

Last class:

Introduced Θ method:

$$u_{j+1} = u_j + \lambda(1-\theta)D u_{j+1} + \lambda\theta D u_j$$

$\Theta = 1$: Forward Euler

$\Theta = 0$: Backward Euler

$\Theta = \frac{1}{2}$: Crank-Nicholson

Von Neumann analysis:

$$\lambda [2\Theta - 1] \leq \frac{1}{2} \quad \text{for "stability."}$$

Always true for $\Theta \leq \frac{1}{2}$. Otherwise a restriction on λ .

For $\Theta = 1 \quad \lambda \leq \frac{1}{2}$, same restriction as before.

Convergence proof assuming $1 - 2\lambda\Theta \geq 0$

$$\max_{i,j} |U_{i,j} - u(x_i, b_j)| \rightarrow 0$$

Two conditions

- a) $\lambda(2\theta - 1) \leq \frac{1}{2}$ for Von Neumann stability
- b) $\lambda 2\theta \leq 1$ for convergence

Exercise: if $0 \leq \theta \leq 1$

\Rightarrow satisfies b) \Rightarrow \Rightarrow satisfies a)

(Can we get convergence only assuming a)?

Yes, but we have to relax our idea of what convergence means.

Why can? $\lambda \leq \frac{1}{2\theta} \quad k \leq h^2 \left(\frac{1}{2\theta}\right)$

Have $k \sim h^2$ (but $\frac{1}{2\theta} \rightarrow \infty$ as $\theta \rightarrow 0$, so

restriction is less severe as $\theta \rightarrow 0$)

$\theta = 0$, no restriction on λ , loosely.

But error still will be $O(k) + O(h^2)$

$\theta = \frac{1}{2}$ we'll have error is $O(k^2) + O(h^2)$

Or max principle convergence proof requires

$\lambda \leq 1$ $k \leq h^2$ so still need
 $O(h^2)$ timesteps.

But, if we have convergence for $\lambda(2\theta-1) \leq \frac{1}{2}$,

then we get $O(k^2) + O(h^2)$ error and arbitrary λ ,
a big win. (Can take $k \sim h$ and see $O(h^2)$).

If you let me change how I measure error
I can get convergence in case $\Theta \leq 1/2$.

$$[1 - ((1-\theta)\lambda) D] \vec{u}_{j+1} = [1 + \theta\lambda D] \vec{u}_j + k \vec{f}_j$$

$$B \vec{u}_{j+1} = A \vec{u}_j + k \vec{f}_j$$

Let's talk about the eigenvalues/vectors of A, B .

For D , $u_i = \sin(r x_i)$ ($0 \leq x_i \leq 1$)

$$1 \leq i \leq N$$

$$\lambda = -4 \sin^2\left(\frac{r\pi}{2}\right) \quad r = k\pi \quad 1 \leq k \leq N$$

Eigenvalues of D : $-4\sin^2(\frac{r\pi}{2})$ $r = n\pi$ $n = 1, \dots, N$

Eigenvalues of θD : $-4\theta \lambda \sin^2(\frac{r\pi}{2})$ (same evecs)

Eigenvalues of $A = I + \theta D$: $1 - 4\theta \lambda \sin^2(\frac{r\pi}{2})$

Eigenvalues of $b = I - (1-\theta)\lambda D$: $1 + 4(1-\theta)\lambda \sin^2(\frac{r\pi}{2})$

Eigenvalues of B^{-1} : $(1 + 4(1-\theta) \dots)^{-1}$

Eigenvalues of $B^{-1}A$: $\frac{1 - 4\theta \lambda \sin^2(\frac{r\pi}{2})}{1 + 4(1-\theta)\lambda \sin^2(\frac{r\pi}{2})}$

Finally: $B^{-1}A = AB^{-1}$: why? same evecs!

Evals of B are all ≥ 1 . So B is invertible.

(B not invertible $\Rightarrow 0$ is an eigenvalue)

$$\vec{U}_{j+1} = B^{-1} A \vec{U}_j + B^{-1} k \vec{f}_j$$

$$u_{j+1} = B^{-1} A u_j + B^{-1} f_j + B^{-1} k \vec{e}_j$$

$$E_{j+1} = B^{-1} A E_j - B^{-1} \vec{z}_j k$$

Vector norms $v = (v_1, \dots, v_n)$

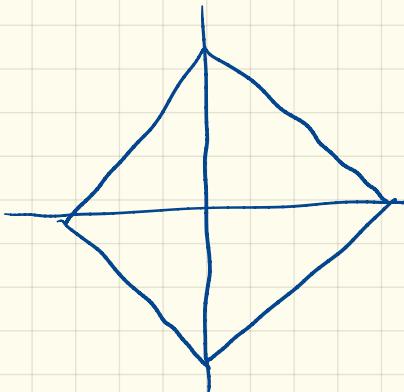
$$\|v\|_1 = \sum_{k=1}^n |v_k|$$

$$\|v\|_2 = \left[\sum_{k=1}^n |v_k|^2 \right]^{1/2}$$

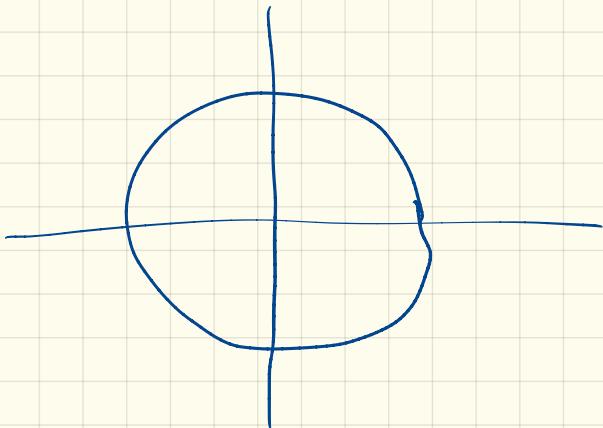
$$\|v\|_p = \left[\sum_{k=1}^n |v_k|^p \right]^{\frac{1}{p}} \quad 0 \leq p < \infty$$

$$\|v\|_\infty = \max_k |v_k| \quad \|v\|_p \rightarrow \|v\|_\infty \text{ as } p \rightarrow \infty.$$

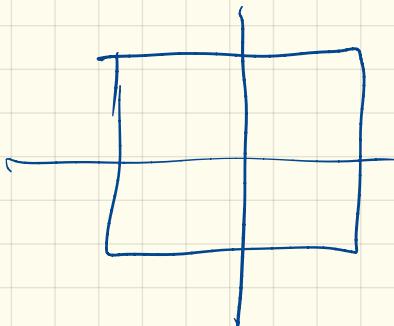
$$\|v\|_1 = 1$$



$$\|v\|_2 = 1$$



$$\|v\|_\infty = 1$$



Matrix norms:

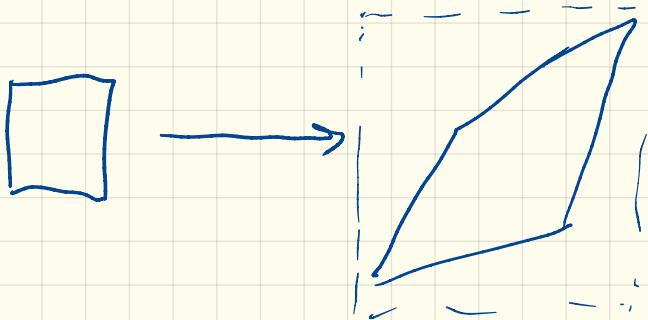
A : $n \times n$ matrix

$B_p(r) = \{x : \|x\|_p \leq r\}$ ball of radius r
v.r.t. p -norm.

$\|A\|_p : A(B_p(1)) = \{Ax : x \in B_p(1)\}$

$\|A\|_p = \inf_r : A(B_p(1)) \subseteq B_p(r)$

It's a measure of the amount of stretching A does, using the $\|\cdot\|_p$ to quantify stretching.



$$\|Ax\|_p \leq \|A\|_p \|x\|_p$$

(if $x = 0$, trivial. Otherwise $\frac{x}{\|x\|_p}$ is a unit vector)

$$\|A\left(\frac{x}{\|x\|_p}\right)\| \leq \|A\|_p \text{ and}$$

$$\|A\left(\frac{x}{\|x\|_p}\right)\| = \frac{\|Ax\|}{\|x\|_p}$$

In fact $\|A\|_p$ is the smallest number such that

$$\|Ax\|_p \leq r \|x\|_p.$$

$$\|A\|_p = \sup_{x \neq 0} \frac{\|Ax\|_p}{\|x\|_p}$$

(1) ↘

either one
lets.

$$= \sup_{\|x\|_p=1} \frac{\|Ax\|_p}{\|x\|_p}$$

$$= \sup_{\|x\|_p=1} \|Ax\|_p$$

(2) ↘

Exercise: $\|cA\|_p = |c| \|A\|_p$

Exercise: $\|A\|_p = 0 \iff A = 0$

Exercise: It is known that $\|x+y\|_p \leq \|x\|_p + \|y\|_p$,
 $0 \leq p \leq \infty$.

Use this to show

$$\|A+B\|_p \leq \|A\|_p + \|B\|_p.$$

(Triangle inequality)

For those in the know, this shows that $\|\cdot\|_p$ is a norm on $n \times n$ matrices.

Exercise: $\|AB\|_p \leq \|A\|_p \|B\|_p$.

Hence the plan

$$B\hat{u}_{j+1} = A\vec{r}_j + k\vec{f}$$

We're going to show $\|B^{-1}A\|_2 \leq 1$ assuming

$$\lambda(2\alpha - 1) \leq 1/2$$

$$\|(B^{-1})\|_2 \leq 1.$$

$$U_{j+1} = B^{-1}A\vec{r}_j + kB^{-1}\vec{f}$$

$$u_{j+1} = B^{-1}A\hat{u}_j + kB^{-1}\vec{f} + kB^{-1}\vec{z}_j$$

$$E_{j+1} = B^{-1}A(E_j) - kB^{-1}\vec{z}_j$$

$$\|E_{j+1}\|_2 \leq \|B^{-1}A E_j\|_2 + k \|B^{-1}\vec{z}_j\|_2$$

$$\leq \|B^{-1}A\|_2 \|E_j\|_2 + k \|B^{-1}\| \|Z_j\|_2$$

$$\|E_{0+}\|_2 \leq \|E_0\|_2 + k \|\tilde{z}\|_2$$

$$\|\tilde{z}\|_2 = \max_j \|\tilde{z}_j\|_2$$

$$\begin{aligned} \|E_j\|_2 &\leq \|E_0\|_2 + k_j \|\tilde{z}\|_2 \\ &\leq \|E_0\|_2 + kM \|\tilde{z}\|_2 \\ &= \|E_0\|_2 + T \|\tilde{z}\|_2 \end{aligned}$$

If $\|E_0\|_2 = 0$,

$$\max_j \|E_j\|_2 \leq T \|\tilde{z}\|_2$$

Now $\|\tilde{z}\|_2 \rightarrow 0$

$$\left[\sum_i (x_i)^2 \right]^{1/2} \xrightarrow[N \text{ entries, sm.}]{} 0$$

$$\max_j \left(\frac{1}{N} \|E_j\|_2 \right) \leq \underbrace{\frac{1}{N} T \|\tilde{z}\|_2}_{\rightarrow 0}$$

So if $\|x\|_\infty \rightarrow 0$ (consistency!)

Then $\max_j \frac{1}{\sqrt{N}} \|E_j\|_2 \rightarrow 0$

This is a weaker norm:

$$x = (N^{1/4}, 0, \dots, 0)$$

$$\|x\|_2 = N^{1/4}$$

$$\frac{\|x\|_2}{\sqrt{N}} = \frac{1}{N^{1/4}} \rightarrow 0.$$

But $\|x\|_\infty \not\rightarrow 0$.

This is a weaker notion of convergence.

I.O.U.: $\|B^{-1}A\|_2 \leq 1$ if $\lambda_{[2Q-1]} \leq \frac{1}{2}$

$$\|B^{-1}\| \leq 1$$

Fact from linear algebra: every symmetric matrix A admits an orthonormal basis of eigenvectors.

v_1, \dots, v_n orthonormal

$\lambda_1, \dots, \lambda_n$

$$P = [v_1, \dots, v_n]$$

$$A = P \Lambda P^{-1} \quad \Lambda = \text{diag}(\lambda_1, \dots, \lambda_n)$$

$$P \Lambda P^{-1} v_k = P \Lambda e_k = P \lambda_k e_k = \lambda_k v_k.$$

$A v_k = \lambda_k v_k$ So they agree on a basis.

$$P^T P = I \Rightarrow P^{-1} = P^T$$

$$\|P\|_2 = 1$$

$$\|\Lambda\|_2 = \max(|\lambda_1|, \dots, |\lambda_n|)$$

$$\|P^{-1}\|_2 = 1$$

$$\|P \Lambda P^{-1}\|_2 \leq \overbrace{\max(|\lambda_1|, \dots, |\lambda_n|)}^{= \sigma(A)}$$

spectral radius
 $\sigma(A)$

In fact $\|PAP^{-1}\|_2 = \max(|\lambda_1|, \dots, |\lambda_n|) = \sigma(A)$.

Just use an eigenvector:

$$\|A\mathbf{x}\|_p = \|\lambda\mathbf{x}\|_p = |\lambda| \|\mathbf{x}\|_p$$

$$\text{So } \|A\|_p \geq |\lambda|.$$

Prop: If A is symmetric, $\|A\|_2 = \sigma(A)$.

B, A are symmetric

B^{-1} is also symmetric.

$$B^{-1} = (B^T)^{-1} = (B^{-1})^T$$

$$(BA)^T = A^T(B^{-1})^T$$

$$= A B^{-1}$$

$$= B^{-1}A \quad (A, B \text{ have a common basis of eigenvectors})$$

eigenvalues of $B^{-1}A$:

$$\frac{1 - 4\theta \gamma \sin^2(\pi h/2)}{1 + 4(1-\theta)\lambda \sin^2(\pi h/2)}$$

$$r = n\pi \quad 1 \leq n \leq N$$

$$-1 \left[1 + 4(1-\theta) \lambda_s \right] \leq 1 - 4\theta \lambda_s$$

$$4\lambda_s [2\theta - 1] \leq 2$$

$$\lambda_s [2\theta - 1] \leq \frac{1}{2}$$

$$\lambda [2\theta - 1] \leq \frac{1}{2}$$

$$\sigma(B^{-1}A) \leq 1 \quad \text{assuming } \lambda [2\theta - 1] \leq \frac{1}{2}$$

$$\|B^{-1}A\|_2 \leq 1.$$