



IN4310 Linear Algebra Review

✉ ali@uio.no



Who Is Your Instructor?

Research Agenda: Machine Learning in Real World

Associate Professor, Department of Informatics, University of Oslo

Principal Investigator, Norwegian Centre for Excellence Integreat

Principal Investigator, SFI Visual Intelligence

<https://alirk.github.io/>



UNIVERSITY
OF OSLO

Norwegian Centre for Knowledge-driven Machine
Learning



What Is This Course About?

Algorithms, Practice, Theory, Major Issues of Deep Learning

Main Application: Image Data

Not a Pure Programming and Math/Stats Course

Useful Tools for Industry/Academic Career

Everything on Course Web Page and Mattermost

Mandatory one: Post on Feb. 28th (deadline in two weeks)

Mandatory two: Post on Apr. 4th (deadline in two weeks)

$$\begin{bmatrix} 1 & 2 & 3 \\ a & b & c \end{bmatrix}$$

Notation

$A \in \mathbb{R}^{m \times n}$ matrix with m rows and n columns with real entries

$\mathbf{x} \in \mathbb{R}^n$ n -dimensional column vector

\mathbf{x}^\top the transpose of \mathbf{x} (row vector)

$\mathbf{a}_j \in \mathbb{R}^m$ or $A_{:,j} \in \mathbb{R}^m$ j -th column of A

$$A = [\mathbf{a}_1 \ \mathbf{a}_2 \ \cdots \ \mathbf{a}_n]$$

$$A = \begin{bmatrix} \mathbf{b}_1^\top \\ \vdots \\ \mathbf{b}_m^\top \end{bmatrix}$$

Vector-Vector Products and Matrix-Vector Products

Let $\mathbf{x}, \mathbf{y} \in \mathbb{R}^n$ and $A \in \mathbb{R}^{m \times n}$

Inner product or dot product $\mathbf{x}^\top \mathbf{y} = \sum_{i=1}^n x_i y_i$

Outer product $\mathbf{xy}^\top = \begin{bmatrix} x_1 y_1 & x_1 y_2 & \cdots & x_1 y_n \\ x_2 y_1 & x_2 y_2 & \cdots & x_2 y_n \\ \vdots & \vdots & \ddots & \vdots \\ x_n y_1 & x_n y_2 & \cdots & x_n y_n \end{bmatrix}$

Writing A by rows $\mathbf{y} = A\mathbf{x} = \begin{bmatrix} \mathbf{b}_1^\top \\ \vdots \\ \mathbf{b}_m^\top \end{bmatrix} \mathbf{x} = \begin{bmatrix} \mathbf{b}_1^\top \mathbf{x} \\ \vdots \\ \mathbf{b}_m^\top \mathbf{x} \end{bmatrix}$

Writing A by columns $\mathbf{y} = A\mathbf{x} = [\mathbf{a}_1 \ \mathbf{a}_2 \ \cdots \ \mathbf{a}_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n \mathbf{a}_i x_i$

Transpose, Symmetric Matrices, and Trace [1]

Transpose of $A \in \mathbb{R}^{m \times n}$ denoted by $A^\top \in \mathbb{R}^{n \times m}$ $(A^\top)_{ij} = A_{ji}$

$$(A^\top)^\top = A; \quad (AB)^\top = B^\top A^\top; \quad (A + B)^\top = A^\top + B^\top$$

Square matrix $A \in \mathbb{R}^{n \times n}$ is symmetric if $A = A^\top$

Trace of a square matrix $\text{tr}(A) = \sum_{i=1}^n A_{ii}$

$$\text{tr}(A) = \text{tr}(A^\top); \quad \text{tr}(A + B) = \text{tr}(A) + \text{tr}(B); \quad \text{tr}(AB) = \text{tr}(BA)$$

$$\text{tr}(ABC) = \text{tr}(BCA) = \text{tr}(CAB)$$

Informally a measure of the length of a vector

Euclidean or ℓ_2 norm $\|\mathbf{x}\|_2 = \sqrt{\sum_{i=1}^n x_i^2}$

$$\|\mathbf{x}\|_2^2 = \mathbf{x}^\top \mathbf{x}$$

ℓ_1 norm $\|\mathbf{x}\|_1 = \sum_{i=1}^n |x_i|$

ℓ_∞ norm $\|\mathbf{x}\|_\infty = \max_i |x_i|$

ℓ_p norm for some $p \geq 1$ $\|\mathbf{x}\|_p = \left(\sum_{i=1}^n |x_i|^p \right)^{1/p}$

Frobenius norm $\|A\|_F = \sqrt{\sum_{i=1}^m \sum_{j=1}^n A_{ij}^2} = \sqrt{\text{tr}(A^\top A)}$

Quadratic Forms and Positive Semidefinite Matrices

Let $A \in \mathbb{R}^{n \times n}$ and $\mathbf{x} \in \mathbb{R}^n$. The scalar $\mathbf{x}^\top A \mathbf{x}$ is **quadratic form**

$$\mathbf{x}^\top A \mathbf{x} = \sum_{i=1}^n \sum_{j=1}^n x_i A_{ij} x_j$$

$$\mathbf{x}^\top A \mathbf{x} = (\mathbf{x}^\top A \mathbf{x})^\top = \mathbf{x}^\top A^\top \mathbf{x} = \mathbf{x}^\top \left(\frac{1}{2} A + \frac{1}{2} A^\top \right) \mathbf{x}$$

A symmetric A is **positive definite** if for all non-zero \mathbf{x} , $\mathbf{x}^\top A \mathbf{x} > 0$

A is **positive semidefinite** if for all non-zero \mathbf{x} , $\mathbf{x}^\top A \mathbf{x} \geq 0$ ($A \succeq 0$)

A is **negative definite** if for all non-zero \mathbf{x} , $\mathbf{x}^\top A \mathbf{x} < 0$

A is **negative semidefinite** if for all non-zero \mathbf{x} , $\mathbf{x}^\top A \mathbf{x} \leq 0$ ($A \preceq 0$)

A is **indefinite** if it is neither PSD nor NSD

Eigenvalues and Eigenvectors

Given $A \in \mathbb{R}^{n \times n}$, $\lambda \in \mathbb{C}$ is an **eigenvalue** of A with corresponding **non-zero eigenvector** $\mathbf{x} \in \mathbb{C}^n$ if $A\mathbf{x} = \lambda\mathbf{x}$

(λ, \mathbf{x}) is an eigenvalue-eigenvector pair if $(\lambda\mathbf{I} - A)\mathbf{x} = 0$, $\mathbf{x} \neq 0$

$(\lambda\mathbf{I} - A)\mathbf{x} = 0$ has non-zero solution iff $\lambda\mathbf{I} - A$ is singular

$$\det(\lambda\mathbf{I} - A) = 0$$

Trace equals sum of eigenvalues $\text{tr}(A) = \sum_{i=1}^n \text{eig}(A) = \sum_{i=1}^n \lambda_i$

Determinant equals product of eigenvalues $\det(A) = \prod_{i=1}^n \lambda_i$

Matrix Calculus: Gradient

$g : \mathbb{R}^{m \times n} \rightarrow \mathbb{R}$ takes an $m \times n$ matrix input and returns a real value

The **gradient** of g w.r.t. A is a matrix of partial derivatives

$$\nabla_A g(A) = \begin{bmatrix} \frac{\partial g(A)}{\partial A_{11}} & \frac{\partial g(A)}{\partial A_{12}} & \cdots & \frac{\partial g(A)}{\partial A_{1n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial g(A)}{\partial A_{m1}} & \frac{\partial g(A)}{\partial A_{m2}} & \cdots & \frac{\partial g(A)}{\partial A_{mn}} \end{bmatrix}$$

$f : \mathbb{R}^n \rightarrow \mathbb{R}$ takes an n -dimensional vector input

$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \begin{bmatrix} \frac{\partial f(\mathbf{x})}{\partial x_1} \\ \vdots \\ \frac{\partial f(\mathbf{x})}{\partial x_n} \end{bmatrix}$$

Matrix Calculus: Hessian

$f : \mathbb{R}^n \rightarrow \mathbb{R}$ takes a vector input and returns a real scalar

The **Hessian** matrix w.r.t. \mathbf{x} is $n \times n$ matrix of partial derivatives

$$\nabla_{\mathbf{x}}^2 f(\mathbf{x}) = \begin{bmatrix} \frac{\partial^2 f(\mathbf{x})}{\partial x_1^2} & \frac{\partial^2 f(\mathbf{x})}{\partial x_1 \partial x_2} & \cdots & \frac{\partial^2 f(\mathbf{x})}{\partial x_1 \partial x_n} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial^2 f(\mathbf{x})}{\partial x_n \partial x_1} & \frac{\partial^2 f(\mathbf{x})}{\partial x_n \partial x_2} & \cdots & \frac{\partial^2 f(\mathbf{x})}{\partial x_n^2} \end{bmatrix}$$

$$(\nabla_{\mathbf{x}}^2 f(\mathbf{x}))_{ij} = \frac{\partial^2 f(\mathbf{x})}{\partial x_i \partial x_j}$$

Exercise: Suppose $f(\mathbf{x}) = \mathbf{x}^\top A \mathbf{x}$. Then show

$$\nabla_{\mathbf{x}} \mathbf{x}^\top A \mathbf{x} = 2A\mathbf{x}, \quad \nabla_{\mathbf{x}}^2 \mathbf{x}^\top A \mathbf{x} = 2A$$

Hint: Show $\frac{\partial f(\mathbf{x})}{\partial x_i} = 2 \sum_{j=1}^n A_{ij} x_j$ and $\frac{\partial^2 f(\mathbf{x})}{\partial x_i \partial x_j} = 2A_{ij}$

- [1] Z. Kolter and C. Do. Linear algebra review. <https://cs229.stanford.edu/section/cs229-linalg.pdf>.