1.

- a) Make a graph of the boundary of the absolute stability region for the Runge-Kutta RK4 method on page 24.
- b) Apply the RK4 method to u' = 30u(1-u) with u(0) = 0.1 on the interval $0 \le t \le 2$. Use 14, 17 and 25 steps. For each run graph the numerical solution and the exact solution on the same plot.
- c) Explain the previous sequence of graphs in terms of the ODE and the plot from part a. Your answer should contain a quantitative explanation for why the transiton occurs at the value of *h* you observe.

Solution, part a:

The RK4 method applied to $u' = \lambda u$ becomes

$$u_{i+1} = R(z)u_i$$

where $R(z) = 1 + z + z^2/2 + z^3/3! + z^4/4!$. The boundary of the stability region is therefore those values of z such that |R(z)| = 1. The worksheet has a graph of this region.

Solution, part b:

See worksheet.

Solution, part c:

The exact solution of the IVP is

$$u(t) = \frac{1}{1 + 9e^{-30t}}.$$

As $t \to \infty$, $u(t) \to 1$. We can write u(t) = 1 + w(t) where w is a small perturbation for large values of t. Inserting this into the ODE we find

$$w' = 30(1+w)(-w) = -30w - 30w^2.$$

When w is close to 0, we can ignore the w^2 term and we find that

$$w' \approx -30w$$
.

That is, w is a transient with large exponential decay. To accurately capture it with RK4, and not experience instability, we need to pick a time step such that z = -30h lies in the absolute stability region. From the graph of the absolute stability region in part a, we see that this requires -3 < -30h. Since h = 2/M, where M is the number of time steps, this condition becomes 2/M < 1/10, or M > 20. The unusual behaviour observed for M = 14 and M = 17 are a consequence of the violation of z laying in the absolute stability region.

2. Newton's method can be used to solve

$$f(x) = 0$$

where $x \in \mathbb{R}^n$ and $f(x) \in \mathbb{R}^n$. Starting from an initial guess x_k ,

$$x_{k+1} = x_k - Df(x_k)^{-1}f(x_k).$$

Here, Df(x) is the Jacobian matrix

$$Df_{ij} = \frac{\partial f_i}{\partial x_j}$$

Implement Newton's method for systems. Your function should take as arguments f, Df and x_0 (an initial guess). It should terminate whenever either

- $|f(x)|_{\infty}$ is less than a specified tolerance
- $|f(x)|_{\infty}$ is less than a sepcified fraction of $|f(x_0)|_{\infty}$.

These tolerances should be specified with optional arguments as used in your language of choice, with values of 10^{-8} as the default.

Your function should return the estimated root and, as a diagnostic, the number of iterations needed to find the root.

Test your code against solving the simultaneous equations $x^2 + y^2 = 1$ and x = y starting from x = 0, y = 3. Report the root found and the number of iterations needed to find it.

Solution:

See worksheet.

3. The energy for the heat equation $u_t = u_{xx}$ for $0 \le x \le 1$ is

$$E(t) = \frac{1}{2} \int_0^1 (u_x(x,t))^2 dx.$$

a) Assuming that at x = 0 and at x = 1 u satisfies either a homogeneous Dirichlet condition or a homogeneous Neumann condition, show that

$$\frac{d}{dt}E(t)\leq 0.$$

Hint: Take a time derivative, use the PDE, and integrate by parts.

b) Conclude that the only solution of $u_t = u_{xx}$ with u = 0 at t = 0, and at x = 0 and x = 1 is the zero solution.

Solution, part a:

From integration by parts and applying the heat equation,

$$\frac{d}{dt}E(t) = \int_0^1 u_x(x,t)u_{tx}(x,t) dx
= \int_0^1 u_x(x,t) \frac{d}{dx}u_t(x,t) dx
= -\int_0^1 u_x x(x,t)u_t(x,t) dx + u_x u_t \Big|_{x=0}^1
= -\int_0^1 u_t(x,t)u_t(x,t) dx + u_x u_t \Big|_{x=0}^1$$
(1)

At an endpoint where a homogeneous Neuman condition holds, $u_x = 0$, so $u_x u_t = 0$. On the other hand, at an endpoint where a homogeneous Diriclhet condition holds, $u_t = 0$ and $u_x u_t = 0$. Thus there are no contributions from the boundary terms and we find

$$\frac{d}{dt}E(t)=-\int_0^1 u_t(x,t)u_t(x,t)\ dx\leq 0.$$

Solution, part b:

Suppose we start with initial data u = 0. Then the initial energy is zero as well. But energy decreases in time and is non-negative. So E(t) = 0 for all t. This implies $u_x = 0$ for all x and t. So x is constant at each time, and from the boundary conditions we conclude u = 0 everywhere.

4. The backwards heat equation reads

$$u_t = -u_{xx}$$

so all that differs is a sign on the right-hand side. But this sign makes all the difference.

We will work with this equation for $0 \le x \le 1$ and $0 \le t \le 1$, and with homogeneous Dirichlet boundary conditions, so u = 0 at x = 0 and x = 1.

a) Show that

$$v(t) = \sin(k\pi x)e^{k^2\pi^2t}$$

is a solution of the PDE and the boundary conditions.

- b) For each $\epsilon > 0$, find a solution of the PDE and boundary conditions that satisfies $|u(0,x)| < \epsilon$ at each x, but $|u(1,x)| \ge 1$ at some x.
- c) Suppose you wish to find the solution u of the backwards heat equation with initial condition u_0 . But you don't know u_0 exactly, you know \hat{u}_0 , and that $|u_0(x) \hat{u}_0(x)| < 10^{-47}$ at every x. So you solve the backwards heat equation for \hat{u} instead. Find an L such that $|u(x,1) \hat{u}(x,1)| < L$ for all x, or explain why no such L exists.

Solution, part a:

Evidently
$$v_t(x, t) = (k^2 \pi^2) v$$
 and $v_{xx} = -(k^2 \pi^2) v$. So $v_t = -v_{xx}$.

Solution, part b:

Let $\epsilon > 0$. Pick a natural number k such that $e^{k^2\pi^2} > 1/\epsilon$. Observe that

$$u(x,t) = \epsilon \sin(k\pi x)e^{k^2\pi^2t}$$

solves the backwards heat equation (by part a), and satisfies $|u| \le \epsilon$ at t = 0. But at t = 1 there is a choice of x such that $|\sin(k\pi x)| = 1$, and at that point,

$$|u(x,t)| = \epsilon e^{k^2 \pi^2} > 1$$

by our choice of *k*.

Solution, part c:

No such L exists. There is nothing special about the number 1 in the previous argument. For any $\epsilon > 0$ there is a solution of the backwards heat equation that satisfies $|u| \le \epsilon$ at t=0 but such that $|u| \ge L$ at t=1 This applies when $\epsilon = 10^{-43}$. So in effect, if there is any error in our estimate of the initial data, we have no estimate whatsoever for the value of the solution at t=1.