

HW 3 - ASTR510

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Q1

Burger's Equation

$$\frac{\partial u(x, t)}{\partial t} + u(x, t) \frac{\partial u(x, t)}{\partial x} = \mu \frac{\partial^2 u(x, t)}{\partial x^2}$$

Initial condition

```
In[63]:= g[x_] = .5 Sin[Pi x] + Sin[2 Pi x];
```

a)

FTCS scheme

```
In[64]:= ftcs=(v[k][l+1]-v[k][l])/ht +  
v[k][l](v[k+1][l]-v[k-1][l])/  
(2 hx) == mu (v[k+1][l]+v[k-1][l]-2 v[k][l])/  
(hx^2);ftcs//TraditionalForm
```

```
Out[64]//TraditionalForm=  

$$\frac{v(k)(l+1)-v(k)(l)}{ht} + \frac{v(k)(l)(v(k+1)(l)-v(k-1)(l))}{2 hx} = \frac{\mu (v(k-1)(l)-2 v(k)(l)+v(k+1)(l))}{hx^2}$$

```

Solving for $v(k)(l+1)$

```
In[65]:= Solve[ftcs, v[k][l+1]][[1, 1]] // TraditionalForm
```

```
Out[65]//TraditionalForm=  

$$v(k)(l+1) \rightarrow \frac{1}{2 hx^2} \left( ht hx v(k-1)(l) v(k)(l) - ht hx v(k)(l) v(k+1)(l) + 2 ht \mu v(k-1)(l) - 4 ht \mu v(k)(l) + 2 ht \mu v(k+1)(l) + 2 hx^2 v(k)(l) \right)$$

```

Function to advance by one time-step using FTCS

```
In[66]:= FTCS = Function[{v, hx, ht, μ},
  ArrayPad[ArrayFilter[ $\frac{1}{2 hx^2}$  (ht #[[1]] (2 μ + hx #[[2]]) + 2 ht μ #[[3]] +
    #[[2]] (2 hx2 - 4 ht μ - ht hx #[[3]])) &, v, 1][[2 ;; -2]], 1]];
```

b)

Function to initialize array given g(x) and hx

```
In[9]:= init = Function[{g, hx}, g /@ Range[0, 1, hx]];
```

Function to iterate upto 1 second given g(x), hx, ht and μ

The function stops iterating if the solution starts to blow up.

```
In[10]:= iter = Function[{f, hx, ht, μ}, NestWhileList[
  FTCS[#, hx, ht, μ] &, init[f, hx], Max@Abs@# < 1.5 &, 1, Floor[1 / ht]]];
```

c)

Function to find largest stable time-step using bisection method

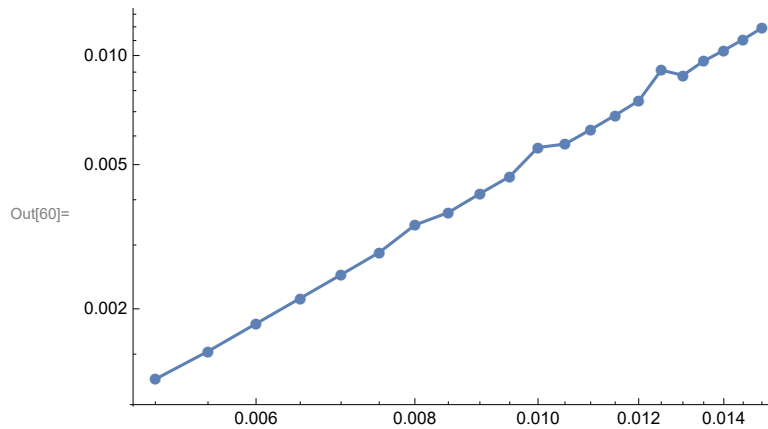
```
In[34]:= fLdt = Function[{f, hx, μ},
  Module[{dtL, dtR, dtC}, dtL = dtR = hx;
  While[Length@iter[f, hx, dtR, μ] == Floor[1 / dtR] + 1, dtR += .5 dtR];
  While[Length@iter[f, hx, dtL, μ] != Floor[1 / dtL] + 1, dtL -= .5 dtL];
  While[Abs[dtL - dtR] > 10-7,
    dtC = .5 (dtL + dtR);
    If[Length@iter[f, hx, dtC, μ] < Floor[1 / dtC] + 1, dtR = dtC, dtL = dtC]];
  dtL];
```

Computing largest time-step for various grid spacings

```
In[57]:= dtDx = Transpose[{#, fLdt[g, #, .01] & /@ #}] &@Range[.005, .015, .0005];
```

Plot of largest time-step vs grid spacing

```
In[60]:= ListLogLogPlot[dtdx, Joined → True, PlotMarkers → Automatic]
```



Best fit curve to the above log-log plot

```
In[61]:= fit[x_] = Fit[Log@dtdx, {1, x}, x]
```

```
Out[61]= 4.20807294458 + 2.05447681479 x
```

This means that dt is proportional to dx^2

Exact relationship between dt and dx

```
In[68]:= fit[x_] = Fit[dtdx, {x^2}, x]
```

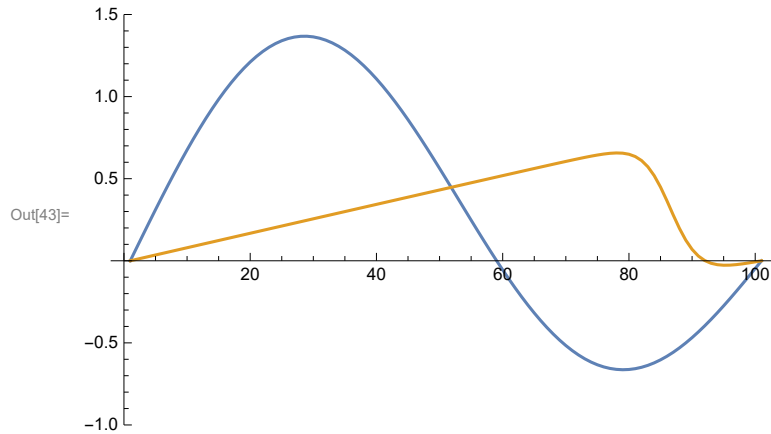
```
Out[68]= 52.9195880506 x^2
```

Therefore the CFL criterion is that dt is approximately equal to $50 dx^2$

d)

Plot of $u(x,t)$ at $t = 0$ and $t = 1$

```
In[43]:= With[{d = iter[g, .01, .1 fLdt[g, .01, .01], .01]},
  ListLinePlot[{d[[1]], d[[-1]]}, PlotRange -> {-1, 1.5}]]
```



We can see that the solution is becoming more steeper with increase in time. This could eventually cause a shock to form.