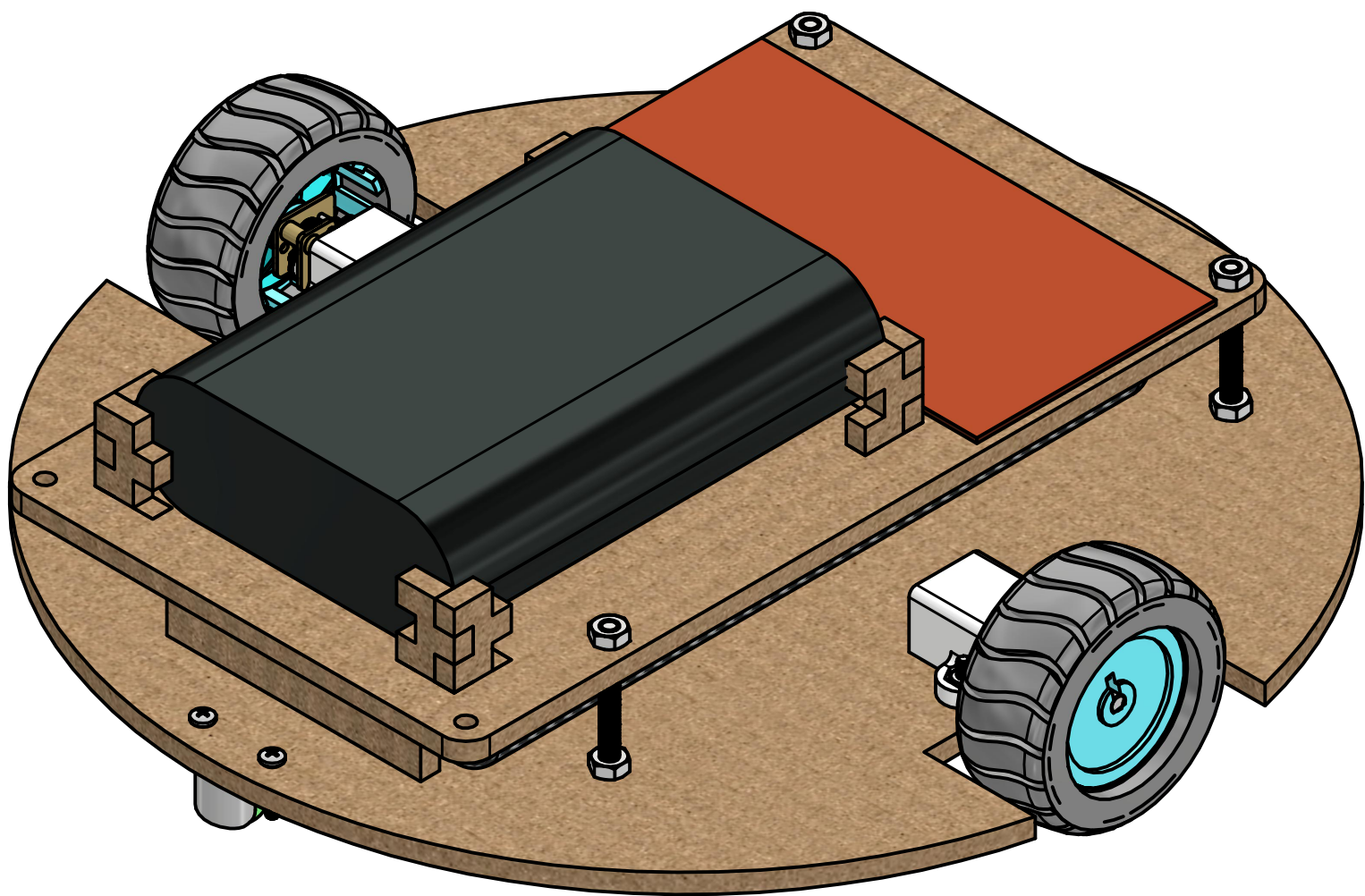


# LAB 05 - ROBÓTICA INDUSTRIAL

2024-2



## ROBOT MÓVIL DE TRACCIÓN DIFERENCIAL

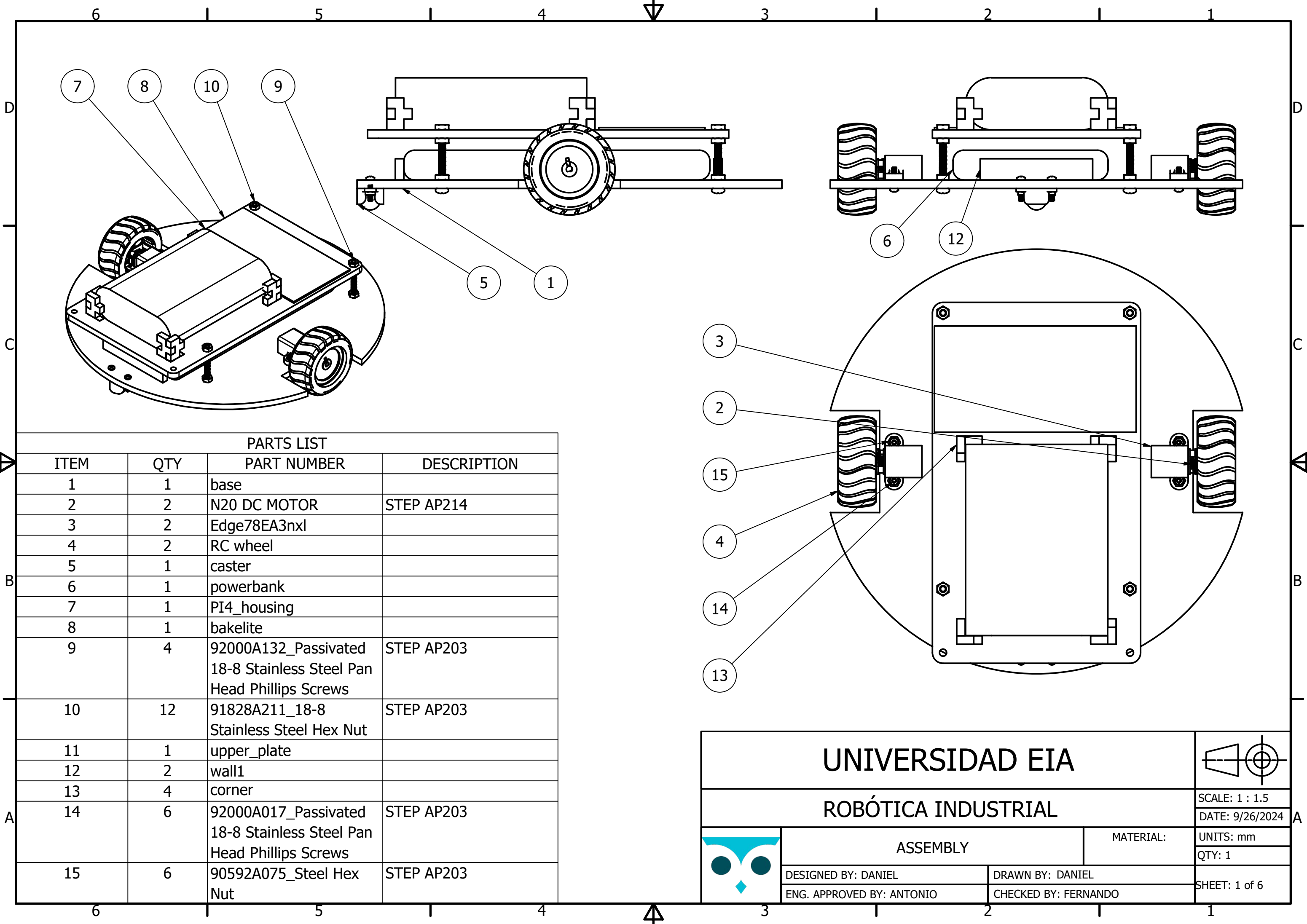
ANTONIO COCK

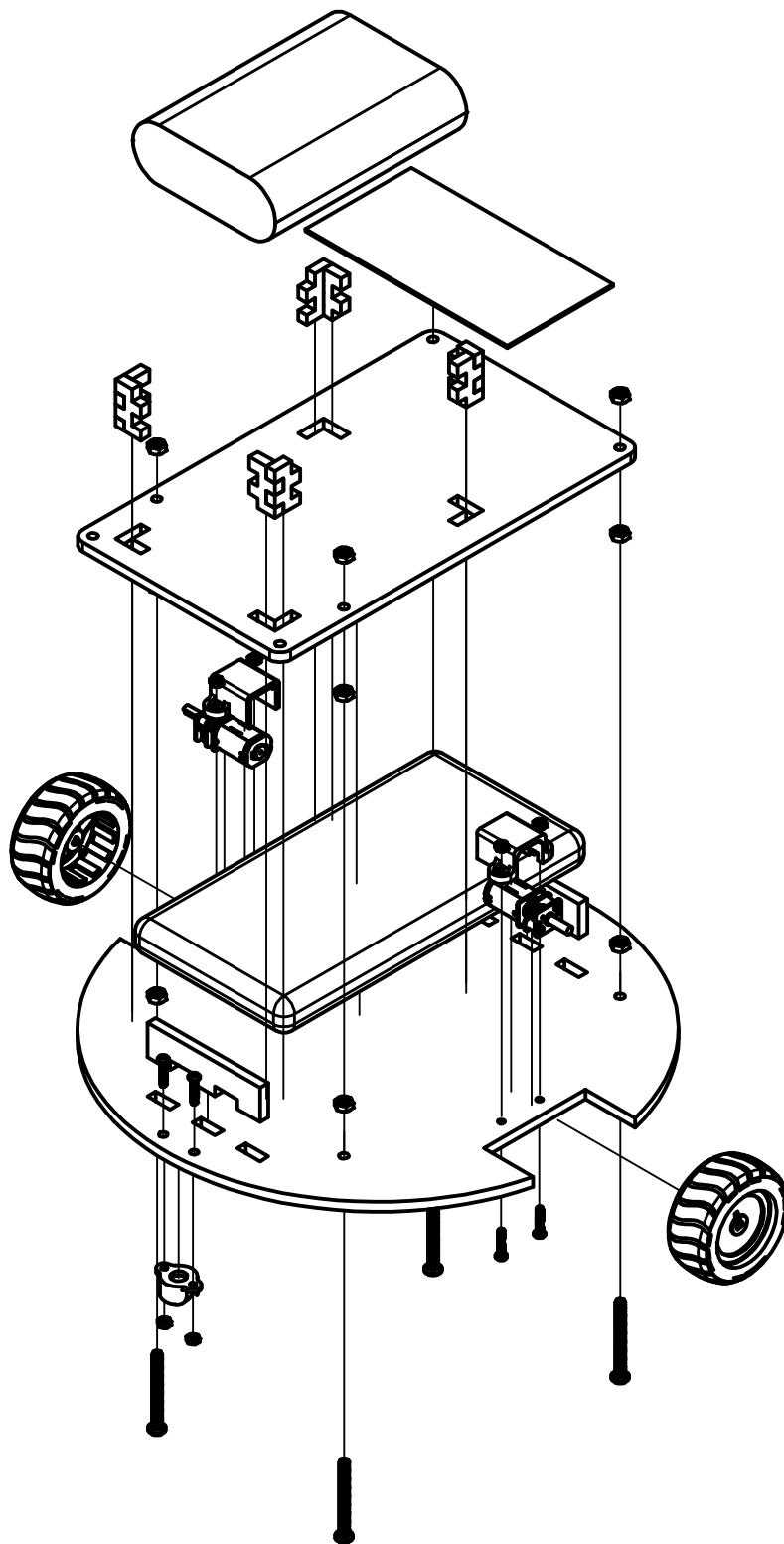
DANIEL CORREA

FERNANDO VELILLA

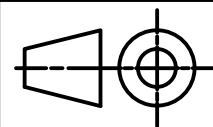
TOMÁS VÉLEZ

RAÚL VILLAMIL





UNIVERSIDAD EIA



ROBÓTICA INDUSTRIAL

SCALE: 1:2.5

DATE: 9/26/2024



ASSEMBLY

MATERIAL:

UNITS: mm

QTY: 1

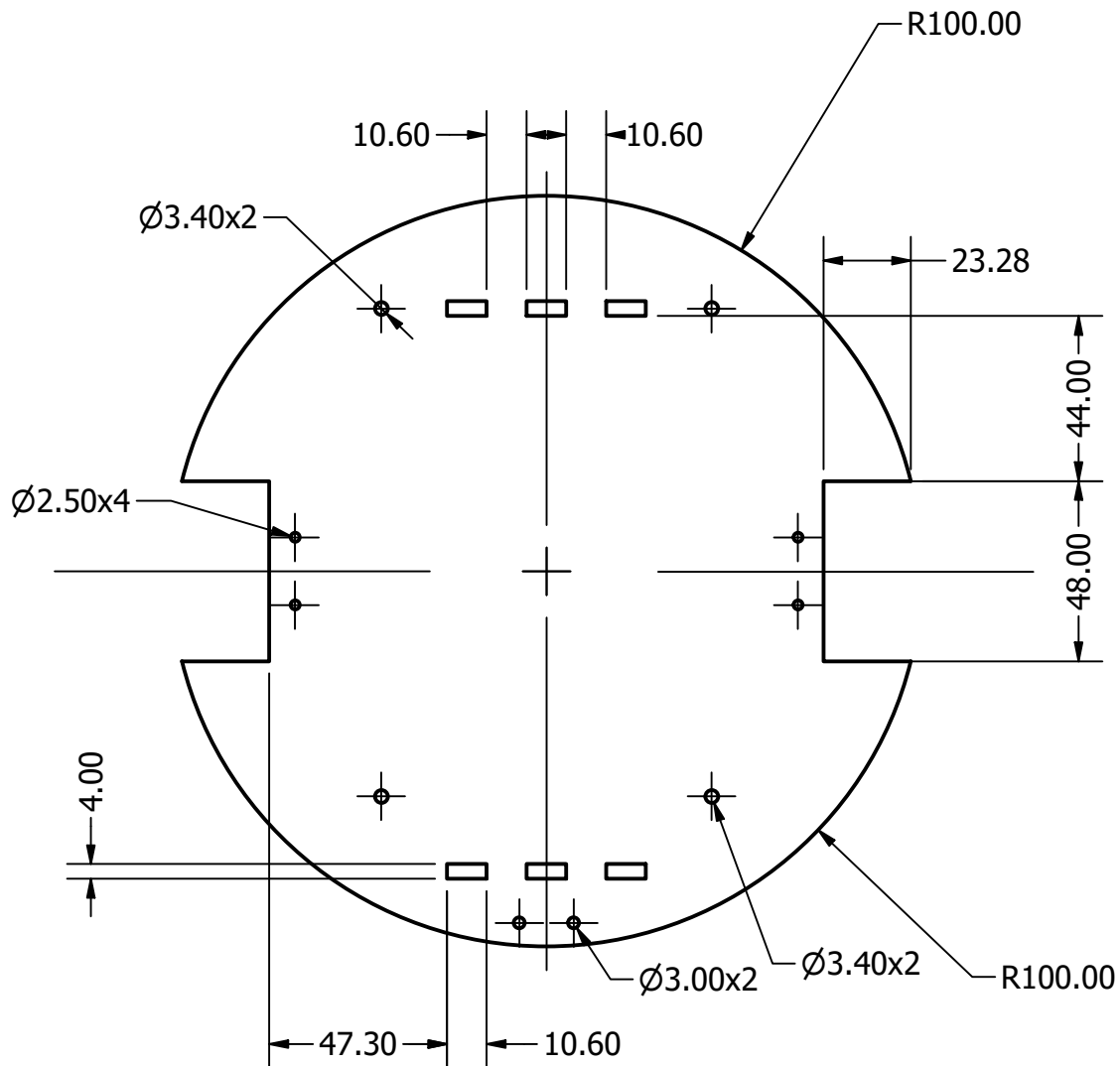
DESIGNED BY: DANIEL

DRAWN BY: DANIEL

ENG. APPROVED BY: ANTONIO

CHECKED BY: FERNANDO

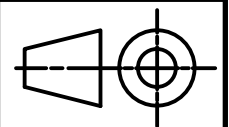
SHEET: 2 of 6



GROSOR DE LA LAMINA: 4mm

METODO DE MANUFACTURA: CORTE LASER

UNIVERSIDAD EIA



ROBÓTICA INDUSTRIAL

SCALE: 1 / 2

DATE: 9/26/2024



BASE

MATERIAL:  
MDF Medium Density  
Fiberboard

UNITS: mm

QTY: 1

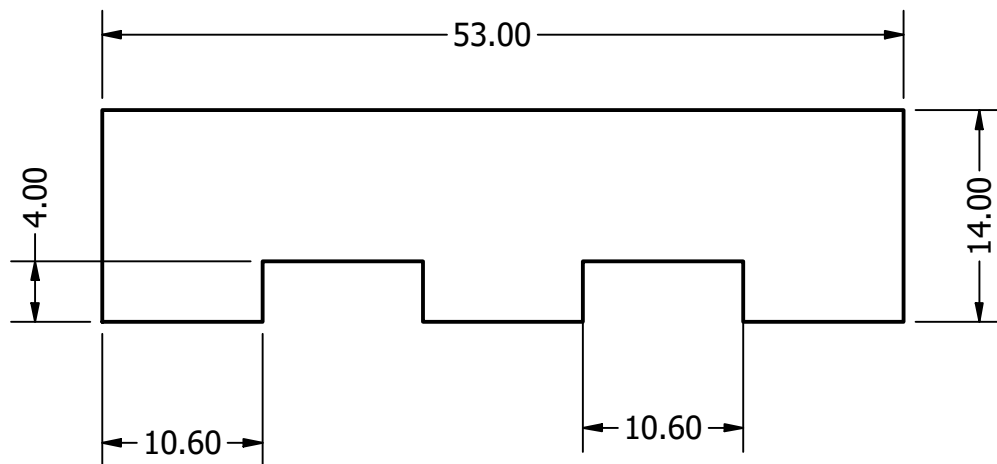
DESIGNED BY: FERNANDO

DRAWN BY: FERNANDO

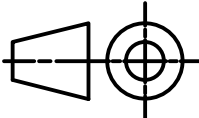

ENG. APPROVED BY: ANTONIO

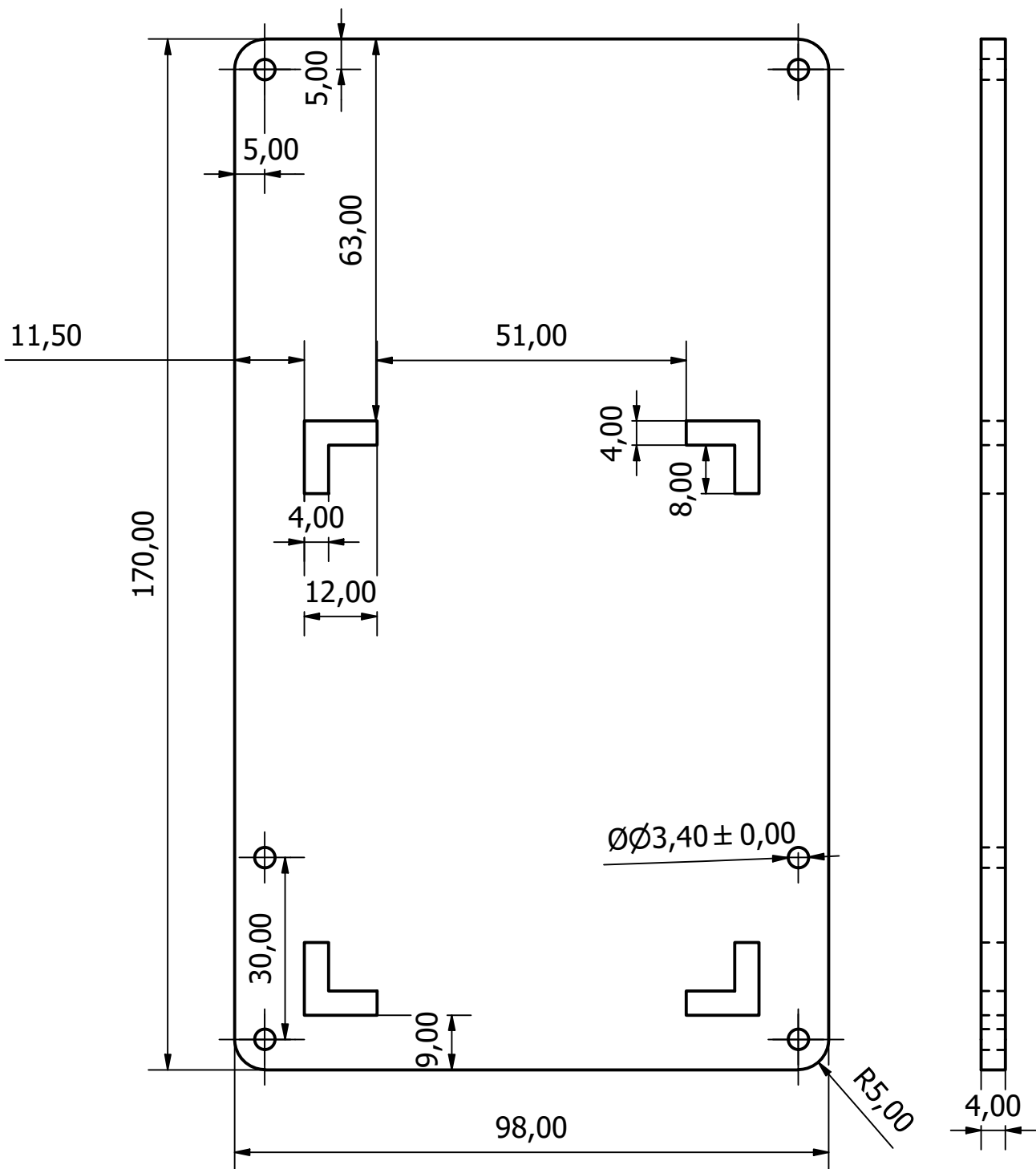
CHECKED BY: DANIEL

SHEET: 3 of 6



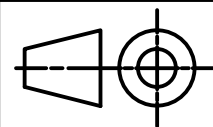
GROSOR DE LA LAMINA: 4mm  
 METODO DE MANUFACTURA: CORTE LASER

UNIVERSIDAD EIA				
ROBÓTICA INDUSTRIAL				SCALE: 2 : 1
				DATE: 9/26/2024
	WALL 1		MATERIAL: MDF Medium Density Fiberboard	UNITS: mm
				QTY: 2
	DESIGNED BY: FERNANDO	DRAWN BY: FERNANDO		SHEET: 4 of 6
	ENG. APPROVED BY:	CHECKED BY: TOMAS		



METODO DE MANUFACTURA: CORTE LASER

UNIVERSIDAD EIA



ROBÓTICA INDUSTRIAL

SCALE: 1 : 1

DATE: 9/26/2024



UPPER PLATE

MATERIAL:  
MDF Medium Density  
Fiberboard

UNITS: mm

QTY: 1

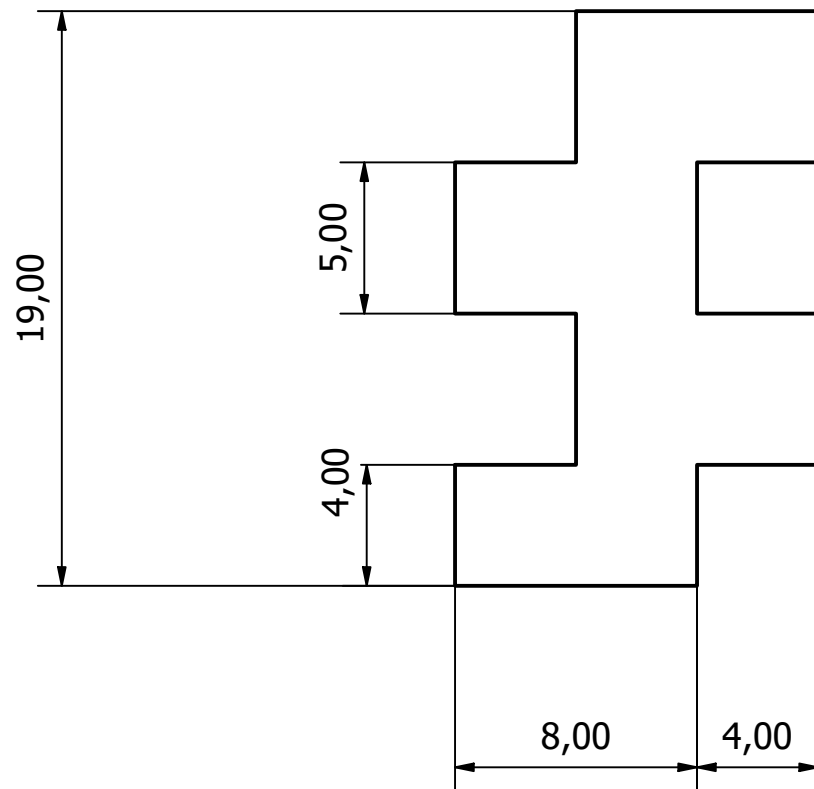
DESIGNED BY: TOMÁS

DRAWN BY: TOMÁS

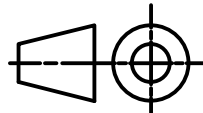

ENG. APPROVED BY: DANIEL

CHECKED BY: DANIEL

SHEET: 5 of 6



METODO DE MANUFACTURA: CORTE LASER

UNIVERSIDAD EIA						
ROBÓTICA INDUSTRIAL				SCALE: 4 : 1		
				DATE: 9/26/2024		
	WALL 2			MATERIAL: MDF Medium Density Fiberboard		UNITS: mm
	DESIGNED BY: TOMÁS			DRAWN BY: TOMÁS		QTY: 8
	ENG. APPROVED BY: DANIEL			CHECKED BY: DANIEL		SHEET: 6 of 6