

1.6 A Review of Matrix Theory

Notes

In this section admit general matrices: A is $m \times n$ of rank r .

Definition: The rank of A is the number, r , of linearly independent columns in A .

IN Ax is always a combination of the columns of A ; it is in the column space of A , denoted $\mathcal{R}(A)$. The system $Ax=b$ has a solution exactly when b is also in the column space of A .

Definition: The nullspace of A , denoted $\mathcal{N}(A)$, is the set of vectors x satisfying $Ax=0$.

For $A \in \mathbb{R}^{m \times n}$:

The column space $\mathcal{R}(A)$ is a subset of \mathbb{R}^m and has dimension r .
The nullspace $\mathcal{N}(A)$ is a subset of \mathbb{R}^n and has dimension $n-r$.

10 If the matrix A has linearly independent columns then:

- (1) The nullspace contains only the point $x=0$.
- (2) The solution to $Ax=b$ is unique (if it exists).
- (3) The rank is $r=n$.

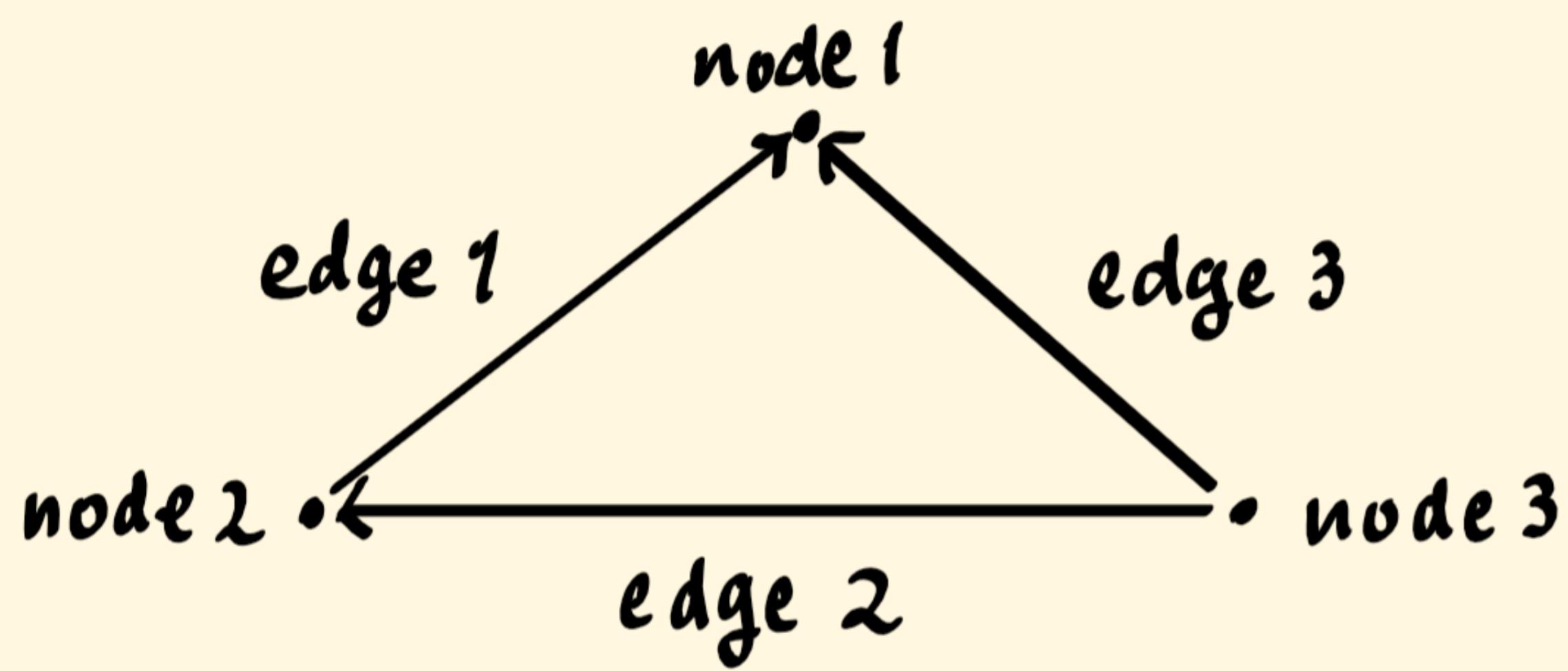
Note that (3) implies we are assuming $n \leq m$. If $n > m$ then $r=n$ is not possible. We could not, for example, find 5 linearly independent vectors of length 4.

Proof: Suppose the columns a_1, \dots, a_n of A are independent.

- (1) $Ax=0 \rightarrow x_1a_1 + \dots + x_na_n = 0 \rightarrow x_i=0 \forall i \rightarrow x=0$.
- (2) $Ax=b = Ay \rightarrow A(x-y) = b - b = 0 \rightarrow x-y=0$ by (1) $\rightarrow x=y$
- (3) A has n columns. We assumed these columns are independent.
The rank is defined to be the number of independent columns. $\therefore r=n$.

Incidence Matrices

Graph:



Edge-node incidence matrix:

$$A = \begin{bmatrix} 1 & -1 & 0 \\ 0 & 1 & -1 \\ 1 & 0 & -1 \end{bmatrix}$$

rows correspond to edges
columns correspond to nodes
+1 for an edge entering a node
-1 for an edge leaving a node

$Ax = b$:

$$\left. \begin{array}{l} x_1 - x_2 = b_1 \\ x_2 - x_3 = b_2 \\ x_1 - x_3 = b_3 \end{array} \right\} \rightarrow (x_1 - x_2) + (x_2 - x_3) = (x_1 - x_3) \\ b_1 + b_2 = b_3$$

For $Ax = b$ to have a solution, we must have $y^T b = 0$, $y = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$

This is an example of Kirchhoff's voltage law: the sum of the potential drops around a closed loop is zero.

Consider $A^T y = f$. Call A^T the node-edge incidence matrix.

$$A^T y = \begin{bmatrix} 1 & 0 & 1 \\ -1 & 1 & 0 \\ 0 & -1 & -1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \\ y_3 \end{bmatrix} = \begin{bmatrix} y_1 + y_3 \\ -y_1 + y_2 \\ -y_2 - y_3 \end{bmatrix} = \begin{bmatrix} f_1 \\ f_2 \\ f_3 \end{bmatrix} = f$$

Questions about $A^T y = f$:

(1) For which f can the system be solved?

$$(y_1 + y_3) + (-y_1 + y_2) - (y_2 + y_3) = 0 \rightarrow f_1 + f_2 + f_3 = 0$$

(The y components sum to 0 \rightarrow The f components sum to 0)

The column space of A^T , $R(A^T)$ contains vectors f s.t.
 $x^T f = 0$, $x^T = [1 \ 1 \ 1]$.

(2) Are the solutions to $A^T y = f$ unique?

Any vector $y_0 = [c, c, -c]^T$ gives $A^T y_0 = 0$ and so for any solution y of $A^T y = f$, $A^T(y + y_0) = f$ as well. The solution of $A^T y$ is not unique.

Note that $x = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$ is in $N(A)$ and is perpendicular to the columns of A^T .

Note that $y = \begin{bmatrix} 1 \\ -1 \\ \vdots \\ 0 \end{bmatrix}$ is in $N(A^T)$ and is perpendicular to the columns of A .

From each matrix A come four fundamental subspaces, two from $Ax = b$ and two from $A^T y = f$:

$R(A)$: column space of A , a subspace of \mathbb{R}^m

$N(A)$: nullspace of A , a subspace of \mathbb{R}^n

$R(A^T)$: row space of A , a subspace of \mathbb{R}^n

$N(A^T)$: left nullspace of A , a subspace of \mathbb{R}^m

The dimensions and perpendicularity of these four spaces make up:

1P (The Fundamental Theorem of Linear Algebra)

The row space and null space are perpendicular to each other and their dimensions add up to n :

$$(i) R(A^T) \perp N(A)$$

$$(ii) \dim R(A^T) + \dim N(A) = r + (n-r) = n$$

The column space and left nullspace are perpendicular to each other and their dimensions add up to m :

$$(iii) R(A) \perp N(A^T)$$

$$(iv) \dim R(A) + \dim N(A^T) = r + (m-r) = m$$

Proof:

$$\left. \begin{array}{l} (i) f \in R(A^T) \rightarrow \exists y \text{ s.t. } A^T y = f \\ x \in N(A) \rightarrow A x = 0 \end{array} \right\} \rightarrow x^T f = x^T A^T y = (Ax)^T y = 0^T y = 0$$

$$\left. \begin{array}{l} (iii) b \in R(A) \rightarrow \exists x \text{ s.t. } A x = b \\ y \in N(A^T) \rightarrow A^T y = 0 \end{array} \right\} \rightarrow y^T b = y^T A x = (A^T y)^T x = 0^T x = 0$$

The theorem claims $\dim R(A) = \dim R(A^T) = r$. That is, the number of independent columns of A equals the number of independent rows of A . One proof of this fact uses orthogonality (orthogonal = perpendicular here).

Let $A \in \mathbb{R}^{m \times n}$ with $\dim R(A^T) = r$. Let x_1, \dots, x_r be a basis for $R(A^T)$.

$$\text{Consider } 0 = c_1 A x_1 + \dots + c_r A x_r = A(c_1 x_1 + \dots + c_r x_r) = A v$$

$$\left. \begin{array}{l} \text{(a) } v = c_1 x_1 + \dots + c_r x_r \text{ means } v \in R(A^T) \\ \text{(b) } A v = 0 \text{ means } v \text{ is orthogonal to each row of } A \\ \text{and thus orthogonal to any linear combination of the} \\ \text{rows of } A (= R(A)) \end{array} \right\} \begin{array}{l} v \in R(A^T) \\ \$ \\ v \perp R(A^T) \\ \rightarrow v = 0 \end{array}$$

$$\therefore c_1 x_1 + \dots + c_r x_r = 0 \rightarrow c_1 = \dots = c_r = 0 \text{ since } x_1, \dots, x_r \text{ are independent.}$$

This means $A x_1, \dots, A x_r$ are independent as well. Each $A x_i$ is a vector in $R(A)$, so we have found r independent vectors in $R(A)$.

$$\dim R(A) \geq r = \dim R(A^T)$$

Next suppose $\dim R(A) = s$ and let x_1, \dots, x_s be a basis for $R(A)$.

Consider $0 = c_1 A^T x_1 + \dots + c_s A^T x_s = A^T(c_1 x_1 + \dots + c_s x_s) = A^T u$. We have

$$\left. \begin{array}{l} \text{(a) } u \in R(A) \\ \text{(b) } u \perp R(A) \end{array} \right\} \rightarrow u = 0 \rightarrow c_1 = \dots = c_s = 0 \rightarrow A^T x_1, \dots, A^T x_s \text{ independent}$$

Since we have s independent vectors in $R(A^T)$,

$$\dim R(A) = s \leq \dim R(A^T)$$

Conclude that since $\dim R(A) \geq \dim R(A^T)$ and $\dim R(A) \leq \dim R(A^T)$, we have $s = r$ and

$$\dim R(A) = \dim R(A^T) = r$$

Finally

(ii) If $\dim R(A^T) = r$, A^T has r independent columns. Then the nullspace of A has a basis with $n-r$ vectors and $r + (n-r) = n$

(iv) If $\dim R(A) = r$, A has r independent columns. Then the nullspace of A^T has a basis with $m-r$ vectors and $r + (m-r) = m$.

Another way to see the orthogonality relationships $R(A^T) \perp N(A)$ and $R(A) \perp N(A^T)$ is:

$$x \in N(A) \iff Ax = 0$$

$$\iff \begin{bmatrix} \text{row 1} \\ \vdots \\ \text{row } m \end{bmatrix} x = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$\iff x$ orthogonal to each row

$\iff x$ orthogonal to any linear combination of rows

$\iff x$ orthogonal to each $f \in R(A^T)$

$$y \in N(A^T) \iff A^T y = 0$$

$$\iff \begin{bmatrix} \text{column 1} \\ \vdots \\ \text{column } n \end{bmatrix} y = \begin{bmatrix} 0 \\ \vdots \\ 0 \end{bmatrix}$$

$\iff y$ orthogonal to each column

$\iff y$ orthogonal to any linear combination of columns

$\iff y$ orthogonal to each $b \in R(A)$

Factorizations Based on $A^T A$

$$A \in \mathbb{R}^{m \times n} \rightarrow A^T A \in \mathbb{R}^{n \times n}$$

$A^T A$ is at least symmetric positive semidefinite:

$$x^T A^T A x = \|Ax\|^2 \geq 0 \text{ with equality iff } Ax = 0$$

Whether $A^T A$ is positive definite then depends on whether there $x \neq 0$ s.t. $Ax = 0$. Nontrivial solutions exist iff the columns of A are dependent. Theorem 1R (1) follows from this.

1R

- (1) If the columns of A are independent then $A^T A$ is s.p.d.
- (2) If the columns of A are dependent then $A^T A$ is positive semi-definite but not invertible and $\lambda = 0$ is an eigenvalue of $A^T A$.
- (3) $N(A) = N(A^T A)$, $R(A^T) = R((A^T A)^T)$, and $\text{rank}(A) = \text{rank}(A^T A)$
($A, A^T A$ have same rowspace)

Proof:

- (2) If the columns of A are dependent $\exists x \neq 0$ s.t. $Ax = 0$ and for such x we have also $A^T A x = A^T 0 = 0$. This implies $A^T A$ is singular. Also $\lambda = 0$ is an eigenvalue for which any $x \neq 0$ s.t. $Ax = 0$ is an eigenvector:

$$A^T A x = \vec{0} = 0x \quad (\text{used } \vec{0} \text{ to distinguish between scalar/vector zero})$$

- (3) $N(A) = N(A^T A)$: $x \in N(A) \iff Ax = 0 \iff A^T A x = 0 \iff x \in N(A^T A)$

Of these statements, $A^T A x = 0 \rightarrow Ax = 0$ is likely the least obvious. We use an argument that has been seen a few times in this section. Suppose x satisfies $A^T A x = 0$ and consider $Ax = b$. We have $b \in R(A)$ and also $A^T b = 0$. $A^T b = 0$ implies b is orthogonal to every vector in $R(A)$. In particular $0 = b^T b$, which holds iff $b = 0$. Conclude that if $A^T A x = 0$ then $Ax = 0$.

$\text{rank } A = \text{rank } A^T A$: Suppose $\text{rank } A = r$. We have seen that this means $\text{rank } A^T = r$ as well. Recall $\text{rank } A^T = \dim R(A^T)$ by definition. From 1P, $r = n - \dim N(A)$. Using $N(A) = N(A^T A)$, 1P, $A^T A = (A^T A)^T$, and the definition of $\text{rank } A^T A$,

$$n = \dim R((A^T A)^T) + \dim N(A^T A) = \text{rank } A^T A + \dim N(A)$$

Conclude $\text{rank } A^T A = n - \dim N(A) = r = \text{rank } A$.

$$R(A^T) = R((A^T A)^T) : f \in R(A^T) \leftrightarrow f \perp N(A) \leftrightarrow f \perp N(A^T A) \leftrightarrow f \in R((A^T A)^T)$$

Here we use the claim that $f \in R(B^T)$ iff $f \perp N(B)$ for a matrix B :

$$f \in R(B^T) \rightarrow \exists y \text{ s.t. } B^T y = f \rightarrow x^T f = x^T B^T y = 0^T y = 0 \quad \forall x \in N(B) \rightarrow f \perp N(B)$$

To prove $f \perp N(B)$ implies $f \in R(B^T)$ use orthogonal projection. For any subspace V of \mathbb{R}^n , any vector $f \in \mathbb{R}^n$ can be written as $f = v + u$, where $v \in V$ and $u \in V^\perp$, where V^\perp is the orthogonal complement of V (the set of all vectors orthogonal to every vector in V). Since $N(A)$ is a subspace of \mathbb{R}^n and $N(A)^\perp = R(A^T)$ we have:

$$f = v + u, \quad v \in N(A) \quad u \in R(A^T)$$

Since $f \perp N(B)$, $x^T f = 0 \quad \forall x \in N(A)$. In particular $v^T f = 0$, so

$$0 = v^T f = v^T v + v^T u = v^T v + 0 = v^T v \rightarrow v = 0 \rightarrow f = u \in R(A^T)$$

Conclude that $f \perp N(B)$ implies $f \in R(A^T)$.

Remark: An important observation follows from TR:

$$Ax = 0 \text{ iff } A^T A x = 0 \text{ iff } x^T A^T A x = 0$$

(Recall $0 = x^T A^T A x = \|Ax\|^2 \rightarrow Ax = 0$ so one could look at these statements as a 'logical loop').

Review of the Review

A rank one matrix has a one dimensional column space; all columns are multiples of the same column. Such a matrix can be written as the product of a column times a row:

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 6 & 3 \\ 2 & 4 & 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \end{bmatrix} = v w^T$$

For a rank one matrix $A = v w^T$,

- (1) The column space $R(A)$ contains all multiples of v .
- (2) The row space $R(A^T)$ contains all multiples of w .
- (3) The nullspace $N(A)$ contains all vectors orthogonal to w .
- (4) The left nullspace $N(A^T)$ contains all vectors orthogonal to v .

The LU factorization is straightforward given v and w .

$$A = \begin{bmatrix} 1 & 2 & 1 \\ 3 & 6 & 3 \\ 2 & 4 & 2 \end{bmatrix} = \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 \\ 3 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

In general,

$$A = v w^T = \begin{bmatrix} 1 & 0 & \dots & 0 \\ v & I & & \\ 0 & & \ddots & \\ & & & 0 \end{bmatrix} \begin{bmatrix} -w^T \\ 0 \end{bmatrix}$$

Eigenvalues:

Since $\text{rank } A = 1$, $\dim N(A) = n-1 \rightarrow \lambda = 0$ is an eigenvalue repeated $n-1$ times. This leaves only one $\lambda \neq 0$ to be found.

$$Av = v w^T v = (w^T v)v = \lambda v$$

This calculation shows $\lambda = w^T v$ is an eigenvalue with v an eigenvector. Unless $w^T v = 0$, this eigenvalue is nonzero. Also,

$$A^2 = v w^T v w^T = v \lambda w^T = \lambda v w^T = \lambda A$$

As long as $v \notin N(A)$, $\lambda = w^T v \neq 0$. That is, $\lambda = w^T v \neq 0$ as long as v and w are not orthogonal.

In one application of rank one matrices we have $v = w = u$ with $u^T u = 1$

$A = u u^T$ is called a projection matrix. $A b = u u^T b$ is the multiple of u closest to b . All projection matrices satisfy $A^2 = u u^T u u^T = u u^T = A$.

Exercises

1.6.8 Show that $(A^{-1})^T = (A^T)^{-1}$ when A is invertible.

$$AA^{-1} = I \rightarrow (A^{-1})^T A^T = I^T = I \rightarrow (A^T)^{-1} = (A^{-1})^T$$

1.6.10 To which of these classes does A belong to: symmetric, orthogonal, triangular, invertible, projection, permutation, Jordan form, diagonalizable? Find the eigenvalues of A.

$$A = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$

$$\lambda = \pm 1, \pm i$$

Symmetric	X
Orthogonal	✓ ($A^T A = I$)
triangular	X
invertible	✓ ($A^{-1} = A^T$)
projection	X ($A^2 \neq A$)
permutation	✓
Jordan form	X ($A = J$ would be upper triangular)
diagonalizable	✓ (orthogonal implies diagonalizable)

1.6.15 The fundamental theorem says either b is in the column space or b is not orthogonal to the left nullspace. Either:

$$(1) Ax = b \text{ for some } x$$

or

$$(2) A^T y = 0, y^T b \neq 0 \text{ for some } y$$

Show directly that (1) and (2) cannot both be true.

Suppose $\exists x, y$ s.t. both (1) and (2) hold.

$$0 \neq y^T b = y^T A x = (A^T y)^T b = 0^T b = 0$$

This produces the contradiction $0 \neq 0$. \therefore (1) and (2) cannot both be true.

1.6.23 If the pivots of A are $d_1=2$ and $d_2=3$ (w/o row exchange), what can be said about the eigenvalues? What if you also know the trace is $\text{tr}(A) = a_{11} + a_{22} = 6$?

The product of the pivots gives the determinant (from $A = LU$) and also the product of the eigenvalues gives the determinant (see 1K). Thus, $\lambda_1 \lambda_2 = 6$.

Also from 1K, $\text{tr}(A) = \sum_i \lambda_i$, so $\lambda_1 + \lambda_2 = 6$ if we know $\text{tr}(A) = 6$.

$\lambda_1 + \lambda_2 = 6$ and $\lambda_1 \lambda_2 = 6$ holds for $\lambda_1, \lambda_2 = 3 \pm \sqrt{3}$ (used Wolframalpha).

1.6.21 Let $v = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$ and $w = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$ so that $v^T w = 0$.

(a) What is $A = vw^T$?

$$A = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{bmatrix} 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix}$$

(b) What are the eigenvalues of A ?

$$0 = (1-\lambda)(-1-\lambda) + 1 = -1 - \lambda + \lambda + \lambda^2 + 1 = \lambda^2 \rightarrow \lambda = 0$$

(c) What are its eigenvectors?

$$\left[\begin{array}{cc|c} 1 & -1 & 0 \\ 1 & -1 & 0 \end{array} \right] \rightarrow x_1 = x_2 \text{ Take } x = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \quad \left. \begin{array}{l} \\ \end{array} \right\} M = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix}$$

$$\left[\begin{array}{cc|c} 1 & -1 & 1 \\ 1 & -1 & 1 \end{array} \right] \rightarrow y_1 = y_2 \text{ Take } y = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

(d) What is the Jordan form of A ?

$$J = \begin{bmatrix} \lambda & 1 \\ 0 & \lambda \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \quad \text{Since } A \text{ has one eigenvalue } \lambda = 0 \text{ with multiplicity 2, } J \text{ consists of one } 2 \times 2 \text{ block.}$$

$$A = \begin{bmatrix} 1 & -1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} -1 & 2 \\ 1 & -1 \end{bmatrix} = MJM^{-1}$$

1.6.22 If $A = S\Lambda S^{-1}$ show that A and A^T have the same eigenvalues. What matrix contains the eigenvectors of A^T . They agree with the eigenvectors of A if $AA^T = A^TA$.

$(A - \lambda I)^T = A^T - \lambda I^T = A^T - \lambda I \rightarrow \det(A^T - \lambda I) = \det((A - \lambda I)^T) = \det(A - \lambda I)$ using the property of determinants: $\det B = \det B^T$ for any matrix B . Since A and A^T have the same characteristic polynomial, they have the same eigenvalues.

$A = S\Lambda S^{-1} \rightarrow A^T = (S^{-1})^T \Lambda S^T$ means the eigenvectors of A^T should be the columns of $(S^{-1})^T = (S^T)^{-1}$. If $AA^T = A^TA$, $(S^T)^{-1} = S$ and $S^T = S^{-1}$

$$AA^T = S\Lambda S^{-1}(S^T)^{-1}\Lambda S^T = (S^T)^{-1}\Lambda S^T S\Lambda S^{-1} = A^TA$$

$$S\Lambda S^{-1}S\Lambda S^{-1} = S\Lambda S^{-1}S\Lambda S^{-1}$$

$$S\Lambda^2 S^{-1} = S\Lambda^2 S^{-1}$$

1.6.24 Show that A^TA can never have a negative eigenvalue.

$$A^TAx = \lambda x \rightarrow x^T A^TAx = \lambda x^T x \rightarrow \|Ax\|^2 = \lambda \|x\|^2 \rightarrow \lambda = \|Ax\|^2 / \|x\|^2$$

$\|Ax\|^2, \|x\|^2 > 0$ since $x \neq 0$ (by definition of an eigenvector). $\therefore \lambda > 0$

1.6.19 True or False?

1. There is no matrix A whose row space contains $[1 \ 2 \ 1 \ 1]^T$ and whose nullspace contains $[1 \ -2 \ 1 \ 1]^T$.

True

Suppose $f = [1 \ 2 \ 1 \ 1]^T \in R(A^T)$ and $x = [1 \ -2 \ 1 \ 1]^T \in N(A)$. By the fundamental theorem of linear algebra, $R(A^T) \perp N(A)$. We must have $x^T f = 0$. But $x^T f = -1$. From this contradiction conclude there can be no A s.t. $f \in R(A^T)$ and $x \in N(A)$.

2. Exactly one vector is in both the row space and the row space.

True

Suppose $x \in R(A^T)$ and $x \in N(A)$. Since $x \in N(A)$, $Ax = 0$. Then x is orthogonal to every row of A and therefore orthogonal to every linear combination of rows of A . This means x is orthogonal to every vector in $R(A^T)$. In particular $x \perp x$. The only vector orthogonal to itself in any vector space is the zero vector. There is exactly one zero vector in \mathbb{R}^n (or any vector space for that matter).

3. If $\text{rank } A = \text{rank } B = 3$, then $\text{rank}(A+B) \leq 6$.

True

In general, $\text{rank}(A+B) \leq \text{rank } A + \text{rank } B$. The rank of $A+B$ is the dimension of the column space of $A+B$. If any vector y is in the column space of $A+B$, then y can be written as a linear combination of the vectors $a_1+b_1, a_2+b_2, \dots, a_n+b_n$. But this means y can be written as a linear combination of the vectors $a_1, \dots, a_n, b_1, \dots, b_n$. This means the column space of $A+B$ is a subset of the space spanned by $a_1, \dots, a_n, b_1, \dots, b_n$. Then $\text{rank}(A+B)$, which is the dimension of the space spanned by the columns of $A+B$, is less than the dimension of the space spanned by $a_1, \dots, a_n, b_1, \dots, b_n$ (since the first is a subset of the second). We know there are $\text{rank } A + \text{rank } B$ independent vectors out of $a_1, \dots, a_n, b_1, \dots, b_n$ (= dimension of the span of these vectors). So $\text{rank}(A+B) \leq \text{rank } A + \text{rank } B$. Conclude

$$\text{rank}(A+B) \leq \text{rank } A + \text{rank } B = 6.$$

4. The rank of the matrix with every $a_{ij}=1$ is 1.

True

In this case every column is the same - only 1 independent column.

5. The rank of the $n \times n$ matrix A with $a_{ij}=i+j$ is $r=n$.

False

Consider the counterexample given by the case $n=3$:

Suppose $Ax=0$:

$$A = \begin{bmatrix} 2 & 3 & 4 \\ 3 & 4 & 5 \\ 4 & 5 & 6 \end{bmatrix} \quad \left. \begin{array}{l} 2x_1 + 3x_2 + 4x_3 = 0 \\ 3x_1 + 4x_2 + 5x_3 = 0 \\ 4x_1 + 5x_2 + 6x_3 = 0 \end{array} \right\} \quad \begin{array}{l} \text{If } x_1 + x_2 + x_3 = 0 \text{ and} \\ 2x_1 + 3x_2 + 4x_3 = 0 \text{ then all} \\ 3 \text{ equations are satisfied.} \end{array}$$

$$\left[\begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 2 & 3 & 4 & 0 \end{array} \right] \sim \left[\begin{array}{ccc|c} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & 0 \end{array} \right] \rightarrow x_1 = x_3 \text{ and } x_2 = -2x_3$$

Take $x = [1 \ -2 \ 1]^T$. Then $Ax=0$ for this nonzero x .
Conclude that $r=\text{rank } A < 3 = n$.