Binary Orbits

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Finding minimum mass of planet

Defining parameters and constants

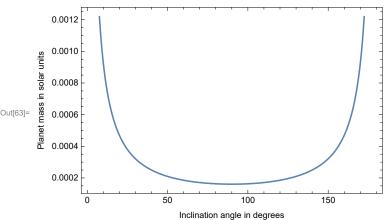
```
G = Quantity["GravitationalConstant"];
mS = Quantity[1., "SolarMass"];(*Mass of star*)
rS = Quantity[1., "SolarRadius"]; (*Radius of star*)
oP = Quantity[40., "Days"]; (*Period of orbit*)
vR = Quantity[10., "m/s"](*Observed radial velocity*)
```

Solving functions of inclination angle (a)

We solve the distances to the two bodies from the center of mass of the system, as well as the mass and velocity of the second body. This solution is accurate for any two bodies, regardless of their mass ratio.

Plot of planet mass vs angle

ln[63]:= Plot[mP[i°], {i, 0, 180}, Frame \rightarrow True, FrameLabel → {"Inclination angle in degrees", "Planet mass in solar units"}]



Therefore the minimum mass is at the edge-on case (i = 90°).

In[28]:= UnitConvert[mP[Pi/2], "JupiterMass"]

Out[28]= **0.16829154877683** M_{2|}

Values for the edge-on case

ln[30]:= {dS[Pi/2], dP[Pi/2], mP[Pi/2], vP[Pi/2]} // Column $5.5003948332559 \times 10^6 \text{ m}$ $3.4238679276079 \times 10^{10} \, \text{m}$ Out[30]= 0.00016064856909065 M_O 62247.675510618 m/s

Solving angle range for crossing

Given density of planet

```
In[53]:= rhoP = Jupiter (planet) ["Density"];
```

Assuming that the tangent touches both bodies

```
ln[55]:= \{iMax, x, y, rP\} = Module[\{i, x, y, rP\},
        List@@Quiet@Reduce[(*Equations*)
             {Abs@Cos[i] = rS/(y) = rP/(x),}
                (x + y) = dP[i] + dS[i],
               mP[i] / (4/3 Pi (rP)^3) = rhoP,
               0 < i < Pi/2, x > rP, y > rS
              /. q_Quantity ⇒ QuantityMagnitude[q, "SI"], {i, x, y, rP}, Reals][[All, 2]]];
```

The range of orbital inclinations in degrees

```
In[48]:= {iMax, Pi - iMax} / °
\mathsf{Out}[48] = \ \{ \ 89.93425608962 \ , \ 90.06574391038 \}
```

Radius of planet

```
In[58]:= Quantity[rP, "Meters"]
Out[58]= 3.8597896555509 \times 10^7 \text{ m}
```