

5.2 Orthogonalization and Eigenvalue Problems

Notes

Orthonormal vectors

5A The components of b with respect to orthonormal vectors q_i in the equation $c_1q_1 + \dots + c_nq_n = b$ are:

$$c_i = q_i^T b$$

The vector $c_i q_i = q_i q_i^T b$ is the projection of b in the direction of q_i .

5B A square orthogonal matrix Q satisfies:

- $Q^T Q = Q Q^T = I \Leftrightarrow Q^T = Q^{-1} \Leftrightarrow Q$ has orthonormal columns, rows
- $\|Qx\| = \|x\|$ for every vector x of appropriate dimension

Note: $Q^T Q = I \Rightarrow Q = QI = Q Q^T Q \Rightarrow 0 = (Q Q^T - I)Q \Rightarrow Q Q^T = I$

If $Qc = b$, $c = Q^T b = \begin{bmatrix} -q_1^T \\ \vdots \\ -q_n^T \end{bmatrix} \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = \begin{bmatrix} q_1^T b \\ \vdots \\ q_n^T b \end{bmatrix}$

with $\|c\| = \|Qc\| = \|b\|$

Least Squares

$$Q = \begin{bmatrix} | & | \\ q_1 & \cdots & q_n \\ | & | \end{bmatrix}$$

$q_i \in \mathbb{R}^m$
 $m > n$

orthonormal columns but not a basis
rows not orthonormal
 $QQ^T \neq I_m$ but $Q^T Q = I_n$

$Qc = b$ usually has no solution

For a least squares solution, use the normal eqn's :

$$Q^T Q c = Q^T b \Rightarrow c = Q^T b = \begin{bmatrix} -q_1^T b \\ \vdots \\ -q_n^T b \end{bmatrix}$$

Projection of b onto the column space of Q :

$$p = Qc = c_1 q_1 + \dots + c_n q_n = q_1^T b q_1 + \dots + q_n^T b q_n$$

5C If the columns of $Q \in \mathbb{R}^{m \times n}$ ($n < m$) are orthogonal
so that $Q^T Q = I \in \mathbb{R}^{n \times n}$, the numbers $c_i = q_i^T b$ give

- (1) the best least squares solution to $Qc = b$
- (2) the projection $p = c_1 b_1 + \dots + c_n b_n$ of b onto $\text{col}(A)$
- (3) the coefficients that minimize the distance
 $\|c_1 q_1 + \dots + c_n q_n - b\|$ between b and any combination
of the columns.

These all describe a projection onto the subspace of \mathbb{R}^m
spanned by q_1, \dots, q_n .

Nonorthogonal Columns

Overdetermined system
more equations than unknowns

$$\begin{array}{l} Ax = b \\ A \in \mathbb{R}^{m \times n} \quad m < n \\ x \in \mathbb{R}^n \quad b \in \mathbb{R}^m \end{array}$$

If the columns of A are independent, the normal eqns give a least squares solution $A^T A x = A^T b$ by elimination and back substitution.

For an ill-conditioned $A^T A$ (when the columns of A are almost dependent, better to orthogonalize.

$$A = [a_1 \dots a_n] = [q_1 \dots q_n] \begin{bmatrix} r_{11} & \dots & r_{1n} \\ \vdots & \ddots & \vdots \\ r_{m1} & \dots & r_{mn} \end{bmatrix} = QR$$

SD If $A = QR$ with $Q^T Q = I$, the least squares solution to $Ax = b$ is $\hat{x} = R^{-1} Q^T b$

Proof: The least squares solution \hat{x} satisfies $A^T A \hat{x} = A^T b$.

$$A^T A \hat{x} = A^T b$$

$$R^T Q^T Q R \hat{x} = R^T Q^T b$$

$$R^T R \hat{x} = R^T Q^T b$$

$$R \hat{x} = Q^T b \Rightarrow \hat{x} = R^{-1} Q^T b$$

Example Forming a set q_1, q_2, q_3 of orthonormal vectors with the same span as a_1, a_2, a_3 .

$$a_1 = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \quad a_2 = \begin{bmatrix} 0 \\ 4 \\ 1 \end{bmatrix} \quad a_3 = \begin{bmatrix} 5 \\ 1 \\ 1 \end{bmatrix}$$

- q_1

$$q_1 = a_1 / \|a_1\| = a_1$$

- q_2

$$v = a_2 - (q_1^T a_2) q_1 = a_2 - q_1 = \begin{bmatrix} 0 \\ 4 \\ 0 \end{bmatrix}$$

$$\|v\| = 4$$

$$q_2 = v / \|v\| = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}$$

- q_3

$$v = a_3 - (q_1^T a_3) q_1 - (q_2^T a_3) q_2 = a_3 - q_1 - q_2 = \begin{bmatrix} 5 \\ 0 \\ 0 \end{bmatrix}$$

$$\|v\| = 5$$

$$q_3 = v / \|v\| = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$$

$$A = \begin{bmatrix} 0 & 0 & 5 \\ 0 & 4 & 1 \\ 1 & 1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 1 & 1 \\ 0 & 4 & 1 \\ 0 & 0 & 5 \end{bmatrix} = QR$$

Notice $a_1 = q_1$, $a_2 = q_1 + 4q_2$, $a_3 = q_1 + q_2 + 5q_3$

Modified Gram-Schmidt

A has independent columns a_1, \dots, a_n . We want orthonormal columns q_1, \dots, q_n with the same span to factor $A = QR$.

$$v_j^{(1)} = a_j$$

For $i = 1$ to n

$$v_j^{(2)} = P_{\perp q_1} v_j^{(1)} = v_j^{(1)} - (q_1^* v_j^{(1)}) q_1$$

$$v_i = a_i$$

$$v_j^{(3)} = P_{\perp q_2} v_j^{(2)} = v_j^{(2)} - (q_2^* v_j^{(2)}) q_2$$

For $i = 1$ to n

⋮

$$\begin{aligned} v_j &= v_j^{(j)} = P_{\perp q_{j-1}} v_j^{(j-1)} \\ &= v_j^{(j-1)} - (q_{j-1}^* v_j^{(j-1)}) q_{j-1} \end{aligned}$$

$$r_{ii} = \|v_i\|$$

$$q_i = v_i / r_{ii}$$

For $j = i+1$ to n

$$r_{ij} = q_i^* v_j$$

$$v_j = v_j - r_{ij} q_i$$

When implemented $P_{\perp q_i}$ can
be applied as soon as q_i is
known to each $v_j^{(i)}$ for $j > i$

Another pseudocode:

For $k = 1, \dots, n$

$$r_{kk} := \left(\sum_{i=1}^m a_{ik}^2 \right)^{1/2}$$

For $i = 1, \dots, m$

$$a_{ik} := a_{ik} / r_{kk}$$

For $j = k+1, \dots, n$

$$v_{kj} := \sum_{i=1}^m a_{ik} a_{ij}$$

For $i = 1, \dots, m$

$$a_{ij} := a_{ij} - a_{ik} v_{kj}$$

The QR Algorithm

Given a square matrix A , factor into $A = QR$

Define $A_1 = RQ$. A_1 is similar to A :

$$A_1 = RQ = Q^{-1}QRQ = Q^{-1}AQ \quad (= Q^T A Q)$$

A_1 and A have the same eigenvalues:

$$A_1 x = \lambda x \Rightarrow QRQx = \lambda Qx \Rightarrow A(Qx) = \lambda(Qx)$$

$$Ay = \lambda y \Rightarrow QRy = \lambda y \Rightarrow QR(Qx) = \lambda Qx$$

$$\Rightarrow Q^T QR Qx = \lambda Q^T Qx \Rightarrow RQx = \lambda x \Rightarrow A_1 x = \lambda x$$

For each $k = 0, 1, \dots$ ($A_0 := A$) factor $A_k = Q_k R_k$ and put $A_{k+1} = R_k Q_k$.

The sequence A_k approaches a diagonal or upper triangular matrix with eigenvalues on the diagonal.

Householder Matrices

$$H = I - 2uu^T \text{ for some unit vector } u$$

These matrices are symmetric and orthogonal:

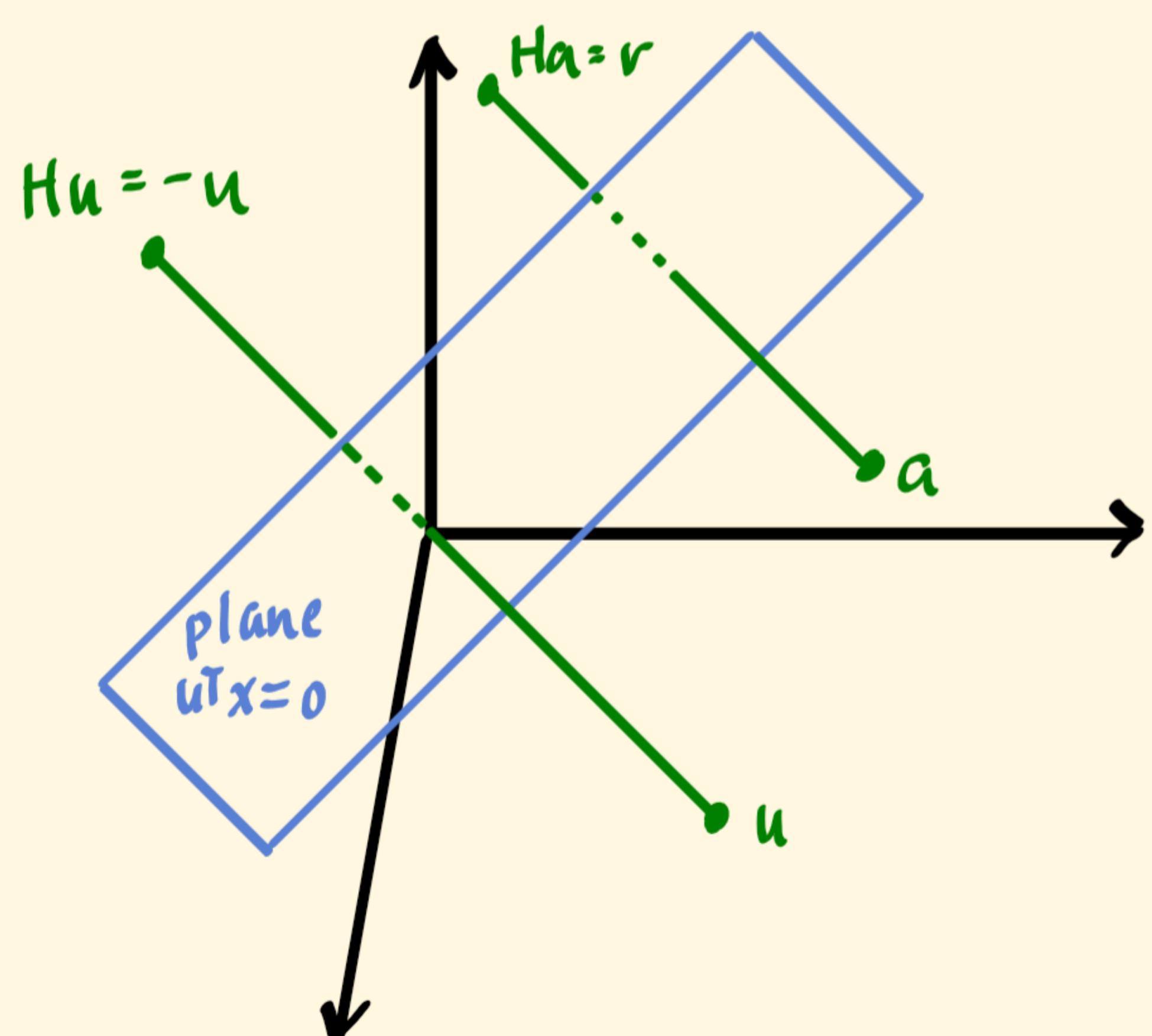
$$\begin{aligned} H^T H &= (I^T - 2(u^T)^T u)(I - 2uu^T) = (I - 2uu^T)(I - 2uu^T) \\ &= I - 4uu^T + 4uu^Tuu^T = I - 4uu^T + 4uu^T = I \end{aligned}$$

Examples

$$u = \begin{bmatrix} 1 \\ 0 \end{bmatrix} \rightarrow H = I - 2uu^T = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \rightarrow H \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} -x \\ y \end{bmatrix}$$

$$u = \begin{bmatrix} 1/\sqrt{2} \\ -1/\sqrt{2} \end{bmatrix} \rightarrow H = I - \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \rightarrow H \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} y \\ x \end{bmatrix}$$

$$\begin{aligned} u &= \begin{bmatrix} \cos \theta \\ -\sin \theta \end{bmatrix} \rightarrow H = \begin{bmatrix} 1 - 2\cos^2 \theta & \sin 2\theta \\ \sin 2\theta & 1 - 2\sin^2 \theta \end{bmatrix} \\ &= \begin{bmatrix} -\cos 2\theta & \sin 2\theta \\ \sin 2\theta & \cos 2\theta \end{bmatrix} \end{aligned}$$



For vectors in the plane

$$u^T x = 0, Hx = x.$$

Given any vector $v \neq 0$,
 $u = v/\|v\|$ gives a Householder matrix:

$$H = I - 2vv^T/\|v\|^2$$

5E The Householder matrix that takes a into r is $H = I - 2vv^T/\|v\|^2$ with $v = a - r$:

$$\text{if } a = \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} \text{ and } r = \begin{bmatrix} \|a\| \\ 0 \\ \vdots \\ 0 \end{bmatrix} \text{ then } Ha = r$$

Since H is orthogonal, $\|a\| = \|r\|$.

$$\begin{aligned} Ha &= Ia - (a-r) \frac{2(a-r)^T a}{(a-r)^T (a-r)} \\ &= a - (a-r) \frac{2a^T a - 2r^T a}{2a^T a - 2r^T a} \quad \left(\begin{array}{l} a^T a = r^T r \\ a^T r = r^T a \end{array} \right) \\ &= a - a + r = r \end{aligned}$$

Example $A = \begin{bmatrix} 3 & 4 \\ 4 & 0 \end{bmatrix}$

$$a = \begin{bmatrix} 3 \\ 4 \end{bmatrix}, \quad r = \begin{bmatrix} \|a\| \\ 0 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}, \quad v = a - r = \begin{bmatrix} -2 \\ 4 \end{bmatrix}$$

$$H = I - 2vv^T/\|v\|^2 = I - \frac{2}{20} \begin{bmatrix} 4 & -8 \\ -8 & 16 \end{bmatrix} = \begin{bmatrix} .6 & .8 \\ .8 & -.6 \end{bmatrix}$$

$$HA = \begin{bmatrix} .6 & .8 \\ .8 & -.6 \end{bmatrix} \begin{bmatrix} 3 & 4 \\ 4 & 0 \end{bmatrix} = \begin{bmatrix} 5 & 2.4 \\ 0 & 3.2 \end{bmatrix} = R$$

In this one step case, $H = Q$. In general Q is the product of several Householders: $Q = H_1 H_2 \cdots H_n$

What would the second step look like if we wanted H_2 ?

$$H_1 A = \begin{bmatrix} r_{11} & * & * \\ 0 & * & * \\ 0 & * & * \\ 0 & * & * \\ 0 & * & * \end{bmatrix} = \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ 0 & [a'] & * \\ 0 & * & * \\ 0 & * & * \\ 0 & * & * \end{bmatrix} \quad \text{The numbers } r_{12}, r_{13} \text{ just whatever is found in } H_1 A.$$

Let $a = \begin{bmatrix} 0 \\ a' \end{bmatrix} \in \mathbb{R}^m$ (take the second column and replace top row by 0)

$$r = (0, \|a\|, 0, \dots, 0) = (0, r_{22}, 0, \dots, 0)$$

$$v = a - r \rightarrow H_2 = I - 2vv^T/\|v\|^2$$

Notice that the first column of H_2 is $\begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ so $H_2(H_1 A)$

leaves the first column unchanged:

$$H_2(H_1 A) = \begin{bmatrix} r_{11} & r_{12} & r_{13} \\ 0 & r_{22} & * \\ 0 & 0 & * \\ 0 & 0 & * \\ 0 & 0 & * \end{bmatrix} \quad \text{In this } 5 \times 3 \text{ case we would apply one more Householder } H_3 \text{ to get: } H_3 H_2 H_1 A = R \rightarrow A = H_1 H_2 H_3 R = QR \text{ with } Q \text{ square and } R \text{ with 2 bottom rows of zeros.}$$

5F The least squares solution to $Ax=b$ is computed by applying Householder transformations H_1, \dots, H_n to both sides, leaving

$$\begin{bmatrix} R \\ 0 \end{bmatrix} \begin{bmatrix} x \end{bmatrix} = \begin{bmatrix} c \\ d \end{bmatrix}$$

$Q = H_1 \cdots H_n$ and the solution x is given by back substitution in $Rx=c$. The error $\|Ax-b\| = \|d\|$.

Exercises

5.2.1 If Q contains the first $n < m$ columns of the $m \times m$ identity matrix, what is the best least squares solution to $Qc = b$? Here $b \in \mathbb{R}^m$ and $c \in \mathbb{R}^n$.

By 5C, the numbers $c_i = q_i^T b$ give the best least squares solution. But here the q_i are the first n standard unit basis vectors for \mathbb{R}^m : $q_1 = e_1, \dots, q_n = e_n$.

$$\therefore c_i = b_i \text{ and } c = (b_1, \dots, b_n)$$

5.2.2

(i) Find $A^T A$ if the columns of A are orthogonal but not orthonormal with lengths $l_1 > 0, \dots, l_n > 0$.

$$A^T A = \begin{bmatrix} -a_1^T & - \\ \vdots & \\ -a_n^T & - \end{bmatrix} \begin{bmatrix} 1 & 1 \\ a_1 & \dots & a_n \\ 1 & & 1 \end{bmatrix} = \begin{bmatrix} l_1 & \dots & l_n \end{bmatrix}$$

(ii) If A has only one column a , $A^T A x = A^T b$ gives $x = a^T b / a^T a$. Find x and the projection p of $b = (1, 1, 1)$ onto the line through $a = (3, 0, 4)$.

First let's verify the claim $x = a^T b / a^T a$. Since $a^T a$ is a scalar:

$$a^T a x = A^T A x = A^T b = a^T b \rightarrow x = a^T b / a^T a$$

Given $b = (1, 1, 1)$ and $a = (3, 0, 4)$, $x = (3+4)/(9+16) = 7/25$.

The one-dimensional projection onto the line through a is the multiple $p = x a$ that is closest to b : $p = 7a/25 = (21/25, 0, 28/25)$.

5.2.3 The distance (squared) from the point b to the line through a is:

$$\|b - p\|^2 = \left\| b - \frac{a^T b}{a^T a} a \right\|^2 = \frac{(b^T b)(a^T a) - (a^T b)^2}{a^T a}$$

Since $\|b - p\|^2 \geq 0$ this gives the Schwarz inequality $|a^T b| \leq \|a\| \|b\|$. Verify:

$$\begin{aligned} 0 \leq \frac{(b^T b)(a^T a) - (a^T b)^2}{a^T a} &\Leftrightarrow 0 \leq (b^T b)(a^T a) - (a^T b)^2 \text{ since } a^T a > 0 \\ &\Leftrightarrow (a^T b)^2 \leq (b^T b)(a^T a) = \|b\|^2 \|a\|^2 \\ &\Leftrightarrow |a^T b| \leq \|a\| \|b\| \end{aligned}$$

(i) How does the Schwarz inequality come from the geometric formula $a^T b = \|a\| \|b\| \cos \theta$?

Just take absolute values:

$$|a^T b| = |\|a\| \|b\| \cos \theta| = \|a\| \|b\| |\cos \theta| \leq \|a\| \|b\| \cdot 1 = \|a\| \|b\|$$

(ii) By making the right choice of b , show that for any $a = (a_1, \dots, a_m)$

$$(a_1 + \dots + a_m)^2 \leq m(a_1^2 + \dots + a_m^2)$$

Try $b = (1, 1, \dots, 1)$:

$$(a_1 + \dots + a_m)^2 = |a^T b|^2 \leq \|a\|^2 \|b\|^2 = (a^T a)(b^T b) = (a_1^2 + \dots + a_m^2) \cdot m$$

(iii) When does equality hold in part (ii)? In $|a^T b| \leq \|a\| \|b\|$?

$$(a_1 + \dots + a_m)^2 = m(a_1^2 + \dots + a_m^2)$$

$$a_1^2 + \dots + a_m^2 + \sum_{i \neq j} 2a_i a_j = m a_1^2 + \dots + m a_m^2$$

$$\|a\|^2 = a_1^2 + \dots + a_m^2 = \frac{\sum_{i \neq j} 2a_i a_j}{m}$$

$$\begin{aligned} a^T b = \|a\| \|b\| \cos \theta \Rightarrow |a^T b| = \|a\| \|b\| \text{ when } \cos \theta = \pm 1 \\ \Rightarrow a \parallel b \text{ (parallel)} \end{aligned}$$

5.2.5 Find the best least squares solution to

$$\frac{1}{2} \begin{bmatrix} 1 & -1 \\ -1 & 1 \\ -1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix} = b$$

What is the projection of b onto the space spanned by these two columns

The least squares solution \hat{x} satisfies $A^T A \hat{x} = A^T b$

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \hat{x} = \frac{1}{4} \begin{bmatrix} 4 & 0 \\ 0 & 4 \end{bmatrix} \hat{x} = A^T A \hat{x} = A^T b = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\hat{x} = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

$$\text{The projection is } P = A \hat{x} = \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}$$

5.2.10 The projection matrix onto the column space of A is $P = A(A^T A)^{-1} A^T$ (since $P = A \hat{x}$, $\hat{x} = (A^T A)^{-1} A^T b$). If $A = QR$, find a simpler formula for P .

$$\begin{aligned} P &= QR(R^T Q^T R Q)^{-1} R^T Q^T = QR(R^T R)^{-1} R^T Q^T \\ &= QRR^{-1}(R^T)^{-1} R^T Q^T = QQ^T \end{aligned}$$

5.2.12 What rotation angle θ produces a zero below the diagonal in the product QA ?

$$QA = \begin{bmatrix} \cos\theta & -\sin\theta \\ \sin\theta & \cos\theta \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

$$QA = \begin{bmatrix} a\cos\theta - c\sin\theta & b\cos\theta - d\sin\theta \\ a\sin\theta + c\cos\theta & b\sin\theta + d\cos\theta \end{bmatrix}$$

$$0 = a\sin\theta + c\cos\theta \Rightarrow \theta \text{ s.t. } \tan\theta = -c/a$$

? 5.2.17 If A_0 is symmetric and tridiagonal show that $A_1 = RQ = Q^{-1}A_0Q$ is also symmetric and tridiagonal.
 Hint: Indicate by 'x' the (generally) nonzero entries of a 4×4 $A_0 = QR$. Each column of Q comes by G-S from the current column and previous column of A_0 .

$$A_0 = \begin{bmatrix} x & x & 0 & 0 \\ x & x & x & 0 \\ 0 & x & x & x \\ 0 & 0 & x & x \end{bmatrix} \stackrel{?}{=} \begin{bmatrix} x & & & \\ & x & x & x \\ & x & x & x \\ & x & x & x \end{bmatrix} \begin{bmatrix} x & x & x & x \\ x & x & x & x \\ x & x & x & x \\ x & x & x & x \end{bmatrix}$$

5.2.18 If H is a Householder matrix and $Hx=y$, show that also $Hy=x$. What 4×4 matrix gives a reflection across the plane $v^T x = x_1 + x_2 + x_3 + x_4 = 0$?

- $Hy = HHx = H^T Hx = x$ (since $H = H^T$ and $H^T H = I$).

- $0 = x_1 + x_2 + x_3 + x_4 = v^T x \Rightarrow v = (1, 1, 1, 1)$

$$H = I - 2vv^T/\|v\|^2 = I - \frac{2}{4} \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \\ 1 & 1 & 1 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 & -1 & -1 \\ -1 & 1 & -1 & -1 \\ -1 & -1 & 1 & -1 \\ -1 & -1 & -1 & 1 \end{bmatrix}$$

H is orthogonal and $Hx=0$ for $0 = x_1 + x_2 + x_3 + x_4$

5.2.21 Find the Householder matrix H_1 that produces zeros below the first entry in A . Compute $H_1 A$.

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 0 \\ 2 & 2 \end{bmatrix}$$

$$a = \begin{bmatrix} 2 \\ 1 \\ 2 \end{bmatrix} \rightarrow r = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix} \rightarrow v = a - r = \begin{bmatrix} -1 \\ 1 \\ 2 \end{bmatrix}, \|v\|^2 = 6$$

$$H_1 = I - 2vv^T/\|v\|^2 = I - \frac{2}{6} \begin{bmatrix} 1 & -1 & 2 \\ -1 & 1 & 2 \\ 2 & 2 & 4 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 2 & 1 & 2 \\ 1 & 2 & -2 \\ 2 & -2 & -1 \end{bmatrix}$$

$$H_1 A = \begin{bmatrix} 3 & 2 \\ 0 & -1 \\ 0 & 0 \end{bmatrix} = R \rightarrow A = \frac{1}{3} \begin{bmatrix} 2 & 1 & 2 \\ 1 & 2 & -2 \\ 2 & -2 & -1 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & -1 \\ 0 & 0 \end{bmatrix} = H_1 R = QR$$

No H_2 needed since $H_1 A$ is already upper triangular

5.2.22 If $H = I - 2uu^T$ show that the unit vector u is an eigenvector and find the eigenvalue. Show that any $x \perp u$ is also an eigenvector with $\lambda=1$. Find the trace and determinant.

- $Hu = Iu - 2uu^Tu = u - 2u = -u \rightarrow \begin{matrix} Hu = -1u \\ \lambda_1 = -1 \end{matrix}$

- $u^Tx = x^Tu = 0 \rightarrow Hx = Ix - 2uu^Tx = x \rightarrow \begin{matrix} Hx = 1x \\ \lambda_2 = 1 \end{matrix}$

- $\det H = \lambda_1\lambda_2 = -1$, $\text{trace } H = \lambda_1 + \lambda_2 = 0$

- What if $u \in \mathbb{R}^n$, $n > 2$ so $H \in \mathbb{R}^{n \times n}$?

Do we find $x_1, \dots, x_{n-1} \perp u$?

Then $\det H = -1$ but $\text{trace } H = -1 + (n-1)1 = n-2$?

5.2.24 Find H and the tridiagonal form $A_0 = HAH$.

$$A = \begin{bmatrix} 1 & 3 & 4 \\ 3 & 2 & 1 \\ 4 & 1 & 0 \end{bmatrix}$$

$$a = \begin{bmatrix} 1 \\ 3 \\ 4 \end{bmatrix} \rightarrow r = \begin{bmatrix} a_{11} \\ \|a\| \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 5 \\ 0 \end{bmatrix} \rightarrow v = a - r = \begin{bmatrix} 0 \\ -2 \\ 4 \end{bmatrix}$$

$$H = I - 2vv^T/\|v\|^2 = \frac{1}{5} \begin{bmatrix} 5 & 0 & 0 \\ 0 & 3 & 4 \\ 0 & 4 & -3 \end{bmatrix}$$

$$A_0 = HAH = \begin{bmatrix} 1 & 5 & 0 \\ 5 & 42/25 & 31/25 \\ 0 & 31/25 & 8/25 \end{bmatrix} \text{ is tridiagonal}$$