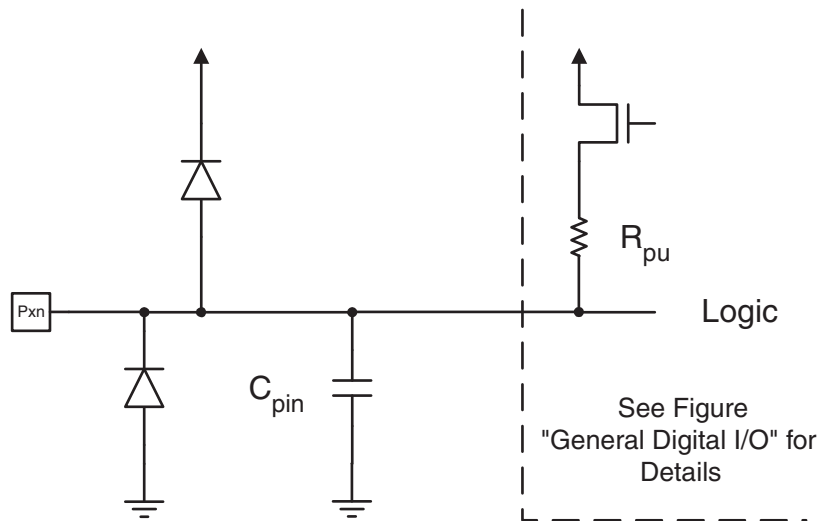


## 14. I/O-Ports

### 14.1 Overview

All AVR ports have true Read-Modify-Write functionality when used as general digital I/O ports. This means that the direction of one port pin can be changed without unintentionally changing the direction of any other pin with the SBI and CBI instructions. The same applies when changing drive value (if configured as output) or enabling/disabling of pull-up resistors (if configured as input). Each output buffer has symmetrical drive characteristics with both high sink and source capability. The pin driver is strong enough to drive LED displays directly. All port pins have individually selectable pull-up resistors with a supply-voltage invariant resistance. All I/O pins have protection diodes to both  $V_{CC}$  and Ground as indicated in [Figure 14-1](#). Refer to ["Electrical Characteristics" on page 317](#) for a complete list of parameters.

**Figure 14-1.** I/O Pin Equivalent Schematic



All registers and bit references in this section are written in general form. A lower case "x" represents the numbering letter for the port, and a lower case "n" represents the bit number. However, when using the register or bit defines in a program, the precise form must be used. For example, PORTB3 for bit no. 3 in Port B, here documented generally as PORTxn. The physical I/O Registers and bit locations are listed in ["Register Description" on page 94](#).

Three I/O memory address locations are allocated for each port, one each for the Data Register – PORTx, Data Direction Register – DDRx, and the Port Input Pins – PINx. The Port Input Pins I/O location is read only, while the Data Register and the Data Direction Register are read/write. However, writing a logic one to a bit in the PINx Register, will result in a toggle in the corresponding bit in the Data Register. In addition, the Pull-up Disable – PUD bit in MCUCR disables the pull-up function for all pins in all ports when set.

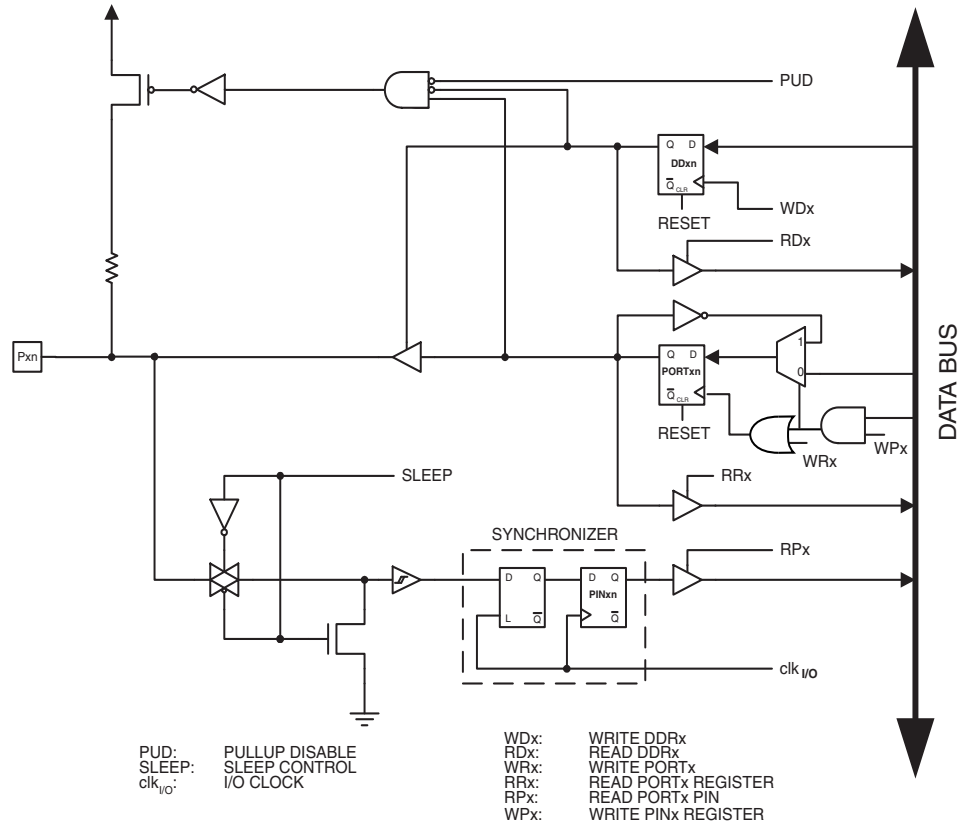
Using the I/O port as General Digital I/O is described in ["Ports as General Digital I/O" on page 78](#). Most port pins are multiplexed with alternate functions for the peripheral features on the device. How each alternate function interferes with the port pin is described in ["Alternate Port Functions" on page 82](#). Refer to the individual module sections for a full description of the alternate functions.

Note that enabling the alternate function of some of the port pins does not affect the use of the other pins in the port as general digital I/O.

## 14.2 Ports as General Digital I/O

The ports are bi-directional I/O ports with optional internal pull-ups. Figure 14-2 shows a functional description of one I/O-port pin, here generically called Pxn.

**Figure 14-2.** General Digital I/O<sup>(1)</sup>



Note: 1. WRx, WPx, WDx, RRx, RPx, and RDx are common to all pins within the same port. clk<sub>I/O</sub>, SLEEP, and PUD are common to all ports.

### 14.2.1 Configuring the Pin

Each port pin consists of three register bits: DDxn, PORTxn, and PINxn. As shown in "Register Description" on page 94, the DDxn bits are accessed at the DDRx I/O address, the PORTxn bits at the PORTx I/O address, and the PINxn bits at the PINx I/O address.

The DDxn bit in the DDRx Register selects the direction of this pin. If DDxn is written logic one, Pxn is configured as an output pin. If DDxn is written logic zero, Pxn is configured as an input pin.

If PORTxn is written logic one when the pin is configured as an input pin, the pull-up resistor is activated. To switch the pull-up resistor off, PORTxn has to be written logic zero or the pin has to be configured as an output pin. The port pins are tri-stated when reset condition becomes active, even if no clocks are running.

If PORTxn is written logic one when the pin is configured as an output pin, the port pin is driven high (one). If PORTxn is written logic zero when the pin is configured as an output pin, the port pin is driven low (zero).

## 14.2.2 Toggling the Pin

Writing a logic one to PINxn toggles the value of PORTxn, independent on the value of DDRxn. Note that the SBI instruction can be used to toggle one single bit in a port.

## 14.2.3 Switching Between Input and Output

When switching between tri-state ( $\{DDRxn, PORTxn\} = 0b00$ ) and output high ( $\{DDRxn, PORTxn\} = 0b11$ ), an intermediate state with either pull-up enabled ( $\{DDRxn, PORTxn\} = 0b01$ ) or output low ( $\{DDRxn, PORTxn\} = 0b10$ ) must occur. Normally, the pull-up enabled state is fully acceptable, as a high-impedance environment will not notice the difference between a strong high driver and a pull-up. If this is not the case, the PUD bit in the MCUCR Register can be set to disable all pull-ups in all ports.

Switching between input with pull-up and output low generates the same problem. The user must use either the tri-state ( $\{DDRxn, PORTxn\} = 0b00$ ) or the output high state ( $\{DDRxn, PORTxn\} = 0b11$ ) as an intermediate step.

Table 14-1 summarizes the control signals for the pin value.

**Table 14-1.** Port Pin Configurations

DDxn	PORTxn	PUD (in MCUCR)	I/O	Pull-up	Comment
0	0	X	Input	No	Tri-state (Hi-Z)
0	1	0	Input	Yes	Pxn will source current if ext. pulled low.
0	1	1	Input	No	Tri-state (Hi-Z)
1	0	X	Output	No	Output Low (Sink)
1	1	X	Output	No	Output High (Source)

## 14.2.4 Reading the Pin Value

Independent of the setting of Data Direction bit DDxn, the port pin can be read through the PINxn Register bit. As shown in Figure 14-2, the PINxn Register bit and the preceding latch constitute a synchronizer. This is needed to avoid metastability if the physical pin changes value near the edge of the internal clock, but it also introduces a delay. Figure 14-3 shows a timing diagram of the synchronization when reading an externally applied pin value. The maximum and minimum propagation delays are denoted  $t_{pd,max}$  and  $t_{pd,min}$  respectively.

## 14.4 Register Description

### 14.4.1 MCUCR – MCU Control Register

Bit	7	6	5	4	3	2	1	0	
0x35 (0x55)	–	BODS <sup>(1)</sup>	BODSE <sup>(1)</sup>	PUD	–	–	IVSEL	IVCE	MCUCR
Read/Write	R	R/W	R/W	R/W	R	R	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

Notes: 1. BODS and BODSE only available for picoPower devices ATmega48PA/88PA/168PA/328P

#### • Bit 4 – PUD: Pull-up Disable

When this bit is written to one, the pull-ups in the I/O ports are disabled even if the DDxn and PORTxn Registers are configured to enable the pull-ups ({DDxn, PORTxn} = 0b01). See ["Configuring the Pin" on page 78](#) for more details about this feature.

### 14.4.2 PORTB – The Port B Data Register

Bit	7	6	5	4	3	2	1	0	
0x05 (0x25)	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	PORTB
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

### 14.4.3 DDRB – The Port B Data Direction Register

Bit	7	6	5	4	3	2	1	0	
0x04 (0x24)	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	DDRB
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

### 14.4.4 PINB – The Port B Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	
0x03 (0x23)	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	PINB
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	

### 14.4.5 PORTC – The Port C Data Register

Bit	7	6	5	4	3	2	1	0	
0x08 (0x28)	–	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	PORTC
Read/Write	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

### 14.4.6 DDRC – The Port C Data Direction Register

Bit	7	6	5	4	3	2	1	0	
0x07 (0x27)	–	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	DDRC
Read/Write	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

### 14.4.7 PINC – The Port C Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	
0x06 (0x26)	–	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	PINC
Read/Write	R	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	N/A	N/A	N/A	N/A	N/A	N/A	N/A	

## 14.4.8 PORTD – The Port D Data Register

Bit	7	6	5	4	3	2	1	0	
0x0B (0x2B)	<b>PORTD7</b>	<b>PORTD6</b>	<b>PORTD5</b>	<b>PORTD4</b>	<b>PORTD3</b>	<b>PORTD2</b>	<b>PORTD1</b>	<b>PORTD0</b>	<b>PORTD</b>
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

## 14.4.9 DDRD – The Port D Data Direction Register

Bit	7	6	5	4	3	2	1	0	
0x0A (0x2A)	<b>DDD7</b>	<b>DDD6</b>	<b>DDD5</b>	<b>DDD4</b>	<b>DDD3</b>	<b>DDD2</b>	<b>DDD1</b>	<b>DDD0</b>	<b>DDRD</b>
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	0	0	0	0	0	0	0	0	

## 14.4.10 PIND – The Port D Input Pins Address<sup>(1)</sup>

Bit	7	6	5	4	3	2	1	0	
0x09 (0x29)	<b>PIND7</b>	<b>PIND6</b>	<b>PIND5</b>	<b>PIND4</b>	<b>PIND3</b>	<b>PIND2</b>	<b>PIND1</b>	<b>PIND0</b>	<b>PIND</b>
Read/Write	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	
Initial Value	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A	

Note: 1. Writing to the pin register provides toggle functionality for IO (see ["Toggling the Pin" on page 79](#))