

MATHEMATICAL MODELS

$$y^{(n)} + a_{n-1}y^{(n-1)} + \dots + a_1\dot{y} + a_0y = b_n u^{(n)} + b_{n-1}u^{(n-1)} + \dots + b_1\dot{u} + b_0u$$

LODE

$$H(s) = \frac{Y(s)}{U(s)} = \frac{b_n s^n + \dots + b_1 s + b_0}{s^n + a_{n-1}s^{n-1} + \dots + a_1 s + a_0}$$

$$= b_n + \frac{c_{n-1}s^{n-1} + \dots + c_1 s + c_0}{s^n + a_{n-1}s^{n-1} + \dots + a_1 s + a_0}$$

$$c_i = b_i - b_n a_i$$

$$= b_n + \frac{\alpha_1 \delta_1}{s+p_1} + \dots + \frac{\alpha_n \delta_n}{s+p_n}$$

TRANSFER FUNCTION

$$\dot{x} = Ax + Bu$$

$$y = Cx + Du$$

$$A = \begin{bmatrix} 0 & 1 & 0 & \dots & 0 \\ 0 & 0 & 1 & \dots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 & 1 \\ -a_0 & -a_1 & \dots & -a_{n-1} & -a_n \end{bmatrix}$$

$$B = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ 1 \end{bmatrix}$$

phase-variable form

$$C = [c_0 \ c_1 \ \dots \ c_{n-1}] \quad D = b_n$$

$$A = \begin{bmatrix} -p_1 & & & 0 \\ & -p_2 & & 0 \\ & & \ddots & \\ 0 & & & -p_n \end{bmatrix}$$

$$B = \begin{bmatrix} \alpha_1 \\ \alpha_2 \\ \vdots \\ \alpha_n \end{bmatrix}$$

diagonal form

$$C = [\delta_1 \ \delta_2 \ \dots \ \delta_n] \quad D = b_n$$

STATE SPACE

EXAMPLE

LODE

$$\ddot{y} + 6\dot{y} + 11y + 6y = 3\ddot{u} + 2\dot{u} + u$$

TRANSFER FUNCTION

$$G(s) = \frac{3s^2 + 2s + 1}{s^3 + 6s^2 + 11s + 6} = 3 + \frac{-16s^2 - 32s - 17}{s^3 + 6s^2 + 11s + 6} = 3 + \frac{-\frac{1}{2}}{s+1} + \frac{17}{s+2} + \frac{-65/2}{s+3}$$

STATE SPACE

$$\left\{ \begin{aligned} \dot{x} &= \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ -6 & -11 & -6 \end{bmatrix} x + \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} u \\ y &= [-17 \ -32 \ -6] x + 3u \end{aligned} \right\} \quad \text{or} \quad \left\{ \begin{aligned} \dot{x} &= \begin{bmatrix} -1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -3 \end{bmatrix} x + \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} u \\ y &= [-\frac{1}{2} \ 17 \ -\frac{65}{2}] x + 3u \end{aligned} \right\}$$

TRANSFORMATIONS: state space representations are not unique

Given $\begin{cases} \dot{x} = A_1 x + B_1 u \\ y = C_1 x + D_1 u \end{cases}$, let $x = Tz$ (T invertible), then $\begin{cases} \dot{z} = A_2 z + B_2 u \\ y = C_2 z + D_2 u \end{cases}$ is a valid state space representation, where $A_2 = T^{-1}A_1T$, $B_2 = T^{-1}B_1$, $C_2 = C_1T$, $D_2 = D_1$

Trans. to phase variable form

- (1) Find $C(A, B)^{-1} = [B \ AB \ A^2B \ \dots \ A^{n-1}B]^{-1}$
- (2) Let $q^T = [0 \ \dots \ 0 \ 1] C(A, B)^{-1}$
- (2) Form $Q^{-1} = \begin{bmatrix} q^T \\ q^T A \\ \vdots \\ q^T A^{n-1} \end{bmatrix}$
- (4) Then $\bar{A} = Q^{-1}AQ$ and $\bar{B} = Q^{-1}B$ are in phase-variable form

Diagonalizing Transformation

- (1) Find the eigenvector v_i associated with each eigenvalue λ_i (assume distinct λ_i)
- (2) Form $P = [v_1 \ v_2 \ \dots \ v_n]$
- (3) Then $\Lambda = P^{-1}AP = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$