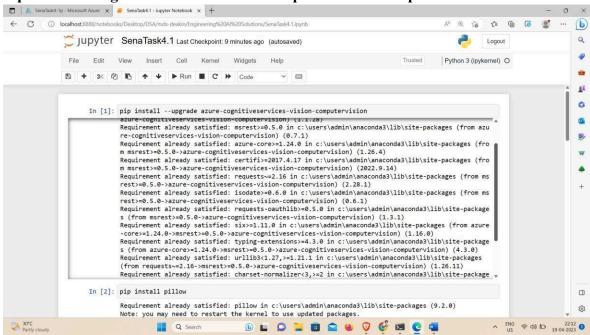
For this task you need to develop a program to detect different objects in images with their rectangles coordinates. To do this task, use the computer vision SDK to detect different objects on Azure. It is recommended to follow the instruction on slides seminar and lecture recording for week 4.

### Submit the following files on Olympus:

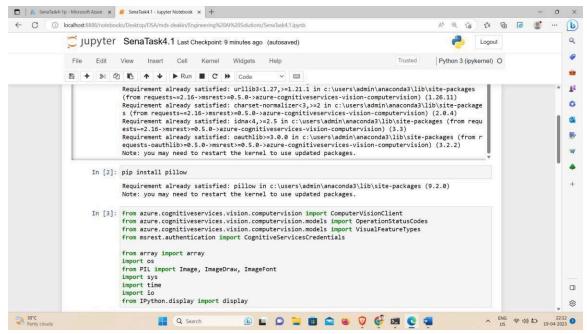
- Submit your answers as a PDF file. You need to answer the following parts in your document.
- Please explain cell by cell of your code from reading a local image to object detection, drawing a bounding box around different objects. To complete this task, you need to provide the screenshot of your code and explain cell by cell of the code and explain what sort of API is being used.

#### **Solution:**

Step 1: Install cognitive services-vision-computer vision and pillow

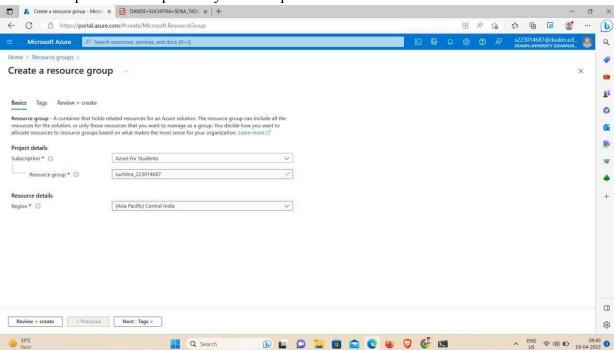


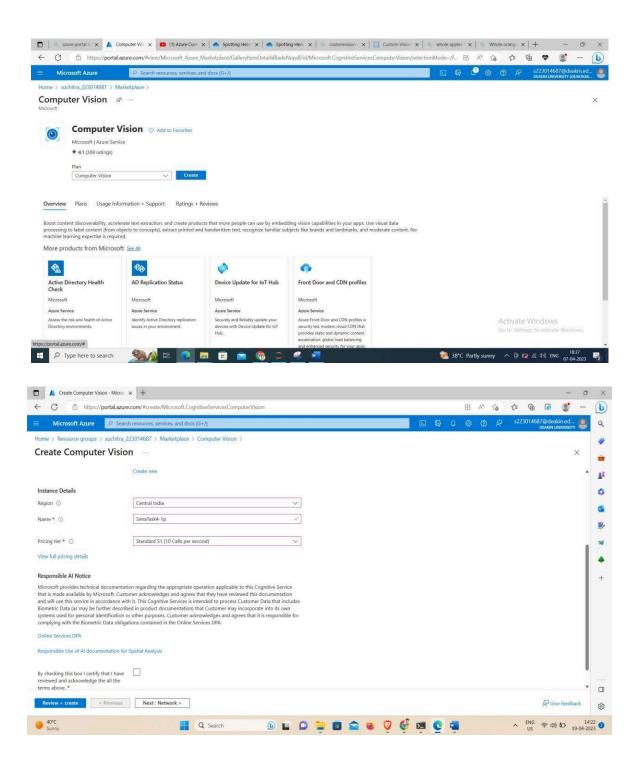
**Step 2: Import Libraries** 

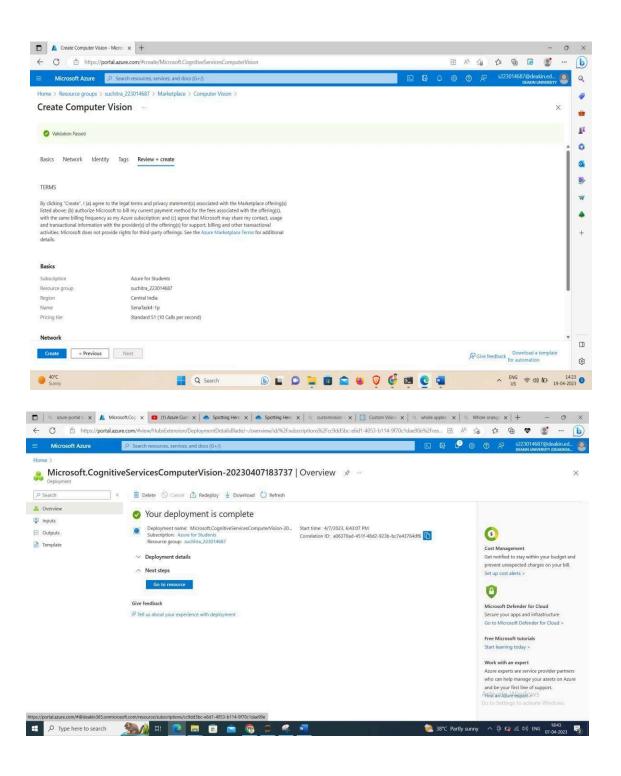


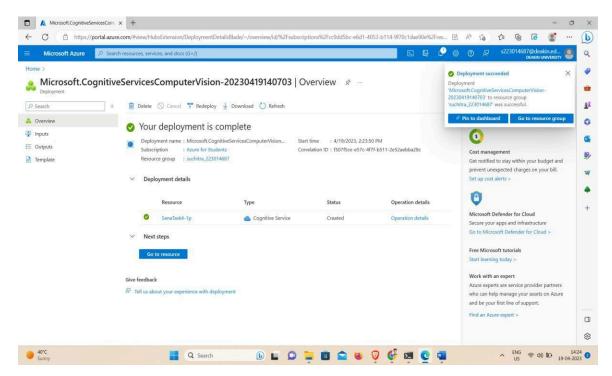
Step3: In the azure portal create a resource group "Suchitra\_223014687" and create computer vision as shown in below screenshots [1].

Add subscription and endpoint keys of Computer Vision

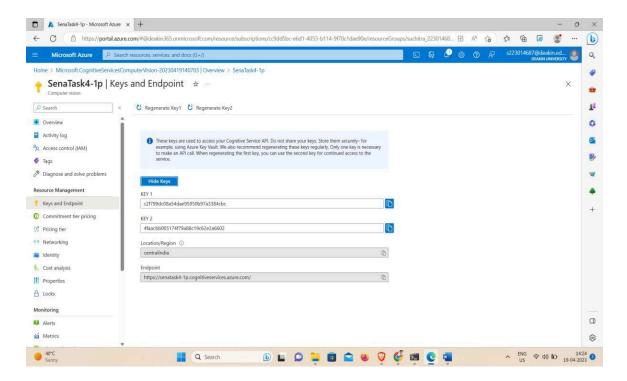








Created SenaTask4-1 resource and see for the keys and Endpoint [1].



**Step 4: Capture the Local Image** 

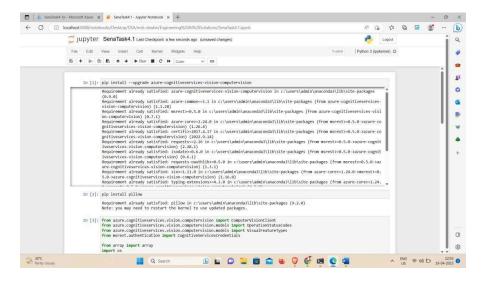
The input image is available at <a href="https://www.colourbox.com/image/handsome-man-standing-near-his-new-car-image-2639638">https://www.colourbox.com/image/handsome-man-standing-near-his-new-car-image-2639638</a>, which is the InputURL for detecting objects [2].



# **Step 5: Object Detection for the Above Image**

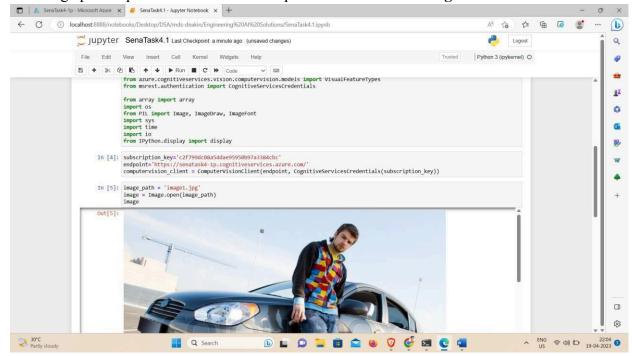
The Python Code in Jupyter Notebook is attached.

1. Firstly, installed necessary packages – azure-cognitiveservices-vision-computervision, pillow and imported necessary libraries [3].



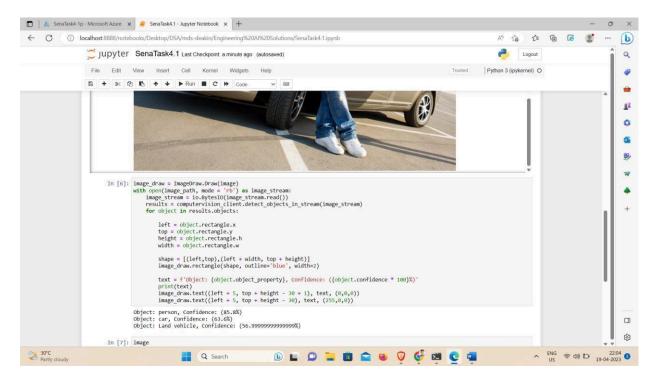
Opening the image which is saved as 'image1.jpg' and displaying it as output.

The image path is provided which is then opened and stored in 'image' variable.



# 2. Code to get the detected Images along with Bounding Boxes and Confidence Probability

- The ImageDraw Library is used to draw the image. The file is read from the image path and the image is converted to stream using BytesIO, which is stored in image\_stream variable [4].
- **detect\_objects\_in\_stream** method is used for detecting objects in this stream, which is stored in **results** variable.
- For loop is used to iterate on the objects detected in results variable, to get the object property, object confidence and object bounding box which are printed as text.
- The bounding box parameters -left, top, height and width are adjusted on the draw image using **image\_draw.text()** [4].



## 3. Output:

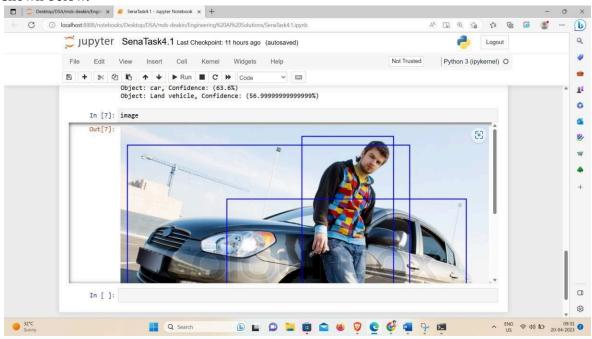
The detected objects are:

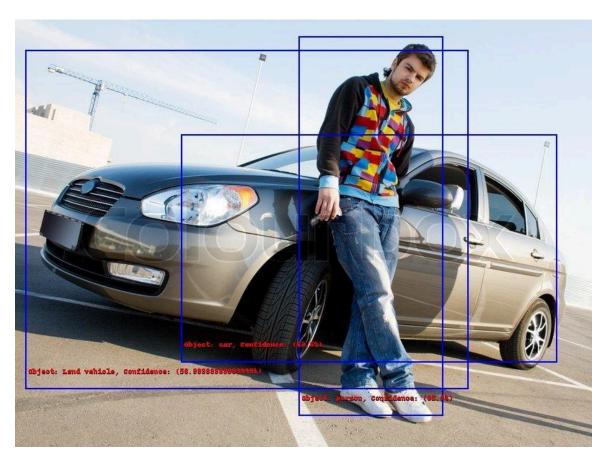
Object: person, Confidence: (85.8%) Object:

car, Confidence: (63.6%)

Object: Land vehicle, Confidence: (56.9999999999999)

The output image along with detected objects, confidence and Bounding box probabilities are shown below.





## **References:**

- [1] George Dolgikh. '*Handsome man standing near his new car. Colourbox*' <a href="https://www.colourbox.com/image/handsome-man-standing-near-his-new-car-image-2639677">https://www.colourbox.com/image/handsome-man-standing-near-his-new-car-image-2639677</a>
- [2] Azure SDK for Python (2.0.0) *Azure Cognitive Services Computer Vision SDK for Python* Computer Vision SDK Documentation <a href="https://azuresdkdocs.blob.core.windows.net/\$web/python/azure-cognitiveservices-vision-computervision/0.7.0/index.html#more-sample-code">https://azuresdkdocs.blob.core.windows.net/\$web/python/azure-cognitiveservices-vision-computervision/0.7.0/index.html#more-sample-code</a>
- [3] CloudCasts Alan Smith (2022) 'Azure Computer Vision using Python', [video], YouTube, accessed 19-April-2023.