

## Diagonal Dominance:

A tridiagonal matrix is diagonal, dominant

$$\text{if } |a_k| \geq |b_k| + |c_k| \quad \forall k$$

and strictly so if the inequality holds

strictly.

$$0 < b_k < a_k < c_k < 0$$

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Thm: Strictly diagonally dominant <sup>tridiagonal!</sup> matrices are  
invertible, and the above algorithm works.

## Rough Motivation:

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- $\begin{bmatrix} \lambda_1 & 0 \\ 0 & \lambda_N \end{bmatrix}$  is invertible if each  $\lambda_k > 0$
- $\det(A) \neq 0$  is an open condition
- perturbations of  $\lambda$  are also invertible

Sadly

$$\begin{bmatrix} -2 & 1 & 0 & \cdots & 0 \\ 1 & -2 & 1 & 0 & \cdots & 0 \\ \vdots & & \ddots & \ddots & 1 & -2 \\ & & & \ddots & 1 & -2 \\ & & & & 1 & -2 \end{bmatrix}$$

Diagonally dominant, but not strictly.

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Strict cannot be relaxed:

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$$\begin{bmatrix} 1 & -1 & 1 \\ -1 & 1 & 0 \\ 0 & 1 & 1 \end{bmatrix}$$

We cannot drop street without adding something else.

We cannot drop strrot without adding something else.

Thm: If  $A$  is tridiagonal and diagonal dominant and

1)  $a_k \neq 0$ ,  $1 \leq k \leq N-1$

2)  $|a_N| > |b_N|$  (strrot at last equation)

then  $A$  is invertible and the  
above algorithm converges.

1)  $c_k \neq 0$ ,  $1 \leq k \leq N-1$

2)  $|a_N| > |b_N|$

$$\begin{bmatrix} -2 & 1 & 0 & \cdots & 0 \\ 1 & -2 & 1 & 0 & \cdots & 0 \\ \vdots & & \ddots & & \ddots & 1 & -2 \\ & & & \ddots & & 1 & -2 \\ & & & & \ddots & & 1 & -2 \end{bmatrix}$$

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$$c_k = 1 \checkmark$$

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$$c_k = 1 \checkmark \quad |-2| > |1| \checkmark$$

$$\text{Step 1: } w = a_1, d_1 = \frac{c_1}{w}, r_1 = \frac{f}{w}$$

$$\text{Step } k: w = a_k - b_k d_{k-1}, d_k = \frac{c_k}{w}, r_k = \frac{f_k - b_k r_{k-1}}{w}$$

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Aim: show  $|d_j| \leq 1$  for all  $j$ .

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$$\text{If so: } |w| = |a_k - b_k d_{k-1}|$$

$$\geq |a_k| - |b_k| |d_{k-1}|$$

$$\geq |a_k| - |b_k|$$

$$\geq |c_k|$$

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$$\geq |a_k| - |b_k| |d_{k-1}|$$

$$\geq |a_k| - |b_k|$$

$$\geq |c_k| > 0 \quad (k \neq N)$$

$$\begin{aligned}|w| &= |a_k - b_k d_{k-1}| \\&\geq |a_k| - |b_k| |d_{k-1}| \\&\geq |a_k| - |b_k| \\&\geq |\zeta_k| > 0 \quad \text{unless } k=N\end{aligned}$$

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 &\geq |a_k| - |b_k| \\
 &\geq |c_k| > 0 \quad \text{unless } k=N
 \end{aligned}$$

If  $|d_{k-1}| \leq 1$  then  $|w| > 0$  and

$$|d_k| = \frac{|c_k|}{|w|} \leq 1.$$

Base case:

$$w = a_1 \quad , \quad d_1 = \frac{c_1}{w} = \frac{c_1}{a_1}$$

$|c_1| \leq |a_1|$  by diagonal

dominance

Base case:

$$w = a_1, \quad d_1 = \frac{c_1}{w} = \frac{c_1}{a_1}$$

$$|c_1| \leq |a_1| \text{ by diagonal}$$

dominance

Final case:

$$w = a_N - b_N d_{N-1}$$

$$|w| \geq |a_N| - |b_N| |d_{N-1}|$$

$$\geq |a_N| - |b_N| > 0.$$

Exercise: Modify the above  
to show strictly diagonally  
dominant matrices are invertible!

## Over system

$$u'' + p u' + q u = f$$

$$b_k = 1 - \frac{p_k h}{2} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{2}$$

Need

- $|a_k| \geq |b_k| + |c_k|$
- $c_k > 0$
- $|a_N| > |b_N|$

## Our system

$$b_k = 1 - \frac{p_k h}{2} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{2}$$

If  $\left| \frac{p_k h}{2} \right| \leq 1$ ,  $|b_k| = b_k$   $|q_k| = c_k$ .

Our system

$$|a_k| \geq |b_k| + |c_k| = 2$$

$$b_k = 1 - \frac{p_k h}{2} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{2}$$

If  $\left| \frac{p_k h}{2} \right| \leq 1$ ,  $|b_k| = b_k$   $|q_k| = c_k$ .

$$b_k + c_k = 2.$$

## OVR system

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$$b_k + c_k = 2.$$

So  $|a_k| > |b_k| + |c_k|$  if

## Over system

$$u'' + pu' + q u = f$$

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$$b_k + c_k = 2.$$

$$\bullet \left| \frac{p_k h}{2} \right| \leq 1$$

$$\text{So } |a_k| > |b_k| + |c_k| \text{ if }$$

$$\bullet q \leq 0$$

## Our system

$$\left| \frac{p_k h}{2} \right| \leq 1, \quad q \leq 0$$

$$b_k = 1 - \frac{p_k h}{2} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{2}$$

Need •  $c_k \neq 0$

## Our system

$$b_k = 1 - \frac{p_k h}{2} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{2}$$

Need

- $c_k > 0$

$$\left| \frac{p_k h}{2} \right| < 1$$

ensures this

↑  
strict now!

## Over system

$$b_k = 1 - \frac{p_k h}{2} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{2}$$

Need

- $|a_N| > |b_N|$

## Over system

$$b_k = 1 - \frac{P_k h}{Z} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{P_k h}{Z}$$

Need

$$\bullet \quad |a_N| > |b_N|$$

$$\left| \frac{P_N h}{Z} \right| < 1$$

$$-2 + q_N$$

vs

$$\boxed{1 - \frac{P_N h}{Z}}$$

$$0 < \uparrow < 2$$

## Over system

$$b_k = 1 - \frac{p_k h}{Z} \quad a_k = -2 + q_k \quad c_k = 1 + \frac{p_k h}{Z}$$

Need

- $|a_N| > |b_N|$

$$-2 + q_k \quad \text{vs} \quad 1 - \frac{p_k h}{Z}$$

$q \leq 0$  and  $\left| \frac{p_k h}{Z} \right| < 1$  ensures this, too

Summary:

$$Lu = f$$

If

- $q \leq 0$
- $\left| \frac{p_k h}{2} \right| < 1$

then  $L = \begin{bmatrix} a_1 & c_1 & & & \\ b_2 & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & c_{N-1} \\ & & b_N & a_N & \end{bmatrix}$  is invertible.

## Summary:

If

- $q \leq 0$

- $\left| \frac{p_k h}{2} \right| < 1$  

convergence condition  
(discrete system approximates  
cts system)

then  $L = \begin{bmatrix} a_1 & c_1 & & & \\ b_2 & \ddots & \ddots & & \\ & \ddots & \ddots & \ddots & c_{N-1} \\ & & b_N & a_N & \end{bmatrix}$  is invertible.

Summary:

$$u'' + p u' + q u = f$$

$$u|_{[0, L]} = 0$$

$$Lu = f$$

PDE condition

If

- $q \leq 0$
- $\left| \frac{p_k h}{2} \right| < 1$

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$[0, \pi]$

Why  $q \leq 0$ ?

$$u_{xx} + q u$$

↑  
negative  
eigenvalues

$$\sin(kx)$$

$$-k^2 \sin(kx)$$

If positive, can create  
a zero eigenvalue.

Why  $\lambda \leq 0$ ?

$$\left( (\partial_x^2 + 1) \sin(x) \right) = 0$$

There is no solution of

$$u_{xx} + u = \sin(x) \quad \text{on } [0, \pi]$$

$$u|_{x=0} = u|_{x=\pi} = 0.$$

Why  $\lambda \leq 0$ ?

$$u_{xx} + u = \sin(x)$$

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$$u_{xx} + u = \sin(x)$$

$$\int_0^{\pi} (u_{xx} + u) \sin(x) dx = \int_0^{\pi} \sin^2(x) dx > 0$$

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$$\int_0^{\pi} -u_x \partial_x \sin(x) + u \sin(x) dx$$

$\downarrow_u$

Why  $\lambda \leq 0$ ?

$$u_{xx} + u = \sin(x)$$

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$$\downarrow$$
$$\int_0^{\pi} -u_x \partial_x \sin(x) + u \sin(x) dx$$

$$\downarrow$$
$$\int_0^{\pi} u \left[ \partial_x^2 \sin x + \sin(x) \right] dx$$

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$$\downarrow$$
$$\int_0^{\pi} u \left[ \partial_x^2 \sin x + \sin(x) \right] dx = 0$$

## Convergence

[consistency + stability  $\Rightarrow$  convergence]

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Consistency:  $\varepsilon = O(h^2) \checkmark$

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[consistency + stability  $\Rightarrow$  convergence]

Consistency:  $\varepsilon = O(h^2)$  ✓

$$u^h - v^h$$

Stability?

$$L^h v^h = f^h$$

$$L^h u^h = f^h + \varepsilon$$

## Convergence

$$\| L^h E^h \|_p \leq \| L^h \|_p \| E^h \|_p$$

[consistency + stability  $\Rightarrow$  convergence]

Consistency:  $\varepsilon = O(h^2)$  ✓

Stability?

$$L^h U^h = f^h$$

$$L^h u^h = f^h + \varepsilon$$

$$L^h (u^h - U^h) = \varepsilon$$