

# Damiano Marsili

PhD student in Computing and Mathematical Sciences, Caltech, Pasadena, USA  
Email, Personal Website

## EDUCATION

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**California Institute of Technology**, Pasadena, USA  
PhD student in Computing and Mathematical Sciences

Sep 2023 — May 2028

**Johns Hopkins University**, Baltimore, USA  
BS Computer Science  
BA Mathematics

Aug 2020 — May 2023

## PUBLICATIONS

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**Recognize Any Object** (PDF)

(in preparation) Nov. 2024

*Damiano Marsili, Pietro Perona, Georgia Gkioxari*

- Proposed Single Instance Recognition, a novel visual perception task aimed at identifying object instances (e.g. *Bob's keys* vs. *Alice's keys*) from few samples, along with an accompanying benchmark.
- Demonstrated our method surpasses vision foundation models and state-of-the-art methods in personalized recognition.

**Visual Agentic AI for Spatial Reasoning with a Dynamic API** (PDF)

(in preparation) Nov. 2024

*Damiano Marsili\*, Rohun Agrawal\*, Yisong Yue, Georgia Gkioxari*

- Designed a training-free agentic visual programming approach, VADAR, that dynamically generates new skills in Python and significantly outperforms previous visual programming methods on spatial reasoning in 3D.
- Introduced Omni3D-Bench, a benchmark for 3D understanding with complex queries involving multiple reasoning steps.

## WORK EXPERIENCE

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**Amazon Robotics**

*Applied Science Intern*

Arlington, USA  
May 2023 — Sep 2023

- Trained an object-centric Vision Language Model (VLM) to resolve spatial relationships for the task of targeted grasping.
- Engineered a large Multi-Modal Spatial Relationship (MMSR) dataset composed of over 300,000 grasp samples.

**Applied Physics Laboratory**

*Research Assistant*

Baltimore, USA  
Aug 2022 — May 2023

- Worked on self-supervised training methods to train robots for gesture recognition using both synthetic and real data. Project funded by Army Research Labs (ARL).
- Leveraged novel techniques in transfer learning to mitigate the synthetic-to-real gap for gesture recognition.

**Malone Center for Engineering in Healthcare, Johns Hopkins University**

*Research Intern*

Baltimore, USA  
Feb 2022 — May 2022

- Developed simulation environments used to train reinforcement learning agents for autonomous ventilators.
- Explored the impact of various medical insults on pulmonary compliance in the simulation environment.

## TEACHING EXPERIENCE

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**Object Oriented Software Engineering**

*Teaching Assistant*

Johns Hopkins University  
Jan 2022 — May 2022

- Mentored a group of 7 students partaking in a semester-long software project.
- Arranged mock presentation sessions to provide feedback ahead of their final.

**Learning Den**

*Mathematics & Computer Science Tutor*

Johns Hopkins University  
Sep 2021 — Jan 2022

- Helped two students improve from a B- to an A-/A in Calculus II and Calculus III respectively.
- Constructed a tailored curriculum of practice sets to reinforce concepts the students found challenging.