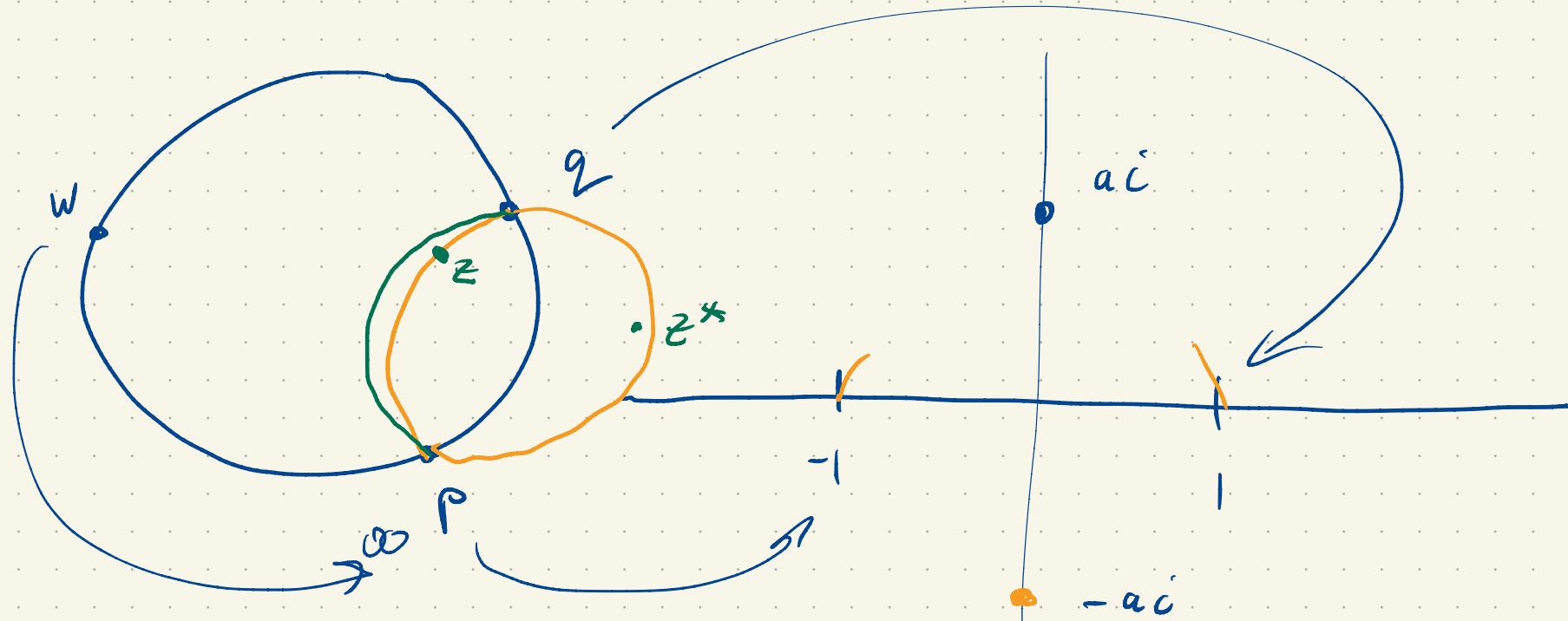


$$\alpha = 0, 1, -1$$



$$(1, -1, ac, -a\bar{c}) = \frac{\begin{pmatrix} 1-ac \\ 1+ac \\ 1-ac \\ 1-a\bar{c} \end{pmatrix}}{(1+ac)^2}$$

$$= \frac{(1-ac)^4}{(1+ac)^2}$$

$$(1-ac)^2 = (1-a^2) - 2ac$$

$$(1-ac)^4 = \left[(1-a^2)^2 - 4a^2 \right] - 4a(1-a^2)ac$$

$$a(1-a^2) = 0 \Rightarrow a=0, a=\pm 1$$

Remark: one can show by similar techniques
that given two ideal points there
is a hyperbolic line passing through both.

(is at most one, by above, so it's unique!)



one point of intersection in D (and one outside S')

"not parallel"

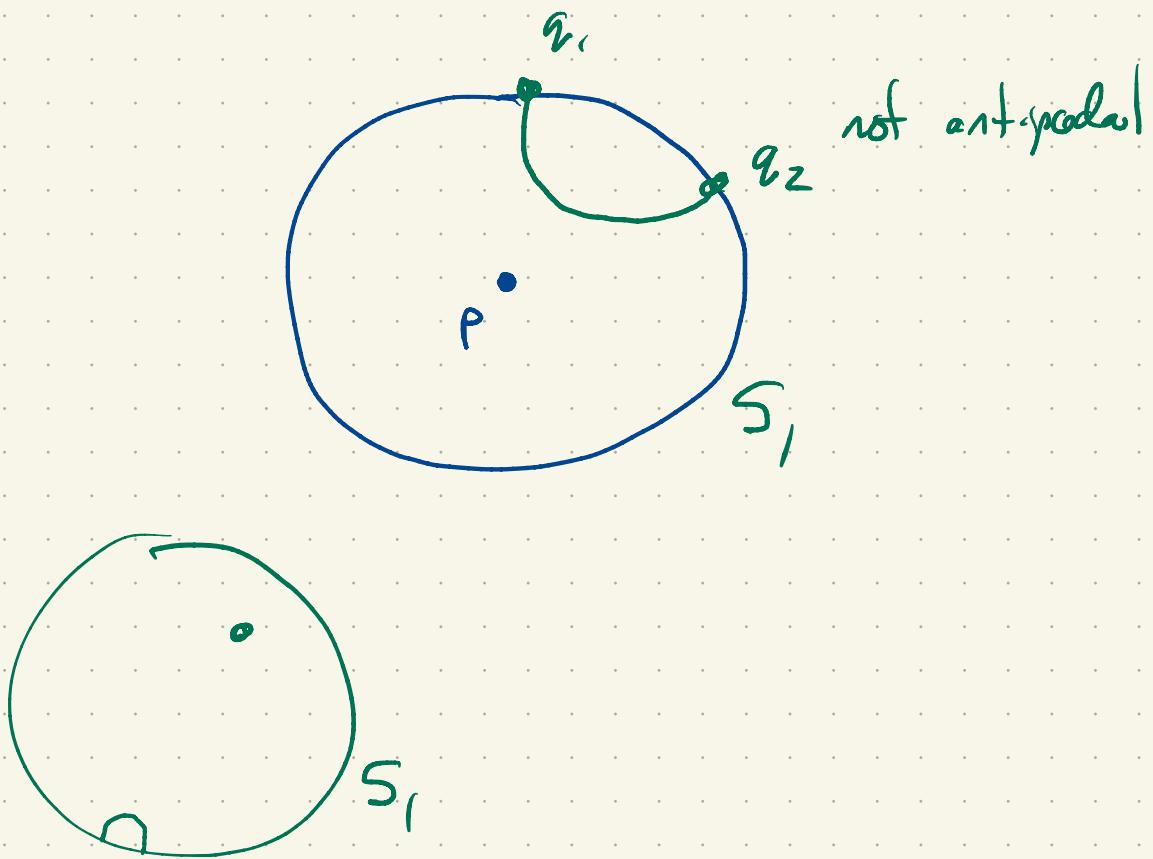
no intersections in D or on S' : hyperparallel

one intersection on S' (none in D): parallel

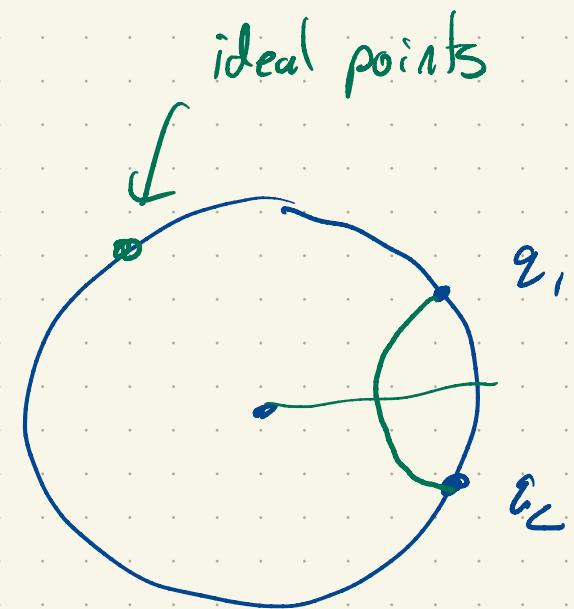
Angle of parallelism.

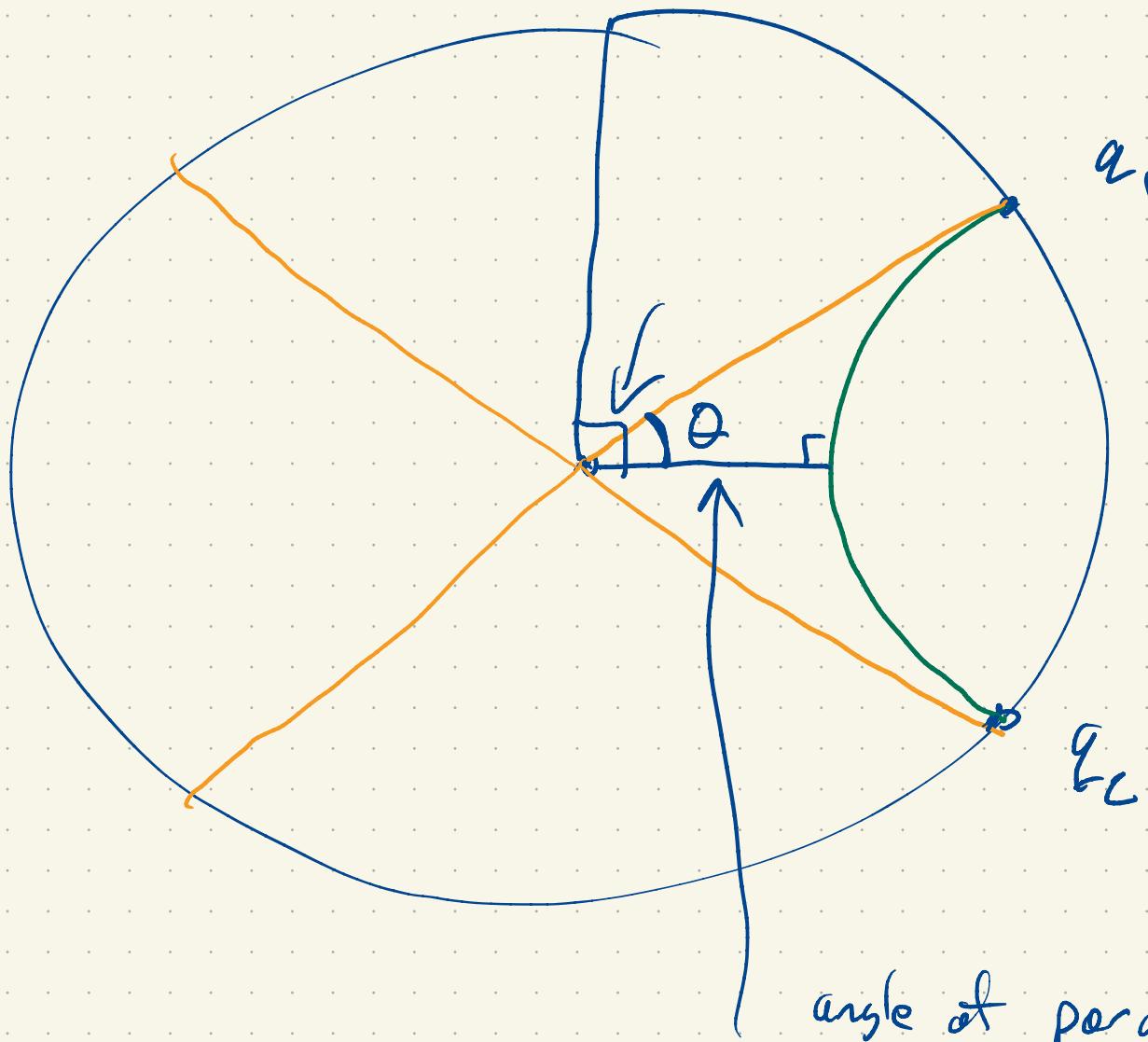
line: L

point p not on L .



s

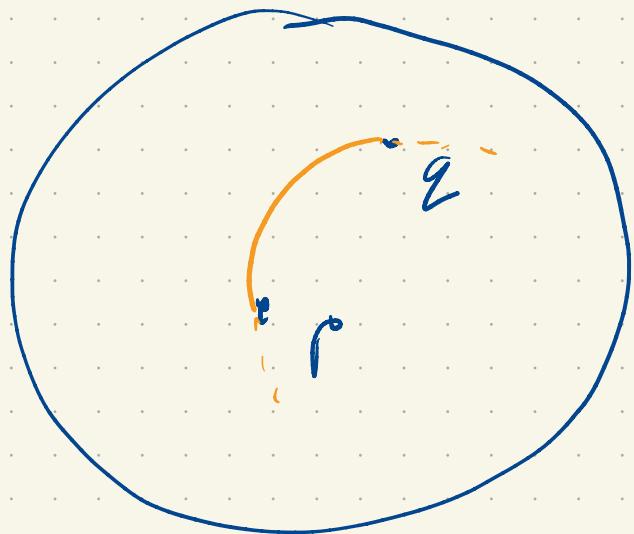




By construction θ is less than
a right angle.



We have violated postulate 5.



Hyperbolic transformations.

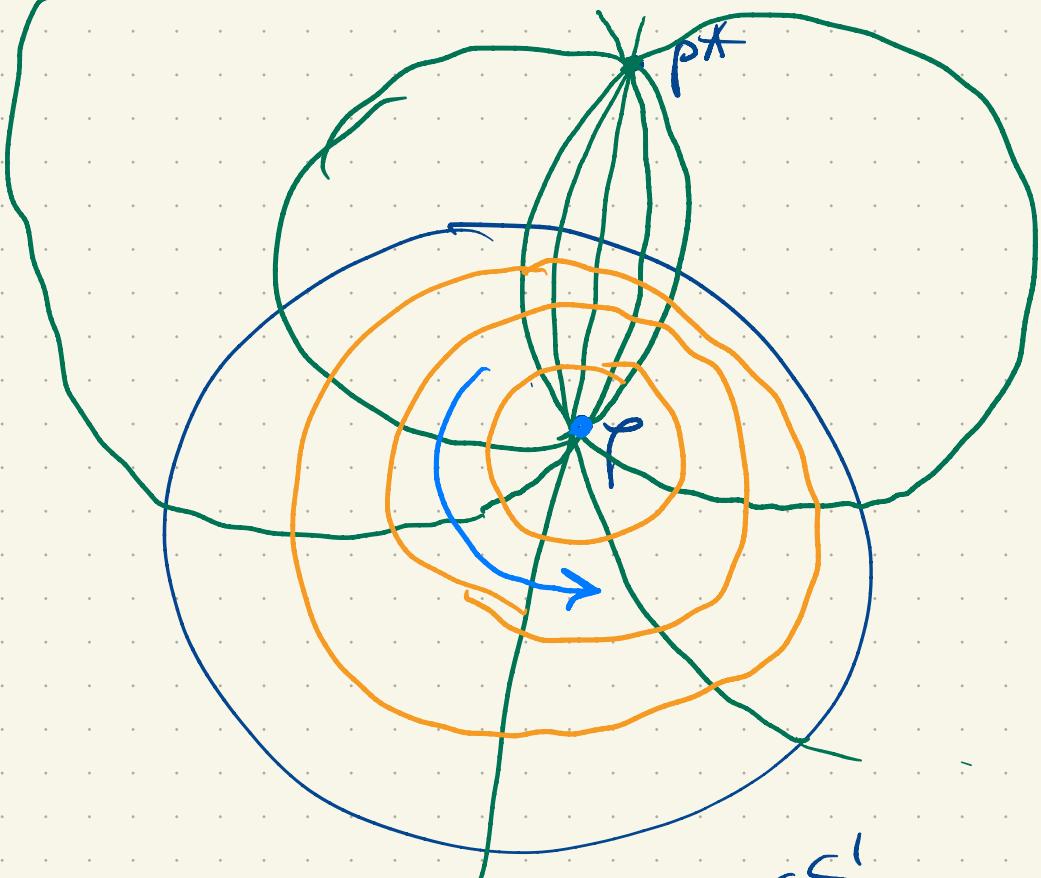
Möbius transformations \rightarrow at most two (unless the id)
one is possible, but not none.

Suppose T is a hyperbolic transformation

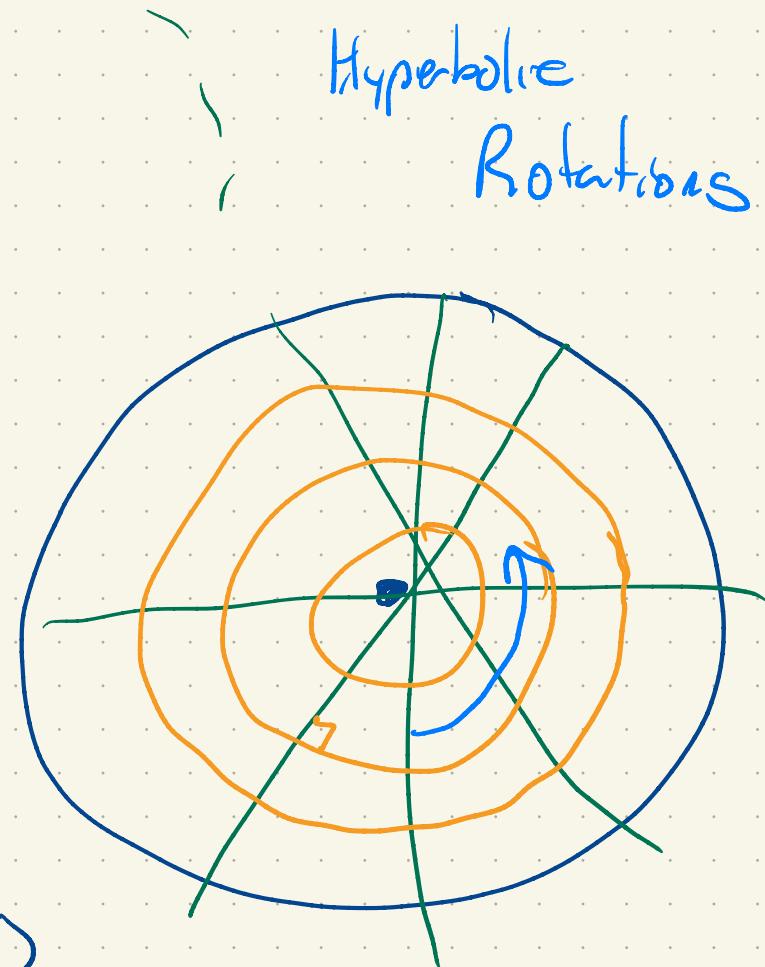
and $p \notin S^1$ is a fixed point.

$$T(p) = p$$

$$T(p^*) = (T(p))^* = p^*$$



$\in S^1$



Hyperbolic
Rotations

$$T(z) = \lambda \frac{z - q}{1 - \bar{q}z}$$

$$T(0) = 0$$

$$T(\infty) = \infty$$

$$T(0) = \lambda \cdot (-\bar{q}) = 0$$

\Rightarrow

$$T(z) = \lambda z \quad \lambda = e^{i\theta}$$