

Foldable Robotics

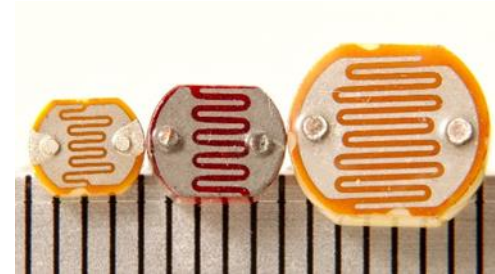
Class XVI: Sensors

Sensors

- Measure Physical properties
 - Light, Strain, Heat
 - Measuring Force is hard directly

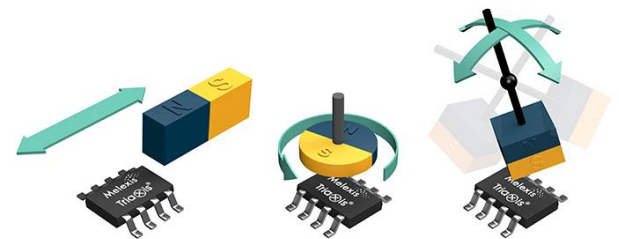
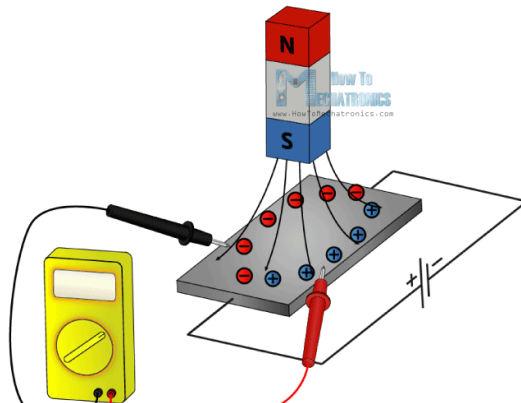
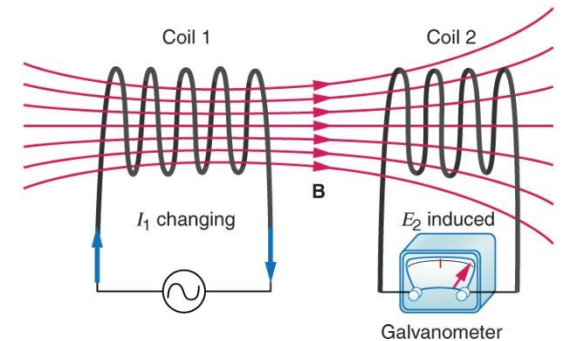
Light

- Lots of different mechanisms for light
- Photoresistor
- Photodiode
 - Photovoltaic
 - $+light \rightarrow +V$
 - Photoconductor
 - $+light \rightarrow -R$
- Phototransistor
 - $+light$



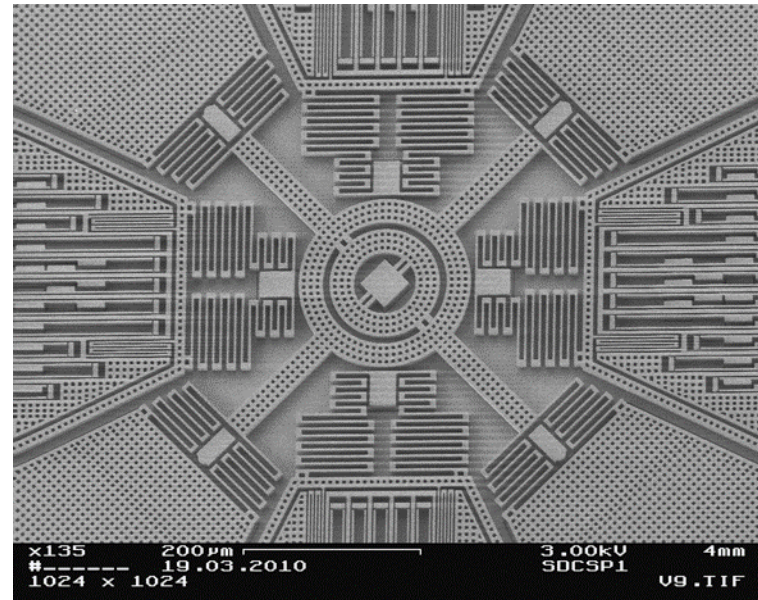
Magnetic Field

- Types
 - Reed Switch
 - Inductive - Galvanometer
 - Hall Effect Sensor – go linear.



Motion

- Accelerometer
 - accelerations
- Gyro
 - Angular accelerations
- IMU
 - Everything
 - Smoothing
 - Integration
 - Position, Velocity, Acceleration
 - Rotation, rotational velocity, angular acceleration



Position Resistive

- Temperature-dependence
- Hysteresis
- Types
 - Linear Potentiometer
 - Rotary Potentiometer
 - Flex Sensor
 - etc



Position Capacitive

- Two charged plates

- Spacing Change

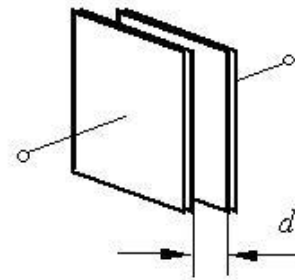
- $$C = \frac{\epsilon A}{d}$$

$$\delta_d = \frac{pd}{\rho E}$$

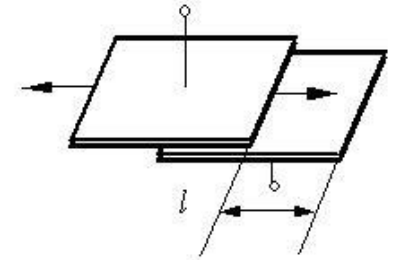
$$\frac{\partial C}{\partial p} = \frac{\epsilon A}{\rho_A E d_0}$$

- Area Change

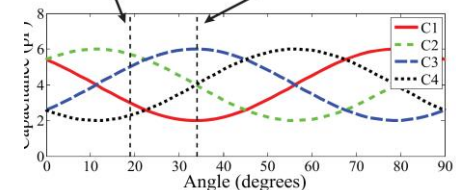
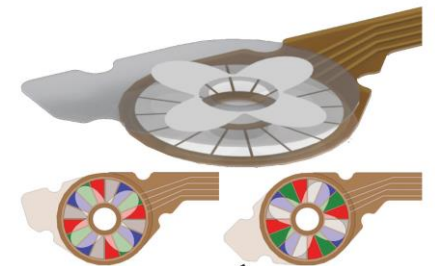
- Digital Calipers



Spacing variation



Area variation

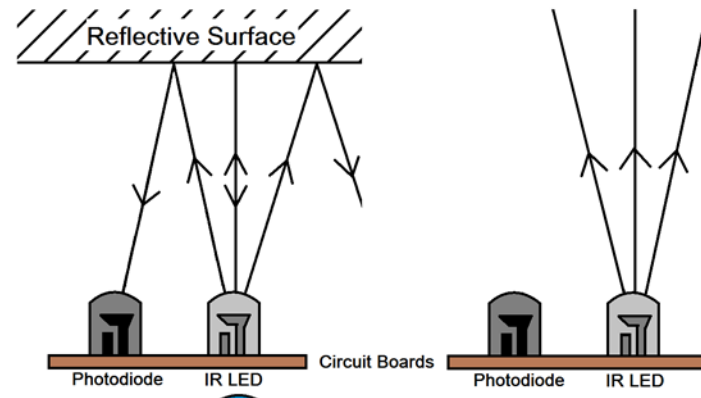


<http://www.chenyang-ism.com/CapaSensorPosi.htm>

D. M. Aukes, B. Hammer, J. Ulmen, H. Stuart, M. R. Cutkosky, S. Kim, P. Garcia, A. Edsinger, J. Ulmen, P. Garcia, H. Stuart, and A. Edsinger, "Design and testing of a selectively compliant underactuated hand," *Int. J. Rob. Res.*, Feb. 2014.

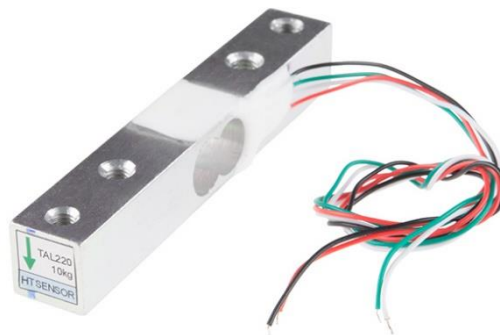
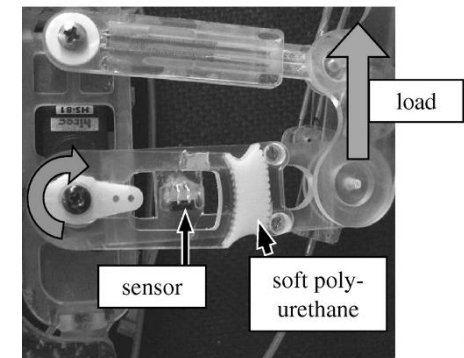
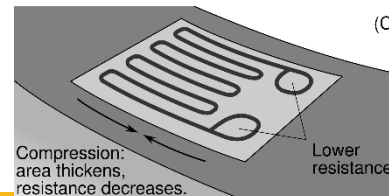
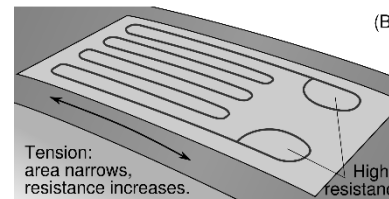
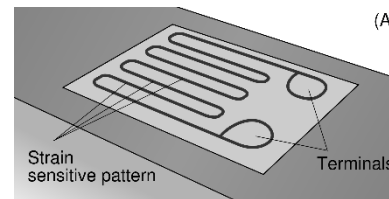
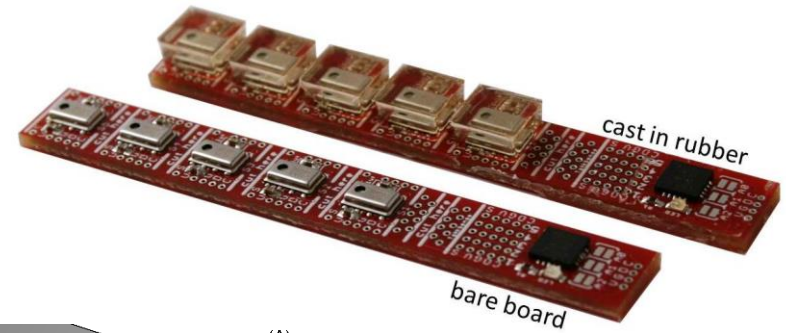
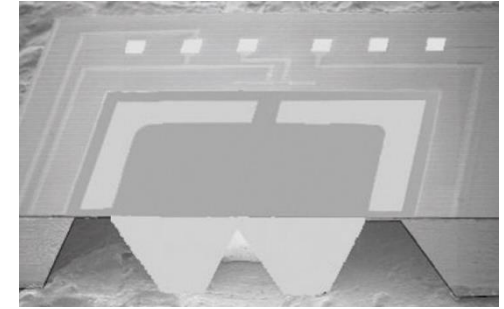
Position - Other

- Emitter/Detector Pair
 - Proximity
 - Based on reflectance
- Ultrasonic
 - High Noise
 - Longer distances



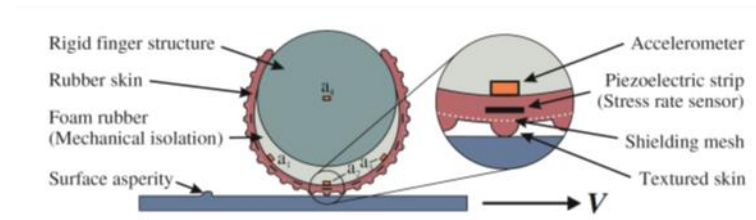
Pressure / Force

- Strain Gauge
 - Temperature-sensitive
 - Wheatstone Bridge
 - Load Cell
- Other Position Sensors



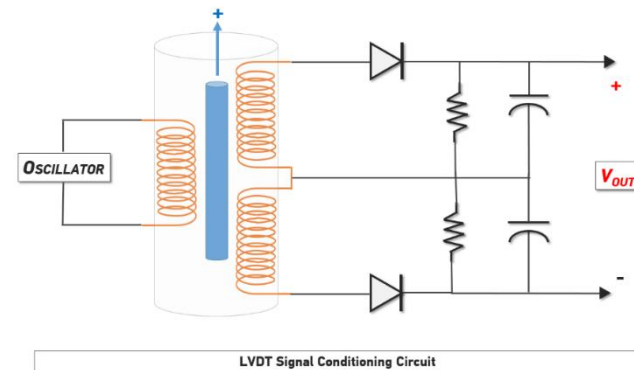
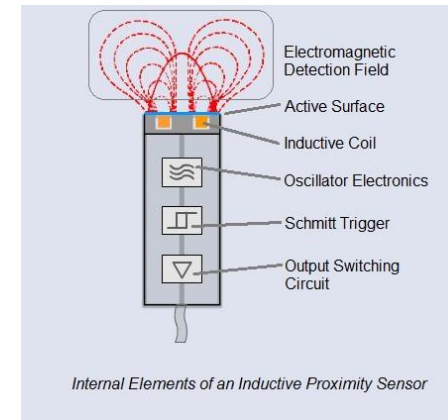
Dynamic Tactile Sensing

- Piezo



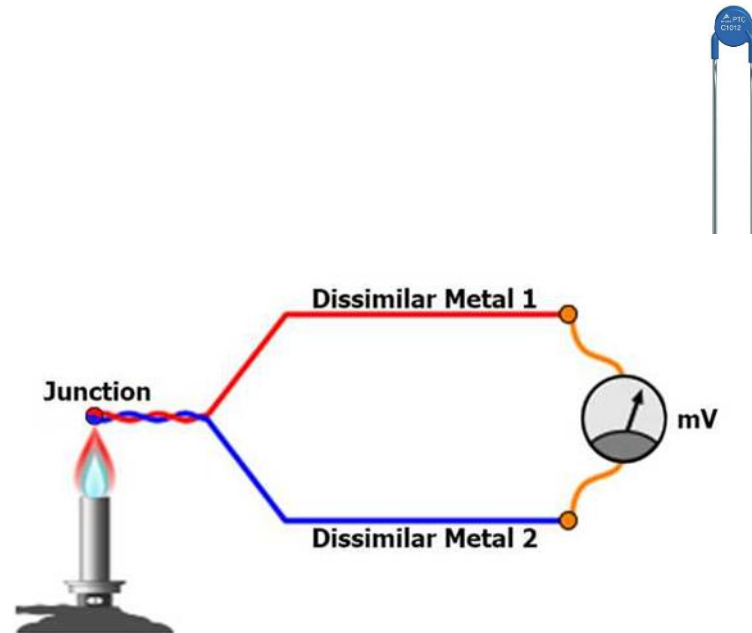
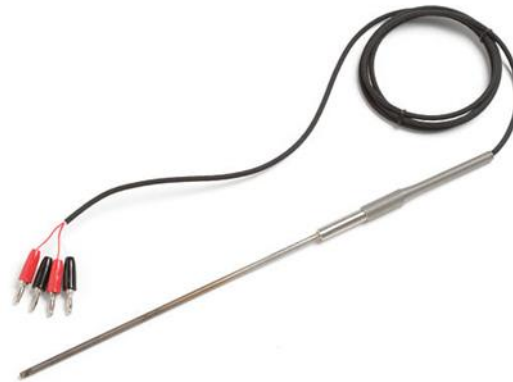
Position Induction

- Non-contacting
- Requires AC
- Senses Metals, esp Ferrous Metals
- Types:
 - Inductive Proximity Switch, Position Sensors
 - LVDT
 - Inductive Encoders



Temperature

- Resistance temperature detector
- Thermistor
- Thermocouple

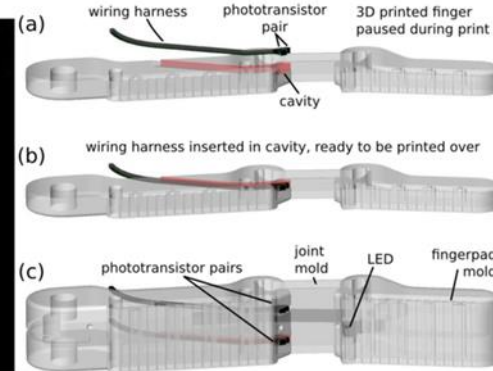
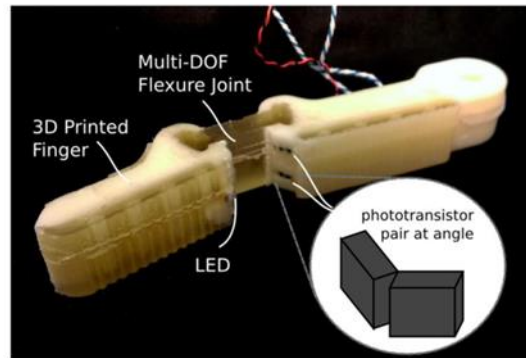
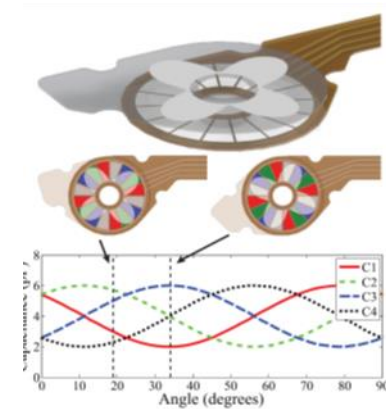
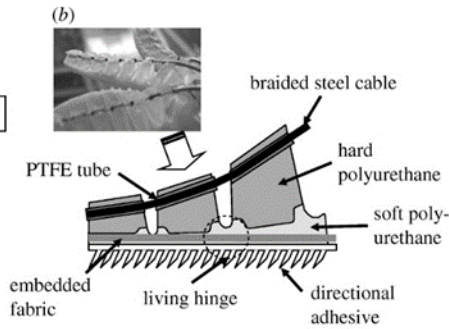
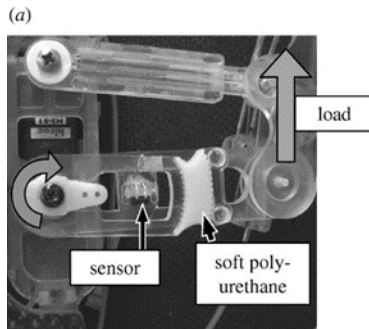


Encoders

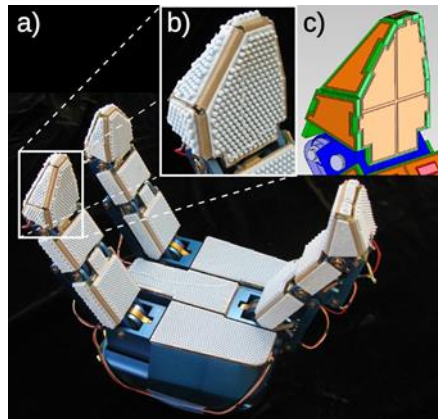
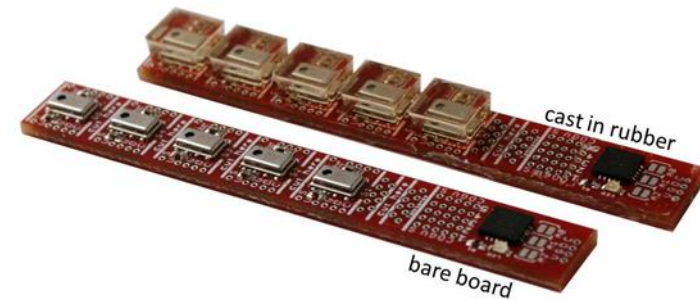
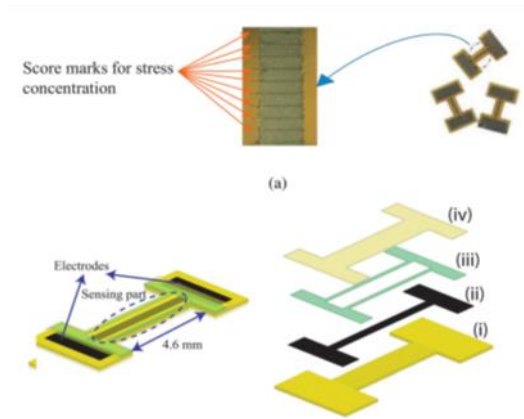
- Types
 - Optical
 - Absolute
 - Relative
 - Magnetic
 - Capacitive
 - Inductive



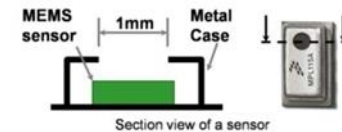
Embedding Sensors



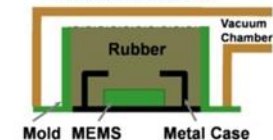
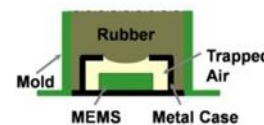
Embedding Sensors



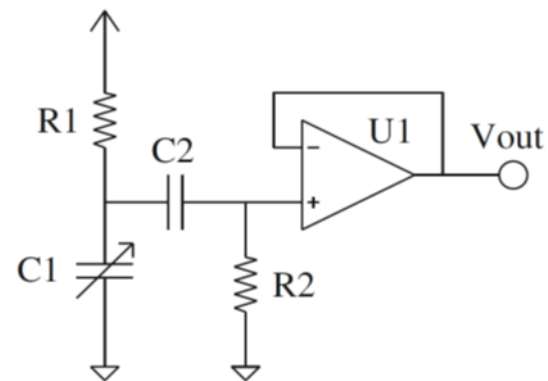
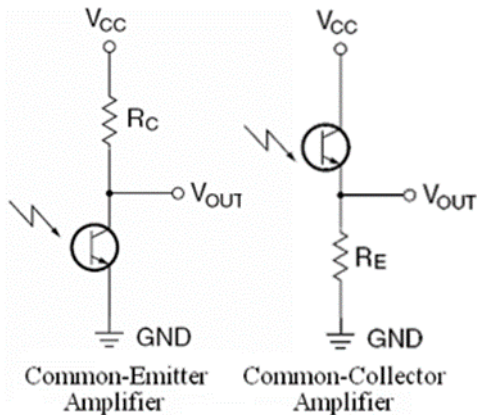
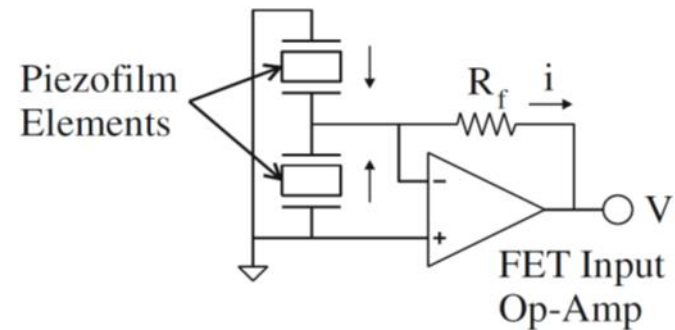
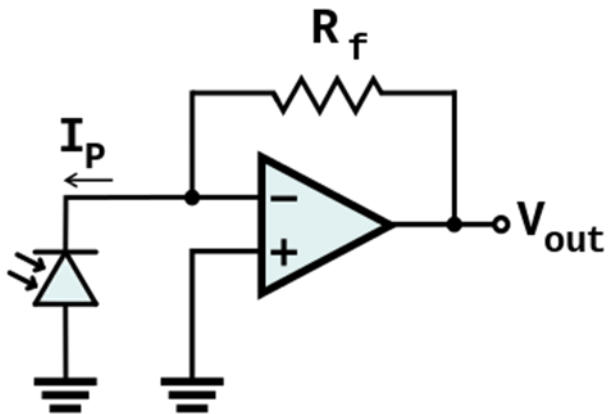
Rubber Casting Process



- 1) Rubber is poured into the mold
 - Rubber does not fill the sensor area
- 2) Use a vacuum chamber
 - Degassing removes air bubbles
 - Rubber fills the sensor



Common Circuits



Circuit Conditioning

- Self-contained packages
- Op Amps
- Transistor-based amplification