

A Eulerian Model for the Dynamics of Polydisperse Evaporating sprays: Combining the Multi-Fluid Model with the Quadrature Method of Moments

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Outline

- 1 Context and Motivation
- 2 Overcoming of Multi-Fluid Limitations
 - Higher order method for polydispersion
 - Results
 - Droplet crossings method
- 3 Coupled model describing polydispersion and droplet crossing
 - Principles
 - Results

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Context

- Presence of fuel droplets in many industrial problems
 - aeronautics or automotive combustion chambers
 - industrial furnaces.

Modelling of droplets: key issue
Highly instationnary problems

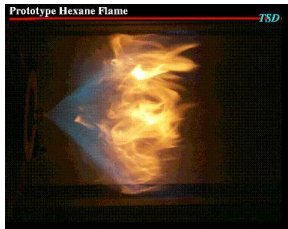


Figure: Source Prof. Edwards (Stanford)



Figure: Source C. Dumouchel (CORIA Rouen)

Context

Influence of the liquid phase on the **physical phenomenon**

- flame structure and dynamics
- combustion efficiency
- pollutants produced

modelling problems

- droplets-gas interactions
 - drag force, evaporation, heat transfer
- droplets-droplets interactions
 - coalescence, breakup

key issue: polydispersion

Statistical Description

- statistical description (spherical droplets)
Introduction of the **number density function** $f(t, \mathbf{x}, T, \mathbf{u}, \phi)$
→ ϕ droplets radius, surface or volume

$$f^R dR = f^S dS = f^V dV$$

following a Williams-Boltzmann equation : **Kinetic Model**

Williams, 1958

$$\underbrace{\partial_t f + \partial_x \cdot (fu)}_{\text{free transport}} + \underbrace{\partial_S (R_S f)}_{\text{vaporisation}} + \underbrace{\partial_u (Ff)}_{\text{drag}} + \underbrace{\partial_T (Ef)}_{\text{heat exchange}} = \underbrace{\Gamma}_{\text{collision operator}}$$

- Lagrangian Model

- Eulerian Multi-Fluid Model

Eulerian Multi-Fluid Model

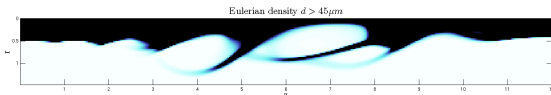
- Equilibrium hypothesis on velocity at fixed (t, x, S)
- Discretization in S by finite volume
→ equations on moments

Advantages:

- accurate description of polydispersion at moderate cost
- easy coupling between gas phase and liquid phase

Realisations:

- Free jet DNS calculation



- Limitations:

- 1st/2nd order accurate method
 - Need to have a lot of sections in ϕ to correctly model polydispersion
- Existence of a single velocity (conditioned by size)
 - Finite Stokes number droplet of same size have the same velocity (singularities)

De Chaisemartin et al, *Submitted to Journal of Computational Physics*

- Objectives:

- Increase the accuracy of the multi-fluid method
 - Massot et al *Submitted to Journal of Aerosol Science*
- Allow droplet crossings in collaboration with R . Fox
 - Desjardin et al, *Journal of Computational Physics*

Context of the study

Simplified Williams equation: $f(t, x, S, u)$

$$\partial_t f + \underbrace{\partial_x u f}_{\text{transport}} + \underbrace{\partial_u F f}_{\text{drag}} + \underbrace{\partial_S R_S f}_{\text{evaporation}} = 0$$

- Mass Moments: $m_k = \int_S S^k f(t, x, S, u) dS du$
- Velocity Moments: $\mathcal{M}_k = \int_u u^k f(t, x, S, u) dS du$
- $m_0 = \mathcal{M}_0$
- Coupling Mass and Velocity Moments:

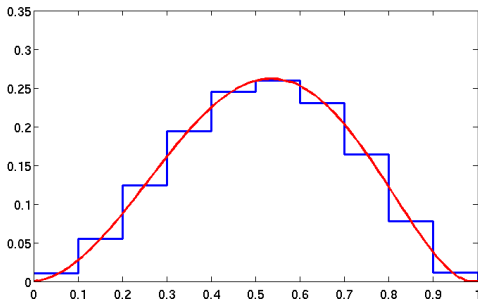
$$f(t, x, u, S) \rightarrow \int_{S, u} S^k u^k f dS du$$

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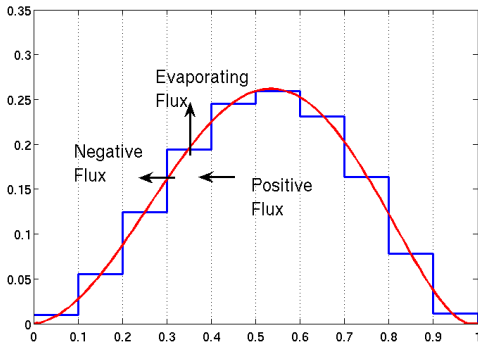
Multi-Fluid Method

- Several sections → mass ($m_{3/2}$) and momentum ($m_{3/2} \frac{\mathcal{M}_1}{\mathcal{M}_0}$)
- Section = **independant fluid**, interacting through fluxes
- Flux → piecewise constant reconstruction



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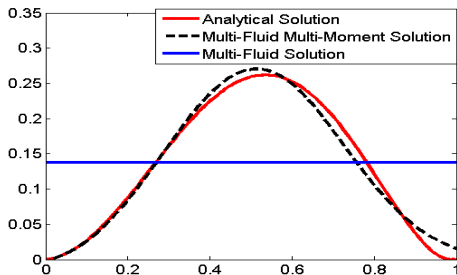


Principles

Objective:

Increase the amount of information in a section

- Multi-Fluid method : 1 moment
- Multi-Fluid Moment method : 4 moments



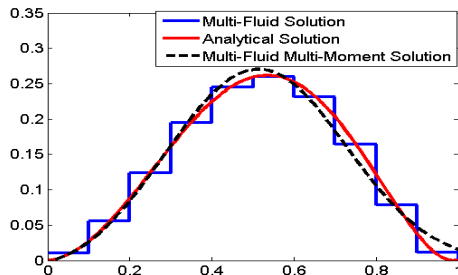
- M-F: 1 section
- M-F Moment: 1 section

Principles

Objective:

Increase the amount of information in a section

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- Multi-Fluid Moment method : 4 moments



- M-F: 10 sections
- M-F Moment: 1 section

M-F Moment equation system

$$\partial_t f + \partial_x u f + \partial_S R_S = 0$$

Phase space (x, **S**, **u**)

Equilibrium hypothesis $\downarrow \int_u$

$$\partial_t n + \partial_S R_S n + \partial_x n \bar{u} = 0$$

Phase space (x, **S**)

Discretization in S, finite Volume $\downarrow \int_S S^k$

$$\partial_t(m_0) + \partial_x \cdot (m_0 \frac{\mathcal{M}_1}{\mathcal{M}_0}) = R_S n(t, S = 0)$$

$$\partial_t(m_1) + \partial_x \cdot (m_1 \frac{\mathcal{M}_1}{\mathcal{M}_0}) = m_0$$

$$\partial_t(m_2) + \partial_x \cdot (m_2 \frac{\mathcal{M}_1}{\mathcal{M}_0}) = 2m_1$$

$$\partial_t(m_3) + \partial_x \cdot (m_3 \frac{\mathcal{M}_1}{\mathcal{M}_0}) = 3m_2$$

$$\partial_t(\mathcal{M}_1) + \partial_x(\frac{\mathcal{M}_1}{\mathcal{M}_0}^2) = R_S n(t, S = 0) \frac{\mathcal{M}_1}{\mathcal{M}_0}$$

Phase space (x)

$R_S n(t, S = 0)$
= Evaporating Flux

Difficulties

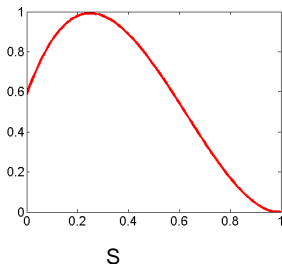
- From $(m_0, m_1, m_2, m_3)^t$ in a section, how to calculate the evaporating flux ($R_S n(t, S = 0)$)?
- $(m_0, m_1, m_2, m_3)^t$ must stay in the Surface **Moment Space**
A number density, f must exist, such as: $\int_S S^k f dS = m_k$
Dette, Studden, 1997

Evaporative flux

Entropy Maximisation.

For a given moment vector $(m_0, m_1, m_2, m_3)^t$, f is reconstructed under the profil $f = \exp(\sum_{i=0}^3 \lambda_i S^i)$,
with $\lambda_i = \lambda_i(m_0, m_1, m_2, m_3)$

Mead, 1984

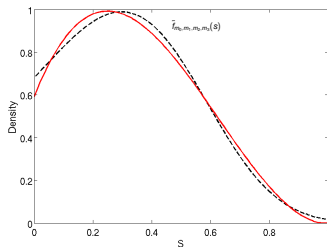


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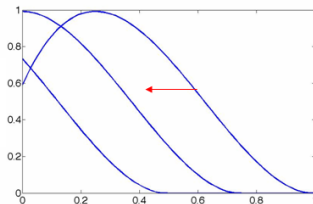
Preservation of the moment space

- Scheme characteristics:
 - Finite volume
 - Kinetic scheme
 - Flux determined by computer algebra (Maple)
- Proprieties of the scheme:
 - positivity on density
 - maximum principle on velocity
 - preservation of moment space

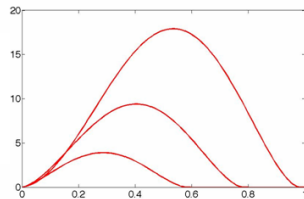
Comparison of moments

Solved kinetic equation: $\partial_t n + \partial_S R_S n = 0$, with $R_S = -1$

- Analytical solution:



number density

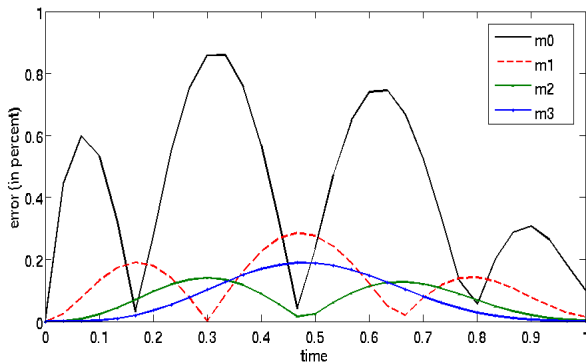


mass density

- Evolution in terms of moments:
 - Multi-Fluid: 12 sections, 1 moment
 - Multi-Fluid Moment: 1 section, 4 moments

Comparison of mass density

Error in size moments (Mutli-Fluid Moment method)

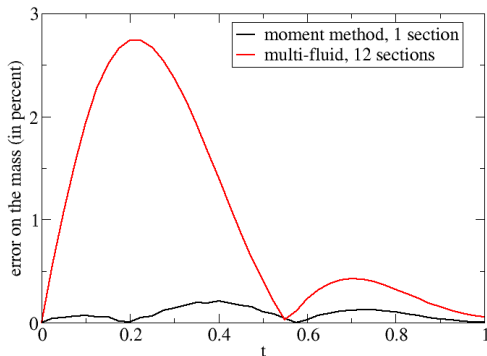


Precision less than 1 percent for the density.

Precision less than 0.4 percent for higher order moments

Comparison of mass density

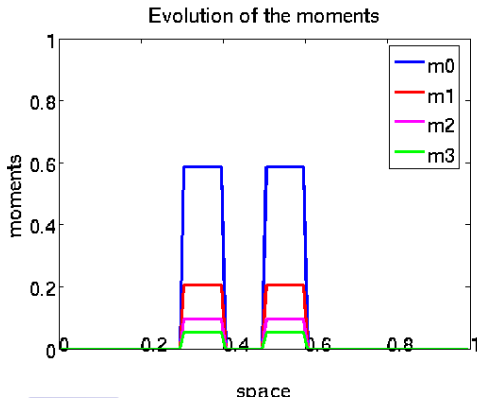
Comparison of error on mass.



MF Moment method much more precise than the simple MF method.

Multi-Fluid Moment: evaporation and transport

Evaporation and transport of a droplet flow



MF Moment

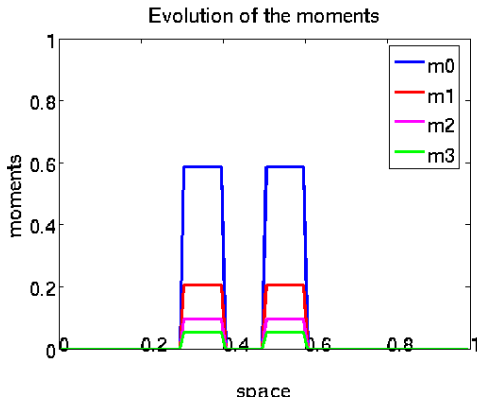
Dilute spray without collisions

→ The two clouds should cross each other

- Free flow: Evaporation and Transport well simulated
- Impinging droplets: δ -shock creation (non physical)

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MF Moment

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Different quadrature methods of moments

Equilibrium hypothesis: $\rightarrow \left(\begin{matrix} \mathcal{M}_0 \\ \mathcal{M}_1 \end{matrix} \right) : f(u) = \mathcal{M}_0 \delta(u - \frac{\mathcal{M}_1}{\mathcal{M}_0}(S))$

Monodisperse flow: equations on $(\mathcal{M}_0, \mathcal{M}_1, \mathcal{M}_2, \mathcal{M}_3)^t$

$$\partial_t(\mathcal{M}_0) + \partial_x(\mathcal{M}_1) = 0$$

$$\partial_t(\mathcal{M}_1) + \partial_x(\mathcal{M}_2) = 0$$

$$\partial_t(\mathcal{M}_2) + \partial_x(\mathcal{M}_3) = 0$$

$$\partial_t(\mathcal{M}_3) + \partial_x(\textcolor{red}{\mathcal{M}_4}) = 0$$

Closure:

$$\Rightarrow f(u) = w_1 \delta(u - \textcolor{blue}{\bar{u}_1}) + w_2 \delta(u - \textcolor{green}{\bar{u}_2}) \rightarrow \text{droplet crossings}$$

R. Fox, 2008

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Multi-Fluid Moment method with droplet crossings

- M-F Moment: **polydispersion** but **one velocity**
- Multi-Velocity(R . Fox): **droplet crossings** but **monodisperse**

Coupling of the two models: one section for the example

$$f(t, x, S, u) = \underbrace{n(t, x, S)}_{\text{size distribution}} \underbrace{\phi(t, x, u)}_{\text{velocity distribution}}$$

$$\partial_t m_0 + \partial_x \mathcal{M}_1 = R_S n(t, S = 0)$$

$$\partial_t m_1 + \partial_x m_1 \mathcal{M}_1 / \mathcal{M}_0 = m_0$$

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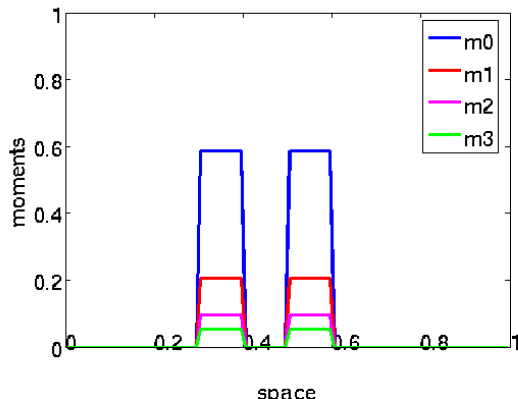
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Multi-Fluid Moment method with droplet crossings: evaporation and transport

Evaporation and transport of a droplet flow

Evolution of the moments



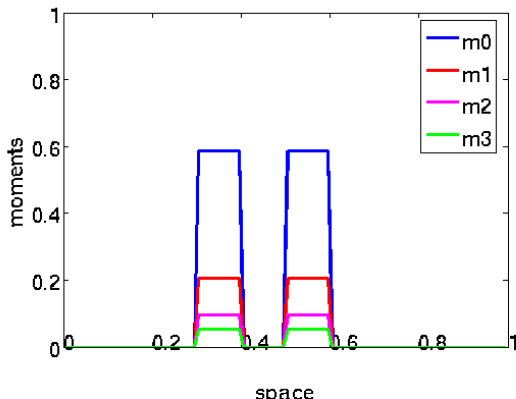
MF Moment

Droplet crossing well resolved

Multi-Fluid Moment method with droplet crossings: evaporation and transport

Evaporation and transport of a droplet flow

Evolution of the moments



MF Moment

Droplet crossing well resolved

Conclusions and Perspectives

Conclusions:

- Solutions to Multi-Fluid Model limitations

Perspectives:

- Simulation of $2D/3D$ configuration with the Multi-Fluid Multi-Moment Multi-Velocity model
- Extending this model to the collision operator
- Including these models in a global code (Summer Program 2008, CTR, Stanford)

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THAHK YOU FOR YOUR ATTENTION

