

Applications:

A

$$\begin{bmatrix} a_1 & \cdots & a_n \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \boxed{x_1 a_1 + \cdots + x_n a_n}$$

audio
time
signal

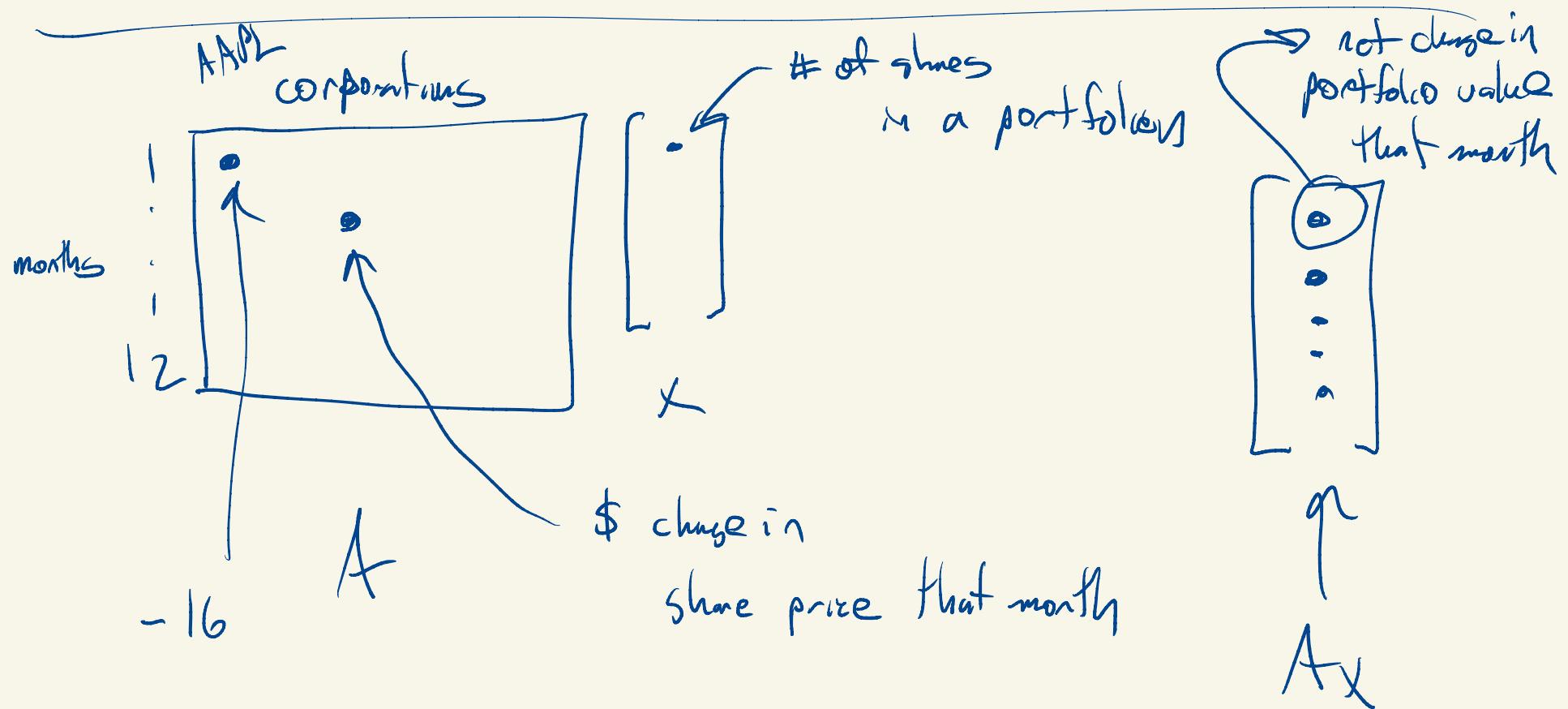
$a_{1,0}$

$$\begin{bmatrix} a_1 & a_2 \end{bmatrix} \begin{bmatrix} 1/2 \\ 1/2 \end{bmatrix} = \frac{1}{2} a_1 + \frac{1}{2} a_2 = \frac{1}{2} (a_1 + a_2)$$

$$n \begin{bmatrix} -1 & 1 & 0 & \cdots & 0 \\ 0 & -1 & 1 & 0 & \cdots & 0 \\ 0 & 0 & -1 & 1 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots & \ddots & 0 \\ 0 & \cdots & \cdots & \cdots & 0 & -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_{n+1} \end{bmatrix} = \begin{bmatrix} x_2 - x_1 \\ x_3 - x_2 \\ \vdots \\ x_{n+1} - x_n \end{bmatrix}$$

"discrete derivative"

↑
temperatures at 1 minute intervals



t_1, t_2, \dots, t_m

$$\begin{bmatrix} 1 & t_1 & t_1^2 & \cdots & t_1^n \\ 1 & t_2 & t_2^2 & \cdots & t_2^n \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & t_m & t_m^2 & \cdots & t_m^n \end{bmatrix} \begin{bmatrix} c_0 \\ c_1 \\ \vdots \\ c_n \end{bmatrix} = \begin{bmatrix} c_0 + c_1 t_1 + c_2 t_1^2 + \cdots + c_n t_1^n \\ c_0 + c_1 t_2 + c_2 t_2^2 + \cdots + c_n t_2^n \\ \vdots \\ c_0 + c_1 t_m + c_2 t_m^2 + \cdots + c_n t_m^n \end{bmatrix}$$

Vandermonde matrix

$$p(t) = c_0 + c_1 t + \cdots + c_n t^n$$

$$\begin{bmatrix} p(t_1) \\ p(t_2) \\ \vdots \\ p(t_m) \end{bmatrix}$$

$$\underset{m \times n}{\textcircled{O}} \xrightarrow{\downarrow X} = \underset{m \text{-vector}}{\textcircled{O}}$$

$$I \xrightarrow{\quad} x = x$$

↑
n-vector

$n \times n$

$$I = \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & 1 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}$$

$$I = [e_1 \ e_2 \ \cdots \ e_n]$$

I acts like the number 1
for multiplication

$$Ix = [e_1 \ \cdots \ e_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = x_1 e_1 + x_2 e_2 + \cdots + x_n e_n$$

$= x$

$$A e_k = [a_1 \ a_2 \ \cdots \ a_n] \begin{bmatrix} 0 \\ \vdots \\ 0 \\ \vdots \\ 0 \end{bmatrix} \leftarrow \text{slot } k$$

$\underbrace{A e_k}_{\text{k}^{\text{th}} \text{ column of } A}$

$$= 0 \cdot a_1 + 0 \cdot a_2 + \cdots + 1 \cdot a_k + 0 \cdot a_{k+1} + \cdots + 0 \cdot a_n = a_k$$

1

$$A \vec{1} = [a_1 \cdots a_n] \begin{bmatrix} 1 \\ \vdots \\ 1 \end{bmatrix} = 1a_1 + 1a_2 + \cdots + 1a_n = a_1 + a_2 + \cdots + a_n$$

$m \times n$ n vector

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} = 1 \begin{bmatrix} 1 \\ 4 \end{bmatrix} + 1 \begin{bmatrix} 2 \\ 5 \end{bmatrix} + 1 \begin{bmatrix} 3 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} 1+2+3 \\ 4+5+6 \end{bmatrix}$$

rules for linear functions

$$A(x+y) = Ax + Ay \quad] \rightarrow$$

$$A(cx) = c(Ax) \quad]$$

$$A(\alpha x + \beta y) = A(\alpha x) + A(\beta y)$$

$$= \alpha(Ax) + \beta(Ay)$$

"superposition"

$$(A+B)x = Ax + Bx$$

$$(cA)x = c(Ax)$$

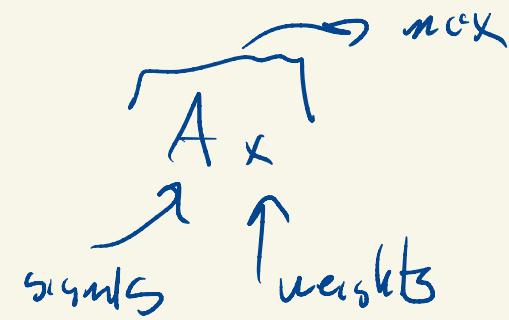
Given a $m \times n$ matrix A

we have an associated map $\mathbb{R}^n \rightarrow \mathbb{R}^m$

$$x \xrightarrow{\quad A \quad} Ax$$

\uparrow
 \mathbb{R}^n

\uparrow
 \mathbb{R}^m



e.g.: share price changes $\xrightarrow{\quad}$ assets $\xrightarrow{\quad}$ portfolio value
by month

audio signals $\xrightarrow{\quad}$ weights $\xrightarrow{\quad}$ mixed signal

I $\xrightarrow{\quad}$ vector $\xrightarrow{\quad}$ some theory

θ , angle

$$R_\theta = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

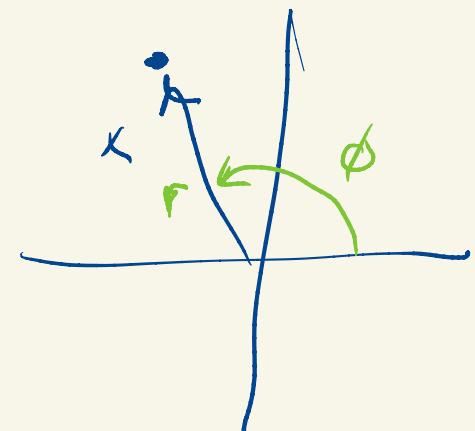


$$R_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$x = \begin{bmatrix} r \cos \phi \\ r \sin \phi \end{bmatrix}$$

$$\cos(A+B) = \cos(A)\cos(B) - \sin(A)\sin(B)$$

$$\sin(A+B) = \cos(A)\sin(B) + \cos(B)\sin(A)$$



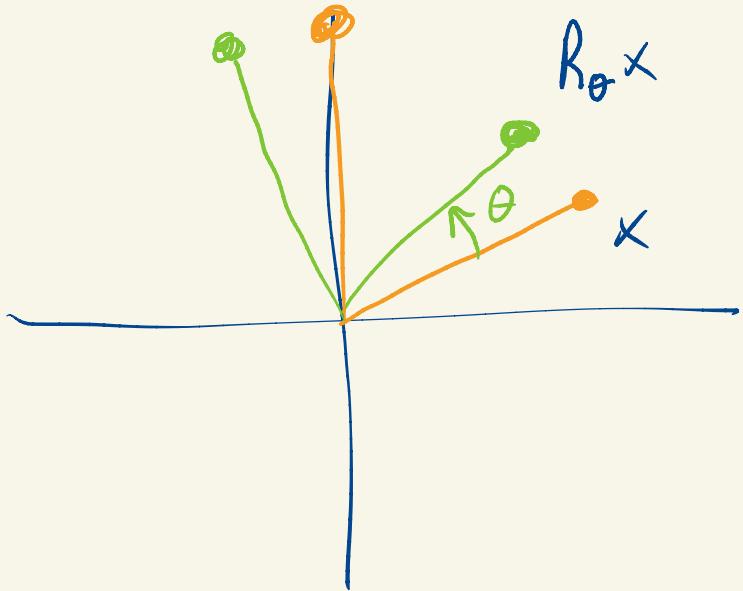
$$R_\theta x = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \begin{bmatrix} r \cos \phi \\ r \sin \phi \end{bmatrix}$$

$$= r \begin{bmatrix} \cos \theta \cos \phi - \sin \theta \sin \phi \\ \sin \theta \cos \phi + \cos \theta \sin \phi \end{bmatrix}$$

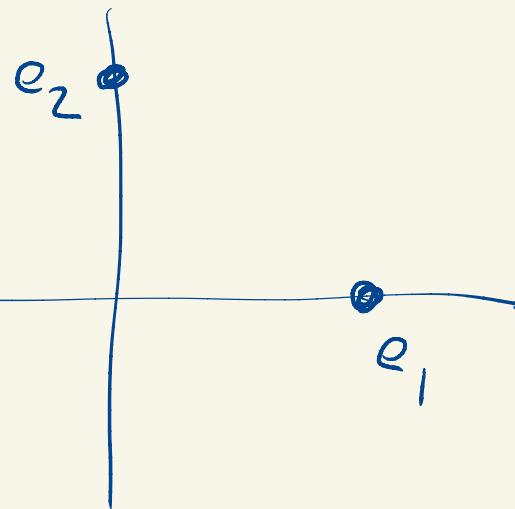
$$= r \begin{bmatrix} \cos(\phi + \theta) \\ \sin(\phi + \theta) \end{bmatrix}$$

$$x = r \begin{bmatrix} \cos \phi \\ \sin \phi \end{bmatrix} \quad R_\theta x = r \begin{bmatrix} \cos(\phi + \theta) \\ \sin(\phi + \theta) \end{bmatrix}$$

R_θ represents rotation of the plane
by angle θ



$x \mapsto R_\theta x$
rotate x by angle θ .



$$R_{\frac{\pi}{2}} = \begin{bmatrix} \cos(\pi/2) & -\sin(\pi/2) \\ \sin(\pi/2) & \cos(\pi/2) \end{bmatrix}$$

$$= \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}$$

$$R_{\pi/2} e_1 = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = e_2$$

$$R_{\pi/2} e_2 = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = -e_1$$

$x + \bar{c}y$

$$\begin{bmatrix} x & -y \\ y & x \end{bmatrix}$$