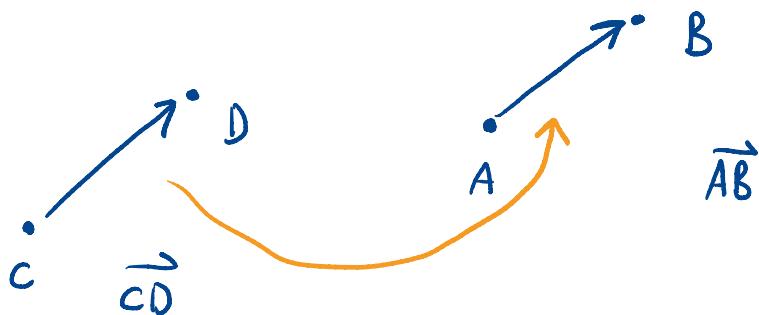


## Section 12.2

### Displacement Vectors



The displacements from C to D and from A to B are the same.

If we translate C to A then D lands on A.

We identify:

$$\vec{CD} = \vec{AB}$$

$$\overrightarrow{CD} = \overrightarrow{AB}$$

$\cdot D$

$\cdot B$

$\cdot C$

$\cdot A$



Level of vectors  
(displacements)



Euclidean space  
(points)

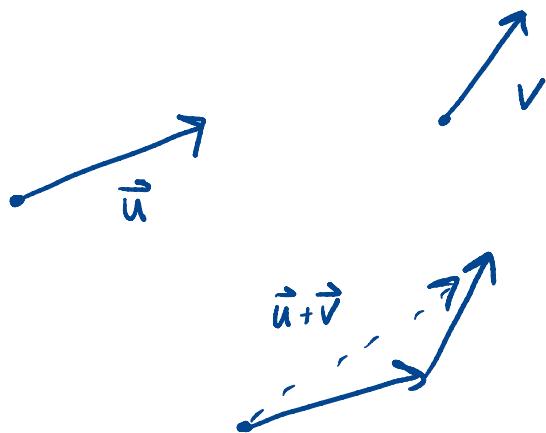
Displacement vectors have a direction  
(mostly) and a length.

$|\overrightarrow{AB}|$  is just the distance from A to B.

The zero vector does not have a direction.

## Operations on vectors:

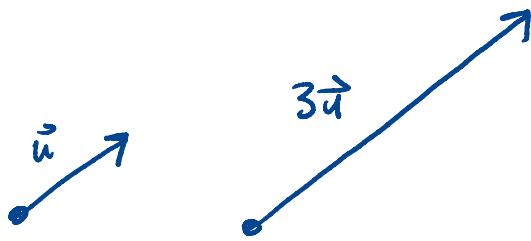
### 1) Vector addition



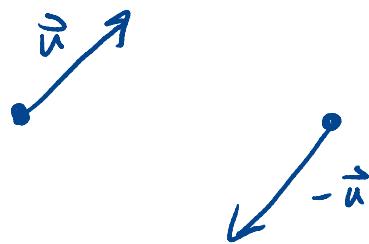
$$\overrightarrow{AB} + \overrightarrow{BC} = \overrightarrow{AC}$$

2) Scalar multiplication:  $a > 0, \vec{u} \neq 0$

$a\vec{u}$  is the vector parallel to  $\vec{u}$   
with length  $a|\vec{u}|$



also: points in opposite directions



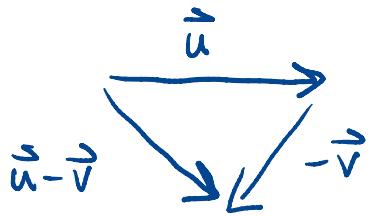
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$$a \cdot \vec{0} = \vec{0} \text{ no matter what } a \text{ is.}$$

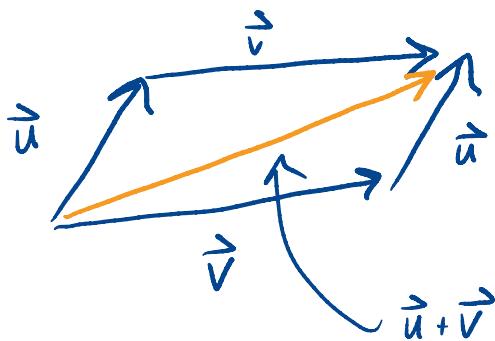
### 3) Subtraction

$$\vec{u} - \vec{v} = \vec{u} + (-\vec{v})$$





Addition is commutative



The zero vector is special:

$$\vec{0} + \vec{u} = \vec{u} + \vec{0} \quad \text{no matter what } \vec{u} \text{ is.}$$

Note: the origin of your coordinate systems  
Cartesian is arbitrary.

The zero vector (zero displacement!)  
is a very real thing.

Once you establish coordinates, vectors gain  
Cartesian displacement  
coordinates as well:

$$P(x_0, y_0, z_0)$$

$$Q(x_1, y_1, z_1)$$

$$\overrightarrow{PQ} = \langle x_1 - x_0, y_1 - y_0, z_1 - z_0 \rangle$$

↳ not standard but used in text

It's just the difference in coordinates.

The geometric vector operations have  
very natural algebraic equivalents:

$$\vec{a} = \langle a_1, a_2, a_3 \rangle$$

$$\vec{b} = \langle b_1, b_2, b_3 \rangle$$

$$\vec{a} + \vec{b} = \langle a_1 + b_1, a_2 + b_2, a_3 + b_3 \rangle$$

$$c\vec{a} = \langle ca_1, ca_2, ca_3 \rangle$$

$$\vec{a} - \vec{b} = \langle a_1 - b_1, a_2 - b_2, a_3 - b_3 \rangle$$

---

Properties:

$$(\vec{a} + \vec{b}) + \vec{c} = \vec{a} + (\vec{b} + \vec{c})$$

$$c(\vec{a} + \vec{b}) = c\vec{a} + c\vec{b}$$

$$(c+d)\vec{a} = c\vec{a} + d\vec{a}$$

$$c(d\vec{a}) = (cd)\vec{a}$$

$$\vec{a} + 0 = \vec{a} \quad | \quad 1\vec{a} = \vec{a}$$

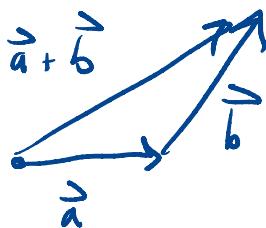
The length of a vector is the Euclidean length of the displacement

$$|\vec{a}| = \sqrt{a_1^2 + a_2^2 + a_3^2}$$

$$\left( \sqrt{(Ax)^2 + (Ay)^2 + (Az)^2} \right)$$

$$|c\vec{a}| = |c| |\vec{a}|$$

$$|\vec{a} + \vec{b}| = |\vec{a}| + |\vec{b}| ? \text{ Nope.}$$



$$|\vec{a} + \vec{b}| \leq |\vec{a}| + |\vec{b}|$$

Common operation:

$$\vec{u} = \langle \sqrt{5}, 2, 4 \rangle$$

$$|\vec{u}|^2 = 5 + 4 + 16 = 25$$

$$|\vec{u}| = 5$$

$$\frac{1}{5}\vec{u} = \left\langle \frac{\sqrt{5}}{5}, \frac{2}{5}, \frac{4}{5} \right\rangle$$

↑

$$\left| \frac{1}{5}\vec{u} \right| = \left| \frac{1}{5} \right| |\vec{u}| = \frac{1}{5} \cdot 5 = 1$$

We say  $\frac{1}{5}\vec{u}$  is a unit vector.

It points parallel to  $\vec{u}$  but has unit

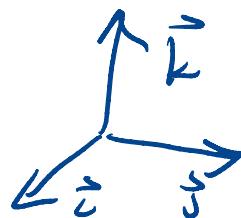
length.

We give names to three unit vectors  
that point along the coordinate axes:

$$\vec{i} = \langle 1, 0, 0 \rangle$$

$$\vec{j} = \langle 0, 1, 0 \rangle$$

$$\vec{k} = \langle 0, 0, 1 \rangle$$



(standard basis vectors)

These depend on your coordinates.

O is special.  $\vec{i}$  is not.

$$\vec{a} = \langle a_1, a_2, a_3 \rangle$$

$$= a_1 \vec{i} + a_2 \vec{j} + a_3 \vec{k}$$

## Other vectorial quantities

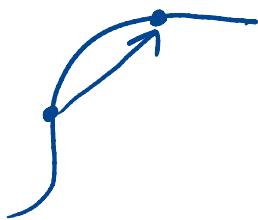
• velocity ( $\text{m/s}$ )

The other parts

• acceleration ( $\text{m/s}^2$ )

are "decom.ation"

• force ( $\text{kg m/s}^2 = \text{N}$ )



$$\frac{\vec{a}(t_f) - \vec{a}(t_0)}{t_f - t_0} \quad \frac{\text{dist}}{\text{time}}$$

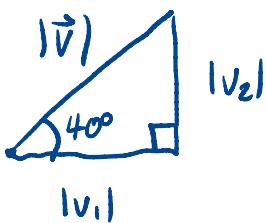
set  $t_i \rightarrow t_0$  and get an  
instantaneous velocity.

All the rules thus far also apply to  
these physical variations of displacement vectors

# Components of Physical vectors

Diagram illustrating the decomposition of a vector  $\vec{V}$  into components along the  $\hat{i}$  and  $\hat{j}$  axes. The angle between  $\vec{V}$  and the  $\hat{i}$ -axis is  $40^\circ$ . The magnitude of  $\vec{V}$  is given as  $|\vec{V}| = 10 \text{ km/h}$ . The decomposition is shown as:

$$\vec{V} = v_1 \hat{i} + v_2 \hat{j}$$



$$|v_1| = |\vec{V}| \cos(40^\circ) \approx 7.7$$

$$|v_2| = |\vec{V}| \sin(40^\circ) \approx 6.4$$

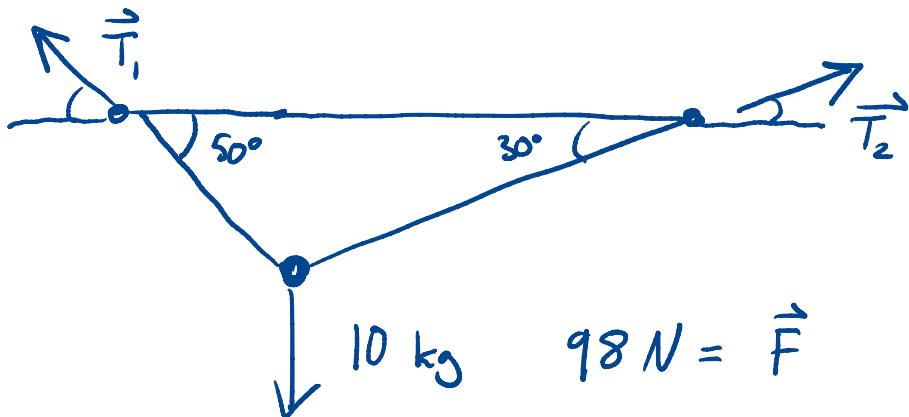
$v_1 > 0, v_2 > 0$  also

in this case.

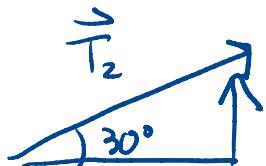
$$\vec{V} \approx 7.7 \hat{i} + 6.4 \hat{j}$$

Forces are especially important

Statics: the sum of forces acting on a body add to zero.



$$\vec{T}_1 + \vec{T}_2 + \vec{F} = 0$$



$$\begin{aligned}\vec{T}_2 &= \cos(30^\circ) |T_2| \vec{i} \\ &\quad + \sin(30^\circ) |T_2| \vec{j}\end{aligned}$$

$$\vec{T}_1 = -\cos(50^\circ) |\vec{T}_1| \hat{i} + \sin(50^\circ) |\vec{T}_1| \hat{j}$$

$$\vec{F} = -98 \hat{j}$$

$\hat{i}$  component:

$$\cos(30^\circ) |\vec{T}_2| - \cos(50^\circ) |\vec{T}_1| = 0$$

$\hat{j}$  component:

$$\sin(30^\circ) |\vec{T}_2| + \sin(50^\circ) |\vec{T}_1| = 98$$

$$|\vec{T}_2| = \frac{\cos(50^\circ)}{\cos(30^\circ)} |\vec{T}_1|$$

$$\left\{ \tan(30^\circ) \cos(50^\circ) + \sin(50^\circ) \right\} |\vec{T}_1| = 98$$

$$|\vec{T}_1| = \frac{98}{\left[ \tan(30^\circ) \cos(50^\circ) + \sin(50^\circ) \right]} \\ 1.137\dots = a$$

$$|\vec{T}_1| = 86.1797\dots$$

$$|\vec{T}_2| = \frac{\cos(50^\circ)}{\cos(30^\circ)} |\vec{T}_1|$$

$$|\vec{T}_2| = 63.16\dots$$

$$\vec{T}_1 = -\cos(50^\circ) |\vec{T}_1| \hat{i} + \sin(50^\circ) |\vec{T}_1| \hat{j} \\ \approx -55.395 \hat{i} + 66.017 \hat{j}$$

$$\vec{T}_2 \approx 55.395 \hat{i} + 31.18 \hat{j}$$