

DACHS® CAN

Runtime for CAN Layer 2

Vers. 1.0.1

for QNX® Neutrino® RTOS v. 6.3

for the for the dual CAN **Janus-MM** PC/104 Board from Diamond Systems

Order No.: CAN2-SJA1000-104-RT-JAN-NTO-[1.0.1-NTO6.3]





Author: Dipl.- Inform. Armin Steinhoff

Copyright 1994-2008



Disclaimer

STEINHOFF (STEINHOFF Automation & Fieldbus-Systems) makes no representations or warranties with respect to the contents or use of this manual or the programs which it describes for any particular purpose or with respect to its adequacy to produce any particular result.

This manual contains information which is subject to change without notice. Although every precaution has been taken in the preparation of this manual, STEINHOFF assume no responsibility for any omissions or errors, nor do STEINHOFF, its employees, its contractors or the authors of this documentation assume liability for damages resulting from the use of the information contained herein - special, direct, indirect or consequential damages, losses, cost, charges, claims, demands, or claim for lost profits, fees or expenses of any nature or kind.

Notice of Copyright

© 1994-2008 by STEINHOFF Automation & Fieldbus-Systems

All rights reserved. No part of this publication may be reproduced, stored in a retrieval system or used by any form or by any means, taping, graphic, electronic, photocopying, mechanical, recording or otherwise without the prior written permission of STEINHOFF Automation & Fieldbus-Systems.

Trademarks

QNX and Neutrino are registered trademarks of QNX Software Systems Ltd. DACHS is a registered trademark of Steinhoff A. All other trademarks belong to their respected owners.

Contents

1	PREFACE	2
2	INSTALLATION	2
_		
_		_
3	DRIVER START	3

1 Preface

The DACHS CAN resource manager for QNX Neutrino RTOS v.6.3 supports individual SJA1000 CAN controllers of the Janus-MM board. Supported are reading and writing of frames, filter management as well as other controller management functions. The internal receive FIFO can hold 128 frames.

2 Installation

Installation of the resource manager software must be done by using the standard gzip and pax utilities of QNX:

- Place the driver CD into the CD drive, mount the CDROM and copy the archive to the root directory.
- Unzip the archive with 'gunzip' and use
 'pax -rv -f <archive>.tar' in order to install the driver software
- After receiving the license file which must be requested after the first driver start, please copy the license file into the working directory of the driver
- After the first driver start you will get displayed the 12 digits of the license. Please, request the key file for your license from <u>support@steinhoff-automation.com</u>
- After receiving the license file please, copy it into the working directory of the driver

3 Driver Start

The DACHS CAN driver (resource manager) for the CAN Layer 2 can be started with several options:

Start command : can [options] & Options:

-n	driver_name	default: CANDRV		
-C	controller number	number of the CAN controller (12)		
-d	board number	default: 1 (14)		
-B	BTR0	channel 1, default: 0 (500 kb/s) Appendices A.1, list parameter BTR0		
-b	BTR1	channel 1, default: 0x1C (500 kb/s) Appendices A.1, list parameter BTR1		
-m	base address	default 0xD0000		
-i	IRQ	default: 11		
-р	task prio	default: 15		
-P	prio interrupt thread	default: 40		

A.1 Bit timing parameters

Baud Rate kb/s	BTR0	BTR1	(SJW)
1000.00	0x00	0x14	0
800.00	0x00	0x16	0
500.00	0x00	0x1C	0
400.00	0x00	0x2F	0
200.00	0x01	0x2F	0
100.00	0x04	0x1C	0
50.00	0x07	0x2F	0
1000.00	0x40	0x14	1
800.00	0x40	0x16	1
500.00	0x40	0x1C	1
400.00	0x40	0x2F	1
200.00	0x41	0x2F	1
100.00	0x43	0x2F	1
50.00	0x47	0x1C	1



