

# Lecture #8

# System Services &

# Sensors

Mobile Applications  
Fall 2024

# Background Tasks

- Sending logs or tracking user progress.
- Upload images, videos or session data.
- Syncing data.
- Processing data.



# Options

- Threads
- Executors
- Services
- AsyncTasks
- Handlers and Loopers
- Coroutines
- Jobs (API 21+)
- GcmNetworkManager
- SyncAdapters
- Loaders
- AlarmManager
- WorkManager

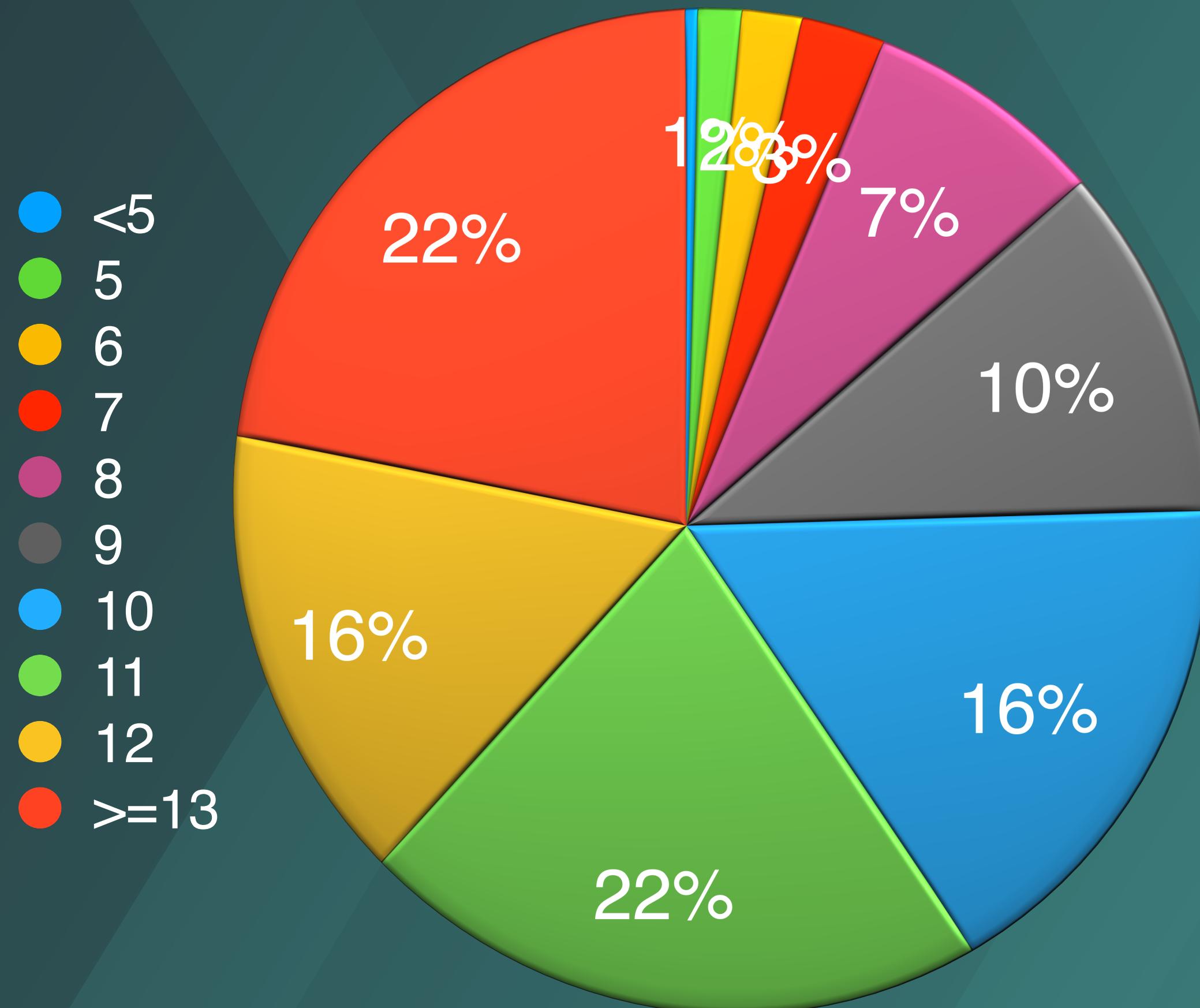


# Battery Optimizations

- Doze mode
- App standby
- Limited implicit broadcasts
- Release cached wakelocks
- Background service limitations
- App standby buckets
- Background restricted apps

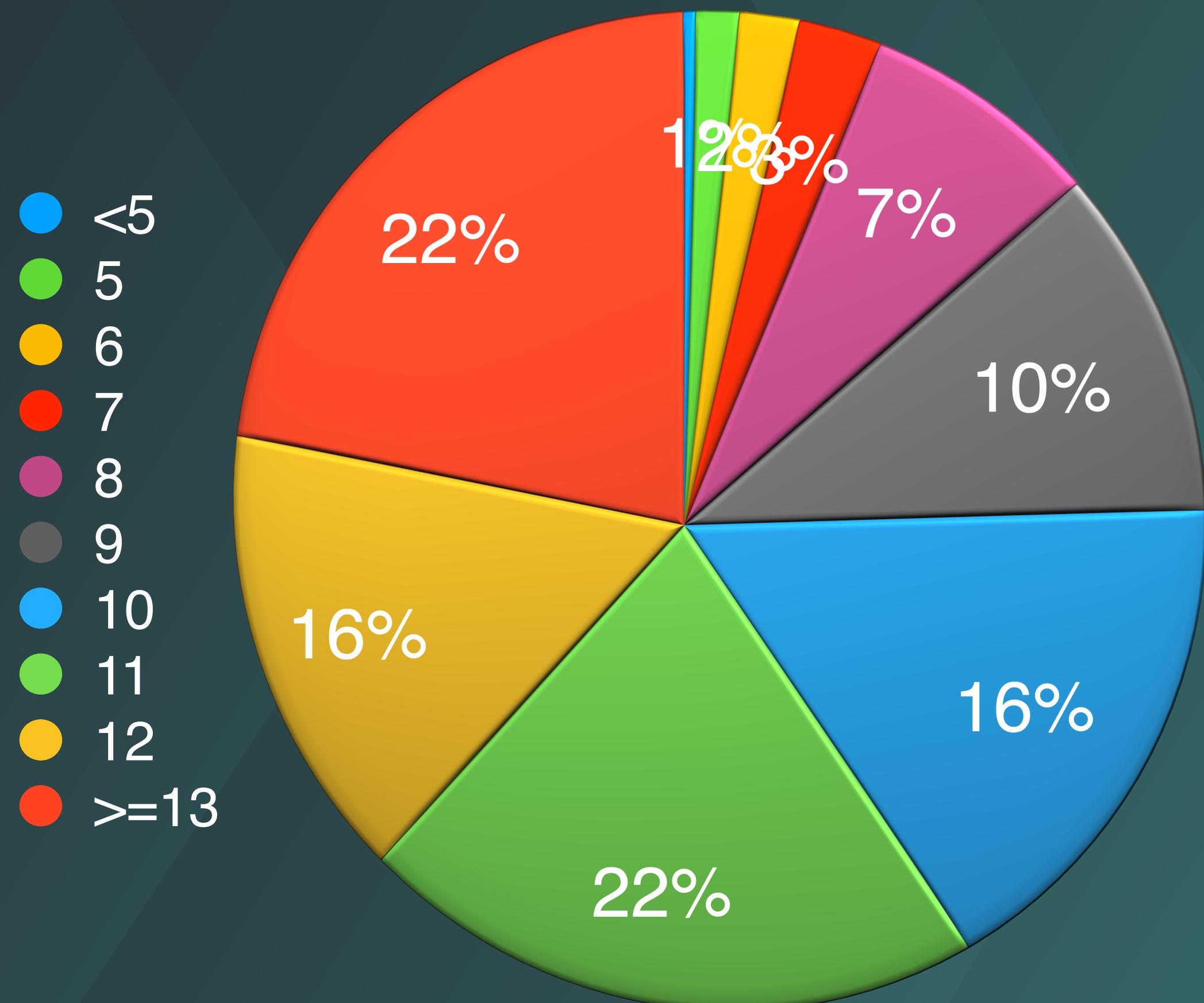


# Compatibility

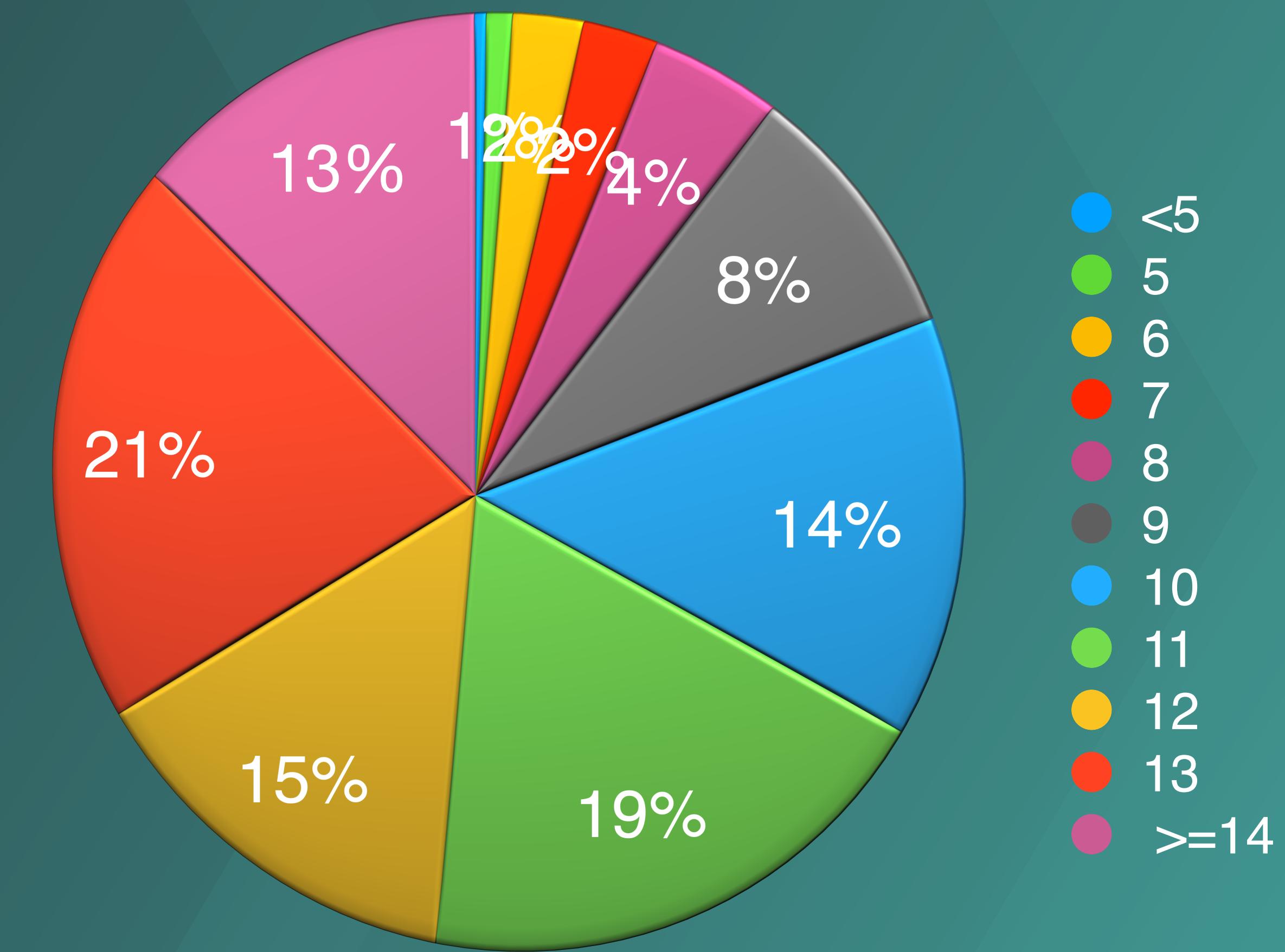


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# Compatibility

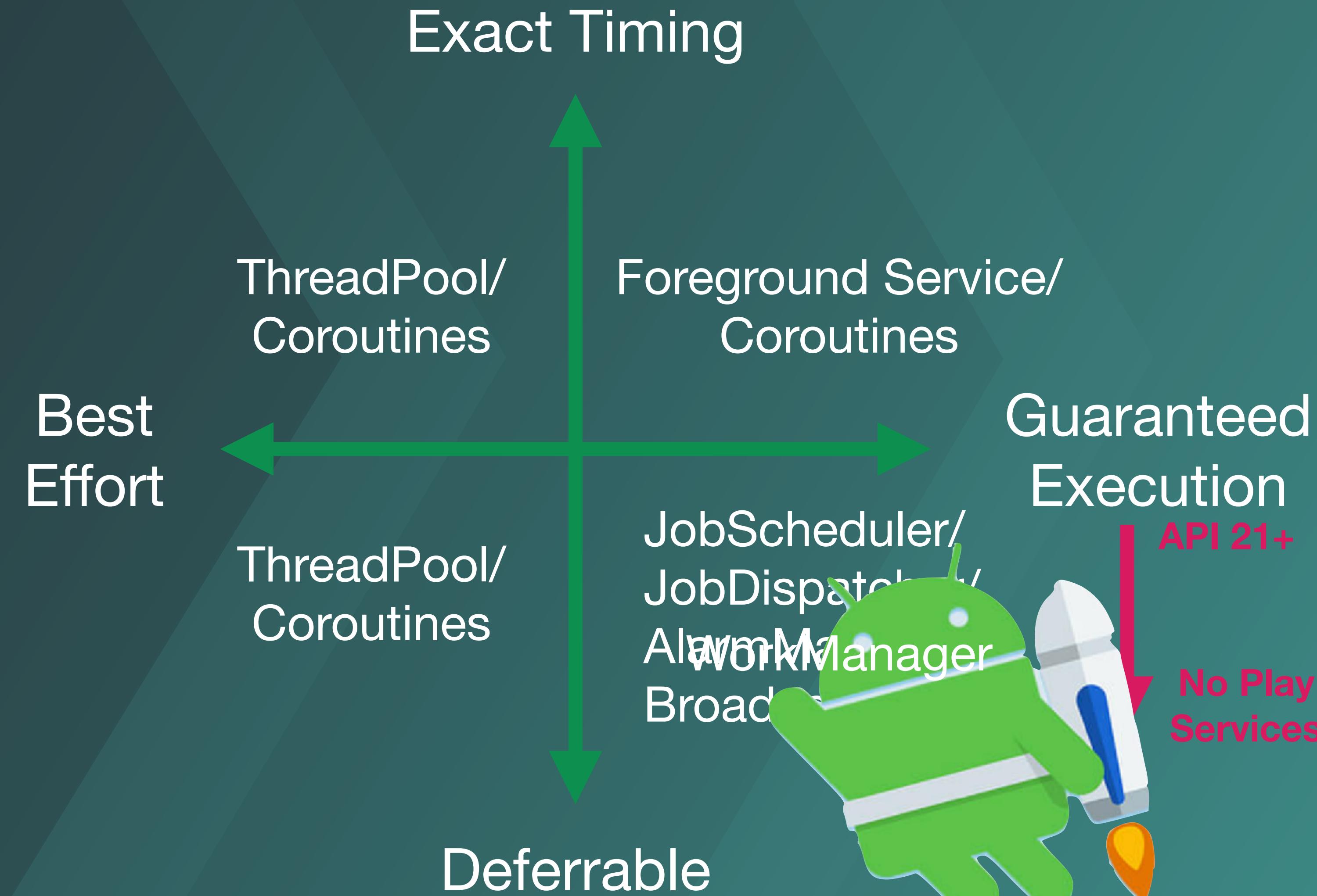


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# Requirements



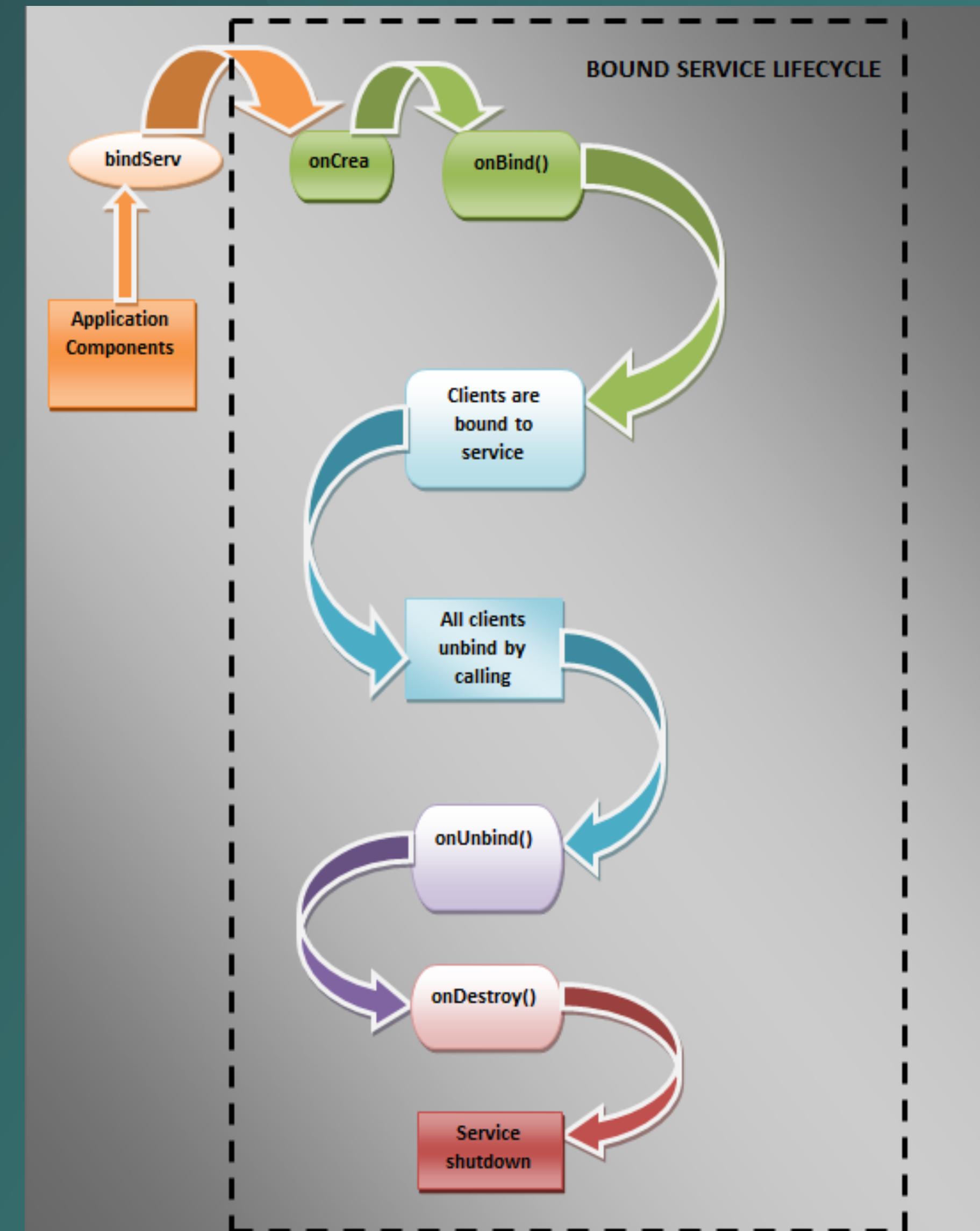
# Services

- Perform long-running operations in the background.
- It does not provide a user interface.
- Continues to run even if the user switches to another application.
- Eg.:
  - Network transactions.
  - Play music.
  - Perform I/O.
  - Use a content provider.



# Services

- Types:
  - Foreground
  - Background
  - Bound



# Foreground

- **Purpose:** Used for tasks that the user is actively aware of and should not be stopped abruptly by the system.
- **Example Use Cases:**
  - Playing music in a media player.
  - Navigation in a GPS app.
- **Characteristics:**
  - Must display a persistent notification to the user while running.
  - The system gives these services higher priority to avoid being killed under memory pressure.

# Background

- **Purpose:** Used for tasks that do not require user interaction and can run in the background.
- **Example Use Cases:**
  - Syncing data periodically (e.g., email).
  - Downloading files in the background.
- **Characteristics:**
  - Lower priority compared to foreground services.
  - Subject to background execution limits in modern Android (starting from Android 8.0/Oreo), which restrict their activity to save power.
  - Often replaced by WorkManager or JobScheduler for better efficiency.

# Bound

- **Purpose:** Provides a client-server interface to allow components (like Activities) to bind to the service and interact with it.
- **Example Use Cases:**
  - Allowing a music app to control playback.
  - Fetching data from a service (e.g., fetching updates in real-time).
- **Characteristics:**
  - Can exist only as long as other application components are bound to it.
  - Ideal for inter-process communication (IPC) using Messenger, AIDL, or direct method calls.

# Key Differences

Feature	Foreground Service	Background Service	Bound Service
User Awareness	Persistent notification shown	Hidden from the user	Depends on the client
Priority	High	Low	Medium (depends on binding component)
Lifecycle	Explicitly managed by the app	Managed by the system	Tied to the lifecycle of binding components
Termination Risk	Low	High (subject to limits)	Exists while bound
Use Cases	Real-time user tasks	Background data handling	Client-server communication

# Declaring a service in the manifest

```
<manifest ... >
...
<application ... >
    <service android:name=".ExampleService" />
    ...android:description="Service Description"
</application>
</manifest>
</application>
</manifest>
```

# Creating a Service

- Service
  - Base class for all services.
  - Create and manage a new thread on your own.
- IntentService
  - Subclass of Service.
  - Uses a worker thread.
  - Implement onHandleIntent()

```
/*
 * A constructor is required
 * with a name for the worker thread.
 */

class HelloService extends Service {
    private ServiceHandler mServiceHandler = null;
    private var mServiceHandler: ServiceHandler? = null
    * The IntentService calls this method
    // Hand the handle to the worker thread
    private inner class ServiceHandler(looper: Looper) : Handler(looper)
        *Override fun handleMessage(msg: SMessage) {
            * stop the service if you do not want to work here, like download a file.
            * // For our sample, we just sleep for 5 seconds.
        override fun onHandleIntent(intent: Intent?) {
            tryThread.sleep(5000)
            Thread.sleep(5000)
        } catch(e: InterruptedException) {
            // Thread.currentThread().interrupt()
            Thread.currentThread().interrupt()
        } // Stop the service using the startId, so that we don't stop
        } // the service in the middle of handling another job
    } stopSelf(msg.arg1)
}
```

# Service Management

- Starting a service
- Stopping a service

```
Intent(this, HelpServiceClass.java).also {  
    intent -> startService(intent)  
}  
        stopSelf()
```

# Notify the User

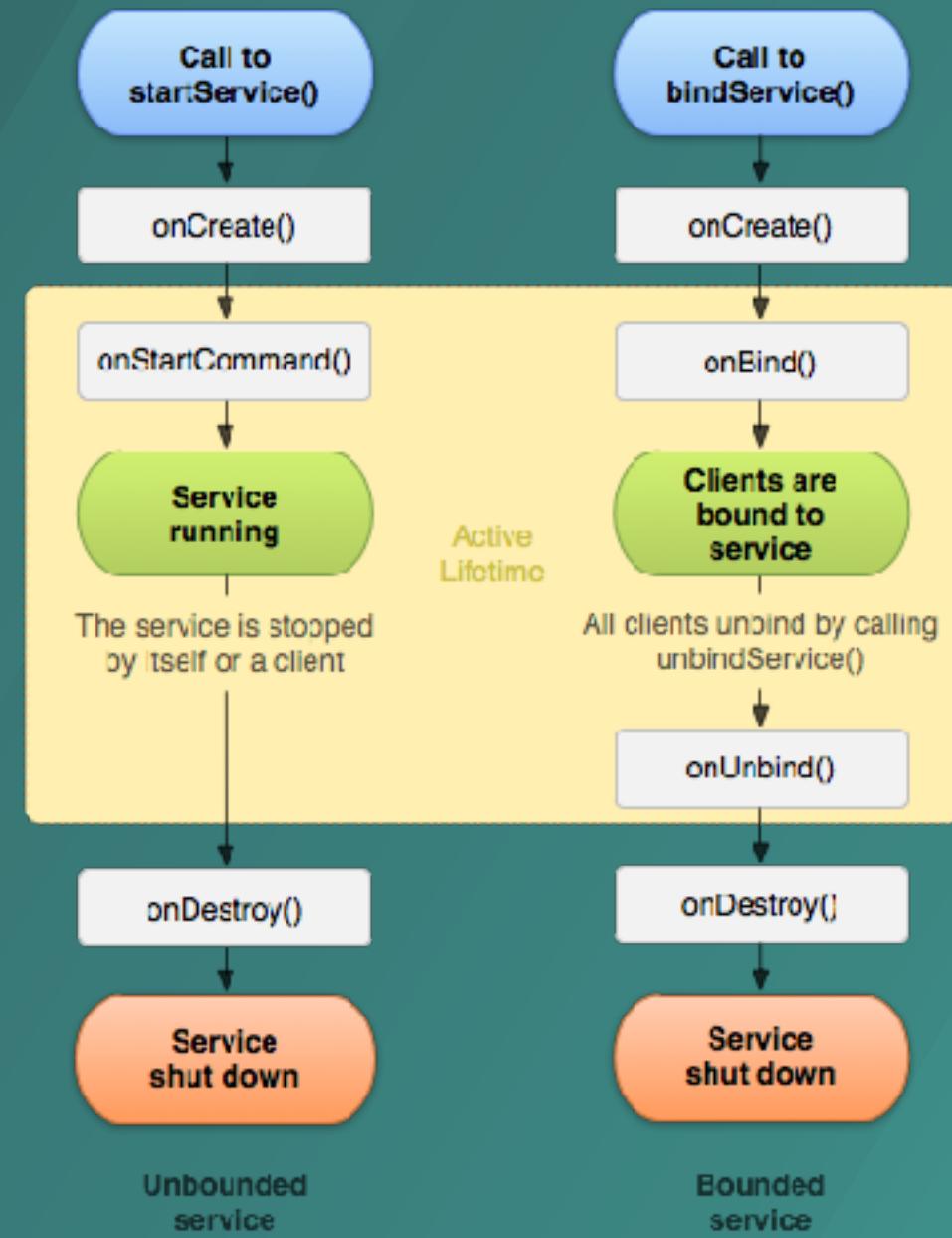
- Toast Notifications
- Status Bar Notifications

```
val pendingIntent: PendingIntent =
    Intent(this, ExampleActivity::class.java).let { notificationIntent ->
        PendingIntent.getActivity(this, 0, notificationIntent, 0)
    }
    val text = "Hello toast!"
    val duration=Toast.LENGTH_SHORT
    val notification=NotificationCompat.Builder(this,
        CHANNEL_DEFAULT_IMPORTANCE)
        .setContentTitle("Hello toast!")
        .setContentText(applicationContext.text)
        .setContentText(getText(R.string.notification_message))
        .setSmallIcon(R.drawable.icon)
        .setContentIntent(pendingIntent)
        .setTicker(getText(R.string.ticker_text))
        .build()
startForeground(ONGOING_NOTIFICATION_ID, notification)
```

# Service Lifecycle

DEMO

```
class ExampleService : Service() {  
    private var mStartMode: Int = 0 // how to behave if the service is killed  
    private var mBinder: IBinder? = null // interface for clients that bind  
    private var mAllowRebind: Boolean = false // whether onRebind should be used  
  
    override fun onCreate() {  
        // The service is being created  
    }  
    override fun onStartCommand(intent: Intent?, flags: Int, startId: Int): Int {  
        // The service is starting, due to a call to startService()  
        return mStartMode  
    }  
    override fun onBind(intent: Intent): IBinder? {  
        // A client is binding to the service with bindService()  
        return mBinder  
    }  
    override fun onUnbind(intent: Intent): Boolean {  
        // All clients have unbound with unbindService()  
        return mAllowRebind  
    }  
    override fun onRebind(intent: Intent) {  
        // A client is binding to the service with bindService(),  
        // after onUnbind() has already been called  
    }  
    override fun onDestroy() {  
        // The service is no longer used and is being destroyed  
    }  
}
```



# Alarm Manager

- Alarm types:
  - ELAPSED\_REALTIME
  - ELAPSED\_REALTIME\_WAKEUP
  - RTC
  - RTC\_WAKEUP

```
alarmMgr?.setInexactRepeating(  
    AlarmManager.ELAPSED_REALTIME_WAKEUP,  
    SystemClock.elapsedRealtime() + AlarmManager.INTERVAL_HALF_HOUR,  
    AlarmManager.INTERVAL_HALF_HOUR,  
    alarmIntent  
)  
    // Cancel the alarm.  
    alarmMgr?.cancel(alarmIntent)
```

# Alarm at 14:00

DEMO

```
// Set the alarm to start at approximately 2:00 p.m.  
val calendar: Calendar = Calendar.getInstance().apply {  
    timeInMillis = System.currentTimeMillis()  
    set(Calendar.HOUR_OF_DAY, 14)  
}  
  
// With setInexactRepeating(), you have to use one of the AlarmManager interval  
// constants--in this case, AlarmManager.INTERVAL_DAY.  
alarmMgr?.setInexactRepeating(  
    AlarmManager.RTC_WAKEUP,  
    calendar.timeInMillis,  
    AlarmManager.INTERVAL_DAY,  
    alarmIntent  
)
```

# JobScheduler

- Register the Service

```
<service  
    android:name=".MyJobService"  
    android:permission="android.permission.BIND_JOB_SERVICE"  
    android:exported="true"/>
```

- Schedule a Job

```
val builder = JobInfo.Builder(jobId++, serviceComponent)  
  
builder.setMinimumLatency(delay.toLong() * TimeUnit.SECONDS.toMillis(1))  
builder.setOverrideDeadline(deadline.toLong() * TimeUnit.SECONDS.toMillis(1))  
builder.setRequiredNetworkType(JobInfo.NETWORK_TYPE_ANY)  
  
builder.run {  
    setRequiresDeviceIdle(requiresIdleCheckbox.isChecked)  
    setRequiresCharging(requiresChargingCheckBox.isChecked)  
    setExtras(extras)  
}  
  
(getSystemService(Context.JOB_SCHEDULER_SERVICE) as JobScheduler).schedule(builder.build())
```

The Job



# Define The Job

DEMO

```
class MyJobService : JobService() {  
    override fun onStartCommand(intent: Intent, flags: Int, startId: Int): Int {  
        activityMessenger = intent.getParcelableExtra(MESSENGER_INTENT_KEY)  
        return Service.START_NOT_STICKY  
    }
```

```
    override fun onStartJob(params: JobParameters): Boolean {  
        // The work that this service "does"  
        // ...  
        // Return true as there's more work to be done with this job.  
        return true  
    }
```

```
    override fun onStopJob(params: JobParameters): Boolean {  
        // Stop tracking these job parameters, as we've 'finished' executing.  
        // ...  
        // Return false to drop the job.  
        return false  
    }  
}
```

# WorkManager

- Core Classes:

- Worker
- WorkRequest

- OneTimeWorkRequest

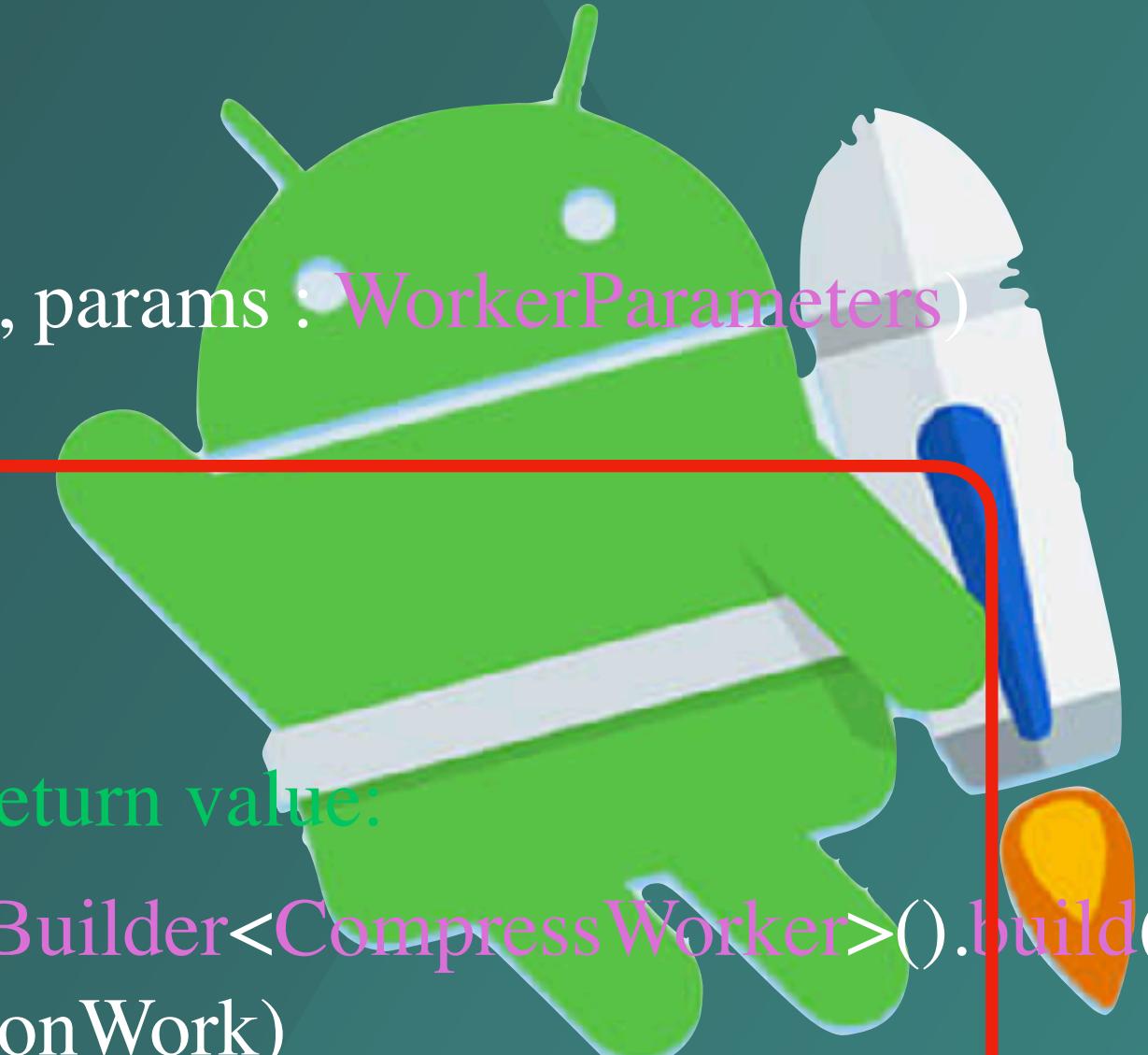
```
class CompressWorker(context : Context, params : WorkerParameters)
    : Worker(context, params) {

    override fun doWork(): Result {
        // The actual work!
        myCompress()
        // Indicate success or failure with your return value:
        return Result.SUCCESS
    }

    val compressionWork = OneTimeWorkRequestBuilder<CompressWorker>()
        .build()

    WorkManager.getInstance().enqueue(compressionWork)
        // - RETRY tells WorkManager to try this task again later
        // - FAILURE says not to try again.

    }
}
```



Runs on a background thread

# Constraints



```
// Create a Constraints object that defines when the task should run
val myConstraints = Constraints.Builder()
    .setRequiresDeviceIdle(true)
    .setRequiresCharging(true)
    // ...
    .build()

// then create a OneTimeWorkRequest that uses those constraints
val compressionWork = OneTimeWorkRequestBuilder<CompressWorker>()
    .setConstraints(myConstraints)
    .build()
```

**Cancel the task**

```
val compressionWorkId:UUID = compressionWork.getId()
WorkManager.getInstance().cancelWorkById(compressionWorkId)
```

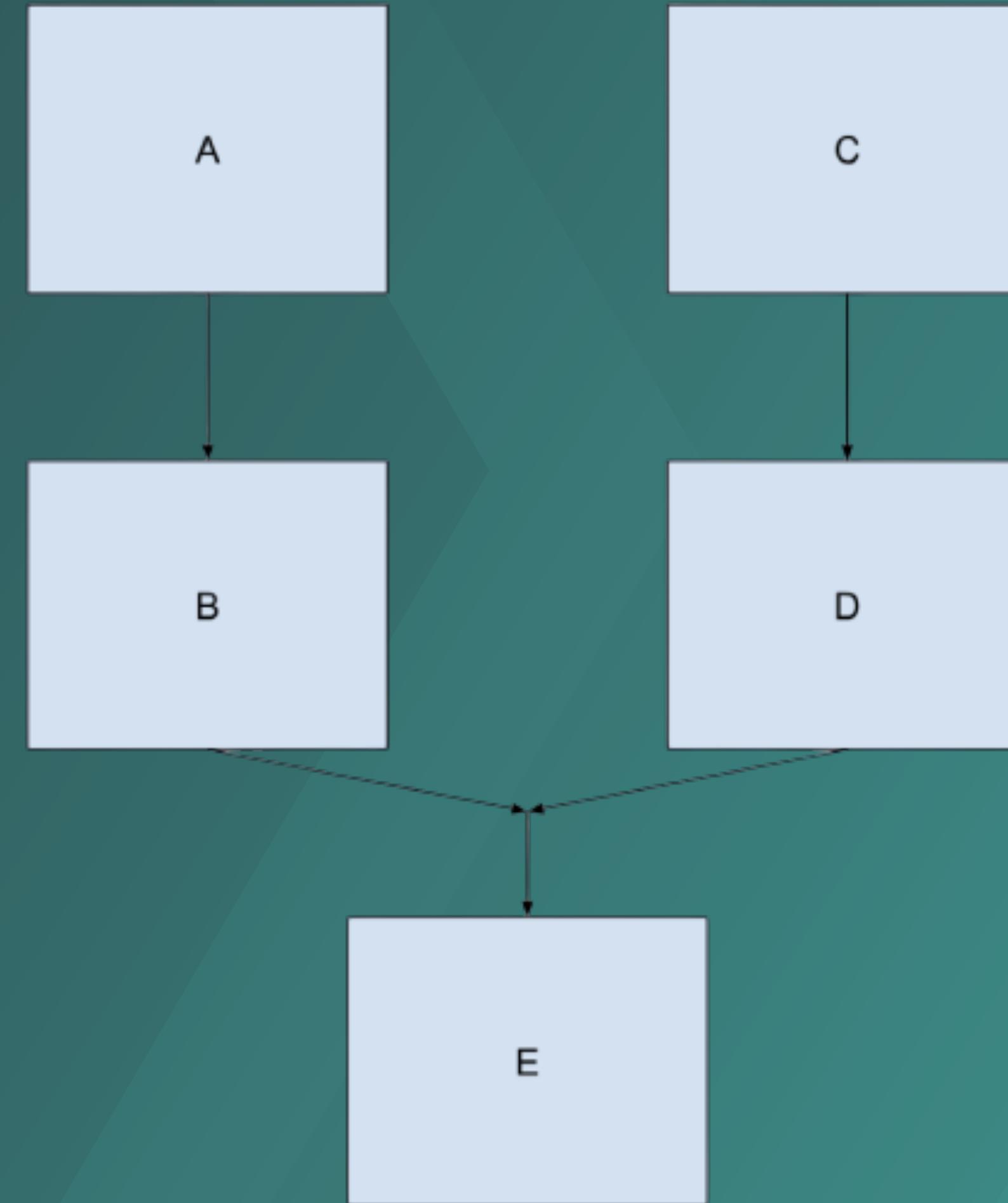
# Chained Tasks

```
WorkManager.getInstance()  
.beginWith(workA)  
  // Note: WorkManager.beginWith() returns a  
  // WorkContinuation object; the following calls are  
  // to WorkContinuation methods  
  WorkManager.getInstance()  
  .then(workB) // FYI, then() returns a new WorkContinuation instance  
  .then(workC)  
  .beginWith(workA1, workA2, workA3)  
  .enqueue()  
  // ...when all A tasks are finished, run the single B task:  
  .then(workB)  
  // ...then run the C tasks (in any order):  
  .then(workC1, workC2)  
  .enqueue()
```

# Chained tasks

DEMO

```
val chain1 = WorkManager.getInstance()  
    .beginWith(workA)  
    .then(workB)  
  
val chain2 = WorkManager.getInstance()  
    .beginWith(workC)  
    .then(workD)  
  
val chain3 = WorkContinuation  
    .combine(chain1, chain2)  
    .then(workE)  
chain3.enqueue()
```



# Sensors

- Motion

The ~~Position~~ sensors measure acceleration forces and rotational forces along three ~~axes~~ axes.

The ~~Environment~~ sensors measure the physical position of a device.

This category includes: various ~~systems~~ This category includes: environmental parameters.

- Accelerometers.

- Orientation sensors.

This category includes:

- Gravity sensors.

- Magnetometers.

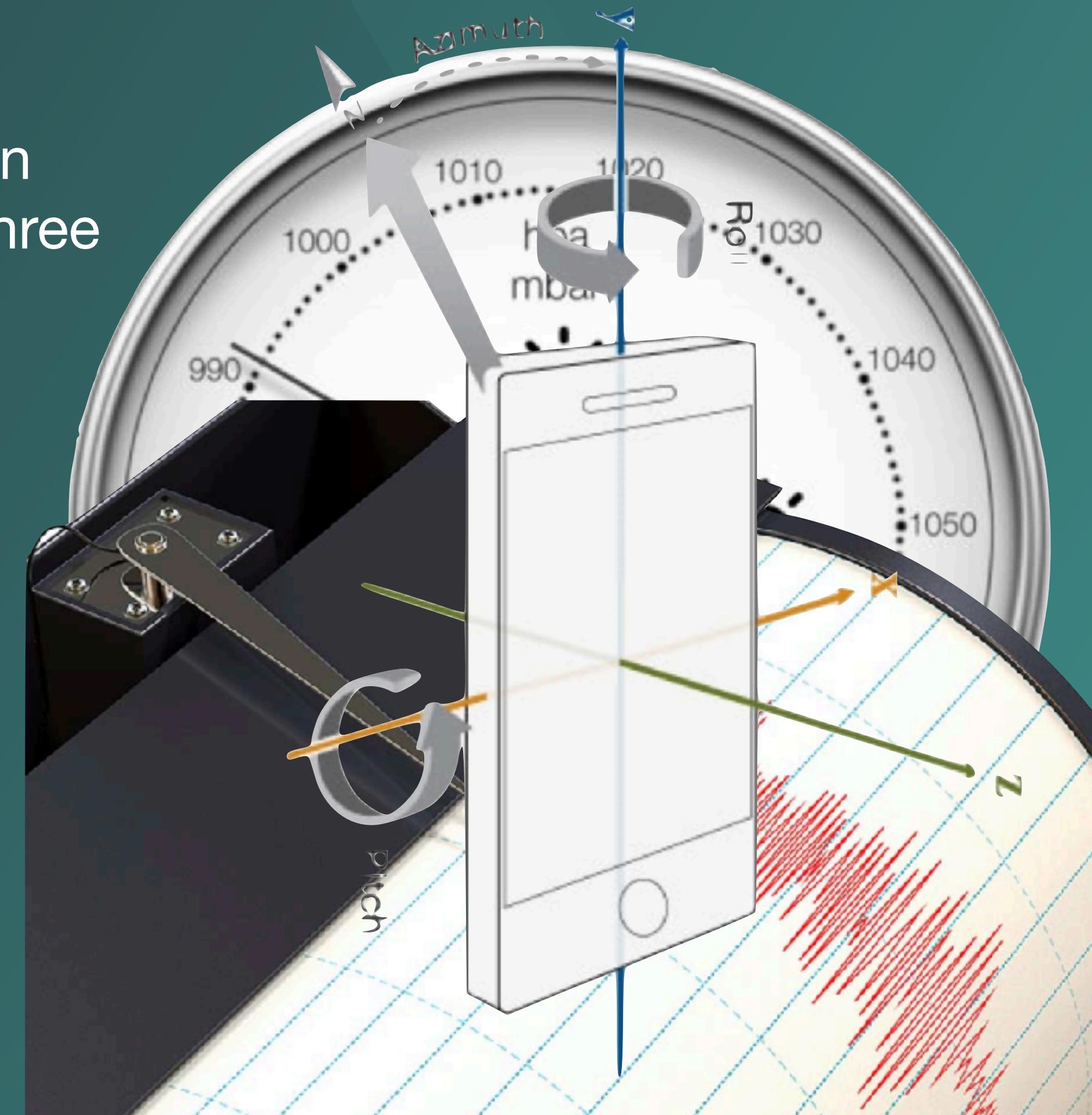
- Barometers.

- Gyroscopes.

- Photometers.

- Rotational vector sensors.

- Thermometers.



# Framework

```
private lateinit var mSensorManager: SensorManager  
    ...  
    mSensorManager = getSystemService(Context.SENSOR_SERVICE) as SensorManager  
    if (mSensorManager.getDefaultSensor(Sensor.TYPE_GRAVITY) != null) {  
        val gravSensors: List<Sensor> = ...  
        mSensorManager = getSystemService(Context.SENSOR_SERVICE) as SensorManager  
        // Esst die Neigungsmagnetometer.  
        val deviceSensors: List<Sensor> = mSensorManager.getSensorList(Sensor.TYPE_ALL)  
        if (deviceSensors.any { it.vendor.contains("Google LLC") && it.version == 3 })  
    }  
  
    class SensorActivity : Activity(), SensorEventListener {  
        private lateinit var mSensorManager: SensorManager  
        private var mLight: Sensor? = null  
        mSensor = if (mSensorManager.getDefaultSensor(Sensor.TYPE_ACCELEROMETER)  
            public null) {  
                mSensorManager.getDefaultSensor(Sensor.TYPE_ACCELEROMETER)  
            } else setContentView(R.layout.main)  
            // Sorry, there are no accelerometers on your device.  
            mSensorManager = getSystemService(Context.SENSOR_SERVICE) as SensorManager  
            mLight = mSensorManager.getDefaultSensor(Sensor.TYPE_LIGHT)  
    }
```

# Motion

Sensor	Sensor event data	Description	Units of measure
TYPE_ACCELEROMETER	<code>SensorEvent.values[0]</code>	Acceleration force along the x axis (including gravity).	$\text{m/s}^2$
	<code>SensorEvent.values[1]</code>	Acceleration force along the y axis (including gravity).	
	<code>SensorEvent.values[2]</code>	Acceleration force along the z axis (including gravity).	
TYPE_ACCELEROMETER_UNCALIBRATED	<code>SensorEvent.values[0]</code>	Measured acceleration along the X axis without any bias compensation.	$\text{m/s}^2$
	<code>SensorEvent.values[1]</code>	Measured acceleration along the Y axis without any bias compensation.	
	<code>SensorEvent.values[2]</code>	Measured acceleration along the Z axis without any bias compensation.	
	<code>SensorEvent.values[3]</code>	Measured acceleration along the X axis with estimated bias compensation.	
	<code>SensorEvent.values[4]</code>	Measured acceleration along the Y axis with estimated bias compensation.	
	<code>SensorEvent.values[5]</code>	Measured acceleration along the Z axis with estimated bias compensation.	

# Position

Sensor	Sensor event data	Description	Units of measure
TYPE_GAME_ROTATION_VECTOR	SensorEvent. values[0]	Rotation vector component along the x axis $(x * \sin(\theta/2))$ .	Unitless
	SensorEvent. values[1]	Rotation vector component along the y axis $(y * \sin(\theta/2))$ .	
	SensorEvent. values[2]	Rotation vector component along the z axis $(z * \sin(\theta/2))$ .	
TYPE_GEOMAGNETIC_ROTATION_VECTOR	SensorEvent. values[0]	Rotation vector component along the x axis $(x * \sin(\theta/2))$ .	Unitless
	SensorEvent. values[1]	Rotation vector component along the y axis $(y * \sin(\theta/2))$ .	
	SensorEvent. values[2]	Rotation vector component along the z axis $(z * \sin(\theta/2))$ .	
TYPE_MAGNETIC_FIELD	SensorEvent. values[0]	Geomagnetic field strength along the x axis.	µT
	SensorEvent. values[1]	Geomagnetic field strength along the y axis.	
	SensorEvent. values[2]	Geomagnetic field strength along the z axis.	
TYPE_MAGNETIC_FIELD_UNCALIBRATED	SensorEvent.	Geomagnetic field strength (without hard	µT

# Environment

DEMO

Sensor	Sensor event data	Units of measure	Data description
TYPE_AMBIENT_TEMPERATURE	event.values[0]	°C	Ambient air temperature.
TYPE_LIGHT	event.values[0]	lx	Illuminance.
TYPE_PRESSURE	event.values[0]	hPa or mbar	Ambient air pressure.
TYPE_RELATIVE_HUMIDITY	event.values[0]	%	Ambient relative humidity.
TYPE_TEMPERATURE	event.values[0]	°C	Device temperature. <sup>1</sup>

 <sup>1</sup> Implementations vary from device to device. This sensor was deprecated in Android 4.0 (API Level 14).

# Lecture outcomes

- Use existing system services.
- Define custom services.
- Understand the user notifications API.
- Consume data from sensors.

