Applied Machine Learning

- Translation and rotations
- Dimensionality reduction
- Error in low-dimensional representation of high-dimensional data

Data Transformation

- Source dataset: {x}
- After translation: {m}
 - $\mathbf{m}_i = \mathbf{x}_i mean(\{\mathbf{x}\})$
- And, after rotation: $\{r\}$
 - Covmat $\{\mathbf{r}\} = U^{\mathsf{T}} \Sigma U = \Lambda$
 - $\mathbf{r}_i = U^{\mathsf{T}} \mathbf{m}_i = U^{\mathsf{T}} (\mathbf{x}_i \text{mean}(\{x\}))$
 - $mean(\{\mathbf{r}\}) = mean(\{\mathbf{m}\}) = 0$

- Eigenvectors U and eigenvalues Λ of S
 - $SU = U\Lambda$
- Diagonalization

•
$$U^{\mathsf{T}}SU = \Lambda$$

•
$$A = U^{\mathsf{T}}$$

• Covmat $\{\mathbf{x}\} = \Sigma = S$

Selection of Features

- Eigenvalues in Λ
 - sorted from largest to smallest
 - the larger the component, the larger the weight for the corresponding feature
- New dataset {p}
 - Select s largest components in Λ and corresponding eigenvectors in U
 - Replace remaining d s components with 0

Error in New Dataset

•
$$\frac{1}{N} \sum_{i} \left[(\mathbf{r}_{i} - \mathbf{p}_{i})^{\mathsf{T}} (\mathbf{r}_{i} - \mathbf{p}_{i}) \right]$$

$$= \frac{1}{N} \sum_{i} \left[\sum_{j=s+1}^{j=d} (r_i^{(j)})^2 \right]$$

$$= \sum_{j=s+1}^{j=d} \left[\frac{1}{N} \sum_{i} (r_i^{(j)})^2 \right]$$

$$= \sum_{j=s+1}^{j=d} var(\{r^{(j)}\})$$

$$\sum_{j=s+1}^{j=d} \lambda_j$$

Relative error

$$\frac{\sum_{j=s+1}^{j=d} \lambda_j}{\sum_{j=1}^{j=d} \lambda_j} \text{ should be small }$$

Inverse Transformation

• Lower dimensional dataset $\{\hat{\mathbf{x}}\}$

$$\hat{\mathbf{x}}_i = U\mathbf{p}_i + mean(\{\mathbf{x}\})$$

- $= \sum_{j=1}^{j=s} r_i^{(j)} \mathbf{u}_j + mean(\{\mathbf{x}\})$
 - $\mathbf{r}_i = U^{\mathsf{T}}(\mathbf{x}_i \mathsf{mean}(\{x\}))$
 - $r_i^{(j)} = \mathbf{u}_j^{\mathsf{T}}(\mathbf{x}_i \mathsf{mean}(\{x\}))$
- $\hat{\mathbf{x}}_i = \sum_{j=1}^{j=s} \left[\mathbf{u}_j^{\mathsf{T}} (\mathbf{x}_i \mathsf{mean}(\{x\})) \mathbf{u}_j \right] + mean(\{x\})$
- Mean error

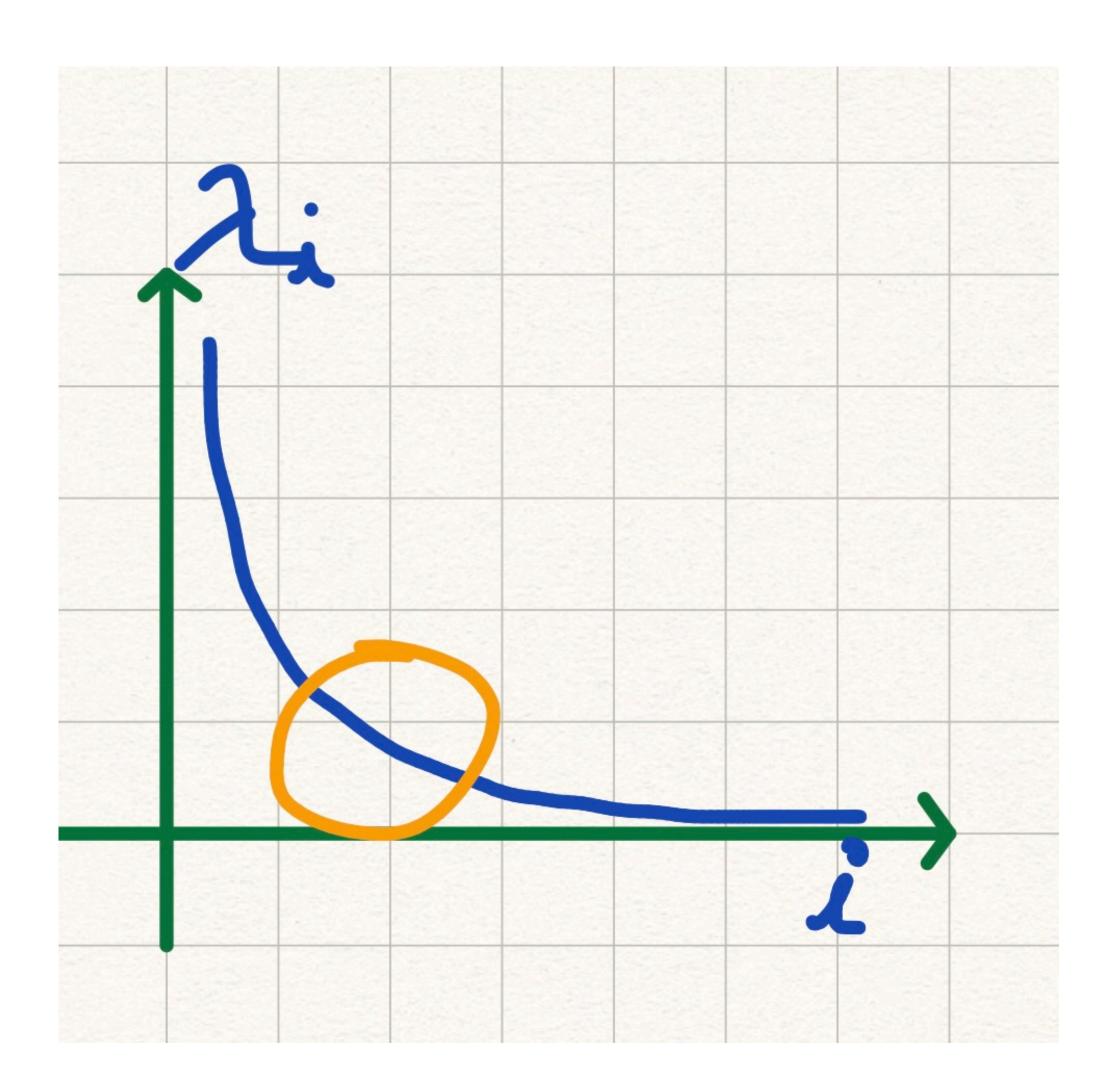
$$\sum_{j=s+1}^{j=d} \lambda_j$$

- Original dataset: {x}
 - *d* features
 - $U^{\mathsf{T}}\mathsf{Covmat}\{\mathbf{x}\}U = U^{\mathsf{T}}\Sigma U = \Lambda$
- Choose s features

small ratio in
$$\frac{\sum_{j=s+1}^{j=d} \lambda_j}{\sum_{j=1}^{j=d} \lambda_j}$$

- plot relative error vs s or λ_i vs i, select s most significant
- Low-Dimensional representation $\hat{\mathbf{x}}$:

$$\hat{\mathbf{x}}_i = \sum_{j=1}^{j=s} \left[\mathbf{u}_j^{\mathsf{T}} (\mathbf{x}_i - \mathsf{mean}(\{x\})) \mathbf{u}_j \right] + mean(\{x\})$$



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