

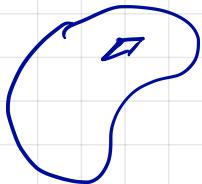
Last class: EM tensor

$$F = \begin{bmatrix} 0 & E_1 & E_2 & E_3 \\ -E_1 & 0 & cB_3 - cB_2 & 0 \\ -E_2 & -cB_3 & 0 & cB_1 \\ -E_3 & cB_2 & -cB_1 & 0 \end{bmatrix}$$

$$\frac{dP}{dc} = g G F V$$

$$L^* \hat{F} L = F$$

$$\tilde{F}(x,y) = X^T F Y \quad \tilde{F}(x,y) = -\tilde{F}(y,x)$$



To this point we have not used the rotation

$$\vec{E} = \int_{R^3} \vec{\Sigma}_\delta(x-y) \rho(y) dy \quad \vec{E}_s = \frac{1}{4\pi\epsilon_0} \frac{1}{|x|^2} \frac{x}{|x|}$$

Next goal: "derive" Maxwell's equations.

Notation:

1° functions on spacetime

$1'$ vector fields on spacetime ($\omega(x) =$

$$[\omega_0(x), \dots, \omega_3(x)]$$

$$d: 1^\circ \rightarrow 1'$$

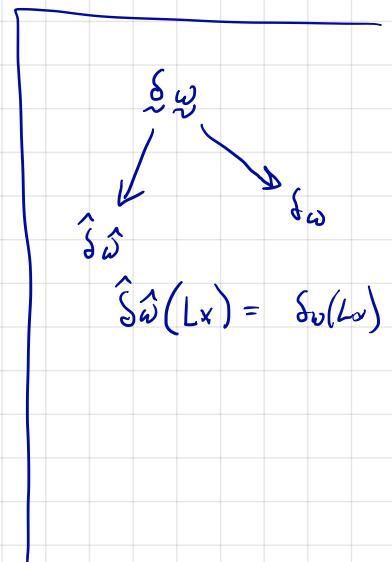
$$\text{in coords, } df = [\partial_0 f, \dots, \partial_3 f]$$

If has a component

$$\delta: 1' \rightarrow 1^\circ$$

$$\delta\omega = \partial_0\omega_0 - \partial_1\omega_1 - \partial_2\omega_2 - \partial_3\omega_3$$

$$\omega \rightarrow V \rightarrow D_n \cdot V = \delta\omega$$



Exercise:

$$\hat{\delta} \hat{\omega} = \delta \omega$$

$$\delta d f = \square f$$

Λ^1 : at each x is a map $\omega: V \rightarrow \mathbb{R}$.

Λ^2 : at each x is a map $F: V \times V \rightarrow \mathbb{R}$,

bilinear, $F(V, W) = -F(W, V)$.

(e.g. the E-M field). We can rep. by an antisymmetric matrix.

Λ^3 , Λ^4 as well.

And each of these is meant to be integrated

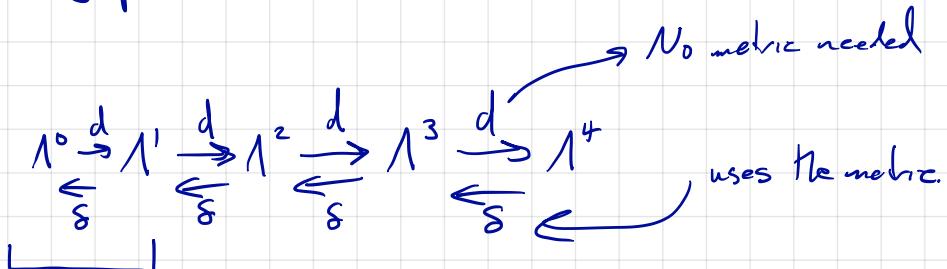
(Λ^1 over lines, Λ^2 over 2-surfaces, etc).



$$\int_a^b$$

$\pi(\alpha'(s)) ds$ is independent of frame,
but depends on direction.

Big picture



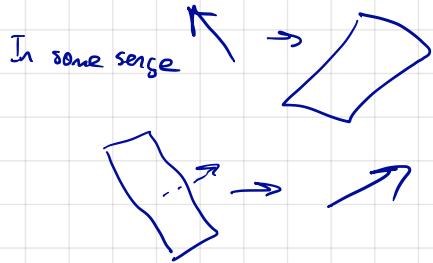
we've seen this

Moreover $d^2 = 0$

$\left[\begin{matrix} \text{we've seen this} \\ \text{we'll visit this for Maxwell!} \end{matrix} \right]$

Hodge $*$ $* : \Lambda^i \rightarrow \Lambda^{4-i}$

$$\begin{aligned} * &: \Lambda^0 \rightarrow \Lambda^4 \\ &: \Lambda^1 \rightarrow \Lambda^3 \\ &: \Lambda^2 \rightarrow \Lambda^2 \\ &: \Lambda^3 \rightarrow \Lambda^1 \\ &: \Lambda^4 \rightarrow \Lambda^0 \end{aligned}$$



$$s = * d *$$

$$\text{e.g. } \Lambda^2 \rightarrow \Lambda^2 \rightarrow \Lambda^3 \rightarrow \Lambda^1$$

$$(\text{so } s^2 = 0)$$

$$\Lambda^1 \rightarrow \Lambda^3 \rightarrow \Lambda^4 \rightarrow \Lambda^0$$

But I'm going to try to avoid discussing Λ^3, Λ^4
($\Lambda^0, \Lambda^1, \Lambda^2$ can be represented in terms of unitary vectors)

$$\Lambda^0 \xrightarrow{d} \Lambda^1 \quad d = \square$$

$$\Lambda^1 \xrightarrow{d} \Lambda^2 \quad -d = \mathcal{M} \rightarrow \text{maxwell operator.}$$

So who is d_3 ?

$$\omega = [\omega_0, \omega_1, \omega_2, \omega_3]$$

$$(d\omega)_{ij} = \partial_i \omega_j - \partial_j \omega_i$$

$$\text{Exercise } L^t \hat{d}\omega L = d\omega \quad (\text{ } d\omega \text{ transforms like a 2-form})$$

$$\text{Exercise } d^2: \Lambda^0 \rightarrow \Lambda^2 = 0$$

This is a deep generalization of $\nabla \times (\nabla f) = 0$

$$\operatorname{div}(\nabla \times V) = 0$$

To describe S I need some notation.

An antisymmetric 4×4 matrix has 6 independent entries.

Given $R = [R_1, R_2, R_3]$

$$S = [S_1, S_2, S_3]$$

$$\mathcal{F}(R, S) = \begin{bmatrix} 0 & R_1 & R_2 & R_3 \\ -R_1 & 0 & S_3 & -S_2 \\ -R_2 & -S_3 & 0 & S_1 \\ -R_3 & S_2 & -S_1 & 0 \end{bmatrix}$$

Gives us a way to talk about them.

e.g. $F = \mathcal{F}_1(E, -cB)$

Exercise: if $\omega = [\omega_0, \vec{\omega}]$

$$d\omega = \mathcal{F}_1(\partial_0 \vec{\omega} - \nabla \omega_0, \nabla \times \vec{\omega})$$

$$*: \Lambda^2 \rightarrow \Lambda^2$$

$$* \mathcal{F}(R, S) = \mathcal{F}(S, -R)$$

$$*d \mathcal{F}(R, S) = [\operatorname{div} S, -\nabla \times R + \partial_0 S]$$

$$*d* \mathcal{F}(R, S) = *d \mathcal{F}(S, -R)$$

$$= [-\operatorname{div} R, -\nabla \times S - \partial_0 R]$$

$$\begin{array}{ccc} F & & \\ \searrow & & \swarrow \\ \hat{F} & & F \\ \downarrow & & \downarrow \\ \hat{\mathcal{F}} & & *F \end{array}$$

$L^t \hat{F} L = F$

$L^t \hat{\mathcal{F}} L = *F$

$(*\hat{F} \text{ defined by } *F)$

(well defined & $L^t \hat{\mathcal{F}} L = *F$)

Much harder $*dF$ transforms like a 1-form.

We define $\mathcal{M} : \Lambda^1 \rightarrow \Lambda^1$

$$\mathcal{M} = -\delta d$$

Exercise: $-\delta d \omega = \square \omega - d \delta \omega$

where $\square \omega = (\square \omega_1, \dots, \square \omega_n)$.

Fact: $\hat{\mathcal{M}} \hat{\wedge} L = \mathcal{M} \omega \quad (\text{ } \omega \text{ transforms as a 1-form})$

$$\phi_s = \frac{1}{4\pi\epsilon_0} \frac{1}{|x|}$$

$$-\nabla \phi_s = E_s$$

$$\phi(x) = \int \phi_s(x-y) \rho(y) dy$$

$$-\nabla \phi = \int E_s(x-y) \rho(y) dy = E$$

$$-\Delta \phi = \int \operatorname{div} E_s \rho(y) dy$$

$$= \frac{1}{\epsilon_0} \rho$$

$$d\omega = \mathcal{R}(\omega_0 \hat{\omega} - \nabla \omega_0 \cdot \nabla \times \hat{\omega})$$

$$\omega = [\phi, 0]$$

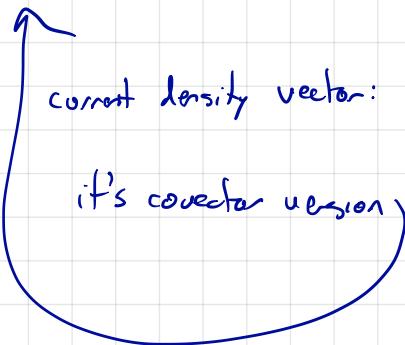
$$d\omega = \mathcal{R}(-\nabla \phi, 0) = \mathcal{R}(E, 0)$$

in any frame

$$\boxed{d\omega = F}$$

$$d\omega = \mathcal{R}(E, \sim c B)$$

$$\begin{aligned}
 -\delta \omega &= \square \omega - d \delta \omega \xrightarrow{=0} \delta \omega = \partial_\nu \omega_0 - \operatorname{div} \vec{\omega} = 0 \\
 &= (-\Delta \phi, 0) \\
 &= (-\operatorname{div} \nabla \phi, 0) \\
 &= \frac{1}{c \epsilon_0} (c \rho, 0)
 \end{aligned}$$



$$\left[\begin{array}{c} c \rho \\ j \end{array} \right] \xrightarrow{\frac{C}{m^3} \cdot \frac{m}{s}} \text{charge flux}$$

So in any frame, not just at rest,
 $\uparrow_{\text{charges}}$

$$m \omega = \frac{1}{c \epsilon_0} (c \rho_j - j)$$

These are Maxwell's equations relating ω and charge density.

They hold in general, not just electrostatics.

$$d\omega = \mathcal{F}(E, -cB) \quad \text{by def of } \Sigma, B.$$

$$*d\omega = \mathcal{F}(-cB, -E)$$

$$*d *d\omega = (-\operatorname{div} E, c\nabla \times B - \partial_0 S)$$

$$-*d *d\omega = (\operatorname{div} E, -c\nabla \times B + \partial_0 E)$$

$$*d \mathcal{F}(R, S) = [\operatorname{div} S, -\nabla \times R + \partial_0 S]$$

$$\textcircled{1} \quad \operatorname{div} E = \frac{1}{c\epsilon_0} \rho \quad (\text{Gauss' Law})$$

$$-\nabla \times B + \partial_0 E = -\frac{1}{c\epsilon_0} j$$

$$\textcircled{2} \quad \nabla \times B = \left[\frac{1}{c^2 \epsilon_0} j \right]_0 - \left[\frac{1}{c} \partial_0 E \right]_{\frac{1}{c^2 \partial_0 t}} \quad (\text{Ampere's equation with Maxwell's addition})$$

$$\text{Exercise: } *d d\omega = 0 \quad (\text{another face of } d^2 = 0)$$

$$*d \mathcal{F}(E, -cB) = [-c\operatorname{div} B, -\nabla \times E + \partial_0 (-cB)]$$

$$\textcircled{3} \quad \operatorname{div} B = 0 \quad (\text{no magnetic sources})$$

$$\textcircled{4} \quad \partial_t B + \nabla \times E = 0 \quad (\text{Faraday's Law of Induction})$$

$$\begin{aligned}\delta \vec{\mathcal{F}}(R, S) &= * \delta \vec{\mathcal{F}}(S, -R) \\ &= [\operatorname{div}(-R), -\partial_0 R - \nabla \times S] \\ &= -[\operatorname{div} R, \partial_0 R + \nabla \times S]\end{aligned}$$

$$\delta [w_0, \vec{\omega}] = \partial_0 w_0 - \operatorname{div} \vec{\omega}$$

Exercise: $\delta^2 = 0$

$$\text{But } \mathcal{M}_0 \omega = -\delta d\omega = \frac{1}{n} [c\rho, -j]$$

$$\delta \mathcal{N} = -\delta^2 d\omega = 0$$

$$\mathbf{J} = \begin{bmatrix} c\rho \\ j \end{bmatrix}$$

$\operatorname{Div} \mathbf{J} = 0 \rightarrow \text{conservation of charge.}$



$\int_S \rho \leftarrow \text{observed charge density}$

Gauge freedom.

Suppose $\mathcal{M} w = \frac{1}{c\epsilon_0} j$

$$\tilde{w} = w + df$$

$$\begin{aligned}\mathcal{M} \tilde{w} &= -\delta d(w + df) \\ &= -\delta dw + -\delta d^2 f \\ &= \frac{1}{c\epsilon_0} j + 0.\end{aligned}$$

Moreover, $d\tilde{w} = dw + d^2 f = dw$ so same EM field.

These are two faces of the same solution of Maxwell's equations and reflect a kind of coordinate change.

Now $\mathcal{M} w = \square w - dS_w$

If we can arrange $S_w \equiv 0$ ($\partial_\mu w_\mu - \text{div } \vec{w} = 0$)

then Maxwell's equations reduce to wave equations

Is this even possible?

$$\tilde{w} = w + df$$

$$\delta \tilde{w} = \delta w + \delta f$$

$$\square f = -\delta w$$

So f needs to solve an inhomogeneous wave eq.

[We didn't discuss, but solution always exists, with arbitrary initial data]

I.e. if you can find one, you can find all with $\delta \tilde{w} = 0$.

This choice of gauge is called Lorentz gauge.

Start with arbitrary w . $\partial_0 w$

Pick f a function of space alone,

$$-\Delta f = -\partial_0 w_0 + \operatorname{div} \vec{w}$$

$$\text{So } \delta f = -\delta w \text{ at } t=0.$$