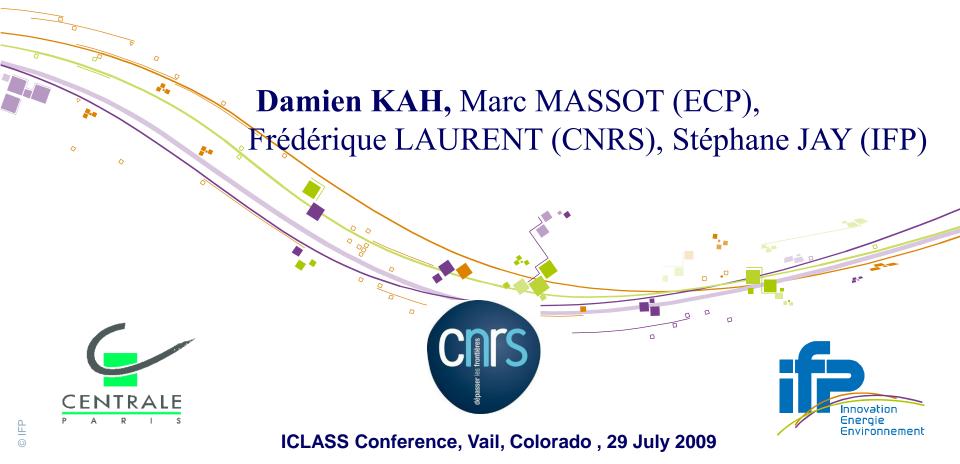
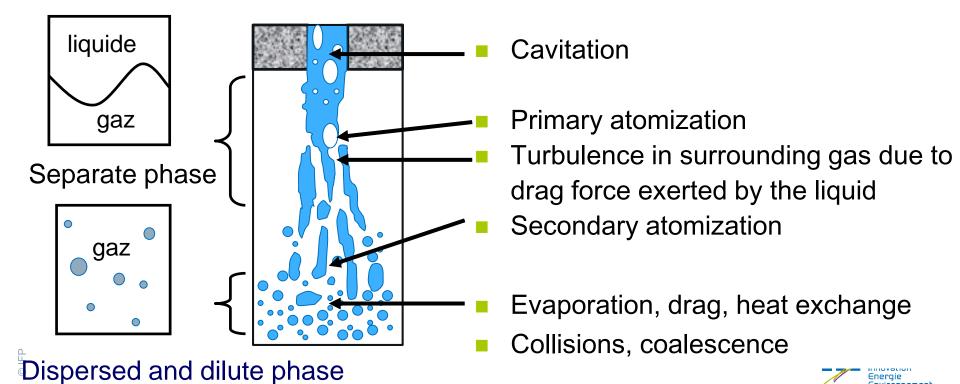
# Modeling of polydisperse sprays using a high order size moment method for the numerical simulation of advection and evaporation



## General context: injection in engines

- Sprays in internal combustion engines
- Numerical simulation of reactive multiphase flow





# General context: modeling of two-phase flow

- Two ways of modeling
- Lagrangian
  - Implementation
  - Coupling gas/liquid
  - ■Non stationary flow: high CPU cost

- Eulerian
  - Coupling gas/liquide
  - Non stationary flow
  - Modeling, Implementation

- Current modeling (IFP-C3D): Euler/Euler version (*Truchot 05, Vessiller 08,* Baer et Nunziato model (85)

  Bayoro 08)
  - 7 equation model
  - Mixture, interface, cavitation, detonation



# Our objective

- Improve the description of the coupling terms (gas/liquid)
- ⇒ Better predict fuel fraction in gas for combustion solvers (Temperature, NOx,...)
  - Separate phase: evolution of interfacial area  $\Sigma$  (Jay 06)
  - Dispersed phase: description of polydispersity



Fig: Prof Edwards (Stanford)

- IFP-C3D: two-fluid formalism
  - Volume fraction :  $\alpha$
  - Interfacial area density :  $\Sigma$

Mean diameter :  $d = \frac{6\alpha}{\Sigma}$ 

How to introduce the capacity to describe polydispersity in the dispersed phase, in a two-fluid formalism?

# Description of polydispersity(1/2)

- Statistical approach
  - Spherical droplets (1-100 µm): no interface problem
  - ullet Number density function (NDF) f(t,x,v,S,T)
  - Williams-Boltzmann Equation (Williams, 1958)

$$\partial_t f + \partial_x v f + \partial_S R f + \partial_v \frac{F}{m} f + \partial_T E f = \Gamma$$

- Eulerian framework
  - Resolution with Finite Volume impossible moment method
  - Size moments  $m_k = \int_0^{S_{max}} \int_{\mathbb{R}} S^k f \, dS dv$
- Models describing polydispersity in a Eulerian framework ?

# Description of polydispersity(2/2)

- Sectional method (Tambour 1985): Multi-fluid method (Laurent 02, Chaisemartin 09)
  - lacksquare Several size sections  $[S_i,S_{i+1}]$
  - ullet Evolution of  $m_{3/2,i}, m_{3/2,i}u_i$  in each section
  - Can describe every distribution function
  - High accuracy potential
  - Important CPU cost, at least 2 sections to describe polydispersity
- Two-fluid formalism: Presumed NDF method (Mossa 05)
  - One section
  - Presumed NDF, not generical
  - Scheme not stable for evaporation



## What we precisely want to achieve

- Design a method
  - Describing polydispersity in a two-fluid formalism
  - Generic
  - Reasonnable CPU cost



#### **Several size moments**

- Difficulties:
  - Mathematic: closure problems
  - Physics : accuracy of the description ?
  - Numerical : stable scheme
- Different contexts, solved independtly through splitting :
  - Evaporation
  - Advection in physical space





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- Evaporation
- Advection

Conclusions - Perspectives





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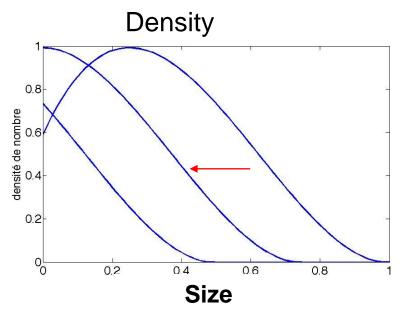
Conclusions - Perspectives

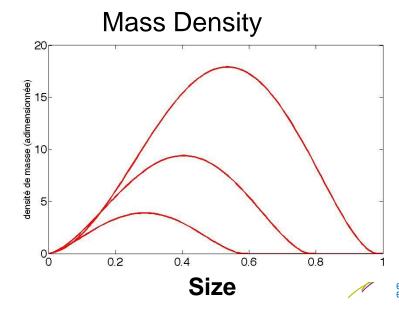


# **Evaporation: Principle**

- Solution of  $\partial_t f + \partial_S R f = 0$
- R, evaporation coefficient, determined by an evaporation model
- We use  $d^2$  law (infinite conductivity) and non dimensional variables:  $R=-1, S\in [0,1]$

#### Analytical solution









## **Evaporation: Model**

phase space: S

$$\int_0^1 \int_{\mathbb{R}} S^k \partial_t f \, dS dv + \int_0^1 \int_{\mathbb{R}} S^k \partial_S (Rf) \, dS dv = 0, \ k = 0 \dots 3$$

Dynamics of four size moments:

 $m_0$ : number density

 $m_1$ : mean size

 $m_2$ : mean square size, dispersion around the mean value

 $m_3$ : mean cubic size





## **Evaporation: Model**

$$\int_0^1 \int_{\mathbb{R}} S^k \partial_t f \, dS dv + \int_0^1 \int_{\mathbb{R}} S^k \partial_S (Rf) \, dS dv = 0, \ k = 0 \dots 3$$

$$\partial_t m_1 = -m_0$$

$$\partial_t m_2 = -2m_1$$

$$\partial_t m_3 = -3m_2$$





## **Evaporation: Model**

$$\int_0^1 \int_{\mathbb{R}} S^k \partial_t f \, dS dv + \int_0^1 \int_{\mathbb{R}} S^k \partial_S (Rf) \, dS dv = 0, \ k = 0 \dots 3$$

• 
$$\partial_t m_0 = -f(t, S=0)$$
: evaporative flux  $\partial_t m_1 = -m_0$   $\partial_t m_2 = -2m_1$   $\partial_t m_3 = -3m_2$ 

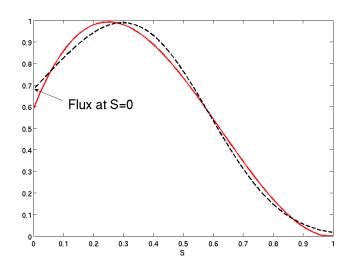
$$\partial_t m_1 = -m_0$$

$$\partial_t m_2 = -2m_1$$

$$\partial_t m_3 = -3m_2$$

#### Feasibility (Moments of a NDF)

(Fox,Laurent,Massot 08)





## **Evaporation: Numerical scheme**

- ODE solvers are unstable: Explicit Euler, 2 stage Runge Kutta.
- New scheme
  - Finite Volume scheme
  - Flux calculation by temporal integration of the kinetic equation Equivalence microscopic / macroscopic description levels (Bouchut 03)  $\partial_t f \qquad \partial_t m_k$

#### Algorithm

- Moments in the section
- Reconstruction of f by Entropy Maximisation
- Calculation of the flux using f, solution of the kinetic equation
- Flux addition and update of the moments
- Kinetic scheme (Perthame 02)
  - Satisfies the feasability condition

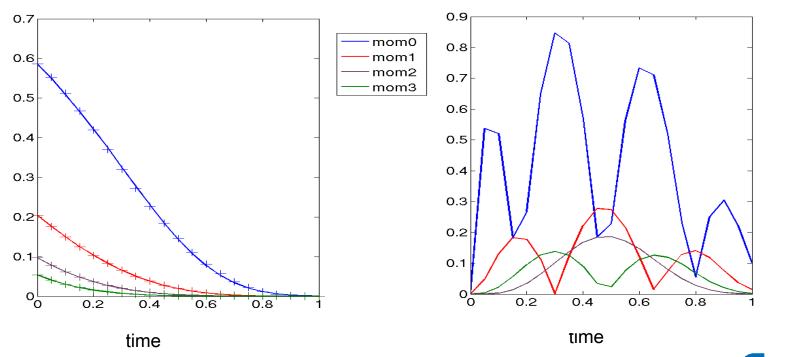


# **Evaporation: Results**

#### Results in terms of moments

Analytical and numerical moments

Error on the moments (in percent)





$$\partial_t f + \partial_S(Rf) = 0$$
 ,  $R = -1, S \in [0, 1]$ 

- Solution in terms of moments (Massot et al 08)
  - Closure problem: Entropy Maximisation
  - Numerical scheme: Kinetic scheme
- Applications:



- Implement these evolution equations in IFP-C3D
- New closure of the evaporation term

Ability to evaporate a population with different sizes

Application in other domain: soots





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# Advection: model (1/2)

Velocity moments





# Advection: model (1/2)

Velocity moments

closure problem

$$f(t, x, v, s) = n(t, x, S)\delta(v - u(t, x, S))$$





# Advection: model (1/2)

Velocity moments

closure problem

Unique velocity conditioned by size

$$f(t, x, v, s) = n(t, x, S)\delta(v - u(t, x, S))$$

$$\partial_t \int_0^1 nu \, dS + \partial_x \int_0^1 n(u)^2 \, dS = 0$$

Size moments







Velocity moments

closure problem

Unique velocity conditioned by size

$$f(t, x, v, s) = n(t, x, S)\delta(v - u(t, x, S))$$

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Size moments

Constant velocity in a section

$$\int_0^1 u^2(S)f \, dS = m_0 \bar{u^2} = m_0(\bar{u})^2$$





# Advection: model (2/2)

$$\partial_t m_0 + \partial_x m_0 \bar{u} = 0$$

$$\partial_t m_1 + \partial_x m_1 \bar{u} = 0$$

$$\partial_t m_2 + \partial_x m_2 \bar{u} = 0$$

$$\partial_t m_3 + \partial_x m_3 \bar{u} = 0$$

$$\partial_t m_0 \bar{u} + \partial_x m_0 \bar{u}^2 = 0$$

Objective: Design a 2nd order scheme satisfying:





# Advection: model (2/2)

$$\partial_t m_0 + \partial_x m_0 \bar{u} = 0$$

$$\partial_t m_1 + \partial_x m_1 \bar{u} = 0$$

$$\partial_t m_2 + \partial_x m_2 \bar{u} = 0$$

$$\partial_t m_3 + \partial_x m_3 \bar{u} = 0$$

$$\partial_t m_0 \bar{u} + \partial_x m_0 \bar{u}^2 = 0$$

- Objective: Design a 2nd order scheme satisfying:
- Feasability condition
  - Independant transport of the moment fails
- Presurreless Gas formalism (Bouchut 03)
  - Potentiel singularity formation (δ-shocks)





#### Pressureless Gas formalism

$$\partial_t m_0 + \partial_x m_0 \bar{u} = 0$$

$$\partial_t m_0 + \partial_x m_0 \bar{u} = 0$$
 
$$\partial_t m_0 \bar{u} + \partial_x m_0 \bar{u}^2 = 0$$
 Pressure=0

- $\partial_t \bar{u} + \bar{u} \partial_x \bar{u} = 0$ (Burgers Equation)
- Potential singularity formation

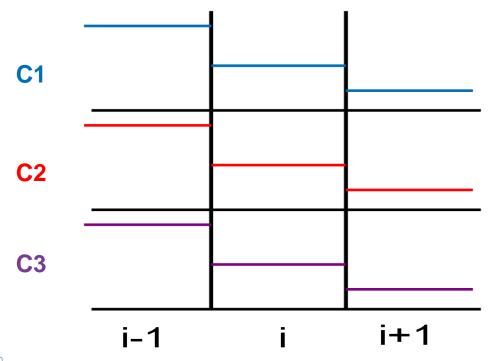






$$c_k = \frac{m_k}{m_0}, \ k = 1..3$$
  $\partial_t c_k + u \partial_x c_k = 0$ 

Reconstruction

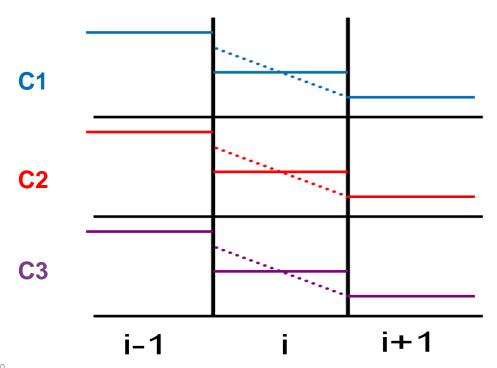






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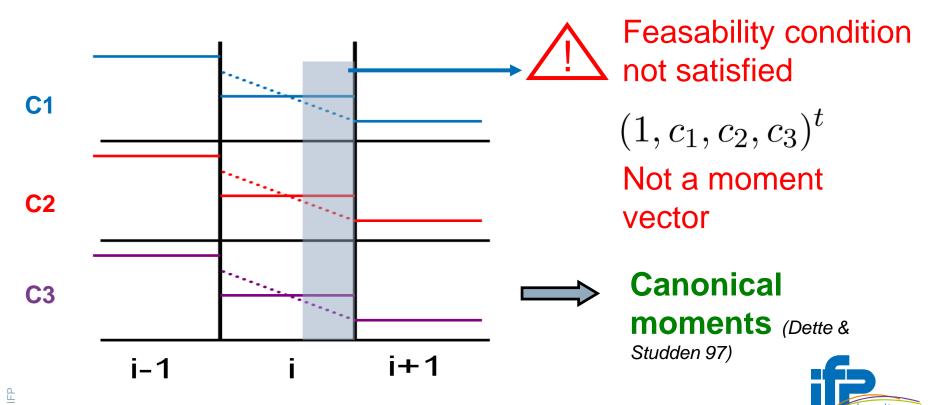






$$c_k = \frac{m_k}{m_0}, k = 1..3$$
  $\partial_t c_k + u \partial_x c_k = 0$ 

Reconstruction





#### Advection: conclusion

- 2nd order scheme for advection of a moment set
  - Kinetic scheme
  - Canonical moment theory (Dette & Studden 97)
- Application:



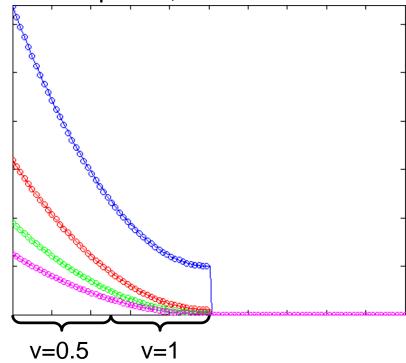
Implementation of these tools in IFP-C3D

- Application in other domains:
  - Combustion
  - Meteorology: (Wright07, McGraw07)





$$\partial_t f + \partial_x (vf) + \partial_S (Rf) = 0$$

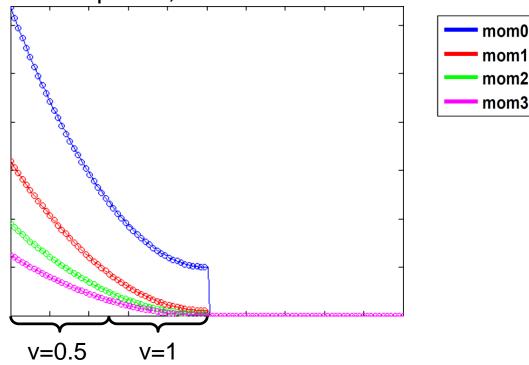








$$\partial_t f + \partial_x (vf) + \partial_S (Rf) = 0$$

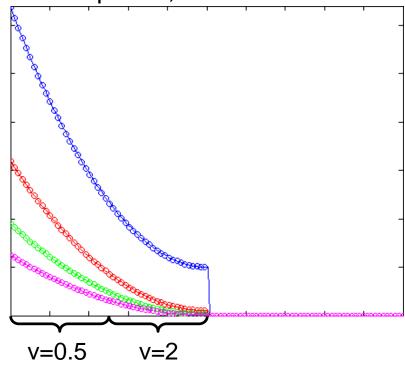


- Transport of the moments
- Vacuum zone handled





$$\partial_t f + \partial_x (vf) + \partial_S (Rf) = 0$$



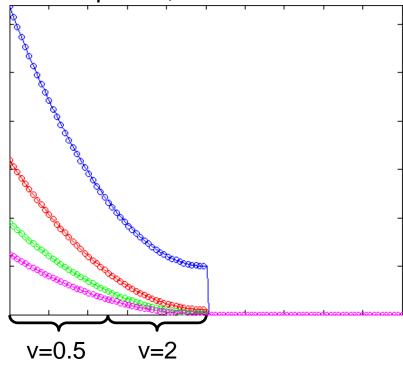


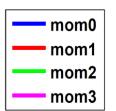
- Dilute flow
- No collision





$$\partial_t f + \partial_x (vf) + \partial_S (Rf) = 0$$





- Dilute flow
- No collision

- Singularity handled
- Not physical





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#### **Conclusions**

#### Objectives

Design a model and numerical schemes for advection of size moments of an evaporative polydisperse spray, in a two-fluid formalism:

#### Achivements:

- High size moment model and numerical scheme for evaporation
  - M.Massot, F.Laurent, D.Kah, S. de Chaisemartin: A robust moment method for evalution of the disappearance rate of evaporating sprays, submitted to SIAM journal of applied mathematics available in HAL (2008)
- High size moment model and 2nd order numerical scheme for advection
  - D.Kah, F. Laurent, M. Massot, S. Jay: A high order moment method simulating evaporation and advection of a polydisperse liquid spray, to be submitted to Journal of Aerosol Science (2009)
- Theoretical and numerical problems solved
- Methods applicable in other fields (soots, meteorology)



## **Perspectives**

- Implementation of these tools in the code IFP-C3D to simulate the dispersed phase
- Test cases in 2D and 3D
- Coupling with the separate phase
- High order velocity moments to overcome singularities (Fox 08)
  - S. De Chaisemartin, L. Fréret, D. Kah, F. Laurent, R.O. Fox, J. Réveillon, M. Massot: Turbulent combustion of polydisperse evaporating sprays with droplet crossing: Eulerian modeling and validation in the infinite Knudsen limit, proceedings of CTR (2008)

# Thank you for your attention

