18.03SC Unit 2 Exam

1. (a) For what value of k is the system represented by $\ddot{x} + \dot{x} + kx = 0$ critically damped? [8]

(b) For *k* greater than that value, is the system overdamped or underdamped?

[4]

(c) Suppose a solution of $\ddot{x} + \dot{x} + kx = 0$ vanishes at t = 1, and then again for t = 2 (but [8] not in between). What is k?

$$\omega = \frac{2\pi}{2(2-1)} = 17$$

$$17^{2} = \omega^{2} = K - (\frac{1}{2})^{2} = K - \frac{1}{4}$$

$$17^{2} + \frac{1}{4} = K$$

[10]

2. (a) Find a solution of
$$\ddot{x} + x = 5te^{2t}$$
.

Let
$$\chi_p = (At+B)e^{2t}$$

 $\dot{\chi}_p = Ae^{2t} + 2(At+B)e^{2t}$
 $\dot{\chi}_p = 2Ae^{2t} + 2(Ae^{2t} + 2(Ae^{2t})e^{2t})$
 $5te^{2t} = e^{2t}[5At + 4A + 5B]$
 $5A = 5$
 $4A+5B=0$ \longrightarrow $A=1$
 $B=-4/5$
 $\chi_p(t) = (t-4/5)e^{2t}$

(b) Suppose that y(t) is a solution of the same equation, $\ddot{x} + x = 5te^{2t}$, such that y(0) = 1 [10] and $\dot{y}(0) = 2$. (This is probably *not* the solution you found in **(a)**.) Use y(t) and other functions to write down a solution x(t) such that x(0) = 3 and $\dot{x}(0) = 5$.

From (a),
$$\chi_{p}(o) = -4/5$$
, $\dot{\chi}_{p}(o) = -3/5$

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3. (a) Consider the equation $\ddot{x} + b\dot{x} + kx = \cos(\omega t)$. We will vary the spring constant but [10] keep b fixed. For what value of k is the amplitude of the sinusoidal solution of $\ddot{x} + b\dot{x} + kx = \cos(\omega t)$ maximal? (Your answer will be a function of ω and may depend upon b as well.)

Amplitude =
$$\frac{1}{|p(i\omega)|} = \frac{1}{|(i\omega)^2 + b(\omega + K)|}$$

$$= \frac{1}{|k-\omega^2 + ib\omega|}$$

$$= \frac{1}{\sqrt{(k-\omega^2)^2 + b^2\omega^2}}$$
minimize $(k-\omega^2)^2 + b^2\omega^2 = \omega^4 + (b^2 - 2k)\omega^2 + k^2$

$$0 = \frac{d}{dk} \left[\omega^4 + (b^2 - 2k)\omega^2 + k^2 \right] = -2\omega^2 + 2k$$

$$K = \omega^2 \quad \text{maximizes amplitude.}$$

(b) (Unrelated to the above.) Find the general solution of $\frac{d^3x}{dt^3} - \frac{dx}{dt} = 0$. [10]

$$r^{3}-r=0$$

 $r(r^{2}-1)=0$
 $v=0, v=\pm 1$
 $\chi(t)=c_{1}+c_{2}e^{t}+c_{3}e^{-t}$.

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4. A certain system has input signal y and system response x related by the differential equation $\ddot{x} + \dot{x} + 6x = 6y$. It is subjected to a sinusoidal input signal.

(a) Calculate the complex gain
$$H(\omega)$$
.

By linearity and time invariance, we can assume
$$y(t) = cos(\omega t)$$
 and $y_{ex}(t) = e^{i\omega t}$

$$\ddot{z} + \dot{z} + 6z = 6e^{i\omega t}$$

$$\ddot{z}(t) = \frac{6}{(i\omega)^2 + i\omega + 6}e^{i\omega t} = \frac{6}{p(i\omega)}y_{ex}$$

$$H(\omega) = \frac{6}{p(i\omega)} = \frac{6}{i^2\omega^2 + i\omega + 6} = \frac{6}{6-\omega^2 + i\omega}$$

(b) Compute the gain at
$$\omega = 2$$
.

$$H(2) = \frac{6}{2+2i} = \frac{12-12i}{8} = \frac{3}{2} - \frac{3}{2}i$$

(c) Compute the phase lag at
$$\omega = 2$$
.

5. Suppose that $\frac{1}{2}t\sin(2t)$ is a solution to a certain equation $m\ddot{x} + b\dot{x} + kx = 4\cos(2t)$.

(a) Write down a solution to
$$m\ddot{x} + b\dot{x} + kx = 4\cos(2t - 1)$$
. [4]

$$2t \rightarrow 2t - 1$$

$$t \rightarrow t - \frac{1}{2}$$

$$\frac{1}{2} t \sin(2t) \rightarrow \frac{1}{2} (t - \frac{1}{2}) \sin(2t - 1)$$

(b) Write down a solution to
$$m\ddot{x} + b\dot{x} + kx = 8\cos(2t)$$
. [4] $\chi(t) = t \sin(2t)$
By linearity $m\ddot{x} + b\dot{x} + k\chi = 2 \cdot 4 \cos(2t)$.

(c) Determine
$$m, b, \text{ and } k$$
.

$$D = m \left(s - 2i \right) \left(s + 2i \right) = m \left(s^2 + 4 \right)$$

$$b = 0, \quad K = 4m$$

$$M = 2 + b = 2 + k = 4 e^{2it}$$

$$m = 2 + k = 4 e^{2it}$$

$$m = 2 + k = 4 e^{2it}$$

$$m =$$