Stabla

DISKRETNE STRUKTURE S TEORIJOM GRAFOVA

Damir Horvat

FOI, Varaždin

Sadržaj

prvi zadatak

drugi zadatak

treći zadatak

četvrti zadatak

peti zadatak

prvi zadatak

Zadatak 1

U stablu T je $\Delta(T) = 5$. Pritom, stablo T ima četiri vrha stupnja 2, jedan vrh stupnja 3, dva vrha stupnja 4 i jedan vrh stupnja 5. Koliko listova ima stablo T i koliki je ukupni broj vrhova i bridova u promatranom stablu?

 $\ell \longleftarrow$ broj listova u stablu T

 $\ell \longleftarrow$ broj listova u stablu T

$$\Delta(T) = 5$$
,

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5, \quad \nu = \ell + 8,$$

 $\ell \longleftarrow$ broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

 $\boldsymbol{\ell}\cdot \boldsymbol{1}$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell \cdot 1 +$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell}\cdot \mathbf{1} + 4\cdot \mathbf{2}$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 +$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell} \cdot \boldsymbol{1} + \boldsymbol{4} \cdot \boldsymbol{2} + \boldsymbol{1} \cdot \boldsymbol{3}$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell} \cdot \boldsymbol{1} + \boldsymbol{4} \cdot \boldsymbol{2} + \boldsymbol{1} \cdot \boldsymbol{3} +$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell}\cdot\boldsymbol{1} + 4\cdot\boldsymbol{2} + 1\cdot\boldsymbol{3} + 2\cdot\boldsymbol{4}$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell} \cdot \boldsymbol{1} + \boldsymbol{4} \cdot \boldsymbol{2} + \boldsymbol{1} \cdot \boldsymbol{3} + \boldsymbol{2} \cdot \boldsymbol{4} +$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell} \cdot \boldsymbol{1} + \boldsymbol{4} \cdot \boldsymbol{2} + \boldsymbol{1} \cdot \boldsymbol{3} + \boldsymbol{2} \cdot \boldsymbol{4} + \boldsymbol{1} \cdot \boldsymbol{5}$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\boldsymbol{\ell} \cdot \boldsymbol{1} + \boldsymbol{4} \cdot \boldsymbol{2} + \boldsymbol{1} \cdot \boldsymbol{3} + \boldsymbol{2} \cdot \boldsymbol{4} + \boldsymbol{1} \cdot \boldsymbol{5} =$$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell \longleftarrow$$
 broj listova u stablu T $\Delta(T)=5, \quad
u=\ell+8, \quad arepsilon=
u-1$ $\sum_{v\in V(T)}d(v)=2arepsilon$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

 $\ell + 24$

$$\ell \longleftarrow$$
 broj listova u stablu T

$$\Delta(T) = 5$$
, $\nu = \ell + 8$, $\varepsilon = \nu - 1$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

 $\ell + 24 =$

$$\ell \longleftarrow$$
 broj listova u stablu T $\Delta(T)=5, \quad
u=\ell+8, \quad \varepsilon=\nu-1$ $\sum_{v\in V(T)}d(v)=2arepsilon$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

 $\ell + 24 = 2(\ell + 8 - 1)$

$$\ell \longleftarrow$$
 broj listova u stablu T
$$\Delta(T)=5,\quad \nu=\ell+8,\quad \varepsilon=\nu-1$$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell\cdot 1+4\cdot 2+1\cdot 3+2\cdot 4+1\cdot 5=2(\nu-1)$$

$$\ell+24=2(\ell+8-1)$$

$$\ell+24=2(\ell+7)$$

$$\ell \longleftarrow$$
 broj listova u stablu T
$$\Delta(T)=5, \quad \nu=\ell+8, \quad \varepsilon=\nu-1$$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell\cdot 1+4\cdot 2+1\cdot 3+2\cdot 4+1\cdot 5=2(\nu-1)$$

$$\ell+24=2(\ell+8-1)$$

$$\ell+24=2(\ell+7)$$

$$\ell+24=2\ell+14$$

$$\ell \longleftarrow$$
 broj listova u stablu T
$$\Delta(T)=5, \quad \nu=\ell+8, \quad \varepsilon=\nu-1$$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell\cdot 1+4\cdot 2+1\cdot 3+2\cdot 4+1\cdot 5=2(\nu-1)$$

$$\ell+24=2(\ell+8-1)$$

$$\ell+24=2(\ell+7)$$

$$\ell+24=2\ell+14$$

$$\ell=10$$

$$\ell \longleftarrow$$
 broj listova u stablu T
$$\Delta(T)=5, \quad \nu=\ell+8, \quad \varepsilon=\nu-1$$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell\cdot 1+4\cdot 2+1\cdot 3+2\cdot 4+1\cdot 5=2(\nu-1)$$

$$\ell+24=2(\ell+8-1)$$

$$\ell+24=2(\ell+7)$$

$$\ell+24=2\ell+14$$

$$\ell=10$$

$$\ell \longleftarrow$$
 broj listova u stablu T
$$\Delta(T)=5, \quad \nu=\ell+8, \quad \varepsilon=\nu-1$$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell\cdot 1+4\cdot 2+1\cdot 3+2\cdot 4+1\cdot 5=2(\nu-1)$$

$$\ell+24=2(\ell+8-1)$$

$$\ell+24=2(\ell+7)$$

$$\ell+24=2\ell+14$$

$$\ell=10$$

$$\ell \longleftarrow$$
 broj listova u stablu T
$$\Delta(T)=5, \quad \nu=\ell+8, \quad \varepsilon=\nu-1$$

$$\sum_{v\in V(T)}d(v)=2\varepsilon$$

$$\ell\cdot 1+4\cdot 2+1\cdot 3+2\cdot 4+1\cdot 5=2(\nu-1)$$

$$\ell+24=2(\ell+8-1)$$

$$\ell+24=2(\ell+7)$$

$$\ell+24=2(\ell+7)$$

$$\ell+24=2\ell+14$$

$$\ell=10$$

$$\ell \longleftarrow \text{broj listova u stablu } T$$

$$\Delta(T) = 5, \quad \nu = \ell + 8, \quad \varepsilon = \nu - 1$$

$$\sum_{v \in V(T)} d(v) = 2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell + 24 = 2(\ell + 8 - 1)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2\ell + 14$$

$$\ell = 10$$

$$\ell \longleftarrow \text{broj listova u stablu } T$$

$$\Delta(T) = 5, \quad \nu = \ell + 8, \quad \varepsilon = \nu - 1$$

$$\sum_{v \in V(T)} d(v) = 2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell + 24 = 2(\ell + 8 - 1)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2\ell + 14$$

$$\ell = 10$$

$$\ell \longleftarrow \text{broj listova u stablu } T$$

$$\Delta(T) = 5, \quad \nu = \ell + 8, \quad \varepsilon = \nu - 1$$

$$\sum_{v \in V(T)} d(v) = 2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell + 24 = 2(\ell + 8 - 1)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\varepsilon = \nu - 1$$

$$\ell = 10 + 8$$

$$\ell = 10$$

$$\ell \longleftarrow \text{broj listova u stablu } T$$

$$\Delta(T) = 5, \quad \nu = \ell + 8, \quad \varepsilon = \nu - 1$$

$$\sum_{v \in V(T)} d(v) = 2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell + 24 = 2(\ell + 8 - 1)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell = 10 + 8$$

$$\ell = 10$$

$$\ell = 10$$

$$\ell \longleftarrow \text{broj listova u stablu } T$$

$$\Delta(T) = 5, \quad \nu = \ell + 8, \quad \varepsilon = \nu - 1$$

$$\sum_{v \in V(T)} d(v) = 2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell + 24 = 2(\ell + 8 - 1)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\varepsilon = \nu - 1$$

$$\varepsilon = 18$$

$$\ell = 10$$

$$\varepsilon = 17$$

$$\ell \longleftarrow \text{broj listova u stablu } T$$

$$\Delta(T) = 5, \quad \nu = \ell + 8, \quad \varepsilon = \nu - 1$$

$$\sum_{v \in V(T)} d(v) = 2\varepsilon$$

$$\ell \cdot 1 + 4 \cdot 2 + 1 \cdot 3 + 2 \cdot 4 + 1 \cdot 5 = 2(\nu - 1)$$

$$\ell + 24 = 2(\ell + 8 - 1)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\ell + 24 = 2(\ell + 7)$$

$$\varepsilon = \nu - 1$$

$$\varepsilon = 18$$

$$\ell = 10$$

$$\varepsilon = 17$$

drugi zadatak

Teorem (rekurzija za broj razapinjućih stabala)

Neka je $\tau(G)$ broj razapinjućih stabala grafa G. Ako je $e \in E(G)$ karika, tada vrijedi

$$\tau(G) = \tau(G - e) + \tau(G \cdot e).$$

Matrični teorem o stablima

Neka je G povezani graf bez petlji sa skupom vrhova $V = \{v_1, v_2, \ldots, v_n\}$. Neka je $A = [a_{ij}]$ matrica susjedstva grafa G. Neka je $Q = [q_{ij}]$ $n \times n$ matrica za koju vrijedi

$$q_{ij} = \begin{cases} -a_{ij}, & i \neq j \\ d_G(v_i), & i = j \end{cases}.$$

Tada je $\tau(G)$ jednak bilo kojem kofaktoru matrice Q.

Zadatak 2

Graf G zadan je matricom susjedstva

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix}.$$

- a) Bez crtanja grafa G odredite ukupni broj petlji u grafu i stupnjeve njegovih vrhova.
- b) Nacrtajte graf G i pomoću rekurzije odredite ukupni broj razapinjućih stabala grafa G.
- c) Pomoću matričnog teorema o stablima odredite ukupni broj razapinjućih stabala grafa G.
- d) Je li G Hamiltonov graf? Postoji li Hamiltonov put u grafu G?

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix}$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

a)

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix}$$

broj petlji =

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

$$\mathsf{broj}\ \mathsf{petlji} = 1 + 0 + 2 + 0$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) =$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & \boxed{1 & 3 & 0 & 0} \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

 $d(v_2) =$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ \hline 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

$$d(v_2) = 3 + 2 \cdot 0 + 1 + 1$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

 $d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix} \\ v_4 \begin{bmatrix} 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

 $d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$
 $d(v_3) =$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

$$d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$$

$$d(v_3) = 0 + 1 + 2 \cdot 2 + 2$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

$$d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$$

$$d(v_3) = 0 + 1 + 2 \cdot 2 + 2 = 7$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

$$d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$$

$$d(v_3) = 0 + 1 + 2 \cdot 2 + 2 = 7$$

$$d(v_4) =$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

$$d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$$

$$d(v_3) = 0 + 1 + 2 \cdot 2 + 2 = 7$$

$$d(v_4) = 0 + 1 + 2 + 2 \cdot 0$$

$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

broj petlji =
$$1 + 0 + 2 + 0 = 3$$

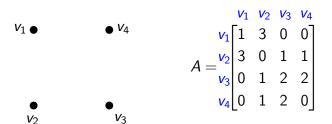
$$d(v_1) = 2 \cdot 1 + 3 + 0 + 0 = 5$$

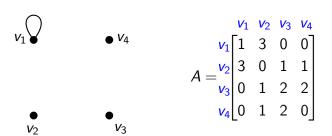
$$d(v_2) = 3 + 2 \cdot 0 + 1 + 1 = 5$$

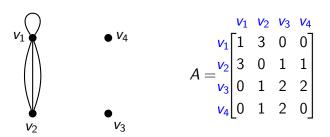
$$d(v_3) = 0 + 1 + 2 \cdot 2 + 2 = 7$$

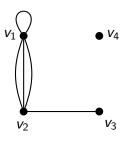
$$d(v_4) = 0 + 1 + 2 + 2 \cdot 0 = 3$$

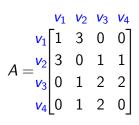
$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$

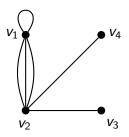


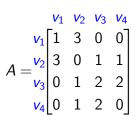


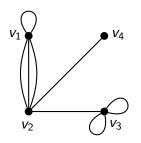


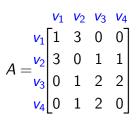


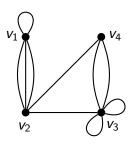




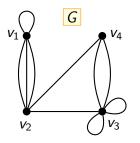




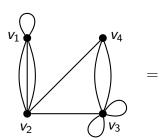


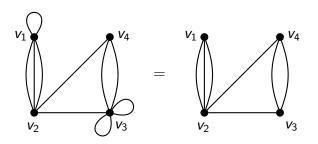


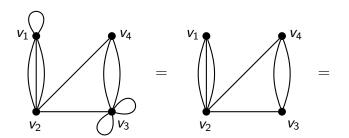
$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$



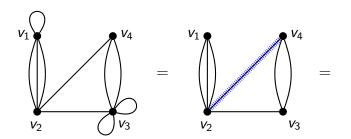
$$A = \begin{bmatrix} v_1 & v_2 & v_3 & v_4 \\ v_1 & 3 & 0 & 0 \\ v_2 & 3 & 0 & 1 & 1 \\ v_3 & 0 & 1 & 2 & 2 \\ v_4 & 0 & 1 & 2 & 0 \end{bmatrix}$$



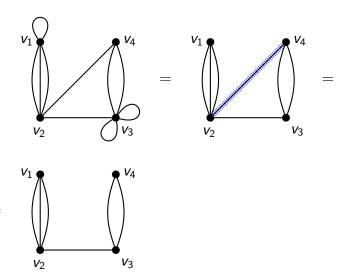




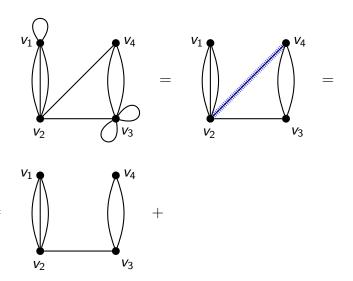
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



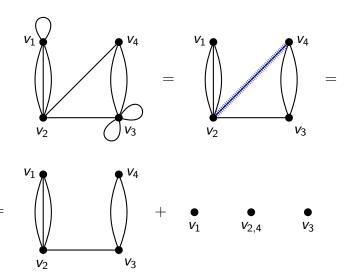
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



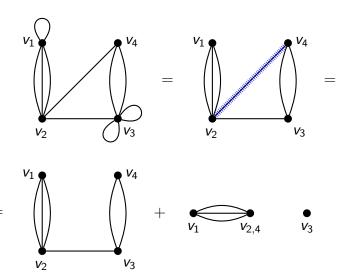
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



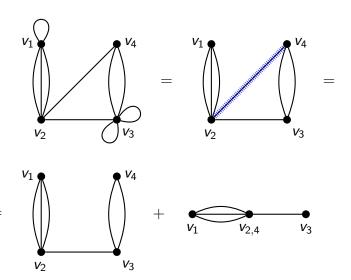
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



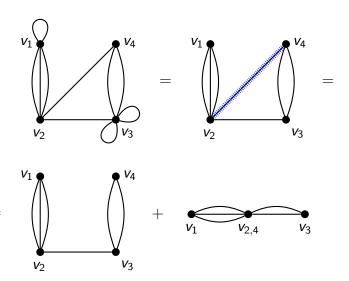
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



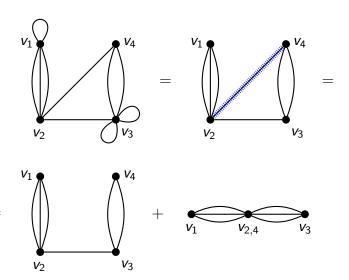
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



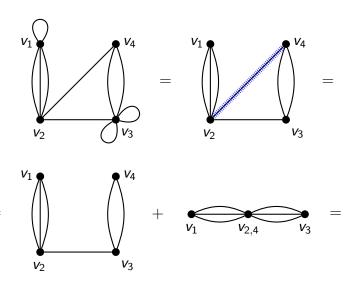
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



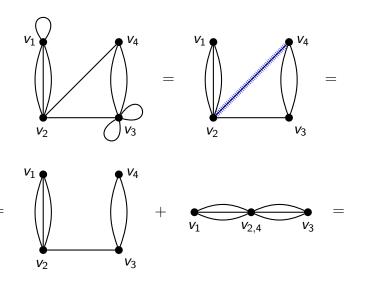
$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

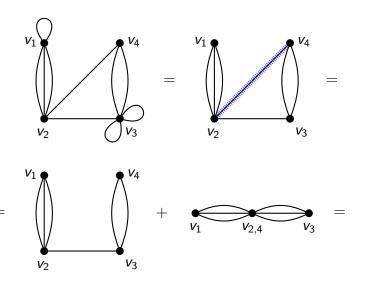


$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



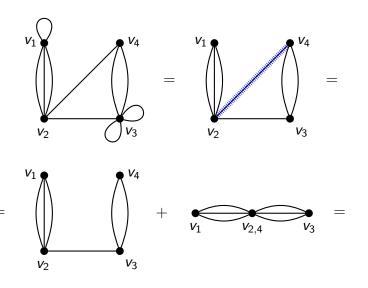
$$= 3 \cdot 1 \cdot 2$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



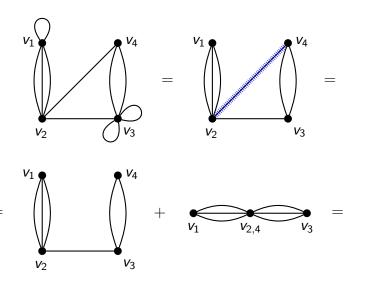
$$= 3 \cdot 1 \cdot 2 +$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



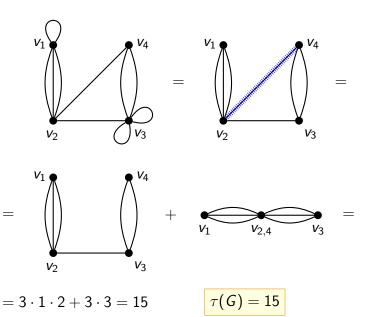
$$= 3 \cdot 1 \cdot 2 + 3 \cdot 3$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



$$=3\cdot 1\cdot 2+3\cdot 3=15$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

$$A = egin{bmatrix} 1 & 3 & 0 & 0 \ 3 & 0 & 1 & 1 \ 0 & 1 & 2 & 2 \ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = egin{bmatrix} \end{array}$$

$$A = egin{bmatrix} 1 & 3 & 0 & 0 \ 3 & 0 & 1 & 1 \ 0 & 1 & 2 & 2 \ 0 & 1 & 2 & 0 \ \end{pmatrix} \quad A_1 = egin{bmatrix} 0 & 0 & 0 \ 0 & 0 & 0 \ \end{pmatrix}$$

$$A = egin{bmatrix} 1 & 3 & 0 & 0 \ 3 & 0 & 1 & 1 \ 0 & 1 & 2 & 2 \ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = egin{bmatrix} 0 & 3 & 0 & 0 \ 0 & 1 & 1 \ 0 & 2 \ 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & 5 & 5 & 5 \\ 0 & 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & & & & & \\ & & 5 & & & \\ & & & 3 & & \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & & & \\ & 5 & & & \\ & & 3 & & \\ & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ 5 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & \\ & & 3 & \\ & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ & & 3 & \\ & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & & 3 & \\ & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & \\ & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & -2 \\ & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & & 3 \end{bmatrix}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

$$A_{ij} = (-1)^{i+j} M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

$$Q_{21} =$$

$$A_{ij}=(-1)^{i+j}M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ -3 & 5 & -1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

$$Q_{21} = (-1)^{2+1}$$

$$A_{ij} = (-1)^{i+j} M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ 3 & 5 & 1 & 1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

$$Q_{21} = (-1)^{2+1}$$
.

$$A_{ij} = (-1)^{i+j} M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ 3 & 5 & 1 & -1 \\ & -1 & 3 & -2 \\ & & -1 & -2 & 3 \end{bmatrix}$$

$$Q_{21} = (-1)^{2+1} \cdot egin{bmatrix} -3 & 0 & 0 \ -1 & 3 & -2 \ -1 & -2 & 3 \ \end{bmatrix}$$

$$A_{ij} = (-1)^{i+j} M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ 3 & 5 & 1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

$$Q_{21} = (-1)^{2+1} \cdot egin{bmatrix} -3 & 0 & 0 \ -1 & 3 & -2 \ -1 & -2 & 3 \end{bmatrix} = -1 \cdot (-15)$$

$$A_{ij} = (-1)^{i+j} M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ 3 & 5 & 1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

$$Q_{21} = (-1)^{2+1} \cdot \begin{vmatrix} -3 & 0 & 0 \\ -1 & 3 & -2 \\ -1 & -2 & 3 \end{vmatrix} = -1 \cdot (-15) = 15$$

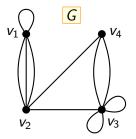
$$A_{ij} = (-1)^{i+j} M_{ij}$$

$$A = \begin{bmatrix} 1 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 2 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad A_1 = \begin{bmatrix} 0 & 3 & 0 & 0 \\ 3 & 0 & 1 & 1 \\ 0 & 1 & 0 & 2 \\ 0 & 1 & 2 & 0 \end{bmatrix} \quad Q = \begin{bmatrix} 3 & -3 & 0 & 0 \\ 3 & 5 & 1 & -1 \\ 0 & -1 & 3 & -2 \\ 0 & -1 & -2 & 3 \end{bmatrix}$$

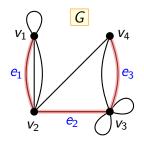
$$Q_{21} = (-1)^{2+1} \cdot \begin{vmatrix} -3 & 0 & 0 \\ -1 & 3 & -2 \\ -1 & -2 & 3 \end{vmatrix} = -1 \cdot (-15) = 15$$

$$\tau(G)=15$$

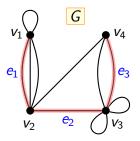
d)



d) G ima Hamiltonov put, npr. $v_1e_1v_2e_2v_3e_3v_4$.



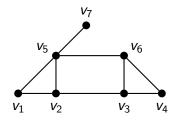
d) G ima Hamiltonov put, npr. $v_1e_1v_2e_2v_3e_3v_4$. G nije Hamiltonov graf jer je v_1 problematični vrh.



treći zadatak

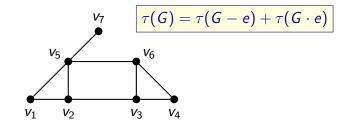
Zadatak 3

Zadan je graf G.

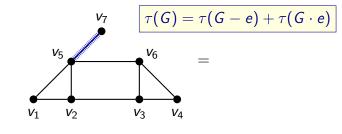


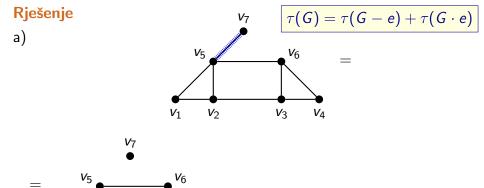
- a) Pomoću rekurzije odredite ukupni broj razapinjućih stabala grafa G.
- b) Pomoću BFS algoritma pronađite jedno razapinjuće stablo grafa G.
- c) Pomoću DFS algoritma pronađite jedno razapinjuće stablo grafa G.

Rješenje a)



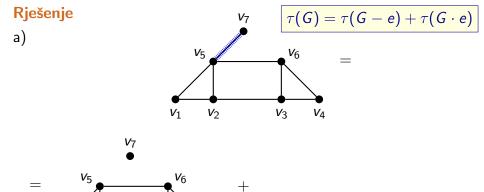
Rješenje a)





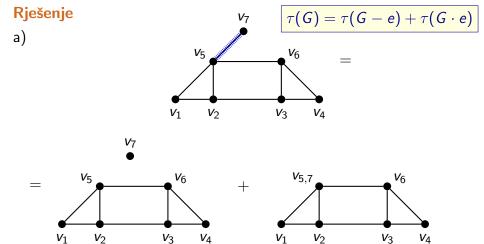
 v_2

*V*3



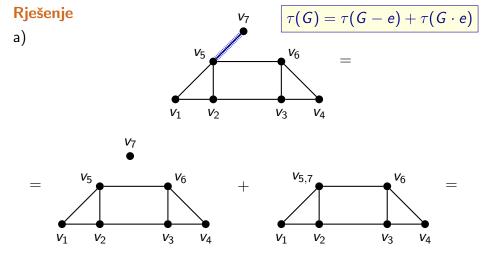
 v_2

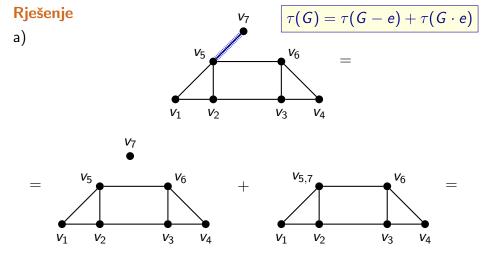
*V*3

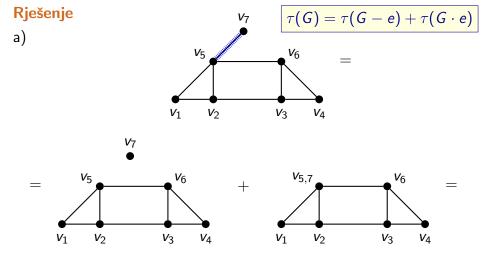


 V_4

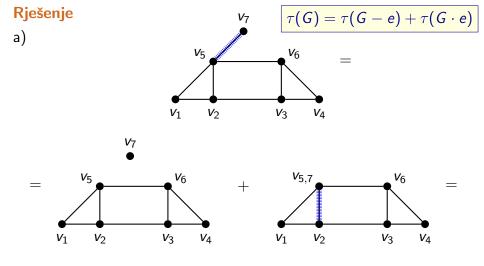
 v_2



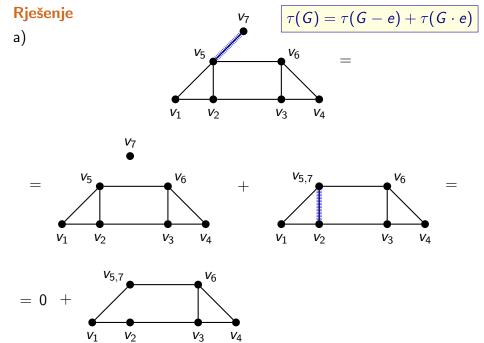




$$= 0 +$$



$$= 0 +$$



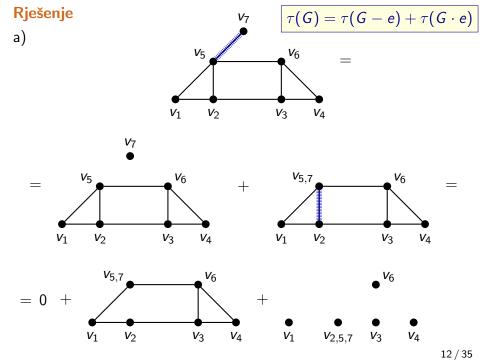
Rješenje
a)
$$v_{7} \qquad \tau(G) = \tau(G - e) + \tau(G \cdot e)$$

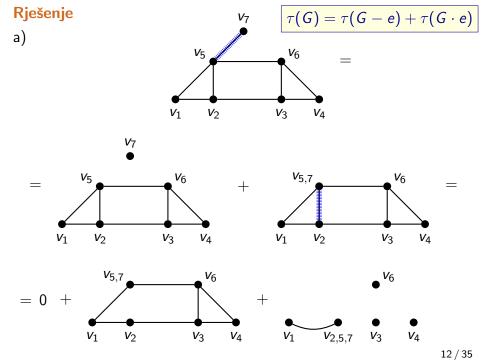
$$v_{7} \qquad v_{6} \qquad =$$

$$v_{7} \qquad v_{7} \qquad v$$

 v_2

*V*3





Rješenje
a)
$$v_{7} = v_{6} = v_{7} = v_{6} = v_{7} =$$

Rješenje
a)
$$v_{7} = v_{6} = v_{7} = v_{6} = v_{7} =$$

Rješenje
a)
$$v_{7} \qquad v_{7} \qquad$$

Rješenje
a)
$$v_{7} = v_{6} = v_{7}$$

$$v_{7} = v_{7} = v_{7}$$

$$v_{7} = v_{7} = v_{7} = v_{7}$$

$$v_{8} = v_{7} = v_{8} = v_{7}$$

$$v_{8} = v_{7} = v_{8} =$$

Rješenje
a)
$$v_{5} \qquad v_{6} = v_{6} = v_{7} \qquad v_{7} = v_{7} = v_{7} \qquad v_{7} = v_{7} = v_{7} \qquad v_{7} = v_{7} =$$

Rješenje
a)
$$v_{7} = v_{6} = v_{7} = v_{6} = v_{7}$$

$$= v_{7} = v_{7}$$

Rješenje
a)
$$v_{7} = v_{6} = v_{7} =$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \frac{v_{5,7}}{v_1 v_2} + \frac{v_6}{v_1 v_{2,5,7} v_3 v_4} =$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + v_{5,7} + v_{6} + v_{1} + v_{2,5,7} + v_{3} + v_{4}$$

$$= v_{5,7} + v_{6}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + v_{5,7} v_{6} + v_{1} v_{2,5,7} v_{3} v_{4} = v_{5,7} v_{1} v_{2} v_{3,6} v_{4}$$

$$= v_{1} v_{2} v_{3} v_{4} + v_{1} v_{2} v_{3,6} v_{4}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + v_{5,7} v_{6} + v_{1} v_{2} v_{3} v_{4} + v_{1} v_{2,5,7} v_{3} v_{4} = v_{5,7} v_{1} v_{2} v_{3,6} v_{4}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + v_{5,7} v_{6} + v_{1} v_{2,5,7} v_{3} v_{4} = v_{5,7} v_{1} v_{2} v_{3} v_{4} + v_{1} v_{2} v_{3,6} v_{4}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_{1} \\ v_{2,5,7} \\ v_3 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_5} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_{1,7} \\ v_{2,5,7} \\ v_3 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,5,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ \end{array}}_{v_{1,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1,7} \\ v_{2,7} \\ v_{3,7} \\ v_{4,7} \\ v_{$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_5,7 \\ v_1 \\ v_2 \\ \end{array}}_{v_2, 5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3,6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ v_4 \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_6 \\ v_5 \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_6 \\ v_5 \\ \end{array}}_{v_5,$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_5,7 \\ v_1 \\ v_2 \\ \end{array}}_{v_2,5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_1} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{3}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_{6} \\ v_{1} \\ v_{2,5,7} \\ v_{3} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{2}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_5,7 \\ v_1 \\ v_2 \\ \end{array}}_{v_2} + \underbrace{\begin{array}{c} v_{5,7} \\ v_3,6 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2}, 5,7 \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_1} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_5,7} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_5,7 \\ v_1 \\ v_2 \\ \end{array}}_{v_2, 5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_1} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3, 6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_1} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{2,5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3} + \underbrace{\begin{array}{c} v_6 \\ v_5,7 \\ v_1 \\ v_2 \\ \end{array}}_{v_2, 5,7} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_1} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2, 5,7 \\ \end{array}}_{v_3, 6} + \underbrace{\begin{array}{c} v_6 \\ v_4 \\ \end{array}}_{v_1} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{2,5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ \end{array}}_{v_{3,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{3,6} \\ \end{array}}_{v_{4,6}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ \end{array}}_{v_{5,7}} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 0 + \underbrace{\begin{array}{c} v_{5,7} \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ \end{array}}_{v_3} \underbrace{\begin{array}{c} v_6 \\ v_1 \\ v_2 \\ v_3 \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{5,7} \\ v_{1} \\ v_{2} \\ v_{3,6} \\ \end{array}}_{v_4} + \underbrace{\begin{array}{c} v_{5,7} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_4} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_5} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1} \\ v_{2,5,7} \\ v_{3,6} \\ v_{4} \\ \end{array}}_{v_{1}} = \underbrace{\begin{array}{c} v_{5,7} \\ v_{1}$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$au(G) = au(G - e) + au(G \cdot e)$$

= 6

 v_1

 $V_{2,5,7}$

V_{3,6}

 V_4

$$= 6 + \frac{\tau(G) = \tau(G - e) + \tau(G \cdot e)}{}$$

 $v_{2,5,7}$

*V*₃

 v_1

$$+ \underbrace{\begin{array}{c} V_{6} \\ V_{1} \\ V_{2,5,7} \\ V_{3} \\ V_{4} \end{array}} + \underbrace{\begin{array}{c} V_{6} \\ V_{1} \\ V_{2,5,7} \\ V_{3,6} \\ V_{4} \\ \end{array}} =$$

$$= 6 + 4 \cdot 2$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$+ \bigvee_{V_1 \quad V_{2,5,7} \quad V_3 \quad V_4}^{V_6} + \bigvee_{V_1 \quad V_{2,5,7} \quad V_{3,6} \quad V_4} =$$

$$= 6 + 4 \cdot 2 +$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

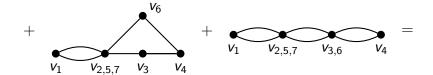
$$+ \bigvee_{V_1 \quad V_{2,5,7} \quad V_3 \quad V_4}^{V_6} + \bigvee_{V_1 \quad V_{2,5,7} \quad V_{3,6} \quad V_4} =$$

$$= 6 + 4 \cdot 2 + 2 \cdot 4$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

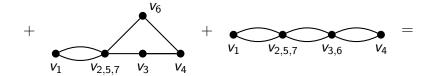
$$= 6 + 4 \cdot 2 + 2 \cdot 4 +$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



$$= 6 + 4 \cdot 2 + 2 \cdot 4 + 2 \cdot 2 \cdot 2$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$



$$= 6 + 4 \cdot 2 + 2 \cdot 4 + 2 \cdot 2 \cdot 2 = 30$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

$$= 6 + 4 \cdot 2 + 2 \cdot 4 + 2 \cdot 2 \cdot 2 = 30$$

$$\tau(G) = 30$$

$$\tau(G) = \tau(G - e) + \tau(G \cdot e)$$

Implementacija BFS algoritma

```
procedure BFS(G, s)
    for u \in V(G) \setminus \{s\} do

    inicijalizacija za sve vrhove osim vrha s

        color[u] \leftarrow WHITE

⊳ vrhovi su bijele boje

        d[u] \leftarrow \infty
                                                                 \triangleright vrhovi su na udaljenosti \infty od vrha s
        \pi[u] \leftarrow \text{NIL}

    ∨rhovi nemaju roditelje

    color[s] \leftarrow GRAY

    ∨rh s je sive boje (vrh je posjećen, ali nije istražen)

    d[s] \leftarrow 0

    vrh s je na udaljenosti 0 od samoga sebe

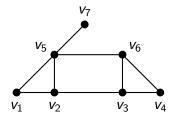
    \pi[s] \leftarrow \text{NIL}

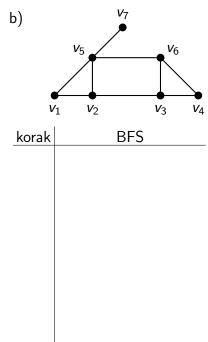
    vrh s nema roditelia

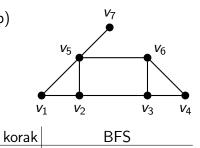
    Q \leftarrow \emptyset
                                          \triangleright inicijalizacija reda Q koji će se puniti sa sivim vrhovima
                                                                         ⊳ sivi vrh s stavi na kraj reda Q
    ENQUEUE (Q, s)
    while Q \neq \emptyset do
                                                                                > sve dok ima sivih vrhova
        u \leftarrow \text{DEQUEUE}(Q)
                                                                  \triangleright uzmi sivi vrh u koji je prvi u redu Q
        for v \in Adj[u] do
                                                                     if color[v] = WHITE then

    b ako je vrh v bijele boje

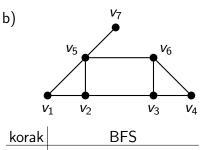
                 color[v] \leftarrow GRAY
                                                                                ⊳ pridruži vrhu v sivu boju
                 d[v] \leftarrow d[u] + 1
                                              \triangleright udaljenost v od s je za 1 veća od udaljenosti u od s
                 \pi[v] \leftarrow u
                                                                                  \triangleright vrh u je roditelj vrha v
                 ENQUEUE (Q, v)
                                                                         ⊳ stavi sivi vrh v na kraj reda Q
        color[u] \leftarrow BLACK
                                                     ▷ pridruži vrhu u crnu boju (vrh u je istražen)
                                                                                                                14/35
```



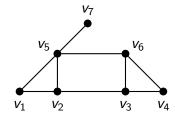




	$\pi(v)$	d(v)
v_1		
<i>V</i> ₂		
<i>V</i> ₃		
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
V ₇		

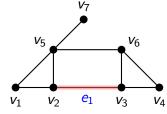


	$\pi(v)$	d(v)
v_1		
v ₂		
<i>V</i> ₃	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
V ₇		



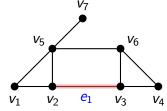
korak	BFS
1	

	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
v ₂		
V 3	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
<i>V</i> ₇		



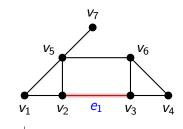
korak	BFS
1	

	$\pi(v)$	d(v)
v_1		
v ₂		
<i>V</i> ₃	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		



ν	1	v ₂	CI.	<i>v</i> ₃	v ₄
korak			BFS		
1	e_1 ,	u =	<i>V</i> ₃		

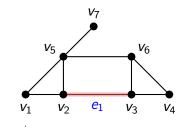
	$\pi(v)$	d(v)
v_1		
v ₂		
<i>V</i> ₃	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
<i>V</i> ₆ <i>V</i> ₇		



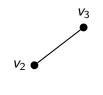
korak		BFS	
1	e_1 ,	$u=v_3$	



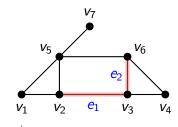
	$\pi(v)$	d(v)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
V ₇		



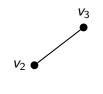
korak	BFS	
1	$e_1, u = v_3$	
2		



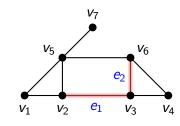
	$\pi(v)$	d(v)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
V ₇		



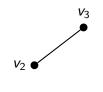
korak	BFS	
1	$e_1, u = v_3$	
2		



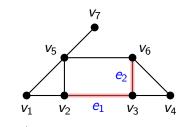
	$\pi(v)$	d(v)
v_1		
v ₂	<i>V</i> ₃	1
V 3	-	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
V ₇		



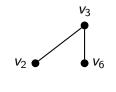
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$



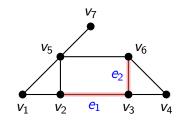
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
v ₂	<i>V</i> ₃	1
V 3	-	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆		
V ₇		



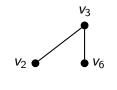
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$



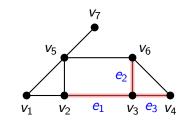
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
<i>V</i> ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆	<i>V</i> ₃	1
<i>V</i> ₇		



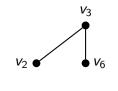
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$
3	



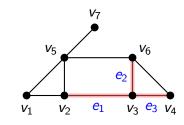
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄		
V ₅		
<i>V</i> ₆	<i>V</i> ₃	1
V ₇		



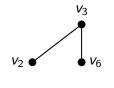
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$
3	



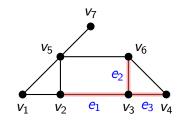
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄		
V ₅		
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



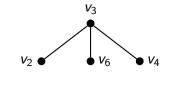
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	



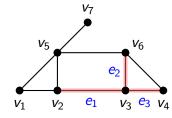
	$\pi(v)$	d(v)
v_1		
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄		
<i>V</i> ₅		
<i>V</i> ₆	<i>V</i> 3	1
V 7		



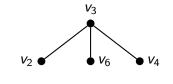
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$
3	$e_1e_2e_3,\ u=v_3$



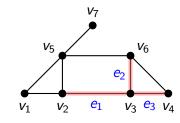
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅		
V ₆	<i>V</i> 3	1
V 7		



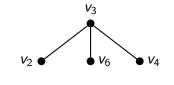
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$
3	$e_1e_2e_3, \ u=v_3$
4	



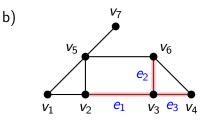
	$\pi(v)$	d(v)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅		
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



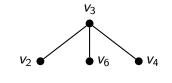
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3,\ u=v_2$



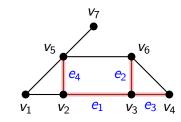
	$\pi(v)$	d(v)
v_1		
v ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅		
V ₆	<i>V</i> 3	1
V ₇		



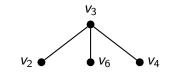
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3,\ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5		



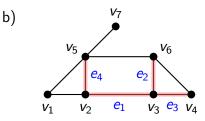
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅		
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



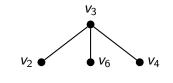
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5		



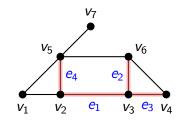
	$\pi(v)$	d(v)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅		
<i>V</i> ₆	<i>V</i> 3	1
V 7		



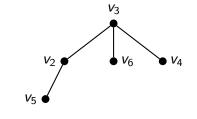
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	



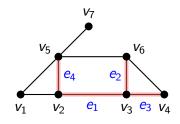
	$\pi(v)$	d(v)
v_1		
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅		
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



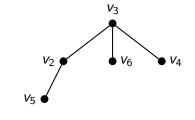
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	



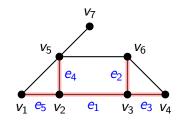
	$\pi(v)$	d(v)
v_1		
V ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



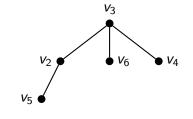
korak	BFS
1	$e_1, u=v_3$
2	$e_1e_2, u=v_3$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_2$
5	$e_1e_2e_3e_4, \ u=v_2$
6	



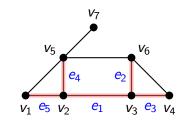
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



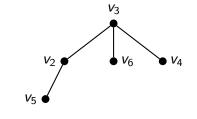
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6		



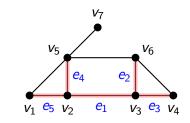
	$\pi(v)$	<i>d</i> (<i>v</i>)
v_1		
V ₂	<i>V</i> ₃	1
<i>V</i> 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



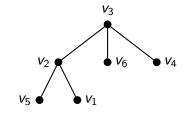
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3,\ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, u=v_2$	



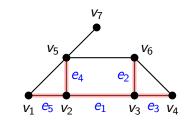
	$\pi(v)$	d(v)
v_1		
V ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



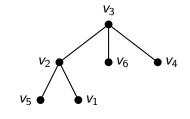
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	



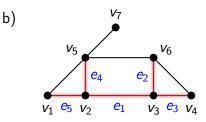
	$\pi(v)$	d(v)
v_1	v ₂	2
<i>V</i> ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



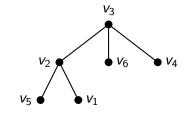
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7		



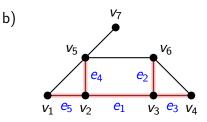
	1	
	$\pi(v)$	d(v)
v_1	V ₂	2
v ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



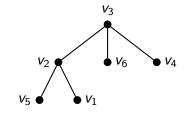
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7	$e_1e_2e_3e_4e_5, \ u=v_6$	



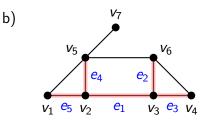
	$\pi(v)$	d(v)
v_1	v ₂	2
<i>V</i> ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



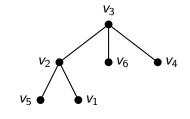
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3,\ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7	$e_1e_2e_3e_4e_5, \ u=v_6$	
8		



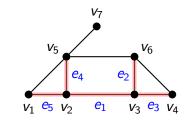
	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



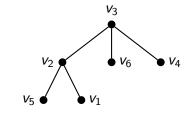
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7	$e_1e_2e_3e_4e_5, \ u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	



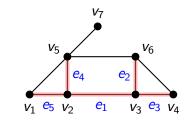
	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	-	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



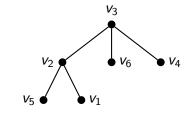
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3,\ u=v_3$	
4	$e_1e_2e_3,\ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9		



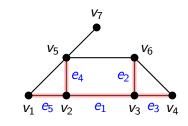
		1/)
	$\pi(v)$	d(v)
v_1	v ₂	2
V ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



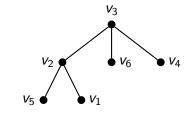
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9	$e_1e_2e_3e_4e_5, \ u=v_5$	



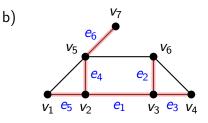
		1/)
	$\pi(v)$	d(v)
v_1	v ₂	2
V ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



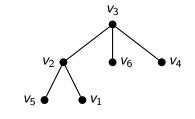
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9	$e_1e_2e_3e_4e_5, \ u=v_5$	
10		



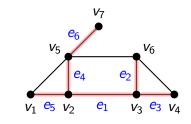
	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
V ₇		



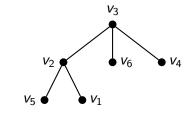
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3,\ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9	$e_1e_2e_3e_4e_5, u=v_5$	
10		



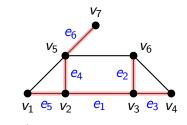
	1	
	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



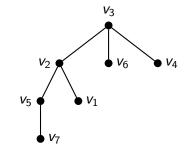
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9	$e_1e_2e_3e_4e_5, u=v_5$	
10	$e_1e_2e_3e_4e_5e_6, u=v_5$	



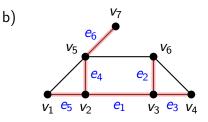
	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇		



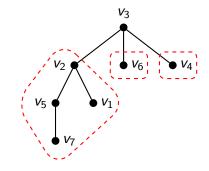
korak	BFS	
1	$e_1, u = v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3, \ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, \ u=v_2$	
7	$e_1e_2e_3e_4e_5, \ u=v_6$	
8	$e_1e_2e_3e_4e_5, \ u=v_4$	
9	$e_1e_2e_3e_4e_5, \ u=v_5$	
10	$e_1e_2e_3e_4e_5e_6, u=v_5$	



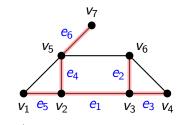
	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
V 3	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇	<i>V</i> ₅	3



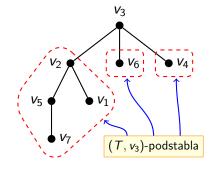
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3,\ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9	$e_1e_2e_3e_4e_5, u=v_5$	
10	$e_1e_2e_3e_4e_5e_6, u=v_5$	



	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇	<i>V</i> ₅	3

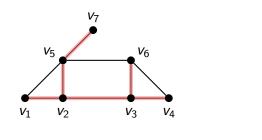


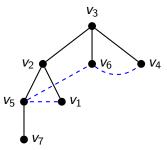
korak	BFS	
1	$e_1, u=v_3$	
2	$e_1e_2, u=v_3$	
3	$e_1e_2e_3,\ u=v_3$	
4	$e_1e_2e_3, \ u=v_2$	
5	$e_1e_2e_3e_4, \ u=v_2$	
6	$e_1e_2e_3e_4e_5, u=v_2$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_4$	
9	$e_1e_2e_3e_4e_5, u=v_5$	
10	$e_1e_2e_3e_4e_5e_6, u=v_5$	



	$\pi(v)$	d(v)
v_1	V ₂	2
V ₂	<i>V</i> ₃	1
<i>V</i> ₃	_	0
<i>V</i> ₄	<i>V</i> 3	1
<i>V</i> ₅	V 2	2
<i>V</i> ₆	<i>V</i> 3	1
<i>V</i> ₇	<i>V</i> ₅	3

Neka svojstva BFS algoritma





Neka je G povezani graf i (T, v) korijensko stablo dobiveno BFS algoritmom započetom u vrhu $v \in V(G)$.

• Krajevi svakog brida povezanog grafa G koji ne pripada BFS stablu (T, v) nalaze se na istom ili susjednim nivoima stabla (T, v).

Neka svojstva BFS algoritma

- U povezanom grafu G postoji ciklus neparne duljine akko postoji brid iz $E(G) \setminus E(T)$ koji ima oba kraja na istom nivou BFS stabla (T, v).
- U povezanom grafu G postoji ciklus koji sadrži vrh $v \in V(G)$ akko postoji brid iz $E(G) \setminus E(T)$ čiji krajevi pripadaju različitim (T, v)-podstablima BFS stabla (T, v).
- U povezanom grafu G postoji ciklus koji sadrži brid {v, w} akko postoji brid iz E(G) \ E(T) kojemu jedan kraj pripada (T, v)-podstablu s korijenom w, a drugi kraj pripada nekom drugom (T, v)-podstablu.

Nivoi u BFS stablu

Standardni BFS algoritam pokrenut u vrhu $v \in V(G)$ daje udaljenosti d(y) vrha v do svakog vrha $y \in V(G)$.

Pomoću vrijednosti $\pi(y)$ rekonstruiraju se najkraći putovi od vrha v do svih preostalih vrhova u grafu G.

Za svaki brid $\{x,y\}$ koji ne pripada BFS stablu (T,v), ispitivanjem uvjeta d(x)=d(y) dobivamo algoritam koji daje odgovor na pitanje "Postoji li u grafu G ciklus neparne duljine?".

BFS podstabla

Pretpostavimo da unutar BFS algoritma pokrenutog iz vrha $v \in V(G)$ za svaki vrh $y \in V(G)$ spremamo informaciju $\alpha(y)$ kojem (T, v)-podstablu vrh y pripada.

Za svaki brid $\{x,y\}$ koji ne pripada BFS stablu (T,v), istraživanjem vrijednosti $\alpha(x)$ i $\alpha(y)$ dobivamo

- ullet algoritam koji određuje postoji li u grafu G ciklus koji sadrži vrh v,
- algoritam koji određuje postoji li u grafu G ciklus koji sadrži brid $\{v, w\}$.

BFS nivoi i BFS podstabla

Pretpostavimo da unutar BFS algoritma pokrenutog iz vrha $v \in V(G)$ za svaki vrh $y \in V(G)$ spremamo informacije d(y) i $\alpha(y)$.

Za svaki brid $\{x,y\}$ koji ne pripada BFS stablu (T,v), istraživanjem vrijednosti $\alpha(x)$ i $\alpha(y)$ dobivamo

- algoritam koji određuje duljinu najkraćeg ciklusa u grafu G koji sadrži vrh v,
- algoritam koji određuje duljinu najkraćeg ciklusa u grafu G koji sadrži brid $\{v, w\}$.

Nakon što prvi put pronađemo brid $\{x,y\} \in E(G) \setminus E(T)$ za koji je $\alpha(x) \neq \alpha(y)$, tada uspoređujemo vrijednosti d(x) i d(y).

Ako je d(x) = d(y), tada algoritam završava.

Ako je $d(x) \neq d(y)$, npr. d(x) < d(y), tada moramo nastaviti s istraživanjem vrhova koji se nalaze na nivou d(x) kako bismo saznali postoji li brid koji ima oba kraja na nivou d(x) koji pripadaju različitim (T, v)-podstablima.

Dakle, ako postoji ciklus u grafu G koji sadrži vrh v, duljina najkraćeg takvog ciklusa jednaka je 2d(x) + 1 ili 2d(x) + 2.

Modifikacije BFS algoritma

Određivanje struka grafa

Ako primijenimo algoritam za određivanje najkraćeg ciklusa u grafu G koji sadrži vrh v na svaki vrh $v \in V(G)$, dobivamo algoritam za određivanje struka grafa koji ima složenost $O(\nu \varepsilon)$.

Ako pritom još za svaki vrh $v \in V(G)$ spremamo informaciju $\pi(v)$, možemo rekonstruirati jedan takav najkraći ciklus.

Neki problemi su ipak teški

Odrediti ciklus neparne duljine u grafu G koji sadrži vrh v.

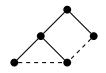
- Ovaj problem je u općenitom slučaju jednako težak kao i problem ispitivanja je li graf Hamiltonov.
- Problem je težak jer nemamo općenitu tvrdnju koja bi davala nužne i dovoljne uvjete za postojanje neparnog ciklusa u grafu G koji sadrži zadani vrh v.

Neki problemi su ipak teški

Tvrdnja 1.

Ako postoji brid $e \in E(G) \setminus E(T)$ koji ima oba kraja na istom nivou BFS stabla (T, v) i u različitim (T, v)-podstablima, tada u grafu G postoji neparni ciklus koji sadrži vrh v.

Gornja tvrdnja daje samo dovoljan, ali ne i nužan uvjet za postojanje neparnog ciklusa koji sadrži zadani vrh u grafu.

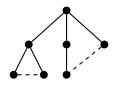


Neki problemi su ipak teški

Tvrdnja 2.

Ako u grafu G postoji neparni ciklus koji sadrži vrh v, tada postoji brid $e_1 \in E(G) \setminus E(T)$ koji ima oba kraja na istom nivou u BFS stablu (T,v) i postoji brid $e_2 \in E(G) \setminus E(T)$ čiji krajevi pripadaju različitim (T,v)-podstablima.

Gornja tvrdnja daje samo nužan, ali ne i dovoljan uvjet za postojanje neparnog ciklusa koji sadrži zadani vrh u grafu.



Rekurzivna implementacija DFS algoritma

```
procedure DFS(G)
   for u \in V(G) do
                                                      ▷ inicijalizacija za sve vrhove grafa G
       color[u] \leftarrow WHITE

    ∨rhovi su biiele boie

       \pi[u] \leftarrow \text{NIL}
                                                                    ▷ vrhovi nemaju roditelje
   time \leftarrow 0
                                                     ▷ globalna varijabla koja mjeri vrijeme
   for u \in V(G) do
                                                                    if color[u] = WHITE then
                                                                    \triangleright ako je vrh u bijele boje
           DFS_VISIT(u)

▷ posjeti vrh u s DFS_VISIT procedurom

procedure DFS_VISIT(u)
   color[u] \leftarrow GRAY
                                                                  ⊳ pridruži vrhu u sivu boju
   time \leftarrow time + 1
                                                                       ⊳ povećaj vrijeme za 1
   d[u] \leftarrow \text{time}
                                               ▷ spremanje trenutka kada je vrh u otkriven
   for v \in Adj[u] do
                                                         if color[v] = WHITE then

    b ako je vrh v bijele boje

           \pi[v] \leftarrow u
                                                                    \triangleright vrh u ie roditeli vrha v
           DFS_VISIT(\nu)

▷ posjeti vrh v s DFS_VISIT procedurom

   color[u] \leftarrow BLACK
                                            ▷ pridruži vrhu u crnu boju (vrh u je istražen)
   time \leftarrow time + 1

⊳ povećaj vrijeme za 1

   f[u] \leftarrow \mathsf{time}
                                               ⊳ spremanje trenutka kada je vrh u istražen
```

Implementacija DFS algoritma pomoću stoga

```
procedure DFS_VISIT(u)
    S \leftarrow \emptyset
                                      ▷ inicijalizacija stoga koji će se puniti s vrhovima grafa G
    PUSH(S, u)
                                                                             \triangleright stavi vrh u na stog S
   while S \neq \emptyset do
                                                                  \triangleright sve dok na stogu S ima vrhova
       x \leftarrow POP(S)

    □ uzmi vrh sa stoga S i spremi ga u varijablu x

       if color[x] = WHITE then

    b ako je vrh x bijele boje

           time \leftarrow time + 1
                                                                              ⊳ povećaj vrijeme za 1
           d[x] \leftarrow \text{time}
                                                     ▷ spremanje trenutka kada je vrh x otkriven
           color[x] \leftarrow GRAY
                                                                         ⊳ pridruži vrhu x sivu boju
           PUSH(S,x)
                                                                    \triangleright stavi ponovo vrh x na stog S
           for v \in Adj[x] do
                                                               if color[v] = WHITE then

    b ako je vrh v bijele boje

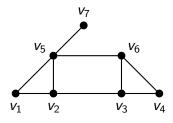
                   \pi[v] \leftarrow x

⊳ stavi da je vrh x roditelj vrha v

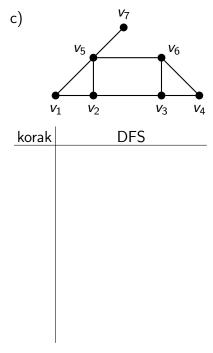
                    PUSH(S, v)
                                                                             else if color[x] = GRAY then

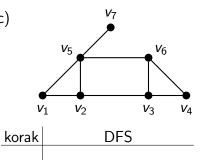
    b ako vrh x nije bijele boje, ali je sive boje

           time \leftarrow time + 1
                                                                              ⊳ povećaj vrijeme za 1
           f[x] \leftarrow \mathsf{time}
                                                      ▷ spremanje trenutka kada je vrh x istražen
           color[x] \leftarrow BLACK
                                                   ▷ pridruži vrhu x crnu boju (vrh x je istražen)
```

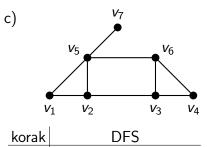


c)



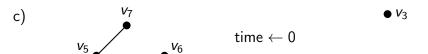


	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
v ₂			
V 3			
<i>V</i> ₄			
<i>V</i> ₅			
<i>v</i> ₆			
V ₇			



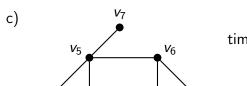
 $\mathsf{time} \leftarrow 0$

rak	DFS				
			$\pi(v)$	d(v)	f(v)
		v_1			
		v _2			
		V ₄			
		_ <i>V</i> ₅			
		_ <i>V</i> ₆			
		<i>V</i> ₇			



v_1	v ₂	<i>V</i> ₃	١
korak		DFS	

	$\pi(v)$	d(v)	f(v)
<i>v</i> ₁			
v ₂			
V 3			
<i>V</i> ₄			
<i>V</i> ₅			
<i>v</i> ₆			
<i>V</i> ₇			



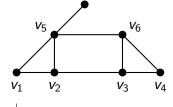
 $\mathsf{time} \leftarrow 1$

v	' 1	v_2		v_3	V_4
korak			DFS		

	$\pi(v)$	d(v)	f(v)
v_1			
V ₂			
V 3			
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			

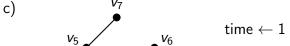
V₃





korak	DFS

	$\pi(v)$	d(v)	f(v)
v_1			
v ₂			
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			



	ν	' 1	V	2			<i>V</i> ₃	V ₂
kor	ak				D	FS		
	1							

	$\pi(v)$	d(v)	f(v)
v_1			
v ₂			
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			



	_	_			
	v_1	v_2	e_1	<i>V</i> ₃	V_4
kora	k		DFS		
	1				

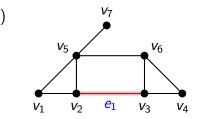
	$\pi(v)$	d(v)	f(v)
<i>v</i> ₁			
v ₂			
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V ₇			



	v_5		<i>V</i> ₆	
●	<i>V</i> ₂	e_1	<i>V</i> ₃	— ● V ₄

korak	DFS
1	$e_1, u = v_2$

	$\pi(v)$	d(v)	f(v)
v_1			
V ₂			
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
V 6			
<i>V</i> ₇			

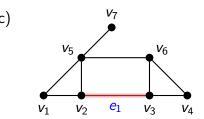


time	\leftarrow	1
------	--------------	---

<i>V</i> ₃	
v ₂	

korak			DFS	
1	e_1 ,	u =	V ₂	

	$\pi(v)$	d(v)	f(v)
v_1			
v ₂			
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			

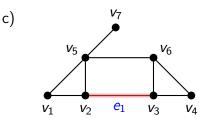


time	\leftarrow	2



korak	DFS
1	$e_1, u=v_2$

	$\pi(v)$	d(v)	f(v)
<i>v</i> ₁			
<i>V</i> ₂			
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			

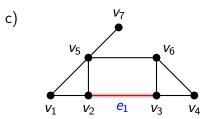


- 2

<i>V</i> 3	
v ₂	

DFS
$e_1, u = v_2$

	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
V ₆			
<i>V</i> ₇			

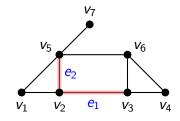


time	← 2	

V 3	
v ₂	

korak	DFS
1	$e_1, u = v_2$
2	

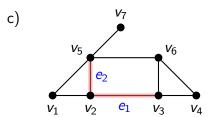
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			



time $\leftarrow 2$	• V ₂

DFS
$e_1, u = v_2$

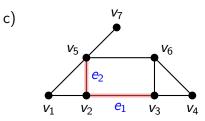
	$\pi(v)$	d(v)	f(v)
v_1			
<i>v</i> ₂	<i>V</i> ₃	2	
<i>V</i> ₃		1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>v</i> ₆			
<i>V</i> ₇			



	<i>V</i> 3
,	v ₂

korak	<u>DFS</u>
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$

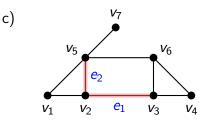
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
<i>V</i> 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>v</i> ₆			
<i>V</i> ₇			



	● <i>V</i> ₃
$time \leftarrow 2$	• <i>v</i> ₂
	• <i>v</i> ₅

korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	

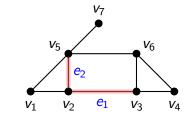
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			



	• <i>V</i> ₃
$time \leftarrow 3$	• <i>v</i> ₂
	v ₅

korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	

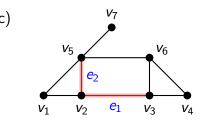
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅			
<i>V</i> ₆			
V 7			



	♥ <i>v</i> ₃
$time \leftarrow 3$	• <i>v</i> ₂
	v ₅

korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	

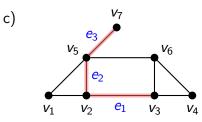
	$\pi(v)$	d(v)	f(v)
v_1			
<i>v</i> ₂	<i>V</i> ₃	2	
<i>V</i> ₃		1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>v</i> ₆			
<i>V</i> ₇			



$time \leftarrow 3$	• <i>v</i> ₂
	v_5

korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3		

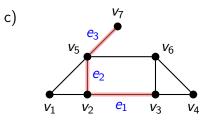
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
V 7			



$time \leftarrow 3$	• v ₂
	<i>V</i> ₅

korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	

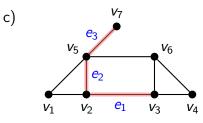
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇			



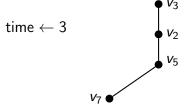
V₂
V ₅

korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$

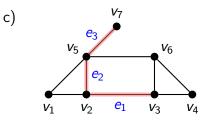
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
V 7			



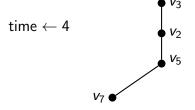
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$



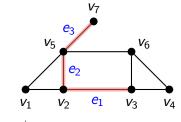
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇			



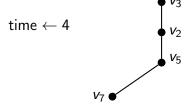
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$



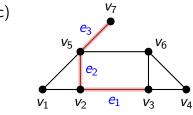
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇			



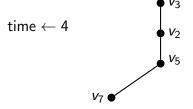
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$



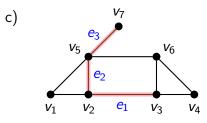
	$\pi(v)$	d(v)	f(v)
<i>v</i> ₁			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇	<i>V</i> ₅	4	



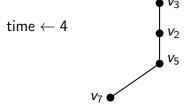
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	



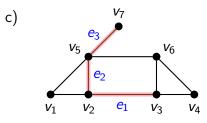
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> 7	<i>V</i> ₅	4	



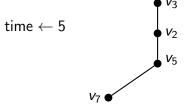
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$



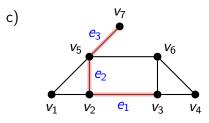
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇	<i>V</i> ₅	4	



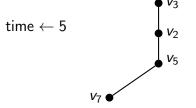
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$



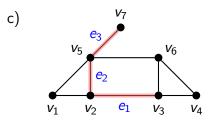
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇	<i>V</i> ₅	4	



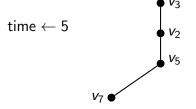
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$



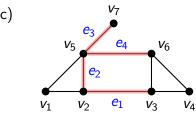
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>v</i> ₆			
<i>V</i> ₇	<i>V</i> 5	4	5



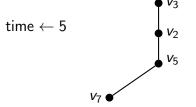
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	



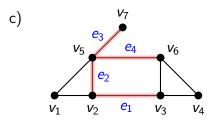
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
<i>V</i> ₇	<i>V</i> ₅	4	5



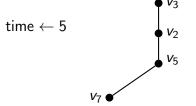
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$
4	$e_1e_2e_3,\ u=v_5$
5	



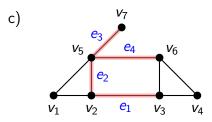
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
V ₄			
	V 2	3	
V ₆			
	<i>V</i> ₅	4	5



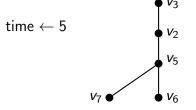
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$



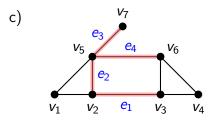
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
V ₄			
	V 2	3	
V 6			
	<i>V</i> ₅	4	5



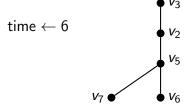
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$



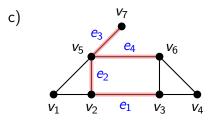
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
V ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆			
	<i>V</i> 5	4	5



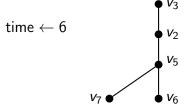
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$



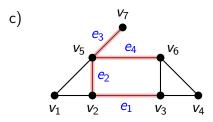
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
V ₄			
	V 2	3	
V ₆			
	<i>V</i> ₅	4	5



korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$



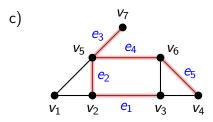
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
V ₄			
	V 2	3	
V ₆	<i>V</i> ₅	6	
V ₇	<i>V</i> ₅	4	5



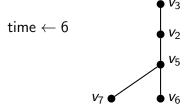
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$
4	$e_1e_2e_3,\ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	

time ← 6		• v ₂
		<i>V</i> ₅
	V ₇ ●	• <i>v</i> ₆

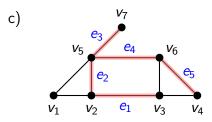
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
<i>V</i> ₇	<i>V</i> ₅	4	5



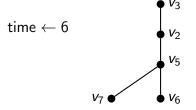
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6		



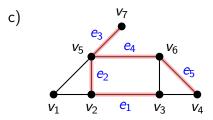
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3		1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
<i>V</i> ₇	<i>V</i> ₅	4	5



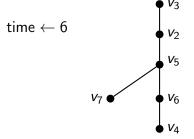
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$



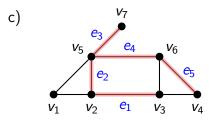
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
<i>v</i> ₁			
v ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
V 7	<i>V</i> ₅	4	5



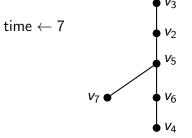
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$



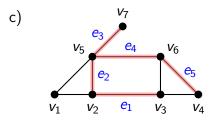
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄			
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



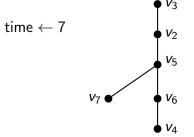
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$



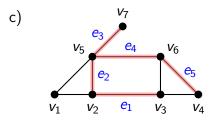
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
V ₄			
<i>V</i> ₅	V 2	3	
V ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



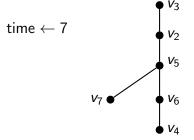
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$



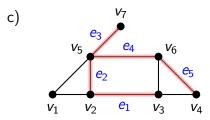
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
V ₄	<i>V</i> ₆	7	
	V 2	3	
V ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



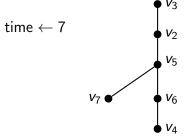
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, \ u=v_4$
7	



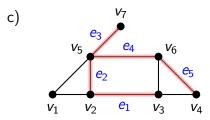
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
V ₇	<i>V</i> ₅	4	5



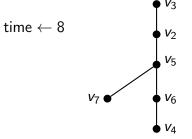
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, \ u=v_4$
7	$e_1e_2e_3e_4e_5, \ u=v_6$



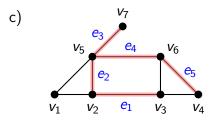
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
V 3	_	1	
V ₄	<i>V</i> ₆	7	
	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



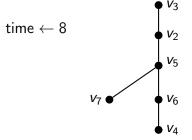
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, \ u=v_4$
7	$e_1e_2e_3e_4e_5, \ u=v_6$



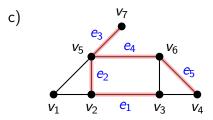
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
V ₄	<i>V</i> ₆	7	
	V 2	3	
V ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



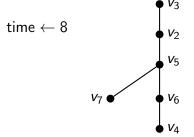
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, \ u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$



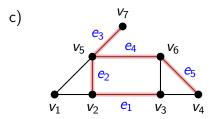
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
<i>V</i> ₃	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



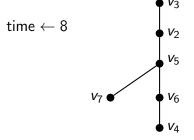
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, \ u=v_4$
7	$e_1e_2e_3e_4e_5, \ u=v_6$
8	



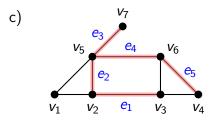
	$\pi(v)$	d(v)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
V ₇	<i>V</i> ₅	4	5



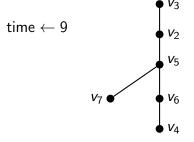
korak	DFS	
1	$e_1, u = v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3,\ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
	!	



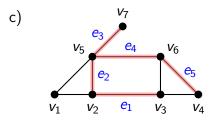
	$\pi(v)$	d(v)	f(v)
v_1			
V ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
V ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



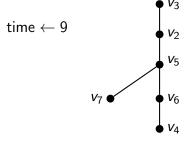
korak	DFS	
1	$e_1, u = v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3,\ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
	!	



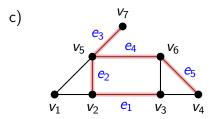
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	
	<i>V</i> ₅	4	5



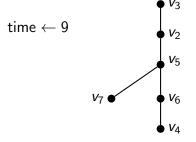
DFS	
$e_1, u = v_2$	
$e_1e_2, u=v_5$	
$e_1e_2e_3, \ u=v_7$	
$e_1e_2e_3, \ u=v_5$	
$e_1e_2e_3e_4, \ u=v_6$	
$e_1e_2e_3e_4e_5, u=v_4$	
$e_1e_2e_3e_4e_5, \ u=v_6$	
$e_1e_2e_3e_4e_5, u=v_5$	



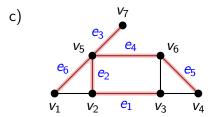
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
V ₇	<i>V</i> ₅	4	5



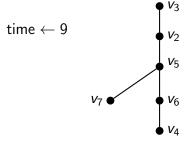
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, \ u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	



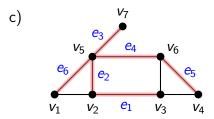
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



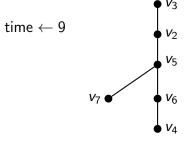
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$
4	$e_1e_2e_3,\ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	



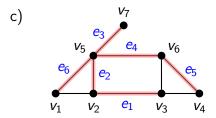
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
V ₇	<i>V</i> ₅	4	5



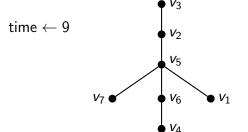
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$
4	$e_1e_2e_3,\ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$



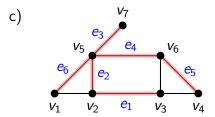
	$\pi(v)$	<i>d</i> (<i>v</i>)	f(v)
v_1			
v ₂	<i>V</i> ₃	2	
-V ₃	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



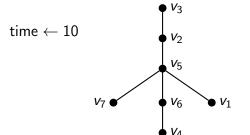
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$



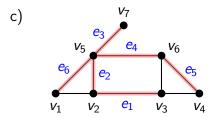
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
V ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



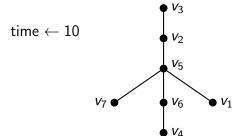
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3,\ u=v_7$
4	$e_1e_2e_3,\ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$



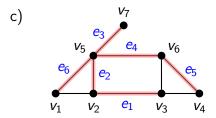
	$\pi(v)$	d(v)	f(v)
v_1			
<i>V</i> ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



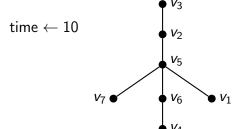
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3,\ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	



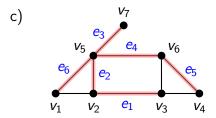
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	
<i>V</i> ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
V ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> ₅	4	5



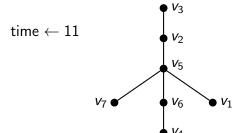
korak	DFS	
1	$e_1, u = v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3,\ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, \ u=v_4$	
7	$e_1e_2e_3e_4e_5, \ u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u=v_5$	



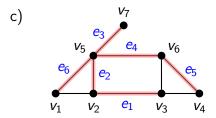
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	
V ₂	<i>V</i> ₃	2	
V 3	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
V ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> ₅	4	5



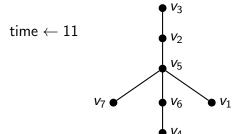
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u=v_5$	



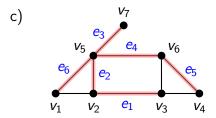
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	
<i>V</i> ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
V ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



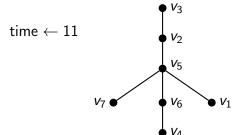
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u=v_5$	



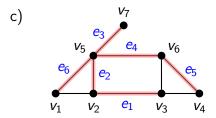
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
<i>V</i> ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



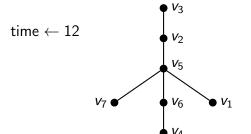
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u=v_5, u=v_2$	



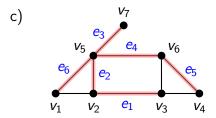
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
<i>V</i> ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
<i>V</i> ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> ₅	4	5



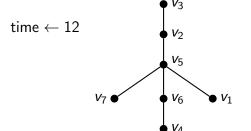
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u=v_5, u=v_2$	



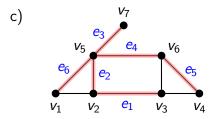
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
V ₂	<i>V</i> ₃	2	
	_	1	
V ₄	<i>V</i> ₆	7	8
	V 2	3	
V ₆	<i>V</i> ₅	6	9
V 7	<i>V</i> 5	4	5



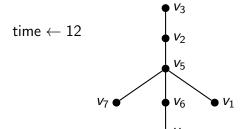
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u=v_5, u=v_2$	



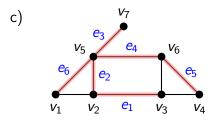
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
v ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	12
<i>V</i> ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> ₅	4	5



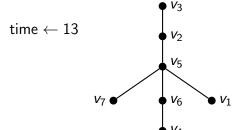
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$
	$u = v_5, u = v_2, u = v_3$



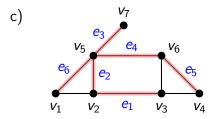
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
v ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	12
<i>V</i> ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> 5	4	5



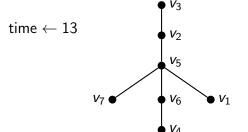
korak	DFS	
1	$e_1, u=v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u = v_5, u = v_2, u = v_3$	



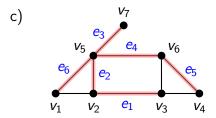
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
V ₂	<i>V</i> ₃	2	
V 3	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	12
V ₆	<i>V</i> ₅	6	9
V ₇	<i>V</i> ₅	4	5



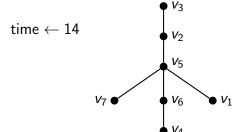
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$
	$u = v_5, u = v_2, u = v_3$



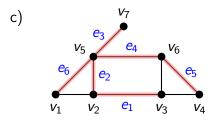
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
V ₂	<i>V</i> ₃	2	13
-V ₃	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	12
V ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



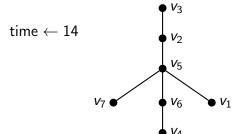
korak	DFS	
1	$e_1, u = v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3, \ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, u=v_6$	
8	$e_1e_2e_3e_4e_5, u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u = v_5, u = v_2, u = v_3$	



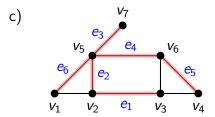
	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
V ₂	<i>V</i> ₃	2	13
-V ₃	_	1	
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	12
V 6	<i>V</i> ₅	6	9
V ₇	<i>V</i> ₅	4	5



korak	DFS	
1	$e_1, u = v_2$	
2	$e_1e_2, u=v_5$	
3	$e_1e_2e_3,\ u=v_7$	
4	$e_1e_2e_3, \ u=v_5$	
5	$e_1e_2e_3e_4, \ u=v_6$	
6	$e_1e_2e_3e_4e_5, u=v_4$	
7	$e_1e_2e_3e_4e_5, \ u=v_6$	
8	$e_1e_2e_3e_4e_5, \ u=v_5$	
9	$e_1e_2e_3e_4e_5e_6, u=v_1$	
	$u = v_5, u = v_2, u = v_3$	

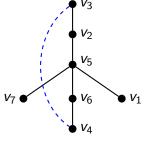


	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
<i>V</i> ₂	<i>V</i> ₃	2	13
	_	1	14
V ₄	<i>V</i> ₆	7	8
	V 2	3	12
V ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5

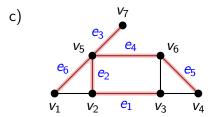


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$
	$u = v_5, u = v_2, u = v_3$



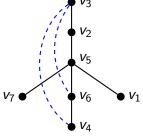


	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
<i>V</i> ₂	<i>V</i> ₃	2	13
V 3	_	1	14
<i>V</i> ₄	<i>V</i> ₆	7	8
<i>V</i> ₅	V 2	3	12
<i>V</i> ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> ₅	4	5

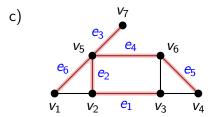


korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, \ u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$
	$u = v_5, u = v_2, u = v_3$



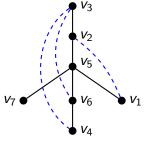


	$\pi(v)$	d(v)	f(v)
<i>v</i> ₁	<i>V</i> ₅	10	11
<i>V</i> ₂	<i>V</i> ₃	2	13
	_	1	14
V ₄	<i>V</i> ₆	7	8
	V 2	3	12
V ₆	<i>V</i> ₅	6	9
	<i>V</i> ₅	4	5



korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_5$
3	$e_1e_2e_3, \ u=v_7$
4	$e_1e_2e_3, \ u=v_5$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_4$
7	$e_1e_2e_3e_4e_5, u=v_6$
8	$e_1e_2e_3e_4e_5, u=v_5$
9	$e_1e_2e_3e_4e_5e_6, u=v_1$
	$u = v_5, u = v_2, u = v_3$





	$\pi(v)$	d(v)	f(v)
v_1	<i>V</i> ₅	10	11
<i>V</i> ₂	<i>V</i> ₃	2	13
	_	1	14
V ₄	<i>V</i> ₆	7	8
	V 2	3	12
V ₆	<i>V</i> ₅	6	9
<i>V</i> ₇	<i>V</i> ₅	4	5

Teorem

Ako primijenimo DFS algoritam na neusmjereni ili usmjereni graf G, tada za svaka dva vrha $v_1, v_2 \in V(G)$ vrijedi točno jedan od sljedeća tri uvjeta:

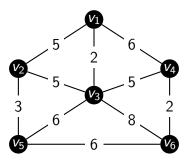
- Intervali $[d(v_1), f(v_1)]$ i $[d(v_2), f(v_2)]$ su disjunktni. Vrh v_1 nije potomak vrha v_2 i vrh v_2 nije potomak vrha v_1 .
- Interval $[d(v_1), f(v_1)]$ je sadržan unutar intervala $[d(v_2), f(v_2)]$. Vrh v_1 je potomak vrha v_2 u pripadnoj DFS šumi.
- Interval $[d(v_2), f(v_2)]$ je sadržan unutar intervala $[d(v_1), f(v_1)]$. Vrh v_2 je potomak vrha v_1 u pripadnoj DFS šumi.

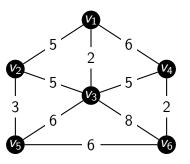


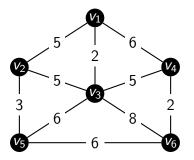
četvrti zadatak

Zadatak 4

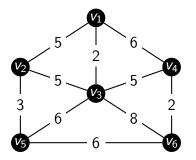
Pomoću Kruskalovog i Primovog algoritma pronađite minimalno razapinjuće stablo u težinskom grafu G.



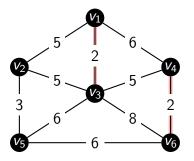




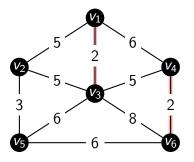
korak			
brid			
težina			



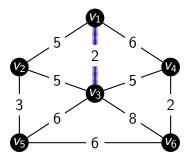
korak	1		
brid			
težina			



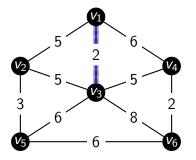
korak	1		
brid			
težina			



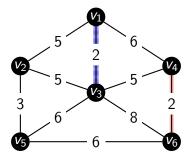
korak	1		
brid	v_1v_3		
težina	2		



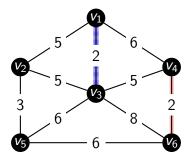
korak	1		
brid	v_1v_3		
težina	2		



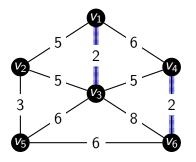
korak	1	2		
brid	v_1v_3			
težina	2			



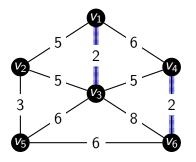
korak	1	2		
brid	v_1v_3			
težina	2			



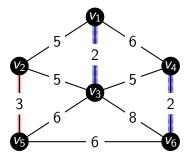
korak	1	2		
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆		
težina	2	2		



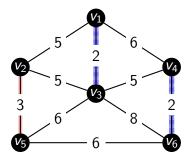
korak	1	2		
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆		
težina	2	2		



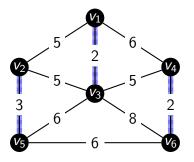
korak	1	2	3	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆		
težina	2	2		



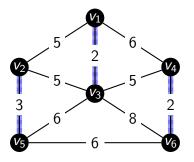
korak	1	2	3	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆		
težina	2	2		



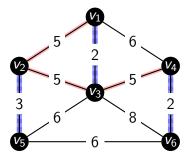
korak	1	2	3	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	
težina	2	2	3	



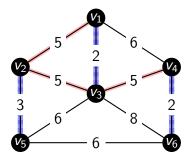
korak	1	2	3	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	
težina	2	2	3	



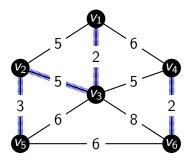
korak	1	2	3	4	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	V_2V_5		
težina	2	2	3		



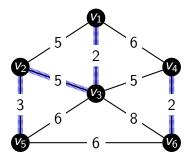
korak	1	2	3	4	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅		
težina	2	2	3		



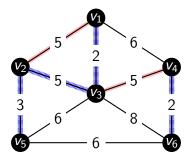
korak	1	2	3	4	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	V_2V_3	
težina	2	2	3	5	



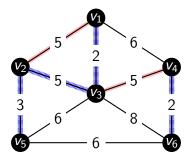
korak	1	2	3	4	
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	V_2V_3	
težina	2	2	3	5	



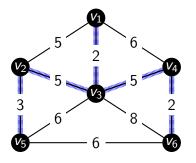
korak	1	2	3	4	5
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	V_2V_3	
težina	2	2	3	5	



korak	1	2	3	4	5
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	V_2V_3	
težina	2	2	3	5	



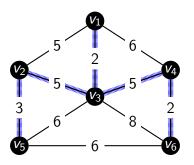
korak	1	2	3	4	5
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	V_2V_3	<i>V</i> ₃ <i>V</i> ₄
težina	2	2	3	5	5



korak	1	2	3	4	5
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	<i>V</i> ₂ <i>V</i> ₃	<i>V</i> ₃ <i>V</i> ₄
težina	2	2	3	5	5

Kruskal

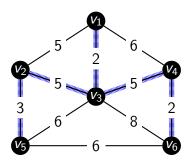
težina stabla:



korak	1	2	3	4	5
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	<i>V</i> ₂ <i>V</i> ₃	<i>V</i> ₃ <i>V</i> ₄
težina	2	2	3	5	5

Kruskal

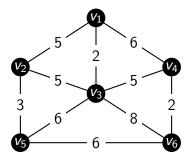
težina stabla: 2 + 2 + 3 + 5 + 5 = 17



korak	1	2	3	4	5
brid	v_1v_3	<i>v</i> ₄ <i>v</i> ₆	<i>V</i> ₂ <i>V</i> ₅	V_2V_3	<i>V</i> ₃ <i>V</i> ₄
težina	2	2	3	5	5

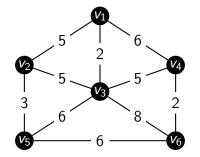


početni vrh: v_5





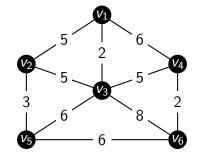
početni vrh: *v*₅



korak			
brid			
težina			



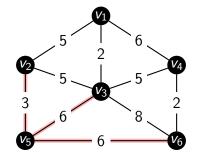
početni vrh: *v*₅



korak	1		
brid			
težina			



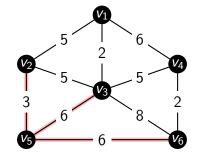
početni vrh: v_5



korak	1		
brid			
težina			



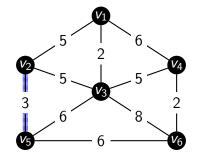
početni vrh: v_5



korak	1		
brid	<i>V</i> ₂ <i>V</i> ₅		
težina	3		

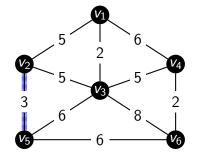


početni vrh: *v*₅



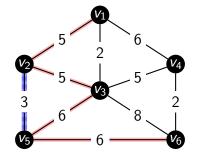
korak	1		
brid	<i>V</i> ₂ <i>V</i> ₅		
težina	3		





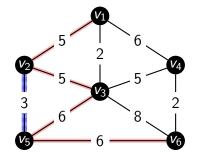
korak	1	2		
brid	<i>V</i> ₂ <i>V</i> ₅			
težina	3			





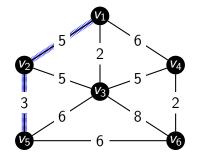
korak	1	2		
brid	<i>V</i> ₂ <i>V</i> ₅			
težina	3			





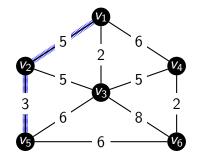
korak	1	2		
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2		
težina	3	5		





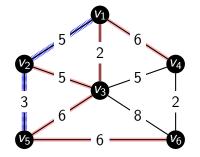
korak	1	2		
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2		
težina	3	5		





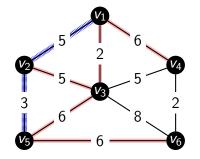
korak	1	2	3	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2		
težina	3	5		





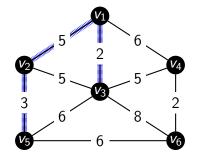
korak	1	2	3	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2		
težina	3	5		





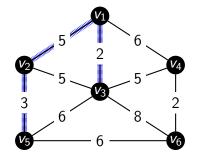
korak	1	2	3	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	
težina	3	5	2	





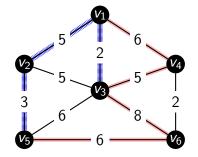
korak	1	2	3	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	
težina	3	5	2	





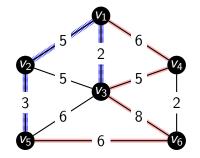
korak	1	2	3	4	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3		
težina	3	5	2		





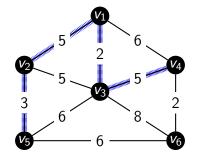
korak	1	2	3	4	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3		
težina	3	5	2		





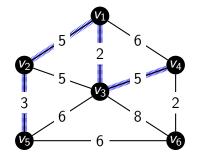
korak	1	2	3	4	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	
težina	3	5	2	5	





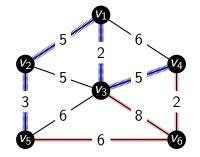
korak	1	2	3	4	
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	
težina	3	5	2	5	





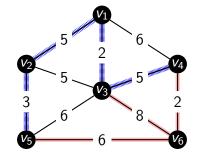
korak	1	2	3	4	5
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	
težina	3	5	2	5	

Prim



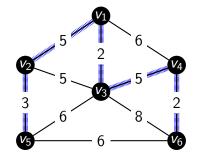
korak	1	2	3	4	5
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	
težina	3	5	2	5	

Prim



korak	1	2	3	4	5
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	<i>v</i> ₄ <i>v</i> ₆
težina	3	5	2	5	2

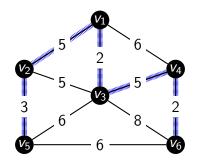
Prim



korak	1	2	3	4	5
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	<i>v</i> ₄ <i>v</i> ₆
težina	3	5	2	5	2

Prim

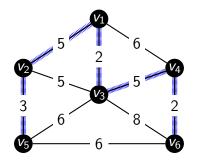
težina stabla:



korak	1	2	3	4	5
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	<i>v</i> ₄ <i>v</i> ₆
težina	3	5	2	5	2



težina stabla: 3 + 5 + 2 + 5 + 2 = 17

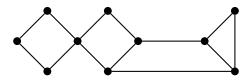


korak	1	2	3	4	5
brid	<i>V</i> ₂ <i>V</i> ₅	v_1v_2	v_1v_3	<i>V</i> ₃ <i>V</i> ₄	<i>V</i> ₄ <i>V</i> ₆
težina	3	5	2	5	2

peti zadatak

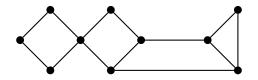
Zadatak 5

Odredite jednu jaku orijentaciju na grafu G ukoliko ona postoji.



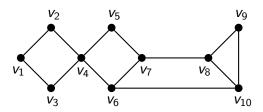
Zadatak 5

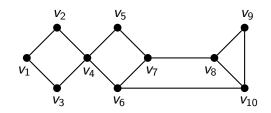
Odredite jednu jaku orijentaciju na grafu G ukoliko ona postoji.



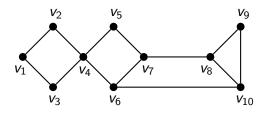
Rješenje

Jaka orijentacija na grafu G postoji jer graf G nema reznih bridova.



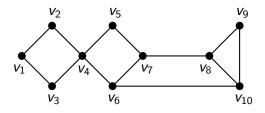


korak DFS



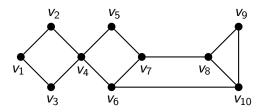
 $\bullet V_1$

korak	DFS



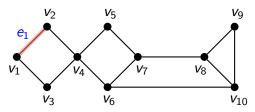
 $1 \bullet V_1$

korak	DFS



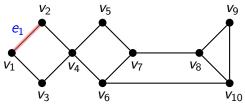
1 ●	<i>v</i> ₁
------------	-----------------------

korak 1	DFS



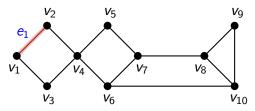
1	•	v_1
---	---	-------

korak	DFS
1	



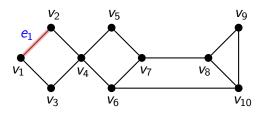
$1 \bullet V_1$	
-----------------	--

korak	DFS
1	$e_1, u = v_2$



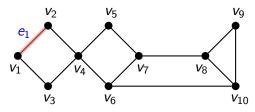


korak	DFS
1	$e_1, u=v_2$



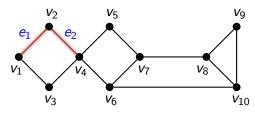
1	•	v_1
2	•	v ₂

korak	DFS
1	$e_1, u = v_2$



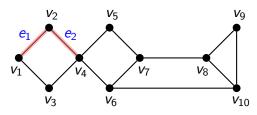
1	•	v_1
2	•	v ₂

korak	DFS
1	$e_1, u = v_2$
2	



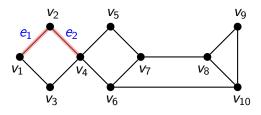
1	•	v_1
2	•	v ₂

korak	DFS
1	$e_1, u = v_2$
2	



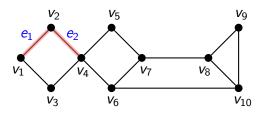
1	•	v_1
2	•	v ₂

korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$



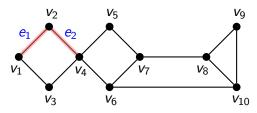


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$



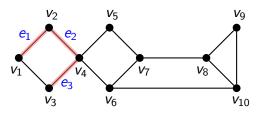


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$



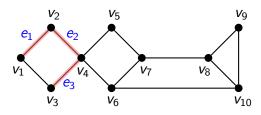


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	



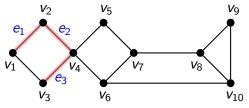


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	

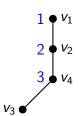


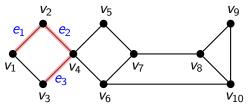


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$

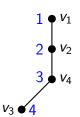


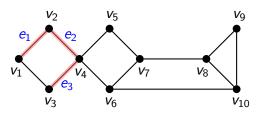
	V_3 V_6
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1 e_2 e_3$. $II = V_3$



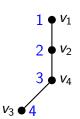


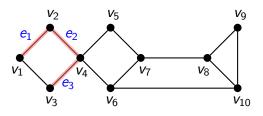
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$



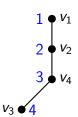


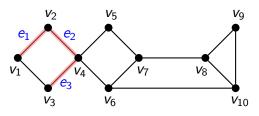
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	



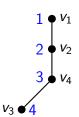


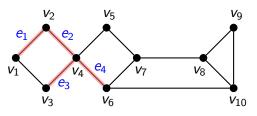
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$



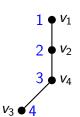


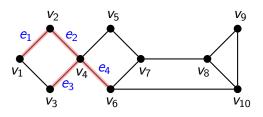
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	



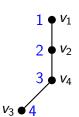


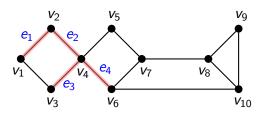
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	



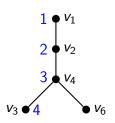


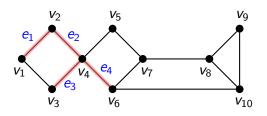
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$



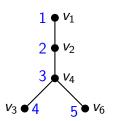


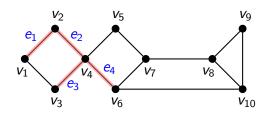
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$



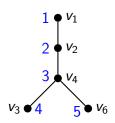


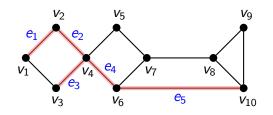
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$



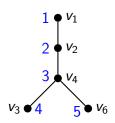


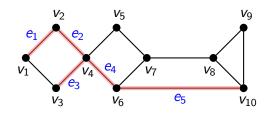
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	



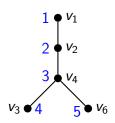


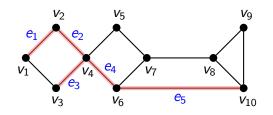
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	



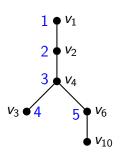


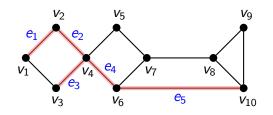
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$



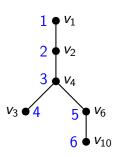


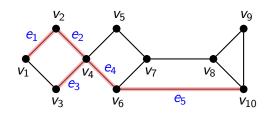
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$



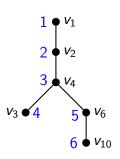


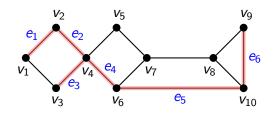
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$



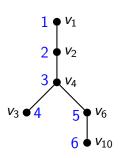


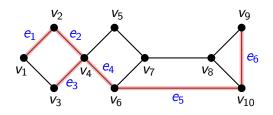
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	



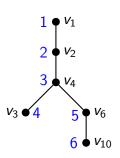


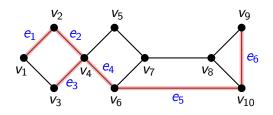
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	



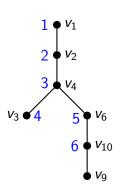


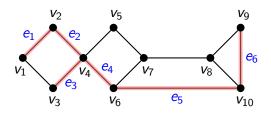
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$



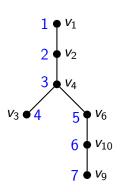


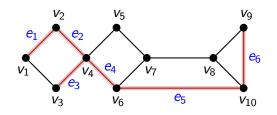
korak	DFS
1	$e_1, u=v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$



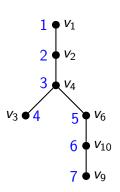


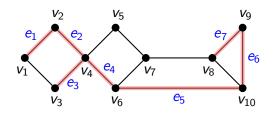
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$



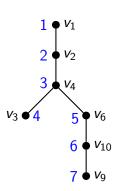


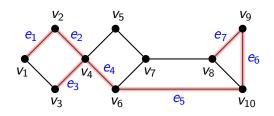
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	



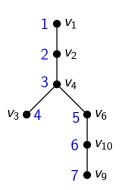


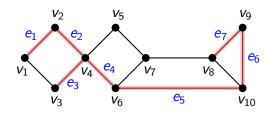
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	



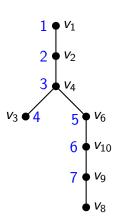


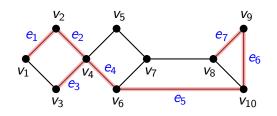
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$

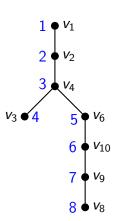


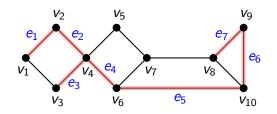


korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$

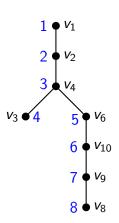


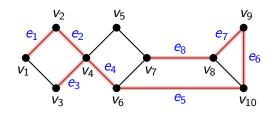




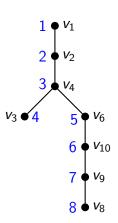


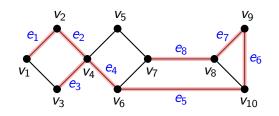
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	



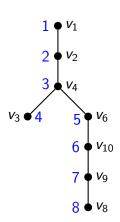


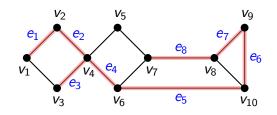
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	



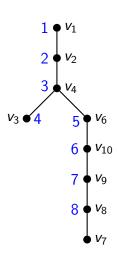


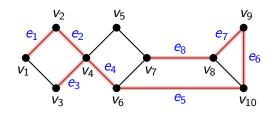
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$



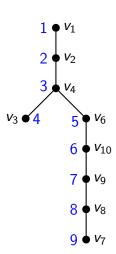


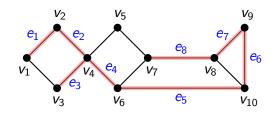
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$



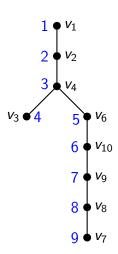


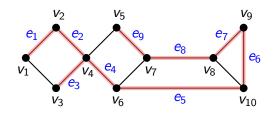
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$



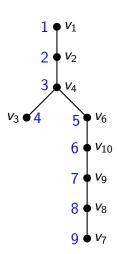


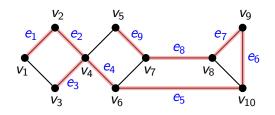
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$
10	



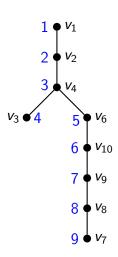


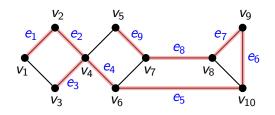
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$
10	



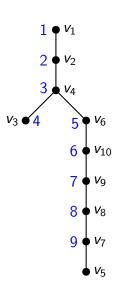


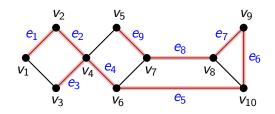
korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$
10	$e_1e_2e_3e_4e_5e_6e_7e_8e_9, u=v_5$





korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, \ u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$
10	$e_1e_2e_3e_4e_5e_6e_7e_8e_9, u=v_5$





korak	DFS
1	$e_1, u = v_2$
2	$e_1e_2, u=v_4$
3	$e_1e_2e_3, \ u=v_3$
4	$e_1e_2e_3, \ u=v_4$
5	$e_1e_2e_3e_4, \ u=v_6$
6	$e_1e_2e_3e_4e_5, u=v_{10}$
7	$e_1e_2e_3e_4e_5e_6, u=v_9$
8	$e_1e_2e_3e_4e_5e_6e_7, u=v_8$
9	$e_1e_2e_3e_4e_5e_6e_7e_8, u=v_7$
10	$e_1e_2e_3e_4e_5e_6e_7e_8e_9, u=v_5$

