Globally convergent decomposition algorithm for risk parity problem in portfolio selection

A.Cassioli, G.Cocchi, F.D'Amato, M.Sciandrone February 8, 2016

1 Introduction

2 Preliminary background

Let us consider the following optimization problem:

$$\min_{x,y} \quad f(x,y) \tag{1a}$$

s.t.
$$l \le x \le u$$
 (1b)

$$\mathbf{1}^T x = 1 \tag{1c}$$

$$x \ge 0 \tag{1d}$$

where $x \in \mathbb{R}^n$, $y \in \mathbb{R}$, $f : \mathbb{R}^{n+1} \to \mathbb{R}$ is a which are the hypothesis on f?, $l, u \in \mathbb{R}^n$ with l < u and $\mathbf{1} \in \mathbb{R}^n$ is the identity vector. We indicate by \mathcal{F} the feasible set of Problem (1), namely

$$\mathcal{F} = \{ x \in \mathbb{R}^n : \mathbf{1}^T x = 1, l \le x \le u, x \ge 0 \}.$$
 (2)

Since the constraints of Problem (1) are linear, we have that a feasible point (x,y) is a stationary point of Problem (1) if and only if the Karush-Kuhn-Tucker (KKT) conditions are satisfied.

Proposition 2.1 (Optimality conditions (Necessary)) Let $(x^*, y^*) \in \mathbb{R}^{n+1}$, with $x^* \in \mathcal{F}$, a local optimum for Problem (1). Then there are two multipliers $\lambda^* \in \mathbb{R}, \ \mu^* \in \mathbb{R}^n \ satisfying$

$$\frac{\partial f(x^*, y^*)}{\partial y} = 0 \tag{3a}$$

$$\frac{\partial f(x^*, y^*)}{\partial y} = 0$$

$$\frac{\partial f(x^*, y^*)}{\partial x_i} + \lambda^* - \mu_i^* = 0$$

$$\mu_i^* x_i^* = 0$$
(3a)
(3b)

$$\mu_i^* x_i^* = 0 \tag{3c}$$

$$\mu_i^* \ge 0 \tag{3d}$$

From Proposition (2.1) it follows that:

Corollary 2.2 If $(x^*, y^*) \in \mathbb{R}^{n+1}$ is a local optimum for Problem (1), then

$$x_j^* > 0 \quad \Rightarrow \quad \frac{\partial f(x^*, y^*)}{\partial x_j} \le \frac{\partial f(x^*, y^*)}{\partial x_i} \quad \forall i \in \{1, ..., n\}$$
 (4)

- 3 A decomposition framework
- 4 Convergence analysis
- 5 Computational experiments