# HW 2 - ASTR510

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# a) Particle-in-Cell code

## Initialization

#### **Parameters**

```
q1 = -1.; q2 = -1.;
m1 = 1.; m2 = 1.;
L = 2. Pi;
ng = 64;
dxg = L / ng;
dt = dxg / 4;
zc = Range [dxg / 2., L, dxg];
wp = Sqrt[2 # ng / L] &;
T = 16 Pi / wp@# &;
```

#### Function to initialize positions

#### Function to initialize velocities

```
vF = Function[r, Module[{v1, v2, np}, np = r ng;
     v1 = Table[4., np];
     v2 = -v1;
     Join[v1, v2]]];
```

### Function to initialize charge and mass of each particle

```
ln[12]:= qmF = Function[r, Join@@ (Table[#, rng] & /@ {q1/m1, q2/m2})];
```

#### Function to find the zone of a particle

```
In[13]:= zone = Mod[Floor[# ng / L], ng] + 1 &;
```

#### Function to assign densities (CIC)

```
 \label{eq:dcic} \begin{tabular}{l} $dCIC = \#-Mean@\#\&[Plus@@(\{q1,q2\}*(Total[SparseArray[Function[1,zone[1] $\rightarrow$ Abs[1-L/ngFloor[\#ng/L+.5]]ng^2/L^2] $$ $/@(\#-.5L/ng,\#+.5L/ng), \{ng\}]\&/@\#]\&/@ $$ $\{Take[\#,Length[\#]/2], Take[\#,-Length[\#]/2]\}))]\&; $$ $$
```

This function takes positions of particles and computes densities on the grid. Each particle assigns density to a sparse array which are all summed up at the end.

#### Function to solve Poisson equation using matrix inversion

```
Module [\{\phi, \text{solf}\}, \phi[\text{ng}+1] = \phi[1] = 0; \phi[\theta] = \phi[\text{ng}];
solf = \text{LinearSolve}[
\text{CoefficientArrays}[\text{Table}[-(\phi[i-1]+\phi[i+1]-2\phi[i])/\text{dxg}^2 = \rho[i], \{i, 2, \text{ng}\}],
\text{Table}[\phi[i], \{i, 2, \text{ng}\}][[2]]];
phif = \text{Prepend}[\text{solf}[\#[[2;;]]], \theta] \&;
```

This function takes densities and returns potential.

#### Function to interpolate acceleration (equivalent to CIC)

```
accF = ListInterpolation[
Append[#, #[[1]]] &@ (RotateLeft[#] - RotateRight[#]) / (2 dxg) &@ - phiF[#],
Range[.5 dxg, L + .5 dxg, dxg], InterpolationOrder → 1, PeriodicInterpolation → True] &;
```

This function takes densities and returns an interpolating function for acceleration.

## Iterating with LeapFrog method

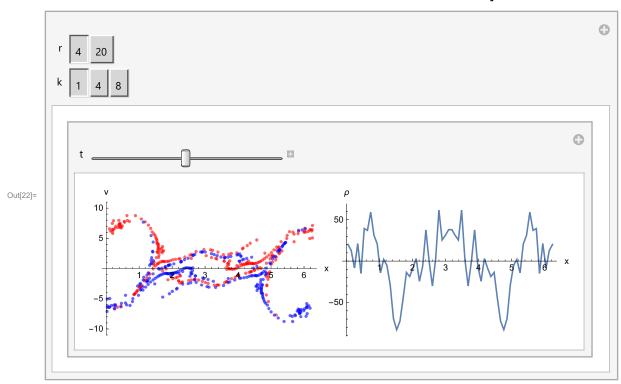
### Time evolution operator

```
H = Function[r, {Mod[#1+dt*#2+.5*dt^2#3, L], #2+dt#3} &[
#[1], #[2], qmF[r] * accF[dCIC[#]][#] &[#[1]] + .5 dt #[2]]] &];
```

This operator takes positions and momenta as input and returns their values at the next time step.

# Interactive plots

```
 \begin{split} & \text{Manipulate} \big[ w = \text{NestList} \big[ \text{H[r], } \{x\text{F[r, k], vF[r]} \}, \text{T[r]} \Big/ \text{dt } // \text{ Floor} \big]; \\ & \text{Manipulate} \big[ \text{Row@} \big\{ \text{ListPlot} \big[ \\ & \text{Take} \big[ \text{Transpose} \big[ \{w[[n, 1]], w[[n, 2]] \} \big], \#] \& /@ \big( \text{Length} \big[ w[[1, 1]] \big] \Big/ 2 \, \{1, -1\} \big), \\ & \text{PlotRange} \to \{\text{Min@\#, Max@\#}\} \&@w[[-1, 2]], \text{PlotStyle} \to \{\{\text{Red, ##}\}, \{\text{Blue, ##}\}\} \& [\\ & \text{Opacity} \big[ .6 \big], \text{PointSize} \big[ .015 \big] \big], \text{ImageSize} \to 250, \text{AxesLabel} \to \{"x", "v"\} \big], \\ & \text{ListLinePlot} \big[ \text{Transpose} \big[ \{\text{zc, dCIC@w} \big[ [n, 1] \big] \} \big], \text{ImageSize} \to 250, \\ & \text{AxesLabel} \to \{"x", "\rho"\} \big] \big\}, \, \{\{n, 1, "t"\}, 1, \text{Length} \big[ w \big], 1\} \big], \\ & \{\{r, 4\}, \{4, 20\}\}, \, \{\{k, 1\}, \{1, 4, 8\}\}, \, \text{SynchronousUpdating} \to \text{False} \big] \\ \end{split}
```



c)