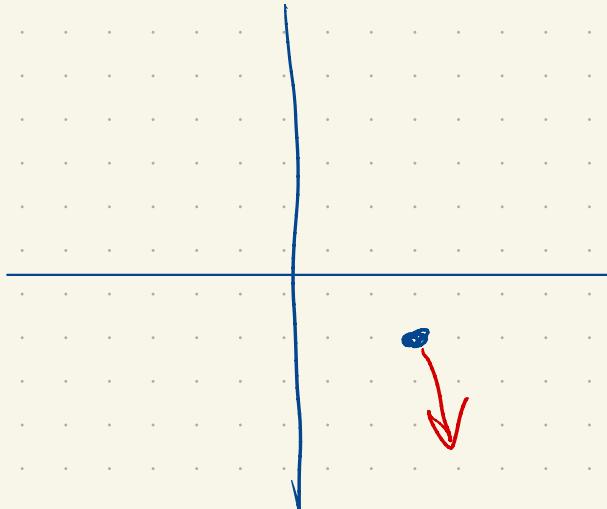


level sets



What is rate of change of h at tangents

with velocity $\langle 1, -2 \rangle$ at $x=3, y=-1$



$$\vec{\nabla}h = \langle 2x, -2y \rangle$$

$$= \langle 6, 2 \rangle \quad (\text{at } 3, -1)$$

$$\vec{\nabla}h \cdot \vec{v} = \langle 6, 2 \rangle \cdot \langle 1, -2 \rangle$$

$$= 6 - 4 = 2$$

Some justifications:

$$\vec{\nabla}f \cdot \vec{v} = \|\vec{\nabla}f\| \|\vec{v}\| \cos\theta$$

So if $\|\vec{v}\|=1$, then $\vec{\nabla}f \cdot \vec{v}$ is biggest if $\cos\theta=1$
 $\theta=0$.

and most negative if $\cos\theta=-1$, $\theta=\pi$.

If $\cos\theta=0$, $\vec{\nabla}f \cdot \vec{v}=0$,

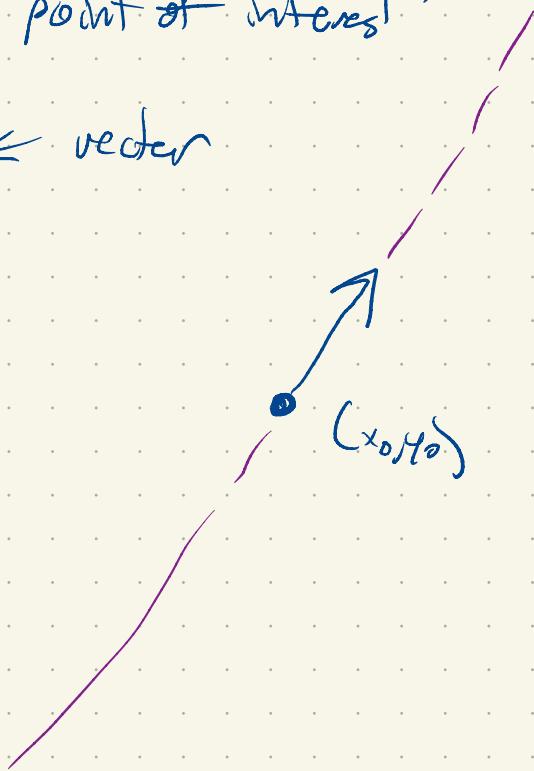
A related notion: directional derivatives.

(so related it'll be confusing at first)

$$f(x, y)$$

$(x_0, y_0) \leftarrow$ point of interest

$\vec{v} = \langle v_x, v_y \rangle \leftarrow$ vector



If I travel along this line, with the given velocity,
what is the observed rate of change of f ?

$$\frac{d}{dt} \Big|_{t=0} f(x_0 + tv_x, y_0 + tv_y) := D_{\vec{v}} f(x_0, y_0)$$

"Directional derivative of f at (x_0, y_0) along \vec{v} "

Note: your book only allows \vec{v} to be a unit vector, which is silly.

$$P = 83 \text{ T/V}$$

$$\frac{1}{\|k\|} \vec{e}$$

Now if you've been paying attention

$$D_{\vec{r}} f = \vec{\nabla} f \cdot \vec{r}$$

almost. There are functions which have directional derivatives in all directions but for which this formula is false.

$$f(x, y) = \begin{cases} \frac{x^2 y}{x^2 + y^2} & (0 \text{ at origin}) \\ 0 & \text{otherwise} \end{cases}$$

$$(x_0, y_0) = (0, 0)$$

$$v = (v_x, v_y)$$

$$f(tv_x, tv_y) = \frac{t^3 v_x^2 v_y}{t^2 (v_x^2 + v_y^2)}$$

$$= t \frac{v_x^2 v_y}{v_x^2 + v_y^2}$$

$$\nabla_{\vec{v}} f = \frac{4x^2y}{\sqrt{x^2+y^2}} \quad \text{But} \quad f=0 \text{ on axes}$$

$$\frac{\partial f}{\partial x} = 0, \quad \frac{\partial f}{\partial y} = 0,$$

$$\frac{x^2}{x^2+y^2} - \frac{2x^2y^2}{(x^2+y^2)^2} = \frac{x^4 - x^2y^2}{(x^2+y^2)^2}$$

along $y=x \rightarrow 0$

along $y=2x$

$$13 \quad \frac{x^4 - 4x^4}{4x^4}$$

$$-\frac{3}{4}$$

Functions for which the tangent plane approx is good are called diff. For a diff function

$$D_{\vec{v}} f = \vec{\nabla} f \cdot \vec{v}. \quad \text{And}$$

If $\frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ exist and are ok

near (x_0, y_0) then f is diff at x_0, y_0 .