This is the Title

This is the Subtitle

Firstname Lastname

01-01-2019

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  + Other classes
    - Asdfasdf
      * asdfasdf
  + Work
  + Transit
  + Meals
  + Family
* Identify at least ***four*** hours shared by the team ***outside of class time.***
* If you find sufficient overlap, create a team in Canvas. You are limited to **four** members maximum (without instructor approval and override). Please email the instructor or see in class for approval.

1. Draft **Business Model Canvas** using [Canvanizer](http://canvanizer.com) ({%POINTS%} points)
2. Draft **Assumptions Exercise** worksheet ([PDF](https://s3.amazonaws.com/TalkingtoHumans/Talking+to+Humans+Assumptions+Exercise.pdf) / [GDOC](https://docs.google.com/a/asu.edu/document/d/1LBGCGtimLLxBfB8WUjJe8KmbBerZwywZCr8hvg5y2uw/edit?usp=sharing)) ({%POINTS%} points)
3. Draft customer discovery interview questions ({%POINTS%} points)
   * Read [*Talking to Humans*](https://s3.amazonaws.com/TalkingtoHumans/Talking+to+Humans.pdf) pp. 37 - 43 and 77 - 80

* Then, write a report with the following sections:

1. Final **Business Model Canvas** (9 sections @ {%POINTS%} points per section = {%POINTS%} points). Using [Canvanizer](http://canvanizer.com), develop a business model for your product.
2. Final **Assumptions Exercise** worksheet ([PDF](https://s3.amazonaws.com/TalkingtoHumans/Talking+to+Humans+Assumptions+Exercise.pdf) / [GDOC](https://docs.google.com/a/asu.edu/document/d/1LBGCGtimLLxBfB8WUjJe8KmbBerZwywZCr8hvg5y2uw/edit?usp=sharing)) (13 questions @ {%POINTS%} points per question = {%POINTS%} points)
3. Final customer discovery interview questions ({%POINTS%} points)

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| * Item | * Description |
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Uncaptioned figure:



Captioned figure

Caption

Caption

Code blocks

import sys  
import os

if (x==1){}  
else  
{  
 asdf = 1;  
}

* Sharifzadeh, Mohammad, and Daniel M. Aukes. 2020. “Curvature-Induced Buckling for Flapping-Wing Vehicles.” IEEE Transactions on Mechatronics (Under Revision).
* Jiang, Yuhao, Mohammad Sharifzadeh, and Daniel M. Aukes. 2020. “Reconfigurable Soft Flexure Hinges via Pinched Tubes.” IEEE Robotics and Automation Letters (Submitted).
* Sharifzadeh, Mohammad, Yuhao Jiang, and Daniel M. Aukes. 2019. “Compensating for Loads in Parallel Compliant Mechanisms.” Soft Robotics(Under Revision).

1. this is a footnote [↑](#footnote-ref-1)