

Describing a polydisperse evaporating spray with mesh movement for internal combustion engine applications

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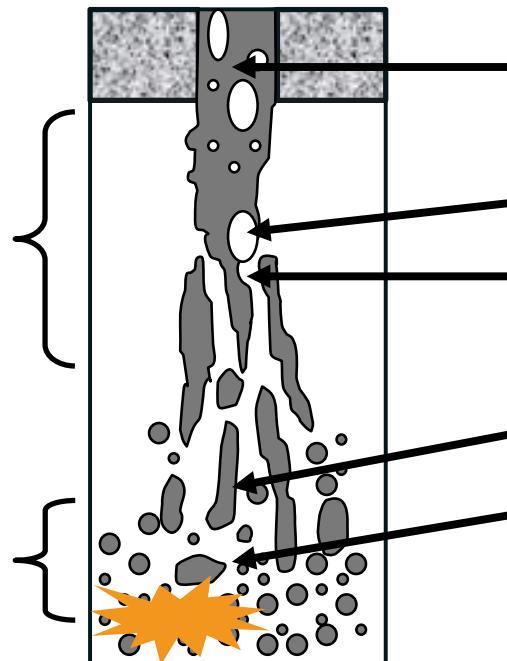
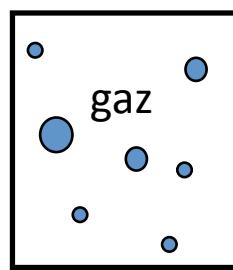
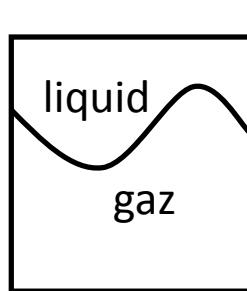
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General context: Fuel Injection in engines



- Simulation of fuel injection in internal combustion engines
- Context: better understand engine cycles to reduce pollutants, increase efficiency



- Cavitation
- Primary atomization
- Turbulence in surrounding gas due to drag force exerted by the liquid
- Secondary atomization
- **Evaporation, drag, heat exchange**
- Collisions, coalescence

**Better predict fuel fraction in gas before combustion
description of polydispersity**



Disperse phase statistical modeling

- Statistical approach with Number Density Function (NDF) $f(t, \mathbf{x}, S, \mathbf{u})$

Simplified Williams-Boltzmann equation (*Williams, 58*)

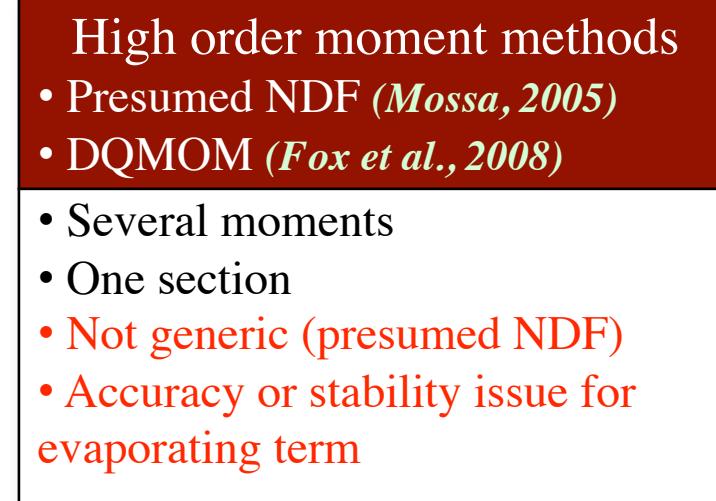
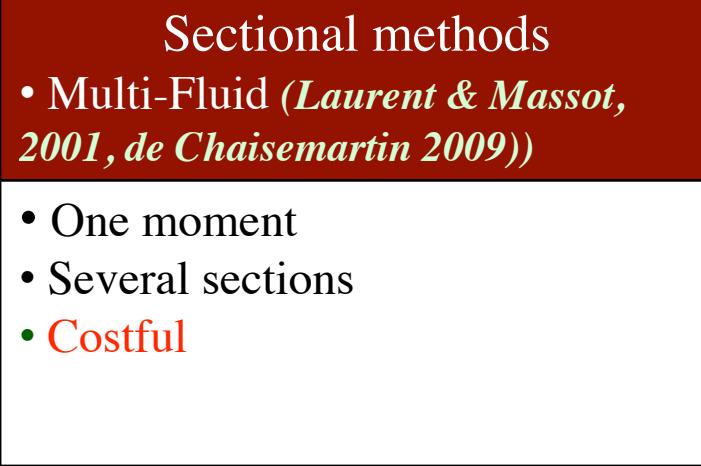
$$\partial_t f + \underbrace{\nabla_{\mathbf{x}}(\mathbf{u}f)}_{\text{advection}} + \underbrace{\partial_S(Kf)}_{\text{evaporation}} + \underbrace{\nabla_{\mathbf{u}}(\mathbf{D}_r f)}_{\text{drag}} = 0$$

→ Eulerian framework: Resolution of f with Finite Volume method expensive:

Resolution of moments : $\mathcal{M}_{k,l} = \int_{S_{min}}^{S_{max}} \int_{\mathbb{R}} S^k \mathbf{u}^l f \, d\mathbf{u} dS$

Disperse phase statistical modeling

- Polydispersity → size moments: $m_k = \mathcal{M}_{k,0}$



- None of the methods are satisfactory for our purpose**



Disperse phase statistical modeling

EMSM (Eulerian Multi-Size Moment) model...

- Treat evaporation term stably and accurately
- Generic
- Much faster than Multi-Fluid model (10 sections)
(4 times faster in 2D)
- One-way framework
- Cell-centered, steady, structured meshes
- Validated of academic test cases (*Massot et al., 2010*) (*Kah et al., 2012*)

... to be exported to an industrial software

- 2 way coupling
- ALE (Arbitrary Lagrangian Eulerian) :
- Staggered grid

Description of fuel injection
Moving mesh formalism
Implementation in industrial
software



Outline

- EMSM: model and achievements
- Extension of EMSM to ALE formalism
- Validation in industrial software



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EMSM: one-way framework

Moment equation system

$$\partial_t m_0 + \nabla_{\mathbf{x}}(m_0 \mathbf{u}_p) = -Kn(t, \mathbf{x}, S = 0) \quad \text{evaporating flux}$$

⋮

$$\partial_t m_N + \nabla_{\mathbf{x}}(m_N \mathbf{u}_p) = -K N m_{N-1}$$

$$\partial_t m_1 \mathbf{u}_p + \underbrace{\nabla_{\mathbf{x}}(m_1 \mathbf{u}_p \otimes \mathbf{u}_p)}_{\text{advection}} = \underbrace{-K m_0 \mathbf{u}_p}_{\text{evaporation}} - \nabla_{\mathbf{x}} P + \underbrace{D}_{\text{drag}}$$

Closure issues in model

- $f(t, \mathbf{x}, S, \mathbf{u}) = n(t, \mathbf{x}, S) \delta(\mathbf{u} - \mathbf{u}_p)$ → $P = 0$ (velocity dispersion)

- Closure of $n(t, \mathbf{x}, S = 0) = \Phi(m_0, \dots, m_N)(t, \mathbf{x})$

Challenge: reconstruct, from the moments,

a pointwise value of the size NDF

Stability condition : Realizability condition

→ Approximation of the size NDF by **Maximization of Entropy** (*Mead and*

$$\mathbf{m}_N = (m_0, \dots, m_N)^t \longrightarrow \tilde{n}_{ME}$$

Papanicoloaou, 84)

EMSM: one-way coupling framework

Numerical Strategy and issues

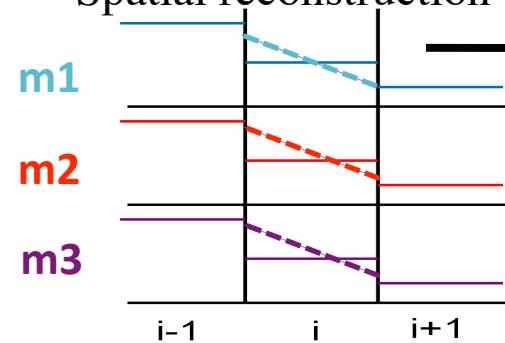
- Splitting: Successive resolution of evaporation, transport and drag
- Evaporation: System **cannot** be solved by ODE solvers: **Realizability Condition**
- Transport:
 - $P = 0$: Pressureless gas dynamics (**Singularities** and **Vacuum zones**)
 - **Realizability Condition**

Solutions

- Flux computation : **Kinetic scheme:**
 Finite Volume method with exact computation of the fluxes from reconstructed profiles (*Bouchut et al, 2003*)

Evaporation (*Massot et al., 2010*)

- Spatial reconstruction of moments: **Canonical moments**

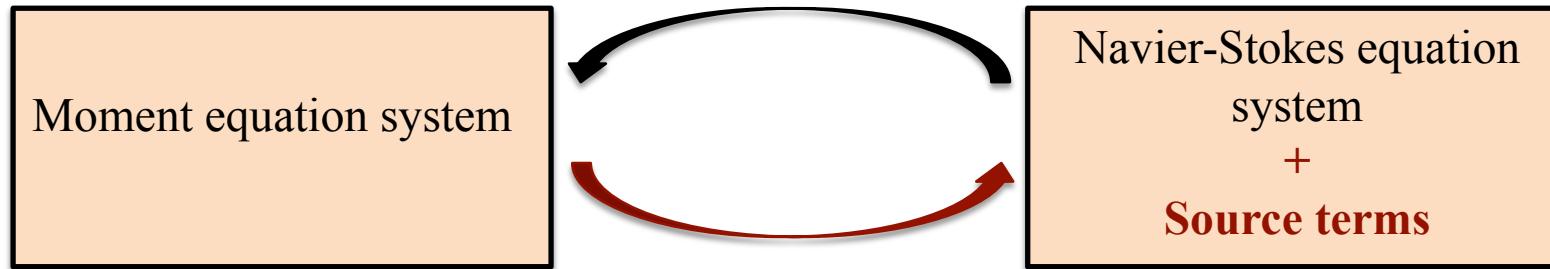


→ Realizability condition might not be satisfied in the whole cell (*Wright 07, McGraw 07*)

→ Canonical moments

Transport (*Kah et al., JCP, 2012*)

EMSM: two-way framework



Solver for coupled system (*Emre et al., 2012*)

- Splitting sequence: transport / evaporation-drag
 - ➡ Fully coupled ODE system solved: gas and spray variables simultaneously vary
- Ability to solve for stiff problem with a time step not constrained by smallest time scales
 - ➡ Implicit Runge Kutta method
- Realizability condition satisfaction
 - ➡ Evaporation decoupled from drag



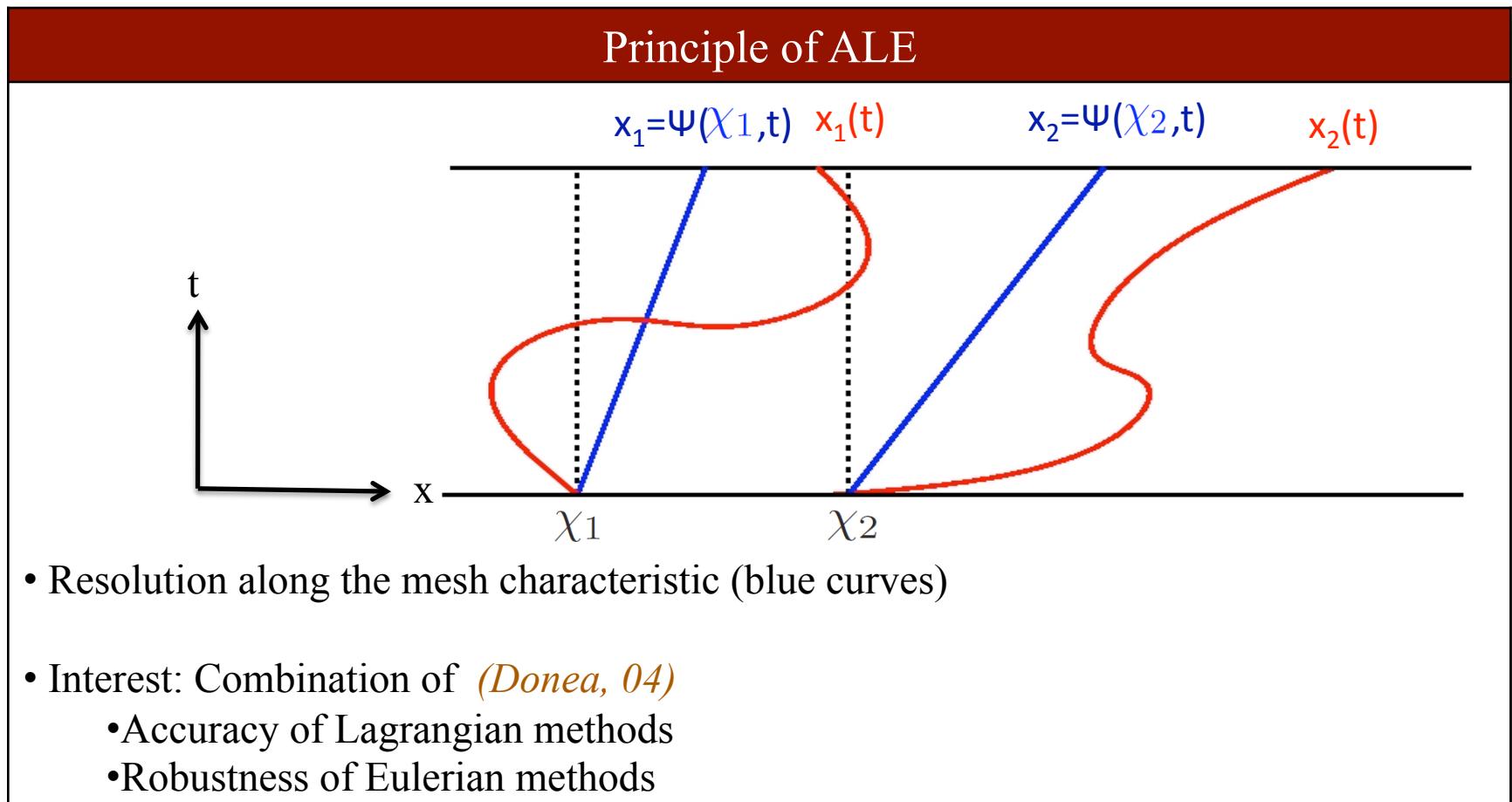
Outline

- EMSM: model and achievements
- Extension of EMSM to ALE formalism
- Validation in industrial software

Extension of EMSM to ALE: Principle of ALE



- IFP-C3D: moving boundary conditions (moving piston)
- Strategy adopted: ALE



Extension of EMSM to ALE: Algorithm of IFP-C3D



- Operator splitting algorithm in IFP-C3D:
 - Phase A: source terms (evaporation, drag, ...) Δt
 - Phase B: resolution of acoustic terms
 - Phase C: advection terms / rezoning step

Δt

Δt

Decouples acoustic waves
from convective waves

Extension of EMSM to ALE: Achievements in a structured grid



- One-way coupling: high order transport scheme for moments in moving, staggered, structured grid (phaseB and C)

Moment transport

- Adaptation of kinetic scheme during rezoning step, with variable cell size (phase C)
- Realizability condition enforced and accuracy preserved

Momentum transport

- Nodal definition of velocity: dual mesh with variable cell size
- Computation of the momentum fluxes so that the two properties are enforced:
 - Conservation of momentum
 - Maximum principle on velocity} *(Larroutrou 04)*



High order in time and space on a moving structured grid (*Kah et al., IJMF,12*)

Extension of EMSM to ALE: Achievements in an unstructured grid



- Extension to two-way coupling: Source term resolution in phase A

Resolution method

- Local resolution: independent of mesh movement, same solver as in Eulerian grid
- Nodal definition of velocity: dual mesh with variable cell size



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IFP-C3D (*Bohbot et al., 09*)

- A hexahedral unstructured solver devoted to internal CFD with spray and combustion modelling
- The conservation equations are solved on moving grids
- The equations are solved using a finite volume method extended with the ALE (Arbitrary Lagrangian Eulerian) method.
- The k- ε turbulence model is used (RANS)

Implementation in IFP-C3D

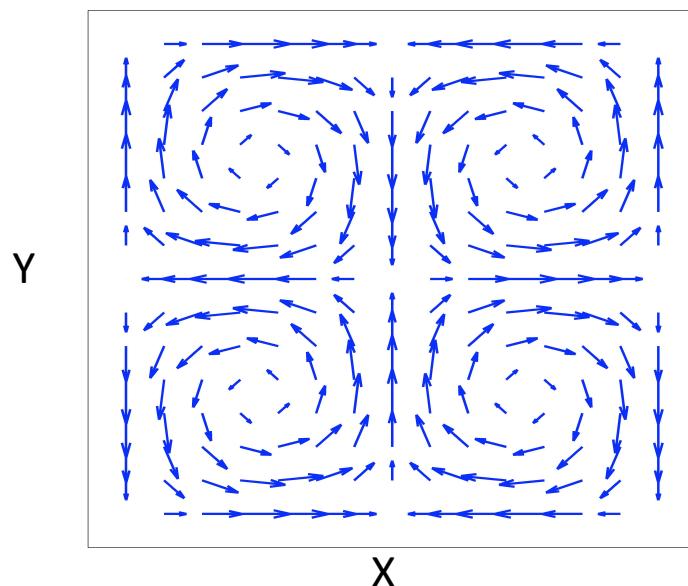
- Validation on three test cases:
 - Moving piston : validates spray dynamics with mesh movement
 - **Interaction with Taylor-Green Vortices**
 - **Fuel injection in bomb-chamber**

Validation in industrial software: Taylor-Green vortices

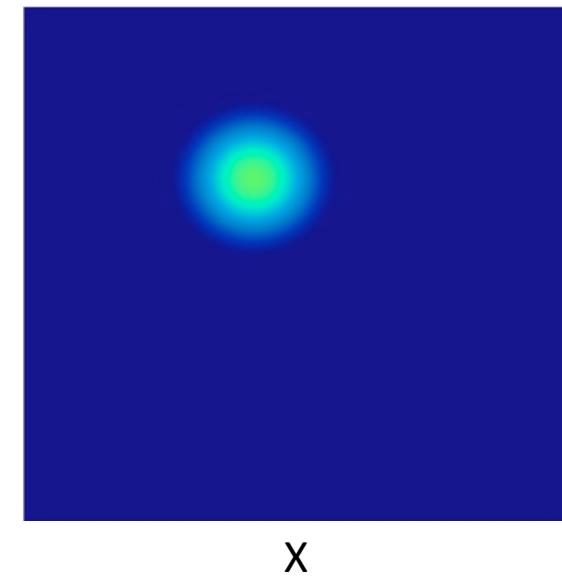


- 2D test with evaporation and drag (One-way coupling)

Taylor-Green vortices for gas flow

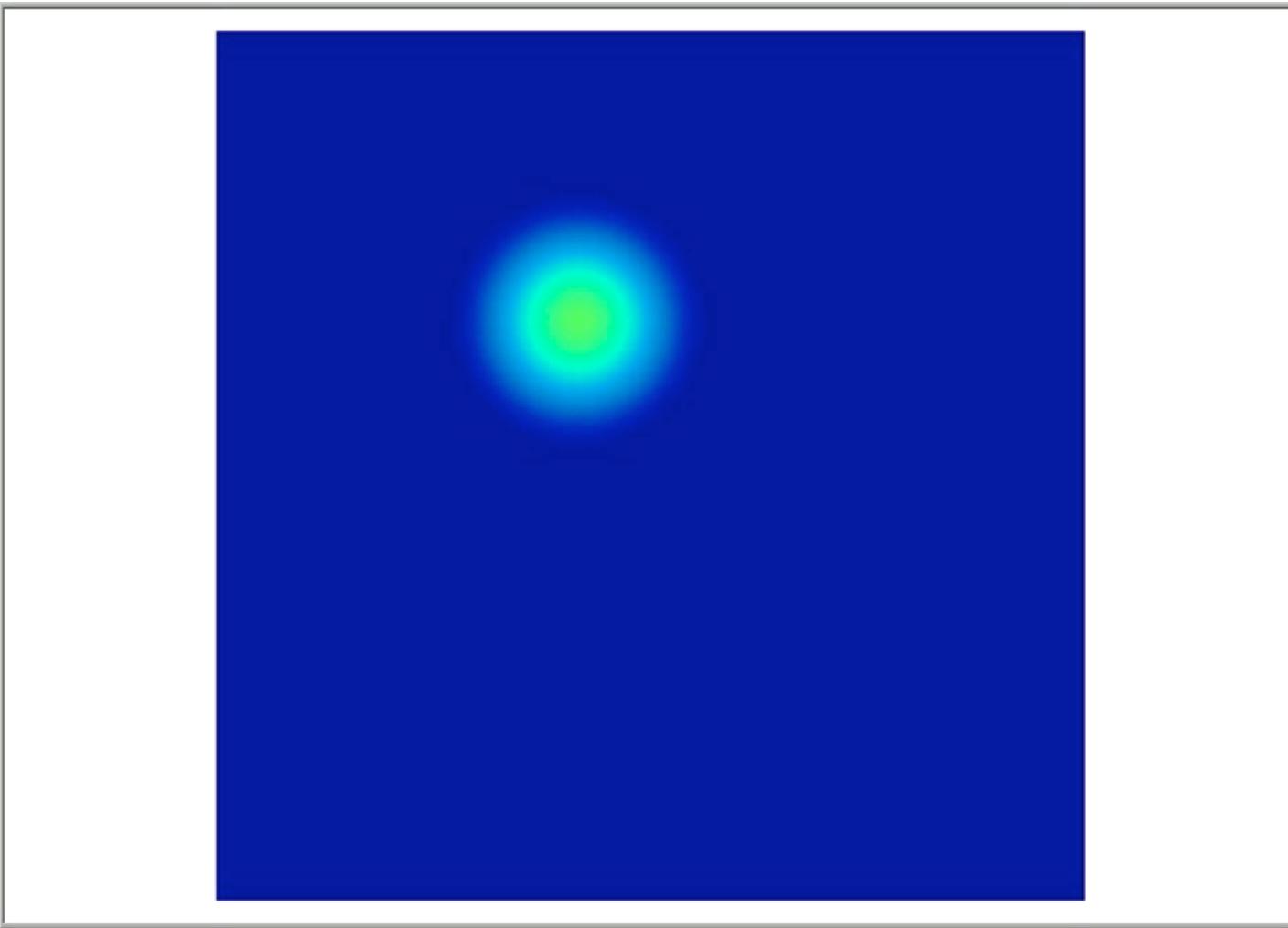


Initial condition for the spray



- Periodic Boundary conditions
- Drag: Maximum Stokes = 2.81
- Evaporation: $K = 0.21$
- Final time = 2 (one eddy turnover time)

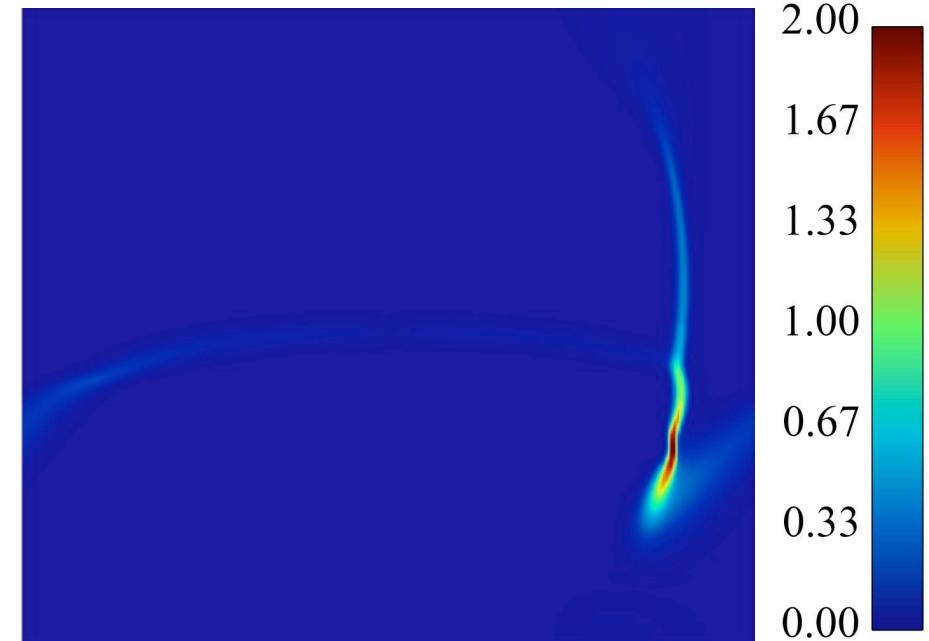
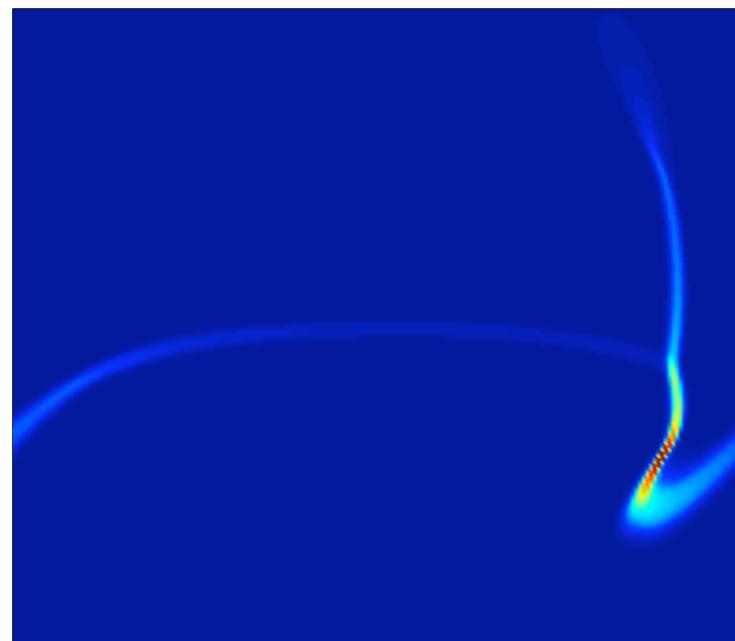
Validation in industrial software: Taylor-Green vortices



Validation in industrial software: Taylor-Green vortices



- Comparison with DNS code
- **Muses3D**
 - Structured
 - Eulerian
 - 2nd order
- **C3D**
 - Unstructured
 - ALE
 - 1st order



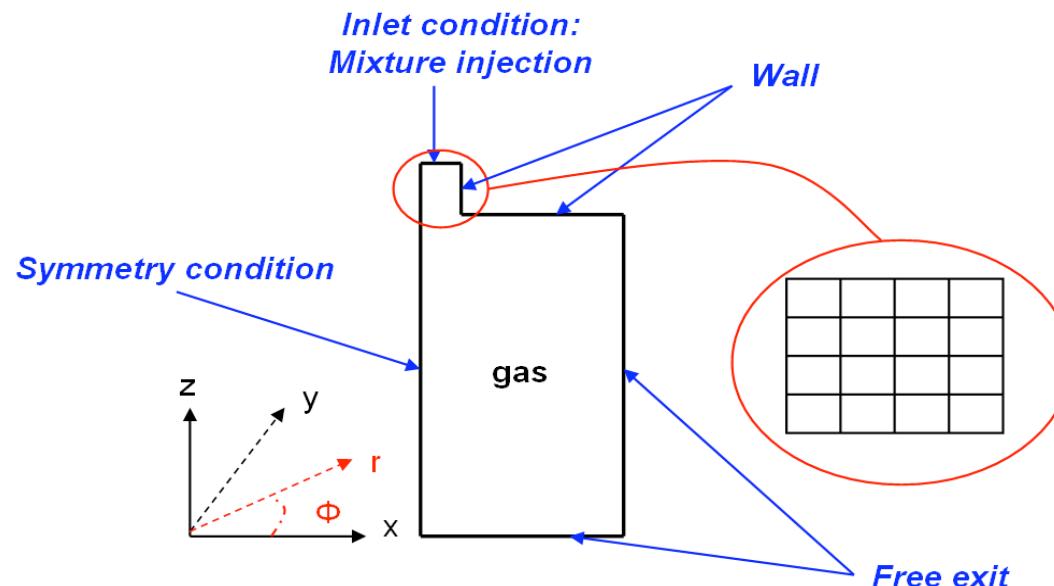
Very satisfactory level of comparison

Same robustness in IFP-C3D as in Muses3D

Validation in industrial software: Two-way coupling



- Fuel and gas injection in steady gas phase
- No turbulence model, coarse mesh, steady geometry
 - ➡ Test robustness of EMSM with two-way coupling in computation with ALE
- 2D axisymmetrical test case:



Physical parameters:

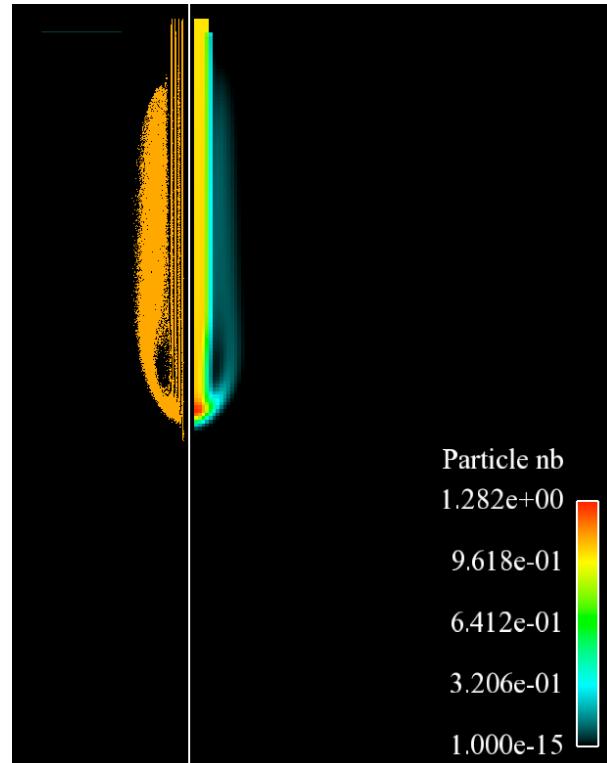
- Evaporation spray
- Drag: Average Stokes = 0.5
- Injection velocity : 18 m/s
- Rosin-Rammler distribution (smr = 5 μm)

Validation in industrial software: Fuel Injection

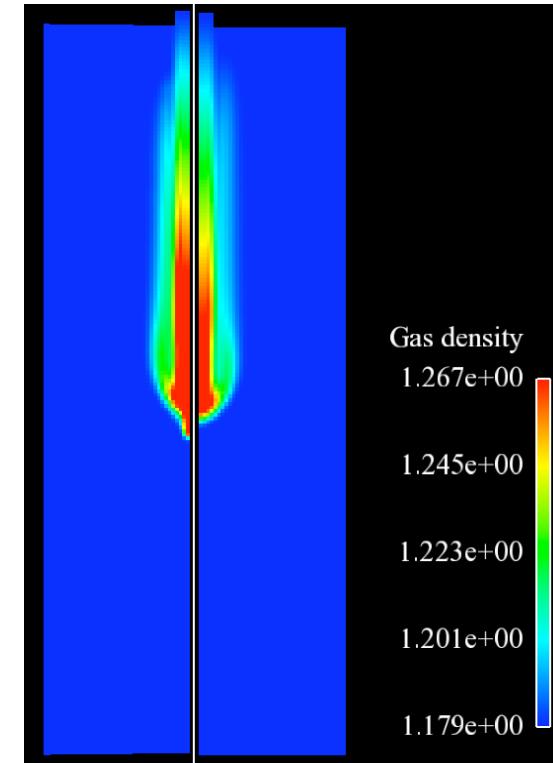


- Comparison Lagrangian vs EMSM with two-way coupling framework:

Lagrangian / Eulerian
(Particle number)



Lagrangian / Eulerian
(Gas density)



Robustness of two-way coupling algorithm in ALE framework



Conclusions

- ✓ EMSM in ALE (one-way coupling framework)

Extension of high order scheme transport for moments and momentum (*Kah et al., JCP, 12*) to ALE formalism, preserving **stability** and **accuracy** for moments (*Kah et al., IJMF, 12*)

- ✓ EMSM in a two-way coupling framework

Solver for the two-way coupling, able to solve for **stiff** system while preserving the **realizability** of the moment vector; extension in **ALE** formalism (*Emre et al., ECCOMAS, 12*)

- ✓ Implementation in IFP-C3D and validation of numerical tools

Scheme robustness assessed through mesh movement; implementation validation through comparison with DNS; Proof of robustness of two-way coupling algorithm in Ale formalism



Perspectives

- Modeling:
Size-velocity correlation for EMSM (*Vie et al., JCP, 2011*)
- Turbulence modeling:
Introduce fluctuation terms from RANS modeling
- Numerical Scheme :
High order scheme in unstructured mesh
- Validation:
Computation of a real injection case, with mesh movement, refined mesh, turbulence model, and comparison with experimental data