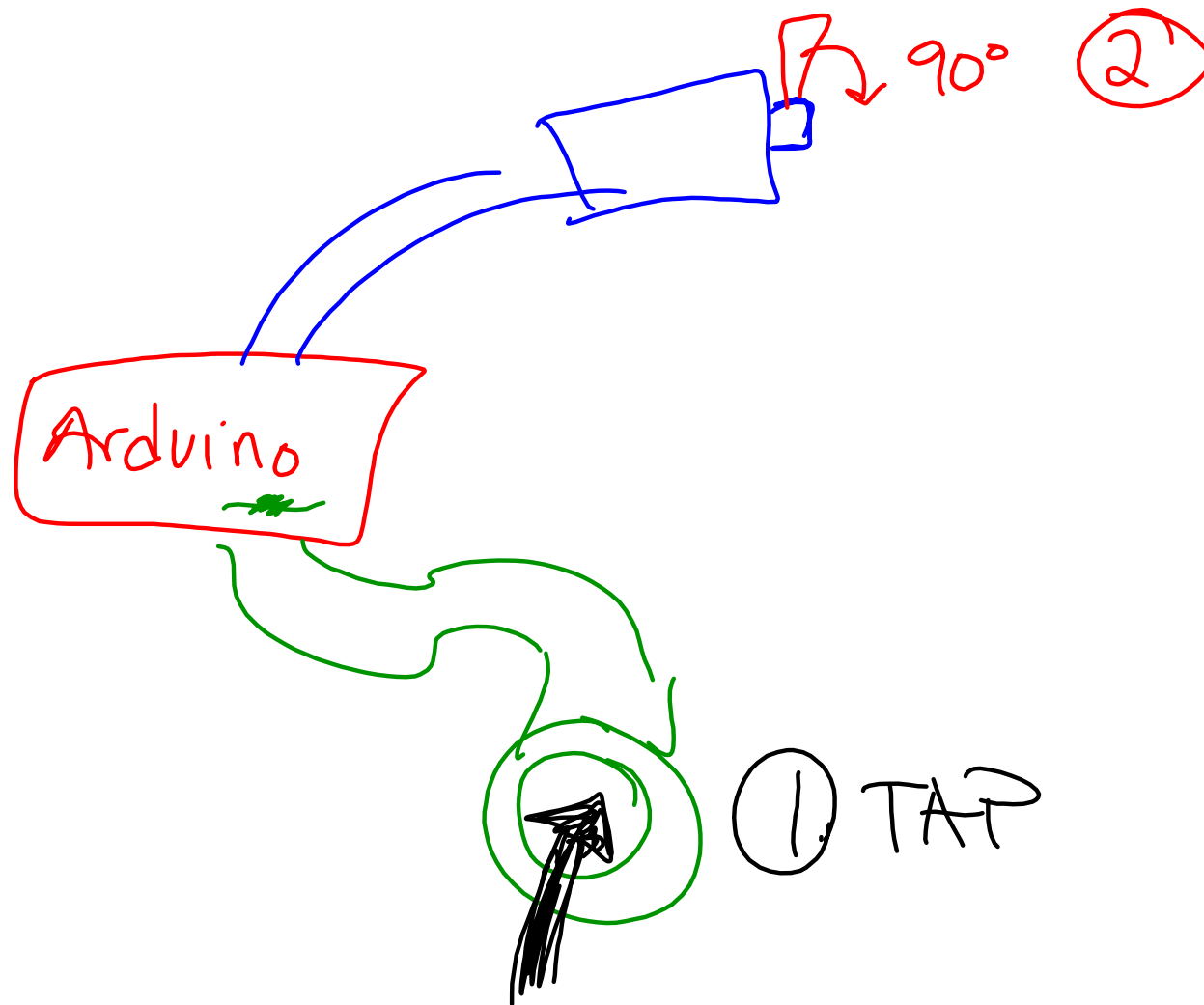


## Today's Goal:

- Set up an Arduino
- Write a sketch

1. Arduino will sense a reasonable tap from a piezo sensor
2. When a tap is sensed, a servo should rotate  $90^\circ$



Piezo

Detects a tap

Servo~~Rotates 180°  
over & over~~modify:  
rotates 90°  
ONCE

Remember: you need to merge  
variables, setup code,  
beginning comments

Pseudocode:

set up variables/constants

setup

establish starting values

set servo to a starting position ( $0^\circ$ )

loop

read the piezo sensor value

check to see if sensor  $>$  threshold

rotate servo to  $90^\circ$

delay to let Arduino catch up

Checklist:

DIRECT WITH PRINTED CODE.

- ☐ When you tap the piezo, the servo rotates  $90^\circ$
- ☐ Unneeded code has been removed (extra variables, LED, serial monitor)
- ☐ Initial comments describe sketch and include your name
- ☐ Sketch has comments that correctly describe the actions of each line of code